FLOYD-WARSHALL + BELLMAN-FORD ALGORITHMS

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Agenda

Floyd-Warshall algorithm

Bibliography







Let G be a weighted graph, finds the shortest path between all pairs of nodes in G

All-pairs shortest paths

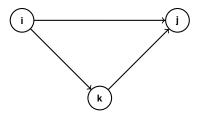
Floyd algorithm: can be used on weighted graphs with negative weights (but no negative cycles)

Based on the Warshall algorithm for computing transitive closures

Design strategy: dynamic programming







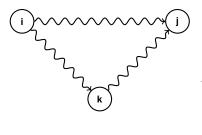
Before first iteration (k = 0)

■ D[i][j]: direct distance between i and jAfter first iteration (k = 0)

■ D[i][j]: best option between $i \rightarrow j$ and $i \rightarrow 0 \rightarrow j$





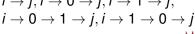


Before second iteration (k = 1)

D[i][j]: best option between $i \rightarrow i$ and $i \rightarrow 0 \rightarrow i$

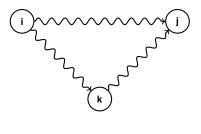
After second iteration (k = 1)

- D[i][i]: best option between $i \rightsquigarrow i$ and $i \rightsquigarrow 1 \rightsquigarrow i$
 - $i \rightsquigarrow i$ the best of $i \rightarrow i$, $i \rightarrow 0 \rightarrow i$
 - $i \rightsquigarrow 1$ the best of $i \rightarrow 1$, $i \rightarrow 0 \rightarrow 1$
 - 1 \rightsquigarrow j the best of 1 \rightarrow j, 1 \rightarrow 0 \rightarrow j
- Considering the best among $i \rightarrow j, i \rightarrow 0 \rightarrow j, i \rightarrow 1 \rightarrow j,$









Before third iteration (k = 2)

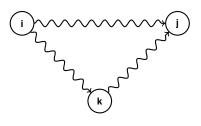
D[i][j]: best option between i → j and i → 1 → j

After third iteration (k = 2)

- D[i][j]: best option between i ~> j and i ~> 2 ~> j
 - $i \rightsquigarrow j$ the best of $i \rightarrow j$, $i \rightarrow 0 \rightarrow j$, $i \rightarrow 1 \rightarrow j$, $i \rightarrow 0 \rightarrow 1 \rightarrow j$, $i \rightarrow 1 \rightarrow 0 \rightarrow j$
 - $i \rightsquigarrow 2$ the best of $i \rightarrow 2$, $i \rightarrow 0 \rightarrow 2$, $i \rightarrow 1 \rightarrow 2$, $i \rightarrow 0 \rightarrow 1 \rightarrow 2$, $i \rightarrow 1 \rightarrow 0 \rightarrow 2$
 - \blacksquare 2 \rightsquigarrow *j* the best of ...







The algorithm stops when k = n

After the last iteration (k = n - 1)

■ D[i][j]: best option between i ~> j and i ~> n-1 ~> j, which means the best among all possibilities





30th January, 2021

Algorithm: void Floyd(Graph G, int[][] D)

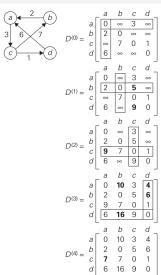
```
for i \leftarrow 0 to n(G) - 1 do
           for i \leftarrow 0 to n(G) - 1 do
2
                 if i = j then D[i][j] \leftarrow 0;
3
                 else if weight(G, i, j) \neq 0 then D[i][j] \leftarrow weight(G, i, j);
4
                  else D[i][j] \leftarrow \infty;
 5
     for k \leftarrow 0 to n(G) - 1 do
           for i \leftarrow 0 to n(G) - 1 do
7
                  for i \leftarrow 0 to n(G) - 1 do
 8
                       if D[i][k] \neq \infty \land D[k][j] \neq \infty \land D[i][j] > D[i][k] + D[k][j] then D[i][j] \leftarrow D[i][k] + D[k][j];
 9
10
```

Time efficiency in $\Theta(\mid V \mid^3)$





Floyd-Warshall algorithm¹







Agenda

1 Floyd-Warshall algorithm

2 Bellman-Ford algorithm

3 Bibliography







Let G be a weighted graph and $v \in V$ (source), finds the shortest path from v to all other nodes in V

Single-source shortest paths

Bellman-Ford algorithm: can be used on weighted graphs with negative cycles

Intuition:

- There can be maximum |V| 1 edges in any simple path
- Processes all edges | V | − 1 times
- Iteration k = 0: all shortest paths which are at most 1 edge long
- Iteration k = |V| 2: all shortest paths
- Iteration k = |V| 1: if something better is found, there is a negative cycle



