

# ESM 270 Week 3 Marxan

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```
library(here)
library(janitor)
library(prioritizr)
library(sf)
library(slam)
library(gurobi)
library(ggmap)
library(patchwork)
library(tidyverse)
```

Information on the `prioritizr` package is at [https://mran.microsoft.com/snapshot/2018-03-04/web/packages/prioritizr/vignettes/quick\\_start.html](https://mran.microsoft.com/snapshot/2018-03-04/web/packages/prioritizr/vignettes/quick_start.html).

A really useful example for summed solutions is under “Selection Frequencies” here: <https://cran.r-project.org/web/packages/prioritizr/vignettes/tasmania.html>

Note: for `solve()` function, must have a solver installed, which for the the summing/multiple runs process, must be `gurobi`. If you don’t have it, it requires getting an academic license and is generally a hassle which required a lot of troubleshooting for me... but the instructions below should make it quicker for you if you decide to.

1. Download gurobi (<https://www.gurobi.com/downloads/gurobi-optimizer-eula/>)
2. Request an academic license (<https://www.gurobi.com/downloads/end-user-license-agreement-academic/>)
3. Verify license in terminal by copying and pasting information in your account > your licenses
4. Must install r package with `install.packages('/Library/gurobi902/mac64/R/gurobi_9.0-2_R_3.6.1.tgz', repos=NULL)` (if on a mac and downloaded the most recent version of gurobi, don’t download newest version of R! (4.0.0)).
5. must install slam package with `install.packages("slam")`
6. add gurobi and slam libraries

## Read in Morro Bay data

```
# species and pu data
# all csv files are unaltered from the xlsx files in the R drive. Just saved as csvs.

spec <- read_csv("MorroBay_spec.csv") %>%
  head(140) %>% # read in extra blank rows
  rename("amount" = "target") # target is called "prop" (relative) or "amount" (absolute)

pu <- read_csv("MorroBay_pu.csv") %>%
  select(1:3) # read in extra blank column

puvsp <- read_csv("MorroBay_puvspr.csv") %>%
```

```

select(1:3) %>%
head(11849)

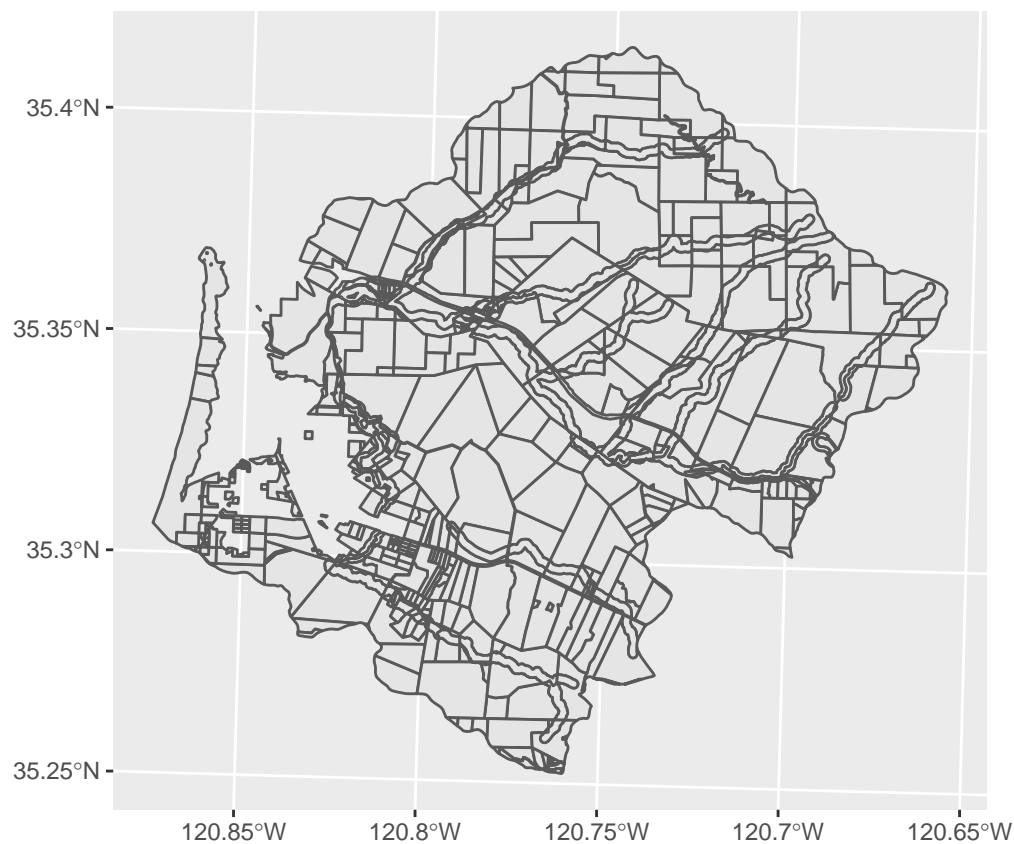
status <- read_csv("spec_name_status.csv") %>%
select(1:3) %>%
head(140)

