

```

In[1]:= Clear["*"];

In[1]:= (*sphere/sphere collision resolver*)
p1 = {p1.x, p1.y, p1.z}; (*position*)
u1 = {u1.x, u1.y, u1.z}; (*velocity*)
r1; (*radius*)
p2 = {p2.x, p2.y, p2.z};
u2 = {u2.x, u2.y, u2.z};
r2;
Solve[EuclideanDistance[p1 + u1 t, p2 + u2 t] == r1 + r2, t]

Out[7]:= { {t -> (-2 p1.x u1.x + 2 p2.x u1.x + 2 p1.x u2.x - 2 p2.x u2.x - 2 p1.y u1.y + 2 p2.y u1.y +
2 p1.y u2.y - 2 p2.y u2.y - 2 p1.z u1.z + 2 p2.z u1.z + 2 p1.z u2.z - 2 p2.z u2.z -
sqrt((2 p1.x u1.x - 2 p2.x u1.x - 2 p1.x u2.x + 2 p2.x u2.x + 2 p1.y u1.y - 2 p2.y u1.y -
2 p1.y u2.y + 2 p2.y u2.y + 2 p1.z u1.z - 2 p2.z u1.z - 2 p1.z u2.z + 2 p2.z u2.z)^2 -
4 (p1.x^2 - 2 p1.x p2.x + p2.x^2 + p1.y^2 - 2 p1.y p2.y + p2.y^2 + p1.z^2 - 2 p1.z p2.z + p2.z^2 - r1^2 - 2 r1 r2 -
r2^2) (u1.x^2 - 2 u1.x u2.x + u2.x^2 + u1.y^2 - 2 u1.y u2.y + u2.y^2 + u1.z^2 - 2 u1.z u2.z + u2.z^2))), /
(2 (u1.x^2 - 2 u1.x u2.x + u2.x^2 + u1.y^2 - 2 u1.y u2.y + u2.y^2 + u1.z^2 - 2 u1.z u2.z + u2.z^2)) } },
{t -> (-2 p1.x u1.x + 2 p2.x u1.x + 2 p1.x u2.x - 2 p2.x u2.x - 2 p1.y u1.y + 2 p2.y u1.y +
2 p1.y u2.y - 2 p2.y u2.y - 2 p1.z u1.z + 2 p2.z u1.z + 2 p1.z u2.z - 2 p2.z u2.z +
sqrt((2 p1.x u1.x - 2 p2.x u1.x - 2 p1.x u2.x + 2 p2.x u2.x + 2 p1.y u1.y - 2 p2.y u1.y -
2 p1.y u2.y + 2 p2.y u2.y + 2 p1.z u1.z - 2 p2.z u1.z - 2 p1.z u2.z + 2 p2.z u2.z)^2 -
4 (p1.x^2 - 2 p1.x p2.x + p2.x^2 + p1.y^2 - 2 p1.y p2.y + p2.y^2 + p1.z^2 - 2 p1.z p2.z + p2.z^2 - r1^2 - 2 r1 r2 -
r2^2) (u1.x^2 - 2 u1.x u2.x + u2.x^2 + u1.y^2 - 2 u1.y u2.y + u2.y^2 + u1.z^2 - 2 u1.z u2.z + u2.z^2))), /
(2 (u1.x^2 - 2 u1.x u2.x + u2.x^2 + u1.y^2 - 2 u1.y u2.y + u2.y^2 + u1.z^2 - 2 u1.z u2.z + u2.z^2)) } } }

In[8]:= (*if overlapping pick nearest t<0, for collision detection check t>0 and t<1*)
np1 = p1 + u1 t; (*move out of collision*)
np2 = p2 + u2 t;
nml = Normalize[np1 - np2]; (*collision plane normal*)
m1; (*mass*)
m2;
(*      velocity given      velocities received along collision plane normal*)
v1 = u1 - (u1.nml) nml + (u1.nml) nml ((m1 - m2) / (m1 + m2)) + (u2.nml) nml (2 m2 / (m1 + m2));
v2 = u2 - (u2.nml) nml + (u2.nml) nml ((m2 - m1) / (m1 + m2)) + (u1.nml) nml (2 m1 / (m1 + m2));
np1 = np1 + v1 (1 - t); (*perform remaining dt with new velocities*)
np2 = np2 + v2 (1 - t);

