

1. Calculate the four 4th roots of the complex number $z = -2\sqrt{3} + 2i$.

Writing z in polar form, we have $z = 4 \left(-\frac{\sqrt{3}}{2} + \frac{1}{2}i \right) = 4e^{i(5\pi/6)}$. If w is a 4th root of z , then $w^4 = z$. Writing $w = re^{i\theta}$, we have $w^4 = r^4 e^{i(4\theta)} = 4e^{i(5\pi/6)} = z$.

Comparing these two numbers, we have $r^4 = 4$, so $r = \sqrt[4]{4} = \sqrt{2}$, and (since we can add any multiple of 2π to the argument $5\pi/6$ without changing the value of z) $4\theta = \frac{5\pi}{6}, \frac{17\pi}{6}, \frac{29\pi}{6}, \frac{41\pi}{6}, \dots$

Dividing by 4, we get the values $\theta = \frac{5\pi}{24}, \frac{17\pi}{24}, \frac{29\pi}{24}, \frac{41\pi}{24}$, (the next value is $\frac{53\pi}{24} = \frac{5\pi}{24} + 2\pi$, and things continue repeat from there) so the four roots are

$$w_0 = \sqrt{2}e^{i(5\pi/24)}, w_1 = \sqrt{2}e^{i(17\pi/24)}, w_2 = \sqrt{2}e^{i(29\pi/24)}, \text{ and } w_3 = \sqrt{2}e^{i(41\pi/24)}.$$

2. Let $P = (1, 0, -2)$, $Q = (-3, 2, 4)$, and $R = (0, 5, -1)$ be points in \mathbb{R}^3 .

- (a) Calculate the vectors $\vec{u} = \overrightarrow{PQ}$, $\vec{v} = \overrightarrow{QR}$, and $\vec{w} = \overrightarrow{PR}$.

We have

$$\begin{aligned}\vec{u} &= \langle -3 - 1, 2 - 0, 4 - (-2) \rangle = \langle -4, 2, 6 \rangle \\ \vec{v} &= \langle 0 - (-3), 5 - 2, -1 - 4 \rangle = \langle 3, 3, -5 \rangle \\ \vec{w} &= \langle 0 - 1, 5 - 0, -1 - (-2) \rangle = \langle -1, 5, 1 \rangle.\end{aligned}$$

- (b) Check that $\vec{u} + \vec{v} = \vec{w}$.

$$\vec{u} + \vec{v} = \langle -4, 2, 6 \rangle + \langle 3, 3, -5 \rangle = \langle -1, 5, 1 \rangle = \vec{w}.$$

- (c) Explain, with a diagram, why your result in part (b) makes sense. (You do not have to accurately plot the points P, Q, R .)

Any diagram showing the three points, labelled P, Q, R , and the vectors between them, will do. The point is to notice that the vector from P to R is the same as the vector obtained by applying the “tip-to-tail” rule for adding vectors. The vector $\vec{u} + \vec{v}$ also gets us from P to R , but takes a detour through the point Q along the way.

3. Let $\vec{a} = \langle 2, -4, 3 \rangle$, $\vec{b} = \langle -5, 2, 7 \rangle$, and $\vec{c} = \langle 1, 0, -3 \rangle$. Calculate the following:

(a) $4\vec{a} - 3\vec{b}$

$$4\vec{a} - 3\vec{b} = 4\langle 2, -4, 3 \rangle - 3\langle -5, 2, 7 \rangle = \langle 8, -16, 12 \rangle + \langle 15, -6, -21 \rangle = \langle 23, -22, -9 \rangle.$$

(b) $\|3\vec{c}\|$

We have $3\vec{c} = 3\langle 1, 0, -3 \rangle = \langle 3, 0, -9 \rangle$, so

$$\|3\vec{c}\| = \|\langle 3, 0, -9 \rangle\| = \sqrt{3^2 + 0^2 + (-9)^2} = \sqrt{90}.$$

(c) $3\|\vec{c}\|$

We have $\|\vec{c}\| = \sqrt{1^2 + 0^2 + (-3)^2} = \sqrt{10}$, so $3\|\vec{c}\| = 3\sqrt{10}$. Note that this is the same value as the previous answer: $\sqrt{90} = \sqrt{9 \cdot 10} = 3\sqrt{10}$.

(d) $\vec{a} \cdot (2\vec{b} - \vec{c})$

Since $2\vec{b} - \vec{c} = \langle -10, 4, 14 \rangle - \langle 1, 0, -3 \rangle = \langle -11, 4, 17 \rangle$, we have

$$\vec{a} \cdot (2\vec{b} - \vec{c}) = \langle 2, -4, 3 \rangle \cdot \langle -11, 4, 17 \rangle = 2(-11) - 4(4) + 3(17) = 13.$$

(e) $2(\vec{a} \cdot \vec{b}) - \vec{a} \cdot \vec{c}$

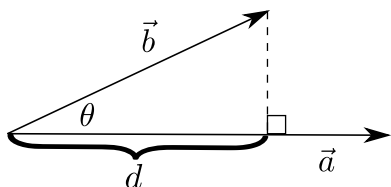
We have

$$\vec{a} \cdot \vec{b} = 2(-5) - 4(2) + 3(7) = 3 \text{ and}$$

$$\vec{a} \cdot \vec{c} = 2(1) - 4(0) + 3(-3) = -7,$$

so $2(\vec{a} \cdot \vec{b}) - \vec{a} \cdot \vec{c} = 2(3) - (-7) = 13$, which is the same as the previous value.

4. Referring to the diagram below, argue that the indicated distance d is given by $d = \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\|}$.



Since $\|\vec{b}\|$ is the length of the hypotenuse of the right-angled triangle shown, we have $\cos \theta = \frac{d}{\|\vec{b}\|}$, and thus $d = \|\vec{b}\| \cos \theta$. We also know that $\vec{a} \cdot \vec{b} = \|\vec{a}\| \|\vec{b}\| \cos \theta$, so $\cos \theta = (\vec{a} \cdot \vec{b}) / (\|\vec{a}\| \|\vec{b}\|)$. Thus,

$$d = \|\vec{b}\| \cos \theta = \|\vec{b}\| \left(\frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\| \|\vec{b}\|} \right) = \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\|},$$

as required.