

Ruby-esque Pseudo-Code for Convex Hull Divide-and-Conquer Algorithm

```
def solve(points)
  points = recursive_solve(points)
  (points.size / 2).times do
    points = points.convexify
  end
  return points
end

def recursive_solve(points)
  if points.size <= 2
    return points
  else
    left, right = points.divide_in_half
    return combine(recursive_solve(left), recursive_solve(right))
  end
end

def combine(left, right)
  merged = left.merge(right)
  clockwise = merged.sort_clockwise
  return clockwise.convexify
end

def convexify(points)
  if points.size > 3
    centroid = points.get_centroid
    # pseudo code:
    # 1. loop through each point in 'points'; let each be called 'current'
    # 2. form a triangle from the centroid to
    #    the point before and the point after 'current'
    # 3. if 'current' falls inside the triangle, remove it from 'points'
  end
  return points
end
```

The diagram illustrates the flow of the algorithm using arrows and colored dots. Blue dots are placed at the end of the `recursive_solve` function, the `combine` function, and the `convexify` function. A blue arrow points from the first blue dot to the `recursive_solve` function definition. Another blue arrow points from the second blue dot to the `combine` function definition. A third blue arrow points from the third blue dot to the `convexify` function definition. Red dots are placed at the end of the `recursive_solve` function, the `combine` function, and the `convexify` function. A red arrow points from the first red dot to the `recursive_solve` function definition. Another red arrow points from the second red dot to the `combine` function definition. A third red arrow points from the third red dot to the `convexify` function definition.

Analysis of Computational Efficiency

1. convexify and sort_clockwise are situated in the inner-most loop.
convexify: order n operation
sort_clockwise: order $n \log n$ operation (merge sort)
2. combine is the next outer loop.
Merge: order n operation
+ time to sort_clockwise
+ time to convexify
3. recursive_solve is the next outer loop
This is the divide-and-conquer portion of the algorithm
Divide: order n operation
+ time to combine
4. solve adds precision to the recursively created solution by iteratively removing unnecessary inner points (using convexify).
+ time to recursive_solve
+ convexify * $(m / 2)$ where m is the number of points in the outer rim after applying recursive_solve

$$T(n) = 2T(n/2) + T_{\text{combine}}(n)$$

$$T_{\text{combine}}(n) = 2n + n \cdot \log(n)$$

$$T(n) = 2T(n/2) + 2n + n \cdot \log(n)$$

$$T(n) = 2T(n/2) + O(n^2) *$$

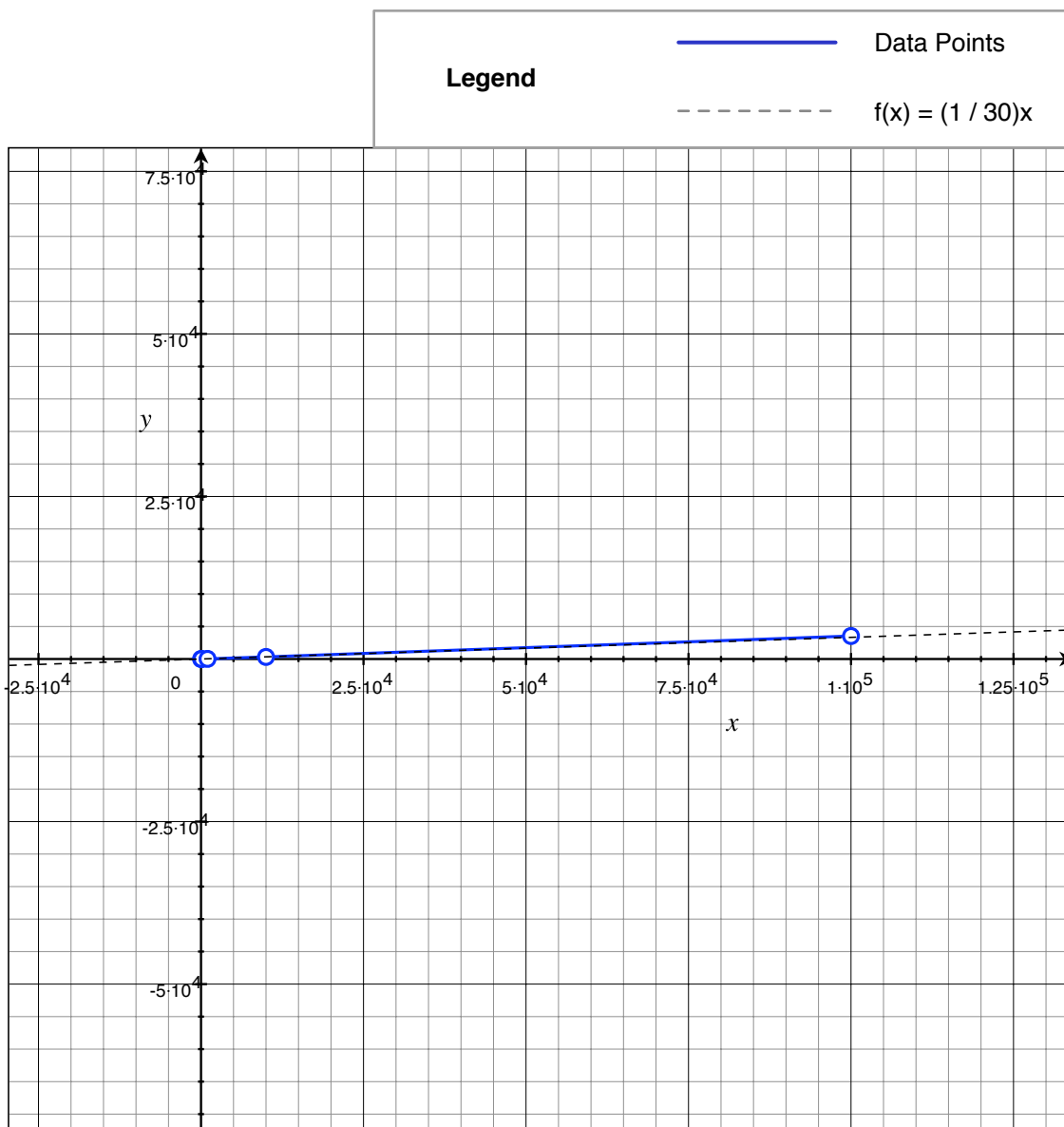
So, by the master theorem:

$$T(n) = O(n^2)$$

* Actually, we can do better than that, but the master theorem doesn't work well without a power in the 2nd function (n raised to some power of d)... so $T(n)$ may actually be bound by $O(n \log(n))$, or something in between.

Emperical Analysis

n	Time (ms)	Time (ms)	Time (ms)
10	0.1	0.2	0.2
100	1.8	1.9	1.8
1,000	21.1	29.5	21.2
10,000	320.2	728.6	368.3
100,000	3,537.1	3,752.2	3,235.8
1,000,000	bad data*	bad data*	bad data*



* Test was completed on a machine with only 256 MB RAM. Disk swapping (virtual memory) became a significant time factor at 1M points.

Comparison of Theoretical and Emperical Analyses

My emperical analysis seems to suggest this is a linear-order growth problem; however, my theoretical analysis places it at $O(n^2)$, or possibly somewhere between $O(n \log(n))$ and $O(n^2)$. So there is a discrepancy between the theory and the practical tests.

It may be that if I could increase the number of points in my test beyond 100,000 I would start to see an increase matching one of the possibilities above. In fact, it seems very unlikely that this is an order n problem, so if I were a betting man, I would place my chips in the "at least $n \log(n)$ " bin. But alas, this is an analysis and betting is not allowed. So I will point out that the theoretical big-O bound of n^2 does indeed bound the seemingly linear order output.

I used a graphing program ("Grapher" on Mac OS X) to find the constant of proportionality, i.e. the fraction $1/30$, as noted on the previous page.

Guide to the Source Code

This page (the one you are reading) is PDF **page 4**.

All of the helper classes such as ColoredPoint and PointList (a list of ColoredPoints) are contained in PDF **pages 5-11**.

The ConvexHullSolver class starts on PDF **page 12** of the source code output and is the most relevant portion of this paper.

