Matrix multiplication: Special cases Matrix multiplication: Definition and examples Matrix Inverses

## Matrix multiplication and inverses

Math 1410 Linear Algebra

#### Row times column

1. 
$$A = \begin{bmatrix} a_1 & a_2 & \cdots & a_n \end{bmatrix}$$
,  $B = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$ .

### Digression: summation notation

Last example: had product  $AB = a_1b_1 + a_2b_2 + \cdots + a_nb_n$ . Shorten the sum using summation notation:

$$a_1b_1 + a_2b_2 + \cdots + a_nb_n = \sum_{i=1}^n a_ib_i$$

In general, 
$$\sum_{j=1}^n c_j = c_1 + c_2 + \cdots + c_n$$
. Examples:

- 1.  $\sum_{i=1}^{6} i$
- 2.  $\sum_{j=2}^{4} 2^{j}$

### Matrix times column

2. 
$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}, B = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

#### Row times matrix

$$3.A = \begin{bmatrix} a_1 & a_2 & \cdots & a_n \end{bmatrix}, B = \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1k} \\ b_{21} & b_{22} & \cdots & b_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{nk} \end{bmatrix}$$

#### Definition of AB

Generalize from previous cases: to form the product AB, multiply the rows of A by the columns of B.

- ▶ Size matters: if A is size  $m \times n$ , B must be size  $n \times p$ .
- ▶ The product AB will be size  $m \times p$ .
- ► The (i, j)-entry of AB is given by multiplying the  $i^{th}$  row of A by the  $j^{th}$  column of B

#### **Definition**

The product AB of the  $m \times n$  matrix A and the  $n \times p$  matrix B is the matrix  $AB = [c_{ij}]_{m \times p}$ , where

$$c_{ij} = \sum_{k=1}^{n} a_{ik} b_{kj} = a_{i1} b_{1j} + a_{i2} b_{2j} + \cdots + a_{in} b_{nj}.$$

### Basic examples

Let 
$$A = \begin{bmatrix} 2 & -1 & 3 \\ 4 & -3 & 5 \end{bmatrix}$$
,  $B = \begin{bmatrix} 2 & 0 \\ -3 & 1 \end{bmatrix}$ ,  $C = \begin{bmatrix} 3 & -4 \\ 1 & 0 \\ -2 & 6 \end{bmatrix}$ .

Which products are defined?

What size are they? What are their entries?

### Example

Let 
$$A = \begin{bmatrix} 2 & -1 \\ 3 & 0 \end{bmatrix}$$
 and  $B = \begin{bmatrix} -1 & 0 & 3 \\ 0 & 2 & 4 \end{bmatrix}$ . Suppose we are given a matrix  $X$  such that  $AX = B$ .

- (a) What size is X?
- (b) What are the entries of X?
- (c) Can you answer the problem if you're told instead that XA = B? What if BX = A?

### Properties of matrix multiplication

- ▶ Multiplication is not commutative:  $AB \neq BA$  in general.
- ► Given  $A_{m \times n}$ ,  $B_{n \times p}$ ,  $C_{n \times p}$ ,

$$A(B+C)=AB+AC.$$

▶ Given  $A_{m \times n}$ ,  $B_{m \times n}$ ,  $C_{n \times p}$ ,

$$(A+B)C=AC+BC.$$

▶ Given  $A_{m \times n}$ ,  $B_{n \times p}$  and  $c \in \mathbb{R}$ ,

$$A(cB) = (cA)B = c(AB).$$

▶ Given  $A_{m \times n}$ ,  $B_{n \times p}$  and  $C_{p \times q}$ ,

$$A(BC) = (AB)C.$$

▶ Given  $A_{m \times n}$  and  $B_{n \times p}$ ,

$$(AB)^T = B^T A^T$$
.