In[17]:= v1 = (u1.nml) nml ((m1 - m2) / (m1 + m2)) + (u2.nml) nml (2 m2 / (m1 + m2));
v2 = (u2.nml) nml ((m2 - m1) / (m1 + m2)) + (u1.nml) nml (2 m1 / (m1 + m2));
m1 u1 + m2 u2 == m1 v1 + m2 v2;

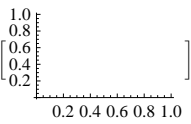
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In[20]:= (*sphere/plane collision resolver*)
p_g = {0, 0, 0}; (*dot on plane*)
n_g = Normalize[{0, 1, 0}]; (*normal*)
p = {0, 1.5, 0}; (*sphere position*)
u = {0, -1, 0}; (*velocity*)
r = 1; (*radius*)
Remove[t];
f = (p + u t - p_g).n_g - r == 0; (*signed distance to plane*)
Plot[f, {t, 0, 1}]
Solve[f, t]
t = .5;
(*pick nearest t<0, t>1 or t<0 collision is in future or past*)
np = p + u t (*move sphere out of collision*)
v = u - 2 (u.n_g) n_g (*reflect*)
np = np + v (1 - t) (*second part of dt*)

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Out[27]= $DisplayFunction[

]

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Out[28]= {{t -> -1. (-0.5 + 1. {0, 1.5, 0}_g)}}

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Out[30]= {0., 1., 0.}

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Out[31]= {0, 1, 0}

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Out[32]= {0., 1.5, 0.}

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(*simplified*)

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In[34]:= Clear["*"];

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In[1]:= (*sphere/sphere collision resolver*)

p₁ = {**p_{1.x}**, **p_{1.y}**, **p_{1.z}**}; (*position*)

u₁ = {**u_{1.x}**, **u_{1.y}**, **u_{1.z}**}; (*velocity*)

r₁; (*radius*)

p₂ = {**p_{2.x}**, **p_{2.y}**, **p_{2.z}**};

u₂ = {**u_{2.x}**, **u_{2.y}**, **u_{2.z}**};

r₂;

Solve[**EuclideanDistance**[**p₁** + **u₁** **t**, **p₂** + **u₂** **t**] == **r₁** + **r₂**, **t**]

$$\text{Out[7]} = \left\{ \left\{ t \rightarrow \left(-2 p_{1.x} u_{1.x} + 2 p_{2.x} u_{1.x} + 2 p_{1.x} u_{2.x} - 2 p_{2.x} u_{2.x} - 2 p_{1.y} u_{1.y} + 2 p_{2.y} u_{1.y} + 2 p_{1.y} u_{2.y} - 2 p_{2.y} u_{2.y} - 2 p_{1.z} u_{1.z} + 2 p_{2.z} u_{1.z} + 2 p_{1.z} u_{2.z} - 2 p_{2.z} u_{2.z} - \sqrt{\left(\left(2 p_{1.x} u_{1.x} - 2 p_{2.x} u_{1.x} - 2 p_{1.x} u_{2.x} + 2 p_{2.x} u_{2.x} + 2 p_{1.y} u_{1.y} - 2 p_{2.y} u_{1.y} - 2 p_{1.y} u_{2.y} + 2 p_{2.y} u_{2.y} + 2 p_{1.z} u_{1.z} - 2 p_{2.z} u_{1.z} - 2 p_{1.z} u_{2.z} + 