AVL TREES

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Agenda

Introduction

AVL: an self-balancing binary search tree

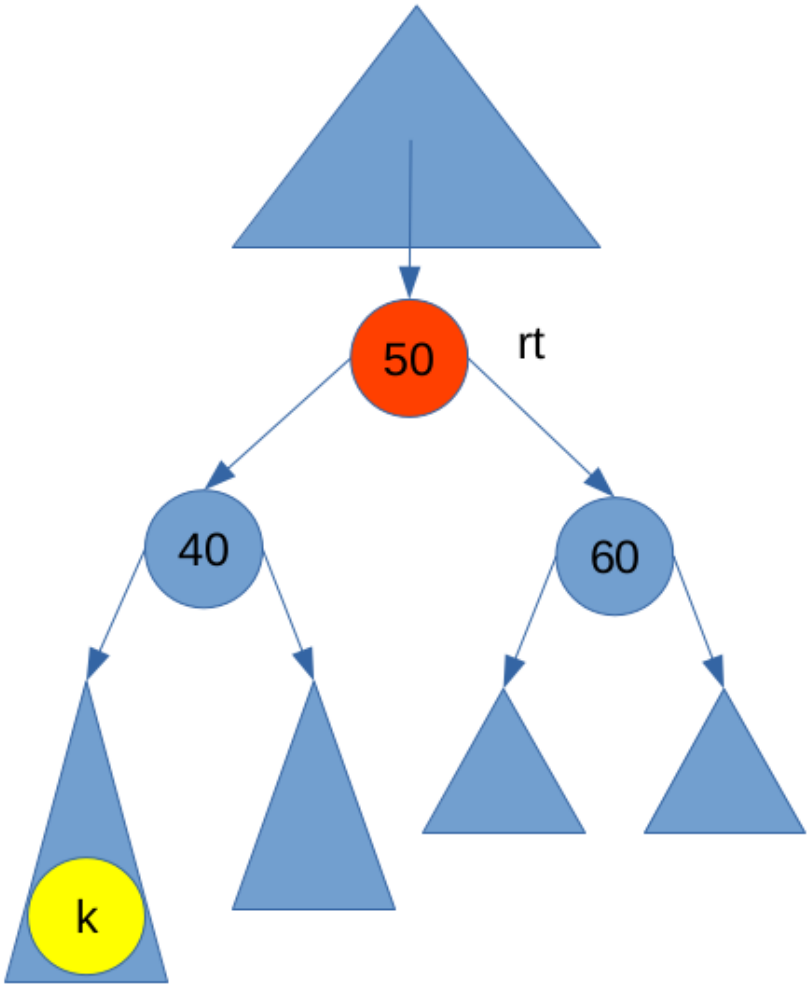
- Proposed in 1962 by G. M. Adelson-Velsky, and E. M. Landis

The balance factor of every node is either -1, 0 or 1

- Difference between the heights of the left and right subtrees
- Height of the empty tree is -1

Rotation: local transformation to rebalance the tree

Introduction



R-rotation: key inserted into the left subtree of the left child of *rt*

If $balance > 1 \wedge k < rt.left.key$ then return $rigthRotate(rt)$

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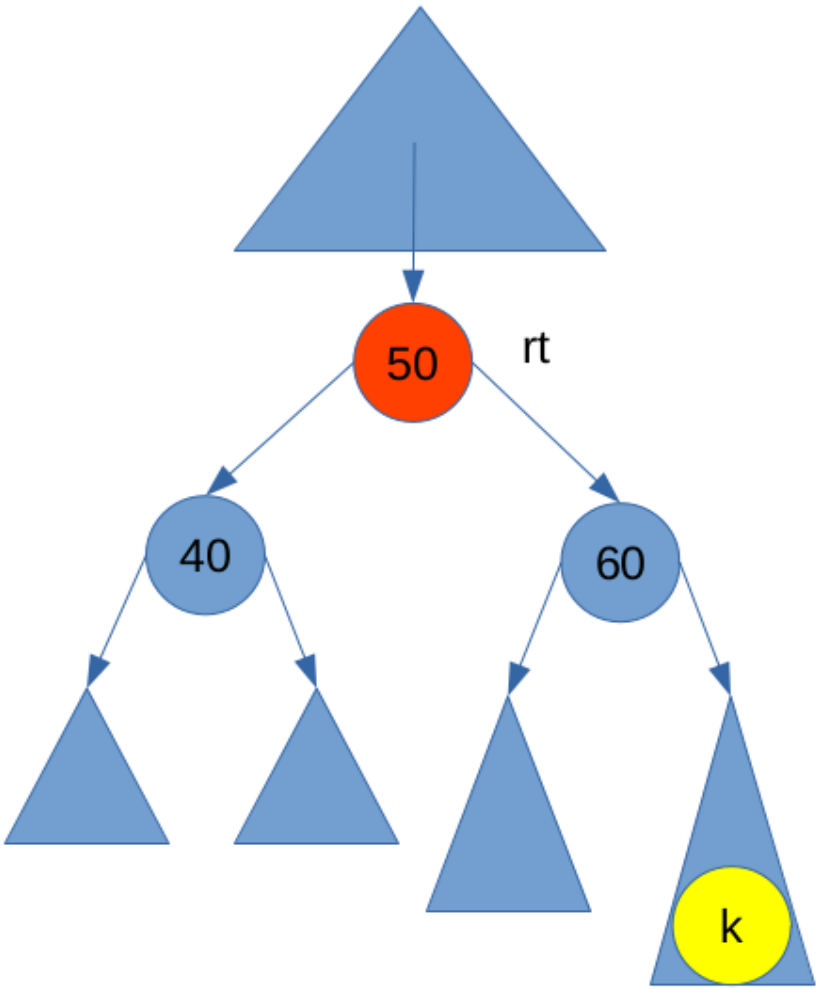

