Cheat Sheet for EE464

Performance Parameters

$$FormFactor = \frac{V_{rms}}{V_{avg}}$$

$$CrestFactor = \frac{V_{peak}}{V_{rms}}$$

$$DistortionFactor = \frac{I_{1rms}}{I_{rms}}$$

 ϕ : phase difference between fundamentals of current and voltage $DisplacementPowerFactor = \cos(\phi)$

$$TruePowerFactor = \frac{P}{S} = DPF \frac{I_{1,RMS}}{I_{RMS}}$$

$$THD = \sqrt{(\frac{I_{rms}}{I_{1rms}})^2 - 1}$$

Symmetry	Condition Required	a_h and b_h
Even	f(-t) = f(t)	$b_h = 0$ $a_h = \frac{2}{\pi} \int_0^{\pi} f(t) \cos(h\omega t) d(\omega t)$
Odd	f(-t) = -f(t)	$a_h = 0$ $b_h = \frac{2}{\pi} \int_0^{\pi} f(t) \sin(h\omega t) d(\omega t)$
Half-wave	$f(t) = -f(t + \frac{1}{2}T)$	$a_h = b_h = 0 \text{ for even } h$ $a_h = \frac{2}{\pi} \int_0^{\pi} f(t) \cos(h\omega t) d(\omega t) \text{ for odd } h$ $b_h = \frac{2}{\pi} \int_0^{\pi} f(t) \sin(h\omega t) d(\omega t) \text{ for odd } h$

Figure 1: Fourier Transform Table

Converters

$$\begin{split} \boxed{V_o = V_s \bigg(\frac{D}{1-D}\bigg) \bigg(\frac{N_2}{N_1}\bigg)} & \boxed{\frac{\Delta V_o}{V_o} = \frac{D}{RCf}} & (L_m)_{\min} = \frac{(1-D)^2 R}{2f} \bigg(\frac{N_1}{N_2}\bigg)^2 \\ I_{L_m,\max} = I_{L_m} + \frac{\Delta i_{L_m}}{2} & L_m = \frac{V_s DT}{\Delta i_{L_m}} = \frac{V_s D}{\Delta i_{L_m} f} \\ & = \frac{V_s D}{(1-D)^2 R} \bigg(\frac{N_2}{N_1}\bigg)^2 + \frac{V_s DT}{2L_m} & \sum_{\substack{i=1\\ i\neq j\\ j \neq j\\ j \neq j}} & \sum_{\substack{i=1\\ i\neq j}} & \sum_{\substack{i=1\\ i\neq j}} & \sum_{\substack{i=1\\ i\neq j\\ j \neq j}} & \sum_{\substack{i=1\\ i\neq j}} & \sum_{\substack{i=1\\ i\neq j}} & \sum_{\substack{i=1\\ i\neq j\\ j \neq j}} & \sum_{\substack{i=1\\ i\neq j}} & \sum_$$

Figure 2: Flyback Formulas

$$\begin{bmatrix} V_o = V_s D \left(\frac{N_2}{N_1} \right) \end{bmatrix} \begin{bmatrix} \frac{\Delta V_o}{V_o} = \frac{1 - D}{8L_x C f^2} \end{bmatrix}$$

$$\Delta V_{o, ESR} = \Delta i_C r_C = \Delta i_{L_x} r_C = \begin{bmatrix} \frac{V_o (1 - D)}{L_x f} \end{bmatrix} r_C$$

$$\Delta i_{L_m} = \frac{V_s D T}{L_m}$$

Figure 3: Forward (single switched) Converter Formulas

$$\boxed{ V_o = 2V_s \bigg(\frac{N_S}{N_P} \bigg) D \left[\frac{\Delta V_o}{V_o} = \frac{1 - 2D}{32L_x C f^2} \right] }$$

$$\Delta V_{o,ESR} = \Delta i_{L_x} r_C = \left[\frac{V_o \bigg(\frac{1}{2} - D \bigg)}{L_x f} \right] r_C$$

Figure 4: Push Pull Formulas

$$SwitchUtilization = \frac{Po}{Psw} = \frac{Io.Vo}{q.Vswmax.Iswmax}$$
 (1)

$$V_{o} = V_{s} \left(\frac{D}{1 - D}\right) \qquad \Delta V_{C_{1}} = \frac{I_{o}DT}{C} = \frac{V_{o}D}{RC_{1}f}$$

$$\Delta i_{L_{1}} = \frac{V_{s}DT}{L_{1}} = \frac{V_{s}D}{L_{1}f} \qquad \Delta V_{o} = \Delta V_{C_{2}} = \frac{V_{o}D}{RC_{2}f}$$

$$\Delta i_{L_{2}} = \frac{V_{s}DT}{L_{2}} = \frac{V_{s}D}{L_{2}f} \qquad C_{1} = \frac{D}{R(\Delta V_{C_{1}}/V_{o})f}$$

$$C_{2} = \frac{D}{R(\Delta V_{o}/V_{o})f}$$

Figure 5: Sepic Converter Formulas

$$\begin{split} V_o &= -V_s \bigg(\frac{D}{1-D} \bigg) \, \Bigg| \, \frac{\Delta V_o}{V_o} &= \frac{1-D}{8L_2C_2f^2} \\ \Delta v_{C_1} &\approx \frac{1}{C_1} \int\limits_{DT}^T I_{L_1} d(t) = \frac{I_{L_1}}{C_1} (1-D)T = \frac{V_s}{RC_1f} \bigg(\frac{D^2}{1-D} \bigg) \\ \Delta v_{C_1} &\approx \frac{V_oD}{RC_1f} \\ \\ \Delta i_{L1} &= \frac{V_sDT}{L_1} = \frac{V_sD}{L_1f} \, \Bigg| \, \Delta i_{L2} = \frac{V_sDT}{L_2} = \frac{V_sD}{L_2f} \\ \\ L_{1, \min} &= \frac{(1-D)^2R}{2Df} \quad L_{2, \min} = \frac{(1-D)R}{2f} \end{split}$$

Figure 6: Cuk Converter Formulas

Switch Selection

Peak Switch Current

$$\hat{I}_{sw} = rac{1}{(1-D)} rac{N_2}{N_1} I_o + rac{N_1}{N_2} rac{(1-D)T_s}{2L_m} V_o$$

Peak Switch Voltag

$$\hat{V}_{sw} = V_d + rac{N_1}{N_2} V_o = rac{V_d}{(1-D)}$$

Figure 7: Flyback switch considerations

Figure 8: Full and Half Bridge Relations

Inverters

$$\begin{split} m_f &= \frac{f_s}{f_1}, m_a = \frac{V_{control}}{V_{triangle}} \\ m_a &< 1: linear, m_a > 1: overmodulation \end{split}$$

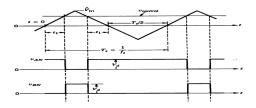


Figure 9: Bipolar Switching

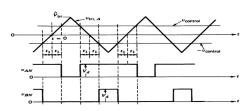


Figure 10: Unipolar switching