Large-Scale Optimization Algorithms for Sparse Conditional Gaussian Graphical Models



computation

no memory

restriction

few cache misses on

off-diagonal blocks

no column

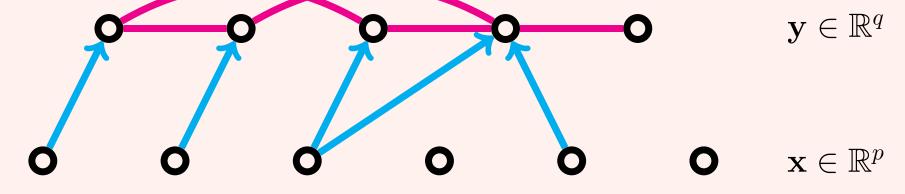
Calvin McCarter & Seyoung Kim

Motivation

Sparse Conditional Gaussian Graphical Model

$$p(\mathbf{y}|\mathbf{x}; \mathbf{\Lambda}, \mathbf{\Theta}) = \exp\{-\mathbf{y}^T \mathbf{\Lambda} \mathbf{y} - 2\mathbf{x}^T \mathbf{\Theta} \mathbf{y}\}/Z(\mathbf{x})$$
$$Z(\mathbf{x}) = (2\pi)^{q/2} |\mathbf{\Lambda}|^{-1} \exp(\mathbf{x}^T \mathbf{\Theta} \mathbf{\Lambda}^{-1} \mathbf{\Theta}^T \mathbf{x})$$

$$\mathbf{y} \in \mathbb{R}^q$$



Sparse Estimation

Given empirical covariances: $\mathbf{S}_{\mathbf{x}\mathbf{x}} \in \mathbb{R}^{p \times p}, \mathbf{S}_{\mathbf{x}\mathbf{y}} = \in \mathbb{R}^{p \times q}, \mathbf{S}_{\mathbf{y}\mathbf{y}} = \in \mathbb{R}^{q \times q}$

$$\min_{\mathbf{\Lambda}\succ 0,\mathbf{\Theta}} f(\mathbf{\Lambda},\mathbf{\Theta}) = g(\mathbf{\Lambda},\mathbf{\Theta}) + h(\mathbf{\Lambda},\mathbf{\Theta})$$

$$g(\mathbf{\Lambda}, \mathbf{\Theta}) = -\log |\mathbf{\Lambda}| + \operatorname{tr}(\mathbf{S}_{\mathbf{y}\mathbf{y}}\mathbf{\Lambda} + 2\mathbf{S}_{\mathbf{x}\mathbf{y}}^T\mathbf{\Theta} + \mathbf{\Lambda}^{-1}\mathbf{\Theta}^T\mathbf{S}_{\mathbf{x}\mathbf{x}}\mathbf{\Theta})$$

 $h(\mathbf{\Lambda}, \mathbf{\Theta}) = \lambda_{\mathbf{\Lambda}} \|\mathbf{\Lambda}\|_1 + \lambda_{\mathbf{\Theta}} \|\mathbf{\Theta}\|_1$

Convex but difficult problem due to last term

Previous Optimization Algorithms

- > OWL-QN [1]
- > FISTA [2]
- Newton Coordinate Descent [3]
 - Second order approximation minimized over active set
 - Proximal Newton subproblem solved via coordinate descent
 - Step size found via backtracking

Second order approximation on both Λ and Θ

$$\bar{g}_{\mathbf{\Lambda},\mathbf{\Theta}}(\Delta_{\mathbf{\Lambda}}, \Delta_{\mathbf{\Theta}}) = \operatorname{vec}(\nabla g(\mathbf{\Lambda}, \mathbf{\Theta}))^{T} \operatorname{vec}([\Delta_{\mathbf{\Lambda}} \Delta_{\mathbf{\Theta}}]) \\
+ \frac{1}{2} \operatorname{vec}([\Delta_{\mathbf{\Lambda}} \Delta_{\mathbf{\Theta}}])^{T} \nabla^{2} g(\mathbf{\Lambda}, \mathbf{\Theta}) \operatorname{vec}([\Delta_{\mathbf{\Lambda}} \Delta_{\mathbf{\Theta}}])$$

