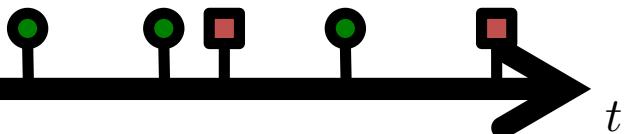


Learning with Temporal Point Processes



Manuel Gomez Rodriguez
MPI for Software Systems

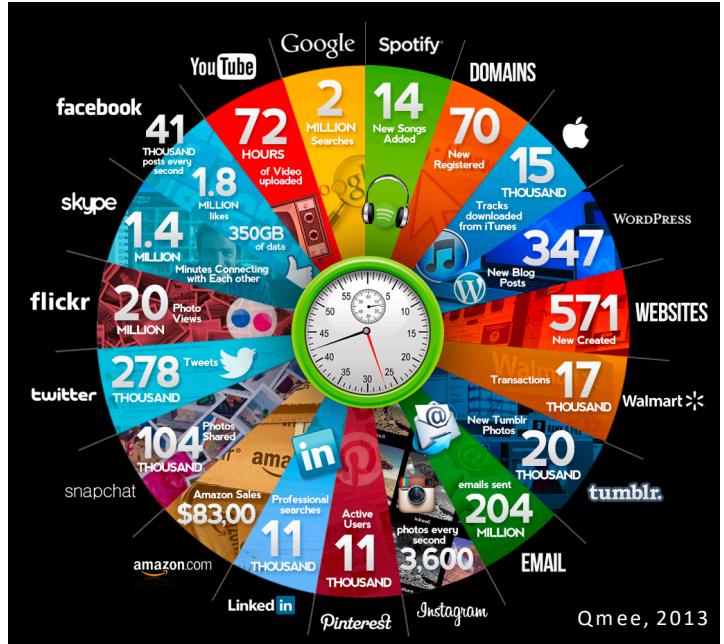


Isabel Valera
MPI for Intelligent Systems

Slides/references: <http://learning.mpi-sws.org/tpp-icml18>

ICML TUTORIAL, JULY 2018

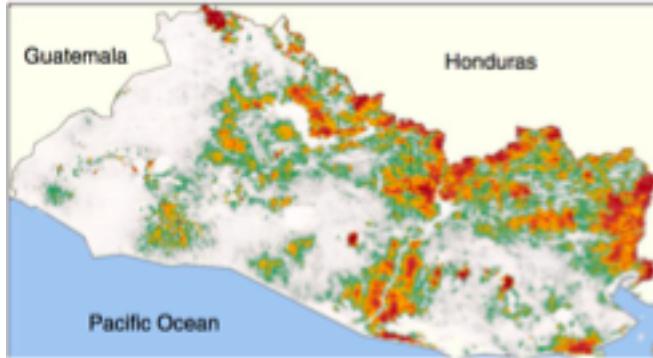
Many discrete events in continuous time



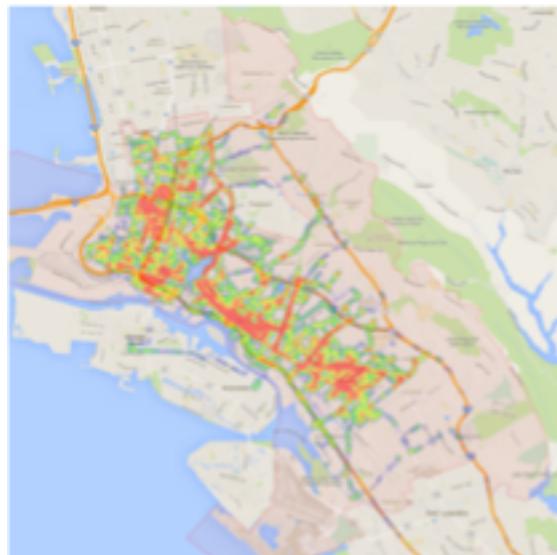
Online actions



Financial trading



Disease dynamics



Mobility dynamics

Variety of processes behind these events

Events are (noisy) observations of a variety of complex dynamic processes...



Stock
trading



Flu
spreading



Article creation
in Wikipedia



News spread in
Twitter



Reviews and
sales in Amazon



Ride-sharing
requests



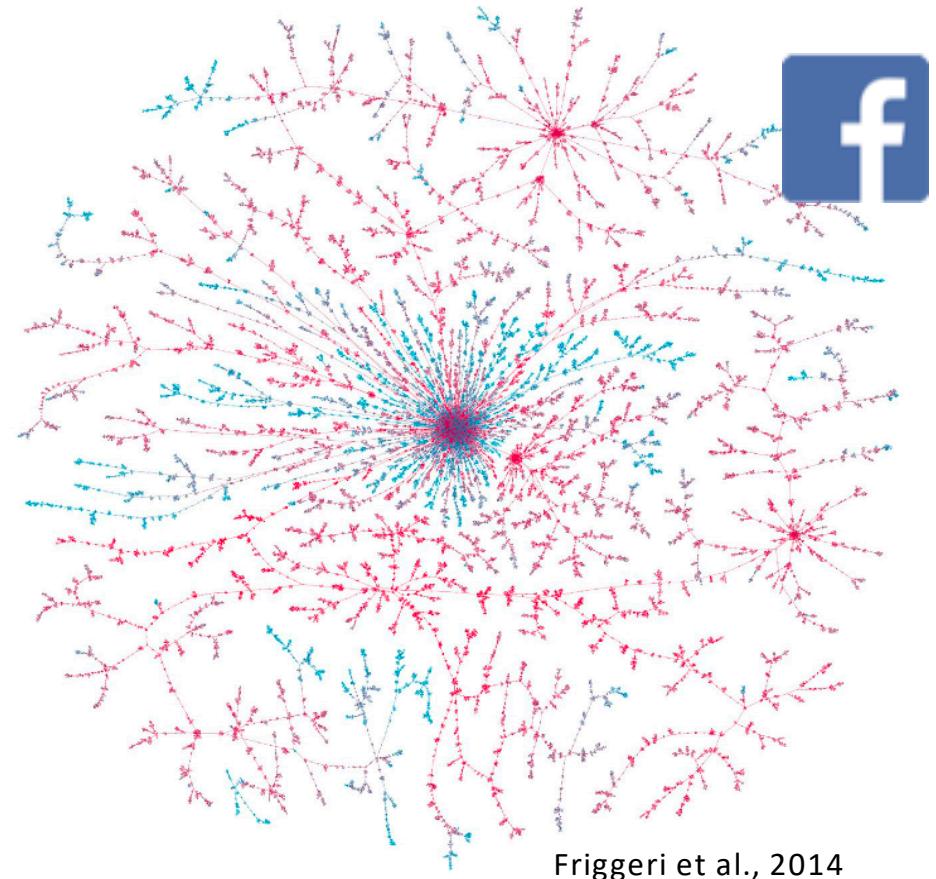
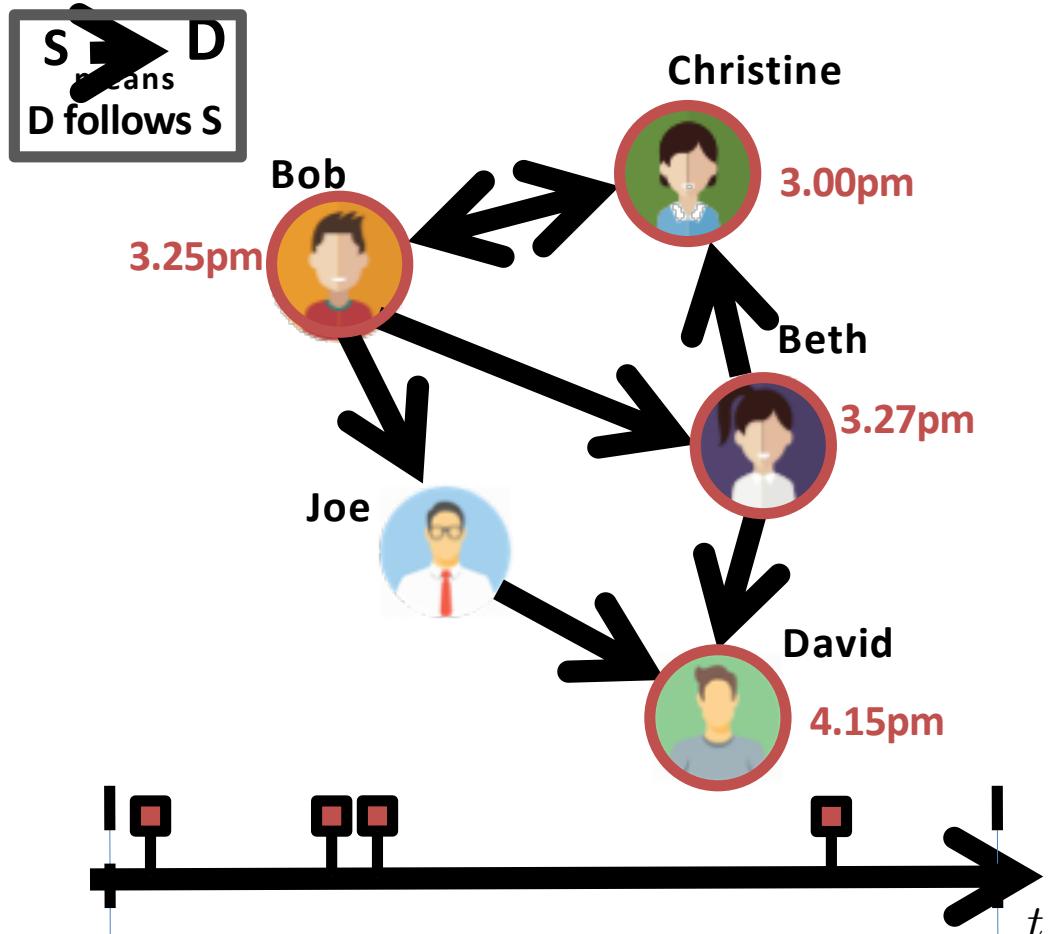
A user's reputation
in Quora

FAST

SLOW

...in a wide range of temporal scales.

Example I: Information propagation



They can have an impact
in the off-line world

the guardian

Click and elect: how fake news helped
Donald Trump win a real election

Example II: Knowledge creation



Barack Obama

From Wikipedia, the free encyclopedia

"Barack" and "Obama" redirect here. For his father, see Barack Obama Sr. For other uses of "Barack", see Barack (disambiguation).

(disambiguation).