L-rotation: key inserted into the right subtree of the right child of *rt*

If $balance < -1 \wedge k \geq rt.right.key$ then return $leftRotate(rt)$

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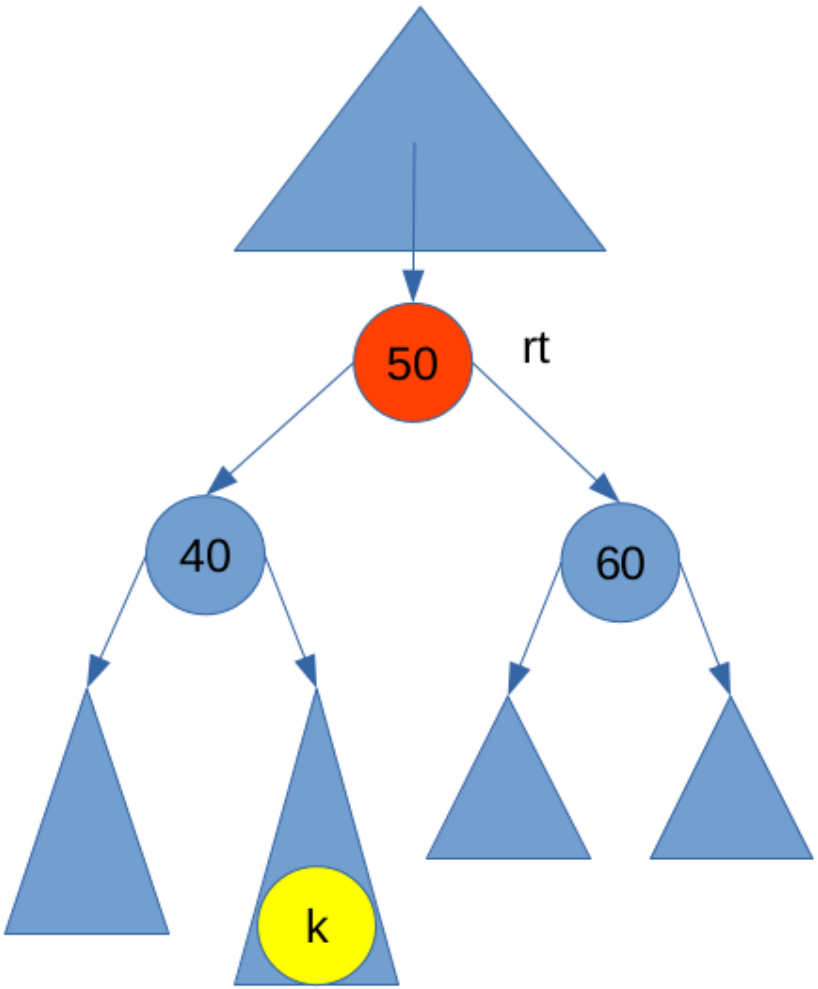

LR-rotation: key inserted into the right subtree of the left child of *rt*

If $balance > 1 \wedge k \geq rt.left.key$
then $rt.left \leftarrow leftRotate(rt.left)$,
and return $rigthRotate(rt)$

