

Least squares regression

a short story on overdetermined linear systems and Moore-Penrose pseudoinverse

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3 Partial Least Squares (PLS) regression

The most general linear equation is of the form:

$$\mathbf{X}\mathbf{w} = \mathbf{y} \quad (1)$$

Preface

Imagine a linear system of equations with more number equations than the number of unknowns.

Goal of this paper: explain why Moore-Penrose inverse give a least squares regression.

This document is still in preparation. Please feel free to contact me with any suggestions, corrections or comments.

Keywords

overdetermined linear systems, partial least squares regression, Moore-Penrose inverse

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1 References on Least Squares

2 Least Squares - the story

At this point, I ought to give a small justification. In many literature references such as [1], the above equation can be encountered written as $A\vec{x} = \vec{b}$ (with unknown \vec{x}) or $A\mathbf{x} = \mathbf{y}$ (with unknown \mathbf{x}). I decided to write it in a different notation, with the unknown vector \mathbf{w} , since I wanted to highlight the link of algebra with geometry.

To avoid naming confusion, in eq.(1), \mathbf{X} and \mathbf{y} contain the actual x and y coordinates of the data points on the x and y axis respectively. Thus, \mathbf{X} and \mathbf{y} are known; the vector of unknown coefficients is \mathbf{w} .

This actually follows the notation presented in [2] in Chapter 3 on *Linear Models for Regression*.

- 1 2D data example
- 1 Have a data set in pairs: (X, Y) . X is a vector of N points and Y is a vector of corresponding N points. Together they make a cloud of points on a 2D-plane.

We now say that: $\mathbf{X}\mathbf{A} = \mathbf{Y}$.

We are interested in finding the coefficients: $\mathbf{y} = \mathbf{C}\mathbf{x} + \mathbf{D}$.

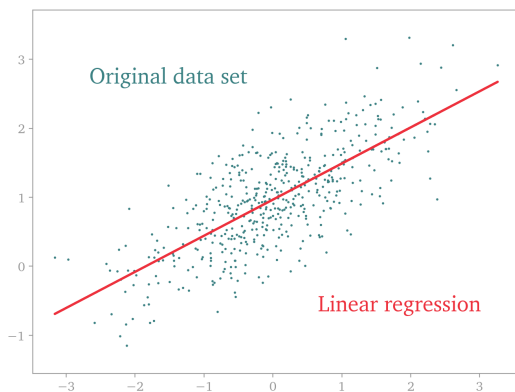


Figure 1: Example of a linear regression.

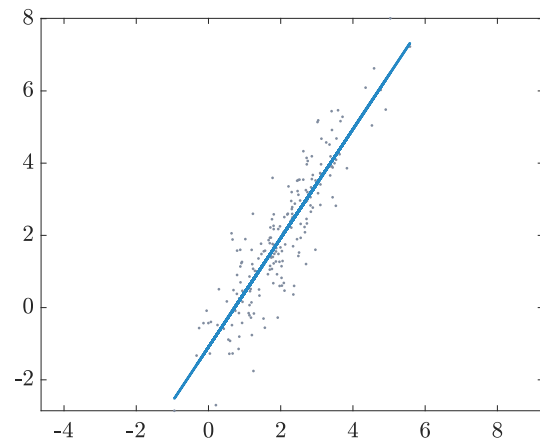


Figure 2: Linear basis function LS regression.

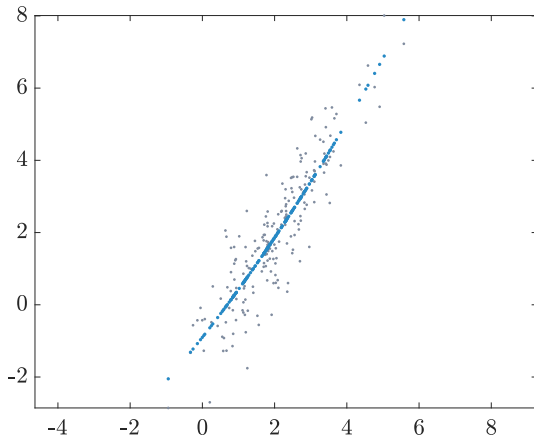


Figure 3: Non-linear (quadratic) basis function LS regression.

References

- [1] Gilbert Strang, *Introduction to Linear Algebra*, Fifth Edition, 2016
- [2] Christopher M. Bishop, *Pattern Recognition and Machine Learning*, 2006
- [3] Nathan Kutz, *Data Driven Discovery of Dynamical Systems and PDEs*, an online lecture
- [4] T. Hastie, R. Tibshirani, J. Friedman, *Elements of Statistical Learning, Data Mining, Inference, and Prediction*, Second Edition, 2008