

view_frames Result

Recorded at time: 1565453521.084

base_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1565453521.084 sec old)
Buffer length: 0.000 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1565453521.084 sec old)
Buffer length: 0.000 sec

caster_back_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1565453521.084 sec old)
Buffer length: 0.000 sec

imu_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1565453521.084 sec old)
Buffer length: 0.000 sec

base_scan