Simulation Methods in Physics I

Worksheet 4: Thermostats

Students:	Michael Marquardt	Cameron Stewart
matriculation numbers:	3122118	3216338

1 Random Numbers

All the functions for this task are implemented in random_numbers.py. The file random_walk.py executes the code.

1.1 Linear Congruental Gemerator (LCG)

The first exercise was to implement the LCG. In order to do this the LCG must be initialized with an overall value Xlcg.

Code block 1: Initialization of LCG script: src/random_numbers.py

```
5  def init_LCG(X):
6      '''
7      Initialize the random nuber generator with Xlgc.
8      '''
9      global Xlcg; Xlcg = X
```

The next step is to perform the LCG; therefore a function LCG() is implemented in code block 2. As you can see the values m, a and c are already given as optional parameters.

Code block 2: LCG script: src/random_numbers.py

```
11 def LCG( m=2**32, a=1664525, c=1013904223 ):
12     '''
13     Returns a normal distributed random number in [0,m-1]
           (natural number).
14     '''
15     global Xlcg
16     Xlcg = ( a*Xlcg + c ) % m
17     return Xlcg
```

Later we want to use the time.time() as a starting value. Therefore the function do2int() is defined which converts a float into an integer by passing the decimal marker after the last relevant number.

Code block 3: do2int script: src/random_numbers.py

```
25 def do2int(x):
26     '''
27     takes a double and converts it into an integer by
           changing the place of the decimal dot behind the
           last relevant place.
28     EXAMPLE: 123.456 -> int(123456)
29     '''
30     while x % 1:
```

```
31              x *= 10
32      return int(x)
```

At last the function normal_LCG() returns a normalized value in [0,1]. Therefore the result must be divided by m-1.

Now it is time to run the random number generator and simulate a random walk. Therefor the function random_walk() is used to generate an 1D random walk with a maximum velocity of ± 0.5 per time step.

Code block 4: Random walk script: src/random_numbers.py

```
34 def random_walk( N=1000 ):
35     '''
36     returns a random walk for N steps with an deviation in
           [-0.5,0.5]
37     '''
38     x = zeros(N+1)
39     for k in range(0,N):
40             x[k+1] = x[k] + normal_LCG() - 0.5
41
42     # Plot
43     plot(range(0,N+1),x,label=r'random walk')
44     xlabel('time')
45     ylabel('position')
46     savefig('../dat/random_walk.png')
47     close()
```

The script random_walk.py takes an optional command line parameter –Xlcg. You can use it to set the starting value Xlcg manually. If it is not given do2int(time.time()) is used. Notice, that you have to use python3 in order to get good results from the time function.

If you perform the random walk several times with the same –Xlcg the trajectory appears to be the same every time. By using time.time() as initialization you obey completely different trajectories every time. You can see one of this trajectories in graphic 1.

To conclude, the LCG is not really a good random number generator. Although it takes a long time until the numbers repeat in the same order in between, there can be no number which was already obeyed. Due to this the random numbers are correlated especially for many used numbers. Furthermore a bad choice of m, a and c will lead to very bad and no longer uniform random number distribution.

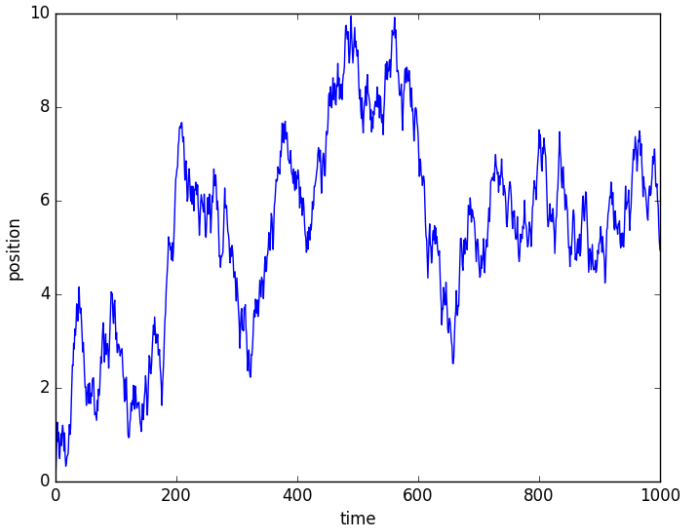

Fig. 1: Random walk for initialization with time.time().

1.2 Box-Muller (BM)

The next exercise is to transform uniformly distributed random numbers into normal distributed one. Therefor the Box-Muller transform is given. It's implementation is split up into two functions. calc_BM() takes two uniform distributed random numbers u1 and u2 and returns the function from the worksheet. The function BM() arranges the usage of calc_BM() in a way that allows to obey an array of $N > 1$ normal distributed random numbers. In order to get better results the function random.random() which returns better uniformly distributed random numbers is used instead of LCG().

