

15-213/18-213, Spring 2014
Malloc Lab: Writing a Dynamic Storage Allocator
Assigned: Thu, Mar 27, 2014
Checkpoint: Thu, Apr 3, 2014, 11:59pm
Due: Tue, Apr 15, 11:59pm
Last Possible Time to Turn In: Fri, Apr 18, 11:59pm

1 Introduction

In this lab you will be writing a *general purpose* dynamic storage allocator for C programs; that is, your own version of the `malloc`, `free`, `realloc`, and `calloc` functions. You are encouraged to explore the design space creatively and implement an allocator that is correct, efficient, and fast.

2 A Note

This lab features a wide design space; feel free to be creative during this lab. In order to get the most out of this lab, we *strongly* encourage you to start early. The total time you spend designing and debugging can easily eclipse the time you spend coding.

Bugs can be especially pernicious and difficult to track down in an allocator, and you will probably spend a significant amount of time debugging your code.

3 Logistics

This is an individual project. You should do this lab on one of the shark machines.

There will be a checkpoint on Thu, Apr 3, 2014, 11:59pm. You must have a malloc implementation that achieves 45% utilization and 40Kops/s performance to score points on this checkpoint.

4 Hand Out Instructions

Start by downloading `malloclab-handout.tar` from Autolab to a protected directory in which you plan to do your work. Then give the command `tar xvf malloclab-handout.tar`. This will cause a number of files to be unpacked into the directory.

The only file you will be modifying and turning in is `mm.c`, which contains your solution. The `mdriver.c` program is a driver program that allows you to locally evaluate the performance of your solution in the same way that Autolab will evaluate your final submission. Use the command `make` to generate the driver code, which consists of two files, `mdriver.fast` and `mdriver.debug`, which can be run with `./mdriver.debug`. We will test your final solution on Autolab using `mdriver.fast`, which will enable compiler optimizations and disable contracts and `checkheap`. However, you should run `./mdriver.debug` if you aren't optimizing performance, as this will enable contracts and run your `checkheap` function to help you ensure your code is correct.

5 How to Work on the Lab

Your dynamic storage allocator will consist of the following functions, which are declared in `mm.h` and defined in `mm.c`:

```
int    mm_init();
void*  malloc(size_t size);
void   free(void* ptr);
void*  realloc(void* ptr, size_t size);
void*  calloc (size_t nmemb, size_t size);
int    mm_checkheap(int verbose);
```

The `mm-naive.c` file we have given you implements everything correctly but naively. In addition, there is an example implicit list allocator described in your textbook.

Because we are running on 64-bit machines, your allocator must be coded accordingly, with one exception: the size of the heap will never be greater than or equal to 2^{32} bytes. This does *not* imply anything about the location of the heap, but there is a neat optimization that can be done using this information. However, be very, very careful if you decide to take advantage of this fact. There are certain invalid optimizations that will pass all the driver checks because of the limited range of functionality we can check in a reasonable amount of time, so we will be manually looking over your code for these violations. If you do not understand this paragraph, you should re-read the x86-64 section of the text and come to office hours with questions if you are still unsure.

You may use `mm.c`, `mm-naive.c`, or the book's example code as starting points for your own `mm.c` file.¹ Implement the functions (and possibly define other private `static` helper functions), so that they obey the following semantics:

- **mm_init**: Performs any necessary initializations, such as allocating the initial heap area. The return value should be `-1` if there was a problem in performing the initialization, `0` otherwise. **Do not call `mem_init` from this function!**

Every time the driver executes a new trace, it resets your heap to the empty heap by calling your `mm_init` function.

- **malloc**: The `malloc` routine returns a pointer to an allocated block payload of at least `size` bytes. The entire allocated block should lie within the heap region and should not overlap with any other allocated chunk.

¹We recommend against copying the example code directly because of its reliance on macros. A better idea would be to modify the given starter code that uses inline functions to implement the book's algorithm.

Your `malloc` implementation must always return 8-byte aligned pointers.

