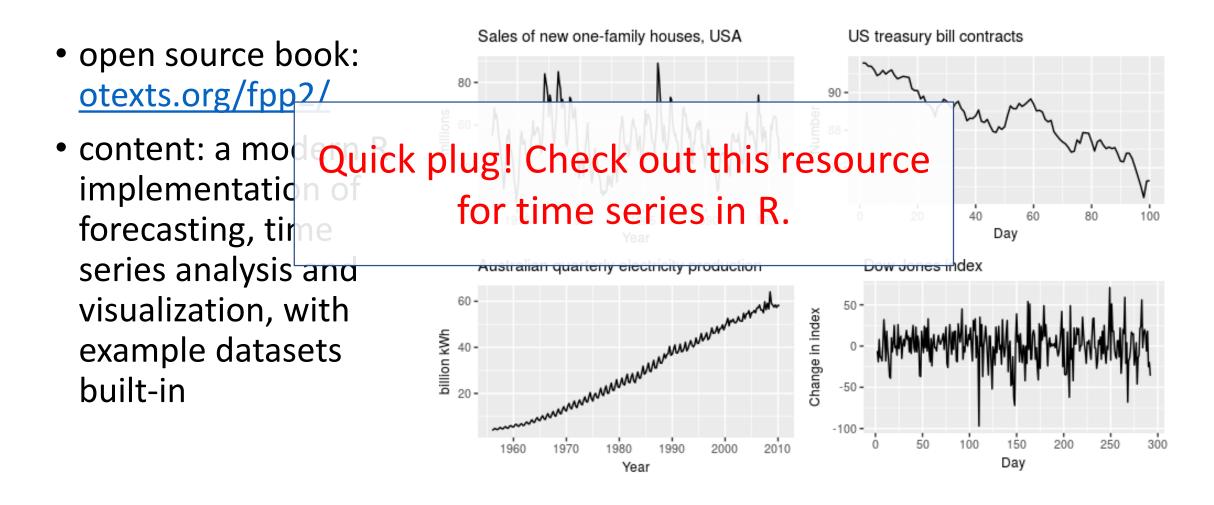


CVEN 6833 - Advanced Data Analysis November 16, 2017 Billy Raseman

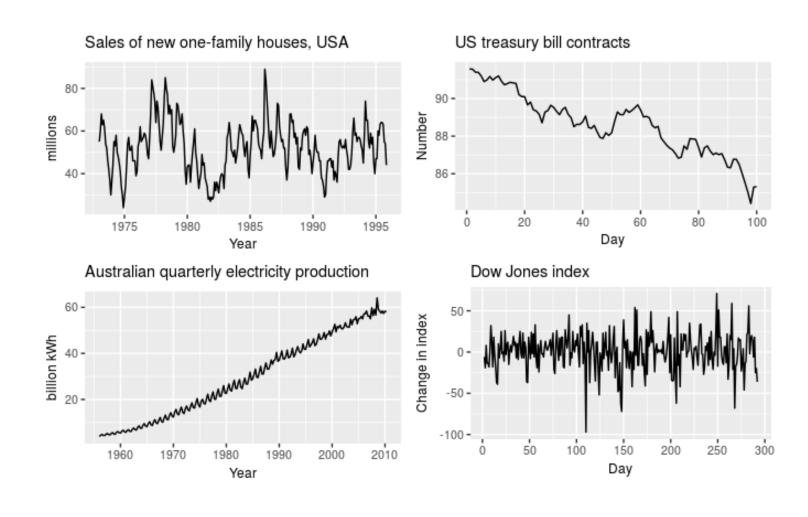
# Hidden Markov Models

# Time Series Analysis and Forecasting in R



# Time Series Analysis and Forecasting in R

- open source book: otexts.org/fpp2/
- content: a modern R implementation of forecasting, time series analysis and visualization, with example datasets built-in



#### Lesson Goals

Following this lecture, you should be able to answer the following questions:

- What is a Markov chain?
- What is the difference between a Markov model and a Hidden Markov model (HMM)?
- What is the purpose of the following algorithms: Viterbi and Baum-Welch?