Code block 5: Box-Muller script: src/random_numbers.py

```
51 def calc_BM( u1, u2 ):
52     '''
53     converts uniform random numbers into normal
           distributet random numbers
54     '''
55     return sqrt(-2.*log(u1)) * array([cos(2.*pi*u2), sin
           (2.*pi*u2)])
56
57 def BM( N, mu=2.0, sigma=5.0 ):
58     '''
59     returns a numpy array of N normal ditributed random
           numbers
60     '''
61     n = int(ceil(N/2.))
```

```
62      bm = zeros((n,2))
63      for k in range(0,n):
64              bm[k,:] = sigma*calc_BM(random.random(),
                    random.random()) + mu
65      return bm.flatten()
```

The function gauss() just returns the Gaussian probability distribution:

$$p(x) = \frac{1}{\sqrt{2\pi}\sigma}\exp\left(-\frac{x^2}{2\sigma^2}\right) \tag{1}$$

Analogous the function gauss_3d() returns the three dimensional Gaussian:

$$p(\boldsymbol{r}) = \sqrt{\frac{2}{\pi}}\frac{\boldsymbol{r}^2}{\sigma^3}\exp\left(-\frac{\boldsymbol{r}^2}{2\sigma^2}\right) \tag{2}$$

In order to test the BM a function show_BM_hist() was created. It draws a histogram of 1000 by the BM() created random numbers in a diagram with the gauss(). You can pass different σ, μ and therefor also new x-axis-limits. The option bars states how many bars you want to have for the histogram. The results can be seen in graphic 2.

Code block 6: Box-Muller histogram script: src/random_numbers.py

```
73  def show_BM_hist( N=10000, mu=2.0, sigma=5.0, limits
        =[-15,20], bars=150 ):
74      '''
75      draws gaussian and hist of random numbers with BM
76      '''
77      bins=linspace(limits[0], limits[1], bars)
78
79      BM_numbers = BM(N, mu, sigma)
80
81      x = linspace(limits[0], limits[1], 1000)
82      gauss_fun = gauss(x, mu, sigma)
83
84      plot(x, gauss_fun, label=r'gauss: $\mu={} \sigma={}$'.
            format(mu,sigma))
85      hist(BM_numbers, bins, normed=1, label=r'BM    : $\mu
            ={} \sigma={}$'.format(mu,sigma))
86      legend()
87      savefig('../dat/BM_hist.png')
88      close()
```

The last exercise was to transform the same principal into three dimensions. You can use the function rand_vel_vec() in order to create a $N \times 3$ vector of BM random numbers (velocity vector). The function show_vel_hist() in code block 7 takes the absolute values

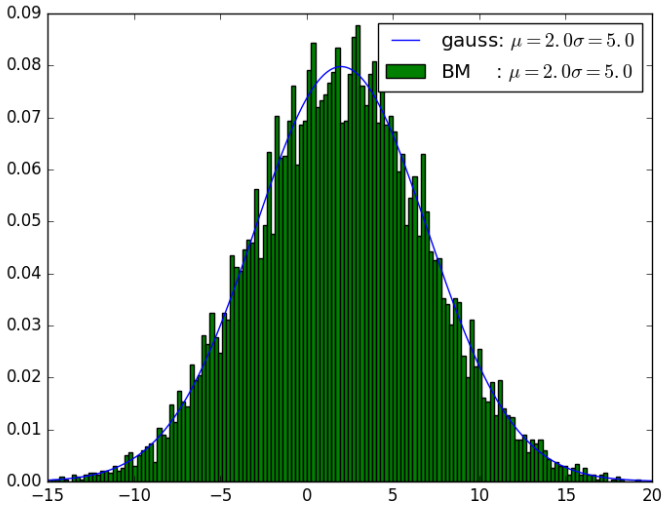

Fig. 2: Histogram of the BM random number distribution and the Gaussian function (1).

of this velocities vel_abs and draws them as histogram against the three dimensional Gaussian (2).

Code block 7: 3D Box-Muller histogram script: src/random_numbers.py

```
105 def show_vel_hist( N=1000, sigma=1., limits=[-0,5], bars
    =100 ):
106     '''
107     draws gaussian and hist of the velocity distribution
108     '''
109     bins=linspace(limits[0], limits[1], bars)
110
111     vel_abs = linalg.norm(rand_vel_vec(N, sigma), axis=1)
112
113     r = linspace(limits[0], limits[1], 1000)
114     gauss_fun = gauss_3d(r, sigma)
115
116     plot(r, gauss_fun, label=r'gauss: $\sigma={}$'.format(
        sigma))
117     hist(vel_abs, bins, normed=1, label=r'BM    : $\sigma
        ={}$'.format(sigma))
118     legend()
119     savefig('../dat/vel_hist.png')
120     close()
```

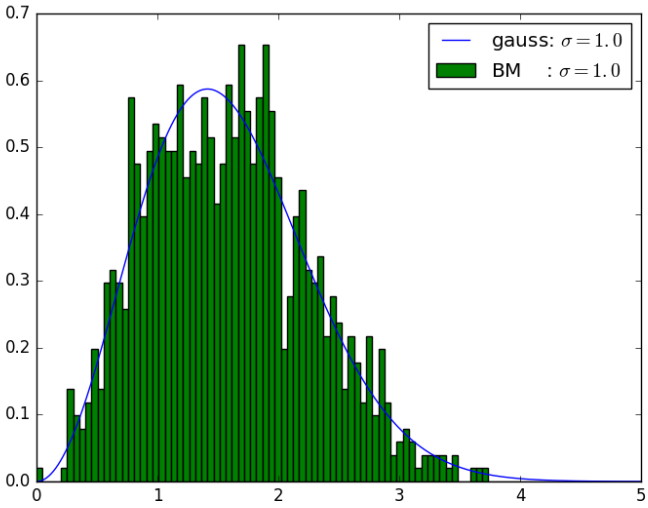

Fig. 3: Histogram of the BM random velocities and the 3D Gaussian function (2).

As you can see the histograms fit to the expected distribution in both cases.

Notice that it would not make sense to set an $\mu \neq 0$ unless you have a drift which means an overall velocity trend in a specific direction.

2 Langevin Thermostat

At first notice that the script ljsim.py was changed in such a way that you can pass more command line parameters via argparse. The simulation ID is now passes via –ID.