I made several modifications to the source code package that was given to us, as I wanted a more hands-on GUI that would let me experiment with groups of Hull objects etc. Therefore, I've included the source code output of FormMain starting on PDF **page 13**.

```
using System;
using System.Collections.Generic;
using System.Drawing;
using System.Text;

namespace ConvexHull
{
    class ColoredPoint
    {
        bool highlighted;
        Pen pen;
        Size size;
        float width;
        public float X, Y;

        public ColoredPoint(ColoredPoint cp)
        {
            init(cp.X, cp.Y, cp.getPen(), cp.getSize(), cp.getWidth(), cp.isHighlighted
());
        }

        public ColoredPoint(float x, float y)
        {
            init(x, y, Color.Black);
        }

        public ColoredPoint(float x, float y, Color color)
        {
            init(x, y, color);
        }

        private void init(float x, float y, Color color)
        {
            init(x, y, new Pen(color, width), new Size(4, 4), 1.0F, false);
        }

        private void init(float x, float y, Pen p, Size s, float w, bool high)
        {
            width = w;
            X = x; Y = y;
            pen = p;
            size = s;
            highlighted = high;
        }

        public bool contains(Point p)
        {
            return getSurroundingRect().Contains(p);
        }

        public Rectangle getRect()
        {
            return getRectWithPadding(0);
        }

        public Rectangle getSurroundingRect()
        {
            return getRectWithPadding(4);
        }

        public Rectangle getRectWithPadding(int padding)
        {
            Size s = new Size(size.Width, size.Height);
            s.Width += padding * 2;
            s.Height += padding * 2;
            PointF p = getPointF();
        }
    }
}
```

```
        p.X -= s.Width / 2;
        p.Y -= s.Height / 2;
        return new Rectangle(Point.Round(p), s);
    }

    public Point getPoint()
    {
        return new Point((int)X, (int)Y);
    }

    public PointF getPointF()
    {
        return new PointF(X, Y);
    }

    public Pen getPen()
    {
        return pen;
    }

    public Color getColor()
    {
        return pen.Color;
    }

    public Size getSize()
    {
        return size;
    }

    public float getWidth()
    {
        return width;
    }

    public bool isHighlighted()
    {
        return highlighted;
    }

    public void highlight()
    {
        highlighted = true;
        width = 2.0F;
        pen = new Pen(Color.Red, width);
    }

    public void unhighlight()
    {
        highlighted = false;
        width = 1.0F;
        pen = new Pen(Color.Black, width);
    }
}
}
```

C:\Documents and Settings\Administrator\My...Distros\ConvexHull\convex-hull\PointList.cs 1

```
using System;
using System.Collections.Generic;
using System.Text;
using System.Drawing;

namespace ConvexHull
{
    class DividedList
    {
        public PointList left;
        public PointList right;

        public DividedList(PointList l, PointList r)
        {
            left = l; right = r;
        }
    }

    class PointList : List<ColoredPoint>
    {
        static PointF compareCenter = new PointF();

        public PointList() : base() {}

        public PointList(PointList p) : base(p) {}

        public PointList(List<ColoredPoint> p) : base(p) { }

        public PointList copy()
        {
            PointList pl = new PointList();
            foreach (ColoredPoint pc in this) pl.Add(new ColoredPoint(pc));
            return pl;
        }

        public int topPointIndex()
        {
            int topIndex = -1;
            for (int i = 0; i < Count; i++)
                if (topIndex == -1 || this[i].Y < this[topIndex].Y) topIndex = i;
            return topIndex;
        }

        public ColoredPoint topPoint() { return this[topPointIndex()]; }

        public int bottomPointIndex()
        {
            int bottomIndex = -1;
            for (int i = 0; i < Count; i++)
                if (bottomIndex == -1 || this[i].Y > this[bottomIndex].Y) bottomIndex = i;
            return bottomIndex;
        }

        public ColoredPoint bottomPoint() { return this[bottomPointIndex()]; }

        public int leftPointIndex()
        {
            int leftIndex = -1;
            for (int i = 0; i < Count; i++)
                if (leftIndex == -1 || this[i].X < this[leftIndex].X) leftIndex = i;
            return leftIndex;
        }

        public ColoredPoint leftPoint() { return this[leftPointIndex()]; }

        public int rightPointIndex()
        {
            int rightIndex = -1;

```

```

        for (int i = 0; i < Count; i++)
            if (rightIndex == -1 || this[i].X > this[rightIndex].X) rightIndex = i;
        return rightIndex;
    }
    public ColoredPoint rightPoint() { return this[rightPointIndex()]; }

    public DividedList divide()
    {
        PointF p = getCentroid();
        Predicate<ColoredPoint> left = delegate(ColoredPoint cp) { return cp.X < p.X; }
        Predicate<ColoredPoint> right = delegate(ColoredPoint cp) { return cp.X >= p.X; }
    };
X; };
    return new DividedList(
        new PointList(FindAll(left)),
        new PointList(FindAll(right)));
    }

    public PointList highlight()
    {
        foreach (ColoredPoint cp in this) cp.highlight();
        return this;
    }

    public PointList unhighlight()
    {
        foreach (ColoredPoint cp in this) cp.unhighlight();
        return this;
    }

    public PointF getCentroid()
    {
        float x = 0.0F, y = 0.0F;
        foreach (ColoredPoint cp in this)
        {
            x += cp.X;
            y += cp.Y;
        }
        return new PointF(x / Count, y / Count);
    }

    public PointList highlightedList()
    {
        Predicate<ColoredPoint> highlighted = delegate(ColoredPoint cp) { return cp. isHighlighted(); };
        return new PointList(FindAll(highlighted));
    }

    public PointList clockwiseList()
    {
        PointList orderedList = new PointList(this);
        compareCenter = orderedList.getCentroid();
        orderedList.Sort(compareClockWise);
        return orderedList;
    }

    public PointList counterClockWiseList()
    {
        PointList orderedList = new PointList(this);
        compareCenter = orderedList.getCentroid();
        orderedList.Sort(compareCounterClockWise);
        return orderedList;
    }

    public PointList selectTopHalf()
    {