Barack Hussein Obama II (

current President of the Unit

continental United States. Bo

was president of the Harvard

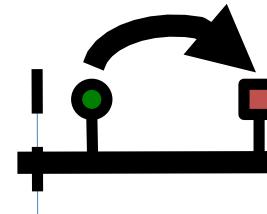
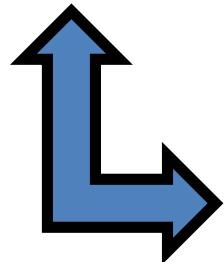
civil rights attorney and taught

representing the 13th District

States House of Representat

Barack Obama: Revision history

03:41, 28 November 2016 Ranze (talk | contribs) ... (301,105 bytes) (+18) ... (E
03:32, 28 November 2016 Xin Deui (talk | contribs) ... (301,087 bytes) (-68) ... (E
00:57, 28 November 2016 SporkBot (talk | contribs) m ... (301,155 bytes) (-37)
07:03, 27 November 2016 Saiph121 (talk | contribs) ... (301,192 bytes) (+25) ...



03:21, 20 September 2016

is a Kenyan politician



possible vandalism by MLM2016

is an American politician

- Addition
- Refutation

t



Moving to Australia

Working in Australia

Study abroad in Australia

+4



What are the pros and cons of living in Australia?

Answer

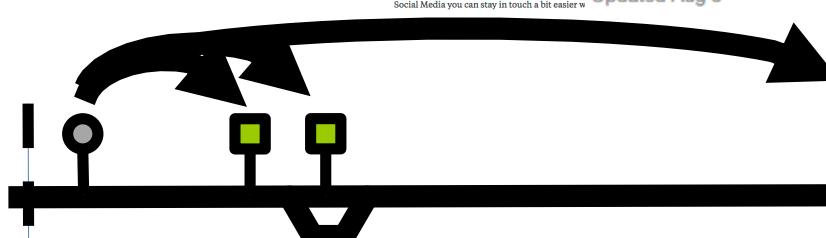
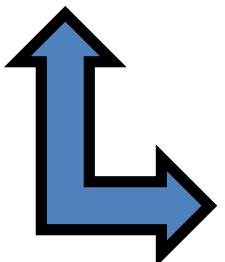
Request

Follow 109

Comment

Share 9

Downvote



I have studied, worked and lived in Australia as an Interna

employee, business owner and a citizen.
I have experienced this country in all the ways possible, you
However, I firmly believe that there are definitely more pros
Australia but still I have mentioned below a few
benefits.

Hope it helps! :)

Possible Challenges

- Language problem for those who don't speak English
- Not having your family and friends around could be challenging and thanks to technology society is more and more connected and thanks to Social Media you can stay in touch a bit easier with them.

Upvote | 150



Av M Sharma, Lived in Australia as Migrant, Student, Worker,

Business Owner & Family Man

Updated Aug 3

- Question
- Answer

t

Upvote

t

Example III: Human learning

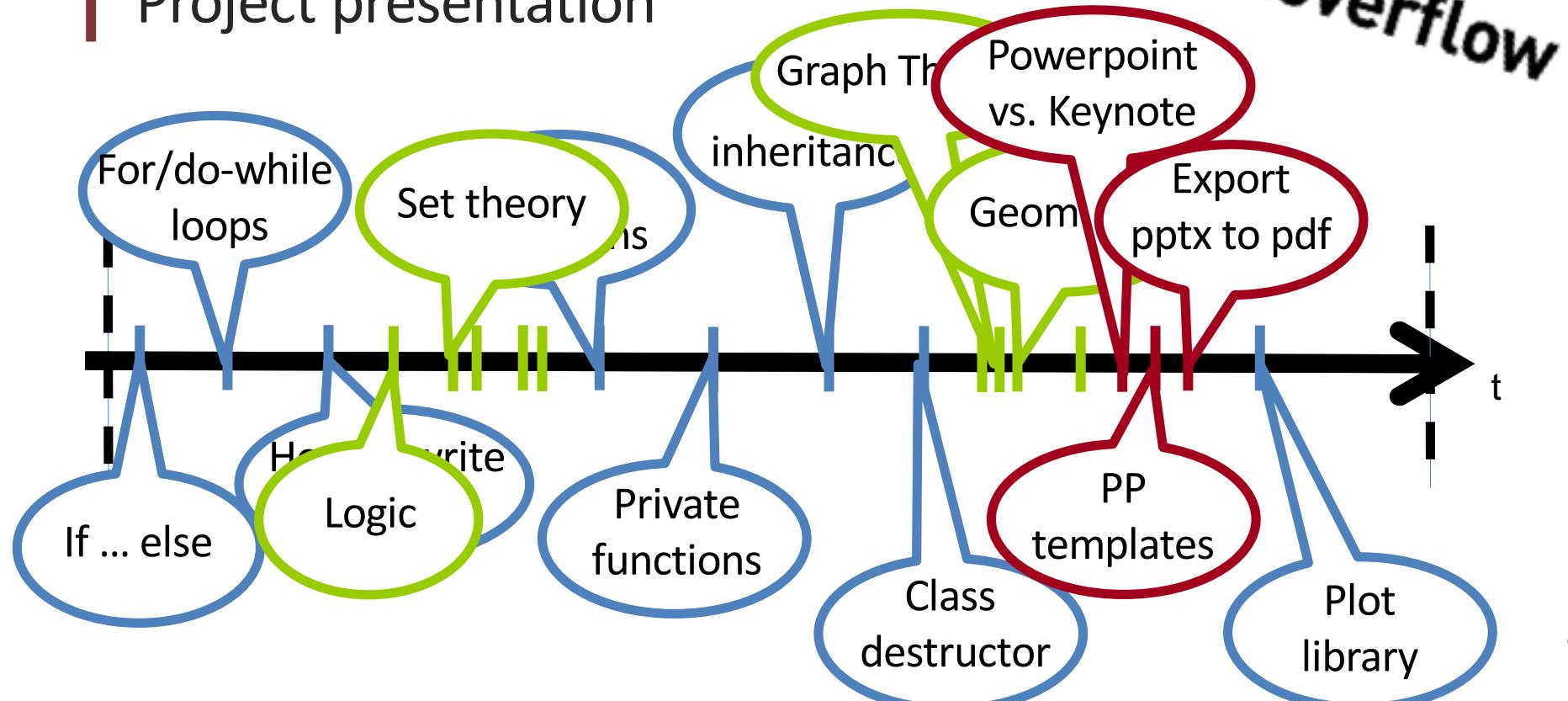


1st year computer science student

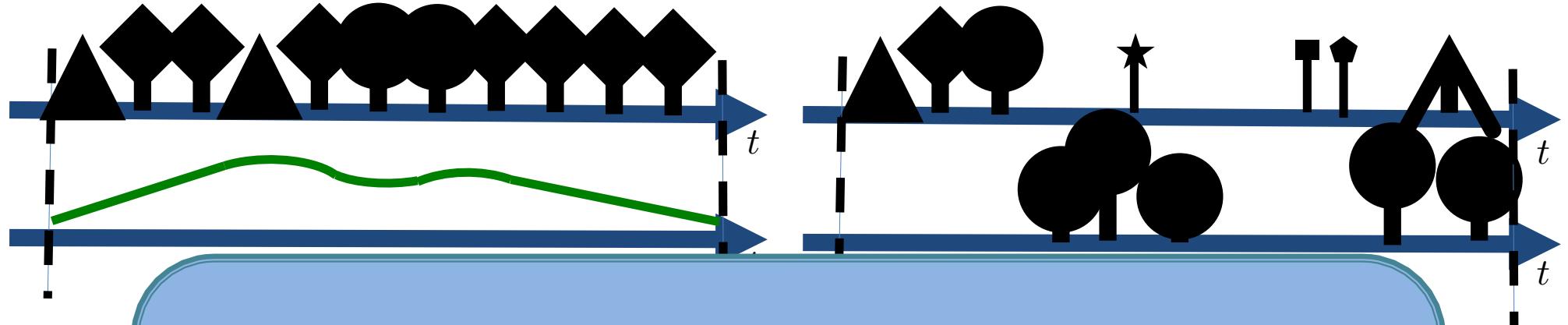
Introduction to programming

Discrete math

Project presentation



Aren't these event traces just time series?

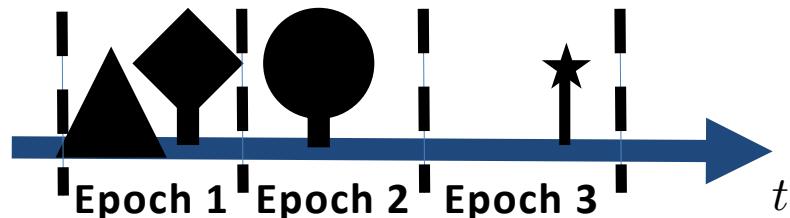


Dis-

The framework of
temporal point processes
provides a *native representation*

W-

what if no event in one epoch?



what if no event in one epoch?

What about time-related queries?

Outline of the Seminar

TEMPORAL POINT PROCESSES (TPPs): INTRO

1. Intensity function
2. Basic building blocks
3. Superposition
4. Marks and SDEs with jumps

Next

MODELS & INFERENCE

1. Modeling event sequences
2. Clustering event sequences
3. Capturing complex dynamics
4. Causal reasoning on event sequences