- `free`: The `free` routine frees the block pointed to by `ptr`. It returns nothing. This routine is only guaranteed to work when the passed pointer (`ptr`) was returned by an earlier call to `malloc`, `calloc`, or `realloc` and has not yet been freed. `free(NULL)` has no effect.
- `realloc`: The `realloc` routine returns a pointer to an allocated region of at least `size` bytes with the following constraints:

- if `ptr` is `NULL`, the call is equivalent to `malloc(size)`;
- if `size` is equal to zero, the call is equivalent to `free(ptr)` and should return `NULL`;
- if `ptr` is not `NULL`, it must have been returned by an earlier call to `malloc` or `realloc` and not yet have been freed. The call to `realloc` takes an existing block of memory, pointed to by `ptr` — the *old block*. It then allocates a region of memory large enough to hold `size` bytes and returns the address of this new block. Note that the address of the new block might be the same as the old block (perhaps there was free space after the old block and it could just be extended, or the new `size` was smaller than the old `size`); or it might be different, depending on your implementation, the amount of internal fragmentation in the old block, and the size of the `realloc` request. If the call to `realloc` does not fail and the returned address is different than the address passed in, the old block has been freed and may not be used again.

The contents of the new block are the same as those of the old `ptr` block, up to the minimum of the old and new sizes. Everything else is uninitialized. For example, if the old block is 8 bytes and the new block is 12 bytes, then the first 8 bytes of the new block are identical to the first 8 bytes of the old block and the last 4 bytes are uninitialized. Similarly, if the old block is 8 bytes and the new block is 4 bytes, then the contents of the new block are identical to the first 4 bytes of the old block.

- `calloc`: Allocates memory for an array of `nmemb` elements of `size` bytes each and returns a pointer to the allocated memory. The memory is set to zero before returning.

Note: Your `calloc` will not be graded on throughput or performance. A correct, simple implementation will suffice.

- `mm_checkheap`: The `mm_checkheap` function (the *heap consistency checker*, or simply *heap checker*) scans the heap and checks it for correctness (e.g., are the headers and footers identical). Your heap checker should run silently until it detects some error in the heap. Then, and only then, should it print a message and return a non-zero exit code. It is very important that your heap checker run silently; otherwise, it will produce too much output to be useful on the large traces.

A quality heap checker is essential for debugging your `malloc` implementation. Many `malloc` bugs are too subtle to debug using conventional `gdb` techniques. The only effective technique for some of these bugs is to use a heap consistency checker. When you encounter a bug, you can isolate it with repeated calls to the consistency checker until you find the instruction that corrupted your heap. Because of the importance of the consistency checker, it will be graded. If you ask a member of the course staff for help, the *first thing we will do is ask to see your `checkheap` function*, so please write this function before coming to see us!

You should call this function through `checkheap`, which will exit and print the location it was called from if `mm_checkheap` reports a failure.

These semantics match the semantics of the corresponding `libc` routines (note that `mm_checkheap` does not have a corresponding function in `libc`). Type `man malloc` to the shell for complete documentation.

6 Support Routines

The `memlib.c` package simulates the memory system for your dynamic memory allocator. You can invoke the following functions in `memlib.c`:

- `void *mem_sbrk(int incr)`: Expands the heap by `incr` bytes, where `incr` is a positive non-zero integer, and returns a generic pointer to the first byte of the newly allocated heap area. The semantics are identical to the Unix `sbrk` function, except that `mem_sbrk` accepts only a positive non-zero integer argument.
- `void *mem_heap_lo(void)`: Returns a generic pointer to the first byte in the heap.
- `void *mem_heap_hi(void)`: Returns a generic pointer to the last byte in the heap.
- `size_t mem_heapsize(void)`: Returns the current size of the heap in bytes.
- `size_t mem_pagesize(void)`: Returns the system's page size in bytes (4K on Linux systems).

7 The Trace-driven Driver Program

The driver program `mdriver.c` in the `malloclab-handout.tar` distribution tests your `mm.c` package for correctness, space utilization, and throughput. The driver program is controlled by a set of *trace files* that are included in the `malloclab-handout.tar` distribution. Each trace file contains a sequence of allocate and free directions that instruct the driver to call your `malloc` and `free` routines in some sequence. The driver and the trace files are the same ones we will use when we grade your handin `mm.c` file.

When the driver program is run, it will run each trace file 12 times: once to make sure your implementation is correct, once to determine the space utilization, and 10 times to determine the performance.

The driver `mdriver.c` accepts the following command line arguments. The normal operation is to run it with no arguments, but you may find it useful to use the arguments during development.

