

# Testing performance of computer vision on different computer hardware

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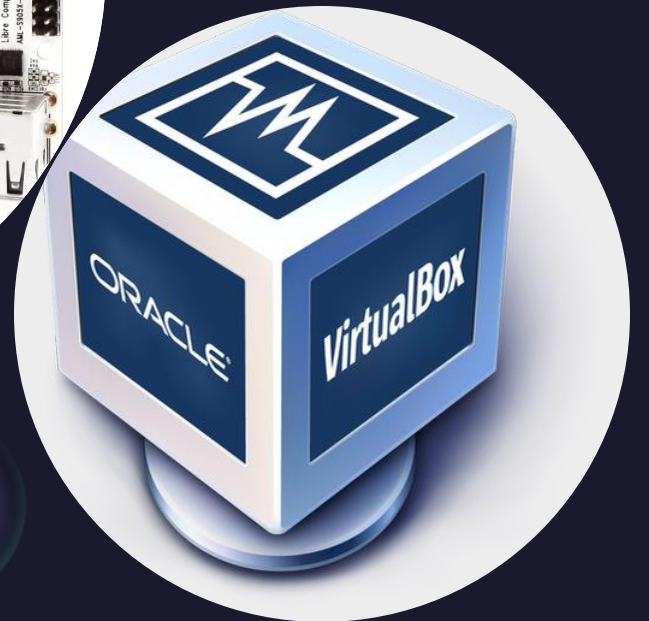
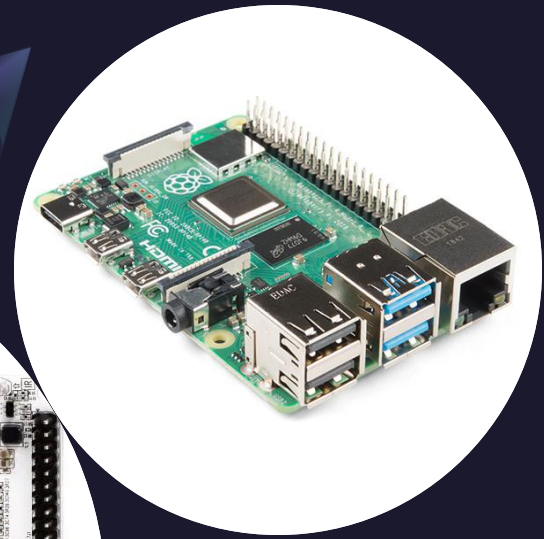


# Project Description

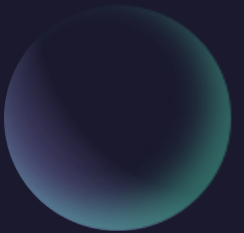
We will be testing several different devices' processor capabilities in recognizing color through visuals and analyzing their performance through software related means.