2 p_{2.z} u_{2.z} \right)^2 - 4 \left(p_{1.x}^2 - 2 p_{1.x} p_{2.x} + p_{2.x}^2 + p_{1.y}^2 - 2 p_{1.y} p_{2.y} + p_{2.y}^2 + p_{1.z}^2 - 2 p_{1.z} p_{2.z} + p_{2.z}^2 - r_1^2 - 2 r_1 r_2 - r_2^2 \right) \left(u_{1.x}^2 - 2 u_{1.x} u_{2.x} + u_{2.x}^2 + u_{1.y}^2 - 2 u_{1.y} u_{2.y} + u_{2.y}^2 + u_{1.z}^2 - 2 u_{1.z} u_{2.z} + u_{2.z}^2 \right)} \right) \right\}, \right. \\ \left. \left\{ t \rightarrow \left(-2 p_{1.x} u_{1.x} + 2 p_{2.x} u_{1.x} + 2 p_{1.x} u_{2.x} - 2 p_{2.x} u_{2.x} - 2 p_{1.y} u_{1.y} + 2 p_{2.y} u_{1.y} + 2 p_{1.y} u_{2.y} - 2 p_{2.y} u_{2.y} - 2 p_{1.z} u_{1.z} + 2 p_{2.z} u_{1.z} + 2 p_{1.z} u_{2.z} - 2 p_{2.z} u_{2.z} + \sqrt{\left(\left(2 p_{1.x} u_{1.x} - 2 p_{2.x} u_{1.x} - 2 p_{1.x} u_{2.x} + 2 p_{2.x} u_{2.x} + 2 p_{1.y} u_{1.y} - 2 p_{2.y} u_{1.y} - 2 p_{1.y} u_{2.y} + 2 p_{2.y} u_{2.y} + 2 p_{1.z} u_{1.z} - 2 p_{2.z} u_{1.z} - 2 p_{1.z} u_{2.z} + 2 p_{2.z} u_{2.z} \right)^2 - 4 \left(p_{1.x}^2 - 2 p_{1.x} p_{2.x} + p_{2.x}^2 + p_{1.y}^2 - 2 p_{1.y} p_{2.y} + p_{2.y}^2 + p_{1.z}^2 - 2 p_{1.z} p_{2.z} + p_{2.z}^2 - r_1^2 - 2 r_1 r_2 - r_2^2 \right) \left(u_{1.x}^2 - 2 u_{1.x} u_{2.x} + u_{2.x}^2 + u_{1.y}^2 - 2 u_{1.y} u_{2.y} + u_{2.y}^2 + u_{1.z}^2 - 2 u_{1.z} u_{2.z} + u_{2.z}^2 \right)} \right) \right\} \right\}$$

In[8]:= **EuclideanDistance**[**p₁** + **u₁** **t**, **p₂** + **u₂** **t**]

$$\text{Out[8]} = \sqrt{\left(\text{Abs}[p_{1.x} - p_{2.x} + t u_{1.x} - t u_{2.x}]^2 + \text{Abs}[p_{1.y} - p_{2.y} + t u_{1.y} - t u_{2.y}]^2 + \text{Abs}[p_{1.z} - p_{2.z} + t u_{1.z} - t u_{2.z}]^2 \right)}$$

In[9]:= $\sqrt{\text{Total}[(p_1 + u_1 t - (p_2 + u_2 t))^2]} == r_1 + r_2$

$$\text{Out[9]} = \sqrt{\left((p_{1.x} - p_{2.x} + t u_{1.x} - t u_{2.x})^2 + (p_{1.y} - p_{2.y} + t u_{1.y} - t u_{2.y})^2 + (p_{1.z} - p_{2.z} + t u_{1.z} - t u_{2.z})^2 \right)} == r_1 + r_2$$

In[10]:= $\left(\sqrt{\text{Total}[(p_1 + u_1 t - (p_2 + u_2 t))^2]} \right)^2 == (r_1 + r_2)^2$

$$\text{Out[10]} = (p_{1.x} - p_{2.x} + t u_{1.x} - t u_{2.x})^2 + (p_{1.y} - p_{2.y} + t u_{1.y} - t u_{2.y})^2 + (p_{1.z} - p_{2.z} + t u_{1.z} - t u_{2.z})^2 == (r_1 + r_2)^2$$

In[11]:= **Total**[(**p₁** + **u₁** **t** - (**p₂** + **u₂** **t**))²] == (**r₁** + **r₂**)²