Following this lecture, you should be able to fit an HMM to a given timeseries dataset.

#### Motivation: persistence in Nile River flow



source: http://kos2013.org/img/HEH\_formal\_portrait.jpeg

# H.E. Hurst: British Hydrologist and "Father of the Nile"

- Spent decades measuring and studying the river
- Hurst noticed that annual streamflow was persistent
- Heavy floods tended to be followed by heavier than average flood years and vice versa.

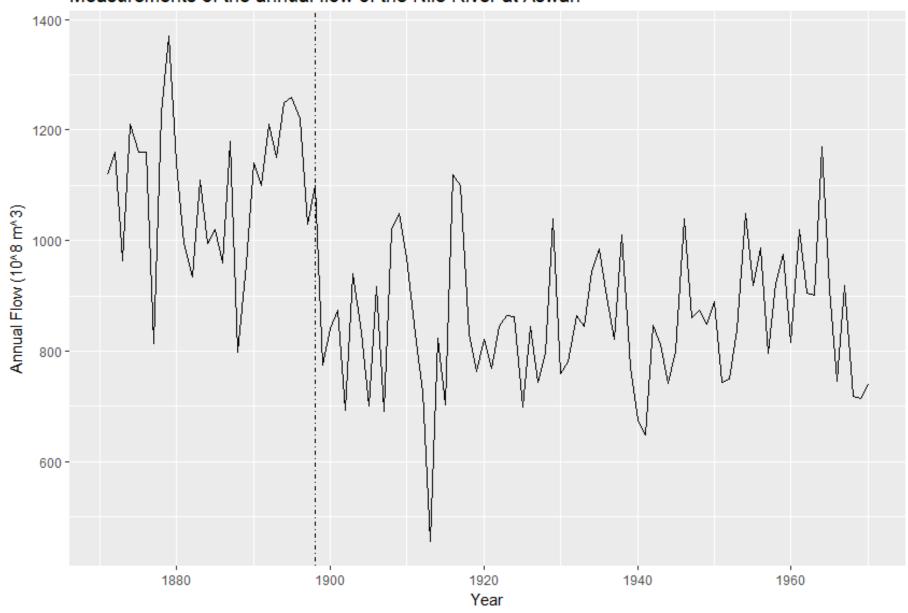
### Motivation: persistence in Nile River flow