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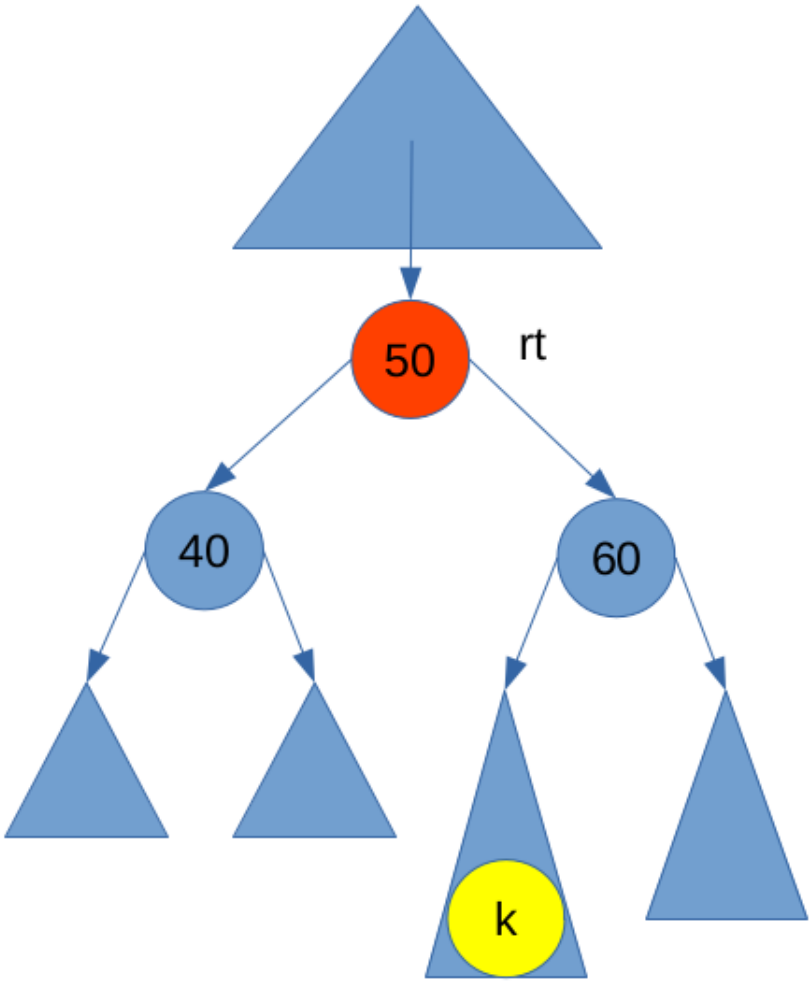

RL-rotation: key inserted into the left subtree of the right child of *rt*

If $balance < -1 \wedge k < rt.right.key$
then $rt.right \leftarrow rightRotate(rt.right)$,
and return $leftRotate(rt)$

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Agenda

Implementing rotations

Algorithm: BSTNode inserthelp(BSTNode rt, Key k, E e)

```
1  if rt = NULL then return create_bstnode(k, e) ;
2  if rt.key > k then
3      rt.left ← inserthelp(rt.left, k, e);
4  else
5      rt.right ← inserthelp(rt.right, k, e);
6  rt.height ← 1 + max(h(rt.left), h(rt.right));
7  int balance ← getBalance(rt);
8  if balance < −1 ∧ k ≥ rt.right.key then return leftRotate(rt) ;
9  if balance > 1 ∧ k < rt.left.key then return rigthRotate(rt) ;
10 if balance > 1 ∧ k ≥ rt.left.key then
11     rt.left ← leftRotate(rt.left);
12     return rigthRotate(rt);
13 if balance < −1 ∧ k < rt.right.key then
14     rt.right ← rightRotate(rt.right);
15     return leftRotate(rt);
16 return rt;
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Algorithm: BSTNode inserthelp(BSTNode rt, Key k, E e)

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1  if rt = NULL then return create_bstnode(k, e) ;
2  if rt.key > k then
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6  return rt;
```

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Implementing rotations

Algorithm: int getBalance(BSTNode rt)

```
1  if rt = NULL then return 0 ;
2  return h(rt.left) − h(rt.right);
```

Algorithm: int h(BSTNode rt)

```
1  if rt = NULL then return −1 ;
2  return rt.height;
```

Implementing rotations

Algorithm: BSTNode rightRotate(BSTNode rt)

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1 BSTNode l ← rt.left;
2 BSTNode lr ← l.right;
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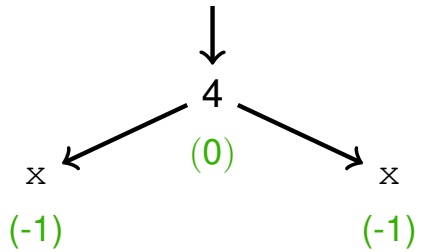
Inserting: 4, 6, 8, 3, 2, 5