$$\text{Out[11]} = (p_{1.x} - p_{2.x} + t u_{1.x} - t u_{2.x})^2 + (p_{1.y} - p_{2.y} + t u_{1.y} - t u_{2.y})^2 + (p_{1.z} - p_{2.z} + t u_{1.z} - t u_{2.z})^2 == (r_1 + r_2)^2$$

In[12]:= **Δp** = **p₁** - **p₂**

$$\text{Out[12]} = \{p_{1.x} - p_{2.x}, p_{1.y} - p_{2.y}, p_{1.z} - p_{2.z}\}$$

In[13]:= **Collect**[**Expand**[**Total**[($\Delta p + u_1 t - u_2 t$)²] - ($r_1 + r_2$)² == 0], t]

Out[13]= $p_{1,x}^2 - 2 p_{1,x} p_{2,x} + p_{2,x}^2 + p_{1,y}^2 - 2 p_{1,y} p_{2,y} + p_{2,y}^2 + p_{1,z}^2 - 2 p_{1,z} p_{2,z} + p_{2,z}^2 - r_1^2 - 2 r_1 r_2 - r_2^2 + t (2 p_{1,x} u_{1,x} - 2 p_{2,x} u_{1,x} - 2 p_{1,x} u_{2,x} + 2 p_{2,x} u_{2,x} + 2 p_{1,y} u_{1,y} - 2 p_{2,y} u_{1,y} - 2 p_{1,y} u_{2,y} + 2 p_{2,y} u_{2,y} + 2 p_{1,z} u_{1,z} - 2 p_{2,z} u_{1,z} - 2 p_{1,z} u_{2,z} + 2 p_{2,z} u_{2,z}) + t^2 (u_{1,x}^2 - 2 u_{1,x} u_{2,x} + u_{2,x}^2 + u_{1,y}^2 - 2 u_{1,y} u_{2,y} + u_{2,y}^2 + u_{1,z}^2 - 2 u_{1,z} u_{2,z} + u_{2,z}^2) == 0$

In[14]:= **Collect**[**Expand**[**Total**[($\Delta p + (u_1 - u_2) t$)²] - ($r_1 + r_2$)² == 0], t]

Out[14]= $p_{1,x}^2 - 2 p_{1,x} p_{2,x} + p_{2,x}^2 + p_{1,y}^2 - 2 p_{1,y} p_{2,y} + p_{2,y}^2 + p_{1,z}^2 - 2 p_{1,z} p_{2,z} + p_{2,z}^2 - r_1^2 - 2 r_1 r_2 - r_2^2 + t (2 p_{1,x} u_{1,x} - 2 p_{2,x} u_{1,x} - 2 p_{1,x} u_{2,x} + 2 p_{2,x} u_{2,x} + 2 p_{1,y} u_{1,y} - 2 p_{2,y} u_{1,y} - 2 p_{1,y} u_{2,y} + 2 p_{2,y} u_{2,y} + 2 p_{1,z} u_{1,z} - 2 p_{2,z} u_{1,z} - 2 p_{1,z} u_{2,z} + 2 p_{2,z} u_{2,z}) + t^2 (u_{1,x}^2 - 2 u_{1,x} u_{2,x} + u_{2,x}^2 + u_{1,y}^2 - 2 u_{1,y} u_{2,y} + u_{2,y}^2 + u_{1,z}^2 - 2 u_{1,z} u_{2,z} + u_{2,z}^2) == 0$

In[15]:= $\Delta u = u_1 - u_2$

Out[15]= { $u_{1,x} - u_{2,x}$, $u_{1,y} - u_{2,y}$, $u_{1,z} - u_{2,z}$ }

In[16]:= **Collect**[**Expand**[**Total**[($\Delta p + \Delta u t$)²] - ($r_1 + r_2$)² == 0], t]

Out[16]= $p_{1,x}^2 - 2 p_{1,x} p_{2,x} + p_{2,x}^2 + p_{1,y}^2 - 2 p_{1,y} p_{2,y} + p_{2,y}^2 + p_{1,z}^2 - 2 p_{1,z} p_{2,z} + p_{2,z}^2 - r_1^2 - 2 r_1 r_2 - r_2^2 + t (2 p_{1,x} u_{1,x} - 2 p_{2,x} u_{1,x} - 2 p_{1,x} u_{2,x} + 2 p_{2,x} u_{2,x} + 2 p_{1,y} u_{1,y} - 2 p_{2,y} u_{1,y} - 2 p_{1,y} u_{2,y} + 2 p_{2,y} u_{2,y} + 2 p_{1,z} u_{1,z} - 2 p_{2,z} u_{1,z} - 2 p_{1,z} u_{2,z} + 2 p_{2,z} u_{2,z}) + t^2 (u_{1,x}^2 - 2 u_{1,x} u_{2,x} + u_{2,x}^2 + u_{1,y}^2 - 2 u_{1,y} u_{2,y} + u_{2,y}^2 + u_{1,z}^2 - 2 u_{1,z} u_{2,z} + u_{2,z}^2) == 0$