```



```

        PointList topHalf = new PointList();
        int leftMost = leftPointIndex(), rightMost = rightPointIndex();
        float bottom = Math.Max(this[leftMost].Y, this[rightMost].Y);
        foreach (ColoredPoint cp in this)
            if (cp.Y <= bottom) topHalf.Add(cp);
        return topHalf;
    }

    public PointList selectBotHalf()
    {
        PointList bottomHalf = new PointList();
        int leftMost = leftPointIndex(), rightMost = rightPointIndex();
        float top = Math.Min(this[leftMost].Y, this[rightMost].Y);
        foreach (ColoredPoint cp in this)
            if (cp.Y >= top) bottomHalf.Add(cp);
        return bottomHalf;
    }

    private static int compareClockWise(ColoredPoint p1, ColoredPoint p2)
    {
        double x1 = (double)(p1.X - compareCenter.X);
        double y1 = (double)(p1.Y - compareCenter.Y);
        double r1 = Math.Atan2(y1, x1);

        double x2 = (double)(p2.X - compareCenter.X);
        double y2 = (double)(p2.Y - compareCenter.Y);
        double r2 = Math.Atan2(y2, x2);

        if (r1 == r2) return 0;
        if (r1 > r2) return 1;
        return -1;
    }

    private static int compareCounterClockWise(ColoredPoint p1, ColoredPoint p2)
    {
        return compareClockWise(p2, p1);
    }

    public void drawPoints(Graphics g)
    {
        foreach (ColoredPoint cp in this)
            g.DrawRectangle(cp.getPen(), cp.getRect());
    }

    public void drawConnections(Graphics g, bool primaryConnections)
    {
        PointList orderedList = clockWiseList();
        ColoredPoint prev = null;
        Pen pen = primaryConnections ? new Pen(Color.Gray, 2F) : new Pen(Color.Blue, 2F);
        foreach (ColoredPoint cp in orderedList)
        {
            if (prev != null)
            {
                g.DrawLine(pen, prev.getPoint(), cp.getPoint());
            }
            prev = cp;
        }
        // Connect head to tail
        if (orderedList.Count > 0)
            g.DrawLine(pen,
                orderedList[0].getPoint(),
                orderedList[orderedList.Count - 1].getPoint());
    }

    public void drawHighlightedConnections(Graphics g, bool primaryConnections)

```

```

    {
        highlightedList().drawConnections(g, primaryConnections);
    }

    private bool pointAboveLine(ColoredPoint p1, ColoredPoint n1, ColoredPoint n2)
    {
        if (n2.Y - n1.Y == 0F)
            return p1.Y <= n1.Y;
        else
            return p1.Y <= ((n2.X - n1.X) * (p1.X - n1.X)) / (n2.Y - n1.Y) + n1.Y;
    }

    private bool pointBelowLine(ColoredPoint p1, ColoredPoint n1, ColoredPoint n2)
    {
        if (n2.Y - n1.Y == 0F)
            return p1.Y >= n1.Y;
        else
            return p1.Y >= ((n2.X - n1.X) * (p1.X - n1.X)) / (n2.Y - n1.Y) + n1.Y;
    }

    public bool hasPointAboveLine(ColoredPoint n1, ColoredPoint n2)
    {
        foreach (ColoredPoint cp in this)
            if (pointAboveLine(cp, n1, n2) && n1 != cp && n2 != cp) return true;
        return false;
    }

    public bool hasPointBelowLine(ColoredPoint n1, ColoredPoint n2)
    {
        foreach (ColoredPoint cp in this)
            if (pointBelowLine(cp, n1, n2) && n1 != cp && n2 != cp) return true;
        return false;
    }

    public void RemoveBetween(int start, int end)
    {
        if (start == end) return;
        if (++start >= Count) start = 0;
        if (--end < 0) end = Count - 1;

        if (start < end)
        {
            RemoveRange(start, end - start);
        }
        else
        {
            RemoveRange(start, Count - start);
            RemoveRange(0, end);
        }
    }

    public PointList Convexify()
    {
        if (Count <= 3) return new PointList(this);

        PointList convex = new PointList();
        PointF centroidF = getCentroid();
        ColoredPoint centroid = new ColoredPoint(centroidF.X, centroidF.Y);

        for (int i = 0; i < Count - 2; i++)
        {
            ColoredPoint p1 = this[i], p2 = this[i + 1], p3 = this[i + 2];
            if (!PointList.insideTriangle(p2, centroid, p1, p3))
                convex.Add(p2);
        }
    }

