CSE 891 - Section 1:
Parallel Computing Fundamentals and Applications

Fall 2014 - Lectures 7:
Programming using the Message Passing Paradigm

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# Lecture 6- Summary

- Programming Using the Message Passing Paradigm
  - Principles of Message-Passing Programming
  - Building Blocks: Send & Recv operations
    - Semantics of Send & Recv
    - Blocking, Buffered, Non-blocking Sends
- MPI: the Message Passing Interface
  - History of MPI and MPI Implementations
  - The minimal set of MPI routines
  - MPI\_Send & MPI\_Recv
  - MPI Datatypes
  - Avoiding deadlocks

### Asynchronous Send & Recvs

 To overlap communication with computation, MPI provides functions to perform non-blocking send & receives which return before the operations are completed.

From OpenMPI manual: A nonblocking send call indicates that the system may start copying data out of the send buffer. The sender should not access any part of the send buffer after a nonblocking send operation is called, until the send completes.

# Asynchronous Send & Recvs (cont.)

- Important: All asynchronous operations are given a request handle that has to be acted on later in one of the following ways:
  - block and wait for the operation to finish with MPI\_Wait(...)
     or MPI\_Waitany(...)

```
int MPI_Wait(MPI_Request *request, MPI_Status *status)
```

test for completion with MPI\_Test(...) or MPI\_Testany(...)
until the test turns out positive

If neither is done, the asynchronous calls may not be fully completed - messages not sent, memory leaks, etc.

5

# Overlapping Communication and Computation

- Recommended usage is to pair a blocking and nonblocking call
- MPI\_Isend on p0 and MPI\_Recv on p1:
   p0 posts the send and goes back to doing useful computations, p1 does useful computations (followed by MPI\_Wait or MPI\_Test) and starts waiting on recv only when it can not proceed further
- MPI\_Send on p0 and MPI\_Irecv on p1:
  p1 posts the MPI\_Irecv as soon as it knows the kind and (max) length of a message it will receive and continues to do useful computations (followed by MPI\_Wait of MPI\_Test). When p0 has a message ready to be sent, it immediately find the posted recv.

# Overlapping Communication and Computation

- So to achieve the best overlapping, why not post all MPI\_Irecv's and/or MPI\_Isend's very early on and put MPI\_Wait's at the very end?
  - First, we do not know well ahead of time how many and how long most messages will be
  - Also, having too many outstanding asynchronous send & recv's may require too much buffer space - and we may run out of memory!

### **Avoiding Deadlocks Revisited**

Non-blocking operations resolve most deadlocks.
 Consider:

```
int a[10], b[10], myrank;
MPI_Status status;
...
MPI_Comm_rank(MPI_COMM_WORLD, &myrank);
if (myrank == 0) {
    MPI_Send(a, 10, MPI_INT, 1, 1, MPI_COMM_WORLD);
    MPI_Send(b, 10, MPI_INT, 1, 2, MPI_COMM_WORLD);
}
else if (myrank == 1) {
    MPI_Recv(b, 10, MPI_INT, 0, 2, &status, MPI_COMM_WORLD);
    MPI_Recv(a, 10, MPI_INT, 0, 1, &status, MPI_COMM_WORLD);
}
```

 Replacing either the send or the receive operations with non-blocking counterparts fixes this deadlock.

# An Example

- Problem: Compute n values and find their sum.
- Serial solution is straight-forward

```
sum = 0;
for (i = 0; i < n; ++i) {
  x = Compute_next_value(...);
  sum += x;
}</pre>
```

# How to do this in parallel?

- We have p cores, where p << n</p>
- How can we compute the sum in parallel?
- It turns out that there are several ways with different communication requirements
- Let us take a look at them in more detail

# Algorithm 1

```
if (my rank == 0) {
 sum = 0;
 for (i = 0; i < n/p; ++i) {
  x = Compute next value(...);
  sum += x;
 for (i = n/p; i < n; ++i) {
  recv(x, src, tag, comm);
  sum += x;
else {
 for (i = 0; i < n/p; ++i) {
  x = Compute next value(...);
  send(x, 0, tag, comm);
```

- Is this a good algorithm?
- How many messages are exchanged?
- How many bytes are communicated?
- Is the computation load balanced?
- Can we improve it?

# Algorithm 2

```
if (my rank == 0) {
my sum = 0;
 for (i = 0; i < n/p; ++i) {
  x = Compute next value(...);
 my sum += x;
 for (i = 1; i < p; ++i) {
  recv(other sum, i,...);
  my sum += other sum;
else {
my sum = 0;
 for (i = 0; i < n/p; ++i) {
  x = Compute next value(...);
  my_sum += x;
 send(my sum, 0, ...);
```

- Let us make it load balanced
- Is the computation load balanced?
- Now how many messages are exchanged?
- How many bytes are communicated?
- Can we improve it?