In[17]:= **Collect**[**Expand**[**Total**[$\Delta p^2 + 2 \Delta p \Delta u t + \Delta u^2 t^2$] - ($r_1 + r_2$)² == 0], t]

Out[17]= $p_{1,x}^2 - 2 p_{1,x} p_{2,x} + p_{2,x}^2 + p_{1,y}^2 - 2 p_{1,y} p_{2,y} + p_{2,y}^2 + p_{1,z}^2 - 2 p_{1,z} p_{2,z} + p_{2,z}^2 - r_1^2 - 2 r_1 r_2 - r_2^2 + t (2 p_{1,x} u_{1,x} - 2 p_{2,x} u_{1,x} - 2 p_{1,x} u_{2,x} + 2 p_{2,x} u_{2,x} + 2 p_{1,y} u_{1,y} - 2 p_{2,y} u_{1,y} - 2 p_{1,y} u_{2,y} + 2 p_{2,y} u_{2,y} + 2 p_{1,z} u_{1,z} - 2 p_{2,z} u_{1,z} - 2 p_{1,z} u_{2,z} + 2 p_{2,z} u_{2,z}) + t^2 (u_{1,x}^2 - 2 u_{1,x} u_{2,x} + u_{2,x}^2 + u_{1,y}^2 - 2 u_{1,y} u_{2,y} + u_{2,y}^2 + u_{1,z}^2 - 2 u_{1,z} u_{2,z} + u_{2,z}^2) == 0$

In[18]:= **Collect**[**Total**[$\Delta p^2 + 2 \Delta p \Delta u t + \Delta u^2 t^2$] - ($r_1 + r_2$)² == 0, t]

Out[18]= $(p_{1,x} - p_{2,x})^2 + (p_{1,y} - p_{2,y})^2 + (p_{1,z} - p_{2,z})^2 - (r_1 + r_2)^2 + t (2 (p_{1,x} - p_{2,x}) (u_{1,x} - u_{2,x}) + 2 (p_{1,y} - p_{2,y}) (u_{1,y} - u_{2,y}) + 2 (p_{1,z} - p_{2,z}) (u_{1,z} - u_{2,z})) + t^2 ((u_{1,x} - u_{2,x})^2 + (u_{1,y} - u_{2,y})^2 + (u_{1,z} - u_{2,z})^2) == 0$

In[19]:= **Total**[Δp^2]

Out[19]= $(p_{1,x} - p_{2,x})^2 + (p_{1,y} - p_{2,y})^2 + (p_{1,z} - p_{2,z})^2$

In[20]:= **Collect**[**Expand**[**Total**[Δp^2] - ($r_1 + r_2$)² + $t (2 (p_{1,x} - p_{2,x}) (u_{1,x} - u_{2,x}) + 2 (p_{1,y} - p_{2,y}) (u_{1,y} - u_{2,y}) + 2 (p_{1,z} - p_{2,z}) (u_{1,z} - u_{2,z})) + t^2 ((u_{1,x} - u_{2,x})^2 + (u_{1,y} - u_{2,y})^2 + (u_{1,z} - u_{2,z})^2)$] == 0], t]

Out[20]= $p_{1,x}^2 - 2 p_{1,x} p_{2,x} + p_{2,x}^2 + p_{1,y}^2 - 2 p_{1,y} p_{2,y} + p_{2,y}^2 + p_{1,z}^2 - 2 p_{1,z} p_{2,z} + p_{2,z}^2 - r_1^2 - 2 r_1 r_2 - r_2^2 + t (2 p_{1,x} u_{1,x} - 2 p_{2,x} u_{1,x} - 2 p_{1,x} u_{2,x} + 2 p_{2,x} u_{2,x} + 2 p_{1,y} u_{1,y} - 2 p_{2,y} u_{1,y} - 2 p_{1,y} u_{2,y} + 2 p_{2,y} u_{2,y} + 2 p_{1,z} u_{1,z} - 2 p_{2,z} u_{1,z} - 2 p_{1,z} u_{2,z} + 2 p_{2,z} u_{2,z}) + t^2 (u_{1,x}^2 - 2 u_{1,x} u_{2,x} + u_{2,x}^2 + u_{1,y}^2 - 2 u_{1,y} u_{2,y} + u_{2,y}^2 + u_{1,z}^2 - 2 u_{1,z} u_{2,z} + u_{2,z}^2) == 0$

In[21]:= $2 \Delta p \cdot \Delta u t$

Out[21]= $2 t ((p_{1,x} - p_{2,x}) (u_{1,x} - u_{2,x}) + (p_{1,y} - p_{2,y}) (u_{1,y} - u_{2,y}) + (p_{1,z} - p_{2,z}) (u_{1,z} - u_{2,z}))$