- `-t <tracedir>`: Look for the default trace files in directory `tracedir` instead of the default directory defined in `config.h`.
- `-f <tracefile>`: Use one particular `tracefile` instead of the default set of tracefiles for testing correctness and performance.
- `-c <tracefile>`: Run a particular `tracefile` exactly once, testing only for correctness. This option is extremely useful if you want to print out debugging messages.
- `-h`: Print a summary of the command line arguments.
- `-l`: Run and measure `libc malloc` in addition to the student's `malloc` package. This is interesting if you want to see how fast a real `malloc` package runs.
- `-V`: Verbose output. Print additional diagnostic information as each trace file is processed. Useful during debugging for determining which trace file is causing your `malloc` package to fail.
- `-v <verbose level>`: This optional feature lets you manually set your verbose level to a particular integer.

- `-d <i>`: At debug level 0, very little validity checking is done. This is useful if you are mostly done but just tweaking performance.
At debug level 1, every array the driver allocates is filled with random bits. When the array is freed or reallocated, we check to make sure the bits have not been changed. This is the default.
At debug level 2, every time any operation is done, all arrays are checked. This is very slow but useful to discover problems very quickly.
- `-D`: Equivalent to `-d2`.
- `-s <s>`: Time out after *s* seconds. The default is to never time out.

8 Programming Rules

- You are writing a general purpose allocator. You may not solve specifically for any of the traces—we will be checking for this. Any allocator that attempts to determine which trace is running and change its behavior based on that trace’s pattern of allocations will receive a penalty of 20 points.
- You should not change any of the interfaces in `mm.h`. However, we strongly encourage you to use `static` helper functions in `mm.c` to break up your code into small, easy-to-understand segments.
- You should not invoke any external memory-management related library calls or system calls. The use of the `libc` `malloc`, `calloc`, `free`, `realloc`, `sbrk`, `brk`, or any other memory management packages is strictly prohibited.
- You are not allowed to define any global data structures such as arrays, structs, trees, or lists in your `mm.c` program. However, you *are* allowed to declare global scalar variables such as integers, floats, and pointers in `mm.c`.

The reason for this restriction is that the driver cannot account for such global variables in its memory utilization measure. If you need space for large data structures, you can put them at the beginning of the heap.

- You are not allowed to simply hand in the code for the allocators from the CS:APP or K&R books. If you do so, you will receive no credit.
However, we encourage you to study these examples and to use them as starting points. For example, you might modify the CS:APP code to use an explicit list with constant-time coalescing. Or you might modify the K&R code to use constant-time coalescing. Or you might use either one as the basis for a segregated list allocator. Please remember, however, that your allocator must be for 64-bit machines.
- It is okay to look at any *high-level* descriptions of algorithms found in the textbook or elsewhere, but it is *not* acceptable to copy or look at any code of `malloc` implementations found online or in other sources, except for the implicit list allocator described in your book or K&R.
- Your allocator must always return pointers that are aligned to 8-byte boundaries. The driver will check this requirement.
- Your code *must* compile without warnings. Warnings often point to subtle errors in your code; whenever you get a warning, you should double-check the corresponding line to see if the code is really doing what you intended. If it is, then you should eliminate the warning by tweaking the code (for

instance, one common type of warning can be eliminated by adding a type-cast where a value is being converted from one type of pointer to another). We have added flags in the Makefile to force your code to be error-free. You may remove those flags during development if you wish, but please realize that we will be grading you with those flags activated.

9 Evaluation

The grading of the final hand-in will be based on the performance of your allocator on the given traces, the quality of your heap checker, and your coding style. The final hand-in is described in more detail below.

There are a total of 120 points. You will receive *zero points* if you break any of the rules or if your code is buggy and crashes the driver.

Please be sure you have read all of the rules above. Otherwise, your grade will be calculated as follows:

Performance (100 points). Two metrics will be used to evaluate your solution:

- *Space utilization:* The peak ratio between the aggregate amount of memory used by the driver (i.e., allocated via `malloc` but not yet freed via `free`) and the size of the heap used by your allocator. The optimal ratio equals 1. You should find good policies to minimize fragmentation in order to make this ratio as close as possible to the optimal.
- *Throughput:* The average number of operations completed per second.