The Langevin thermostat simulates a solvent in which causes friction and random forces (through collisions). It allows to conserve the canonical (N,V,T)-ensemble.

2.1 Implementation

The implementation of the formulas which were given on the worksheet is done in code block 8.

Code block 8: Langevin thermostat script: src/ljsim.py

```
94 def step_vv_langevin(x, v, f, dt, xup):
95     '''
96     velocity verlet for langevin thermostat
97     '''
98     global rcut, skin, gamma, T_des
```

```
99
100     # update positions
101     x += v*dt*(1.-0.5*gamma*dt) + 0.5*f*dt*dt
102
103     # half update of the velocity
104     v += -0.5*gamma*dt*v + 0.5*f*dt
105
106     # for this excercise no forces from other particles
107     f = sqrt( 24.*T_des*gamma/dt ) * ( random.random(x.
            shape) - 0.5 )
108
109     # second half update of the velocity
110     v += 0.5*f*dt
111     v /= 1.+0.5*gamma*dt
112
113     return x, v, f, xup
```

The random force is generated in line 114 with the the function $\boldsymbol{W}_i(t) = \sqrt{12}\sigma \cdot a$ where a is a uniform random number between -0.5 and 0.5 and the standard deviation $\sigma = \sqrt{\frac{2mk_BT\gamma}{\Delta t}}$.

The script allows to take the optional command line argument –gamma which is default $\gamma = 0.3$. Furthermore the main loop is modified in such a way, that it stores the trajectory, the velocities and the temperatures in the *.dat-file, so that you can not only restart the simulation but also get knowledge about the former simulation data. The new command line parameter –restart allows you to restart a simulation instead of continuing it.

2.2 Simulation

Now the simulation can be performed. The desired temperature T_des can be set by –T and is default 1.0. The result of the simulation is shown as a plot of temperature over time 4.

In order to check weather the Maxwell-Boltzmann distribution for the velocities is fulfilled a histogram of the velocity distribution is drawn in figure 5. Of course the distribution is meant over over time, because we are simulationg only one particle, but the script allows also to get a distribution also over all particles if we set other initial conditions with more than one particle. For a physical system with Temperature T, the deviation is $\sigma = \sqrt{T}$.

Code block 9: Calculation of the histogram script: src/ljsim.py

```
290 # Velocity distribution
291 r = linspace(0, 10, 1000)
```

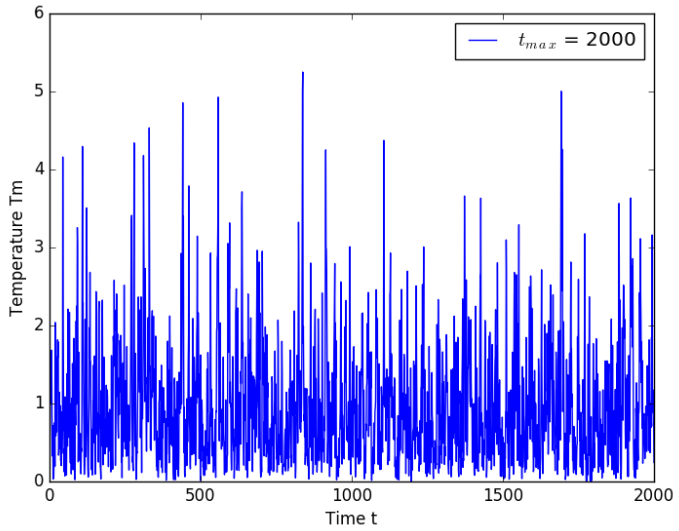

Fig. 4: Plot of the temperature over time for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Langevin thermostat and $\gamma = 0.3$.

```
292 gauss_fun = gauss_3d(r, sqrt(T_des))        # function from
        random_numbers.py
293 plot(r, gauss_fun, label=r'gauss')
294 hist(linalg.norm(array(vs), axis=1).flatten(), linspace
       (0,10,100), normed=1, label=r'simulation, $t_m$$_a$$_x$
        = {}'.format(round(t)))
295 xlabel('Velocity v')
296 ylabel('Frequenzy of v in time')
297 legend()
298 savefig('../dat/{}_vv.png'.format(simulation_id))
299 close()
```

The figures show that the simulated velocity behaves like we physically expect it to behave. The temperature is varies around 1.0 with many high peaks in between, but the velocity distribution clearly fits the expected Gaussian.

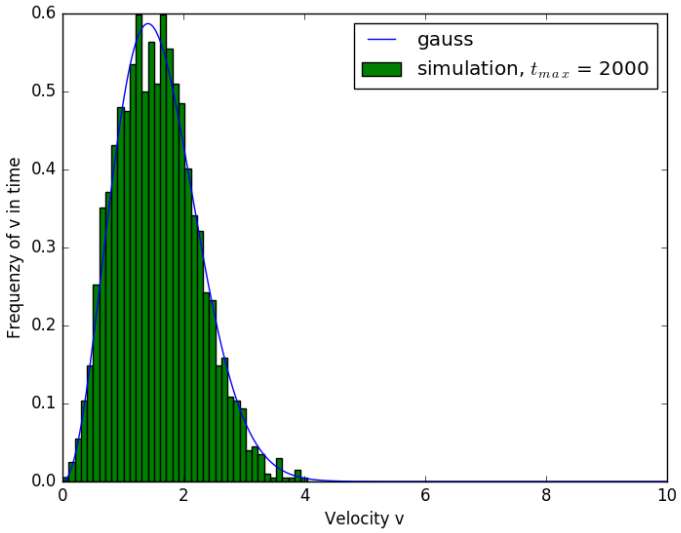

Fig. 5: Histogram for the distribution of the absolute of the velocities in time for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Langevin thermostat and $\gamma = 0.3$.