Scalability Problems

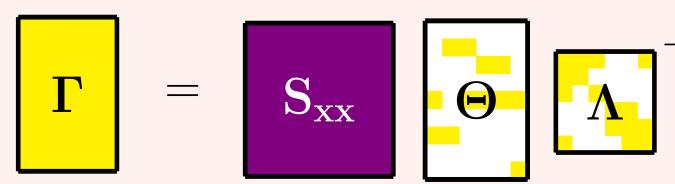
Genomic dataset with p = 34k, q = 10k: > 50 hours Time:

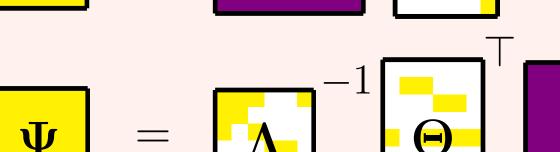
Memory: Requires $O(pq+q^2)$ memory: >100 Gb when p+q=80k

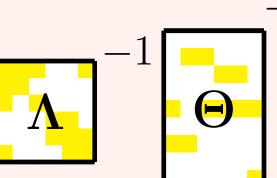
$$\nabla g(\mathbf{\Lambda}, \mathbf{\Theta}) = \begin{bmatrix} \mathbf{S}_{\mathbf{y}\mathbf{y}} - \mathbf{\Sigma} - \mathbf{\Psi} & 2\mathbf{S}_{\mathbf{x}\mathbf{y}} + 2\mathbf{\Gamma} \end{bmatrix}$$

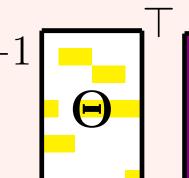
$$\nabla^2 g(\mathbf{\Lambda}, \mathbf{\Theta}) = \begin{bmatrix} \mathbf{\Sigma} \otimes (\mathbf{\Sigma} + 2\mathbf{\Psi}) & -2\mathbf{\Sigma} \otimes \mathbf{\Gamma}^T \\ -2\mathbf{\Sigma} \otimes \mathbf{\Gamma} & 2\mathbf{\Sigma} \otimes \mathbf{S}_{\mathbf{x}\mathbf{x}} \end{bmatrix}$$

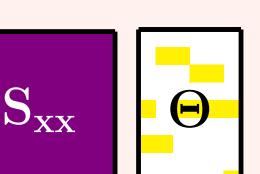
$$\Sigma$$
 = Λ

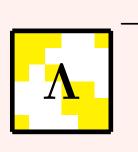












Alternating Newton Coordinate Descent

Update Λ given fixed Θ:

 Solve for Newton direction via CD $\bar{g}_{\boldsymbol{\Lambda},\boldsymbol{\Theta}}(\Delta_{\boldsymbol{\Lambda}}) = \text{vec}(\nabla_{\boldsymbol{\Lambda}}g(\boldsymbol{\Lambda},\boldsymbol{\Theta}))^T \text{vec}(\Delta_{\boldsymbol{\Lambda}}) + \frac{1}{2} \text{vec}(\Delta_{\boldsymbol{\Lambda}})^T \nabla_{\boldsymbol{\Lambda}}^2 g(\boldsymbol{\Lambda},\boldsymbol{\Theta}) \text{vec}(\Delta_{\boldsymbol{\Lambda}}) \text{vec}(\Delta_{\boldsymbol{\Lambda}})^T \nabla_{\boldsymbol{\Lambda}}^2 g(\boldsymbol{\Lambda},\boldsymbol{\Theta}) \text{vec}(\Delta_{\boldsymbol{\Lambda}}) \text{vec}(\Delta_{\boldsymbol{\Lambda}}) \text{vec}(\Delta_{\boldsymbol{\Lambda}})^T \nabla_{\boldsymbol{\Lambda}}^2 g(\boldsymbol{\Lambda},\boldsymbol{\Theta}) \text{vec}(\Delta_{\boldsymbol{\Lambda}}) \text{vec}(\Delta_{\boldsymbol{\Lambda}}$