# Special matrices

Zero matrix:

► Identity matrix:

### Mutliplicative inverses of real numbers

Recall two basic facts about real numbers:

- 1. For any real number  $a \in \mathbb{R}$ ,  $1 \cdot a = a \cdot 1 = a$ .
- 2. For any non-zero real number  $a \in \mathbb{R}$ ,  $a \neq 0$ , the reciprocal  $a^{-1} = \frac{1}{a}$  satisfies

$$\frac{1}{a} \cdot a = a \cdot \frac{1}{a} = 1.$$

#### Matrix inverses

#### **Definition**

Let A be an  $n \times n$  square matrix. We say that A is invertible if there exists an  $n \times n$  matrix B such that

$$AB = BA = I_n$$
.

We call B the inverse of A and write  $B = A^{-1}$ .

Example: the inverse of 
$$A = \begin{bmatrix} 2 & 1 \\ 3 & 2 \end{bmatrix}$$
 is  $A^{-1} = \begin{bmatrix} 2 & -1 \\ -3 & 2 \end{bmatrix}$ .

### Not all matrices are invertible

If A = 0, then AB = 0 for any matrix B, so A is not invertible.

What if 
$$A \neq 0$$
? It's still not guaranteed. Consider  $A = \begin{bmatrix} 1 & -2 \\ -2 & 4 \end{bmatrix}$ .

#### Cancellation

For numbers, if ab = ac and  $a \neq 0$ , we have b = c. For matrices, this may not be the case.

Example

If 
$$A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$
,  $B = \begin{bmatrix} 1 & 1 \\ 2 & 3 \end{bmatrix}$ , and  $C = \begin{bmatrix} 3 & 3 \\ 1 & 2 \end{bmatrix}$ , compute  $AB$  and  $AC$ 

However, if A is invertible and AB = AC, then we have B = C.

### Properties of the inverse

Inverses are unique: if A is invertible and there exist matrices B and C such that  $AB = BA = I_n$  and  $AC = CA = I_n$ , then B = C.

▶ If A and B are invertible  $n \times n$  matrices, then so is AB, and

$$(AB)^{-1} = B^{-1}A^{-1}.$$

### More properties

If A is an invertible  $n \times n$  matrix, then,

$$(A^{-1})^{-1} = A$$

$$(A^T)^{-1} = (A^{-1})^T$$
.

### Computing the inverse

Given an  $n \times n$  matrix A, how do we

- (a) Determine if A is invertible?
- (b) Find the inverse of A?

To answer both, need to solve (if possible)  $AB = I_n$ .

Example: Given 
$$A = \begin{bmatrix} 2 & -1 \\ 3 & 3 \end{bmatrix}$$
, let  $B = \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix}$ .

# Algorithm for finding $A^{-1}$

Given an  $n \times n$  matrix A, we can find  $A^{-1}$  (if it exists) as follows:

- 1. Form the  $n \times 2n$  augmented matrix  $(A|I_n)$ .
- 2. Use elementary row operations (as usual) to reduce  $(A|I_n)$  to reduced row-echelon form.
- 3. If a row  $\begin{bmatrix} 0 & 0 & 0 & | & a & b & c \end{bmatrix}$  appears, stop: A is not invertible.
- 4. If not, the RREF will be of the form  $(I_n|A^{-1})$ .

Consequence: An  $n \times n$  matrix A is invertible if (and only if) rank A = n.

### Examples

$$A = \begin{bmatrix} 2 & -3 \\ 4 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 1 & -2 & 3 \\ 2 & 0 & -4 \\ -1 & -6 & 17 \end{bmatrix}$$

## Systems of equations

Can use inverses to solve system AX = B of n equations in n variables. (So A is  $n \times n$ .) If A is invertible, then  $X = A^{-1}(AX) = A^{-1}B$ .

Warning: This method is not useful in practice. The process of (a) finding  $A^{-1}$  and (b) computing  $A^{-1}B$  takes roughly twice as much work as the Gaussian algorithm.