

MATH 54 PRACTICE MIDTERM 2

Your Name	
Student ID	

Section number and leader	
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Do not turn this page until you are instructed to do so.

Show all your work in this exam booklet. No material other than simple writing utensils may be used. *In the event of an emergency or fire alarm leave your exam (closed) on your seat and meet with your GSI outside.*

If you need to use the restroom, leave your exam with your GSI while out of the room.

Your grade is determined from all of the following 5 problems. Some extra credit problems are interspersed and can make up for up to 5 missed points within the same problem. However, only complete answers earn this credit, so check your other work before attempting these.

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1. (a) Consider the subspace $H = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mid x_1 + 2x_2 + 3x_3 = 0 \right\}$ of \mathbb{R}^3 .
(Without reasoning) find the dimension and a basis of H .

(b) Explain which vector(s) to drop from the spanning set $S = \{(t-1)^2, (t+1)^2, t^2 - 1, 2t\}$ of \mathbb{P}_2 to obtain a basis.

- (c) Explain why the space of solutions to $\frac{d}{dt}\mathbf{x}(t) = A(t)\mathbf{x}(t)$ is a vector space for any coefficient matrix $A : \mathbb{R} \rightarrow M_{n \times n}$. (You may use the fact that functions $\mathbb{R} \rightarrow \mathbb{R}^n$ form a vector space.)
- (extra credit)** Explain how one could approximate a basis for this vector space.

- (d) Show that $t \cos t, t \sin t, \cos^2 t$ are linearly independent as functions on $[0, \frac{\pi}{2}]$. *Hint: You can avoid calculation of the Wronskian by working from the definition and plugging in convenient values of t .*

2. (a) Show that $S : M_{2 \times 2} \rightarrow M_{2 \times 2}, A \mapsto A - A^T$ is a linear transformation. Describe its kernel and range and determine their dimensions.

(b) What does the rank theorem assert about the kernel and range of a linear transformation $\mathbb{R}^n \rightarrow \mathbb{R}^n$?

(extra credit) Show that the same assertion is true for the linear transformation in (a).

(c) Define $T : \mathbb{P}_2 \rightarrow \mathbb{R}^2$ by $T(p) = \begin{bmatrix} p'(0) \\ p''(0) \end{bmatrix}$. Find its matrix A with respect to the standard bases of \mathbb{P}_2 and \mathbb{R}^2 , and explain how $Nul(A)$, $Col(A)$ are related to the kernel and range of T .

(d) Given a linear transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ and a basis $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$ of \mathbb{R}^2 so that $T(\mathbf{b}_1) = \mathbf{b}_1 - \mathbf{b}_2$ and $T(\mathbf{b}_2) = 5\mathbf{b}_1$, find the matrix for T in \mathcal{B} -coordinates, $[T]_{\mathcal{B}}$.

3. (a) Find a change-of-coordinates that diagonalizes $A = \begin{bmatrix} 3 & 0 & 0 \\ -3 & 4 & 9 \\ 0 & 0 & 3 \end{bmatrix}$.

(b) Explain how each of $Nul(A)$, $Col(A)$ and $\text{rank}(A)$ changes under a row operation on a matrix A .

4. (a) Find a basis for the kernel of the differential operator $L = (D^2 - 2D + 10)^2(D^2 + 3)(D^2 - D)^3$.

(b) Use the facts that $r^3 - 3r^2 + 10r + 14$ has roots $r = 1$ and $r = -2 \pm i\sqrt{10}$, and

$$(D^3 - 3D^2 + 10D + 14)[\ln(2+t)] = 14\ln(2+t) + \frac{10t^2+43t+48}{(2+t)^3},$$

to find the solution of

$$L[y] = y^{(3)} - 3y'' + 10y' + 14y = 14\ln(2+t) + \frac{10t^2+43t+48}{(2+t)^3}, \quad y(0) = \ln 2, \quad y'(0) = 1, \quad y''(0) = 4.$$

Write the result as explicit function of t and constants C_i together with a linear system that determines the C_i . Indicate the interval on which the solution is valid. Don't solve for the constants!

Hint: To simplify derivatives, use the identity $Ae^{\alpha t} \cos \beta t + Be^{\alpha t} \sin \beta t = \operatorname{Re}((A - iB)e^{(\alpha+i\beta)t})$.

5. (a) Rewrite the following coupled differential equations for real functions x, y, z as first order system in standard form:

$$0 = e^t \frac{d}{dt} x + t^2(x - y) + 3(x - z)$$

$$0 = \frac{d}{dt} y + \cos t(x - \sin t)$$

$$0 = \frac{d}{dt} z + e^{2t}(z - y)$$

(b) Given a 3×3 matrix A so that $A \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = 5 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ and $A \begin{bmatrix} 0 \\ 1+i \\ i \end{bmatrix} = i \begin{bmatrix} 0 \\ 1+i \\ i \end{bmatrix}$, find the general solution of the system $\mathbf{x}' = A\mathbf{x}$.

(c) Given the fundamental matrix $X(t) = \begin{bmatrix} \frac{1}{2} \cos \pi t & 6e^t \sin \pi t \\ \frac{1}{3} \sin \pi t & 4e^t \cos \pi t \end{bmatrix}$ for a (time-dependent) system $\mathbf{x}'(t) = A(t)\mathbf{x}(t)$, find the solutions $\mathbf{x}_1(t)$ and $\mathbf{x}_2(t)$ with $\mathbf{x}_1(2) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ and $\mathbf{x}_2(2) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.