# Algorithm 2 (cont.)

#### my\_sum after local n/p local summations

Core	0	1	2	3	4	5	6	7
my_sum	8	19	7	15	7	13	12	14

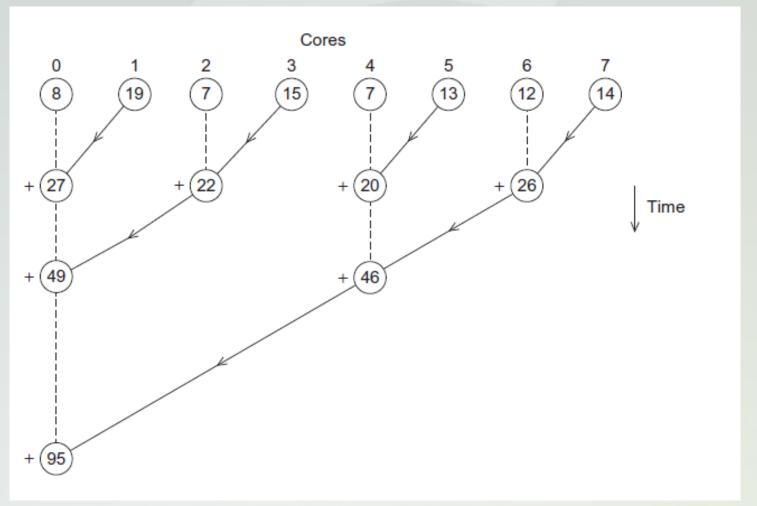
#### Global sum

$$8 + 19 + 7 + 15 + 7 + 13 + 12 + 14 = 95$$

my sum after comm & summations at process 0

Core	0	1	2	3	4	5	6	7
my_sum	95	19	7	15	7	13	12	14

# How about a tree algorithm?



# Algorithm 3

```
my sum = 0;
for (i = 0; i < n/p; ++i) {
 x = Compute next value(...);
 my sum += x;
m = log(p);
for (i = 0; i < m; ++i) {
 determine my partner
 if (I am sender)
   send (my sum, partner, ...);
 else { // I am receiver
   recv(other sum, partner, ...);
  my sum += other sum;
// At this point, p0's my sum
  is the global sum
```

- Let us make it load balanced
- Is the computation load balanced?
- Now how many messages are exchanged?
- How many bytes are communicated?

# Algorithm 3 (cont.)

- Parallel sum example shows how send & recv can be used as building blocks for complex communication patterns
- The tree structure used is called a binomial tree similar to, but not to be confused with a binary tree
- As we will see, commonly used complex operations are already implemented in MPI
- Parallel sum is called a reduction as implemented by MPI\_Reduce

- MPI provides an extensive set of functions for performing common collective communication operations.
- Each of these operations is defined over a group corresponding to the communicator.
- All processors in a communicator must call these operations.
- Up until MPI-3, all collective calls used to be blocking.
   Now there exists their non-blocking counterparts, too!
  - At least they are in the specification
  - When will they be implemented? and how efficient will the implementations be???

The barrier synchronization operation in MPI:

```
int MPI Barrier (MPI Comm comm)
```

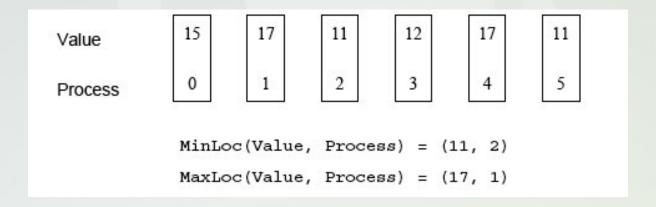
The one-to-all broadcast operation is:

The all-to-one reduction operation is:

# Pre-defined Reduction Operations

Operation	Meaning	Datatypes
MPI_MAX	Maximum	C integers and floating point
MPI_MIN	Minimum	C integers and floating point
MPI_SUM	Sum	C integers and floating point
MPI_PROD	Product	C integers and floating point
MPI_LAND	Logical AND	C integers
MPI_BAND	Bit-wise AND	C integers and byte
MPI_LOR	Logical OR	C integers
MPI_BOR	Bit-wise OR	C integers and byte
MPI_LXOR	Logical XOR	C integers
MPI_BXOR	Bit-wise XOR	C integers and byte
MPI_MAXLOC	max-min value-location	Data-pairs
MPI_MINLOC	min-min value-location	Data-pairs <sup>18</sup>

- The operation MPI\_MAXLOC combines pairs of values  $(v_i, l_i)$  and returns the pair (v, l) such that v is the maximum among all  $v_i$  's and l is the corresponding  $l_i$  (if there are more than one, it is the smallest among all these  $l_i$  's).
- MPI\_MINLOC does the same, except for minimum value of  $v_i$ .



MPI datatypes for data-pairs used with the MPI\_MAXLOC and MPI MINLOC reduction operations

MPI Datatype	C Datatype
MPI_2INT	pair of ints
MPI_SHORT_INT	short and int
MPI_LONG_INT	long and int
MPI_LONG_DOUBLE_INT	long double and int
MPI_FLOAT_INT	float and int
MPI_DOUBLE_INT	double and int

If the result of the reduction operation is needed by all processes, MPI provides:

To compute prefix-sums, MPI provides:

The gather operation is performed in MPI using:

MPI\_Allgather function gathers the data at all processes:

The corresponding scatter operation is:

The all-to-all personalized communication operation is performed by:

 Using this core set of collective operations, parallel programs can be greatly simplified.