```

```
// Add the end points
if (!PointList.insideTriangle(this[0], centroid, this[Count - 1], this[1]))
    convex.Add(this[0]);

- 2]))
    if (!PointList.insideTriangle(this[Count - 1], centroid, this[0], this[Count
        convex.Add(this[Count - 1]);

    return convex;
}

public static PointList Merge(PointList p1, PointList p2)
{
    PointList newList = new PointList();
    foreach (ColoredPoint cp in p1) newList.Add(cp);
    foreach (ColoredPoint cp in p2) newList.Add(cp);
    return newList;
}

public static bool insideTriangle(ColoredPoint p, ColoredPoint a, ColoredPoint b,
ColoredPoint c)
{
    float m = (a.X - p.X) * (b.Y - p.Y) - (b.X - p.X) * (a.Y - p.Y);
    float n = (b.X - p.X) * (c.Y - p.Y) - (c.X - p.X) * (b.Y - p.Y);
    float o = (c.X - p.X) * (a.Y - p.Y) - (a.X - p.X) * (c.Y - p.Y);
    return (Math.Sign(m) == Math.Sign(n) && Math.Sign(n) == Math.Sign(o));
}
}
```

```
using System;
using System.Collections.Generic;
using System.Text;
using System.Windows.Forms;
using System.Drawing;

namespace ConvexHull
{
    class ConvexHullSolver
    {
        PictureBox picture;
        Graphics graphics;

        public ConvexHullSolver(PictureBox p)
        {
            picture = p;
            graphics = Graphics.FromImage(picture.Image);
        }

        public PointList Solve(PointList points)
        {
            //return RecursiveSolve(points).Convexify().Convexify().Convexify().Convexify()
            ().Convexify().Convexify();
            PointList solution = RecursiveSolve(points);
            for (int i = 0; i < solution.Count / 2; i++)
                solution = solution.Convexify();
            return solution;
        }

        public PointList RecursiveSolve(PointList points)
        {
            if (points.Count <= 2)
            {
                return points.copy();
            }
            else
            {
                DividedList dl = points.divide();
                PointList left = Solve(dl.left);
                PointList right = Solve(dl.right);
                return Combine(left, right);
            }
        }

        public PointList Combine(PointList left, PointList right)
        {
            if (left.Count == 0) return right;
            if (right.Count == 0) return left;

            return PointList.Merge(left, right).clockWiseList().Convexify();
        }

        public PointList CombineHex(PointList left, PointList right)
        {
            if (left.Count == 0) return right;
            if (right.Count == 0) return left;

            left = left.clockWiseList();
            right = right.counterClockWiseList();

            PointList combined = new PointList();
            ColoredPoint edgePoint;

            edgePoint = left.topPoint();
            if (!combined.Contains(edgePoint)) combined.Add(edgePoint);
            edgePoint = left.leftPoint();
```

```
        if (!combined.Contains(edgePoint)) combined.Add(edgePoint);
        edgePoint = left.bottomPoint();
        if (!combined.Contains(edgePoint)) combined.Add(edgePoint);

        edgePoint = right.topPoint();
        if (!combined.Contains(edgePoint)) combined.Add(edgePoint);
        edgePoint = right.rightPoint();
        if (!combined.Contains(edgePoint)) combined.Add(edgePoint);
        edgePoint = right.bottomPoint();
        if (!combined.Contains(edgePoint)) combined.Add(edgePoint);

        return combined;
    }
}
```

```

using System;
using System.Collections.Generic;
using System.Collections;
using System.ComponentModel;
using System.Data;
using System.Drawing;
using System.Text;
using System.Windows.Forms;
using System.Diagnostics;

namespace ConvexHull
{
    public partial class FormMain : Form
    {
        abstract class PointGenerator
        {
            /// <summary>
            /// Generates a random point in a rectangle defined with the given width x
            height.
            /// Sub classes should implement a specific algorithm to determine point
            distribution.
            /// </summary>
            /// <param name="width">Width of the bounding rectangle</param>
            /// <param name="height">Height of the bounding rectangle</param>
            /// <returns>The generated random point</returns>
            public abstract ColoredPoint generatePointIn(int width, int height);
        }

        class GaussianPointGenerator : PointGenerator {
            // Uses this to generate the Guassian distribution
            // from http://msdn.microsoft.com/msdnmag/issues/06/09/TestRun/default.aspx
            // (http://msdn.microsoft.com/msdnmag/issues/06/09/TestRun/default.aspx?loc=&
            fig=true#fig9)
            class Gaussian
            {
                private Random r = new Random(0);
                private bool use_last_result = false; // flag for NextGaussian3()
                private double y2 = 0.0; // secondary result for NextGaussian3()

                public double NextGaussian(double mean, double sd) // most efficient
                {
                    double x1, x2, w, y1 = 0.0;

                    if (use_last_result) // use answer from previous call?
                    {
                        y1 = y2;
                        use_last_result = false;
                    }
                    else
                    {
                        do
                        {
                            x1 = 2.0 * r.NextDouble() - 1.0;
                            x2 = 2.0 * r.NextDouble() - 1.0;
                            w = (x1 * x1) + (x2 * x2);
                        }
                        while (w >= 1.0); // are x1 and x2 inside unit circle?

                        w = Math.Sqrt((-2.0 * Math.Log(w)) / w);
                        y1 = x1 * w;
                        y2 = x2 * w;
                        use_last_result = true;
                    }
                }
            }
        }
    }
}