3 Andersen Thermostat

The Andersen thermostat is an easier model than the Langevin thermostat. As before we assume a solvent but now there is no friction but only random velocity replacement. We simply state, that a particle gets a normal distributed velocity through collisions with the solvent with a certain probability. The mean difference is that we are are not assuming a random **force** but a new random **velocity**, no matter which velocity the particle had before. This is not physical!

Due to this the Andersen thermostat creates a (N,V,T)-ensemble, but not allows to determine dynamical properties of the system, because the random velocity replacement destroys the memory of the system (especially if there is only one particle or no interaction between particles).

3.1 Implementation

For the Andersen thermostat most parts of the existing script can be used. The new part is the function step_vv_andersen() which you can see in code block 10.

Code block 10: Andersen thermostat — script: src/ljsim.py

```
115 def step_vv_andersen(x, v, f, dt, xup):
116     '''
117     velocity verlet for anderson thermostat
```

```
118         '''
119         global rcut, skin, nu, T_des
120 
121         # update positions
122         x += v*dt + 0.5*f * dt*dt
123 
124         # half update of the velocity
125         v += 0.5*f * dt
126 
127         # for this excercise no forces from other particles
128         f = zeros_like(x)
129 
130         # second half update of the velocity
131         v += 0.5*f * dt
132 
133         # random velocity replacing:
134         for k in range(0,v.shape[1]): # (only one particle to
                test, but extendable or more)
135             if random.random() < nu*dt:
136                 v[:,k] = sqrt(T_des)*random.randn(3)
137 
138         return x, v, f, xup
```

The function equals the original step_vv() function except that there is the velocity replacement at the end. In line 141 it loops over all particles. This may not be necessary when simulating only one particle, but it allows to use other initial conditions for the same script with more than one particle. The next line asks weather a random number is smaller than $\nu\Delta t$ where –nu allows you to pass a parameter nu (default: $\nu = 0.1$). This term represents the probability for a stochastic collision. If the statement is fulfilled the velocity of the selected particle is replaced by a normal distributed random velocity with a deviation of $\sigma = \sqrt{T_{\text{des}}}$.

3.2 Simulation

Simulating with the Andersen thermostat works exactly like in the former task. The results can be seen in the figures 6 and 7.

As you can see the temperature is also varying around 1.0 but not with the same regularity. The velocity distribution comes near to the Gaussian but it does not fit as good as for the Langevin thermostat.

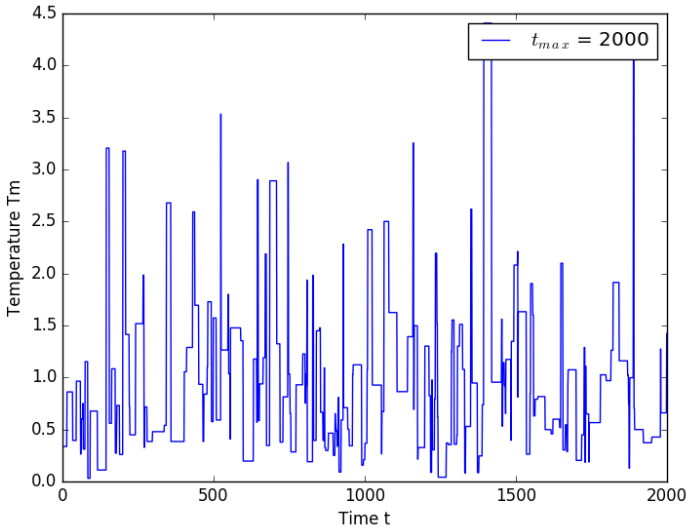

Fig. 6: Plot of the temperature over time for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Andersen thermostat and $\nu = 0.3$.

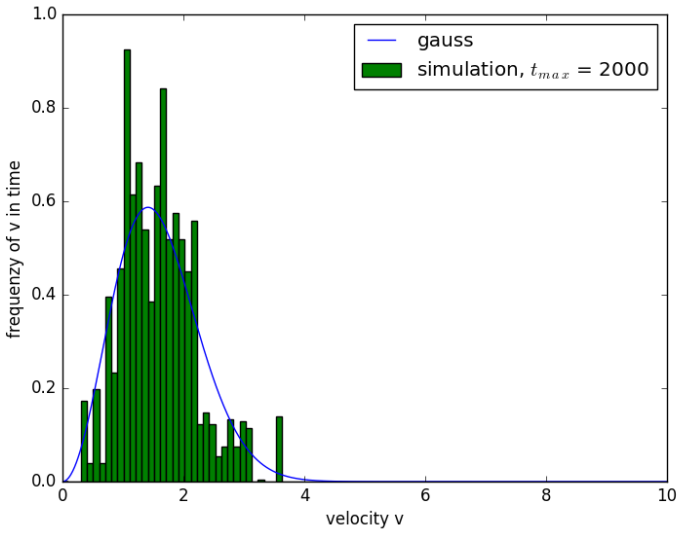

Fig. 7: Plot of the temperature over time for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Andersen thermostat and $\nu = 0.3$.