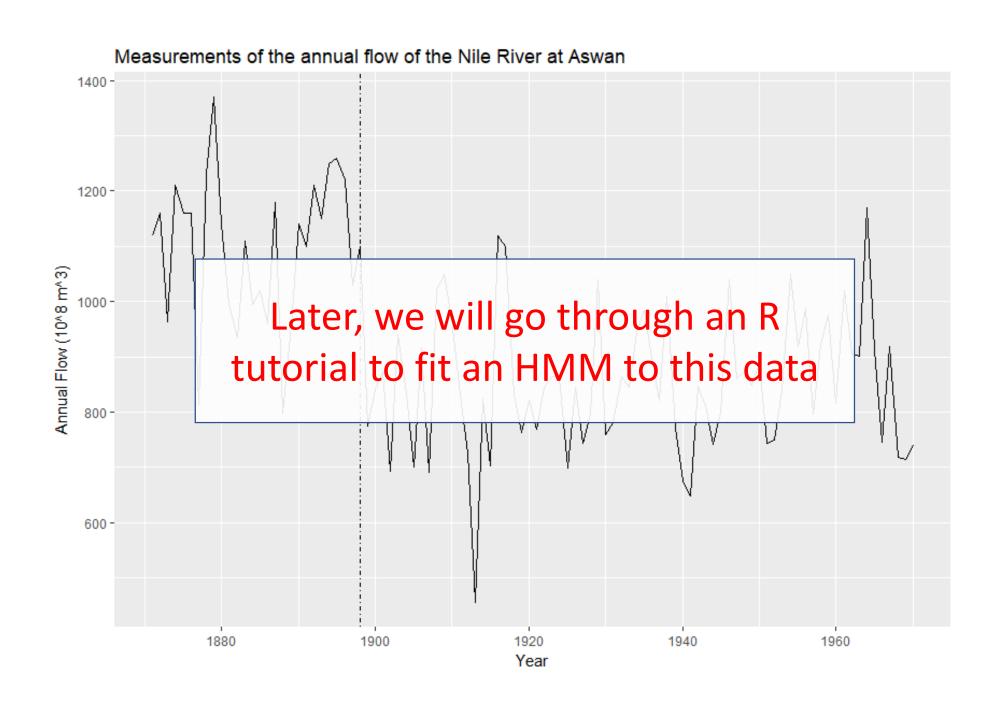


source: http://emerald.tufts.edu/alumni/magazine/spring2007/images/features/A4763\_NS.jpg

- Hurst number which shows persistence in a given state
  - 0.5 1: time series with long-term positive autocorrelation
  - 0 0.5: time series with long-term switching between high and low values in adjacent pairs
- Hidden Markov models (HMM) can do a nice job of modeling persistence

#### Measurements of the annual flow of the Nile River at Aswan





# Motivation: other applications

Google search PageRank

#### What is a Hidden Markov model?

A statistical Markov model in which the system being modeled is assumed to be a Markov process with unobserved (i.e. hidden) states. [source: Wikipedia]

What is a Markov process?

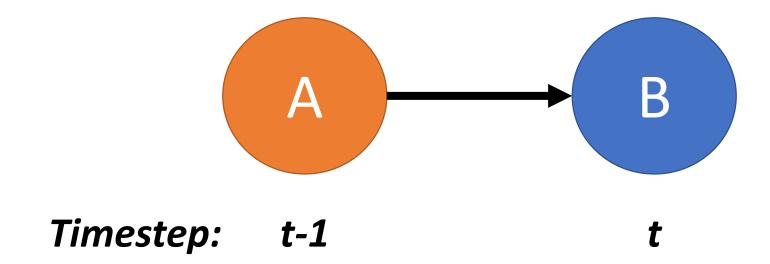
#### What is a Hidden Markov model?

A statistical **Markov model** in which the system being modeled is assumed to be a **Markov process** with unobserved (i.e. hidden) states. [source: Wikipedia]

What is a Markov process?

#### Markov Process

A phenomenon in which the outcome of a given event is only dependent on the previous timestep.

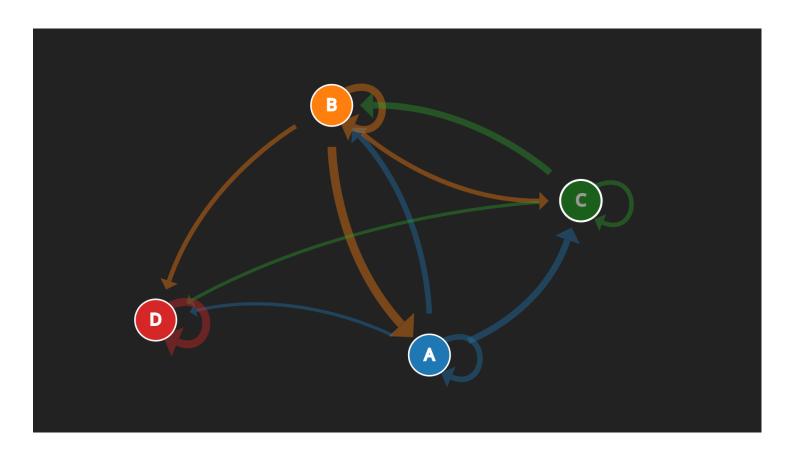


This is often represented using what are known as acyclic graphs.