```

```

        return mean + y1 * sd;
    }
}
Gaussian m_rand;

public GaussianPointGenerator() {
    m_rand = new Gaussian();
}

public override ColoredPoint generatePointIn(int width, int height) {
    // mdj 1/8/07 generate random points with floats instead of ints to avoid
    having so many
    // duplicates as per Dr. Ringger's comments from Fall 06. Doubles would
    be better, but there's
    // no built-in point data structure for doubles.
    return new ColoredPoint(width / 2 + (float)m_rand.NextGaussian(0, width /
6),
        height / 2 + (float)m_rand.NextGaussian(0, height / 6));
}

}

class UniformPointGenerator : PointGenerator
{
    private Random rand = new Random(0);

    /// <summary>
    /// Generates points that are uniformly distributed inside of the oval
    /// defined by the bounding rectangle passed in.
    /// </summary>
    /// <param name="width">Width of the bounding rectangle</param>
    /// <param name="height">Height of the bounding rectangle</param>
    /// <returns>Random point in an oval bound by the rectangle</returns>
    public override ColoredPoint generatePointIn(int width, int height) {
        double r, x, y;

        do {
            //First generate points inside a circle
            x = 2.0 * rand.NextDouble() - 1.0;
            y = 2.0 * rand.NextDouble() - 1.0;

            //Check radius
            r = Math.Sqrt(x * x + y * y);
        } while( r > 1.0 );

        //Now convert to possibly-oval, larger bounds
        x *= width / 2 - 10;    //giving 5px border on each side
        y *= width / 2 - 10;
        //Translate to screen coords
        x += width / 2;
        y += height / 2;

        //Using float gives fewer duplicates than using int.
        //Double would be better but there is no Point-Double class.
        return new ColoredPoint((float)x, (float)y);
    }
}

PointGenerator pointGenerator;
PointList m_primaryPointList, m_originalPointList;
List<PointList> m_pointLists;
ColoredPoint m_mouseDragPoint;
ColoredPoint m_contextPoint;
private Hashtable UniquePoints;
//bool m_imageScaled;

public FormMain()

```

```

    {
        InitializeComponent();
        pictureBoxView.Image = new Bitmap(pictureBoxView.Width, pictureBoxView.
Height);
        pointGenerator = new UniformPointGenerator();
        radioUniform.Checked = true;    //start with this as the default
        UniquePoints = new Hashtable();
        m_primaryPointList = new PointList();
        m_originalPointList = new PointList();
        m_pointLists = new List<PointList>();
        this.ContextMenuStrip = cmUnhighlightedPoint;
    }

    private ColoredPoint getRandomPoint()
    {
        //eam, 1/17/08 -- changed to use a Strategy Pattern for generating pts w/
different distributions
        return pointGenerator.generatePointIn(pictureBoxView.Width, pictureBoxView.
Height);
    }

    private void resetPoints()
    {
        m_primaryPointList.Clear();
        m_pointLists.Clear();
        buttonCombineHulls.Enabled = false;
        buttonRemoveHulls.Enabled = false;
    }

    private void generatePoints()
    {
        // create point list
        int numPoints = int.Parse(textBoxNumPoints.Text);
        resetPoints();
        UniquePoints.Clear();
        ColoredPoint NewlyCreatedPoint;
        pbProgress.Value = pbProgress.Minimum;
        pbProgress.Maximum = 100;

        // make sure X value are unique.  Y values may contain duplicates by the way.
        while (UniquePoints.Count < numPoints)
        {
            pbProgress.Value = (int) (100f * ((float) UniquePoints.Count / ((float)
numPoints)));
            NewlyCreatedPoint = getRandomPoint();    //get the next point to add
            if (!UniquePoints.Contains(NewlyCreatedPoint.X))
                UniquePoints.Add(NewlyCreatedPoint.X, NewlyCreatedPoint);
        };

        // more convenient from here on out to use list.
        foreach (ColoredPoint point in UniquePoints.Values)
        {
            m_primaryPointList.Add(point);
        }

        // find the max and min
        float maxX = pictureBoxView.Image.Width, maxY = pictureBoxView.Image.Height;
        float minX = 0, minY = 0;
        foreach (ColoredPoint point in m_primaryPointList)
        {
            if(maxX < point.X) maxX = point.X;
            if(maxY < point.Y) maxY = point.Y;
            if(minX > point.X) minX = point.X;
            if(minY > point.Y) minY = point.Y;
        }
    }