Run backtracking line search

Update Θ given fixed Λ:

Solve Lasso problem directly via CD

$$g_{\Lambda}(\boldsymbol{\Theta}) = \operatorname{tr}(2\mathbf{S}_{\mathbf{x}\mathbf{y}}^T \boldsymbol{\Theta} + \boldsymbol{\Lambda}^{-1} \boldsymbol{\Theta}^T \mathbf{S}_{\mathbf{x}\mathbf{x}} \boldsymbol{\Theta})$$

Second order approximation only on \(\Lambda\)

- Eliminate **F**
- ✓ Reduce CD time complexity
- Backtrack only for ∧ faster early convergence

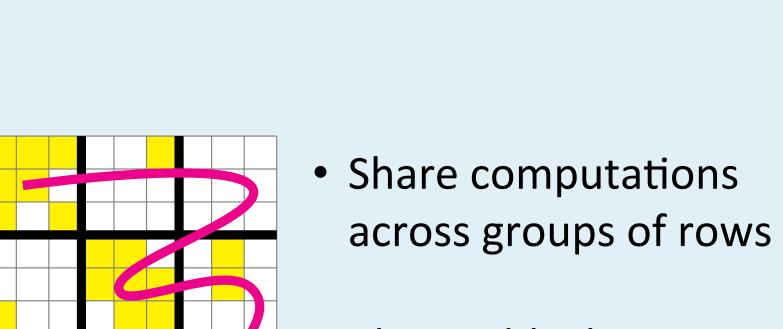
Alternating Newton Block Coordinate Descent

