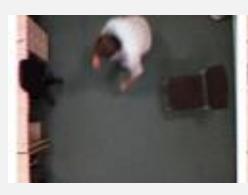
Edge Computing of YOLO for use in Fall Detection

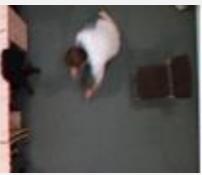
Ben Hempelmann and Cameron Legg

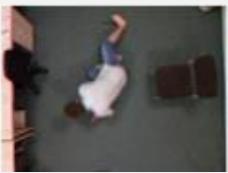
Project Overview

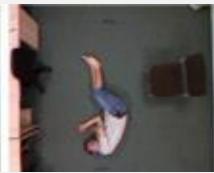
Original Plan

- Detect human falls using a computer vision approach
 - This does not require wearables or other sensors
- Run YOLO Darknet on a Raspberry Pi, using the OAK-D camera and its built-in hardware accelerator and compare with Coral USB TPU





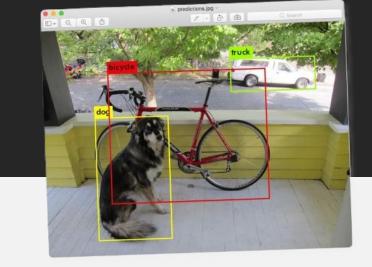




Changed Plans

- Run YOLO Darknet on Nvidia Jetson Orin NX and Oak-D Camera
 - Compute inferences on
 - Oak-D Camera
 - GPU
 - CPU
 - For benchmarking a 5 minute video was passed as a stream to the models
 - The camera feature of the OAK-D was not used, just the processor
 - The benchmarking scripts took the average power consumption and fps every 300 frames.

YOLO



- Convolutional Neural Network
- How Fall Detection Works
 - 3 Classes: Sitting, Walking, Fall_Detected
 - Fall_Detected is triggered when someone is laying down
- Parallelization Improves Performance
 - Based on CNNs
 - Applies kernals across different parts of the image
 - Many matrix operations



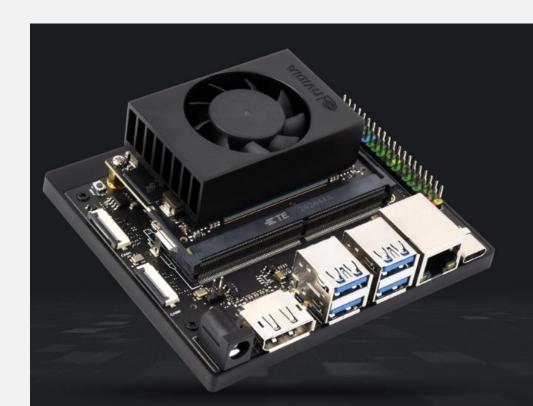
Training YOLO

- Found a dataset of Labeled Walking/Sitting/Fall_Detected images
 374 Images for training / 111 for validation
- Trained a YOLOv11 model using Google Colab
- Model trained on 640p images

Acceleration Frameworks

Nvidia Jetson Orin NX

- Ampere GPU 1024 Nvidia Cuda Cores
- 8 Core Arm Cortex-A78AE CPU



OAK-D Camera

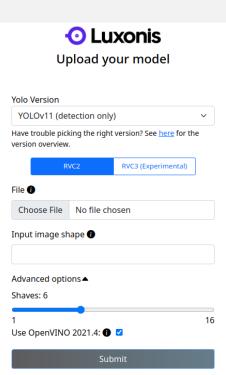
- Based on Robotics Vision Core 2 (RVC2)
 - System on a Chip Architecture
 - Uses Intel Movidius Myriad X Vision Processing Unit
 - Used for on-device deep neural network and computer vision applications
 - 2xLeon CPU cores
 - 16x SHAVE cores
 - Vector Processing Units
 - Max power consumption of 4.5W
 - 2x NCEs (Neural Compute Engines)