# polygons

parcels <- read_sf(dsn = here("MorroBay_data"), layer = "MorroBay_parcels") %>%
clean_names()

ggplot(data = parcels) +
geom_sf()

```



```

# create df with pus and polygons

```

## Run Marxan problem

```

# marxan_problem(), more 'canned' approach apparently, but seems good for our purposes. If more customi

marxan_1 <- marxan_problem(x = pu,
                           spec = spec,
                           puvspr = puvsp,
                           bound = NULL,
                           blm = 0)

```

```

marxan_1_problem <- marxan_1 %>%
  add_gurobi_solver(gap = 0.15) %>%
  add_pool_portfolio(method = 2, number_solutions = 100) # see method meaning under ?add_pool_portfolio

print(marxan_1_problem)

marxan_1_soln <- solve(marxan_1_problem)

## Gurobi Optimizer version 9.0.2 build v9.0.2rc0 (mac64)
## Optimize a model with 140 rows, 670 columns and 11849 nonzeros
## Model fingerprint: 0xd2c5bccb
## Variable types: 0 continuous, 670 integer (670 binary)
## Coefficient statistics:
##   Matrix range      [1e+00, 1e+00]
##   Objective range   [2e+00, 5e+06]
##   Bounds range      [1e+00, 1e+00]
##   RHS range         [3e-01, 2e+02]
## Found heuristic solution: objective 4.238988e+07
## Presolve removed 116 rows and 205 columns
## Presolve time: 0.01s
## Presolved: 24 rows, 465 columns, 3066 nonzeros
## Variable types: 0 continuous, 465 integer (465 binary)
## Presolve removed 1 rows and 0 columns
## Presolved: 23 rows, 465 columns, 3058 nonzeros
##
##
## Root relaxation: objective 2.840941e+07, 14 iterations, 0.00 seconds
##
##   Nodes      |   Current Node      |   Objective Bounds      |   Work
##  Expl Unexpl |  Obj  Depth IntInf | Incumbent    BestBd   Gap | It/Node Time
##
## *    0      0              0   2.840941e+07 2.8409e+07  0.00%    -    0s
##
## Optimal solution found at node 0 - now completing solution pool...
##
##   Nodes      |   Current Node      |   Pool Obj. Bounds      |   Work
##           |   |   Worst          |   |
##  Expl Unexpl |  Obj  Depth IntInf | Incumbent    BestBd   Gap | It/Node Time
##
##    0      0      -    0              - 2.8409e+07      -    -    0s
##    0      0      -    0              - 2.8409e+07      -    -    0s
##    0      2      -    0              - 2.8409e+07      -    -    0s
##
## Explored 1958 nodes (383 simplex iterations) in 0.10 seconds
## Thread count was 1 (of 4 available processors)
##
## Solution count 100: 2.84094e+07 2.84097e+07 2.842e+07 ... 3.34128e+07
##
## Optimal solution found (tolerance 1.50e-01)
## Best objective 2.840941400000e+07, best bound 2.840941400000e+07, gap 0.0000%

