VisgraphVar: A Benchmark Generator for Assessing Variability in Graph Analysis Using Large Vision-Language Models (Supplementary material)

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Table 1: Task 1 (Detection)

(a)

							Lay	Layout						
MIVI	ranc	random	ν.΄	spiral	C	circular	sk	shell	spring	ing	kan	kamada	spectral	tral
	CoT	0-shot	CoT	0-shot	ot CoT	[0-shot	CoT	0-shot	CoT	0-shot	$_{ m CoT}$	0-shot	CoT	0-sho
claude-3.5-sonnet	80.27	79.20	78.49					69.37	69.12	71.39	73.66	75.71	47.11	48.85
gemini-pro-1.5	81.69	82.16	78.31	75.83	3 72.12		75.73	76.37	80.87	80.89	85.62	86.61	55.47	55.11
gpt-4o-2024-08-06	67.87	68.30	66.01					56.38	81.55	80.85	84.73	84.52	64.07	66.0
llama-3.2-90b-vision-instruct	62.80	62.37	67.45					70.40	50.77	50.62	55.75	59.47	39.99	44.34
pixtral-12b qwen-2-vl-72b-instruct	61.17 66.01	68.27 68.20	67.35 61.45			$ \begin{array}{cccc} 1 & 47.81 \\ 4 & 44.57 \end{array} $		49.38 48.89	65.17 67.91	70.57 69.78	67.41 73.57	75.77 72.29	44.71 55.78	50.92 54.56
	(b)									(c)				
		三	Edge type	pe							Node color	color		
MIXI		directed		undirected	ted	[W]	IMIM		I	one color	olor	random colors	colors	
	Ŭ	CoT 0-shot		CoT 0	0-shot				I	CoT	0-shot	CoT	0-shot	
claude-3,5-sonnet	75.27			64.63	64.44	cla ₁	claude-3,5-sonnet	nnet		69.58	68.92	70.33	69.94	
gemini-pro-1,5	79.40			_	72.41	gen	gemini-pro-1,5	5.		74.92	75.45	76.45	76.47	
gpt-4o-2024-08-06	74.21	_			65.51	gpt	gpt-40-2024-08-06	90-80		80.69	67.12	70.52	96.89	
llama-3,2-90b-vision-instruct					56.35	llar	na-3,2-90l	Hama-3,2-90b-vision-instruct	nstruct	90.09	59.53	57.18	60.34	
pixtral-12b	62.79		66.94 5	54.81	53.39	pix	pixtral-12b			62.22	60.05	55.38	60.28	
qwen-2-vl-72 b -instruct	66.92				52.96	dwe	en-2-vl-72	qwen-2-vl-72b-instruct	c	62.02	59.33	60.27	58.29	
						(p)								
							Node labels	hels						

		rode labels	labeis	
INIM	pre	present	not present	resent
	CoT	CoT 0-shot		CoT 0-shot
claude-3.5-sonnet	71.63	70.84	68.28	68.01
gemini-pro-1.5	76.33	76.27	75.05	75.65
gpt-40-2024-08-06	73.41	73.45	66.19	62.63
llama-3.2-90b-vision-instruct	60.27	60.20	56.97	59.67
pixtral-12b	59.65	60.33	57.95	60.01
gwen-2-vl-72b-instruct	64.05	62.55	58.25	55.06

Table 2: Task 2 (Classification)

							Grap	h type						
LVLM	acy	rclic	cyc	elic	bipa	rtite	com	plete	me	esh	pla	nar	t	ree
272112	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot
claude-3.5-sonnet	70.00	50.00	90.00	90.00	100.00	100.00	100.00	90.00	100.00	100.00	40.00	0.00	90.00	90.00
gemini-pro-1.5	40.00	40.00	10.00	80.00	100.00	100.00	0.00	40.00	90.00	100.00	100.00	100.00	90.00	100.00
gpt-4o-2024-08-06	50.00	30.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	10.00	30.00	90.00	90.00
llama-3.2-90b-vision-instruct	10.00	10.00	10.00	40.00	0.00	10.00	20.00	20.00	20.00	10.00	30.00	40.00	50.00	50.00
pixtral-12b	0.00	10.00	60.00	50.00	20.00	40.00	50.00	80.00	90.00	50.00	10.00	10.00	60.00	70.00
qwen-2-vl-72b-instruct	30.00	60.00	70.00	50.00	100.00	90.00	90.00	90.00	100.00	100.00	20.00	20.00	70.00	40.00

Table 3: Task 3 (Segmentation)

