CSE 891 - Section 1:
Parallel Computing Fundamentals and Applications

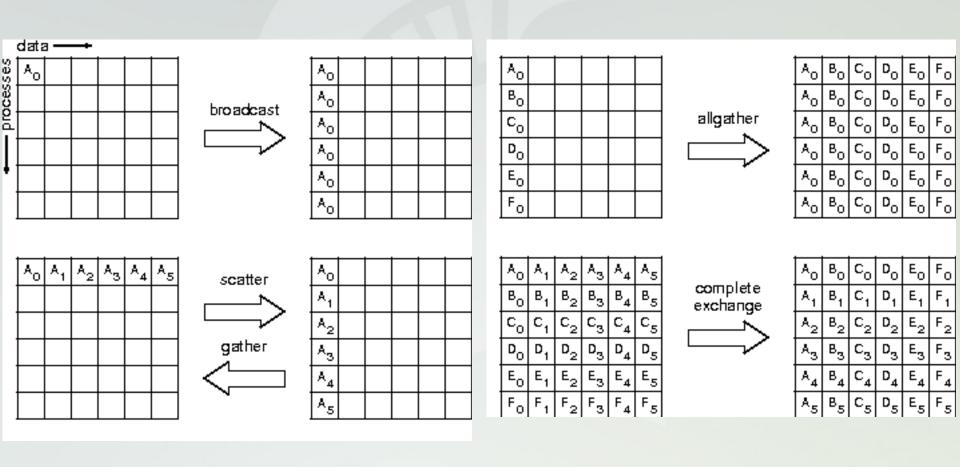
Fall 2014 - Lecture 8: Programming using the Message Passing Paradigm

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Lecture 7- Summary

- Programming Using the Message Passing Paradigm
 - Asynchronous Send & Recv
 - Parallel Sum Reduction
 - 3 different algorithms
 - Parallel complexity analyses
 - Collective Communications in MPI
 - Barrier, Broadcast, Reduce, All_reduce
 - Gather, Scatter, All_gather, Alltoall
 - Variable variants

Lecture 7- Summary



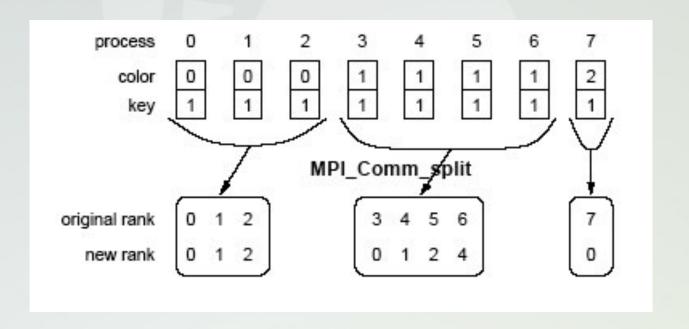
Groups and Communicators

- In many parallel algorithms, communication operations need to be restricted to certain subsets of processes.
- MPI provides mechanisms for partitioning the group of processes that belong to a communicator into subgroups each corresponding to a different communicator.
- The simplest such mechanism is:

 This operation groups processors by color and sorts resulting groups on the key.

Groups and Communicators

Using MPI_Comm_split to split a group of processes in a communicator into subgroups.