# sum solutions

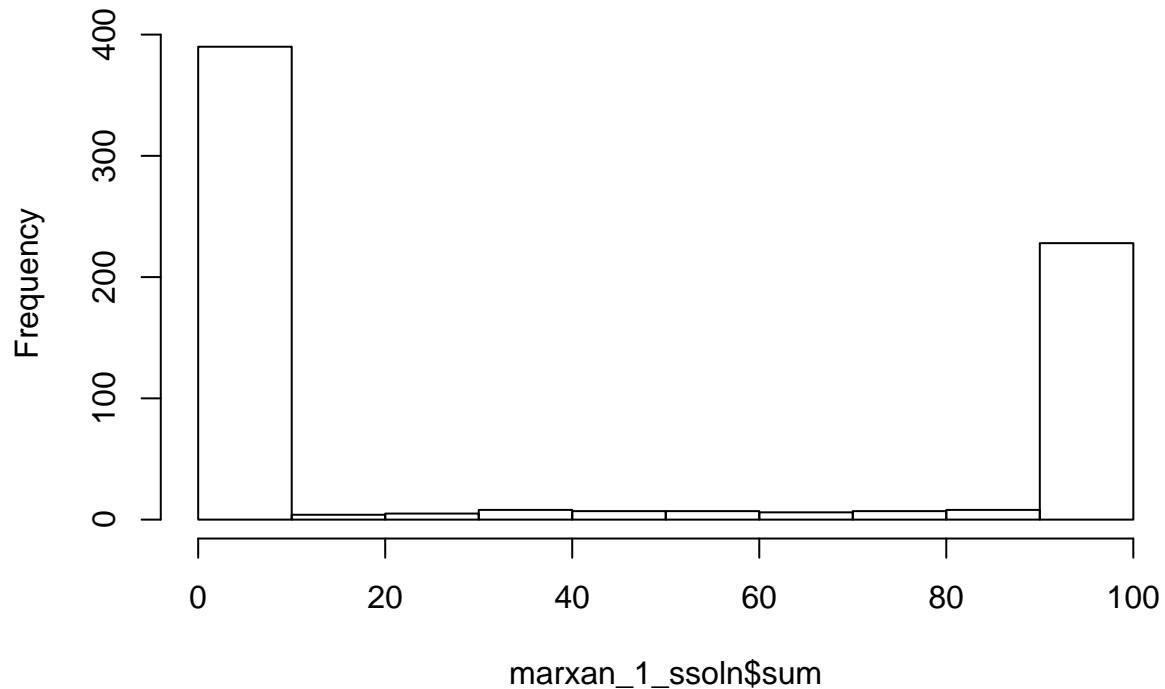
marxan_1_ssoln <- marxan_1_soln %>%

```

```
mutate(sum = rowSums(.[6:105])) %>%
select(id, cost, status, locked_in, locked_out, sum)

