Line Following Algorithm

Camiel Verschoor

June 14, 2012

- 1. Capture image
- 2. Colour filter?
- 3. Smoothing
- 4. Edge Detection¹
 - Canny Edge detection
 - Edge Drawing²
 - Marr-Hildreth Edge detection
 - The Local Threshold and Boolean Function Based Edge Detection
 - Color Edge Detection Using Euclidean Distance and Vector Angle
 - Color Edge Detection using the Canny Operator
 - Depth Edge Detection using Multi-Flash Imaging
- 5. Edge thinning?
- 6. Ridge detection?
- 7. Line Segment Detection algorithms
 - Hough Line Transform
 - EDLines³

 $^{^{1}} http://www.m-hikari.com/ams/ams-password-2008/ams-password29-32-2008/nadernejadAMS29-32-2008.pdf$

²http://ceng.anadolu.edu.tr/CV/EdgeDrawing/

³http://ceng.anadolu.edu.tr/cv/EDLines/

- Minimum Partition Consistent Subsystems (MIN-PCS)⁴
- Line Segment Detector⁵
- On straight line detection ⁶

8. Line Following

```
while ( detectLine() )
{
    // Align with the line
    // Move along the line by keeping the line in a virtual box and
    // making adjustments are made to flight direction if the line
    // direction changes
}
```

⁴http://infoscience.epfl.ch/record/86864/files/Mattavelli2001_880.pdf

⁵http://www.ipol.im/pub/algo/gjmr_line_segment_detector/

⁶http://www.cmla.ens-cachan.fr/fileadmin/Documentation/Prepublications/2007/CMLA2007-09.pdf