RL & CONTROL

1. Marked TPPs: a new setting
2. Stochastic optimal control
3. Reinforcement learning

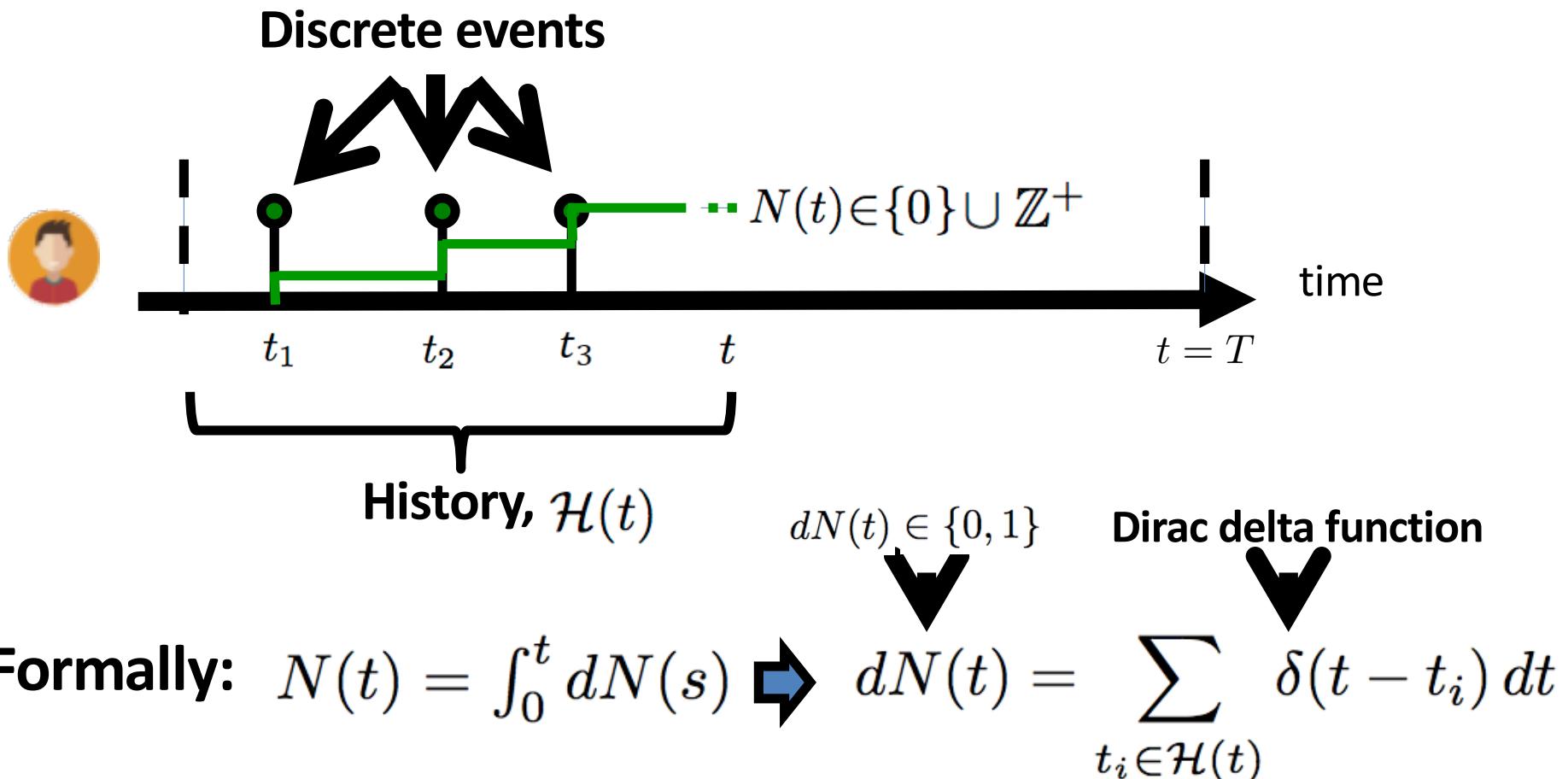
Temporal Point Processes (TPPs): Introduction

- 1. Intensity function**
2. Basic building blocks
3. Superposition
4. Marks and SDEs with jumps

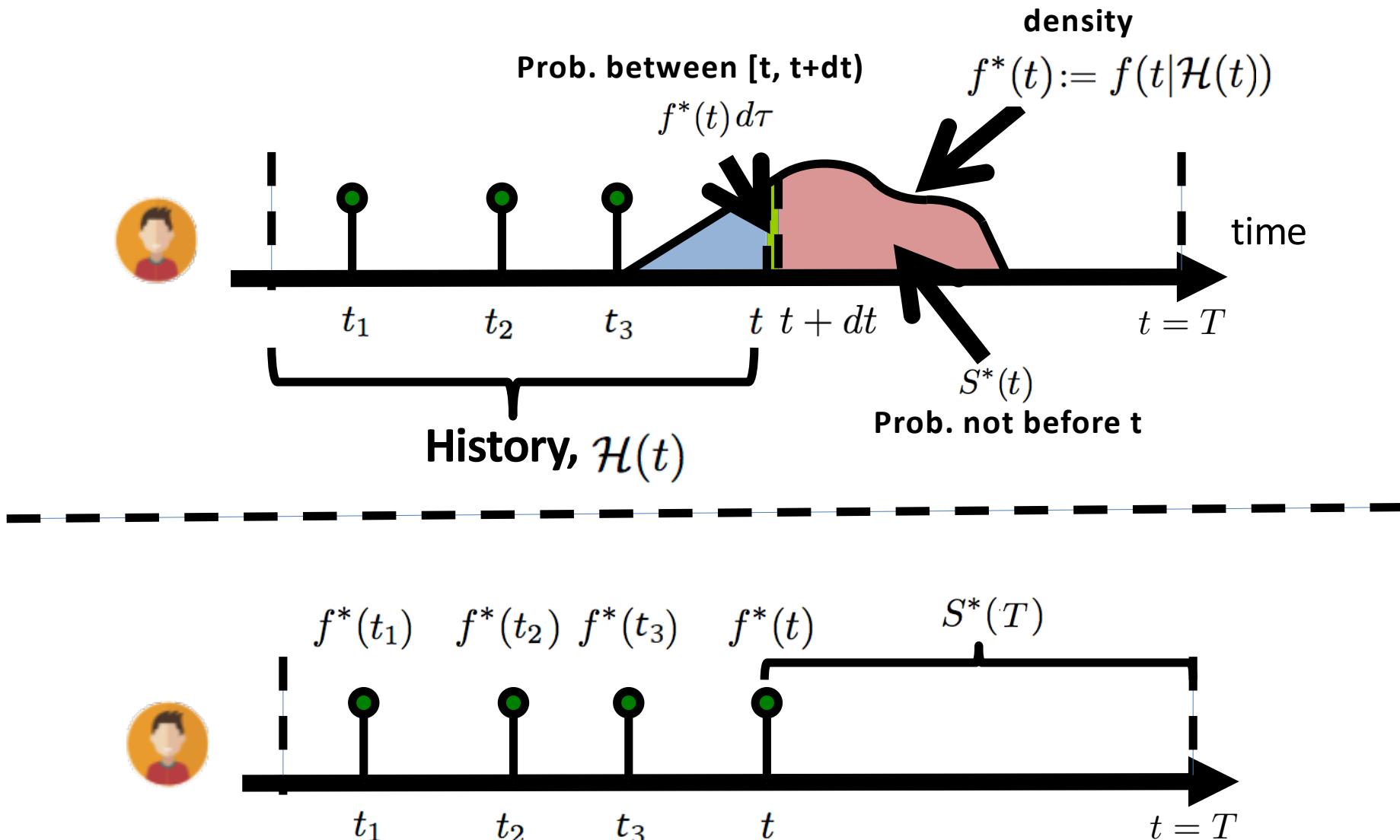
Temporal point processes

Temporal point process:

A random process whose realization consists of discrete events localized in time

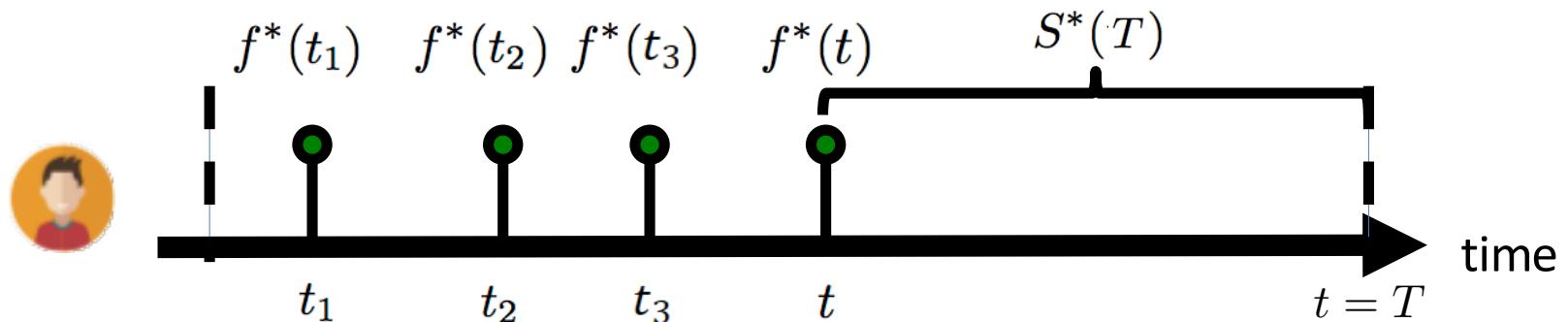


Model time as a random variable



Likelihood of a timeline: $f^*(t_1) \ f^*(t_2) \ f^*(t_3) \ f^*(t) \ S^*(T)$

Problems of density parametrization (I)

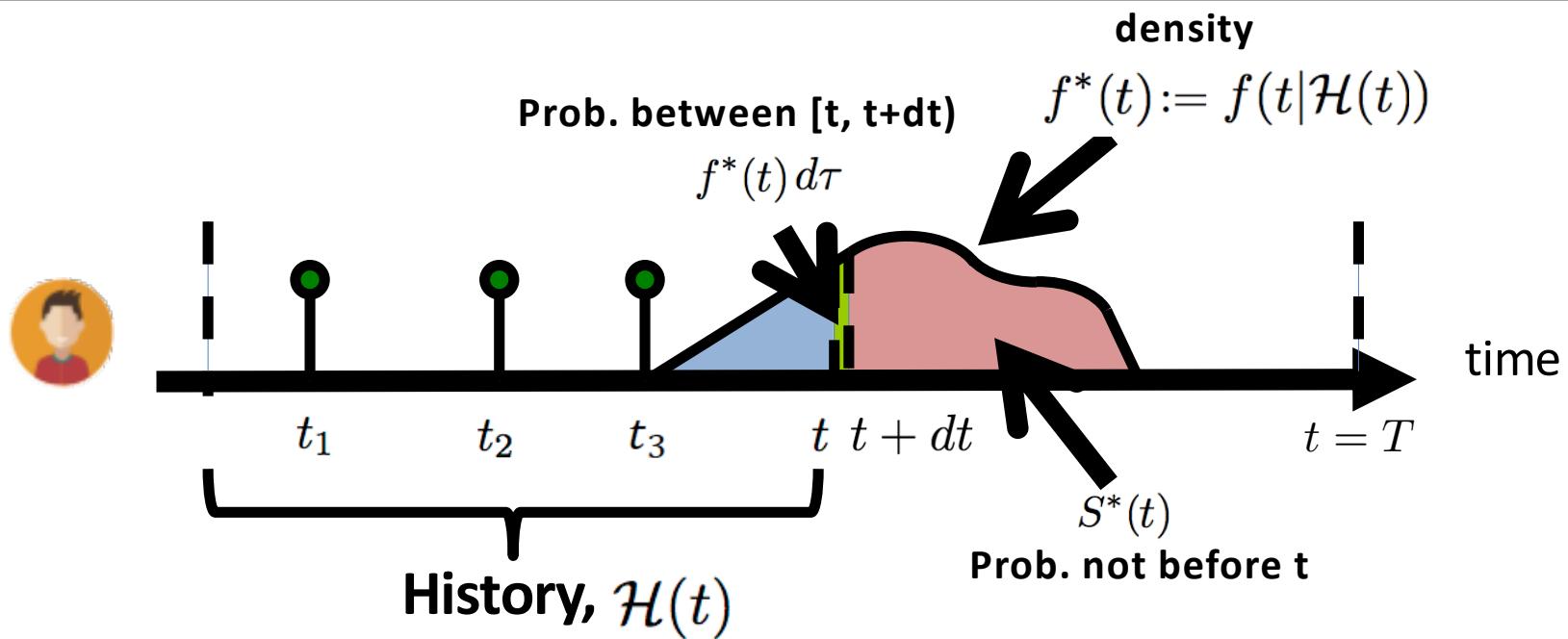


$$\frac{\exp\langle w, \psi^*(t_1) \rangle}{Z} \quad \frac{\exp\langle w, \psi^*(t_2) \rangle}{Z} \quad \frac{\exp\langle w, \psi^*(t_3) \rangle}{Z} \quad \frac{\exp\langle w, \psi^*(t) \rangle}{Z} \quad 1 - \int_t^T \frac{\exp\langle w, \psi^*(\tau) \rangle}{Z} d\tau$$