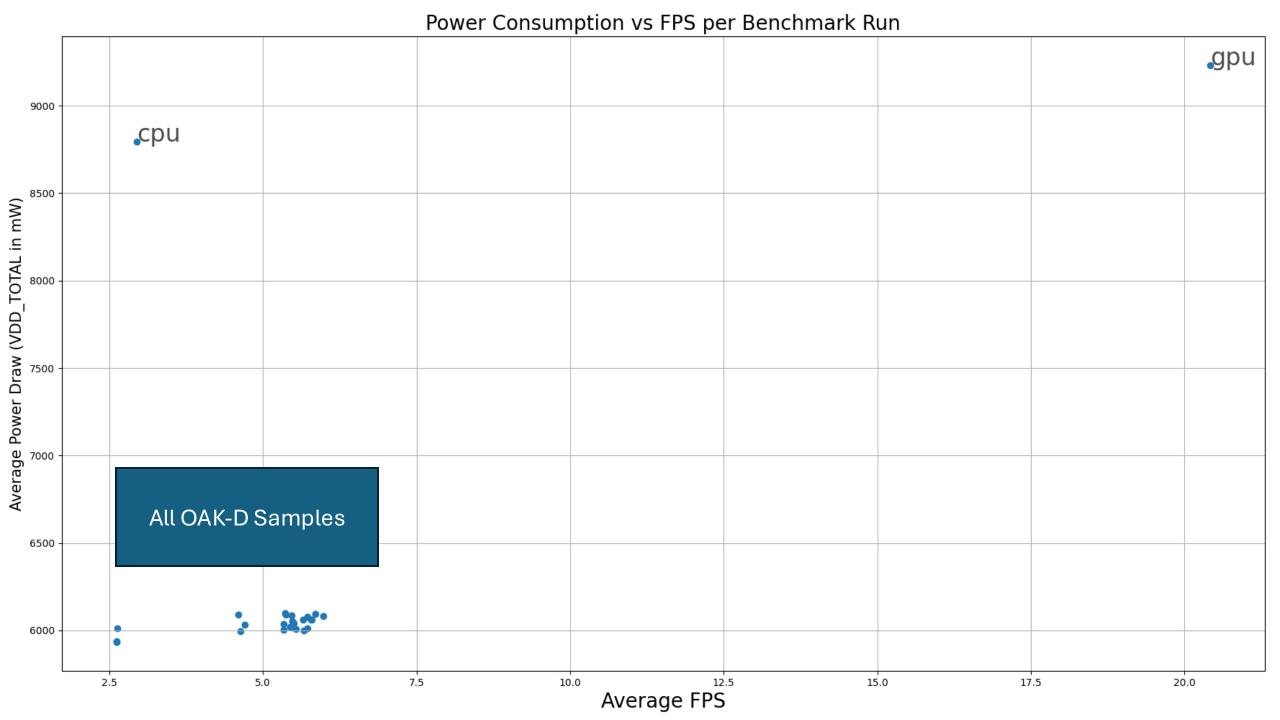


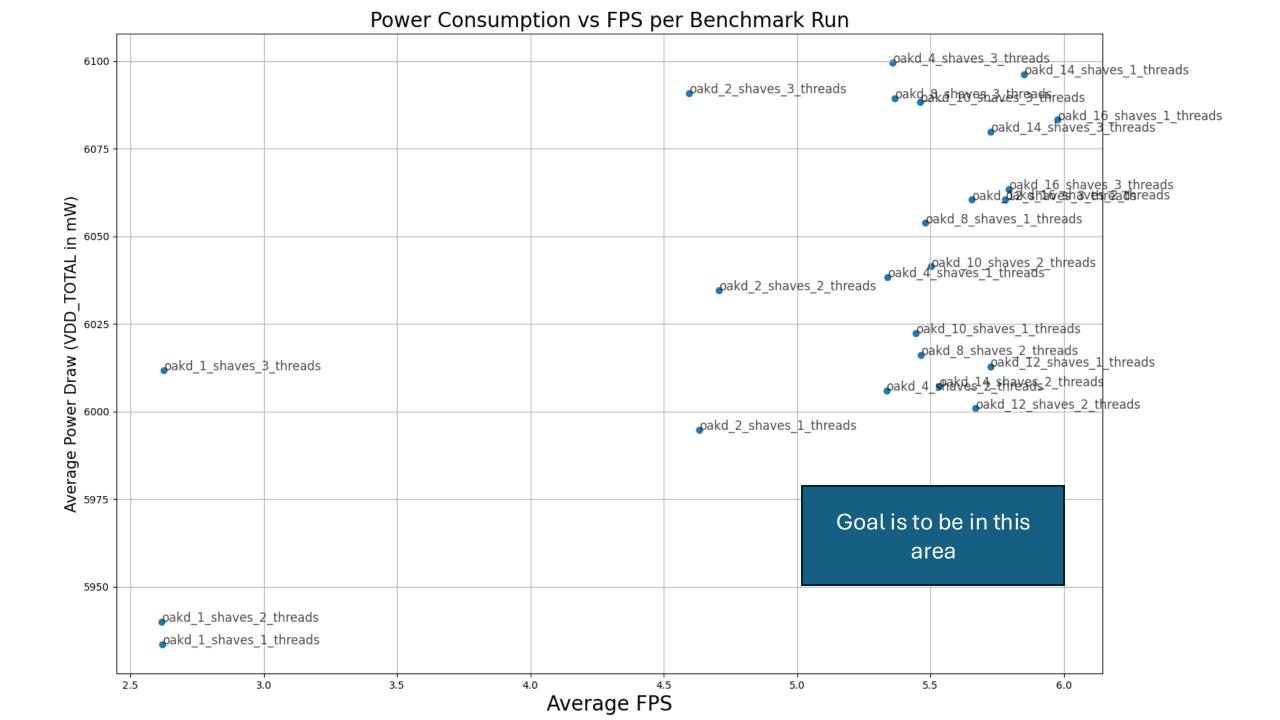
Runtime Framework / Programing Interface

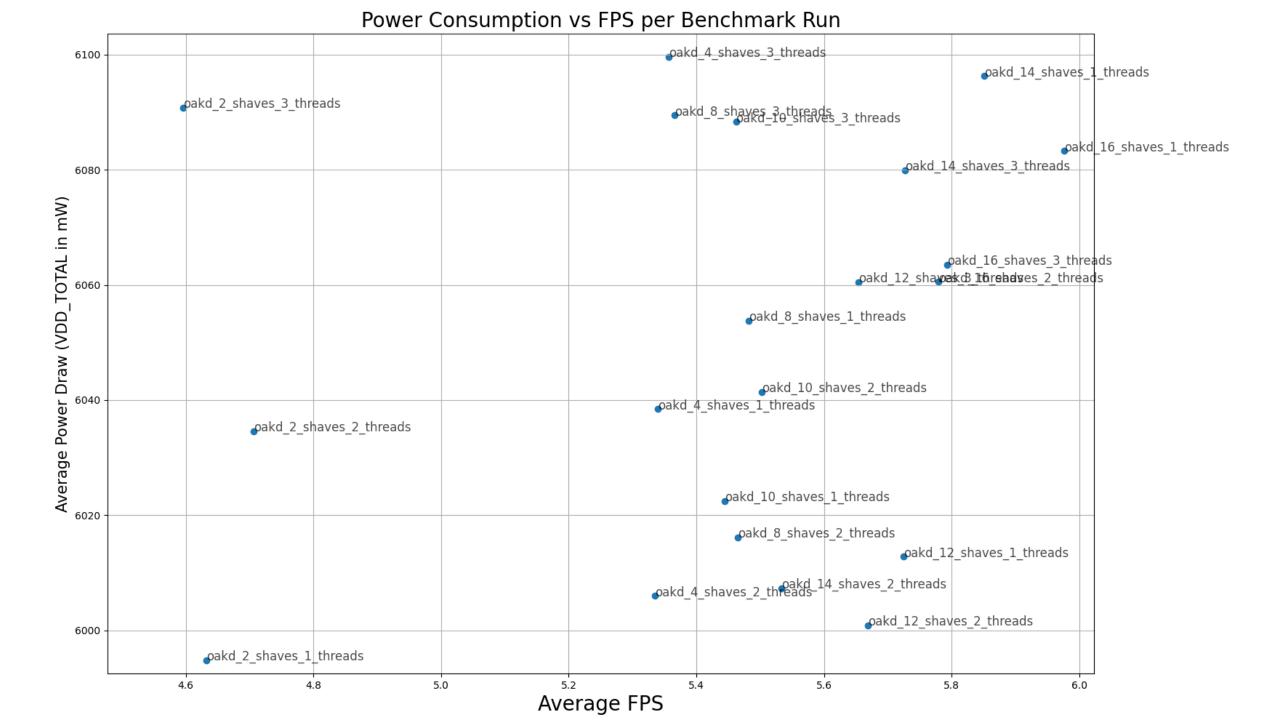
- Used Depth AI Python Library
- Runs the YOLO model after it has been converted to OpenVino format
- OpenVino required for running on Movidius Myriad X
- Oak-Models are compiled with number of shaves in mind
- Difficult part was converting the model
- CPU/GPU
 - PyTorch Framework CUDA and OpenMP (Via Ultralytics library)