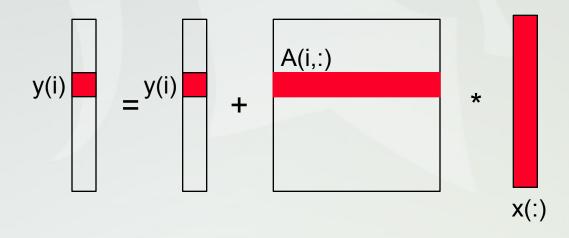


```
{implements y = y + A*x}

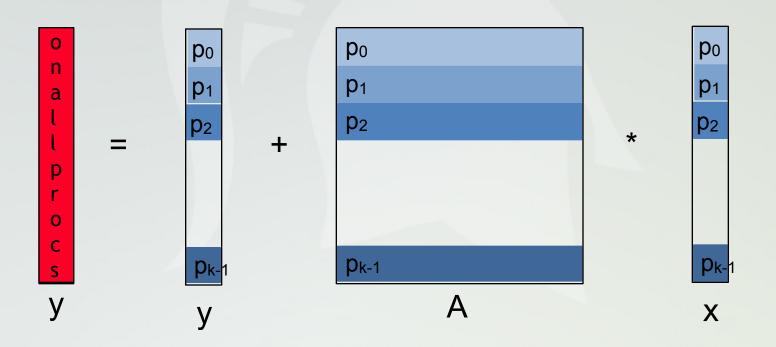
for i = 1:n

for j = 1:n

y(i) = y(i) + A(i,j)*x(j)
```

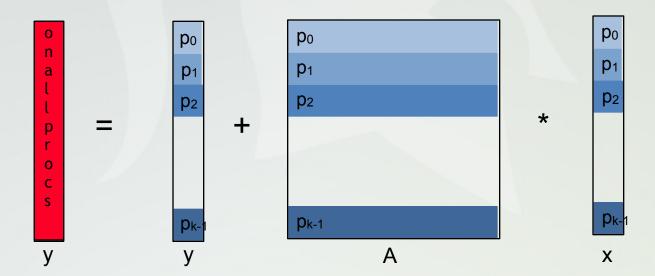


Assume we have *k* processors with the following initial data layout



A high-level parallel algorithm:

- collect the entire x vector on all processors
- perform local matrix-vector multiplications y(i) = y(i) + A(i,:) * x(:)
- collect partial output vectors y on all processors



```
finclude <mpi.h>
#include <stdio.h>
#include <sys/time.h>
#define N 3000
int main(int argc, char *argv[])
  int P, i, myrank, M;
  int i, j;
  double t_start, t_end;
  double **my_A, *my_x, *my_y, *x, *y;
  /* Initializations */
 MPI_Init(&argc, &argv);
  MPI Comm size(MPI COMM WORLD, &P);
  MPI_Comm_rank(MPI_COMM_WORLD, &myrank);
  M = N / P; // Assuming N is a multiple of P
  my x = (double*) malloc(M * sizeof(double));
  my_y = (double*) malloc(M * sizeof(double));
  x = (double*) malloc(N * sizeof(double));
 y = (double*) malloc(N * sizeof(double));
  A = (double**) malloc(M * sizeof(double*));
  for (i = 0; i < M; ++i)
   A[i] = (double*) malloc(N * sizeof(double));
  srand(time(NULL));
  for (i = 0; i < M; ++i) {
   my_x[i] = rand()/N;
   my_y[i] = rand()/N;
   for (j = 0; j < N; ++j)
      A[i][i] = rand()/N;
```

```
/* collect x vector on all processors */
/* first copy my_x into x */
for (j = 0; j < M; ++j)
   x[myrank*M +j] = my_x[j];

for (i = 0; i < P; ++i)
   MPI_Bcast(&(x[myrank*M]), M, MPI_DOUBLE, i, MPI_COMM_WORLD);</pre>
```

What is the complexity of the operations above? $O(N/P+P\log P)$ What is the total communication volume? O(PN)

Is there a better way? YES!

```
/* collect x vector on all processors */
MPI_Gather(my_x, M, MPI_DOUBLE, x, N, MPI_DOUBLE, 0, MPI_COMM_WORLD);
MPI_Bcast(x, N, MPI_DOUBLE, 0, MPI_COMM_WORLD);
```

