## Computational Finance FIN-472 Homework 9

## November 17, 2017

Exercise 1: Consider the following PDE (steady Black & Scholes eq. in log-price on bounded domain).

$$\begin{cases}
-\frac{\sigma^2}{2}\partial_{xx}V(x) - \left(r - \frac{\sigma^2}{2}\right)\partial_x V(x) + rV(x) = f(x), & x \in (x_{min}, x_{max}) \\
V(x_{min}) = a, V(x_{max}) = b.
\end{cases}$$
(1)

- a) Compute f(x), a, b such that (1) is solved by  $V(x) = 3x^2 + 1$ .
- b) Write a finite differences solver for (1), starting from the draft file draft\_bs\_logform\_steady.m.
- c) Let  $\sigma = 1, r = 1, x_{min} = 0, x_{max} = 4$ . Use the finite differences solver to compute a numerical solution  $u_h$  for problem (1), and verify that the result is correct by comparing graphically the exact solution and the approximated one (use Nx = 251 intervals). Moreover, verify that the finite differences error  $e = \max_i |V(x_i) V_h(x_i)|$  is 0 (up to machine precision).

Exercise 2: Consider the following PDE (time-dependent Black & Scholes in log-prices on bounded domain).

$$\begin{cases} \partial_t V(x,t) - \frac{\sigma^2}{2} \partial_{xx} V(x,t) - \left(r - \frac{\sigma^2}{2}\right) \partial_x V(x,t) + rV(x,t) = f(x,t), \ x \in (x_{min}, x_{max}), t \in (0,T] \\ V(x_{min}) = a(t), \quad V(x_{max}) = b(t) \\ V(x,0) = G(x) \end{cases}$$

$$(2)$$

- a) Compute f(x,t), G(x), a(t), b(t) such that (2) is solved by  $V(x,t) = 4t(3x^2 + 1)$ .
- b) Write the Forward Euler finite differences solver for (2), starting from the draft file draft\_bs\_logform\_forward\_euler.m.
- c) Let  $\sigma = 1, r = 1, x_{min} = 0, x_{max} = 1, T = 1$ . Use the finite differences solver to compute a numerical solution  $u_h$  for problem (2), and verify that the result is correct by comparing graphically the real solution and the approximated one at final time (use Nx = 21 intervals in space and  $N_t = 512$  intervals in time). Moreover, verify that the finite differences error  $e = \max_i |V(x_i) V_h(x_i)|$  is 0 (up to machine precision).

d) Repeat the previous point with  $N_t = 256$ . What happens? Explain the results obtained.

Exercise 3: Consider again the PDE of the previous exercise (2).

- a) Write a  $\theta$ -method time-stepping finite differences solver for (2), starting from the draft file draft\_bs\_logform\_timestepping.m.
- b) Let  $f(x,t), a(t), b(t), G(x), \sigma, r, x_{min}, x_{max}, T$  as in the previous exercise. Use the  $\theta$ -method finite differences solver with  $\theta = 1$  and  $\theta = 0.5$  to compute a numerical solution  $u_h$  for problem (2), and verify that the result is correct by comparing graphically the real solution and the approximated one (use Nx = 21 intervals in space and  $N_t = 100$  time-intervals). Moreover, verify that the finite differences error  $e = \max_i |V(x_i) V_h(x_i)|$  is 0 up to machine precision.

Exercise 4: Consider again equation (2). Set  $S_{min} = 0.6$  and  $S_{max} = 1.65$ ,  $x_{min} = \log(S_{min})$ ,  $x_{max} = \log(S_{max})$ , f(x,t) = 0,  $a(t) = Ke^{-rt} - S_{min}$ , b(t) = 0,  $\sigma = 0.21$ , r = 0.015, T = 1, and  $G(x) = \max\{K - e^x, 0\}$ , in order to solve the Black & Scholes model in log-prices for an European Put option with strike price K = 1. Use the Crank-Nicholson time-stepping method with 500 intervals in time and 925 intervals in space  $(N_t = 500, Nx = 925)$ .

- a) Plot the final value of the option versus the price of the underlying asset (<u>not</u> the logprice), and compare it with the Matlab built-in command blsprice (contained in the Matlab financial toolbox). Are the two solutions comparable?
- b) Compute the finite differences approximation of the value of the option for S = 0.9, using the Matlab command interp1 with 'linear' option.
- c) Given any tolerance tol, use the result stated in Proposition 4 of the class slides to obtain  $S_{min}$  and  $S_{max}$  such that the truncation error committed when solving the Black & Scholes model in  $[S_{min}, S_{max}]$  instead of  $(0, \infty)$  is smaller than tol. Hint: derive  $S_{min}, S_{max}$  s.t.

$$\frac{tol}{K} = \phi(\alpha_1(S_{min})), \quad \frac{tol}{K} = \phi(\alpha_2(S_{max}))$$

and implement it in Matlab (you will need the quantiles of the standard normal distribution, which can be computed by the Matlab command norminu, contained in the Statistics Matlab toolbox).

d) Consider a decreasing sequence of tolerances,  $tol = [10^{-2}, 10^{-3}, 10^{-4}, 10^{-5}]$ . For each tolerance, compute the associated interval, solve numerically the equation, compute the error  $e = \max_i |V(x_i, T) - V_h(x_i, T)|$  and verify that such error is smaller than the required tolerance (use a log-log plot to this end). Note that for a fair comparison, the spatial discretization should be kept constant as  $S_{max}$  increases (i.e. same Nx and same  $N_t$ ).