CODE BLOG

• Main

```
1 ;4 number values given in the question
 2 numl
                EQU 0x40000004
 3 num2
                EQU 0x40000002
 4 num3
                EQU 0x3FFFFFFE
  5
    num4
                 EQU 0x3FFFFFFC
  6
    ;address initial values
  7
 8 adress1 EQU 0X20000040
                EQU 0X20000060
 9 adress2
 10
 11
 12
                 AREA MYCODE, CODE
 13
                 ALIGN
                 ENTRY
 14
                 EXPORT __main
EXTERN mean
 15
 16
 17
     __main
                 ; the given has been saved to the register
 18
 19
                 LDR
                       R0, = numl
 20
                 LDR
                         R1, = num2
 21
                 LDR
                          R3, = num3
                         R4, = num4
 22
                 LDR
                         R5, = adress1
                 LDR
 23
                         R7, = adress2
 24
                 LDR
25
               ;r6 is offset value for the save process
26
27
               ; values recorded in registers RO, R2, R3, R4
28
               ;numbers saved starting from address 0X20000040
29
               MOV
                      R6,#0
30
               STR
                       RO, [R5, R6]
                       R6, R6, #4
31
               ADD
32
               STR
                       R1, [R5, R6]
33
               ADD
                      R6, R6, #4
                      R3, [R5, R6]
34
               STR
35
               ADD
                      R6, R6, #4
36
                      R4, [R5, R6]
               STR
37
38
               ;subroutine
39
              BL
                      mean
40
41
               ;We calculated the R2 value in subroutine
               ; Given the question; I subtract the average value from the given numbers
42
43
               SUB
                      RO, RO, R2
44
               SUB
                       R1, R1, R2
45
               SUB
                      R3, R3, R2
46
               SUB
                    R4, R4, R2
47
```

```
48
               ;r6 is offset value for the save process
49
               MOV
                      R6,#0
50
51
                ; The last step is the value of the subtraction operations, starting from the address 0X20000060.
52
                       RO, [R7, R6]
                STR
53
                ADD
                        R6,R6,#4
54
                STR
                        R1, [R7, R6]
                        R6, R6, #4
55
                ADD
56
                STR
                       R3, [R7, R6]
57
                ADD
                       R6,R6,#4
58
                STR
                       R4, [R7, R6]
59
60
61
                В
62 loop
                        loop
63
                END
```

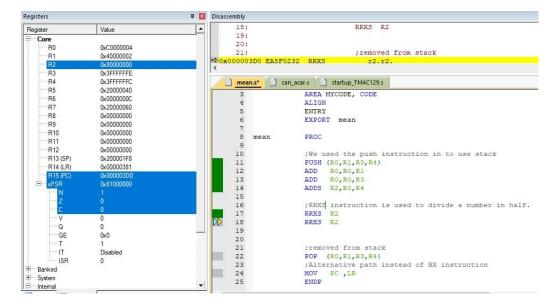
Subroutines

```
can_acar.s
mean.s*
   1
   2
   3
                  AREA MYCODE, CODE
   4
                  ALIGN
                  ENTRY
   5
   6
                  EXPORT mean
   8
     mean
                  PROC
  10
                  ;We used the push instruction in to use stack
  11
                  PUSH {R0,R1,R3,R4}
  12
                  ADD RO,RO,R1
  13
                  ADD RO, RO, R3
  14
                  ADDS R2, R0, R4
  15
                  ;RRC instruction is used to divide a number in half.
  16
  17
                  RRXS R2
  18
                  RRXS R2
  19
  20
  21
                  ;removed from stack
                  POP {R0,R1,R3,R4}
  22
                  ;Alternative path instead of BX instruction
  23
                  MOV PC , LR
  24
  25
                  ENDP
```

ALGORITHM and CODE

- First, I defined the values given in the question. And then these values are recorded in registers. **EQU** instruction was used for defining operations, and **LDR** instruction was used to register to the Register.
- The values given afterwards were recorded in the addresses with **STR** instruction. For example, R1 value is written to the address in R5, starting from the R6 offset.
- The most important part; BL instruction is used when entering subroutine. Here the LR of the next step is kept.
- On the Mean blog, numbers were collected and averaged. Adding 4 numbers, the number became 33 bits and 1 bit went to hand. Here, when making division, the **RRXS** instruction was used and the number was divided including the hand bit.
- When exiting subroutine, instead of BX; Actually, when entering the subroutine, we said that the BL instruction holds the LR of the next step. Program Counter; It is the register that performs operation in programs. If the PC value is LR, the subroutine output is provided.(MOV PC, LR)
- Finally, the average value in the R2 register is subtracted from each element and stored starting at address 0x00000060.
- **PUSH** and **POP** commands provide input and output to stacks.
- ADDS instruction also adds by checking the hand bit.

RRXS insturaction



• The visual shows the status of the registers while running the RRXS instruction.

KODLAR

```
;4 number values given in the question
num1
                   EOU 0x40000004
                   EQU 0x40000002
num2
num3
                   EQU 0x3FFFFFE
                   EQU 0x3FFFFFC
num4
;address initial values
adress1
                EQU
                            0X20000040
                EQU
                            0X20000060
adress2
                            AREA MYCODE, CODE
                            ALIGN
                            ENTRY
                            EXPORT __main
                            EXTERN mean
__main
                            ;the given has been saved to the register
                            LDR
                                      R0, = num1
                            LDR
                                      R1, = num2
                            LDR
                                      R3, = num3
                            LDR
                                      R4, = num4
                            LDR
                                      R5, = adress1
                            LDR
                                      R7, = adress2
                            ;r6 is offset value for the save process
                            ;values recorded in registers R0, R2, R3, R4
                            ;
numbers saved starting from address 0X20000040
                            MOV
                                      R6,#0
                            STR
                                      R0,[R5,R6]
                            ADD
                                      R6,R6,#4
                                      R1,[R5,R6]
                            STR
                            ADD
                                      R6,R6,#4
                                      R3,[R5,R6]
                            STR
                                      R6,R6,#4
                            ADD
                            STR
                                      R4,[R5,R6]
```

;subroutine

BL mean

;We calculated the R2 value in subroutine

;Given the question; I subtract the average value from the given numbers

 SUB
 R0,R0,R2

 SUB
 R1,R1,R2

 SUB
 R3,R3,R2

 SUB
 R4,R4,R2

;r6 is offset value for the save process

MOV R6,#0

; The last step is the value of the subtraction operations, starting from the address 0×20000060 .

 STR
 R0,[R7,R6]

 ADD
 R6,R6,#4

 STR
 R1,[R7,R6]

 ADD
 R6,R6,#4

 STR
 R3,[R7,R6]

 ADD
 R6,R6,#4

 STR
 R4,[R7,R6]

loop B loop

END

Subroutines

AREA MYCODE, CODE

ALIGN ENTRY EXPORT mean

mean PROC

;We used the push instruction in to use stack

PUSH {R0,R1,R3,R4} ADD R0,R0,R1 ADD R0,R0,R3 ADDS R2,R0,R4

;RRXS instruction is used to divide a number in half.

RRXS R2 RRXS R2

;removed from stack POP {R0,R1,R3,R4}

;Alternative path instead of BX instruction

MOV PC ,LR

ENDP