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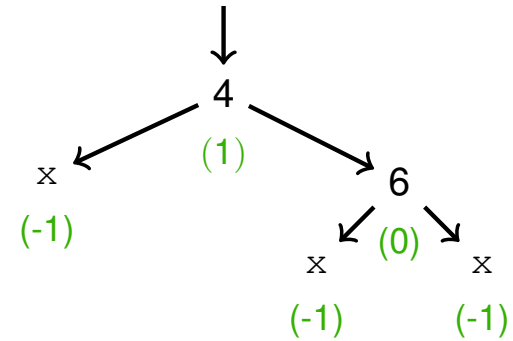

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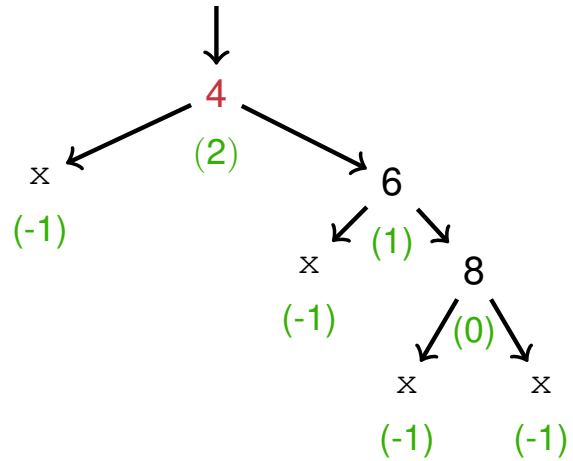

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4: unbalanced = -1 - 1 = -2

L-rotation: right + right

return *leftRotate*(*rt*)

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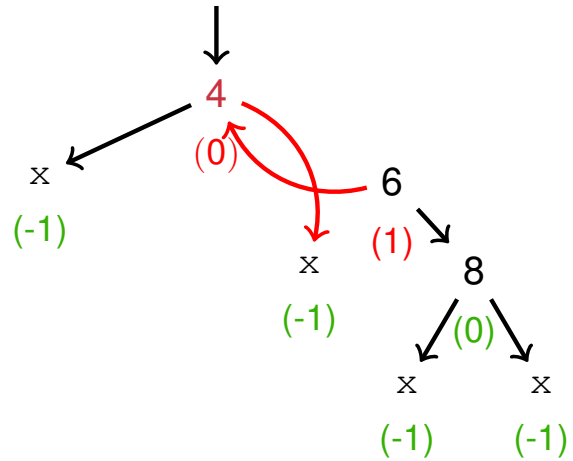

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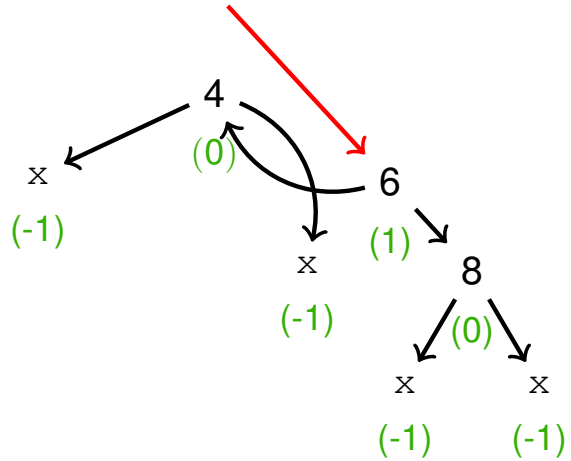

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after *bst.root* ← *inserthelp*(_, _, _)

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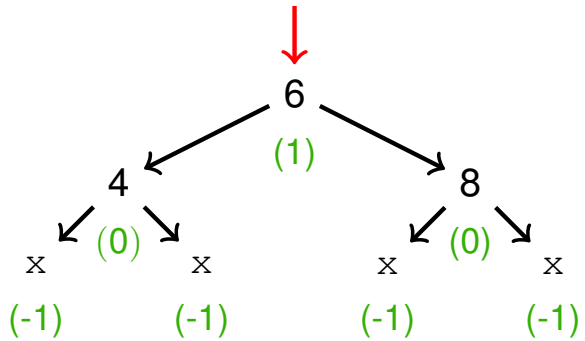