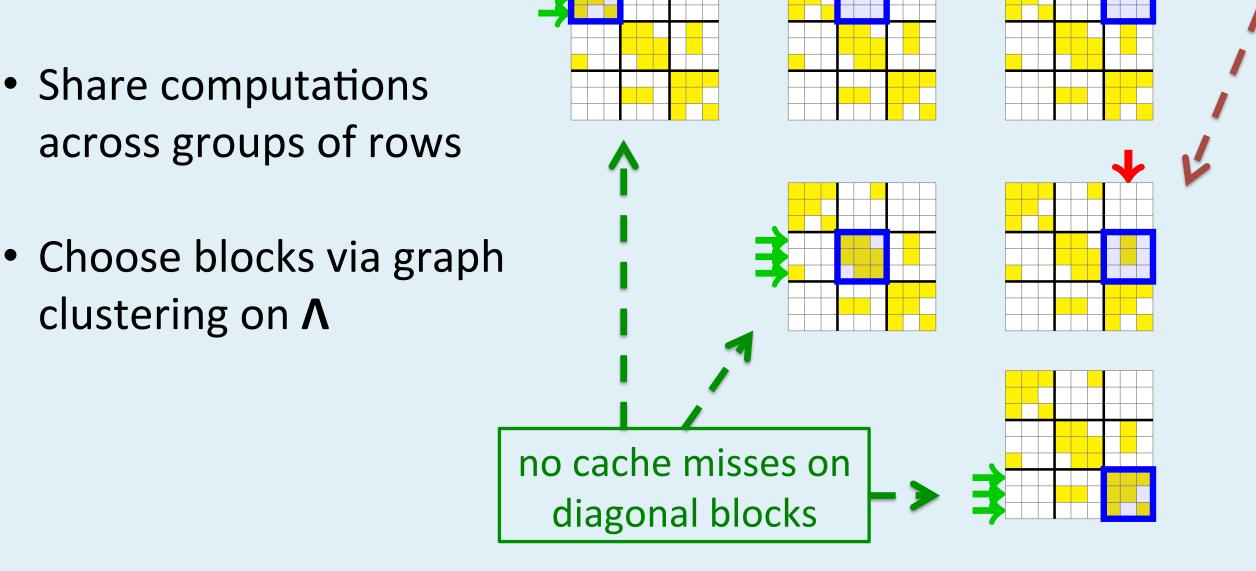
Block-wise strategy for A

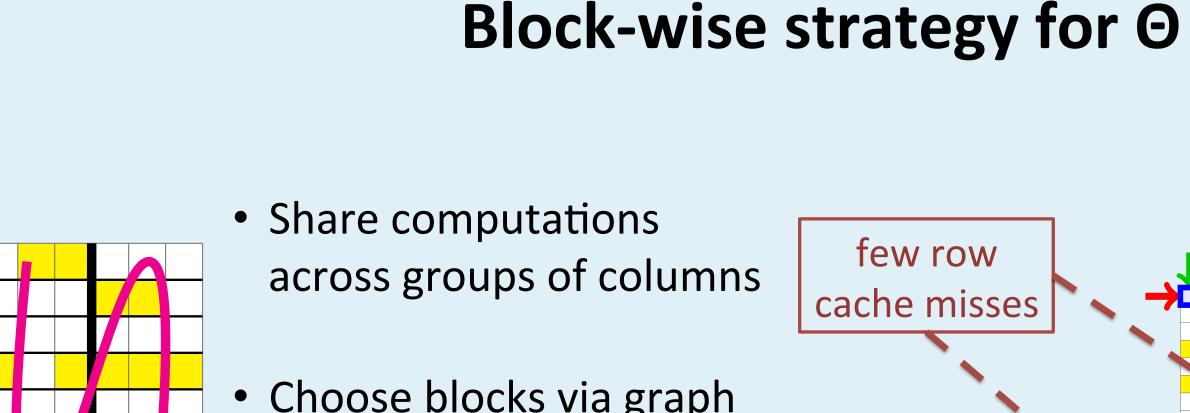
- Pre-compute all matrices: lots of memory, fast
- little memory, slow (many cache misses) Compute as needed:

☑ Block coordinate descent: fast as possible given available memory

(few cache misses)