Or better yet:

```
/* collect x vector on all processors */
MPI_Allgather(my_x, M, MPI_DOUBLE, x, N, MPI_DOUBLE, MPI_COMM_WORLD);
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```

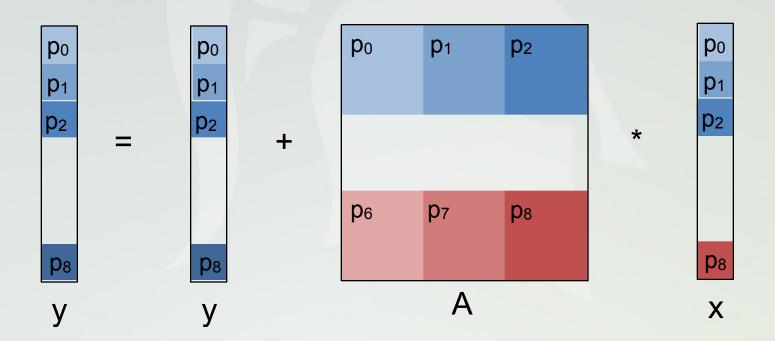
```
/* local computations */
for (i = 0; i < M; ++i)
   for (j = 0; j < N; ++j)
    my_y[i] += A[i][j] * x[j];

/* collect partial results at all processors */
MPI_Allgather(my_y, M, MPI_DOUBLE, x, N, MPI_DOUBLE, MPI_COMM_WORLD);</pre>
```

MPI_Allgather is simpler to implement and potentially will have a better execution time than a series of broadcasts. Nevertheless, in the current scheme, $\Omega(PN)$ is the lower bound on the communication volume and it is not likely to scale well.

Can we do better?

Assume we have 9 processors using a 2D decomposition:

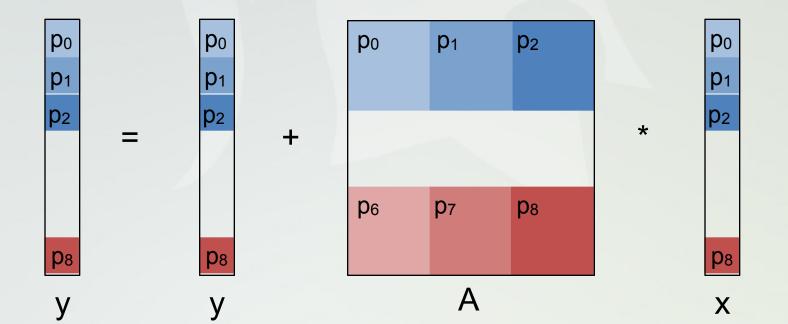


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An MPI Example: Parallel Matrix-Vector Multiply

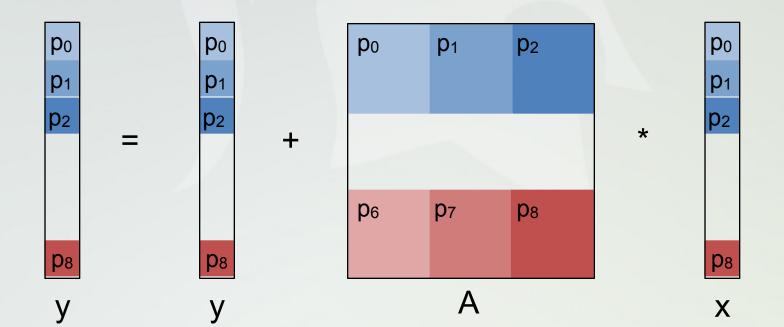
How is a 2D decomposition different from 1D decomposition?

- Number of matrix elements? Same, N²/P. So the computational work does not change.
- How about communication volume?



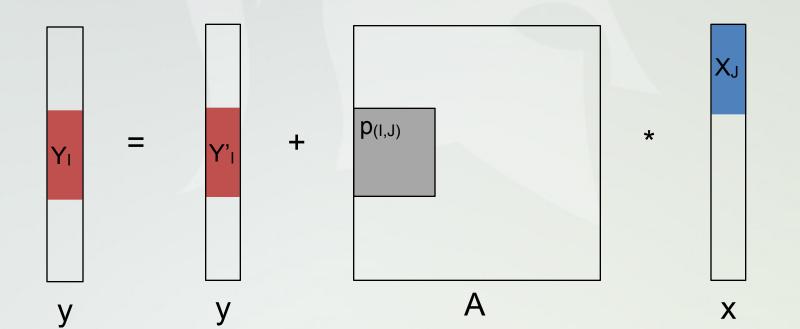
Each processor still starts with an N/P partition of x, but now each one needs only a partition of x which is of length $N/P^{1/2}$.

So input communication volume is now $\Omega(P(N/P^{1/2} - N/P)) = \Omega(P^{1/2}N)$ - compare with the 1D partitioning case which was O(PN)!

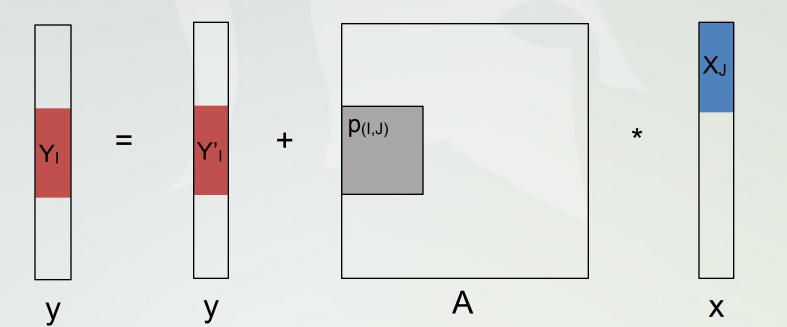


Let us consider the processor at the ith row and ith column:

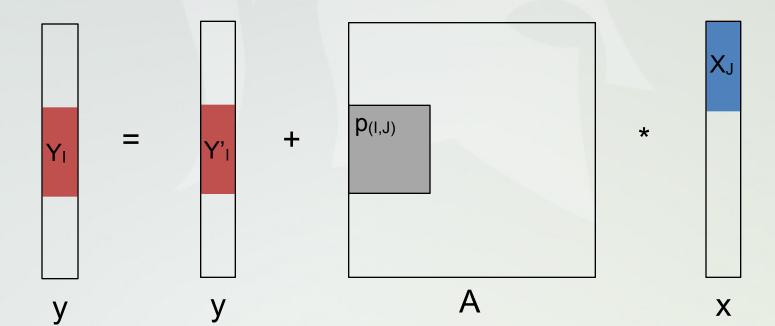
- It needs to talk to P^{1/2} other processors on its column for input
- So the input vector can be collected through a gather along rows



- But what about the output vector?
- Matrix-vector multiply in block notation: Y'[I] += A[I][J] * X[J]
- The output of each processor is only partial, hence denoted by Y'1
- Need a reduction this time along rows



- So instead of the default communicator MPI_COMM_WORLD, we now need column and row communicators!
- This can be implemented using MPI_Comm_split
- Use the row and and column index values as colors



```
#define N 3000
int main(int argc, char *argv[])
 int P, i, myrank, M, myrow, mycol;
  double t_start, t_end;
 double **my_A, *my_x, *my_y, *x, *y;
 MPI Comm rowcomm, colcomm;
  /* Initializations */
 MPI Init(&argc, &argv);
 MPI Comm size(MPI COMM WORLD, &P);
 MPI Comm rank(MPI COMM WORLD, &myrank);
  sqrtP = sqrt(P); // Assuming P is a perfect square
 M = N / P; // Assuming N is a multiple of P
  bigM = N / sqrtP; // Assuming N is a multiple of P
 my_x = (double*) malloc(M * sizeof(double));
 my y = (double*) malloc(M * sizeof(double));
 x = (double*) malloc(bigM * sizeof(double));
 y = (double*) malloc(bigM * sizeof(double));
 A = (double**) malloc(bigM * sizeof(double*));
 for (i = 0; i < bigM; ++i)
   A[i] = (double*) malloc(bigM * sizeof(double));
  srand(time(NULL));
  for (i = 0; i < M; ++i) {
   mv x[i] = rand()/N;
   my_y[i] = rand()/N;
  for (i = 0; i < bigM; ++i)
   for (j = 0; j < bigM; ++j)
     A[i][i] = rand()/N:
```