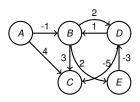


Algorithm: void

BellmanFord(Graph G, int s, int[] D)

```
for i \leftarrow 0 to n(G) - 1 do D[i] \leftarrow \infty;
     D[s] \leftarrow 0;
     for k \leftarrow 0 to n(G) - 2 do
           for i \leftarrow 0 to n(G) - 1 do
 4
                 i \leftarrow first(G, i);
 5
                  while j < n(G) do
 7
                        if D[j] > D[j] + weight(G, i, j)
                         then
                              D[j] \leftarrow D[i] + weight(G, i, j);
 8
                        i \leftarrow next(G, i, i);
 9
     for i \leftarrow 0 to n(G) - 1 do
10
           i \leftarrow first(G, i);
11
           while i < n(G) do
12
                  if D[i] > D[i] + weight(G, i, j) then
13
                        negative cycle detected
14
```

Let s = A



	Α	В	С	D	E
Distance	0	∞	∞	∞	∞





15

 $i \leftarrow next(G, i, i)$;

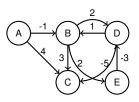
Algorithm: void

BellmanFord(Graph G, int s, int[] D)

```
for i \leftarrow 0 to n(G) - 1 do D[i] \leftarrow \infty;
    D[s] \leftarrow 0;
    for k \leftarrow 0 to n(G) - 2 do
          for i \leftarrow 0 to n(G) - 1 do
4
                 j \leftarrow first(G, i);
                 while i < n(G) do
                       if D[j] > D[i] + weight(G, i, j)
                         then
                              D[j] \leftarrow D[i] + weight(G, i, j);
                       j \leftarrow next(G, i, j);
9
```

```
for i \leftarrow 0 to n(G) - 1 do
10
11
          i \leftarrow first(G, i);
           while i < n(G) do
12
                 if D[j] > D[i] + weight(G, i, j) then
13
                      negative cycle detected
14
                 i \leftarrow next(G, i, i);
15
```

Let s = A



	Α	В	С	D	E
Distance	0	-1	4	∞	∞

Considering k=0

 \blacksquare After i = 0 (node A)





Algorithm: void

BellmanFord(Graph G, int s, int[] D)

```
10 for i \leftarrow 0 to n(G) - 1 do

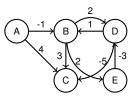
11 j \leftarrow first(G, i);
12 while j < n(G) do

13 if D[j] > D[i] + weight(G, i, j) then

14 negative cycle detected

15 j \leftarrow next(G, i, j);
```

Let s = A



	Α	В	С	D	E
Distance	0	-1	2	1	1

Considering k = 0

■ After *i* = 1 (node B)





Algorithm: void

BellmanFord(Graph G, int s, int[] D)

```
10 for i \leftarrow 0 to n(G) - 1 do

11 j \leftarrow first(G, i);

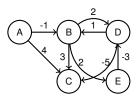
12 while j < n(G) do

13 if D[j] > D[i] + weight(G, i, j) then

14 negative cycle detected

15 j \leftarrow next(G, i, j);
```

Let s = A



	Α	В	С	D	E
Distance	0	-1	2	1	1

Considering k = 0

■ After *i* = 2 (node C)





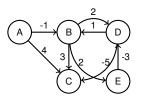
Algorithm: void

BellmanFord(Graph G, int s, int[] D)

```
for i \leftarrow 0 to n(G) - 1 do D[i] \leftarrow \infty;
    D[s] \leftarrow 0;
    for k \leftarrow 0 to n(G) - 2 do
          for i \leftarrow 0 to n(G) - 1 do
4
                 i \leftarrow first(G, i);
                 while i < n(G) do
                       if D[j] > D[i] + weight(G, i, j)
                         then
                              D[j] \leftarrow D[i] + weight(G, i, j);
                       j \leftarrow next(G, i, j);
9
```

```
for i \leftarrow 0 to n(G) - 1 do
10
11
          i \leftarrow first(G, i);
           while i < n(G) do
12
                 if D[j] > D[i] + weight(G, i, j) then
13
                      negative cycle detected
14
                 i \leftarrow next(G, i, i);
15
```

Let s = A



	Α	В	С	D	E
Distance	0	-1	-4	1	1

Considering k=0

■ After *i* = 3 (node D)