```



```

    }

    // find translation factors
    float transX = (minX < 0F) ? -minX : 0F;
    float transY = (minY < 0F) ? -minY : 0F;

    // find the point range
    float rangeX = transX + (maxX - minX);
    float rangeY = transY + (maxY - minY);

    // find scaling factors
    const int padding = 20;
    float scaleX = (pictureBoxView.Image.Width - padding) / rangeX;
    float scaleY = (pictureBoxView.Image.Height - padding) / rangeY;

    // only shrink points , not enlarge them
    if (scaleX > 1.0) scaleX = 1F;
    if (scaleY > 1.0) scaleY = 1F;

    // scale points
    for(int i = 0; i < m_primaryPointList.Count; ++i)
    {
        ColoredPoint p = m_primaryPointList[i];
        p.X = transX + (p.X * scaleX);
        p.Y = transY + (p.Y * scaleY);
        m_primaryPointList[i] = p;
    }

    /*if (scaleX != 1.0 || scaleY != 1.0)
        m_imageScaled = true;*/
    m_originalPointList = m_primaryPointList.copy();
    pictureBoxView.Invalidate();
    statusLabel.Text = "" + numPoints + " points Generated. Scale factor: " +
        ((scaleX >= scaleY) ? scaleX : scaleY);
}

#region GUI Control
private void buttonGenerate_Click(object sender, EventArgs e)
{
    generatePoints();
}

private void textBoxNumPoints_Validating(object sender, CancelEventArgs e)
{
    int result;
    if(!(int.TryParse(textBoxNumPoints.Text, out result)))
    {
        e.Cancel = true;
    }
}

private void buttonSolve_Click(object sender, EventArgs e)
{
    // Clear our list of lists, except for the first one

    // Start solving
    Stopwatch timer = new Stopwatch();
    timer.Start();
    ConvexHullSolver convexHullSolver = new ConvexHullSolver(pictureBoxView);
    //m_pointLists = convexHullSolver.Solve2(m_primaryPointList);
    m_pointLists.Add(convexHullSolver.Solve(m_primaryPointList).highlight());
    timer.Stop();
    m_primaryPointList.unhighlight();
    buttonRemoveHulls.Enabled = true;
    pictureBoxView.Invalidate();
    statusLabel.Text = "Done. Time taken: " + timer.Elapsed;
}

```

```

    }

    private void buttonClearToPoints_Click(object sender, EventArgs e)
    {
        resetPoints();
        m_primaryPointList = m_originalPointList.copy();
        pictureBoxView.Invalidate();
        statusLabel.Text = "Cleared to the original points.";
    }
    #endregion

    private void radioUniform_CheckedChanged(object sender, EventArgs e) {
        if( !(pointGenerator is UniformPointGenerator) ) {
            pointGenerator = new UniformPointGenerator();
        }
    }

    private void radioGaussian_CheckedChanged(object sender, EventArgs e) {
        if( !(pointGenerator is GaussianPointGenerator) ) {
            pointGenerator = new GaussianPointGenerator();
        }
    }

    private void pictureBoxView_Paint(object sender, PaintEventArgs e)
    {
        Graphics g = e.Graphics;
        // Clear the picture box view
        g.Clear(Color.White);
        // Draw dots and connections
        foreach (PointList pointList in m_pointLists)
        {
            pointList.drawPoints(g);
            pointList.drawHighlightedConnections(g, false);
        }
        // Draw the official source list as well
        m_primaryPointList.drawPoints(g);
        m_primaryPointList.drawHighlightedConnections(g, true);
    }

    private void buttonHighlightEverything_Click(object sender, EventArgs e)
    {
        m_primaryPointList.highlight();
        pictureBoxView.Invalidate();
    }

    private void buttonHighlightNothing_Click(object sender, EventArgs e)
    {
        m_primaryPointList.unhighlight();
        pictureBoxView.Invalidate();
    }

    private void btnTop_Click(object sender, EventArgs e)
    {
        PointList top = m_primaryPointList.selectTopHalf();
        if (top[0].isHighlighted())
            m_primaryPointList.unhighlight();
        else
            top.highlight();
        pictureBoxView.Invalidate();
    }

    private void btnBottom_Click(object sender, EventArgs e)
    {
        PointList bottom = m_primaryPointList.selectBotHalf();
        if (bottom[0].isHighlighted())