hist(marxan_1_ssoln$sum)
```

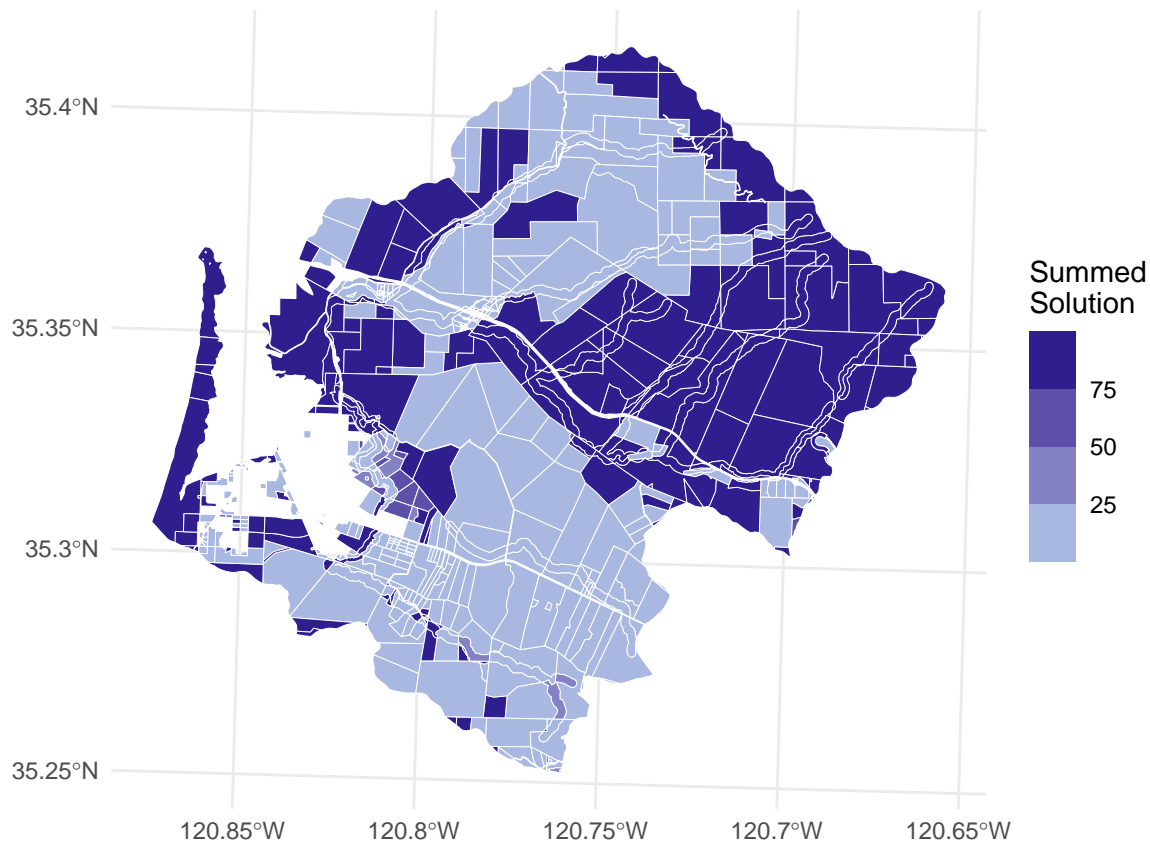
**Histogram of marxan\_1\_ssoln\$sum**



Join parcels polygons with output

```
parcels_marxan_1 <- inner_join(parcels, marxan_1_ssoln, by = "id")