#### Markov Chains

Markov chains, named after Andrey Markov, are mathematical systems that hop from one "state" (a situation or set of values) to another.

source: http://setosa.io/ev/markov-chains/



setosa.io/markov

For example, a baby could be in very different states...

#### Baby state space

- Laughing
- Sleeping
- Eating
- Crying

Each state has some relationship with the others.



Imagine you have the following daily timeseries in which the weather on that day can be classified as rainy (R) or sunny (S):

This would represent a two-state Markov chain.

You might notice that exactly half of these days are rainy and the other half are sunny:

This equates to a total probability of P(R) = 0.5 and P(S) = 0.5

Now let's generate a new sequence of weather events. Since it's a 50-50 chance it'll be just like flipping a coin, right?

How'd we do? **Not well...** 

#### Observed record:

#### Our model:

We looked at the *total* probability of each event occurring but we haven't considered the conditional probabilities. Let's say the data looked like this for n=80 observed samples:

Count	Result	
Condition	R <sub>t</sub>	S <sub>t</sub>
R <sub>t-1</sub>	36	8
S <sub>t-1</sub>	4	32

$$Total\ Probability: P(A) = \frac{\#\ outcomes\ of\ A}{total\ outcomes}$$

$$P(R_t) = \frac{35+5}{80} = \frac{1}{2}$$

$$P(S_t) = \frac{32+8}{80} = \frac{1}{2}$$

We looked at the *total* probability of each event occurring but we haven't considered the conditional probabilities. Let's say the data looked like this for n=80 observed samples:

Count	Result	
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R <sub>t-1</sub>	36	8
S <sub>t-1</sub>	4	32

$$\frac{all\ outcomes\ resulting\ in\ A\ and\ B}{total\ outcomes}$$

$$P(R_t \cap R_{t-1}) = 36/80 = 0.45$$
  
 $P(R_t \cap S_{t-1}) = 4/80 = 0.05$   
 $P(S_t \cap R_{t-1}) = 8/80 = 0.10$   
 $P(S_t \cap S_{t-1}) = 32/80 = 0.40$ 

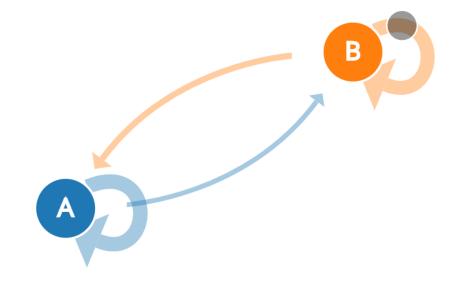
We looked at the *total* probability of each event occurring but we haven't considered the conditional probabilities. Let's say the data looked like this for n=80 observed samples:

Conditional Probability 
$$P(B|A) = P(A \cap B)/P(A)$$

Probability	Result		
Condition	R <sub>t</sub>	S <sub>t</sub>	
R <sub>t-1</sub>	$P(R_t R_{t-1}) = 0.45/0.5 = 0.90$	$P(S_t R_{t-1}) = 0.10/0.5 = 0.20$	
S <sub>t-1</sub>	$P(R_t S_{t-1}) = 0.05/0.5 = 0.10$	$P(S_t S_{t-1}) = 0.40/0.5 = 0.80$	

#### Markov Chains

The thickness of the lines represents the conditional probability.



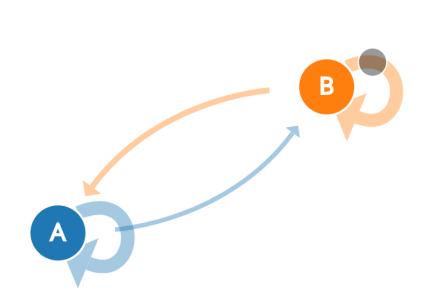
For Markov chains, this is known as the transition matrix:

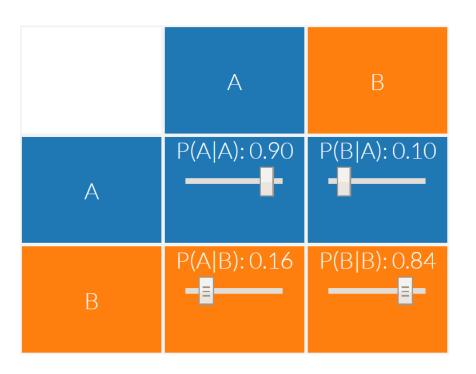
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#### Markov Chains

This is all shown interactively at the following website:

http://setosa.io/ev/markov-chains/





#### What is a hidden Markov model?

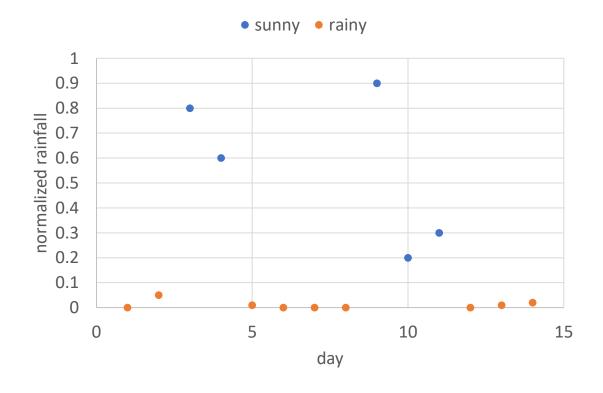
Wikipedia: a statistical Markov model in which the system being modeled is assumed to be a Markov process with *unobserved* (i.e. hidden) states.

Weather example: where the states were the observed data (this is a Markov model)

What if we want to predict how much precipitation is going to occur rather than whether it will by rainy or sunny?

