

```

In[103]:= ms = {{sx, 0, 0, 0}, {0, sy, 0, 0}, {0, 0, sz, 0}, {0, 0, 0, 1}}
Out[103]= {{sx, 0, 0, 0}, {0, sy, 0, 0}, {0, 0, sz, 0}, {0, 0, 0, 1}}

In[104]:= mrz = {{cosz, -sinz, 0, 0}, {sinz, cosz, 0, 0}, {0, 0, 1, 0}, {0, 0, 0, 1}}
Out[104]= {{cosz, -sinz, 0, 0}, {sinz, cosz, 0, 0}, {0, 0, 1, 0}, {0, 0, 0, 1}}

In[105]:= mt = {{1, 0, 0, 0}, {0, 1, 0, 0}, {0, 0, 1, 0}, {tx, ty, tz, 1}}
Out[105]= {{1, 0, 0, 0}, {0, 1, 0, 0}, {0, 0, 1, 0}, {tx, ty, tz, 1}}

In[106]:= v = {x, y, z, 1}
Out[106]= {x, y, z, 1}

In[107]:= v.ms.mrz.mt
Out[107]= {tx + cosz sx x + sinz sy y, ty - sinz sx x + cosz sy y, tz + sz z, 1}

In[108]:= mmw = ms.mrz.mt
Out[108]= {{cosz sx, -sinz sx, 0, 0}, {sinz sy, cosz sy, 0, 0}, {0, 0, sz, 0}, {tx, ty, tz, 1}}

In[109]:= v.mmw
Out[109]= {tx + cosz sx x + sinz sy y, ty - sinz sx x + cosz sy y, tz + sz z, 1}

In[110]:= ms.mrz.mt // MatrixForm
Out[110]//MatrixForm=

$$\begin{pmatrix} \cos z \, s_x & -\sin z \, s_x & 0 & 0 \\ \sin z \, s_y & \cos z \, s_y & 0 & 0 \\ 0 & 0 & s_z & 0 \\ t_x & t_y & t_z & 1 \end{pmatrix}$$


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