

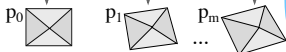
Input Video and Optical Flow



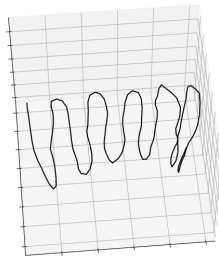
Depth Network



Relative Pose Estimator

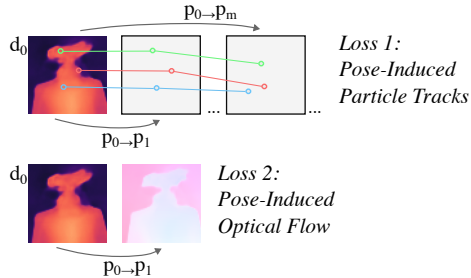


Globally Aligned Poses



Pose Integration

Reprojection Consistency Losses:



Gradient Flow