# Hardware

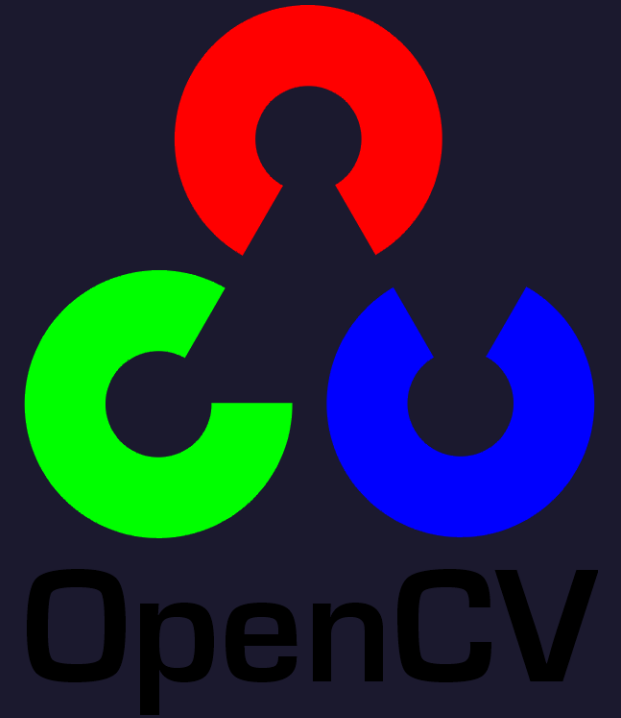


	Le Potato	RaspberryPi 4	Virtual Box
Price	\$35	~\$45	~Free
Available	Yes	No	Yes
Processor	4 Core ARMv8 Cortex-A53 1.512GHz	4 Core ARMv8 Cortex-A72 1.8GHz	4
GPU	5 Core 3D		~
RAM	2GB DDR3	1/2/4/8 GB	2GB
Video	H.264/H.265	H.264/H.265	~
Video Out	HDMI 2.0 4K HDR	micro-HDMI x2 4k	~
USB	USB2.0 x 4	USB2.0 x 2, USB3.0 x 2	~
Ethernet	100 Mb	1Gb	~
Wireless	X	2.4GHz + 5GHz	~
Bluetooth	X	5.0 and BLE	~
Power-in	MicroUSB	Micro SD	~
Load OS	Micro SD	Micro SD	~
Tinker!	40 Pin GPIO Header	40 Pin GPIO Header	~



# Software

- Operating System: Linux (Ubuntu)
- OpenCV: Open Source Computer Vision Library
  - Python bindings
- Color recognition (K-means clustering algorithm)



# Performance Metrics

- CPU Execution Time
- Cost/Performance: Which choice is more economical for the price you pay
- CPU Usage: Monitor the Percent of the CPU used
- Memory Usage: Track RAM Consumption while the algorithm runs
- I/O Operations: Elapsed time for file I/O operations like read/write.






# How will we measure the Performance

- Python has in-built utilities that can be added to your code to check to see how performant your algorithm is
- For example, the following is for measuring the **CPU** and **Memory Usage**

python

 Copy code

```
import time
import psutil

start_time = time.time()
# Execute your algorithm here
end_time = time.time()
execution_time = end_time - start_time

cpu_usage = psutil.cpu_percent(interval=1)
memory_usage = psutil.virtual_memory().percent
```

```
memory_usage = psutil.virtual_memory().percent
cpu_usage = psutil.cpu_percent(interval=1)
```

# Our progress and in progress

- We have the Le Potato and we are waiting for the Wi-Fi adapter to arrive
- Waiting on the Raspberry Pi 4
- We set up virtual box
- Evaluating our software potential





# Update

We focus setting up Virtual Box, in each team member computers. Tested Python3-OpenCV algorithms, on a live camera, image and video to detect a specific color.

Will be implementing all the multiple test for the 3 phases for each hardware test for CPU Usage, Memory Usage, Execution time.



Find a color in a live video



Find color in a image



Find color in a Video



Test performance using python library.



Implement in raspberry pi and le potato.