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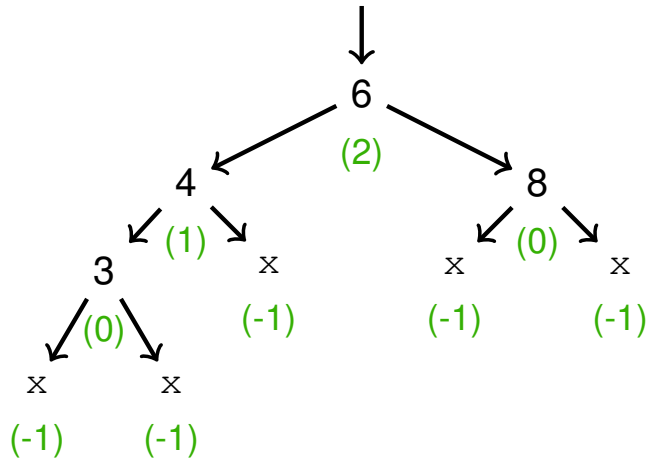

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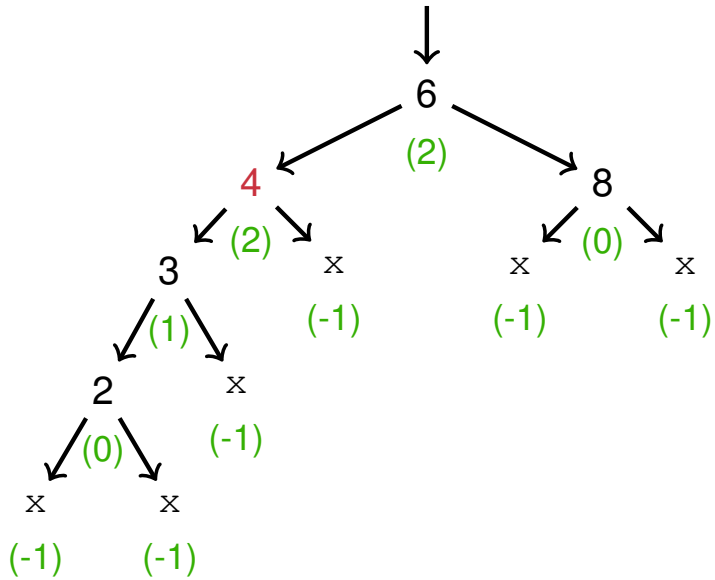

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4: unbalanced = 1 - -1 = 2

R-rotation: left + left

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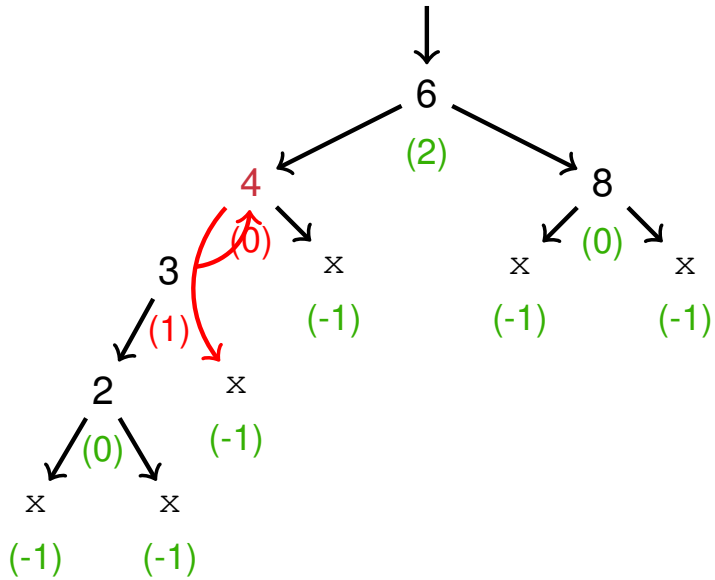

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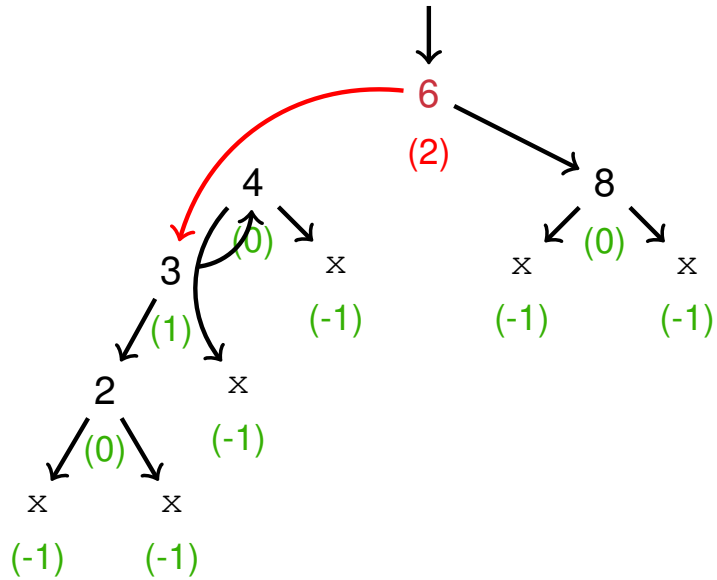

Green number: height

after *rt.left* ← *inserthelp*(_, _, _) and *rt.height* ← ...