clustering on Λ

 Choose blocks via graph clustering on **O**^T**O**

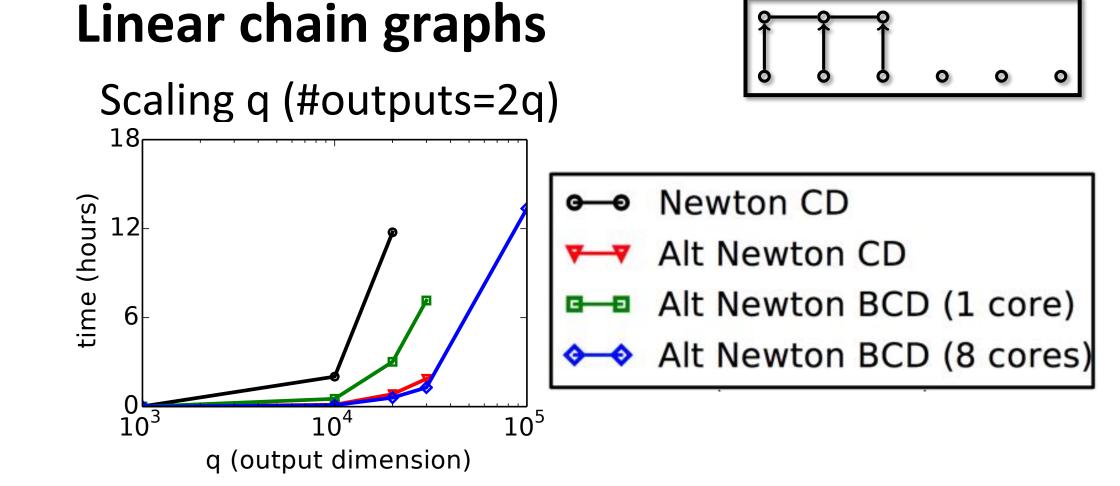
Exploit row-wise sparsity

cache misses

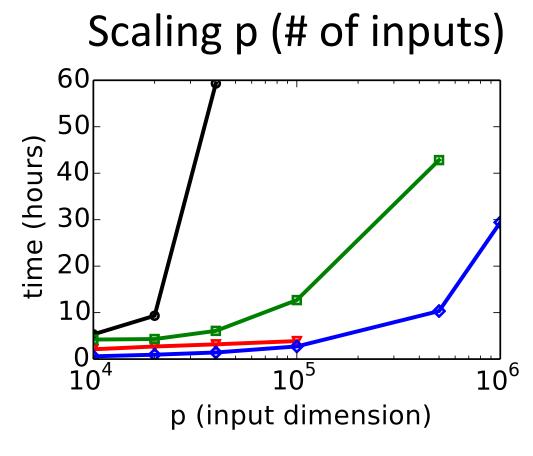
Simulation Results

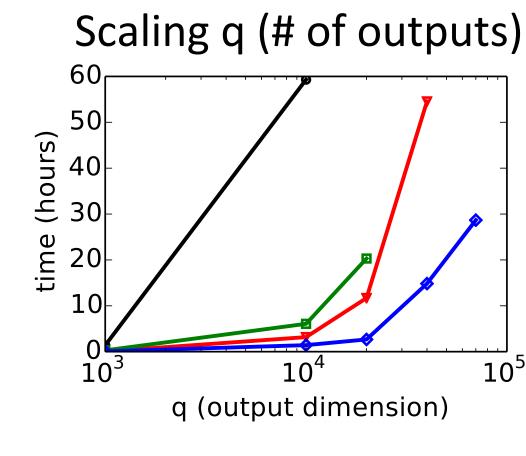
Scaling q (#outputs=q)

q (output dimension)



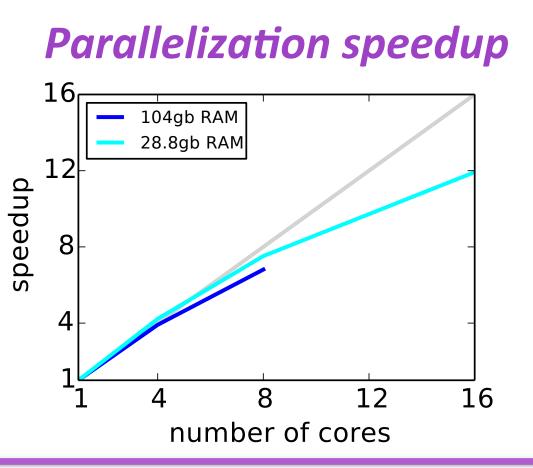
Random graphs with clustering





Convergence in graph structure

time (hours)