It is **difficult for model design and interpretability**:

1. Densities need to integrate to 1 (i.e., partition function)
2. Difficult to combine timelines

Intensity function



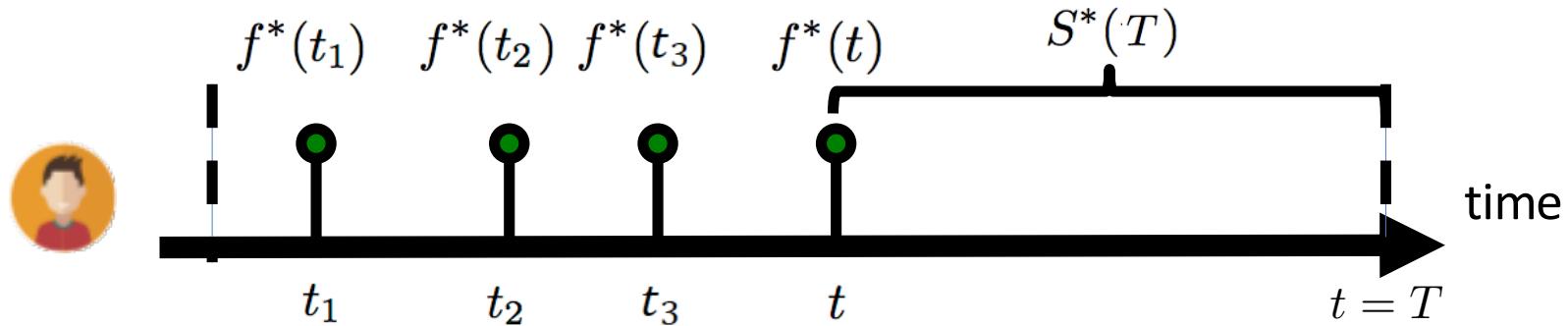
Intensity:

Probability between $[t, t+dt]$ but not before t

$$\lambda^*(t)dt = \frac{f^*(t)dt}{S^*(t)} \geq 0 \quad \rightarrow \quad \lambda^*(t)dt = \mathbb{E}[dN(t)|\mathcal{H}(t)]$$

Observation: $\lambda^*(t)$ It is a rate = # of events / unit of time

Advantages of intensity parametrization (I)

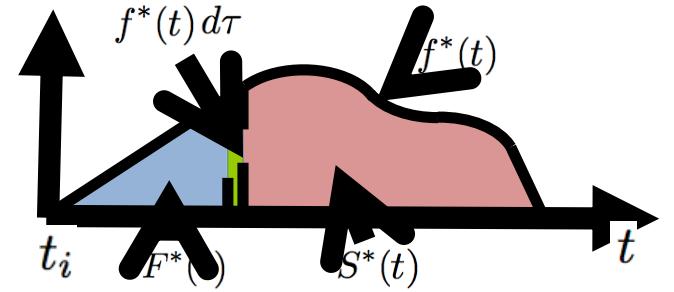
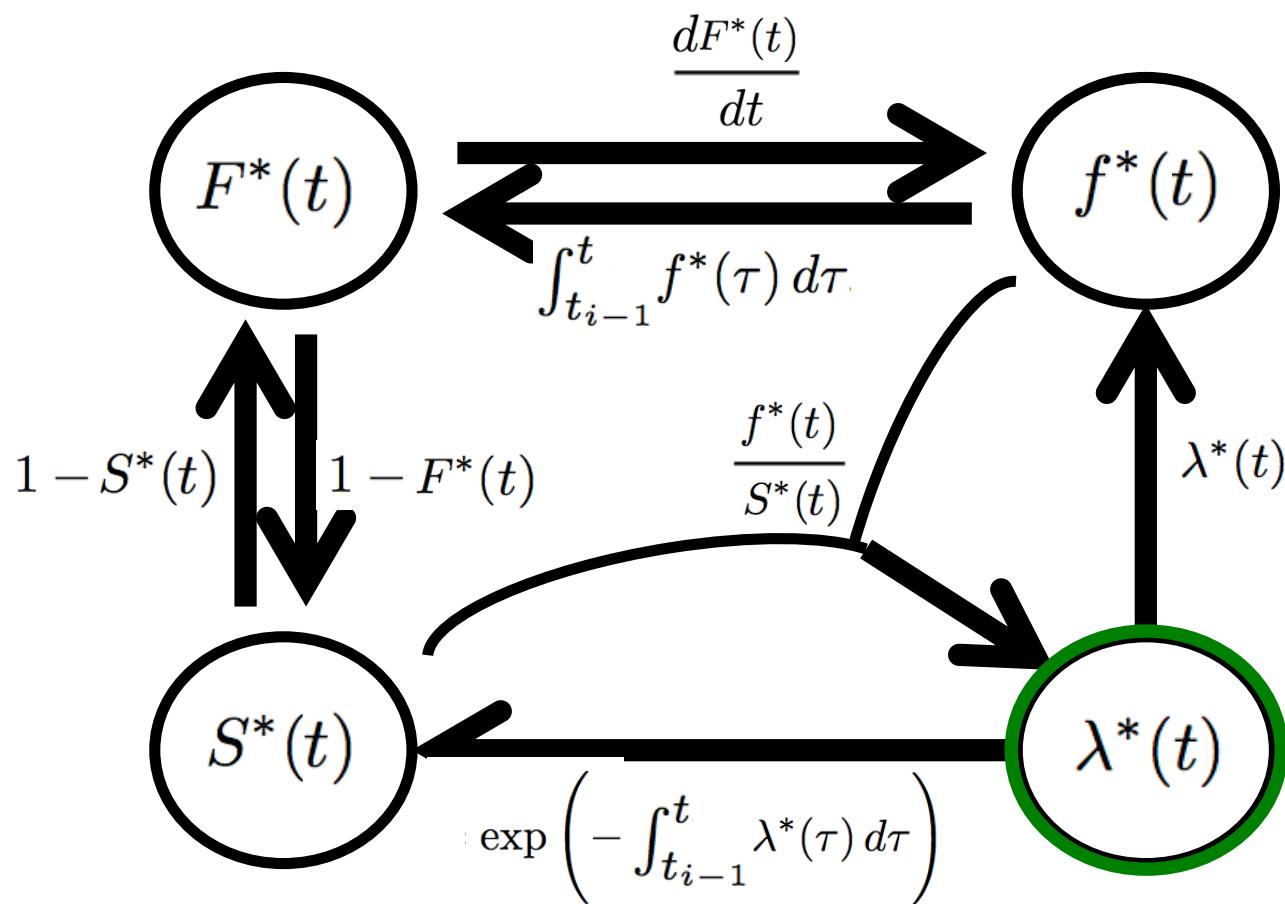


$$\lambda^*(t_1) \lambda^*(t_2) \lambda^*(t_3) \lambda^*(t) \exp\left(-\int_0^T \lambda^*(\tau) d\tau\right)$$
$$\langle w, \phi^*(t_1) \rangle \quad \langle w, \phi^*(t_2) \rangle \quad \langle w, \phi^*(t_3) \rangle \quad \langle w, \phi^*(t) \rangle \quad \exp\left(-\int_0^T \langle w, \phi^*(\tau) \rangle d\tau\right)$$

Suitable for model design and interpretable:

1. Intensities only need to be nonnegative
2. Easy to combine timelines

Relation between f^* , F^* , S^* , λ^*



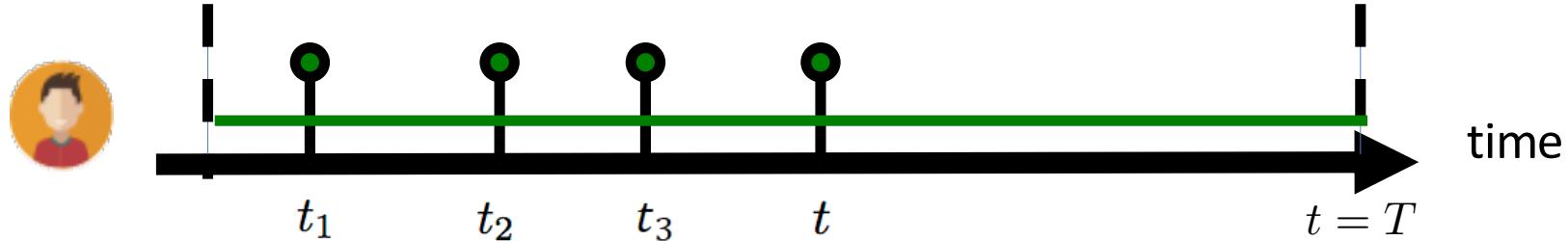
$$\lambda^*(t) \exp \left(- \int_{t_{i-1}}^t \lambda^*(\tau) d\tau \right)$$

Central quantity
we will use!

