

# Rank and Homogeneous systems

Math 1410 Linear Algebra

# Notation

Given a system

$$\begin{array}{ccccccc} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n & = & b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n & = & b_2 \\ \vdots & & \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n & = & b_m \end{array}$$

denote

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}, \quad X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, \quad \text{and} \quad B = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

# Structure of a solution

- ▶ With notation as on the previous page, write  $(A|B)$  for the augmented matrix of our system.
- ▶ Use row operations to reduce  $(A|B)$  to an augmented matrix  $(A'|B')$  in (reduced) row echelon form.
- ▶ Cases:
  1. The matrix  $(A'|B')$  has a row of the form  $\begin{bmatrix} 0 & 0 & \cdots & 0 & | & 1 \end{bmatrix}$ .
  2. Every column in  $A'$  contains a leading 1.
  3.  $A$  has  $n$  columns and  $A'$  has  $k$  leading 1s, with  $k < n$ .
- ▶ Note: The number of leading 1s is equal to the number of non-zero rows.

# Rank

## Definition

The **rank** of a matrix  $A$  is the number of leading ones in the row-echelon form of  $A$ .

## Theorem

*Let  $(A|B)$  denote the augmented matrix of a system of  $m$  linear equations in  $n$  variables. Then:*

- 1. If  $\text{rank } A < \text{rank}(A|B)$ , then the system is inconsistent.*
- 2. If  $\text{rank } A = \text{rank}(A|B) = n$ , then the system has a unique solution.*
- 3. If  $\text{rank } A = \text{rank}(A|B) = r < n$ , then the system has infinitely many solutions, with  $n - r$  parameters.*

Note:  $\text{rank } A \leq \min\{m, n\}$ . If our system is consistent and  $n > m$ , then we will have infinitely many solutions.

# Examples

In each case, find  $\text{rank } A$ ,  $\text{rank}(A|B)$ , and the solution of the corresponding system of equations:

$$\left[ \begin{array}{ccc|c} 1 & -2 & 3 & 0 \\ -2 & 0 & 1 & 4 \\ 0 & -8 & 14 & 8 \end{array} \right] \quad (1)$$

$$\left[ \begin{array}{cccc|c} -2 & 8 & 4 & 0 & 6 \\ 0 & 3 & -2 & 1 & -5 \\ -1 & 0 & 2 & 6 & 7 \\ 0 & 0 & 1 & -1 & 4 \end{array} \right] \quad (2)$$

# Column vectors

A **column vector** is an object of the form  $C = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_k \end{bmatrix}$ . For

example, we could have

$$A = \begin{bmatrix} 1 \\ -3 \\ 5 \end{bmatrix} \quad B = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \quad \text{or} \quad C = \begin{bmatrix} 7 \\ -5 \\ 3.72 \\ 0 \end{bmatrix}.$$

We say two column vectors are **equal** if each corresponding entry is equal. Instead of writing  $x_1 = 2, x_2 = -4, x_3 = 1$ , we can write

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ -4 \\ 1 \end{bmatrix}.$$

# Algebra of column vectors

We allow two operations on column vectors: **addition**, and **scalar multiplication**.

$$\text{Addition: } X + Y = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} + \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} x_1 + y_1 \\ x_2 + y_2 \\ \vdots \\ x_n + y_n \end{bmatrix}$$

$$\text{Scalar multiplication: } cX = c \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} cx_1 \\ cx_2 \\ \vdots \\ cx_n \end{bmatrix}$$

# Examples



# Vector form of a system

Given a system of  $m$  equations in  $n$  variables, let  $A$ ,  $X$ , and  $B$  be as before. Let

$$A_1 = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix}, A_2 = \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix}, \dots, A_n = \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix}$$

denote the columns of  $A$ . If we define

$AX = x_1 A_1 + x_2 A_2 + \dots + x_n A_n$ , then we can write our system compactly as

$$AX = B.$$

## Example

Re-write the system of equations as a single matrix equation:

$$\begin{array}{cccccccl} x_1 & - & 2x_2 & - & x_3 & + & 3x_4 & = & 1 \\ 2x_1 & - & 4x_2 & + & x_3 & & & = & 5 \\ x_1 & - & 2x_2 & + & 2x_3 & - & 3x_4 & = & 4 \end{array}$$

# Solutions in vector form

Solving our system: row-reducing gives

$$\left[ \begin{array}{cccc|c} 1 & -2 & -1 & 3 & 1 \\ 2 & -4 & 1 & 0 & 5 \\ 1 & -2 & 2 & -3 & 4 \end{array} \right] \rightarrow \dots \rightarrow \left[ \begin{array}{cccc|c} 1 & -2 & 0 & 1 & 4 \\ 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right].$$

Leading variables:

Parameters:

Solution:

Vector form:

$$X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

# Homogeneous systems

A homogeneous system of equations is a system of the form

$$\begin{array}{ccccccc} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n & = & 0 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n & = & 0 \\ \vdots & & \vdots & & \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n & = & 0 \end{array}$$

That is, all the constants  $b_i$  on the right-hand side are zero.

Matrix form:  $AX = 0$ .

Note: homogeneous systems are always consistent. (Why?)

Homogeneous system: relationship among the variables.

$\Rightarrow$  unique solution not desirable.

# Example

Solve the homogeneous system

$$\begin{array}{ccccccccc} x & + & 3y & - & 2z & + & w & = & 0 \\ 2x & - & y & + & 5z & & & = & 0 \\ & & 14y & - & 2z & + & w & = & 0 \end{array}$$

# Linear combinations

## Definition

We say that a column vector  $Y$  is a **linear combination** of column vectors  $X_1, X_2, \dots, X_k$  if  $Y$  can be written in the form

$$Y = c_1 X_1 + c_2 X_2 + \dots + c_k X_k$$

for constants  $c_1, c_2, \dots, c_k$ .

Given a homogeneous system  $AX = 0$  in  $n$  variables, with  $\text{rank } A = r$ , we will have parameters  $t_1, t_2, \dots, t_k$ , where  $k = n - r$ . The general solution is then of the form

$$X_h = t_1 X_1 + t_2 X_2 + \dots + t_k X_k.$$

*Note:* in Lyryx the vectors  $X_1, \dots, X_k$  are referred to as **basic solutions**.

# General solution - nonhomogeneous case

Let's return to the case of a general system  $AX = B$ .

Suppose:

1. The system is consistent.
2. We have the general solution  $X_h$  to the homogeneous system  $AX = 0$ .
3. We have a **particular** solution (no parameters)  $X_p$  to  $AX = B$ .

Then the general solution to  $AX = B$  is given by  $X = X_h + X_p$ .

# Example

Let's return to an earlier example: the system

$$\begin{array}{cccccccl} x_1 & - & 2x_2 & - & x_3 & + & 3x_4 & = & 1 \\ 2x_1 & - & 4x_2 & + & x_3 & & & = & 5 \\ x_1 & - & 2x_2 & + & 2x_3 & - & 3x_4 & = & 4 \end{array}$$