Testing using in in each processor



# Find a color on a live video



# Find color in an image



(x=550, y=542) ~ R:255 G:255 B:255

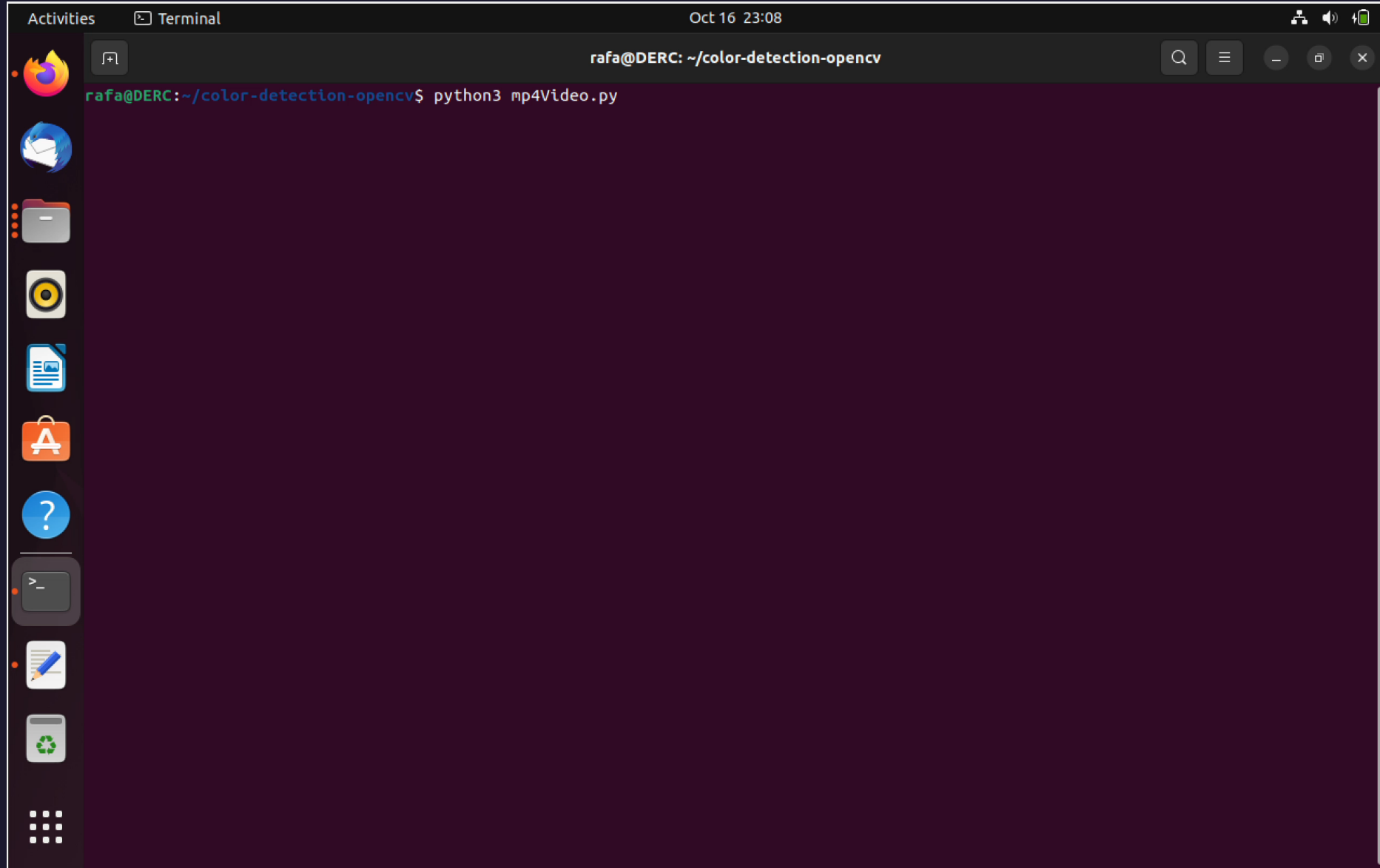
```
1 import cv2 as cv
2 from PIL import Image
3
4 from util import get_limits
5
6 yellow = [0, 255, 255]
7
8 img = cv.imread('lemon.jpg')
9
10 if img is None:
11     sys.exit("could not read the image.")
12
13 hsvImage = cv.cvtColor(img, cv.COLOR_BGR2HSV)
14
15 lowerLimit, upperLimit = get_limits(color=yellow)
16
17 mask = cv.inRange(hsvImage, lowerLimit, upperLimit)
18
19 mask_ = Image.fromarray(mask)
20
21 bbox = mask_.getbbox()
22
23 if bbox is not None:
24     x1, y1, x2, y2 = bbox
25
26     img = cv.rectangle(img, (x1, y1), (x2, y2), (0,
27         255, 0), 5)
28
29 cv.imshow('Display window', img)
30 k = cv.waitKey(0)
```