The driver program summarizes the performance of your allocator by computing a *performance index*, $0 \leq P \leq 100$, which is a weighted sum of the space utilization and throughput

$$P(U, T) = 100 \left(w \min \left(1, \frac{U - U_{min}}{U_{max} - U_{min}} \right) + (1 - w) \min \left(1, \frac{T - T_{min}}{T_{max} - T_{min}} \right) \right)$$

where U is your space utilization, T is your throughput, U_{max} and T_{max} are the estimated space utilization and throughput of an optimized `malloc` package, and U_{min} and T_{min} are minimum space utilization and throughput values, below which you will receive 0 points.² The performance index favors space utilization over throughput: $w = 0.61$.

Observing that both memory and CPU cycles are expensive system resources, we adopt this formula to encourage balanced optimization of both memory utilization and throughput. Since each metric will contribute at most w and $1 - w$ to the performance index, respectively, you should not go to extremes to optimize either the memory utilization or the throughput only. To receive a good score, you must achieve a balance between utilization and throughput.

The 100 performance points (`$perfpnts`) will be allocated as a function of the performance index (`$perfindex`):

```
if ($perfindex < 60) {  
$perfpnts = 0.8 * $perfindex;  
}
```

²The values for U_{min} , U_{max} , T_{min} , and T_{max} are constants in the driver (0.60, 0.92, 3,000 Kops/s, and 14,000 Kops/s) that your instructor established when they configured the program. This means that once you beat 92% utilization and 14,000 Kops/s, your performance index is perfect.

```
else {
$perfpoints = $perfindex;
}
```

You will receive no performance points for an allocator that fails on any of the traces.

We give you a handful of traces. Some of them are smaller traces that don't count towards your memory utilization or throughput. These will be useful for debugging. In the `mdriver`'s output, you will see these marked without a '*' next to them. The traces that count towards both your memory utilization and throughput are marked with a '*' in `mdriver`'s output. There are two traces which only count towards your memory utilization - these are marked with a 'u'. Likewise there is one trace which only counts towards your throughput, and is marked with a 'p'.

Note: The performance score that counts is the one computed on Autolab after you submit. The throughput component of this score may be different from that computed when you run the driver on the shark machines. Make sure that you check your score after you submit to avoid any surprises.

Heap Consistency Checker (10 points). Ten points will be awarded based on the quality of your implementation of `mm_checkheap`. It is up to your discretion how thorough you want your heap checker to be. The more the checker tests, the more valuable it will be as a debugging tool. However, to receive full credit for this part, we require that you check *all* of the invariants of your data structures. Some examples of what your heap checker should check are provided below.

- Checking the heap (implicit list, explicit list, segregated list):
 - Check epilogue and prologue blocks.
 - Check each block's address alignment.
 - Check heap boundaries.
 - Check each block's header and footer: size (minimum size, alignment), previous/next allocate/free bit consistency, header and footer matching each other.
 - Check coalescing: no two consecutive free blocks in the heap.
- Checking the free list (explicit list, segregated list):
 - All next/previous pointers are consistent (if A's next pointer points to B, B's previous pointer should point to A).
 - All free list pointers points between `mem_heap_lo()` and `mem_heap_high()`.
 - Count free blocks by iterating through every block and traversing free list by pointers and see if they match.
 - All blocks in each list bucket fall within bucket size range (segregated list).

Style (10 points). Your code should follow the Style Guidelines posted on the course Web site. In particular:

- You **must** use contracts in your code (`REQUIRES()`, `ENSURES()`, or `assert()`). Failure to do so will make your code significantly more difficult to debug and will raise serious doubts about your implementation's correctness. While it may not be possible to have contracts on the public functions (`malloc()`, `calloc()`, etc.), each data structure method should have contracts that can uphold its invariants. See the given starter code for examples.

- Your code should be decomposed into functions and use as few global variables as possible. You should use inline functions or packed structs to isolate pointer arithmetic to a few places.
- Your `mm.c` file must begin with a header comment that gives an overview of the structure of your free and allocated blocks, the organization of the free list, and how your allocator manipulates the free list.
- In addition to this overview header comment, each function should be preceded by a header comment that describes what the function does.
- You will want to use inline comments to explain code flow or code that is tricky.
- Macros can be acceptable, but they generally indicate poor style and make your program more difficult to debug without providing performance or readability benefits. Use your best judgement to decide whether a macro is really better than an inline function. We will deduct points for unnecessary use of macros.