ggplot(data = parcels_marxan_1) +
  geom_sf(aes(fill = sum,
    color = "white",
    size = 0.05) +
  scale_fill_binned(low = "slategray2",
    high = "navy") +
  labs(fill = "Summed \nSolution") +
  theme_minimal()
```



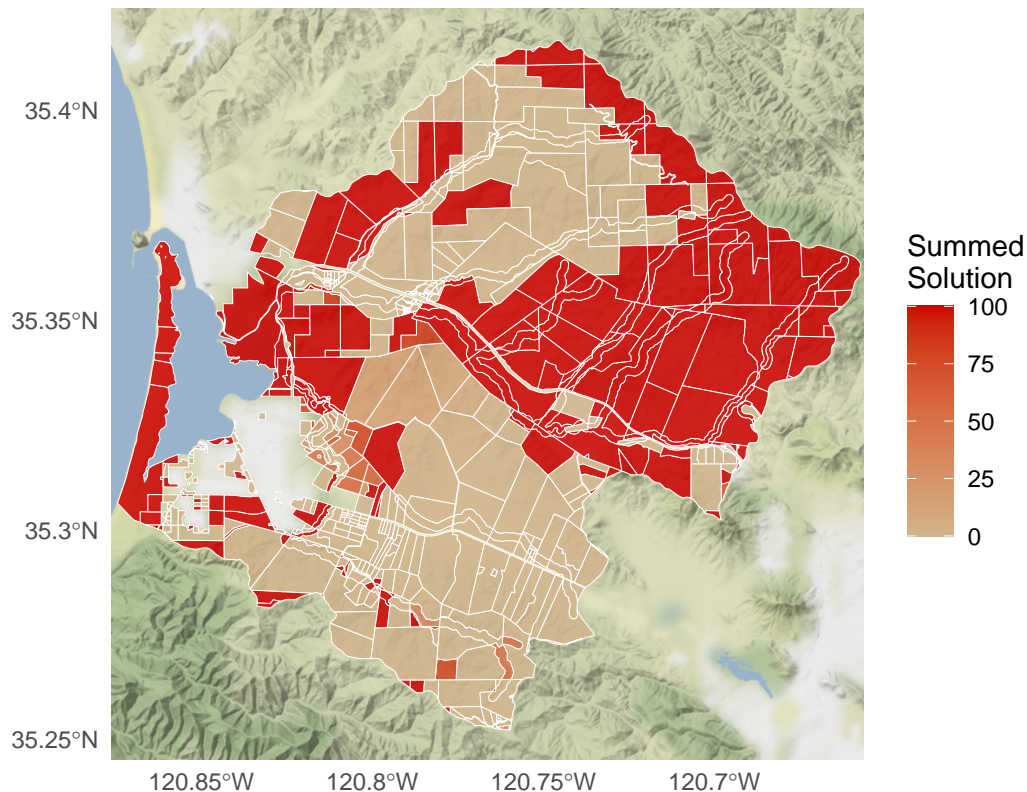
```
# add basemap

morrobay <- get_map(location = c(lon = -120.7665, lat = 35.335),
                    zoom = 12,
                    maptype = "terrain-background",
                    source = "google")

# see different ggmap maptypes here: https://www.nceas.ucsb.edu/sites/default/files/2020-04/ggmapCheats
# - background means no references, omit if want references

ggmap(morrobay) +
  geom_sf(data = parcels_marxan_1,
          aes(fill = sum),
          color = "white",
          size = 0.1,
          alpha = 0.85,
          inherit.aes = FALSE) +
  coord_sf(crs = st_crs(4326)) +
  scale_fill_gradient(low = "tan",
                     high = "red3") +
  labs(title = "All Species",
       fill = "Summed \nSolution",
       x = NULL,
       y = NULL) +
  theme_minimal()
```

## All Species



```
ggsave("spec_graph.png")
```

## Considering endangered species

Make spec and pucsp files with only endangered & threatened species

```
end_status <- status %>%
  mutate("endangered" = case_when(
    str_detect(status, pattern = "endangered") == TRUE ~ "yes",
    str_detect(status, pattern = "threatened") == TRUE ~ "yes",
    T ~ "no")) %>%
  filter(endangered == "yes")

end_spec <- merge(end_status, spec, by = "id") %>%
  select(id, amount, spf, name.x) %>%
  rename("name" = "name.x")

pucsp_id <- pucsp %>%
  rename("id" = "species")

end_pucsp <- merge(end_status, pucsp_id, by = "id") %>%
  rename("species" = "id")
```

## Run Marxan problem

```
marxan_end <- marxan_problem(x = pu,
                             spec = end_spec,
```

```

        puvspr = end_puvspr,
        bound = NULL,
        blm = 0)

marxan_end_problem <- marxan_end %>%
  add_gurobi_solver(gap = 0.15) %>%
  add_pool_portfolio(method = 2, number_solutions = 100)

print(marxan_end_problem)

marxan_end_soln <- solve(marxan_end_problem)