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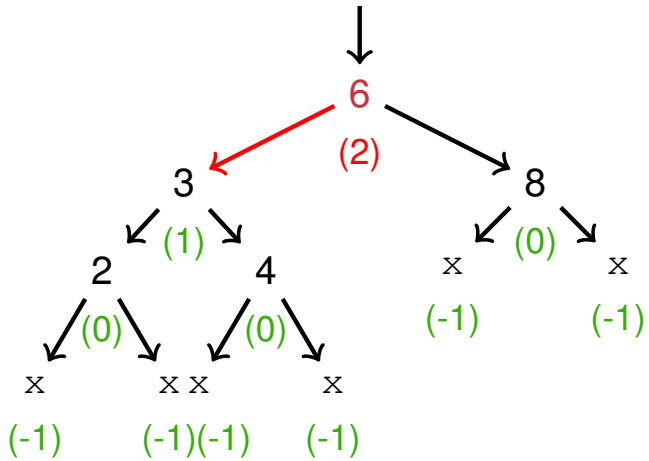

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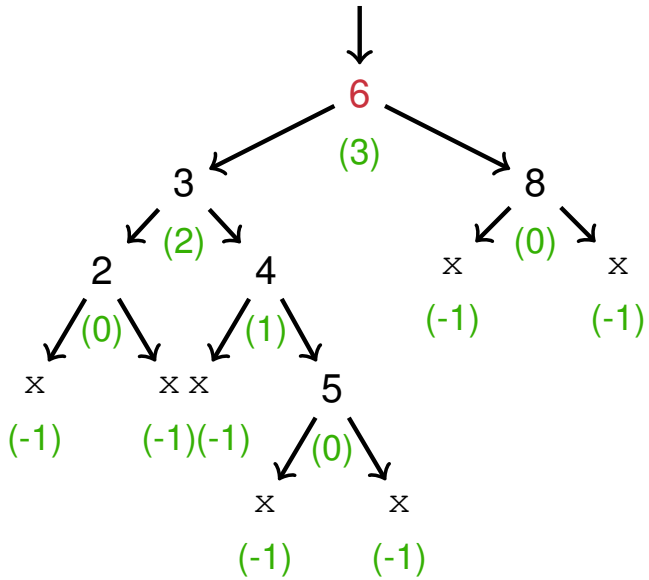

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6: unbalanced = 2 - 0 = 2

LR-rotation: left + right

$rt.left \leftarrow leftRotate(rt.left)$, and return $rigthRotate(rt)$

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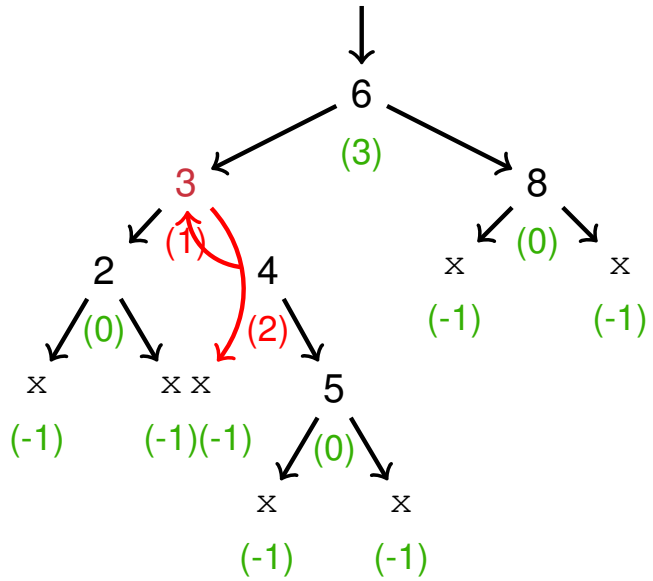