4 Berendsen Thermostat

The Berendsen thermostat is very similar to the velocity-rescaling on the former worksheet. It just multiplies the velocities of all particles with a factor $\lambda = \sqrt{1 + \frac{\Delta t}{\tau_T}\left(\frac{T_{\text{des}}}{T_{\text{act}}} - 1\right)}$ so that the Thereby T_{act} is the actual temperature. As the mentioned velocity-rescaling this thermostat does no physical stuff and is not useful for observing the dynamics of a system.

4.1 Implementation

The implementation is as easy as possible. The function step_vv_berendsen() equals step_vv() but in line 159 the temperature is measured in order to rescale velocities in line 160.

Code block 11: Berendsen thermostat script: src/ljsim.py

```
140 def step_vv_berendsen(x, v, f, dt, xup):
141     '''
142     velocity verlet for berendsen thermostat
143     '''
144     global rcut, skin, tau, T_des
145 
146     # update positions
147     x += v*dt + 0.5*f * dt*dt
148 
149     # half update of the velocity
150     v += 0.5*f * dt
151 
152     # for this excercise no forces from other particles
153     f = zeros_like(x)
154 
155     # second half update of the velocity
156     v += 0.5*f * dt
157 
158     # velocity rescaling
159     T_act = compute_temperature(v)
160     v *= sqrt( 1 + ( T_des/T_act - 1 )/tau )
161 
162     return x, v, f, xup
```

The parameter tau (τ_T) can be set by –tau and has a default value of 3.0.

4.2 Simulation

The simulation is done in the same way as for the other thermostats. The results can be seen in the figures 8 and 9.

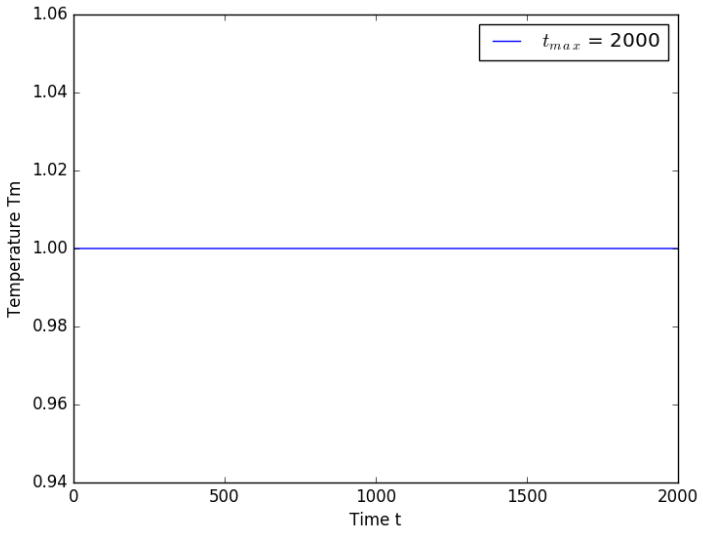

Fig. 8: Plot of the temperature over time for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Berendsen thermostat and $\tau_T = 3.0$.

As you can see the results differ from the further tasks. The temperature is constant at the desired temperature 1.0. There is no fluctuation any more. It is the same for the velocities. The velocity stays constant at a value which gives us the right temperature. There is no Gaussian at all. Of course this will look different for more than one particle with pair interactions, but it would also not fulfill the Gaussian.

Because of this the Berendsen thermostat is the worst of the three thermostats (in a physical meaning).

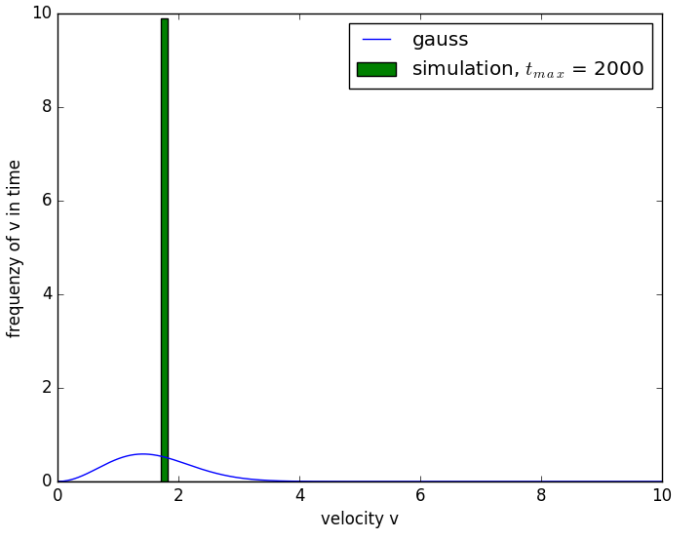

Fig. 9: Plot of the temperature over time for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Berendsen thermostat and $\tau_T = 3.0$.

5 Diffusion

For this exercise the new script ljanalyze.py was created. It reads the data ot of a *.dat-file which is given by –ID like in ljsim.py.

5.1 Implementation

5.1.1 Mean Squared Displacement (MSD)

The MSD is defined by:

$$\left\langle \Delta x^2 \right\rangle (\Delta t) = \frac{1}{N} \sum_{k=1}^{N} \left| \boldsymbol{x}\left(k\Delta t\right) - \boldsymbol{x}\left(\left(k-1\right)\Delta t\right)\right|^2 \tag{3}$$

Notice that Δt is not the simulation timestep, but a duration for a sub-trajectory. Later it will be in $(0, T]$ where T is the simulation time.

From the MSD we can derive the diffusion constant D by fitting the following expression to the MSD.

$$\left\langle \Delta x^2 \right\rangle = 2D_x d\Delta t \tag{4}$$

Where $d = 3$ is the dimension of $\boldsymbol{x}$. The x in D_x means that it was derived from the position because later we derive it from the velocity v.