LVLM	10 n	odes	20 n	odes	30 n	odes
2,211	СоТ	0-shot	СоТ	0-shot	CoT	0-shot
claude-3.5-sonnet	100.00	100.00	100.00	100.00	40.00	30.00
gemini-pro-1.5	100.00	90.00	100.00	100.00	70.00	60.00
gpt-4o-2024-08-06	100.00	100.00	70.00	80.00	50.00	50.00
llama-3.2-90b-vision-instruct	50.00	50.00	30.00	30.00	30.00	30.00
pixtral-12b	50.00	60.00	60.00	80.00	30.00	30.00
qwen-2-vl-72b-instruct	60.00	50.00	60.00	50.00	10.00	20.00

Table 4: Task 4 (Pattern recognition)

									Pa	ttern type	:							
			ch	ain					clie	que					st	ar		
LVLM		2		3		4	:	2		3	4		:	2	;	3	4	4
17 11.11	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot
claude-3.5-sonnet	96.67	96.67	96.67	96.67	88.33	86.67	100.00	100.00	95.00	93.33	100.00	98.33	100.00	100.00	100.00	100.00	100.00	100.00
gemini-pro-1.5	98.33	98.33	93.33	93.33	90.00	88.33	100.00	100.00	96.67	96.67	96.67	96.67	100.00	95.00	100.00	100.00	90.00	85.00
gpt-4o-2024-08-06	96.67	95.00	95.00	95.00	83.33	78.33	100.00	100.00	96.67	100.00	91.67	86.67	100.00	100.00	100.00	95.00	75.00	85.00
llama-3.2-90b-vision-instruct	55.00	51.67	61.67	55.00	53.33	48.33	56.67	50.00	70.00	60.00	65.00	58.33	40.00	55.00	55.00	40.00	55.00	50.00
pixtral-12b	91.67	83.33	83.33	78.33	80.00	71.67	65.00	66.67	66.67	56.67	70.00	66.67	100.00	95.00	90.00	85.00	90.00	95.00
qwen-2-vl-72b-instruct	98.33	90.00	88.33	88.33	75.00	86.67	91.67	95.00	98.33	98.33	80.00	81.67	90.00	80.00	60.00	85.00	55.00	45.00

Table 5: Task 5 (Link Prediction)

LVLM	4 no	des	5 no	odes	6 no	odes
	CoT	0-shot	CoT	0-shot	CoT	0-shot
claude-3.5-sonnet	90.00	95.00	90.00	90.00	65.00	65.00
gemini-pro-1.5	100.00	95.00	90.00	75.00	66.67	50.00
gpt-4o-2024-08-06	95.00	95.00	85.00	70.00	60.00	60.00
llama-3.2-90b-vision-instruct	55.00	65.00	60.00	75.00	60.00	55.56
pixtral-12b	70.00	55.00	75.00	60.00	75.00	55.00
qwen-2-vl-72b-instruct	65.00	75.00	75.00	60.00	60.00	60.00

Table 6: Task 6 (Reasoning)

		Shortest	path (Ja	accard sin	milarity)	
LVLM	5 n	odes	6 no	odes	7 no	odes
	CoT	0-shot	CoT	0-shot	CoT	0-shot
claude-3.5-sonnet	67.83	63.83	66.83	67.00	68.50	72.00
gemini-pro-1.5	66.67	59.17	59.17	63.50	75.64	67.71
gpt-4o-2024-08-06	68.17	72.17	68.67	63.67	66.83	58.67
llama-3.2-90b-vision-instruct	58.50	31.50	54.00	43.67	44.50	50.83
pixtral-12b	65.17	53.83	59.00	58.67	61.00	59.00
qwen-2-vl-72b-instruct	73.50	64.67	52.33	50.17	74.00	57.50

Table 7: Task 7 (Matching)

			m	atch					no n	natch		
LVLM	4 (n	odes)	5 (no	odes)	6 (n	odes)	4 (no	odes)	5 (no	odes)	6 (no	odes)
1,11,1	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot	CoT	0-shot
claude-3.5-sonnet	40.00	50.00	40.00	50.00	90.00	90.00	100.00	100.00	80.00	80.00	80.00	80.00
gemini-pro-1.5	50.00	30.00	50.00	50.00	70.00	70.00	80.00	90.00	60.00	70.00	60.00	60.00
gpt-4o-2024-08-06	60.00	80.00	60.00	70.00	80.00	100.00	90.00	80.00	50.00	50.00	70.00	60.00
llama-3.2-90b-vision-instruct	30.00	10.00	30.00	20.00	30.00	10.00	90.00	40.00	100.00	90.00	100.00	80.00
pixtral-12b	0.00	0.00	0.00	0.00	0.00	0.00	100.00	100.00	100.00	100.00	100.00	100.00
qwen-2-vl-72b-instruct	0.00	0.00	20.00	10.00	20.00	0.00	80.00	90.00	100.00	90.00	100.00	100.00