10 Handin Instructions

Make sure you have included your name and Andrew ID in the header comment of `mm.c`.

Hand in your `mm.c` file by uploading it to Autolab. You may submit your solution as many times as you wish until the due date.

Only the last version you submit will be graded.

For this lab, you must upload your code for the results to appear on the class status page.

NOTE: In previous semesters we have had a number of students who did not finish this lab within the time limits; for this reason we strongly encourage you to submit whatever code you have that receives the highest grade possible on the due date (and 24 hours thereafter if you are using a grace day). This will ensure that you have *something* submitted for which we can give you points.

11 Hints

- The measured throughput on your class machines and on Autolab might be different. Your job is to ensure that your allocator is fast enough that these differences don't matter.
- For those who have taken 15-122, we have included the `contracts.h` header file in the handout directory. You should use this to check your invariants during development.
- *Use the `mdriver -c` option or `-f` option.* During initial development, using tiny trace files will simplify debugging and testing.
- *Use the `mdriver -V` options.* The `-V` option will also indicate when each trace file is processed, which will help you isolate errors.
- *Use the `mdriver -D` option.* This does a lot of checking to quickly find errors.
- *Use a debugger.* A debugger will help you isolate and identify out-of-bounds memory references.
- *Use `gdb's watch` command* to find out what changed some value you did not expect to have changed.

- *Encapsulate your pointer arithmetic in C inline functions.* Pointer arithmetic in memory managers is confusing and error-prone because of all the casting that is necessary. You can significantly reduce the complexity by writing functions for your pointer operations. See the code for manipulating blocks provided in `mm.c`.
- *Remember we are working with 64-bit shark machines.* Pointers take up 8 bytes of space, so you should understand the macros in the book and port them to 64-bit machines. Notably, on the 64-bit shark machines, `sizeof(size_t) == 8`.
- *Use your heap consistency checker.* We are assigning ten points to your `mm_checkheap` function for a reason. A good heap consistency checker will save you hours and hours when debugging your `malloc` package. You can use your heap checker to find out where exactly things are going wrong in your implementation (hopefully not in too many places!). Make sure that your heap checker is detailed. To be useful, your heap checker should only produce output when it detects an error. Every time you change your implementation, one of the first things you should do is think about how your `mm_checkheap` will change, what sort of tests need to be performed, and so on. Remember that `checkheap` will be disabled by `-DNDEBUG`, so feel free to call it anywhere necessary to check invariants as it won't affect your performance.
- *Use a profiler.* You may find the `gprof` tool helpful for optimizing performance.
- *Keep backups.* Now would be an great time to learn an industrial-strength version control system like Git (<http://git-scm.com>). Whenever you have a working allocator and are considering making changes to it, commit or keep a backup copy of the last working version. It is very common to make changes that inadvertently break the code and then have trouble undoing them.
- *Versioning your implementation.* You may also find it useful to manage a couple of different versions of implementation (e.g., explicit list, segregated list) during the assignment. Since `mdriver` looks for `mm.c`, creating a symbolic link between files is useful in this case. For example, you can create a symbolic link between `mm.c` and your implementation such as `mm-explicit.c` with command line `ln -s mm-explicit mm.c`.
- *Start early!* It is possible to write an efficient `malloc` package with a few pages of code. However, we can guarantee that it will be some of the most difficult and sophisticated code you have written so far in your career. So start early, and good luck!

12 More Hints

Basically, you want to design an algorithm and data structure for managing free blocks that achieves the right balance of space utilization and speed. Note that this involves a trade-off. For space, you want to keep your internal data structures small. Also, while allocating a free block, you want to do a thorough (and hence slow) scan of the free blocks, to extract a block that best fits our needs. For speed, you want fast (and hence complicated) data structures that consume more space. Here are some of the design options available to you:

- Data structures to organize free blocks:
 - Implicit free list
 - Explicit free list

- Segregated free lists
- Algorithms to scan free blocks:
 - First fit/next fit
 - Blocks sorted by address with first fit
 - Best fit

You can pick (almost) any combination from the two. For example, you can implement an explicit free list with next fit, a segregated list with best fit, and so on. Also, you can build on a working implementation of a simple data structure to a more complicated one.

In general, we suggest that you start with an implicit free list, then change this to an explicit list, and then use the explicit list as the basis for a final version based on segregated lists.

Good luck!