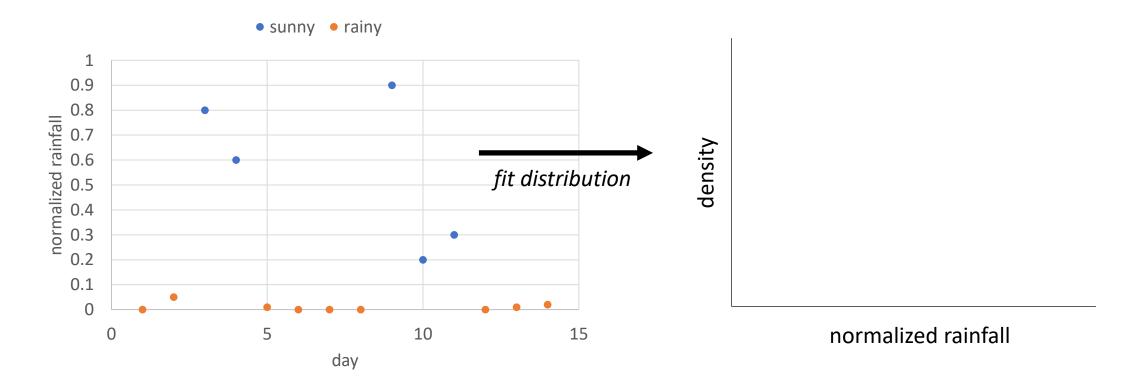
#### HMM: 2-state precipitation example

**NEW weather example:** where we want to predict precipitation and we notice that there seem to be different states.



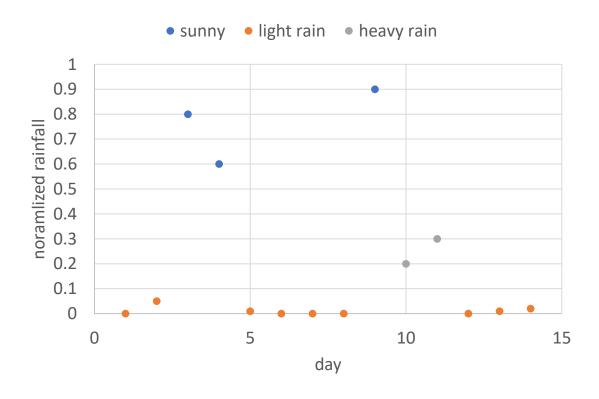
### HMM: 2-state precipitation example

**NEW weather example:** where we want to predict precipitation and we notice that there seem to be different states.



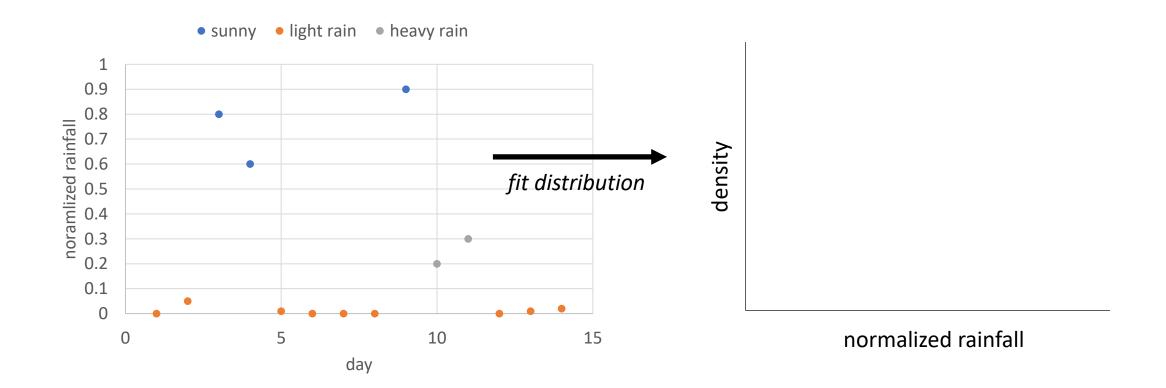
# HMM: 3-state precipitation example

Why do we think it is two states? Could there be a third?



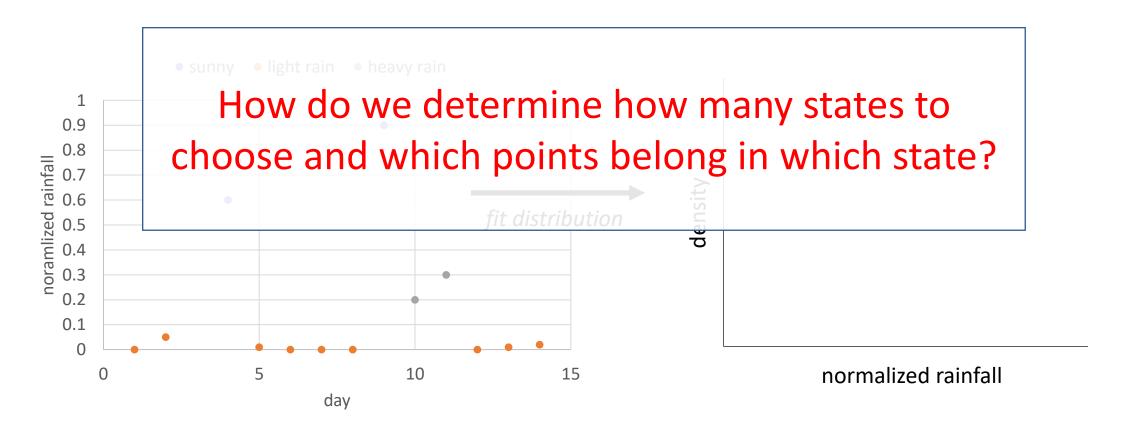
# HMM: 3-state precipitation example

Why do we think it is two states? Could there be a third?



# HMM: 3-state precipitation example

Why do we think it is two states? Could there be a third?



#### Important HMM algorithms

 Baum-Welch (aka the Forward-Backward algorithm): automatically estimates parameters of HMM

```
HiddenMarkov package function: BaumWelch()
```

 Viterbi: predicts the most likely sequence of Markov states given the observed dataset

```
HiddenMarkov package function: Viterbi()
```