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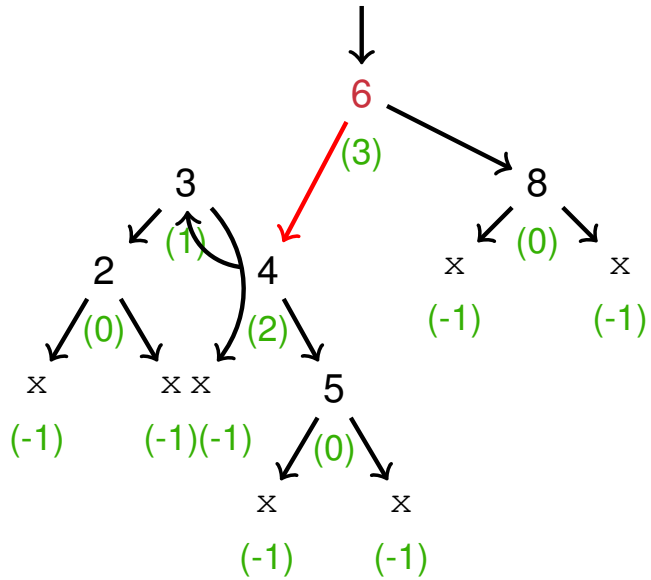

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Algorithm: BSTNode leftRotate(BSTNode rt)

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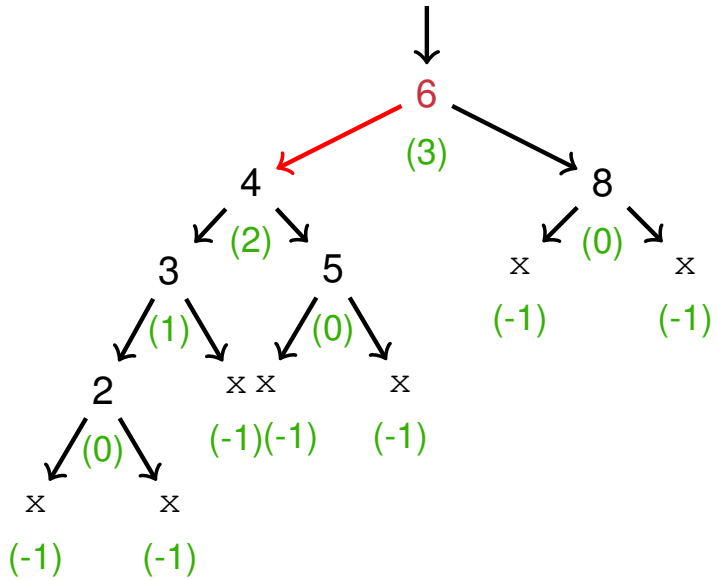
Inserting: 4, 6, 8, 3, 2, 5



Green number: height

6: unbalanced = 2 - 0 = 2

LR-rotation: left + right

$rt.left \leftarrow leftRotate(rt.left)$,

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Implementing rotations

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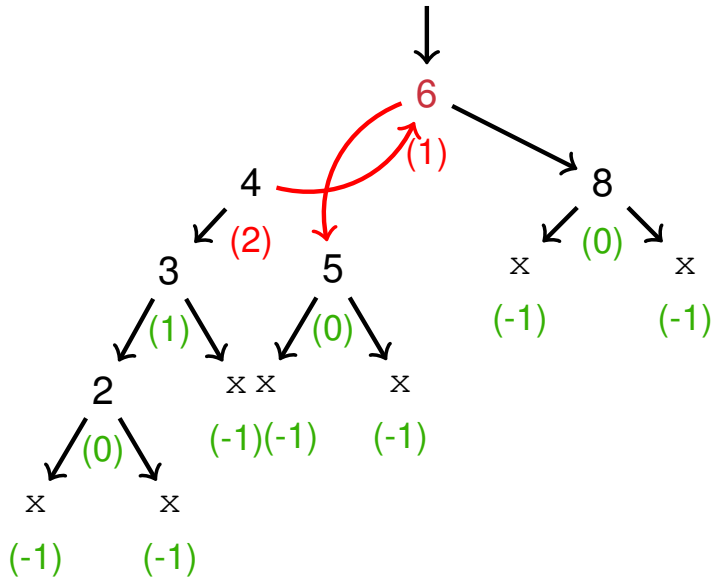

