AUTOPILOT TEST

DATE: <u>(1)</u>			W/O:(2)	<u>.</u>		
(3)						
Equipment	Manufacturer	Model	Serial No.			
Computer						
Computer		1				
Air Data		1				
Attitude Gyro		+	 			
Mode Selector		+	 			
		+				
Servo		+				
Servo						
Servo						
Servo]			
(4)						
Attitude Gyro Operation		٦	Heading Cure Operation			
		J.,	Heading Gyro Operation			24.16
Current Drain	@	Volts	Power Supply Voltage Check		Low Voltage Operation	Voits
Left Turn Bank Angle		Degrees	Roll Trim		Right Turn Bank Angle	Degrees
		10.				
	Heading DC		Heading AC			
	L R		<u>L</u> R			
	VOR INTERCEPT		LOC INTERCEPT			
	DC CRSE L R		DC CRSE L R			
	50 01.02 <u>2 11</u>		20 CHS2 <u>2 H</u>			
	AC CRSE L R		AC CRSE L R			
Pitch Up Angle	Degree	Pitch Down Angle	Degree	Alt. Hold Signal	Versus Pitch	Angle
	0	· ·	v		·	0
GS Inhibit (BC)		Speed and Scheduling		Pitch Sync	1	
BC Operation		Nav 1 / Nav 2 Select		Auto		
ве орегалоп		Nav 1 / Nav 2 Select	l l			
		-	 	Disconnect		
Autopilot Engage		Remote Disconnect				
		= "		Self Test		
1		<u>-</u>		Self Test		
1			LIGHT DIRECTOR OPERATION			
Pitch Up		(5) F Pitch Down	LIGHT DIRECTOR OPERATION	Self Test		Roll Right
Pitch Up Yaw Damp Signal Input			LIGHT DIRECTOR OPERATION			Roll Right Remote Disconnect
		Pitch Down	LIGHT DIRECTOR OPERATION	Roll Left		
		Pitch Down	LIGHT DIRECTOR OPERATION Torque	Roll Left		
		Pitch Down Versus Output		Roll Left Engage		
Yaw Damp Signal Input		Pitch Down Versus Output		Roll Left Engage		
Yaw Damp Signal Input Roll Servo Pitch Servo		Pitch Down Versus Output		Roll Left Engage		
Yaw Damp Signal Input Roll Servo Pitch Servo Yaw Servo		Pitch Down Versus Output		Roll Left Engage		
Yaw Damp Signal Input Roll Servo Pitch Servo Yaw Servo Pitch Trim		Pitch Down Versus Output		Roll Left Engage		
Yaw Damp Signal Input Roll Servo Pitch Servo Yaw Servo		Pitch Down Versus Output		Roll Left Engage		
Yaw Damp Signal Input Roll Servo Pitch Servo Yaw Servo Pitch Trim Yaw Trim	Start Voltage	Pitch Down Versus Output		Roll Left Engage		
Yaw Damp Signal Input Roll Servo Pitch Servo Yaw Servo Pitch Trim Yaw Trim		Pitch Down Versus Output		Roll Left Engage	VA.E.	
Yaw Damp Signal Input Roll Servo Pitch Servo Yaw Servo Pitch Trim Yaw Trim This unit meets or exceeds r	Start Voltage Start Voltage	Pitch Down Versus Output Speed		Roll Left Engage	KA-5	
Yaw Damp Signal Input Roll Servo Pitch Servo Yaw Servo Pitch Trim Yaw Trim	Start Voltage Start Voltage manufacturer's specifications.	Pitch Down Versus Output Speed		Roll Left Engage	KA-5 PAGE 10 DATED 01/2004	

INSTRUCTIONS FOR FORM USE; AUTOPILOT TEST

- 1. Enter the date of the work
- 2. Enter the Work Order number on which the work is being performed
- 3. Enter the Autopilot equipment specifics; Manufacturer, Model, and Serial Number
- 4. Equipment Operational characteristics;
 - a. Attitude Gyro; enter all performance parameters as tested
 - b. Heading Gyro; enter all performance parameters as tested
 - c. Left Turn and Bank; enter all performance parameters as tested
 - d. Right Turn and Bank; enter all performance parameters as tested
 - e. Heading DC; enter all performance parameters as tested
 - f. Heading AC; enter all performance parameters as tested
 - g. VOR intercept; enter an X for L and R to denote functional check accomplished
 - h. LOC intercept; enter an X for L and R to denote functional check accomplished
 - i. Pitch Up Angle; enter degrees as tested
 - j. Pitch Down Angle; enter degrees as tested
 - k. Altitude Hold Signal; enter values as tested
 - 1. Versus Pitch Angle; enter values as tested
 - m. GS Inhibit (BC); enter an X to denote functional check accomplished
 - n. Speed and Scheduling; enter an X to denote functional check accomplished
 - o. Pitch Sync; enter an X to denote functional check accomplished
 - p. BC Operation; enter an X to denote functional check accomplished
 - q. Nav 1 / Nav 2 Select; enter an X to denote functional check accomplished
 - r. Auto Disconnect; enter an X to denote functional check accomplished
 - s. Autopilot Engage; enter an X to denote functional check accomplished
 - t. Remote Disconnect; enter an X to denote functional check accomplished
 - u. Self Test; enter an X to denote functional check accomplished

v.

- 5. Flight Director Operational characteristics
 - a. Pitch Up; enter an X to denote functional check accomplished
 - b. Pitch Down; enter an X to denote functional check accomplished
 - c. Roll Left; enter an X to denote functional check accomplished
 - d. Roll Right; enter an X to denote functional check accomplished
 - e. Yaw Damp Signal Input; enter an X to denote functional check accomplished
 - f. Versus Output; enter an X to denote functional check accomplished
 - g. Engage; enter an X to denote functional check accomplished
 - h. Remote Disconnect; enter an X to denote functional check accomplished
 - i. Enter values as tested for Start Voltage, Speed, Torque, and Clutch Torque for;
 - i. Roll Servo
 - ii. Pitch Servo
 - iii. Yaw Servo
 - iv. Pitch Trim
 - v. Yaw Trim
- 6. Enter the name of the person performing the tests and functional checks
- 7. Enter the name of the person performing inspections of the work performed

NOTE: Not all fields always require text entry. Contact your supervisor if there are questions. In cases where data is not required, DO NOT leave blank; enter N/A.