The function calc_msd() performs equation (3). The while loop in line 61 goes over all possible $0 < k\Delta t < T$. Because of the fact, that the simulation times (nearly) equal their index ndt is an integer.

Code block 12: MSD calculation — script: src/ljanalyze.py

```
54 def calc_msd( ndt, x ):
55     '''
56     calculates the msd for time steps of dt = ts[ndt] - ts
       [0]
57     '''
58     n = shape(x)[0]/ndt
59     k = 1
60     msd = 0.
61     while k < n:
62         msd += sum( ( x[ndt*k,:] - x[ndt*(k-1),:] )**2 )
63         k += 1
64     return msd / (k-1.)
```

In the main loop (code block 13) the calculation is done for all Δt in steps of 1 until dtmax is reached. You can set dtmax by –dtmax; its default is T.

Code block 13: MSD main loop — script: src/ljanalyze.py

```
81 print('Calculating MSD...')
82 msd_vec = zeros(dtmax)
83 dt = zeros(dtmax)
84 err_vec = zeros(dtmax)
85 for k in range(1,dtmax+1):
86     msd_vec[k-1] = calc_msd( k, xs )
87     dt[k-1] = ts[k]-ts[0]
88     err_vec[k-1] = calc_err( k, msd_vec[k-1], xs )
```

In the main loop also an error is detected by calc_err(). It works like:

$$\Delta\left\langle\Delta x^2\right\rangle = \sqrt{\frac{\sum_{k=1}^{N}\left\{\left|\boldsymbol{x}\left(k\Delta t\right)-\boldsymbol{x}\left(\left(k-1\right)\Delta t\right)\right|^2-\left\langle\Delta x^2\right\rangle\right\}^2}{N\cdot\left(N-1\right)}} \tag{5}$$

You can see the code in code block 14.

Code block 14: MSD error — script: src/ljanalyze.py

```
66 def calc_err( ndt, msd, x ):
67     '''
68     calculates the error of msd_vec
69     '''
70     n = shape(x)[0]/ndt
```

```
71      k = 1
72      err = 0.
73      while k < n:
74          err += ( sum( ( x[ndt*k,:] - x[ndt*(k-1),:] )**2 )
                - msd )**2
75          k += 1
76      if k > 2:
77          return sqrt( err / ( (k-1.)*(k-2.) ) )
78      else:
79          return 0.
```

As you can see the error is set to zero if $N = 1$ in line 78-79 in order to provide division by zero. In this area no representative error can be estimated any more.

The fit is done with a simple order 1 numpy.polyfit(). Furthermore you can pass the regression limits via –linreg ¡min¿ ¡max¿.

Code block 15: MSD Fit script: src/ljanalyze.py

```
92 print('Fit onto MSD...')
93 p = polyfit( dt[linreg[0]:linreg[1]], msd_vec[linreg[0]:
      linreg[1]], 1 )
94 Dx = p[0] * 0.5 / float(d)
```

5.1.2 Velocity autocorrelation Function (VACF)

Another way to find the diffusion constant (now D_v) is via the VACF. It is defined by:

$$\mathrm{VACF}(t) = \langle \boldsymbol{v}(t) \cdot \boldsymbol{v}(0) \rangle \tag{6}$$

$$\approx \mathrm{normed} \left\{ \mathrm{ifft} \left(\overline{\mathrm{fft}(\boldsymbol{v})} \cdot \mathrm{fft}(\boldsymbol{v}) \right) \right\} \tag{7}$$

It can be derived from a discrete velocity vector $\boldsymbol{v}$ via Fast Fourier Transformation fft (inverse: ifft). Normed means that $\mathrm{VACF}(0) = 1$.

This Autocorrelation is implemented in code block 16. The calculation of fft is split up into the 3 dimensions. In line 118 they are added. Furthermore the while statement in 117 is not necessary for the task but allows the usage for other shapes (n,m,...) or 1D-arrays.

Code block 16: Autocorrelation function script: src/ljanalyze.py

```
110 def autocor(v):
111     '''
112     returns the autocorrelation function of vestorial
            observable v
113     It uses scalar produkt of v with itself
```

```
114     The result is normed to autocor(v)[0] = 1
115     '''
116     ftv = real( fft.ifft( conj( fft.fft(v, axis=0) ) * fft
            .fft(v, axis=0), axis=0 ) )
117     while size(ftv.shape) > 1:  # only one loop in this
            case
118         ftv = sum( ftv, axis=1 )
119     return ftv[:ftv.shape[0]//2] / ftv[0]
```

D_v now can be derived by integrating over the VACF (Green-Kubo relation). This is done in the script with numpy.trapz.

5.2 Analyze

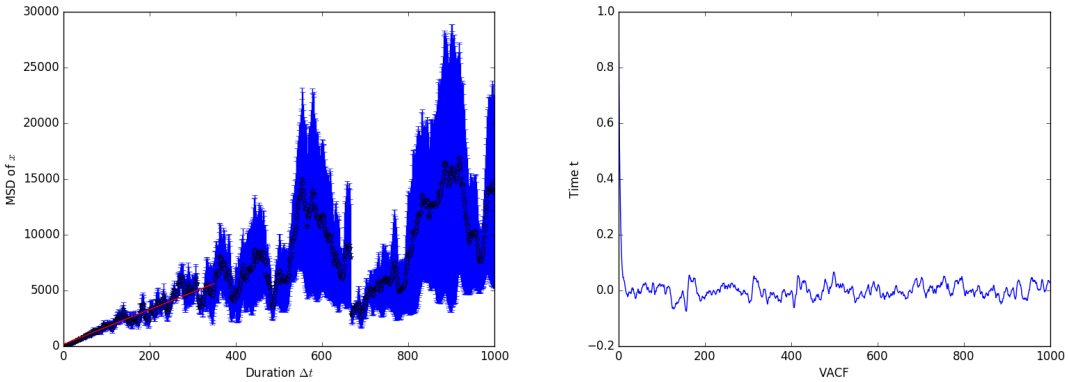

Fig. 10: Plot of the MSD (left) and the VACF (right) for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Langevin thermostat and $\gamma = 0.3$.

