

Guides and Resources: Basic IO - QBot 2

Cameras

This document will summarize how to read data from the QBot 2's Kinect RGB-D camera.

Reading from the Cameras

Note: Ensure that your QBot 2 is powered ON and that a connection has been established to it. Follow the steps under [Charging Vehicle Batteries](#) and [Communicating with the QBot 2](#) in the [Research Studio Setup Guide](#).

Note: Ensure that you have read and understood all the safety procedures and guidelines regarding charging Lithium Polymer batteries as well as guidelines on using the QBot 2 in a safe manner outlined in the [Research Studio Setup Guide](#). If you have any concerns or questions, please contact Quanser technical support (tech@quanser.com).

Note: Safety eye glasses should always be worn, even outside the net.

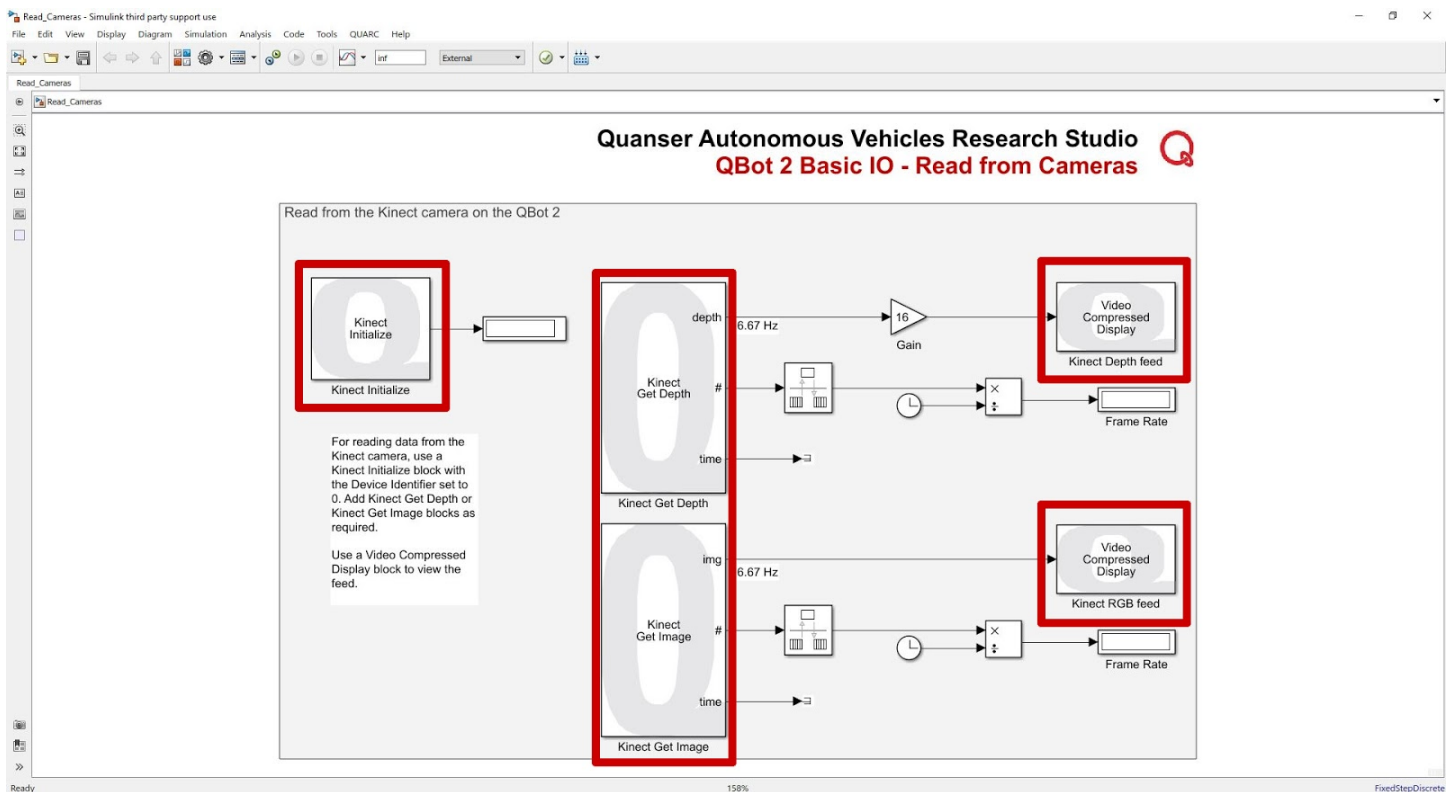


Figure 1: Read_Cameras.slx model, highlighting the Kinect Initialize, Kinect Get Depth, Kinect Get Image and Video Compressed Display blocks

1. Under the [Guides and Resources > Basic IO > QBot 2 > Software](#) folder, open [Read_Cameras.slx](#) (Figure 1)

Note: For the latest documentation and controllers, please visit [Autonomous Vehicles Research Studio Resources](#).

Autonomous Vehicles Research Studio Resources weblink:
<https://www.quanser.com/products/autonomous-vehicles-research-studio/>

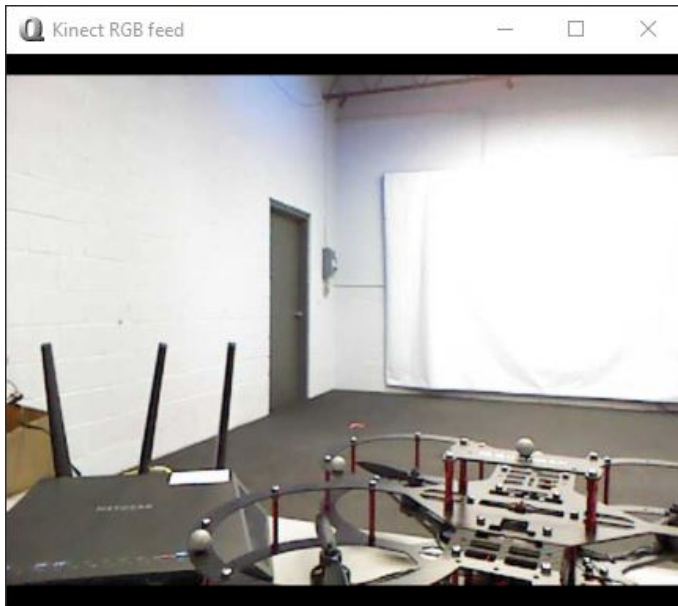
2. Under Model Configuration Settings, enter the correct QDrone hostname.

Note: See the [QBot 2 IO Check](#) section in the [Research Studio Setup Guide](#) for more information.

3. Build the model (QUARC menu > Build).
4. Start the model (QUARC menu > Start).
5. The QBot 2 will emit a sequence of beeps, which signifies that the model has started running.
6. Ensure that safety glasses are worn. Enter the workspace and move the QBot 2. The **Kinect RGB feed** display (Figure 3a) should show the camera feed from the Kinect on the QBot 2 (Figure 2). The **Kinect Depth feed** display (Figure 3b) should show the camera feed from the Kinect on the QBot 2.



Figure 2: Kinect Camera on the QBot 2



a. RGB image



b. Depth image

Figure 3: Camera feed from the QBot 2

7. Stop the model.

This completes a tutorial on how to capture images/videos from the QDrone. More information on configuring the Video Capture and Video Display blocks can be found under [Guides and Resources > Concepts](#).