Representation: Temporal Point Processes

- 1. Intensity function**
- 2. Basic building blocks**
- 3. Superposition**
- 4. Marks and SDEs with jumps**

Poisson process



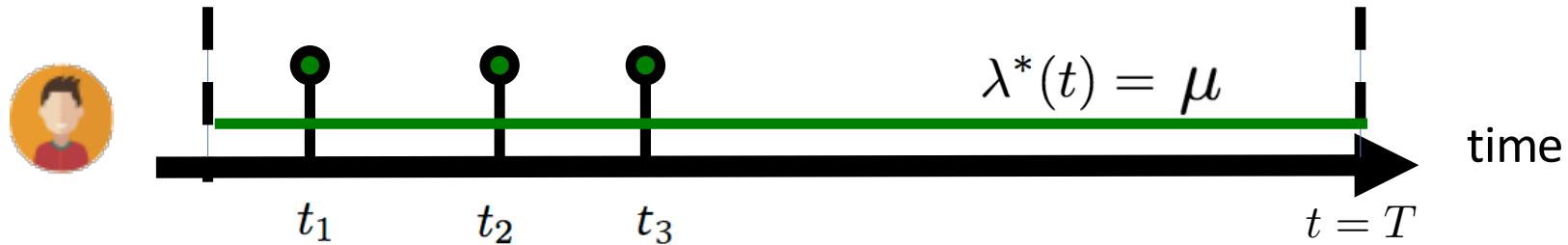
Intensity of a Poisson process

$$\lambda^*(t) = \mu$$

Observations:

- 1. Intensity independent of history**
- 2. Uniformly random occurrence**
- 3. Time interval follows exponential distribution**

Fitting & sampling from a Poisson



Fitting by maximum likelihood:

$$\mu^* = \underset{\mu}{\operatorname{argmax}} \ 3 \log \mu - \mu T = \frac{3}{T}$$

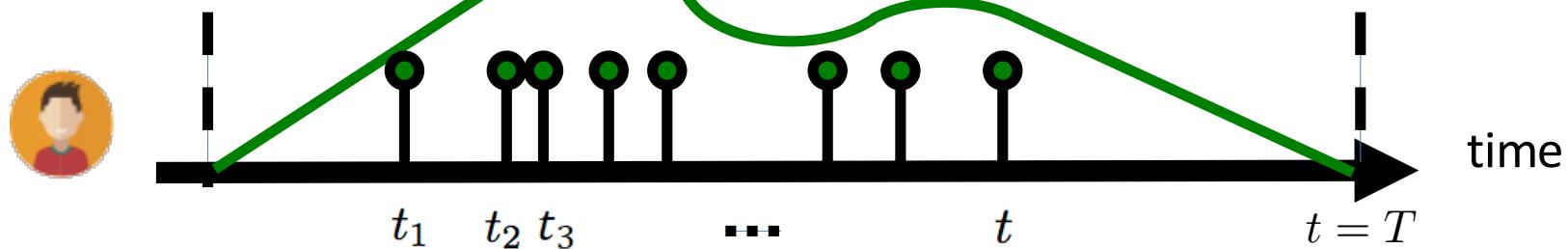
Sampling using inversion sampling:

$$t \sim \mu \exp(-\mu(t - t_3)) \quad \xrightarrow{\text{ }} \quad t = -\frac{1}{\mu} \log(1 - u) + t_3$$

$f_t^*(t)$ $F_t^{-1}(u)$

$Uniform(0, 1)$

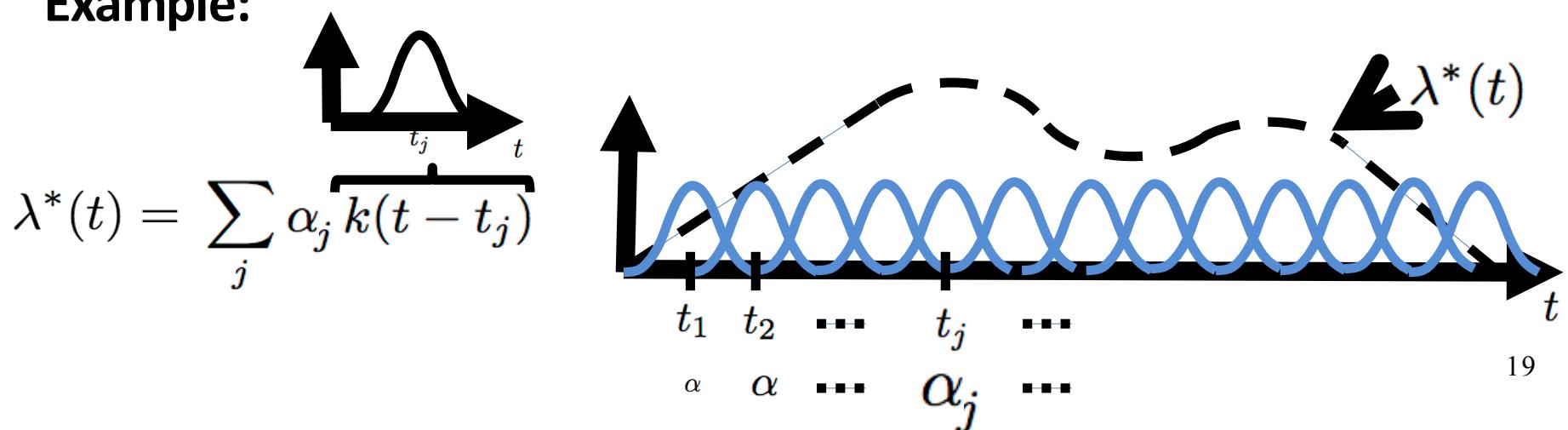
Inhomogeneous Poisson process



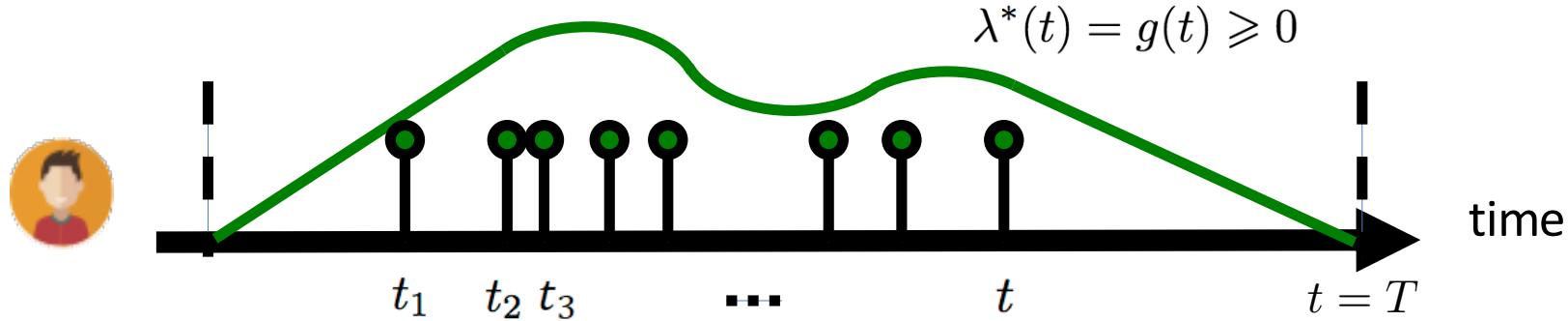
Intensity of an inhomogeneous Poisson process

$$\lambda^*(t) = g(t) \geq 0 \quad (\text{Independent of history})$$

Example:



Fitting & sampling from inhomogeneous Poisson

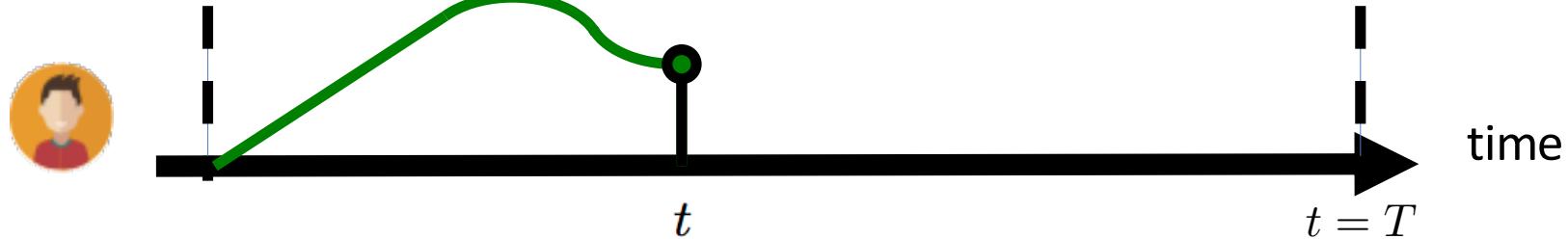


Fitting by maximum likelihood: $\underset{g(t)}{\text{maximize}} \quad \sum_{i=1}^n \log g(t_i) - \int_0^T g(\tau) d\tau$

Sampling using thinning (reject. sampling) + inverse sampling:

1. Sample t from Poisson process with intensity μ using inverse sampling
 2. Generate $u_2 \sim \text{Uniform}(0, 1)$
 3. Keep the sample if $u_2 \leq g(t) / \mu$
-]} Keep sample with prob. $g(t) / \mu$

Terminating (or survival) process



Intensity of a terminating (or survival) process

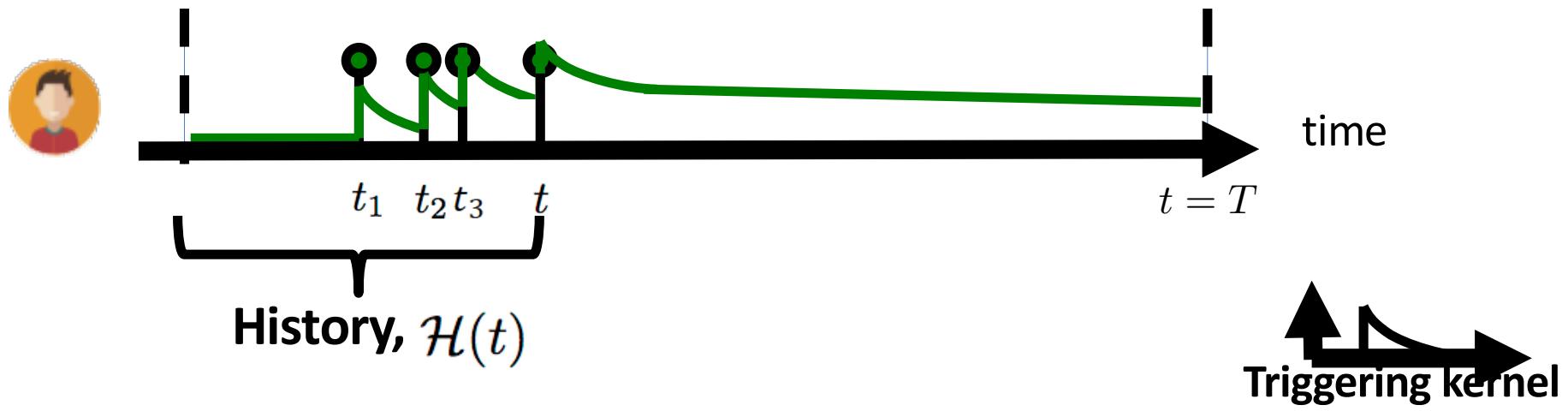
$$\lambda^*(t) = g^*(t)(1 - N(t)) \geq 0$$

Observations:

1. Limited number of occurrences

Try sampling
and fitting!

