

Setup

```
source /opt/ros/foxy/setup.bash  
cd colcon3_ws  
source install/local_setup.bash
```

```
ros2 run wall_follower wall_follower  
ros2 run image_processing image_processing  
ros2 launch turtlebot3_cartographer cartographer.launch.py
```

```
ros2 launch turtlebot3_gazebo empty_world.launch.py
```

```
ros2 launch turtlebot3_bringup robot.launch.py
```