```

```

        m_primaryPointList.unhighlight();
    else
        bottom.highlight();
    pictureBoxView.Invalidate();
}

private void pictureBoxView_MouseDown(object sender, MouseEventArgs e)
{
    Point mouse = new Point(e.X, e.Y);
    if (e.Button == MouseButtons.Left)
    {
        foreach (ColoredPoint cp in m_primaryPointList)
        {
            if (cp.contains(mouse))
            {
                m_mouseDragPoint = cp;
            }
        }
    }
}

private void pictureBoxView_MouseMove(object sender, MouseEventArgs e)
{
    if (e.Button == MouseButtons.Left && m_mouseDragPoint != null)
    {
        m_mouseDragPoint.X = e.X;
        m_mouseDragPoint.Y = e.Y;
        pictureBoxView.Invalidate();
    }

    // Context Menus
    Point mouse = new Point(e.X, e.Y);
    foreach (ColoredPoint cp in m_primaryPointList)
    {
        if (cp.contains(mouse))
        {
            // Store for later context menu use
            m_contextPoint = cp;

            if (cp.isHighlighted())
            {
                this.ContextMenuStrip = cmHighlightedPoint;
                break;
            }
            else
            {
                this.ContextMenuStrip = cmUnhighlightedPoint;
                break;
            }
        }
        else
        {
            this.ContextMenuStrip = null;
        }
    }
}

private void pictureBoxView_MouseUp(object sender, MouseEventArgs e)
{
    if (e.Button == MouseButtons.Left)
    {
        m_mouseDragPoint = null;
    }
}

```

```

private void pictureBoxView_MouseClick(object sender, MouseEventArgs e)
{
}

private void pictureBoxView_MouseDoubleClick(object sender, MouseEventArgs e)
{
    Point mouse = new Point(e.X, e.Y);
    if (e.Button == MouseButtons.Left)
    {
        foreach (ColoredPoint cp in m_primaryPointList)
        {
            if (cp.contains(mouse))
            {
                if (cp.isHighlighted())
                    cp.unhighlight();
                else
                    cp.highlight();
                pictureBoxView.Invalidate();
                return;
            }
        }

        // Did not click on a point, so create one
        ColoredPoint newPoint = new ColoredPoint(e.X, e.Y);
        newPoint.highlight();
        m_primaryPointList.Add(newPoint);
        pictureBoxView.Invalidate();
    }
}

private void highlightMenuItem_Click(object sender, EventArgs e)
{
    m_contextPoint.highlight();
    pictureBoxView.Invalidate();
}

private void unhighlightMenuItem_Click(object sender, EventArgs e)
{
    m_contextPoint.unhighlight();
    pictureBoxView.Invalidate();
}

private void removeUnhighlightedMenuItem_Click(object sender, EventArgs e)
{
    m_primaryPointList.Remove(m_contextPoint);
    pictureBoxView.Invalidate();
}

private void removeHighlightedMenuItem_Click(object sender, EventArgs e)
{
    m_primaryPointList.Remove(m_contextPoint);
    pictureBoxView.Invalidate();
}

private void buttonCombineHulls_Click(object sender, EventArgs e)
{
    ConvexHullSolver convexHullSolver = new ConvexHullSolver(pictureBoxView);
    if (m_pointLists.Count < 2) throw new Exception("Must have 2 point lists to
combine.");
    PointList combined = convexHullSolver.Combine(m_pointLists[0], m_pointLists
[1]);

    m_primaryPointList.unhighlight();
    m_pointLists.Clear();
}

```

```
        buttonCombineHulls.Enabled = false;
        buttonRemoveHulls.Enabled = false;

        m_pointLists.Add(combined);
        pictureBoxView.Invalidate();
    }

    private void addAsHullToolStripMenuItem_Click(object sender, EventArgs e)
    {
        m_pointLists.Add(m_primaryPointList.highlightedList().copy());
        if (m_pointLists.Count >= 1) buttonRemoveHulls.Enabled = true;
        if (m_pointLists.Count >= 2) buttonCombineHulls.Enabled = true;
        m_primaryPointList.unhighlight();
        pictureBoxView.Invalidate();
    }

    private void buttonRemoveHulls_Click(object sender, EventArgs e)
    {
        m_pointLists.Clear();
        buttonCombineHulls.Enabled = false;
        buttonRemoveHulls.Enabled = false;
        pictureBoxView.Invalidate();
    }
}
}
```