Self-exciting (or Hawkes) process



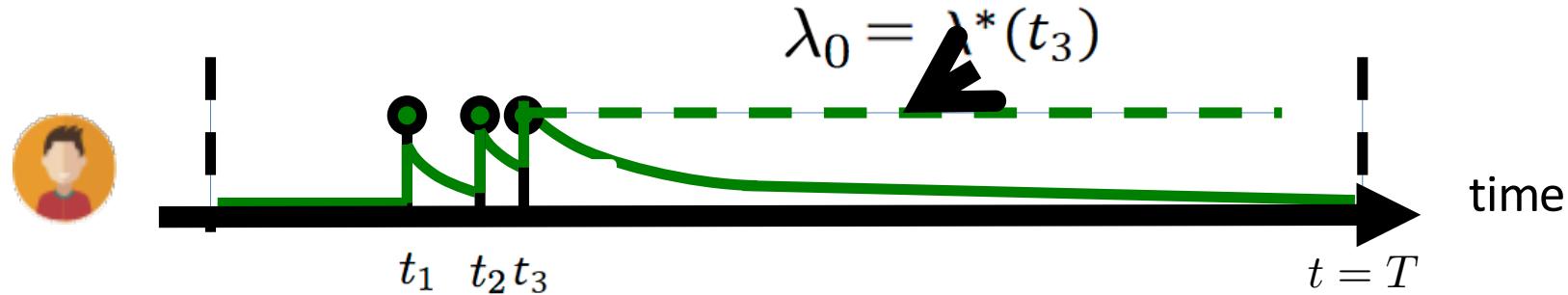
**Intensity of self-exciting
(or Hawkes) process:**

$$\begin{aligned}\lambda^*(t) &= \mu + \alpha \sum_{t_i \in \mathcal{H}(t)} \kappa_\omega(t - t_i) \\ &= \mu + \alpha \kappa_\omega(t) \star dN(t)\end{aligned}$$

Observations:

1. Clustered (or bursty) occurrence of events
2. Intensity is stochastic and history dependent

Fitting a Hawkes process from a recorded timeline



Fitting by maximum likelihood:

$$\text{maximize}_{\mu, \alpha} \sum_{i=1}^n \log \lambda^*(t_i) - \int_0^T \lambda^*(\tau) d\tau \quad \left. \right\} \begin{array}{l} \text{The max. likelihood} \\ \text{is jointly convex} \\ \text{in } \mu \text{ and } \alpha \end{array}$$

Sampling using thinning (reject. sampling) + inverse sampling:

Key idea: the maximum of the intensity λ_0 changes over time

Summary

Building blocks to represent different dynamic processes:

Poisson processes:

$$\lambda^*(t) = \lambda$$



Inho

We know **how to fit them**
and **how to sample from them**

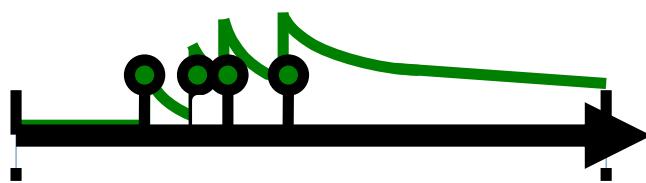
Term

$$\lambda^*(t) = g^-(t)(1 - N(t))$$



Self-exciting point processes:

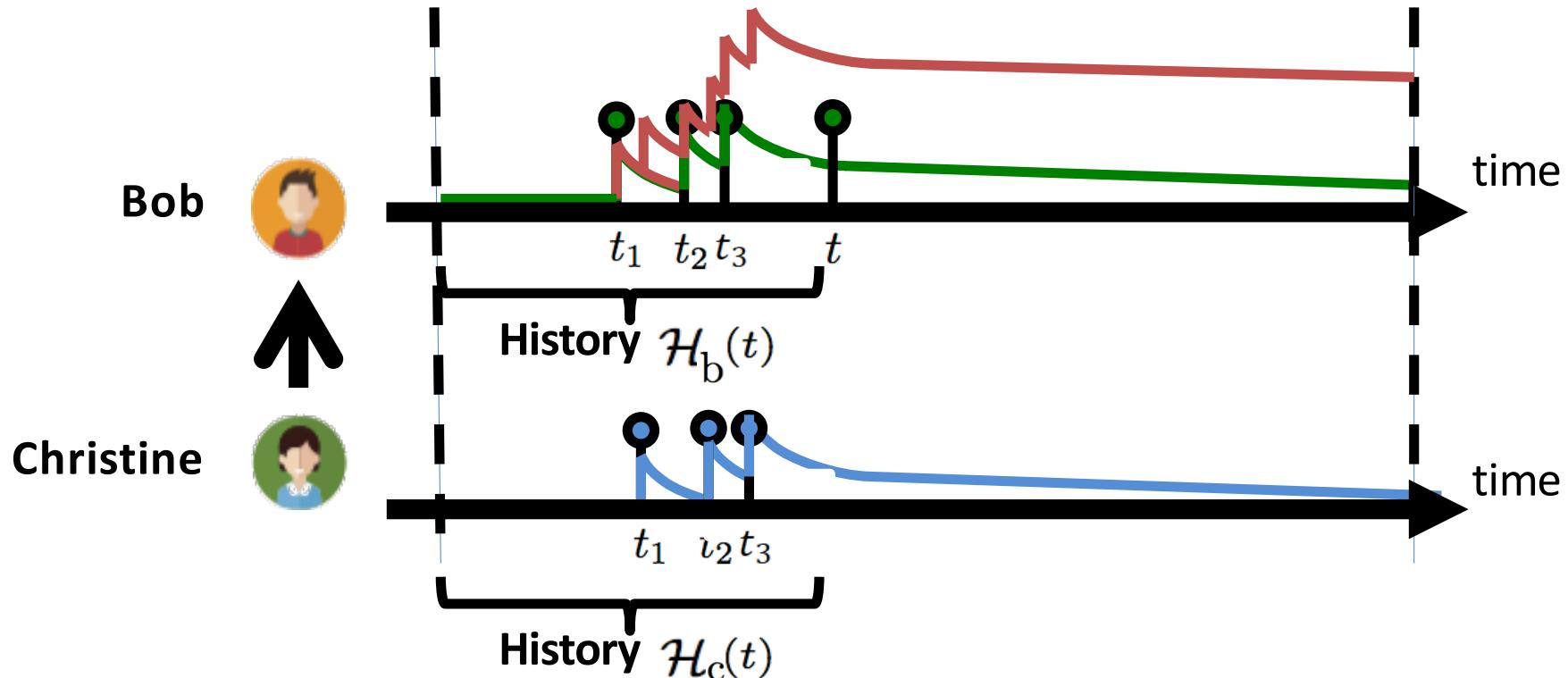
$$\lambda^*(t) = \mu + \alpha \sum_{t_i \in \mathcal{H}(t)} \kappa_\omega(t - t_i)$$



Representation: Temporal Point Processes

- 1. Intensity function**
- 2. Basic building blocks**
- 3. Superposition**
- 4. Marks and SDEs with jumps**

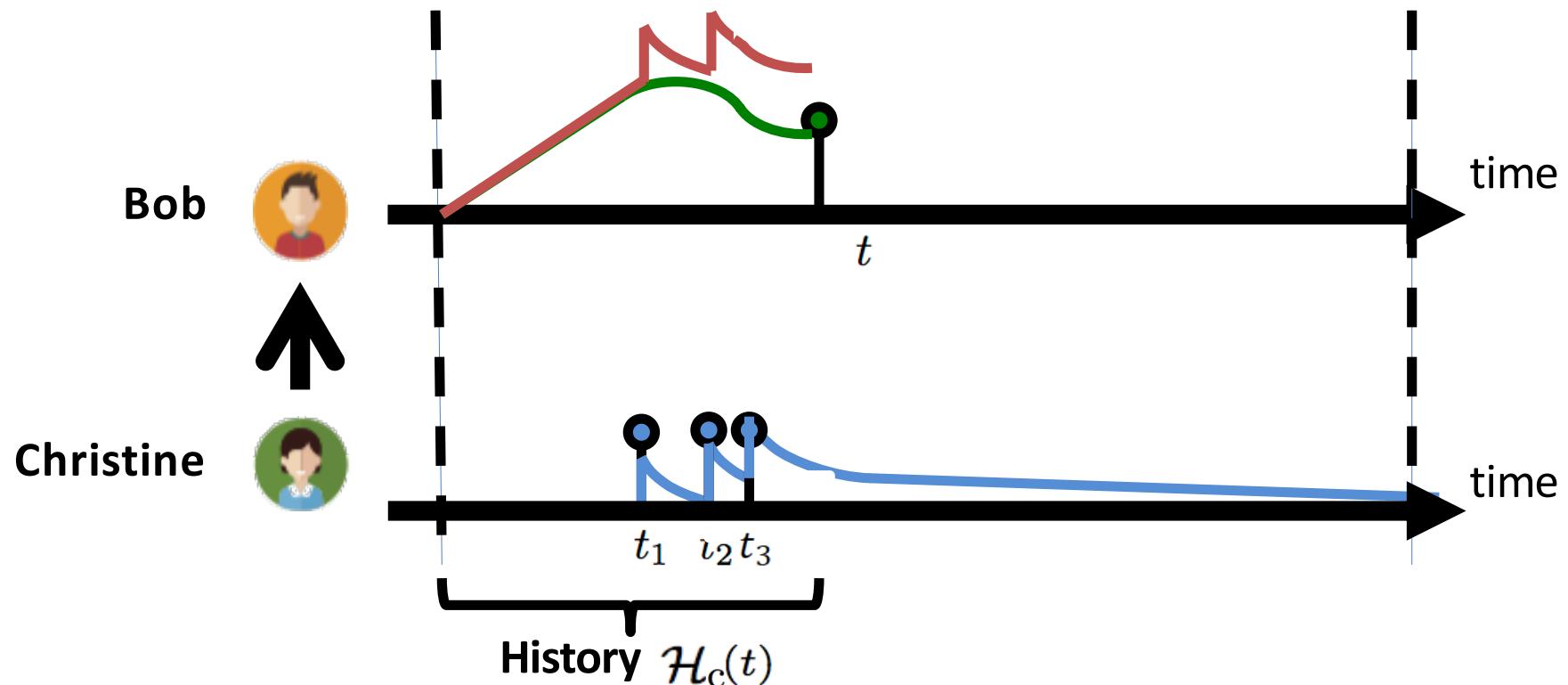
Mutually exciting process



Clustered occurrence affected by neighbors

$$\begin{aligned}\lambda^*(t) = & \mu + \alpha \sum_{t_i \in \mathcal{H}_b(t)} \kappa_\omega(t - t_i) \\ & + \beta \sum_{t_i \in \mathcal{H}_c(t)} \kappa_\omega(t - t_i)\end{aligned}$$