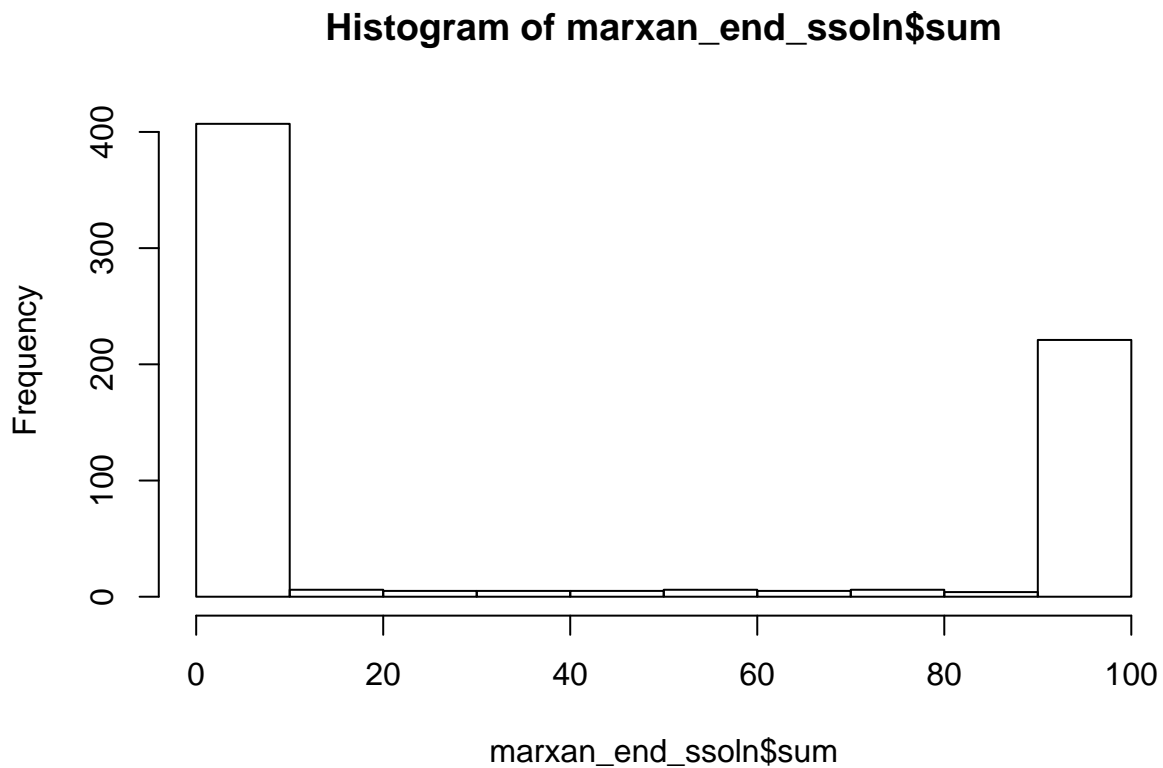
## Gurobi Optimizer version 9.0.2 build v9.0.2rc0 (mac64)
## Optimize a model with 18 rows, 670 columns and 970 nonzeros
## Model fingerprint: 0x6e88f508
## Variable types: 0 continuous, 670 integer (670 binary)
## Coefficient statistics:
##   Matrix range      [1e+00, 1e+00]
##   Objective range   [2e+00, 5e+06]
##   Bounds range      [1e+00, 1e+00]
##   RHS range         [9e-01, 1e+02]
## Found heuristic solution: objective 4.174920e+07
## Presolve removed 14 rows and 203 columns
## Presolve time: 0.00s
## Presolved: 4 rows, 467 columns, 495 nonzeros
## Variable types: 0 continuous, 467 integer (467 binary)
## Found heuristic solution: objective 3.534249e+07
## Presolved: 4 rows, 467 columns, 495 nonzeros
##
##
## Root relaxation: objective 2.677119e+07, 1 iterations, 0.00 seconds
##
##      Nodes      |      Current Node      |      Objective Bounds      |      Work
##  Expl Unexpl |  Obj  Depth IntInf | Incumbent    BestBd   Gap | It/Node Time
##
## *    0      0              0   2.677119e+07 2.6771e+07  0.00%    -    0s
##
## Optimal solution found at node 0 - now completing solution pool...
##
##      Nodes      |      Current Node      |      Pool Obj. Bounds      |      Work
##      |      |      |      |      |      |      |      |
##  Expl Unexpl |  Obj  Depth IntInf | Incumbent    BestBd   Gap | It/Node Time
##
##    0      0      -    0      - 2.6771e+07      -      -    0s
##    0      0      -    0      - 2.6771e+07      -      -    0s
##    0      2      -    0      - 2.6771e+07      -      -    0s
##
## Explored 4914 nodes (1716 simplex iterations) in 0.33 seconds
## Thread count was 1 (of 4 available processors)
##
## Solution count 100: 2.67712e+07 2.67732e+07 2.67736e+07 ... 3.14836e+07
##
## Optimal solution found (tolerance 1.50e-01)
## Best objective 2.677119300000e+07, best bound 2.677119300000e+07, gap 0.0000%

```