```
/* setup communication groups */
myrow = myrank / sqrtP;
mycol = myrank % sqrtP;
MPI_Comm_split(MPI_COMM_WORLD, myrow, myrank, &rowcomm);
MPI_Comm_split(MPI_COMM_WORLD, mycol, myrank, &colcomm);

/* collect x vectors along column comms, y vector along row comms */
MPI_Allgather(my_x, M, MPI_DOUBLE, x, bigM, MPI_DOUBLE, colcomm);
MPI_Allgather(my_y, M, MPI_DOUBLE, y, bigM, MPI_DOUBLE, rowcomm);

/* local computations */
for (i = 0; i < bigM; ++i)
    for (j = 0; j < bigM; ++j)
        y[i] += A[i][j] * x[j];

/* collect partial results along rows */
for (i = 0; i < sqrtP; ++i)
    MPI_Reduce(&(y[M*i]), my_y, M, MPI_DOUBLE, MPI_SUM, i, rowcomm);</pre>
```

Or there is a (potentially) more efficient way:

```
/* collect partial results along rows */
MPI_Reduce_scatter(y, my_y, array_of_M, MPI_DOUBLE, MPI_SUM, rowcomm); 19
```

- So what is overall communication volume of the 2D algorithm?
- We have seen that decisions made at an algorithmic level have important consequences in terms of communication overheads
- Not only that, but how we implement the algorithm is important! (a series of bcasts vs. allgather, or a series of reduces vs. reduce_scatter)

We can create cartesian topologies using the function:

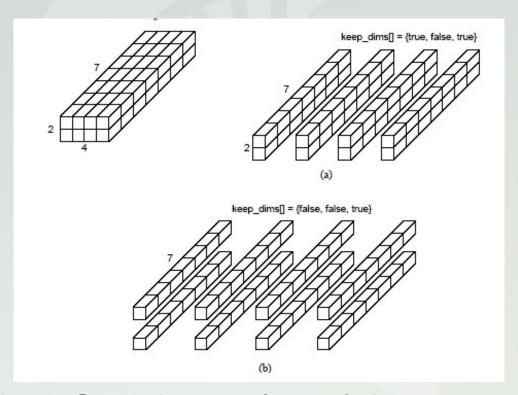
- This function takes the processes in the old communicator and creates a new communicator with dims dimensions.
- Each processor can now be identified in this new cartesian topology by a vector of dimension dims.

 Since sending and receiving messages still require (onedimensional) ranks, MPI provides routines to convert ranks to cartesian coordinates and vice-versa.

The most common operation on cartesian topologies is a shift. To determine the rank of source and destination of such shifts, MPI provides the following function:

MPI provides a convenient way to partition a Cartesian topology to form lower-dimensional grids:

- If keep_dims[i] is true (non-zero value in C) then the ith dimension is retained in the new sub-topology.
- The coordinate of a process in a sub-topology created by MPI_Cart_sub can be obtained from its coordinate in the original topology by disregarding the coordinates that correspond to the dimensions that were not retained.



Splitting a Cartesian topology of size 2 x 4 x 7 into (a) four subgroups of size 2 x 1 x 7, and (b) eight subgroups of size 1 x 1 x 7.

How to time your application?

- C provide gettimeofday() not so practical
- MPI alternative MPI_Wtime()
- Make sure to put a barrier before starting the timer and right before stopping the timer!
- Average over multiple executions for small tasks!