



```

numg1 = [2]; deng = [1 0]; sysg1 = tf(numg1, deng1);
numg2 = [1]; deng = [1 0]; sysg2 = tf(numg2, deng2);
sysg3 = [1];
sys1 = parallel(sysg1, sysg3);
sys2 = series(sys1, sysg2);
sys = feedback(sys2, [1]);

```

sys-ss = ss(sys)

(State-space model bilgileri)