Now we can analyze the simulation data. Therefor some new data with different coefficients was created. The plotted MSD and VACF is shown in the figures 10 until 16.

As you can see the MSD is only linear at the beginning. For higher Δt the MSD fluctuates heavily because of the lesser number of values for the calculation. As you can see for example in picture 10 the linear regression is only done in the area in which the red line is drawn.

By taking a look at figure 16 you can see that there is no linear behaviour at all, but a quadratic behavior. This is because the velocity does not change at all and therefor the distance Δx grows linear in t and the MSD therefor quadratic.

Figure 15 shows that for tiny $\nu = 0.01$ the behavior of the MSD also loose its linear beginning. There are not many collisions any more and the velocity is changed not often.

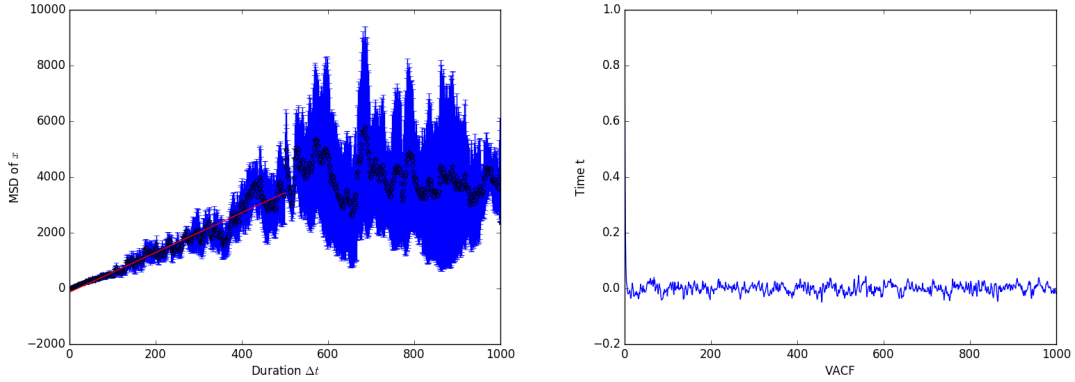

Fig. 11: Plot of the MSD (left) and the VACF (right) for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Langevin thermostat and $\gamma = 0.8$.

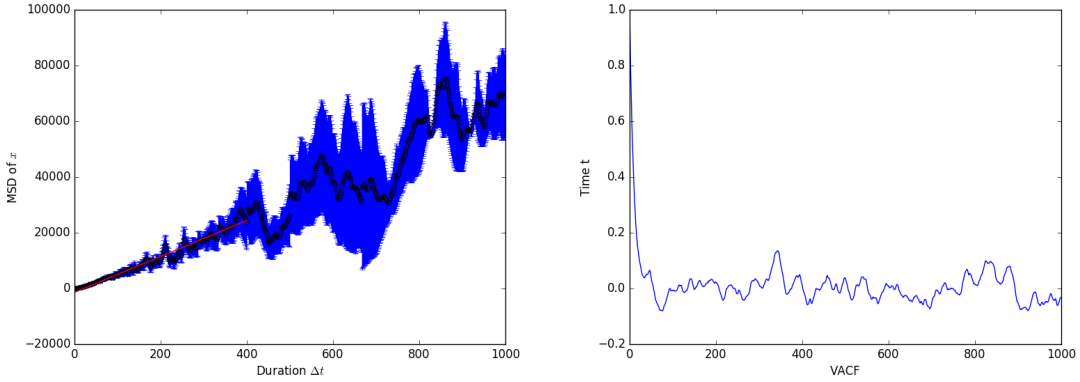

Fig. 12: Plot of the MSD (left) and the VACF (right) for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Langevin thermostat and $\gamma = 0.1$.

As consequence the curve is build up from quadratic like sub-curves.

In order to get an better overview the values of the diffusion constant are written to a tabular:

Thermostat	Langevin			Andersen	
γ/ν	0 1	0 3	0 8	0 1	0 5
D_x	10 76	2 59	1 19	9 15	2 71
D_v	10 06	2 64	1 11	15 90	2 68

This values show that it the values D_x and D_v are very similar for the l=Langevin thermostat. But this may also depend on "good" choices of the regression interval.