Python 2 ▾ Tab Width: 8 ▾ Ln 6, Col 23 ▾ INS



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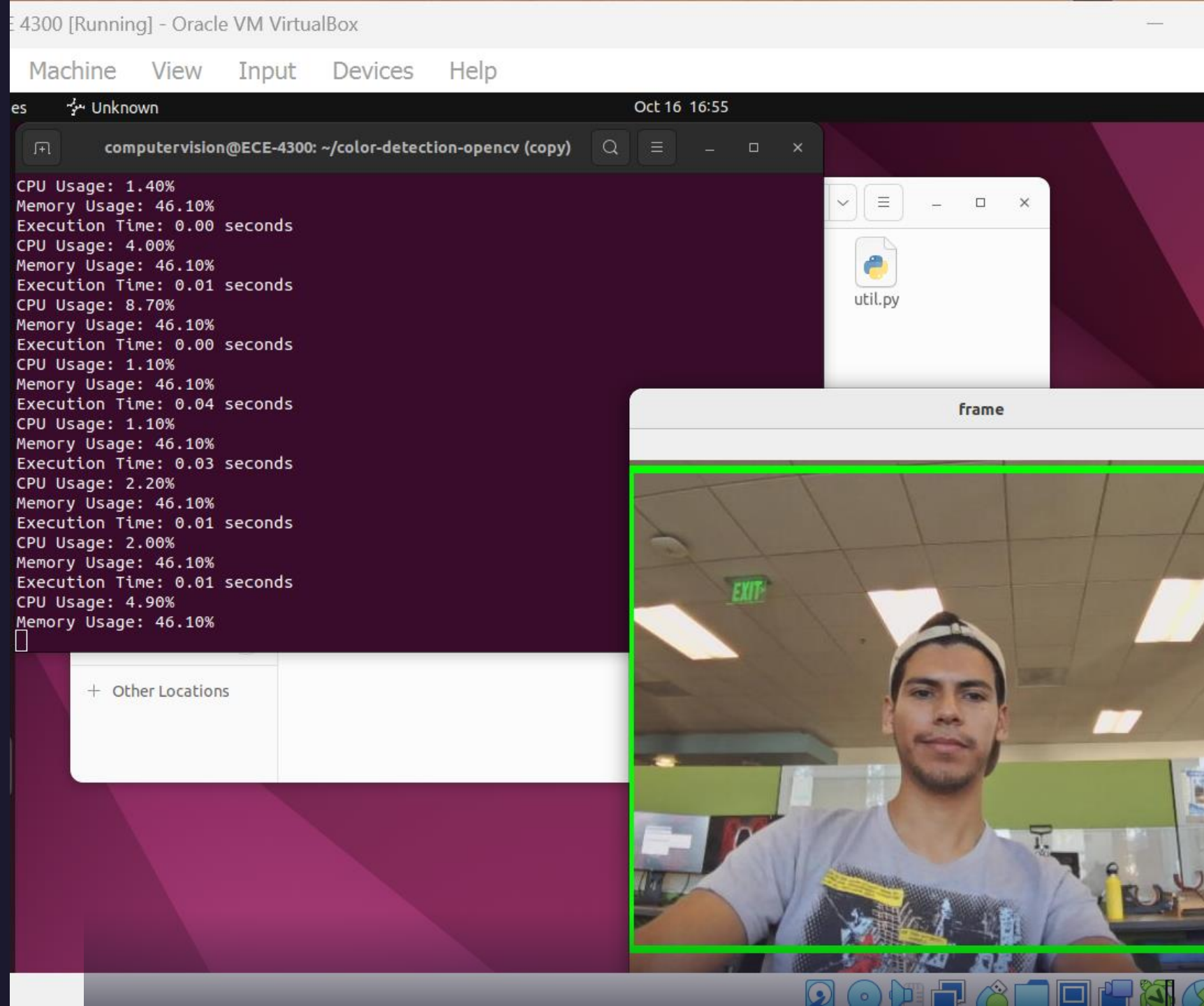
# Find Color in a Video





# Test performance of the video

- CPU Usage
- Memory Usage
- Execution time



# Progress

	HARDWARE	SET UP		TEST		
		UBUNTU	LIBRARIES	LIVE CAMERA	FIND COLOR IN IMAGE	VIDEO
VIRTUAL BOX	13th Gen Intel(R) Core(TM) i7-13700H 2.90 GHz					
	11th Gen Intel(R) Core(TM) i7-1165G7 @ 2.80GHz					
	11th Gen Intel(R) Core(TM) i7-11800H @ 2.30GHz					
	Intel(R) Core(TM) i5-7300U CPU @ 2.60GHz					
MICRO COMPUTER	Quad core Cortex-A72 (ARMv8) 64-bit SoC @ 1.8GHz					
	Quad core ARM Cortex-A53 64-bit SoC @ 1.512GHz					