```
# sum solutions

marxan_end_ssoln <- marxan_end_soln %>%
  mutate(sum = rowSums(.[6:105])) %>%
  select(id, cost, status, locked_in, locked_out, sum)

hist(marxan_end_ssoln$sum)
```

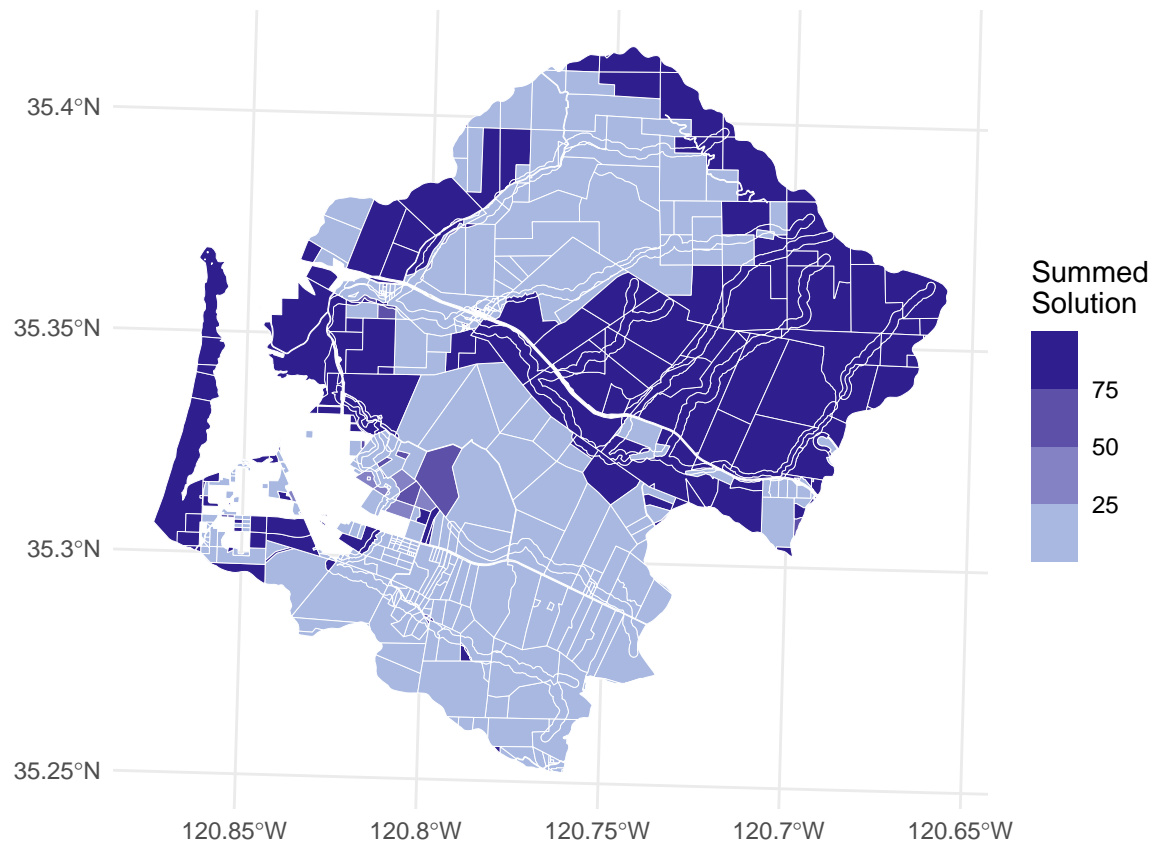


Join parcels polygons with output

