Linear Algebra Review 1 MAT 442

Colin Moore

Nov 2020

Vector Spaces

A vector space V over a field F has the following properties:

- 1. $\forall x, y \in V$, x + y = y + x
- 2. $\forall x, y, z \in V$, (x + y) + z = x + (y + z)
- 3. There exists an element in V, denoted by 0, such that $\forall x \in V, x+0=x$
- 4. $\forall x \in V, \exists y \in V \text{ such that } x + y = 0$
- 5. $\forall x \in V, 1 \cdot x = x$
- 6. $\forall \alpha, \beta \in F \text{ and } \forall x \in V, (\alpha \beta)x = \alpha(\beta x)$
- 7. $\forall \alpha \in F \text{ and } \forall x, y \in V, \ \alpha(x+y) = \alpha x + \alpha y$
- 8. $\forall \alpha, \beta \in F$, and $\forall x \in V$, $(\alpha + \beta)x = \alpha x + \beta x$

Remark

Vector multiplication need not be defined. Only scalar multiplication and vector addition are required.

Colin Moore Linear Algebra Review 1 Nov 2020 2 / 15

Vector Spaces

Thereom

Let V be a vector space and W a subset of V. Then W is a subspace of V if and only if:

- 1. 0 ∈ *W*
- 2. $x + y \in W$ whenever $x, y \in W$
- 3. $\alpha x \in W$ whenever $\alpha \in F$ and $x \in W$
 - Is the intersection of subspaces of a vector space V a subspace of V?
- Is the union of subspaces of a vector space V a subspace of V?

Colin Moore Linear Algebra Review 1 Nov 2020 3 / 15

Definiton: Let V and W be vector spaces over F. We call a function $T:V\to W$ a **linear transformation from V to W** if, $\forall x,y\in V$ and $\forall \alpha\in F$, we have:

- 1. T(x + y) = T(x) + T(y)
- 2. $T(\alpha x) = \alpha T(x)$
- If T is linear, then T(0) = 0
- To show that a given transformation is linear, it is enough to prove that $T(\alpha x + y) = \alpha T(x) + T(y)$

Problem: Is the following transformation T: $V \rightarrow V$ linear?

$$T(A) = A^t$$
 with $F = \mathbb{C}, V = Mat_2(\mathbb{C})$



Colin Moore

Definition: Let V and W be vector spaces and let T: $V \to V$ be linear. We define the **null space** (or **kernel**) of T as:

$$N(T) = \{x \in V : T(x) = 0\}$$

We define the range (or image) of T as:

$$R(T) = \{T(x) : x \in V\}$$

or in other words:

$$R(T) = \{ y \in W : T(x) = y \}$$

Important note: N(T) is a subspace of V while R(T) is a subspace of W

Problem: Find N(T) and R(T) for a linear transformation T: $R^3 \to R^2$ defined by

$$T(a_1, a_2, a_3) = (a_1 - a_2, 2a_3)$$

<□ > <□ > <□ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Theorem

Let V and W be vector spaces, and let T: V \rightarrow W be linear. If $\beta = \{v_1, v_2, ..., v_n\}$ is a basis for V, then

$$R(T) = \text{span}(T(\beta)) = \text{span}(\{T(v_1), T(v_2), ..., T(v_n)\})$$

Example: Let T: $R^3 \to R^3$ be defined by T(a, b, c) = (a+b, 2b, 0). Find a basis for R(T).

Using the standard basis for R^3 , we see

$$R(T) = span(\{T(1,0,0), T(0,1,0), T(0,0,1)\})$$

$$= span(\{(1,0,0), (1,2,0), (0,0,0)\})$$

$$= span(\{(1,0,0), (1,2,0)\})$$

◆ロ > ◆母 > ◆ き > ◆き > き の < ○</p>

Dimension Theorem

Let V and W be vector spaces, and let T: V \rightarrow W be linear. If V is finite-dimensional, then

$$\operatorname{nullity}(\mathsf{T}) + \operatorname{rank}(\mathsf{T}) = \operatorname{dim}(\mathsf{V})$$

Proof:

- Suppose dim(V) = n, dim(N(T)) = k, define a basis for N(T) as $\{v_1, ..., v_k\}$
- \blacktriangleright Extend to a basis for V, so $\beta = \{v_1, ..., v_k, v_{k+1}, ..., v_n\}$
- ► Claim $S = \{T(v_{k+1}), T(v_{k+2}), ..., T(v_n)\}$ is a basis for R(T)
- ▶ $T(v_i) = 0$ for $1 \le i \le k$ since v_i comes from the null space of T, thus

$$R(T) = \operatorname{span}(T(\beta)) = \operatorname{span}(\{T(v_1), ..., T(v_n)\})$$

$$= \operatorname{span}(\{0, ..., T(v_{k+1}), T(v_{k+2}), ..., T(v_n)\})$$

$$= \operatorname{span}(\{T(v_{k+1}), T(v_{k+2}), ..., T(v_n)\})$$

Colin Moore Linear Algebra Review 1 Nov 2020 7/15

Proof (cont):

