# Probabilistic Graphical Models

Course 2: Markov Logic Networks

Hoel Le Capitaine Academic year 2017-2018

## Outline

Introduction

Background

Markov Logic

Inference

Learning

# Introduction

## Motivation

### Information and Knowledge - 1988

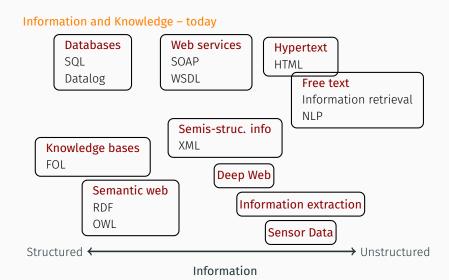
**Databases**SQL
Datalog

Knowledge bases

Free text Information retrieval NLP

Structured ← → Unstructured
Information

### Motivation



## We need languages that can handle

- Structured information
- Unstructured information
- · Any variation or combination of them

### We need efficient algorithms for them

- Inference
- Machine learning

Background

# This lecture: Markov Logic

## Unifies first-order logic and probabilistic graphical models

 $\cdot$  First-order logic handles structured information

# This lecture: Markov Logic

## Unifies first-order logic and probabilistic graphical models

- First-order logic handles structured information
- Probability handles unstructured information

# This lecture : Markov Logic

## Unifies first-order logic and probabilistic graphical models

- First-order logic handles structured information
- Probability handles unstructured information
- · No separation between the two
- · Builds on previous work (BN, PRM, ...)

## Undirected graphical models



#### Potential functions

- potential functions defined on cliques
- · joint distribution of the MN:

$$P(X=X) = \frac{1}{Z} \prod_{k} \phi_k(X_{\{k\}})$$

- $x_{\{k\}}$  is the state of the kth clique
- $\cdot$  Z is the partition function

$$Z = \sum_{x} \prod_{k} \phi_{k}(x_{\{k\}})$$

Smoking	Cancer	$\phi(S,C)$
false	false	4.5
false	true	4.5
true	false	2.7
true	true	4.5

## Undirected graphical models



### Log-linear models

 each clique replaced by an exponentiated weighted sum of (binary) features of the state

$$P(X = x) = \frac{1}{Z} \exp \left( \sum_{j} w_{j} f_{j}(x) \right)$$

## Undirected graphical models



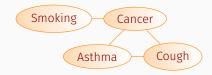
## Log-linear models

 each clique replaced by an exponentiated weighted sum of (binary) features of the state

$$P(X = x) = \frac{1}{Z} \exp \left( \sum_{j} w_{j} f_{j}(x) \right)$$

weight of feature j

## Undirected graphical models



### Log-linear models

 each clique replaced by an exponentiated weighted sum of (binary) features of the state

$$P(X = x) = \frac{1}{Z} \exp \left( \sum_{j} w_{j} f_{j}(x) \right)$$

- · weight of feature j
- feature j

# First order logic

#### Some recalls

- constants, variables, functions, predicates
   Sarah, x, MotherOf(x), Friends(x,y)
- grouding: replace all variables by constants
   Friends(Sarah, Bernard)
- World (model, interpretation): assignment of truth valuser to all ground predicates

Markov Logic

# Markov logic

## From logic to probability

- a logical knowledge base is a set of hard constraints on the set of possible worlds
- transform them into soft constraints: if a world violates a formula, it becomes less probable, not impossible
- each formula is associated to a weight, corresponding to the strength of the constraint

$$P(world) \approx \exp\left(\sum weights of satisfied formulas\right)$$

#### Definition

A Markov Logic Network (MLN) is a set of pairs (F, w) where F is a 1<sup>st</sup>-order logic formula, and w is a real value.

It defines a Markov network with

- one node for each grounding of each predicate
- one feature for each grounding of each formula *F*, with corresponding weight *w*

#### A first KB

smoking causes cancer

#### A first KB

• smoking causes cancer  $\forall x \ Smokes(x) \rightarrow Cancer(x)$ 

#### A first KB

- smoking causes cancer  $\forall x \ Smokes(x) \rightarrow Cancer(x)$
- $\cdot$  if 2 people are friends, either both smokes or neither does

#### A first KB

- smoking causes cancer  $\forall x \ Smokes(x) \rightarrow Cancer(x)$
- if 2 people are friends, either both smokes or neither does  $\forall x \forall y \; Friends(x,y) \rightarrow \Big(Smokes(x) \Leftrightarrow Smokes(y)\Big)$

#### A first KB

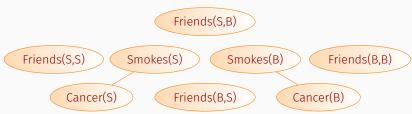
· smoking causes cancer

$$\forall x \ Smokes(x) \rightarrow Cancer(x)$$
  $w = 1.5$ 

• if 2 people are friends, either both smokes or neither does

$$\forall x \forall y \ Friends(x,y) \rightarrow \Big(Smokes(x) \Leftrightarrow Smokes(y)\Big)$$
  $w = 1.1$ 

Two constants: Sarah (S) and Bernard (B)