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Algorithm: void

BellmanFord(Graph G, int s, int[] D)

```
\begin{array}{lll} & \textbf{for } i \leftarrow 0 \textbf{ to } n(G)-1 \textbf{ do } D[i] \leftarrow \infty \ ; \\ 2 & D[s] \leftarrow 0; \\ 3 & \textbf{for } k \leftarrow 0 \textbf{ to } n(G)-2 \textbf{ do} \\ 4 & & \textbf{for } i \leftarrow 0 \textbf{ to } n(G)-1 \textbf{ do} \\ 5 & & & j \leftarrow \textit{first}(G,i); \\ 6 & & & \textbf{while } j < n(G) \textbf{ do} \\ 7 & & & \textbf{if } D[j] > D[i] + \textit{weight}(G,i,j) \\ & & \textbf{then} \\ & & & L D[j] \leftarrow D[i] + \textit{weight}(G,i,j); \\ 9 & & & j \leftarrow \textit{next}(G,i,j); \\ \end{array}
```

```
10 for i \leftarrow 0 to n(G) - 1 do

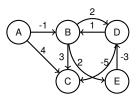
11 j \leftarrow first(G, i);
12 while j < n(G) do

13 if D[j] > D[i] + weight(G, i, j) then

15 negative cycle detected

15 i \leftarrow next(G, i, j);
```

Let s = A



	Α	В	С	D	E
Distance	0	-1	-4	-2	1

Considering k = 0

■ After *i* = 4 (node E)





Algorithm: void

BellmanFord(Graph G, int s, int[] D)

```
\begin{array}{lll} & \textbf{for } i \leftarrow 0 \textbf{ to } n(G) - 1 \textbf{ do } D[i] \leftarrow \infty \ ; \\ & D[s] \leftarrow 0; \\ & \textbf{for } k \leftarrow 0 \textbf{ to } n(G) - 2 \textbf{ do} \\ & \textbf{for } i \leftarrow 0 \textbf{ to } n(G) - 1 \textbf{ do} \\ & \textbf{j} \leftarrow \textit{first}(G,i); \\ & \textbf{while } j < n(G) \textbf{ do} \\ & \textbf{if } D[j] > D[i] + \textit{weight}(G,i,j); \\ & \textbf{then} \\ & \textbf{b} D[j] \leftarrow D[i] + \textit{weight}(G,i,j); \\ & \textbf{j} \leftarrow \textit{next}(G,i,j); \\ \end{array}
```

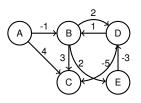
```
10 for i \leftarrow 0 to n(G) - 1 do

11 j \leftarrow first(G, i);
12 while j < n(G) do

13 if D[j] > D[i] + weight(G, i, j) then

15 j \leftarrow next(G, i, j);
```

Let s = A



	Α	В	С	D	E
Distance	0	-1	-7	-2	1

Considering k = 1

■ After *i* = 0..4





Algorithm: void

BellmanFord(Graph G, int s, int[] D)

```
10 for i \leftarrow 0 to n(G) - 1 do

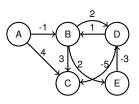
11 j \leftarrow first(G, i);
12 while j < n(G) do

13 if D[j] > D[i] + weight(G, i, j) then

14 negative cycle detected

15 j \leftarrow next(G, i, j);
```

Let s = A



	Α	В	С	D	E
Distance	0	-1	-7	-2	1

Considering k = 2..3

Nothing changes



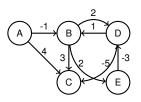


Algorithm: void

BellmanFord(Graph G, int s, int[] D)

```
for i \leftarrow 0 to n(G) - 1 do D[i] \leftarrow \infty;
     D[s] \leftarrow 0;
     for k \leftarrow 0 to n(G) - 2 do
           for i \leftarrow 0 to n(G) - 1 do
 4
                 i \leftarrow first(G, i);
 5
                 while j < n(G) do
 7
                       if D[j] > D[j] + weight(G, i, j)
                         then
                              D[j] \leftarrow D[i] + weight(G, i, j);
 8
                       j \leftarrow next(G, i, j);
 9
     for i \leftarrow 0 to n(G) - 1 do
10
           j \leftarrow first(G, i);
11
           while i < n(G) do
12
                 if D[i] > D[i] + weight(G, i, j) then
13
                       negative cycle detected
14
```

Let s = A



	Α	В	С	D	E
Distance	0	-1	-7	-2	1

One more loop

Nothing changes, implies no neg. cycle

48 4 5 4 5





15

 $i \leftarrow next(G, i, i)$;

Another example of dynamic programming

Time efficiency in $\Theta(\mid V \mid \mid E \mid) = \Theta(\mid V \mid^3)$, since $\mid E \mid \in O(\mid V \mid^2)$





Agenda

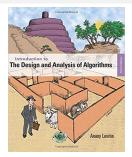
Floyd-Warshall algorithm

Bibliography





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