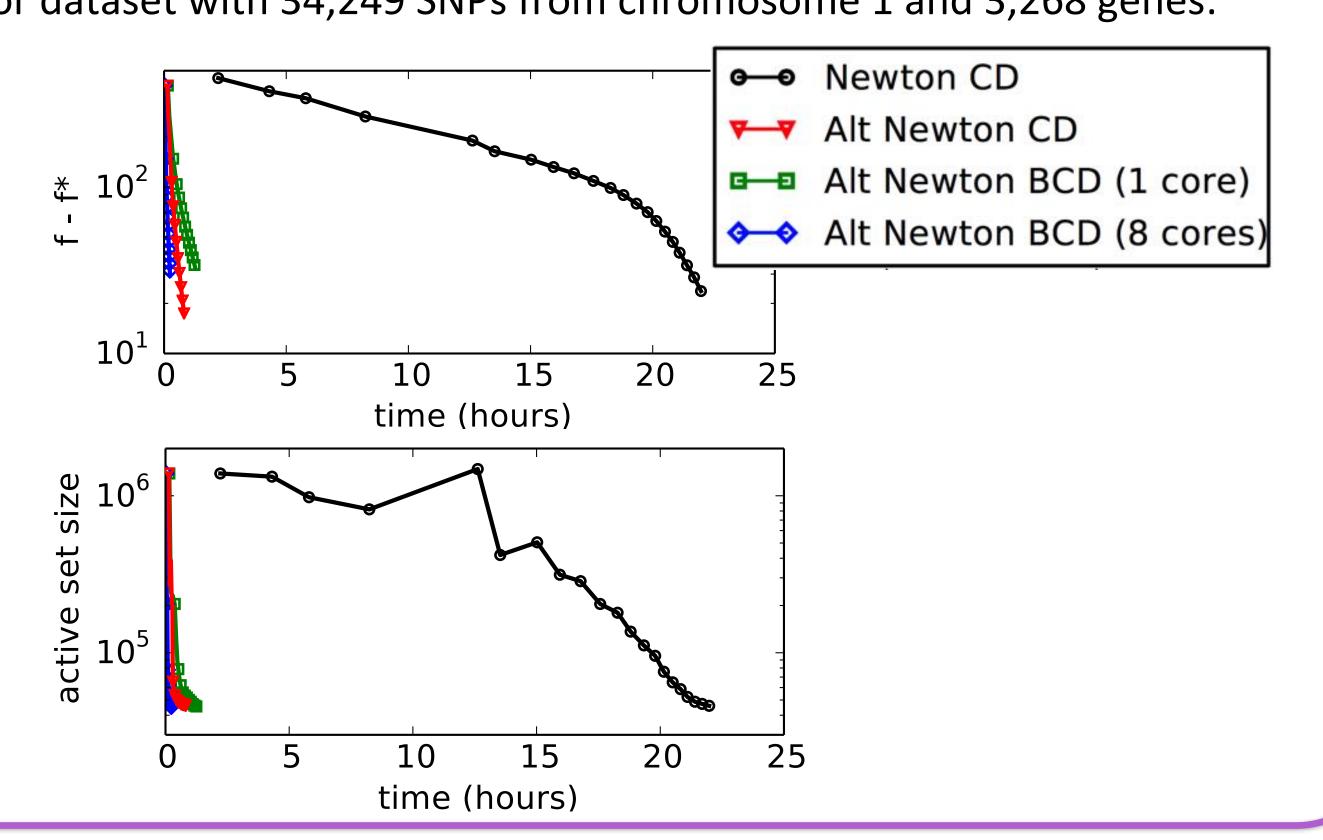


Genomic Data Analysis

- Genotypes and gene expression levels for 171 individuals with asthma
- Contains 442,440 SNPs and 10,256 genes with variance > 0.01
- Regularization parameters chosen to learn graphs with 10q edges

\overline{p}	q	Newton CD	Alt Newton CD	Alt Newton BCD
34,249	3,268	22.0	0.51	0.24
34,249	10,256	> 50	2.4	2.3
442,440	3,268	*	*	11

Results for dataset with 34,249 SNPs from chromosome 1 and 3,268 genes:



References [1] Sohn & Kim. Joint estimation of structured sparsity and output structure in multiple-output regression via inverse-covariance regularization. AISTATS 2012. [2] Yuan & Zhang. Partial gaussian graphical model estimation. IEEE Transactions on Information Theory. 2014. [3] Wytock & Kolter. Sparse Gaussian conditional random fields: algorithms, theory, and application to energy forecasting. ICML 2013. [4] Hsieh et al. BIG & QUIC: Sparse inverse covariance estimation for a million variables. NIPS 2013.