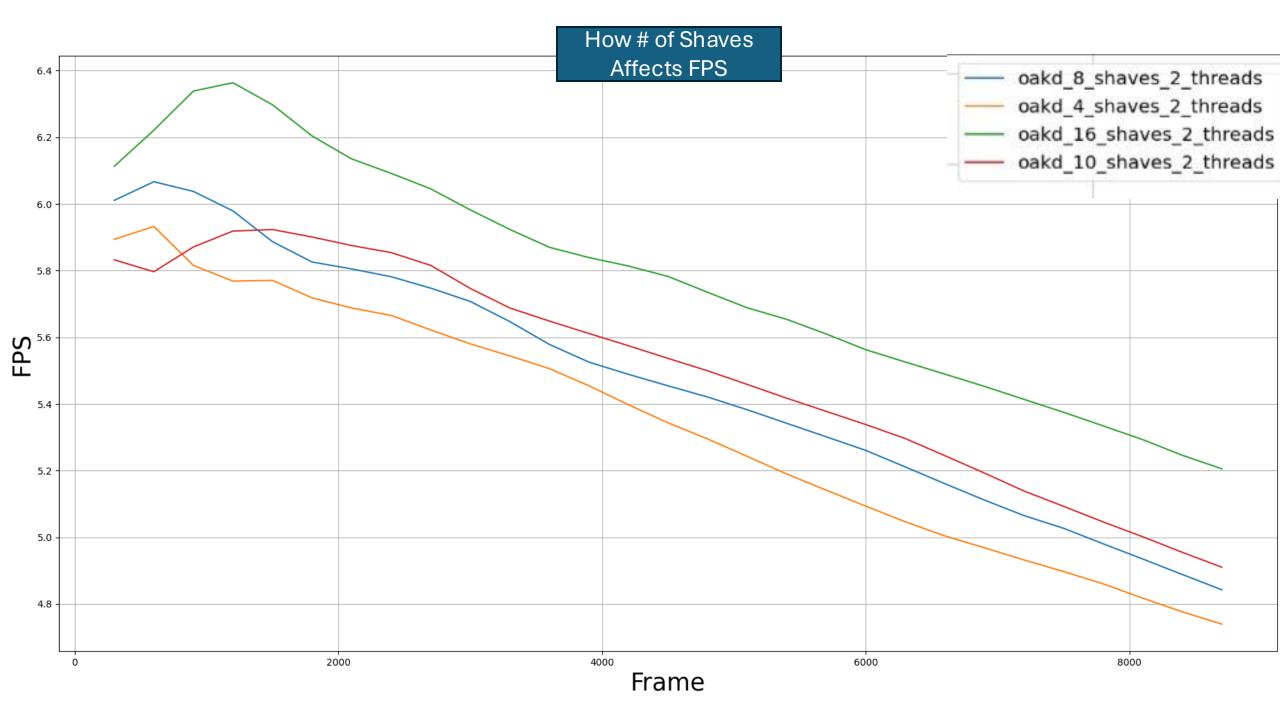


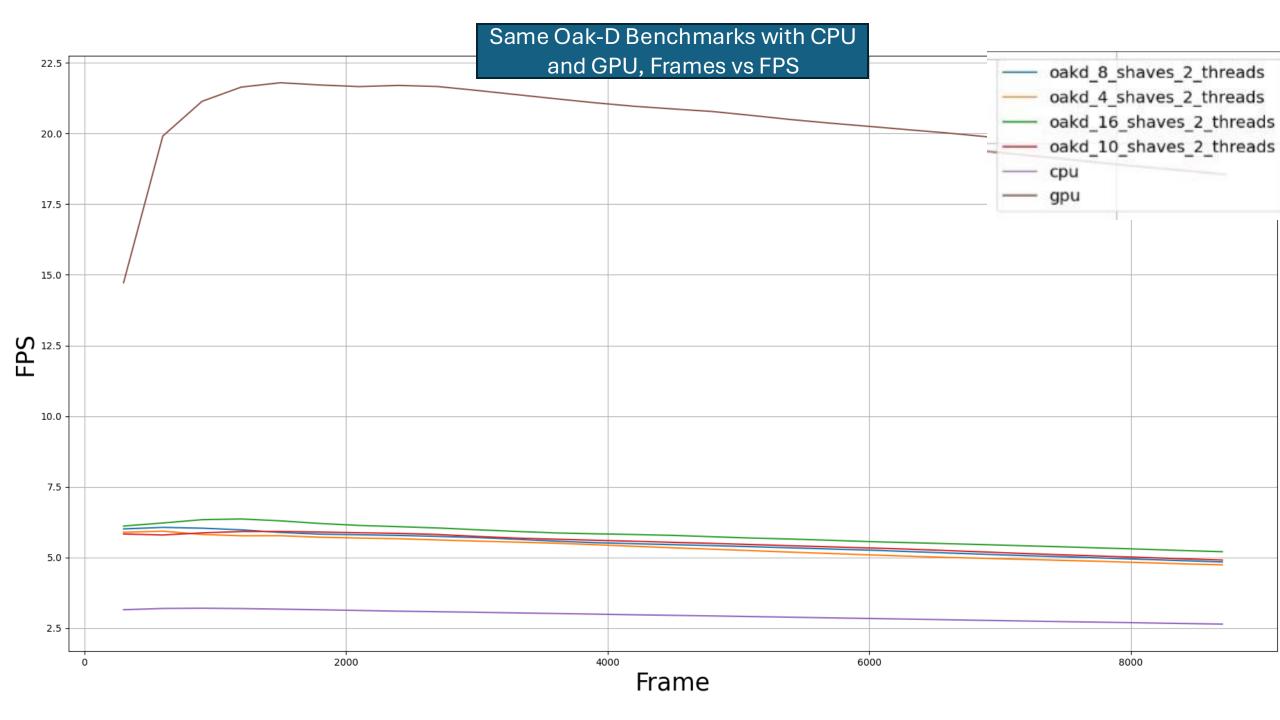
Performance Comparisons

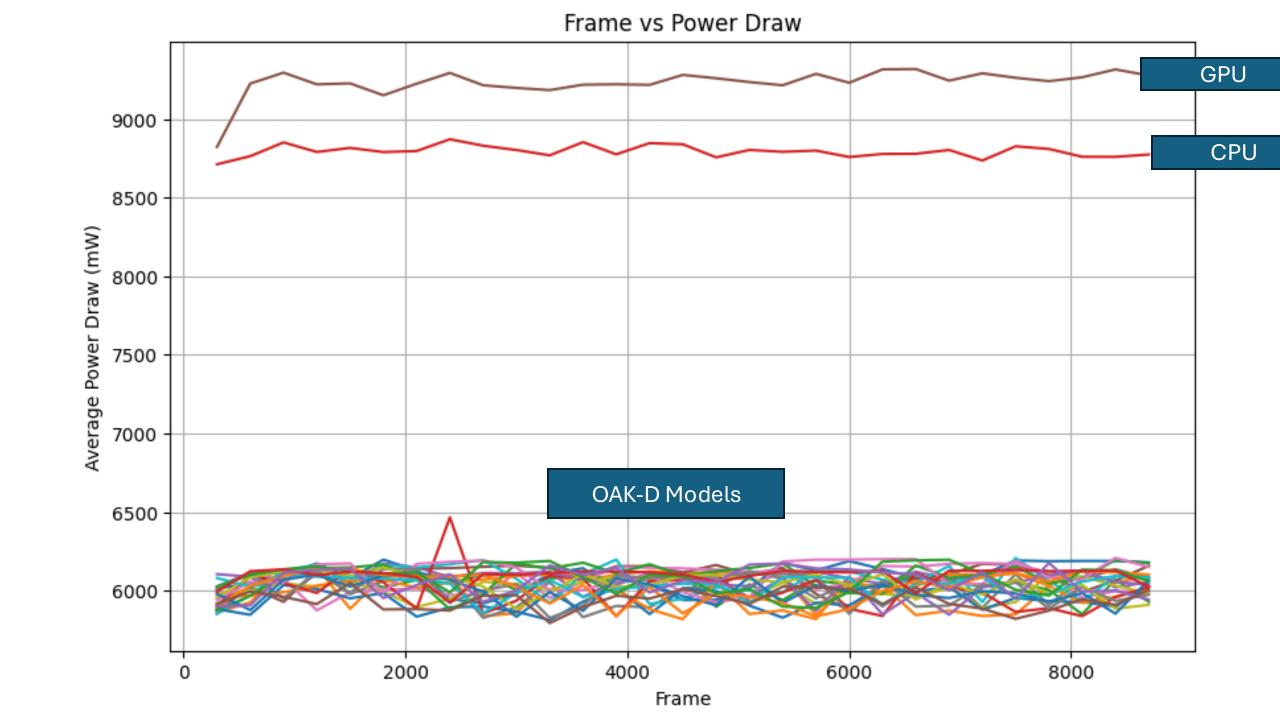




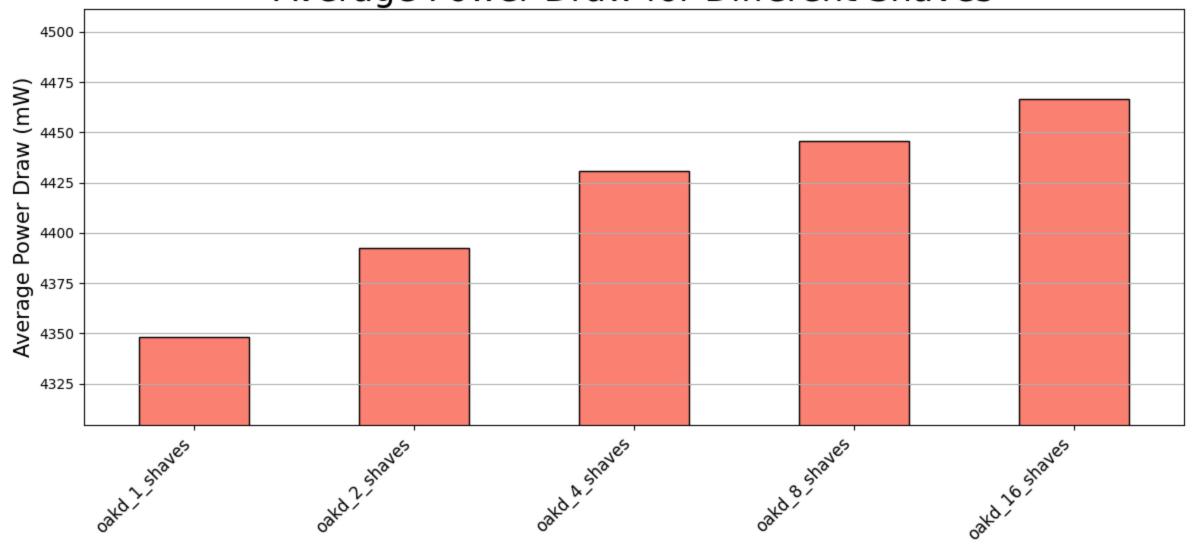