```
In[22]:= Collect[Expand[
  Total[Δp2] - (r1 + r2)2 + 2 Δp.Δu t + t2 ((u1.x - u2.x)2 + (u1.y - u2.y)2 + (u1.z - u2.z)2) == 0], t]
```

```
Out[22]= p1,x2 - 2 p1,x p2,x + p2,x2 + p1,y2 - 2 p1,y p2,y + p2,y2 + p1,z2 - 2 p1,z p2,z + p2,z2 - r12 - 2 r1 r2 -
  r22 + t (2 p1,x u1,x - 2 p2,x u1,x - 2 p1,x u2,x + 2 p2,x u2,x + 2 p1,y u1,y - 2 p2,y u1,y -
  2 p1,y u2,y + 2 p2,y u2,y + 2 p1,z u1,z - 2 p2,z u1,z - 2 p1,z u2,z + 2 p2,z u2,z) +
  t2 (u1,x2 - 2 u1,x u2,x + u2,x2 + u1,y2 - 2 u1,y u2,y + u2,y2 + u1,z2 - 2 u1,z u2,z + u2,z2) == 0
```

```
In[23]:= Total[Δu2]
```

```
Out[23]= (u1,x - u2,x)2 + (u1,y - u2,y)2 + (u1,z - u2,z)2
```

```
In[24]:= Collect[Expand[Total[Δp2] - (r1 + r2)2 + 2 Δp.Δu t + t2 Total[Δu2] == 0], t]
```

```
Out[24]= p1,x2 - 2 p1,x p2,x + p2,x2 + p1,y2 - 2 p1,y p2,y + p2,y2 + p1,z2 - 2 p1,z p2,z + p2,z2 - r12 - 2 r1 r2 -
  r22 + t (2 p1,x u1,x - 2 p2,x u1,x - 2 p1,x u2,x + 2 p2,x u2,x + 2 p1,y u1,y - 2 p2,y u1,y -
  2 p1,y u2,y + 2 p2,y u2,y + 2 p1,z u1,z - 2 p2,z u1,z - 2 p1,z u2,z + 2 p2,z u2,z) +
  t2 (u1,x2 - 2 u1,x u2,x + u2,x2 + u1,y2 - 2 u1,y u2,y + u2,y2 + u1,z2 - 2 u1,z u2,z + u2,z2) == 0
```