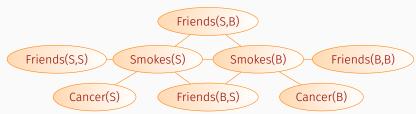


#### A first KB

- · smoking causes cancer
  - $\forall x \ Smokes(x) \rightarrow Cancer(x)$  w = 1.5
- · if 2 people are friends, either both smokes or neither does

$$\forall x \forall y \ Friends(x,y) \rightarrow \Big(Smokes(x) \Leftrightarrow Smokes(y)\Big)$$
  $w = 1.1$ 

Two constants: Sarah (S) and Bernard (B)



## Markov Logic Networks

- · MLN is a template for ground Markov networks
- probability of a world X

$$P(X) = \frac{1}{Z} \exp \left( \sum_{i} w_{i} n_{i}(X) \right)$$

 $n_i(X)$ : number of true groundings of formula i in X

- typed variables and constants reduce size of the net
- · functions, existential quantifiers
- · both infinite and continuous domains

# Coming back to first order logic

- infinite weights exactly correspond to first-order logic
- satisfiable KB, positive weights: Satisfying assignments = Modes of distribution
- · Markov logic allows contradictions between formulas

Inference

• we want to find the most likely state of world, given our observation  $\underset{}{\operatorname{argmax}_{y}} P(y|x)$ 

• we want to find the most likely state of world, given our observation  $\underset{\sim}{\operatorname{argmax}_{V}} P(y|x)$ 

y: queryx: evidence

- we want to find the most likely state of world, given our observation  $\underset{\sim}{\operatorname{argmax}}_{V} P(y|x)$ 
  - y: query
  - · x : evidence
- using definition,  $\operatorname{argmax}_{y} \frac{1}{Z_{x}} \exp\left(\sum_{i} w_{i} n_{i}(x, y)\right)$

- we want to find the most likely state of world, given our observation  $\underset{\sim}{\operatorname{argmax}}_{V} P(y|X)$ 
  - y: queryx: evidence
- using definition,  $\operatorname{argmax}_{y} \frac{1}{Z_{x}} \exp\left(\sum_{i} w_{i} n_{i}(x, y)\right)$
- · due to indep. and monotonocity,  $\operatorname{argmax}_{V} \sum_{i} w_{i} n_{i}(x, y)$
- · reduced to a weighted maxSAT problem (eg walkSAT)
- · may be faster than logical inference!

## walkSAT Algorithm (1996)

```
for i \leftarrow 1 to max-tries do
   solution = random truth assignment
   for j \leftarrow 1 to max-flips do
       if all clauses satisfied then
            return solution
       c ← random unsatisfied clause
       with probability p
            flip a random variable in c
       else
            flip variable in c that maximizes number of satisfied clauses
return failure
```

# maxwalkSAT Algorithm (1997)

```
for i ←1 to max-tries do

solution = random truth assignment

for j ← 1 to max-flips do

if ∑ weights of satisfied clauses > t then

return solution

c ← random unsatisfied clause

with probability p

flip a random variable in c

else

flip variable in c that maximizes ∑ weights of satisfied clauses
```

return failure, best solution found

### Ok .. but

- · memory explosion ...
- if there are n constants, and highest clause arity is c, ground network requires  $O(n^c)$  memory
- we need to exploit sparseness: LazySAT (2006)

Learning

# Learning

- · Data is a relational database
- · Closed world assumption (if not: EM)
- Learning parameters (weights)
  - Generatively
  - Discriminatively
- · Learning structure (formulas)

# Generative weight learning

- · based on maximum likelihood
- uses gradient ascent (or more complicated ones)
- · no local maxima  $\Delta_{w_i} \log P_w(x) = n_i(x) E_w[n_i(x)]$ 
  - $E_W[n_i(x)]$  expected number of true groundings according to the model
- but requires inference at each step of the optimization (slow)

## Pseudo-likelihood

· Likelihood of each variable given its neighbors in the data

$$PL(x) = \prod_{i} P(x_i|N(x_i))$$

- · Does not require inference at each step
- · Consistent estimator
- · Widely used in vision, spatial statistics, etc.
- But PL parameters may not work well for long inference chains

# Discriminative weight learning

 $\cdot$  maximize conditional likelihood of query y given observation x

$$\Delta_{w_i} \log P_w(y|x) = n_i(x,y) - E_w[n_i(x,y)]$$

 approximation of expectation counts by counts in MAP state of y given x (voted perceptron)

# Structure learning

- · Generalizes feature induction in Markov nets
- · Any inductive logic programming approach can be used, but . . .
- · Goal is to induce any clauses, not just Horn
- · Evaluation function should be likelihood
- · Requires learning weights for each candidate
- Turns out not to be bottleneck
- · Bottleneck is counting clause groundings
- Solution: Subsampling

# Structure learning

- · Initial state: Unit clauses or hand-coded KB
- Operators : Add/remove literal, flip sign
- Evaluation function : Pseudo-likelihood + Structure prior
- · Search: Beam, Shortest-first, Bottom-up (2005–2007)