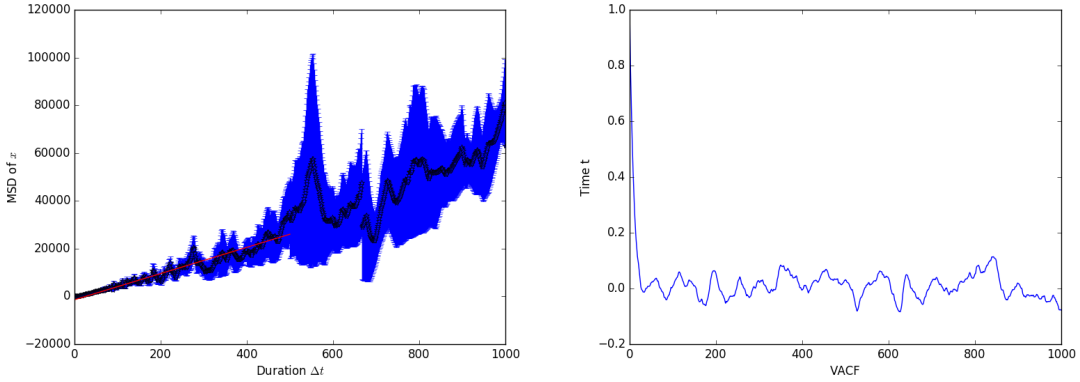

Fig. 13: Plot of the MSD (left) and the VACF (right) for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Andersen thermostat and $\nu = 0.1$.

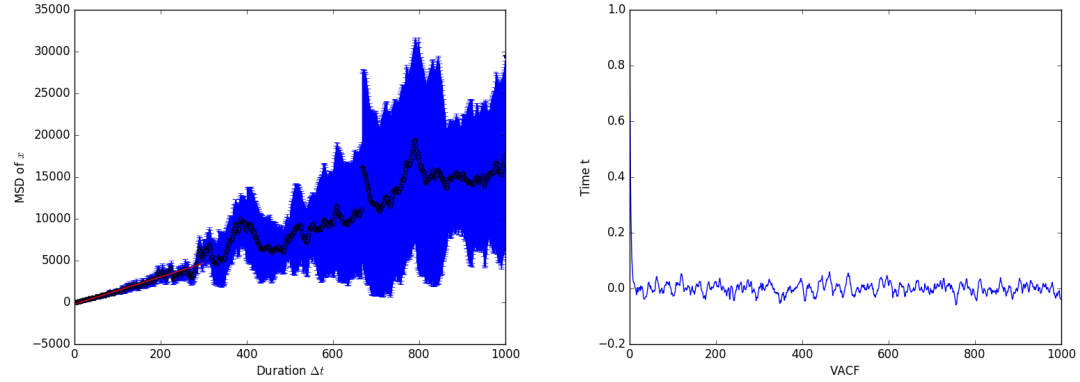

Fig. 14: Plot of the MSD (left) and the VACF (right) for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Andersen thermostat and $\nu = 0.5$.

As you can see the diffusion decreases with growing friction constant γ and also with an growing collision probability ν. This is due to the fact that the more random walk influences the simulation the less the position $|\boldsymbol{x}|$ will change over time (in the stochastic average).

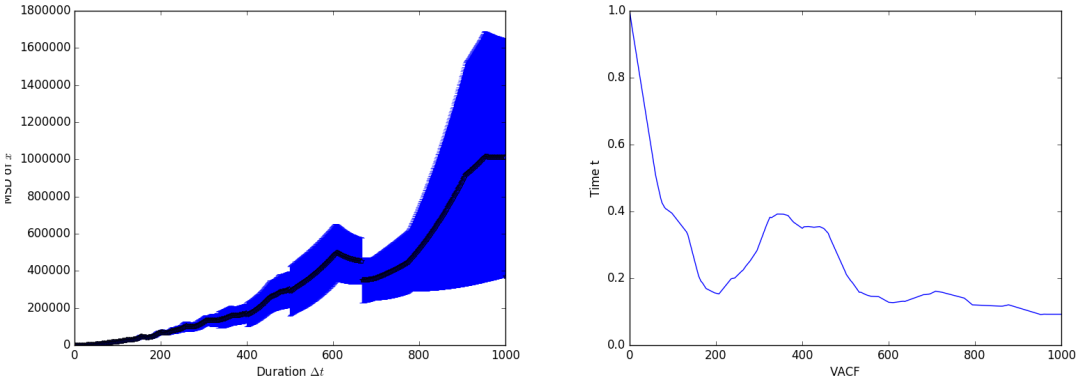

Fig. 15: Plot of the MSD (left) and the VACF (right) for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Andersen thermostat and $\nu = 0.01$.

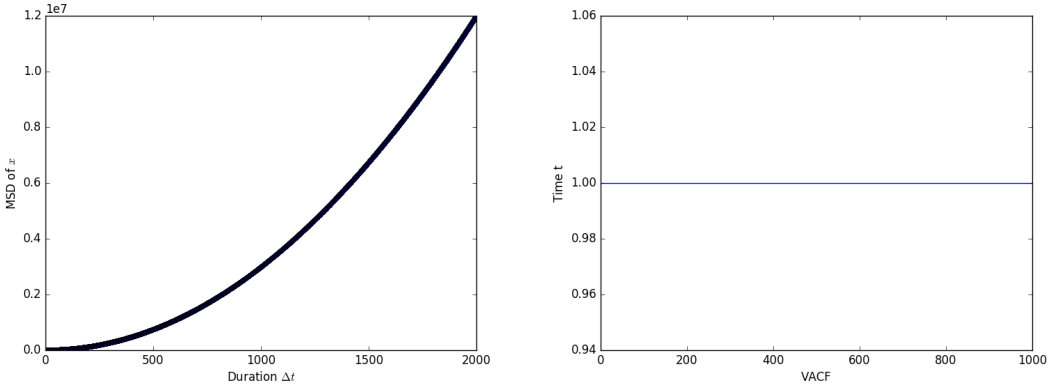

Fig. 16: Plot of the MSD (left) and the VACF (right) for a desired temperature of $T_{\text{des}} = 1.0$ for a simulation with the Berendsen thermostat and $\tau_T = 3.0$.