- Correct number of vectors, need to check for linear independence. Suppose we have $b_{k+1}T(v_{k+1}) + b_{k+2}T(v_{k+2}) + ... + b_nT(v_n) = 0$
- ► T is linear, thus $T(b_{k+1}v_{k+1} + b_{k+2}v_{k+2} + ...b_nv_n) = 0$
- ► Hence $b_{k+1}v_{k+1} + b_{k+2}v_{k+2} + ... b_n v_n \in N(T)$
- ▶ $\{v_1, v_2, ..., v_k\}$ is a basis for N(T), so $\exists \mu_1, ... \mu_k \in F$ such that $b_{k+1}v_{k+1} + ... + b_nv_n = \mu_1v_1 + ... + \mu_kv_k$
- Rewrite as $\mu_1 v_1 + ... + \mu_k v_k b_{k+1} v_{k+1} ... b_n v_n = 0$
- ▶ But notice that $\{v_1, ..., v_k, v_{k+1}, ..., v_n\} = \beta$, a basis for V. Thus $b_i = 0$ for all i. Thus S is linearly independent.
- ightharpoonup S spans R(T) and is linearly independent, thus it is a basis for R(T)
- ▶ Therefore rank T = k n



Definition: Let $\beta = \{u_1, u_2, ..., u_n\}$ be an ordered basis for a finite dimensional vector space V. For $x \in V$ we can represent x as a linear combination of β with $a_i \in F$:

$$x = a_1u_1 + a_2u_2 + ... + a_nu_n$$

We define the **coordinate vector of** x **relative to** β , denoted $[x]_{\beta}$, by

$$[x]_{\beta} = (a_1, a_2, ..., a_n)^t$$

Definition

We call the m×n matrix A defined by $A_{ij}=a_{ij}$ the matrix representation of T in the ordered bases β and γ and write $A=[T]_{\beta}^{\gamma}$

Note that the jth column of A is $[T(v_j)]_{\beta}$



Nov 2020

9 / 15

Colin Moore Linear Algebra Review 1

Example: Let $T: R^2 \to R^3$ be the linear transformation defined by

$$T(a_1, a_2) = (0, 2a_1 + 2a_2, a_1 - 3a_2)$$

Let β and γ be the standard ordered bases for R^2 and R^3 respectively

$$T(1,0)=(0,2,1)$$

$$T(0,1) = (0,2,-3)$$

Thus the matrix representation of T is

$$[T]^{\gamma}_{\beta} = \begin{pmatrix} 0 & 0 \\ 2 & 2 \\ 1 & -3 \end{pmatrix}$$

< ロト < 個 ト < 重 ト < 重 ト 三 重 ・ の Q @

10 / 15

Problem: Let T: $\mathbb{R}^2 \to \mathbb{R}^3$ be given by $\mathsf{T}(x,y) = (x-y,\ y,\ 2x+y)$ Let $A = \{(1,2),(2,3)\}$ and $B = \{(1,1,0),(0,1,1),(2,2,3)\}$. Find

- \bullet $[T]_A^B$
- a basis for ker(T)
- a basis for range(T)



Colin Moore Linear Algebra Review 1 Nov 2020 11 / 15

Theorem

Let V and W be finite-dimensional vector spaces having ordered bases β and γ , respectively, and let T: V \rightarrow W be linear. Then, for each $u \in V$, we have

$$[T(u)]_{\gamma} = [T]_{\beta}^{\gamma} [u]_{\beta}$$

Colin Moore Linear Algebra Review 1 Nov 2020 12 / 15

Example: Let T: $P_3(\mathbb{R}) \to P_2(\mathbb{R})$ be the linear transformation defined by T(f(x)) = f'(x). Let $\beta = \{1, x, x^2, x^3\}$ and let $\gamma = \{1, x, x^2\}$. Then

$$A = [T]_{\beta}^{\gamma} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{pmatrix}$$

Let $u(x) = 4 + x + 3x^2 + x^3$. Then

$$[T(u)]_{\gamma} = [1 + 6x + 3x^2]_{\gamma} = (1, 6, 3)^t$$

But also note

$$[T]^{\gamma}_{\beta}[u]_{\beta} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{pmatrix} \begin{pmatrix} 4 \\ 1 \\ 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 6 \\ 3 \end{pmatrix}$$

Invertibility

Theorem

Let V and W be *finite-dimensional* vector spaces with ordered bases β and γ , respectively. Let T: V \to W be linear. Then T is invertible if and only if $[T]_{\beta}^{\gamma}$ is invertible. Furthermore, $[T^{-1}]_{\gamma}^{\beta} = ([T]_{\beta}^{\gamma})^{-1}$

Problem: Let $T: P_1(R) \to R^2$ be the linear transformation defined by T(a+bx)=(a,a+b). Given β,γ to be the standard ordered bases for $P_1(R)$ and R^2 respectively, find $T^{-1},[T]^{\gamma}_{\beta}$, and $[T^{-1}]^{\beta}_{\gamma}$.

<ロト < 個 ト < 重 ト < 重 ト 三 重 の < で

Colin Moore Linear Algebra Review 1 Nov 2020 14 / 15

Quotient Spaces

Definition

Let W be a subspace of a vector space V. For any $v \in V$, the set $\{v\} + W = \{v + w : w \in W\}$ is called the **coset** of W **containing** v. We define the **quotient space** of V modulo W using the following operations:

$$(x+W) + (y+W) = (x+y) + W$$
$$\alpha(x+W) = (\alpha x) + W$$

Problem: Show that x + W = y + W if and only if $x - y \in W$

Problem: Let $V = \{a_0 + a_1X + ... + a_3X^3 : a_j \in \mathbb{Q}\}$, a vector space over \mathbb{Q} under the usual polynomial addition and scalar multiplication. Let $W = \text{span}(\{x+1,2x-1,x^2+x\})$. Find a spanning set for V/W.

15 / 15