```
parcels_marxan_end <- inner_join(parcels, marxan_end_ssoln, by = "id")

ggplot(data = parcels_marxan_end) +
  geom_sf(aes(fill = sum,
    color = "white",
    size = 0.05) +
  scale_fill_binned(low = "slategray2",
    high = "navy") +
  labs(fill = "Summed \nSolution") +
  theme_minimal()
```

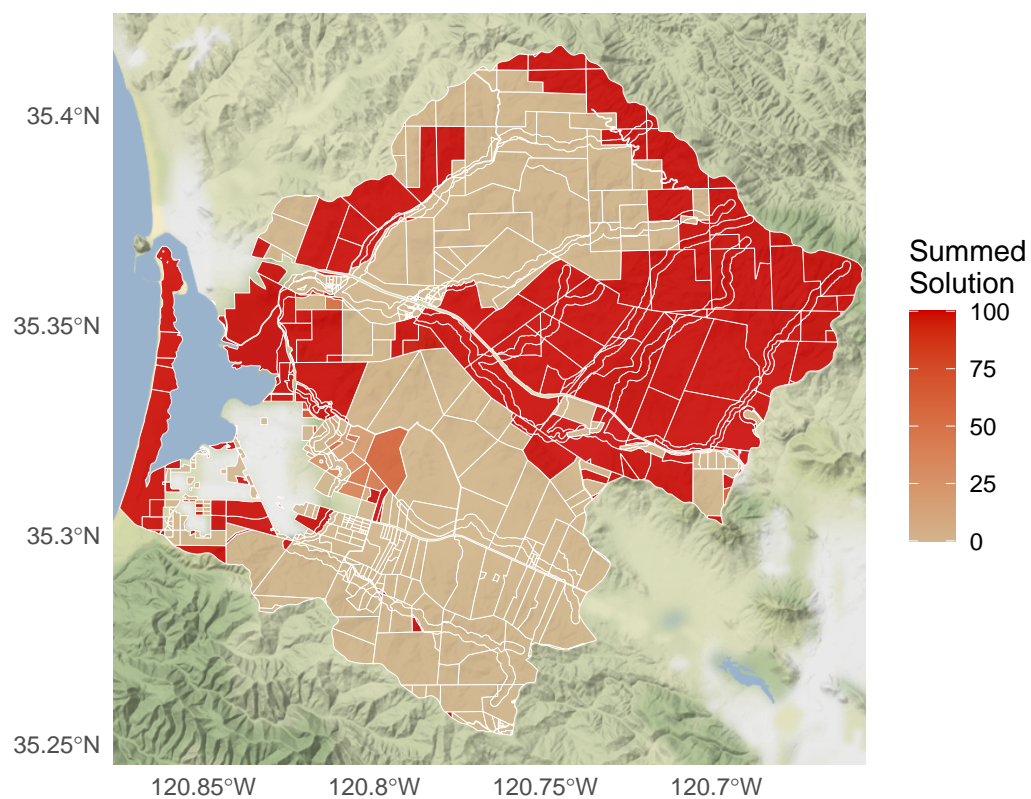




## Map

```
ggmap(morrobbay) +
  geom_sf(data = parcels_marxan_end,
    aes(fill = sum),
    color = "white",
    size = 0.15,
    alpha = 0.85,
    inherit.aes = FALSE) +
  coord_sf(crs = st_crs(4326)) +
  scale_fill_gradient(low = "tan",
    high = "red3") +
  labs(title = "Endangered & Threatened Species",
    fill = "Summed \nSolution",
    x = NULL,
    y = NULL) +
  theme_minimal()
```

## Endangered & Threatened Species



```
ggsave("end_graph.png")
```