Mutually exciting terminating process



Clustered occurrence affected by neighbors

$$\lambda^*(t) = (1 - N(t)) \left(g(t) + \beta \sum_{t_i \in \mathcal{H}_c(t)} \kappa_\omega(t - t_i) \right)$$

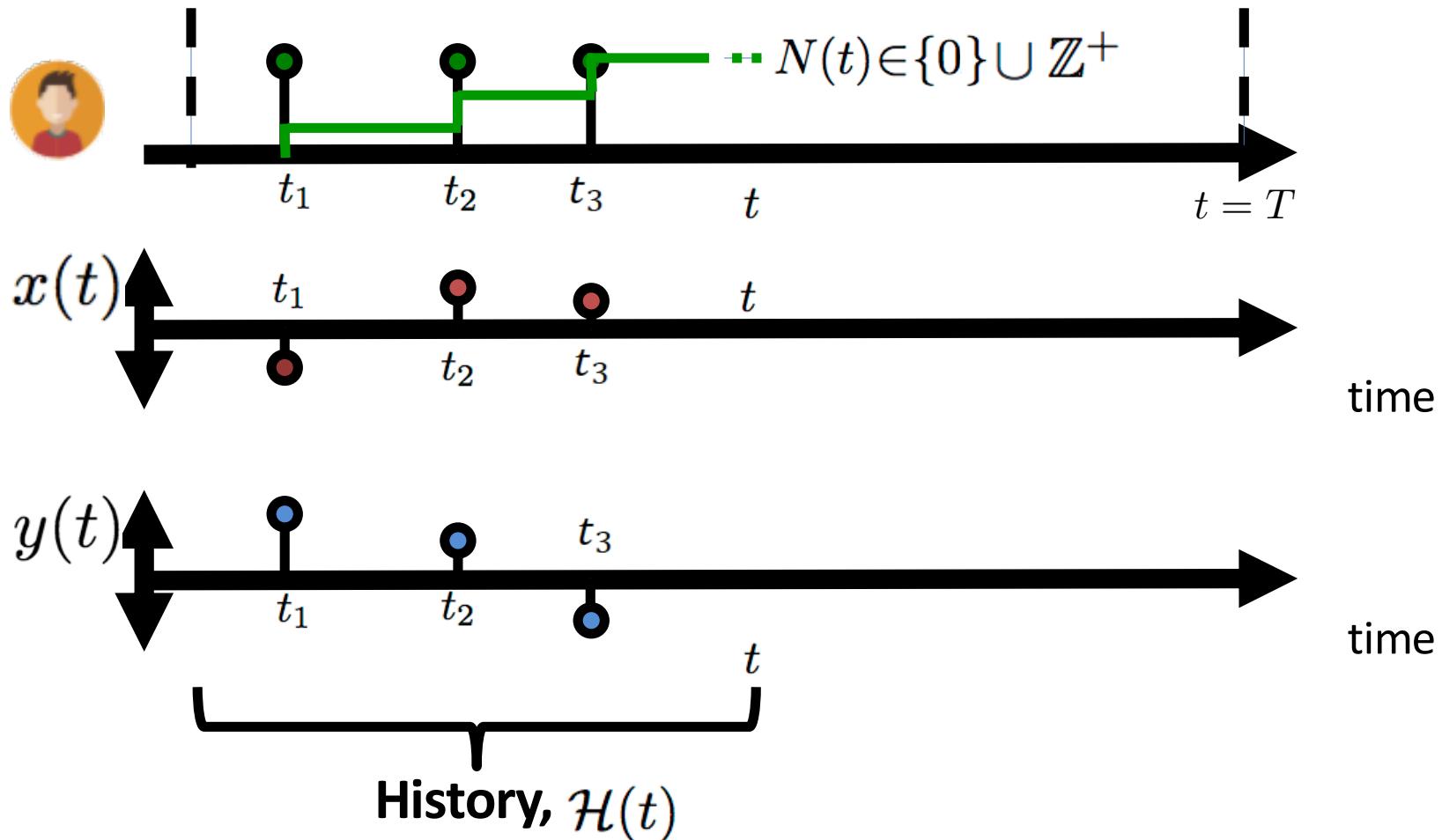
Representation: Temporal Point Processes

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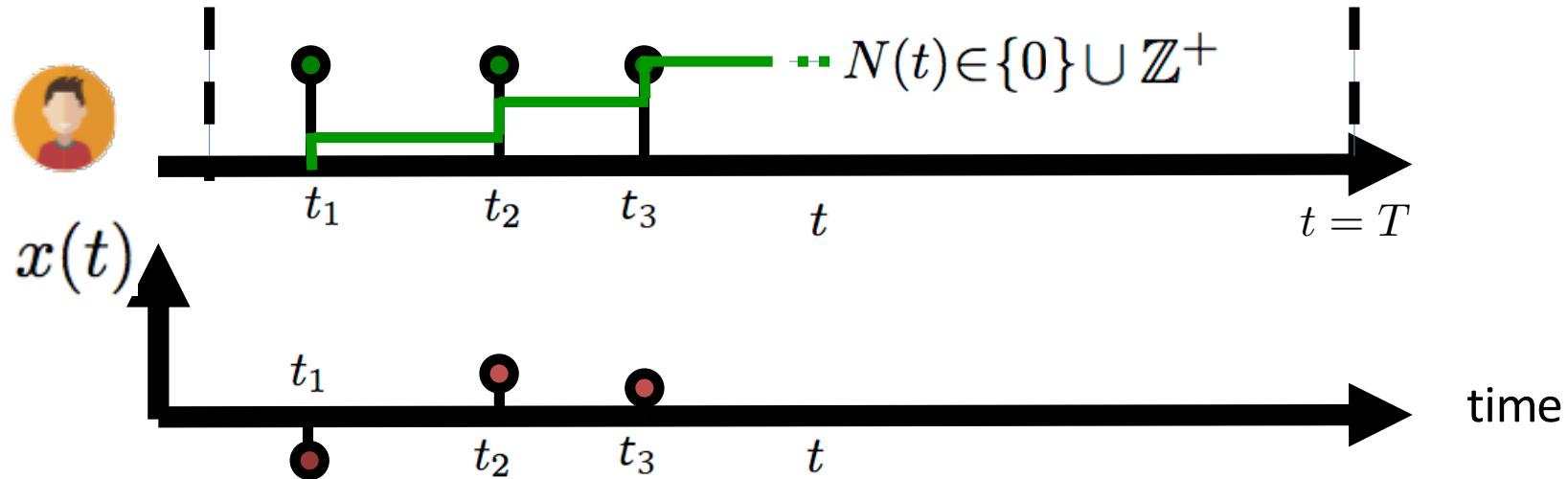
Marked temporal point processes

Marked temporal point process:

A random process whose realization consists of discrete *marked events localized in time*



Independent identically distributed marks



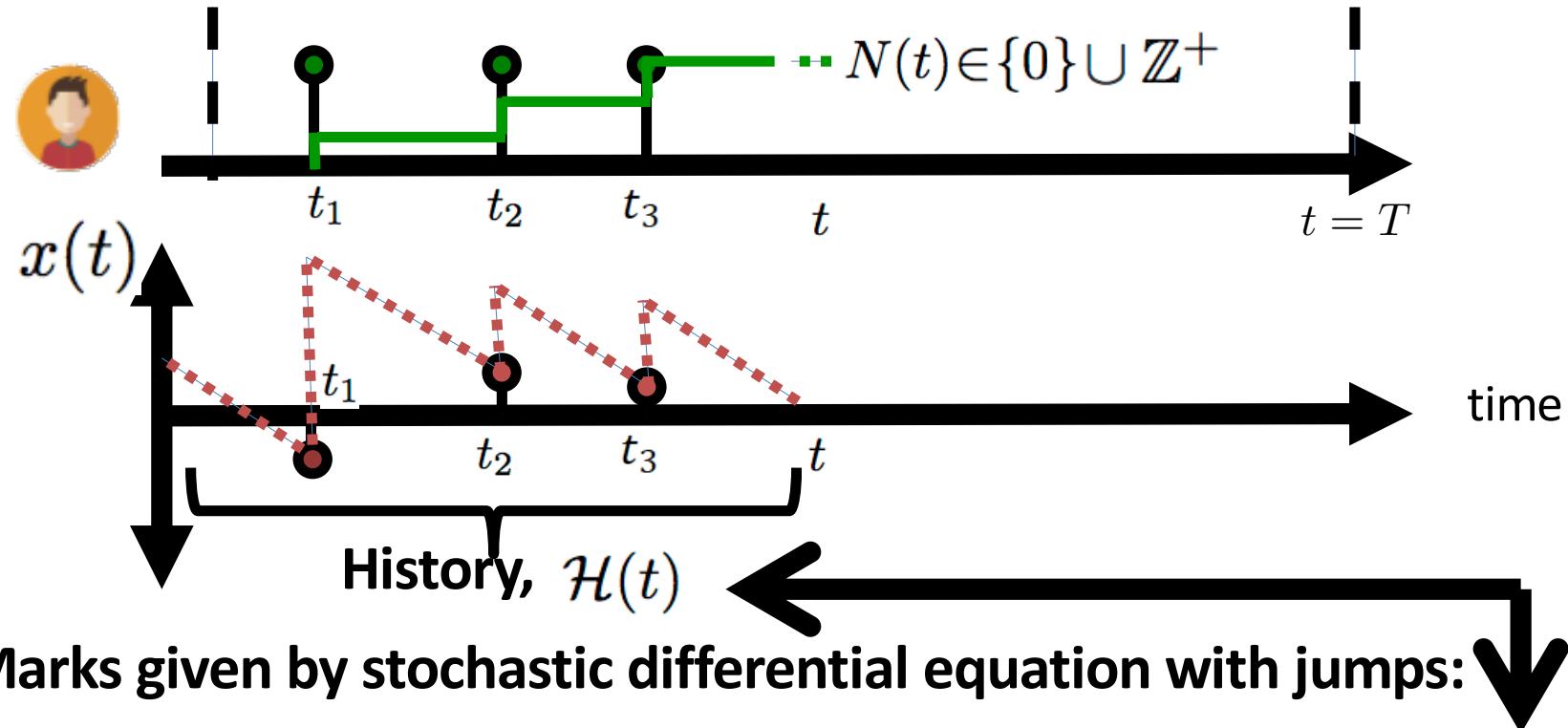
Distribution for the marks:

$$x^*(t_i) \sim p(x)$$

Observations:

1. Marks independent of the temporal dynamics
2. Independent identically distributed (I.I.D.)

Dependent marks: SDEs with jumps

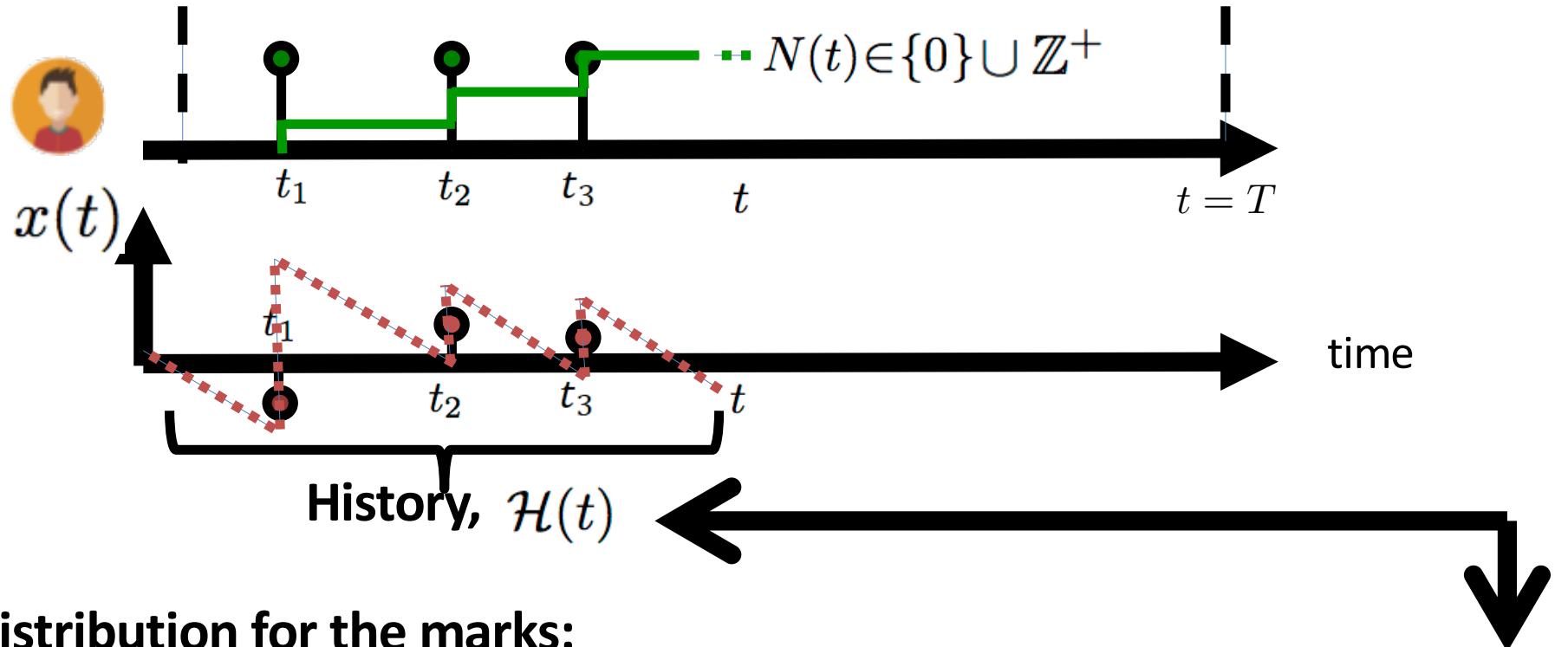


$$x(t + dt) - x(t) = dx(t) = \underbrace{f(x(t), t)dt}_{\text{Drift}} + \underbrace{h(x(t), t)dN(t)}_{\text{Event influence}}$$

Observations:

1. Marks dependent of the temporal dynamics
2. Defined for all values of t

Dependent marks: distribution + SDE with jumps

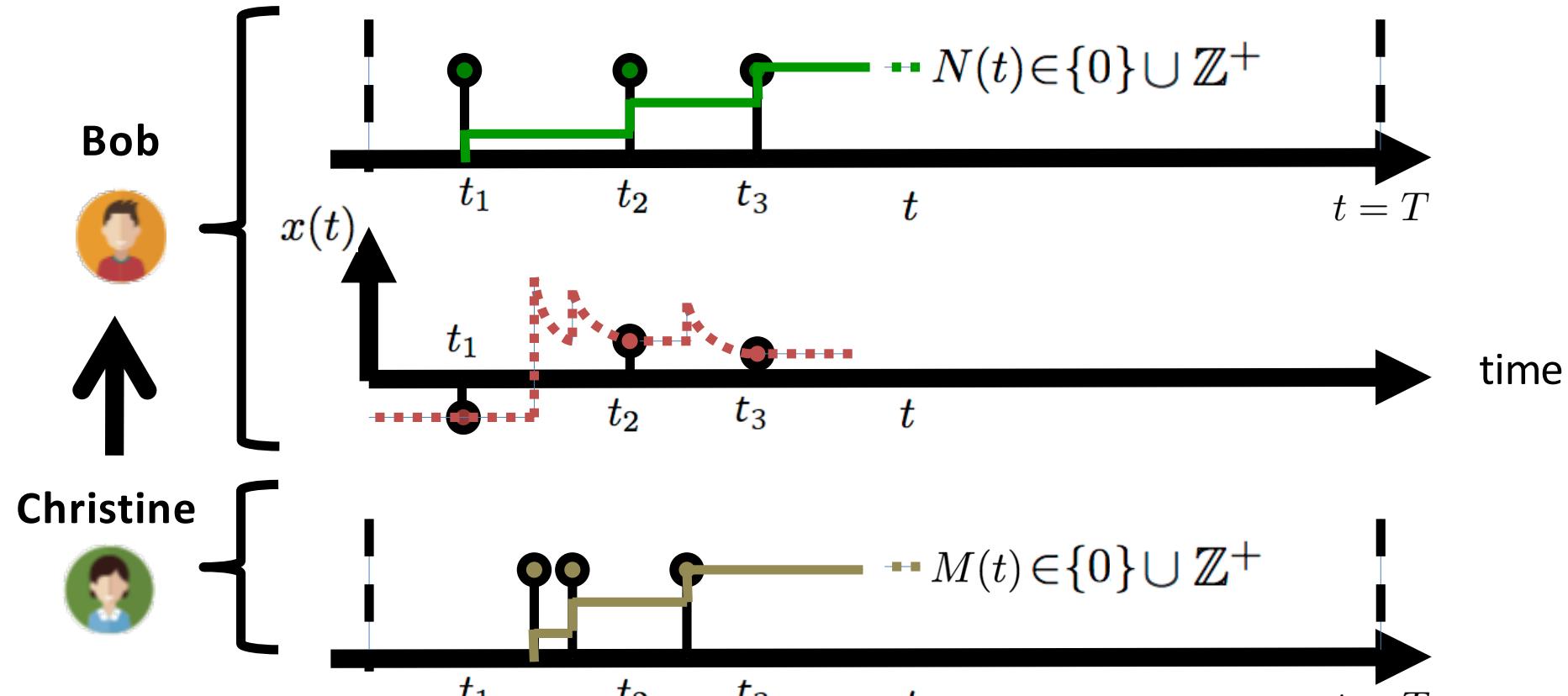


$$x^*(t_i) \sim p(x^* | x(t)) \rightarrow dx(t) = \underbrace{f(x(t), t)dt}_{\text{Drift}} + \underbrace{h(x(t), t)dN(t)}_{\text{Event influence}}$$

Observations:

1. Marks dependent on the temporal dynamics
2. Distribution represents additional source of uncertainty

Mutually exciting + marks

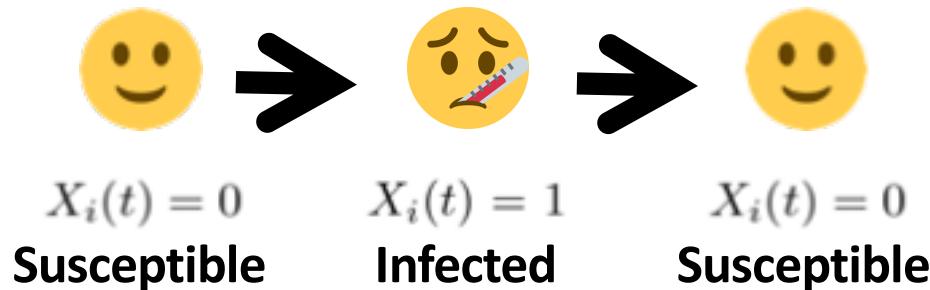


Marks affected by neighbors

$$dx(t) = \underbrace{f(x(t), t)dt}_{\text{Drift}} + \underbrace{g(x(t), t)dM(t)}_{\text{Neighbor influence}}$$

Marked TPPs as stochastic dynamical systems

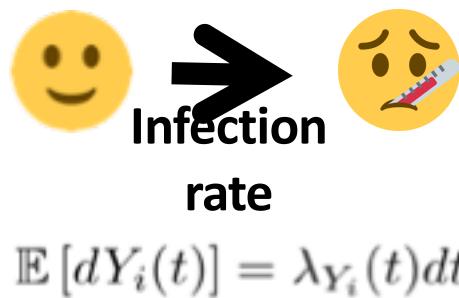
Example: Susceptible-Infected-Susceptible (SIS)



SDE with jumps

$$dX_i(t) = dY_i(t) - dW_i(t)$$

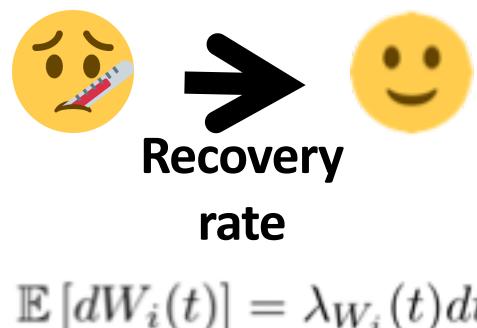
It gets infected It recovers



Node is susceptible

$$\lambda_{Y_i}(t)dt = (1 - X_i(t))\beta \sum_{j \in \mathcal{N}(i)} X_j(t)dt$$

If friends are infected, higher infection rate



SDE with jumps

$$d\lambda_{W_i}(t) = \delta dY_i(t) - \lambda_{W_i}(t)dW_i(t) + \rho dN_i(t)$$

Self-recovery rate when node gets infected If node recovers, rate to zero Rate increases if node gets treated

Outline of the Seminar

TEMPORAL POINT PROCESSES (TPPs): INTRO

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MODELS & INFERENCE

1. Modeling event sequences
2. Clustering event sequences
3. Capturing complex dynamics
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Next

RL & CONTROL

1. Marked TPPs: a new setting
2. Stochastic optimal control
3. Reinforcement learning