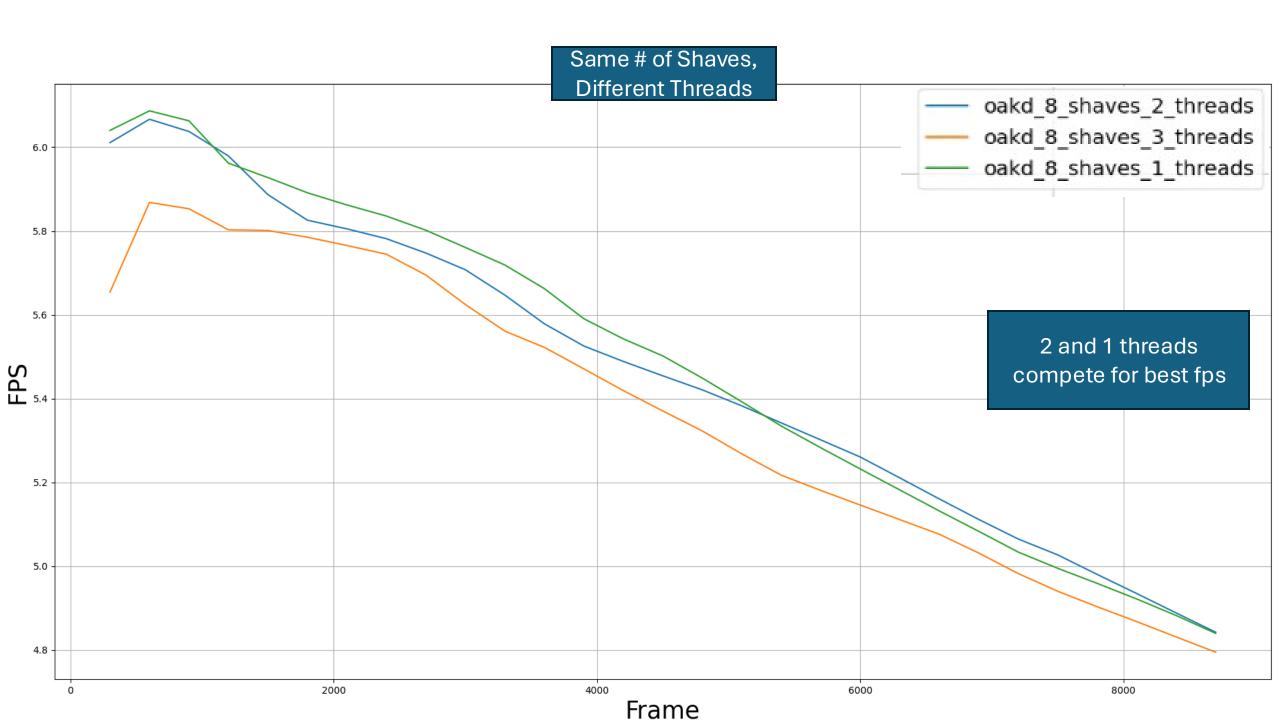


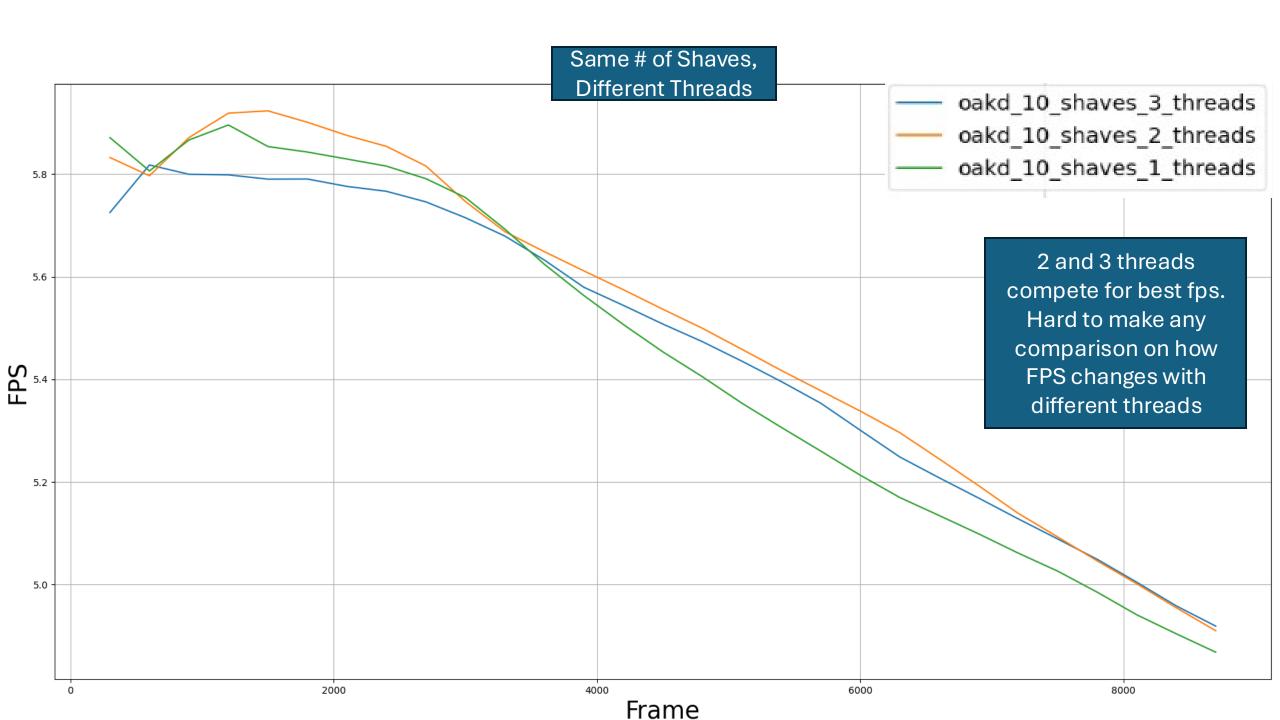




Average Power Draw for Different Shaves







Project Learnings

- Increasing number of shaves increased power consumption
- Increasing number of shaves increased inferencing frame rate
- Oak-D outperforms CPU in terms of performance and lower power consumption
- GPU outperforms Oak-D on FPS, but takes much more power
- Oak-D had the best power to FPS Ratio

Hurdles and Future Work

Project Hurdles

- Power Consumption on a Rasberry PI
 - Switched to Orin
- Testing Models with Different Shave Counts
 - You have to recompile the model for each one
- Automating Data Collection
 - Long inference times on videos to get accurate results

Future Work

- Try different file sizes/video qualities
- Inference directly from camera
- Try different models

Questions?