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Problem 1. Consider the advection equation

$$u_t + au_x = 0$$

on the interval [0,1) with periodic boundary conditions. Space is discretized as  $x_j = j\Delta x$  for j = 0, ..., N-1, so that  $\Delta x = 1/N$ . Discretize the spatial derivative with the second-order centered difference operator.

(a) For simplicity, assume N is odd. The eigenvectors of the centered difference operator are

$$v_i^k = \exp(2\pi i k x_j),$$

for  $k = -(N-1)/2, \dots, (N-1)/2$ . Compute the eigenvalues.

⇒ With centered difference operator

$$Du_j = \frac{u_{j+1} - u_{j-1}}{2\Delta x},$$

we have that

$$Dv_j^k = \lambda_k v_j^k$$

$$\frac{v_{j+1}^k - v_{j-1}^k}{2\Delta X} = \lambda_k v_j^k$$

$$\frac{e^{2\pi i k(x_j + \Delta x)} - e^{2\pi i k(x_j - \Delta x)}}{2\Delta x} = \lambda_k v_j^k$$

$$\left(\frac{e^{2\pi i k\Delta x} - e^{-2\pi i k\Delta x}}{2\Delta x}\right) v_j^k = \lambda_k v_j^k$$

$$\left(\frac{i \sin(2\pi k\Delta x)}{\Delta x}\right) v_j^k = \lambda_k v_j^k.$$

Hence the eigenvalues are

$$\lambda_k = \frac{i \sin(2\pi k \Delta x)}{\Delta x}.$$

(b) Derive a time step restriction on a method-of-lines approach which uses classical fourth-order Runge-Kutta for time stepping.

The fourth-order Runge-Kutta scheme applied to  $y' = \lambda y$  is

$$\begin{aligned} y_1^* &= y^n \\ y_2^* &= y^n \left( 1 + \frac{\Delta t}{2} \lambda \right) \\ y_3^* &= y^n \left( 1 + \frac{\Delta t}{2} \lambda \left( 1 + \frac{\Delta t}{2} \lambda \right) \right) \\ y_4^* &= y^n \left( 1 + \Delta t \lambda \left( 1 + \frac{\Delta t}{2} \lambda \left( 1 + \frac{\Delta t}{2} \lambda \right) \right) \right) \end{aligned}$$

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$$y^{n+1} = y^n + \frac{\Delta t \lambda}{6} (y_1^* + 2y_2^* + 2y_3^* + y_4^*)$$
  
=  $y^n \left( 1 + \Delta t \lambda + \frac{(\Delta t \lambda)^2}{2} + \frac{(\Delta t \lambda)^3}{3!} + \frac{(\Delta t \lambda)^4}{4!} \right).$ 

So for  $z = \Delta t \lambda$ , the region of stability for the 4<sup>th</sup> order Runge-Kutta scheme is

$$\left|1 + z + z^2/2 + z^3/3! + z^4/4!\right| \le 1.$$

This translates to

$$Re(z) = 0, -2\sqrt{2} < Im(z) < 2\sqrt{2},$$

and since z is pure imaginary,

$$z = \Delta t \lambda = i \frac{\Delta t}{\Delta x} \sin(2\pi k \Delta x)$$
, and also  $|z| \le 1$ ,

we have the requirement that

$$\Delta t \le 2\sqrt{2}\Delta x$$

for z to be in the region of stability and the scheme to be stable.

Problem 2. Consider the following PDE

$$u_t = 0.01u_{xx} + 1 - \exp(-t), \ 0 < x < 1$$
  
 $u(0,t) = 0, \ u(1,t) = 0$   
 $u(x,0) = 0.$ 

Write a program to solve the problem using Crank-Nicolson up to time t=1, and perform a refinement study that demonstrates that the method is second-order accurate in space and time.

**Problem 3.** Consider the following PDE

$$u_t = u_{xx}, \quad 0 < x < 1$$

$$u(0,t) = 1, \quad u(1,t) = 0$$

$$u(x,0) = \begin{cases} 1, & \text{if } x < 0.5\\ 0, & \text{if } x \ge 0.5. \end{cases}$$

- (a) Use Crank-Nicolson with grid spacing  $\Delta x = 0.02$  and time step  $\Delta t = 0.1$  to solve the problem up to time t = 1. Comment on your results. What is wrong with this solution?
- (b) Give a mathematical argument to explain the unphysical behavior you observed in the numerical solution.
- (c) Repeat the simulation using BDF2, and discuss why the unphysical behavior is not present in the numerical solution for any time step.