Sensor Fusion on a mini Unmanned Vehicle

Integrating vision-based algorithms on an Asctec Pelican to autonomously
follow linear shaped structures in a landscape.

Camiel R. Verschoor
10017321

Bachelor thesis
Credits: 18 EC

Bachelor Opleiding Kunstmatige Intelligentie

University of Amsterdam
Faculty of Science
Science Park 904
1098 XH Amsterdam

Supervisors
Dr. A. Visser

Informatics Institute
Faculty of Science
University of Amsterdam
Science Park 904
1098 XH Amsterdam

Drs. G. Poppinga

Mini UAS National Aerospace Lab
NLR Amsterdam
Anthony Fokkerweg 2
1059 CM Amsterdam

June 24th, 2010