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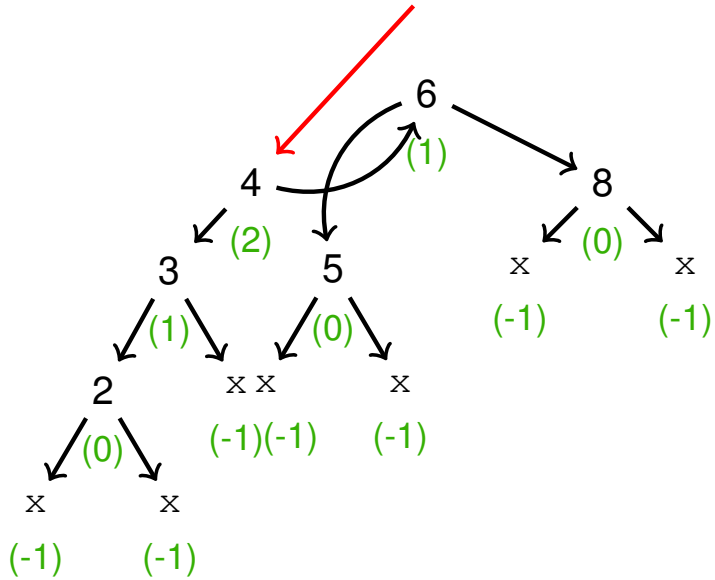

Green number: height

after *bst.root* ← *inserthelp*(_, _, _)

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Implementing rotations

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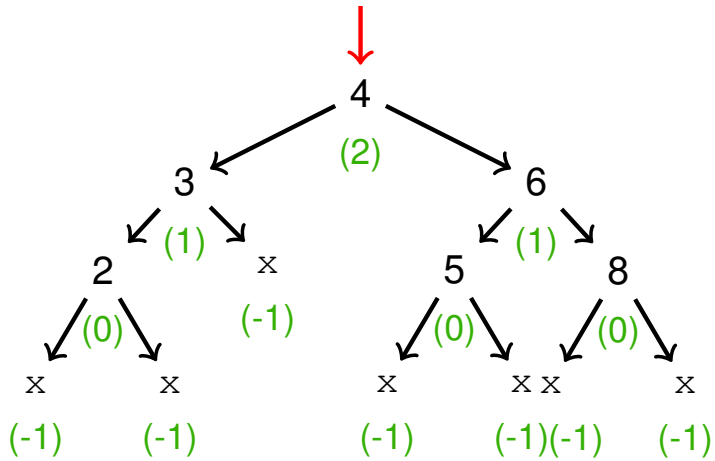

Green number: height

better presented as above

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Implementing rotations

Implementing deletion is analogous to the insertion implementation

- Deletion code, in addition to code of rotations
- Updating heights (and balance factors) from the actually removed node (*deletemin*) to the root

Asymptotic efficiency of AVLs[2]

Data Structure	Time Complexity								Space Complexity
	Average				Worst				Worst
	Access	Search	Insertion	Deletion	Access	Search	Insertion	Deletion	
Array	O(1)	O(n)	O(n)	O(n)	O(1)	O(n)	O(n)	O(n)	O(n)
Stack	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)
Queue	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)
Singly-Linked List	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)
Doubly-Linked List	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)
Skip List	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n log(n))
Hash Table	N/A	O(1)	O(1)	O(1)	N/A	O(n)	O(n)	O(n)	O(n)
Binary Search Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n)
Cartesian Tree	N/A	O(log(n))	O(log(n))	O(log(n))	N/A	O(n)	O(n)	O(n)	O(n)
B-Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)
Red-Black Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)
Splay Tree	N/A	O(log(n))	O(log(n))	O(log(n))	N/A	O(log(n))	O(log(n))	O(log(n))	O(n)
AVL Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)
KD Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n)

1

AVL $\approx$ the same number of comparisons of binary search

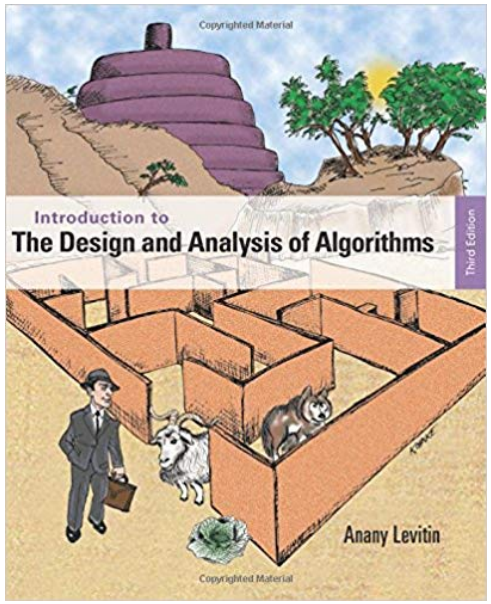
- Cons: frequent rotations + storing the node height

[1] http://bigocheatsheet.com/

[2] Source: http://bigocheatsheet.com/

Agenda

Bibliography



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