```
In[29]:= a = Total[Δu2];
```

```
b = 2 Δp.Δu;
```

```
c = Total[Δp2] - (r1 + r2)2;
```

```
Collect[Expand[a t2 + b t + c == 0], t]
```

```
Solve[a t2 + b t + c == 0, t]
```

```
Out[32]= p1,x2 - 2 p1,x p2,x + p2,x2 + p1,y2 - 2 p1,y p2,y + p2,y2 + p1,z2 - 2 p1,z p2,z + p2,z2 - r12 - 2 r1 r2 -
  r22 + t (2 p1,x u1,x - 2 p2,x u1,x - 2 p1,x u2,x + 2 p2,x u2,x + 2 p1,y u1,y - 2 p2,y u1,y -
  2 p1,y u2,y + 2 p2,y u2,y + 2 p1,z u1,z - 2 p2,z u1,z - 2 p1,z u2,z + 2 p2,z u2,z) +
  t2 (u1,x2 - 2 u1,x u2,x + u2,x2 + u1,y2 - 2 u1,y u2,y + u2,y2 + u1,z2 - 2 u1,z u2,z + u2,z2) == 0
```

```
Out[33]= {{t -> (-2 p1,x u1,x + 2 p2,x u1,x + 2 p1,x u2,x - 2 p2,x u2,x - 2 p1,y u1,y + 2 p2,y u1,y +
  2 p1,y u2,y - 2 p2,y u2,y - 2 p1,z u1,z + 2 p2,z u1,z + 2 p1,z u2,z - 2 p2,z u2,z -
  √((2 p1,x u1,x - 2 p2,x u1,x - 2 p1,x u2,x + 2 p2,x u2,x + 2 p1,y u1,y - 2 p2,y u1,y -
  2 p1,y u2,y + 2 p2,y u2,y + 2 p1,z u1,z - 2 p2,z u1,z - 2 p1,z u2,z + 2 p2,z u2,z)2 -
  4 (p1,x2 - 2 p1,x p2,x + p2,x2 + p1,y2 - 2 p1,y p2,y + p2,y2 + p1,z2 - 2 p1,z p2,z + p2,z2 - r12 - 2 r1 r2 -
  r22) (u1,x2 - 2 u1,x u2,x + u2,x2 + u1,y2 - 2 u1,y u2,y + u2,y2 + u1,z2 - 2 u1,z u2,z + u2,z2)))/
  (2 (u1,x2 - 2 u1,x u2,x + u2,x2 + u1,y2 - 2 u1,y u2,y + u2,y2 + u1,z2 - 2 u1,z u2,z + u2,z2))}},
  {t -> (-2 p1,x u1,x + 2 p2,x u1,x + 2 p1,x u2,x - 2 p2,x u2,x - 2 p1,y u1,y + 2 p2,y u1,y +
  2 p1,y u2,y - 2 p2,y u2,y - 2 p1,z u1,z + 2 p2,z u1,z + 2 p1,z u2,z - 2 p2,z u2,z +
  √((2 p1,x u1,x - 2 p2,x u1,x - 2 p1,x u2,x + 2 p2,x u2,x + 2 p1,y u1,y - 2 p2,y u1,y -
  2 p1,y u2,y + 2 p2,y u2,y + 2 p1,z u1,z - 2 p2,z u1,z - 2 p1,z u2,z + 2 p2,z u2,z)2 -
  4 (p1,x2 - 2 p1,x p2,x + p2,x2 + p1,y2 - 2 p1,y p2,y + p2,y2 + p1,z2 - 2 p1,z p2,z + p2,z2 - r12 - 2 r1 r2 -
  r22) (u1,x2 - 2 u1,x u2,x + u2,x2 + u1,y2 - 2 u1,y u2,y + u2,y2 + u1,z2 - 2 u1,z u2,z + u2,z2)))/
  (2 (u1,x2 - 2 u1,x u2,x + u2,x2 + u1,y2 - 2 u1,y u2,y + u2,y2 + u1,z2 - 2 u1,z u2,z + u2,z2))}}}
```