## Cheat Sheet for EE464

## **Performance Parameters**

$$FormFactor = \frac{V_{rms}}{V_{avg}}$$
 
$$CrestFactor = \frac{V_{peak}}{V_{rms}}$$
 
$$DistortionFactor = \frac{I_{1rms}}{I_{rms}}$$

 $\phi$ : phase difference between fundamentals of current and voltage  $DisplacementPowerFactor = \cos(\phi)$ 

$$TruePowerFactor = \frac{P}{S} = DPF \frac{I_{1,RMS}}{I_{RMS}}$$
 
$$THD = \sqrt{(\frac{I_{rms}}{I_{1rms}})^2 - 1}$$

Symmetry	Condition Required	$a_h$ and $b_h$
Even	f(-t) = f(t)	$b_h = 0$ $a_h = \frac{2}{\pi} \int_0^{\pi} f(t) \cos(h\omega t) d(\omega t)$
Odd	f(-t) = -f(t)	$a_h = 0$ $b_h = \frac{2}{\pi} \int_0^{\pi} f(t) \sin(h\omega t) d(\omega t)$
Half-wave	$f(t) = -f(t + \frac{1}{2}T)$	$a_h = b_h = 0 \text{ for even } h$ $a_h = \frac{2}{\pi} \int_0^{\pi} f(t) \cos(h\omega t) d(\omega t) \text{ for odd } h$ $b_h = \frac{2}{\pi} \int_0^{\pi} f(t) \sin(h\omega t) d(\omega t) \text{ for odd } h$

Figure 1: Fourier Transform Table

## **Switch Selection**

Peak Switch Current

$$\hat{I}_{sw} = rac{1}{(1-D)} rac{N_2}{N_1} I_o + rac{N_1}{N_2} rac{(1-D)T_s}{2L_m} V_o$$

Peak Switch Voltage

$$\hat{V}_{sw} = V_d + rac{N_1}{N_2} V_o = rac{V_d}{(1-D)}$$

Figure 2: Flyback switch considerations

$$\begin{bmatrix} V_o = V_s \bigg( \frac{D}{1-D} \bigg) \bigg( \frac{N_2}{N_1} \bigg) \\ \end{bmatrix} \begin{bmatrix} \frac{\Delta V_o}{V_o} = \frac{D}{RCf} \end{bmatrix} (L_m)_{\min} = \frac{(1-D)^2 R}{2f} \bigg( \frac{N_1}{N_2} \bigg)^2 \\ I_{L_{m,\max}} = I_{L_m} + \frac{\Delta i_{L_m}}{2} \\ = \frac{V_s D}{(1-D)^2 R} \bigg( \frac{N_2}{N_1} \bigg)^2 + \frac{V_s DT}{2L_m} \Big|_{\substack{b \in \mathbb{N} \\ 0 \neq 0 \\ 0 \neq 0}} \begin{vmatrix} \widehat{L}_m \\ \widehat{J}_m \end{vmatrix} = \frac{V_s D}{\Delta i_{L_m}} f \\ I_{L_{m,\min}} = I_{L_m} - \frac{\Delta i_{L_m}}{2} & \text{equate this to zero for drm boundary} \\ = \frac{V_s D}{(1-D)^2 R} \bigg( \frac{N_2}{N_1} \bigg)^2 - \frac{V_s DT}{2L_m} \Big|_{\substack{b \in \mathbb{N} \\ 0 \neq 0 \\ 0 \neq 0}} \begin{vmatrix} \widehat{J}_m \\ \widehat{J}_m \end{vmatrix} = \frac{V_s D}{N_1} \\ \begin{bmatrix} \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \end{vmatrix} = \frac{V_s D}{N_1} \\ \begin{bmatrix} \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ N_2 \end{bmatrix} = \frac{V_s D}{N_1} \\ \begin{bmatrix} \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ N_2 \end{bmatrix} = \frac{V_s D}{N_1} \\ \begin{bmatrix} \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ N_2 \end{bmatrix} = \frac{V_s D}{N_1} \\ \begin{bmatrix} \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ N_2 \end{bmatrix} = \frac{V_s D}{N_1} \\ \begin{bmatrix} \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ N_2 \end{bmatrix} = \frac{V_s D}{N_1} \\ \begin{bmatrix} \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ N_2 \end{bmatrix} = \frac{V_s D}{N_1} \\ \begin{bmatrix} \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ N_2 \end{bmatrix} = \frac{V_s D}{N_1} \\ \begin{bmatrix} \widehat{J}_m \\ N_2 \end{bmatrix} = \frac{V_s D}{N_1} \\ \begin{bmatrix} \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ \widehat{J}_m \\ N_2 \end{bmatrix} = \frac{V_s D}{N_1} \\ \begin{bmatrix} \widehat{J}_m \\ \underbrace{J}_m \\ \widehat{J}_m \\$$

Figure 3: Flyback Formulas

$$\begin{bmatrix} V_o = V_s D \left( \frac{N_2}{N_1} \right) \end{bmatrix} \begin{bmatrix} \frac{\Delta V_o}{V_o} = \frac{1 - D}{8L_x C f^2} \end{bmatrix}$$

$$\Delta V_{o, ESR} = \Delta i_C r_C = \Delta i_{L_x} r_C = \begin{bmatrix} \frac{V_o (1 - D)}{L_x f} \end{bmatrix} r_C$$

$$\Delta i_{L_m} = \frac{V_s DT}{I_{cos}}$$

Figure 4: Forward (single switched) Converter Formulas

$$SwitchUtilization = \frac{Po}{Psw} = \frac{Io.Vo}{q.Vswmax.Iswmax} \qquad (1)$$

$$\begin{bmatrix} V_o = 2V_s \left(\frac{N_S}{N_P}\right) D \end{bmatrix} \begin{bmatrix} \frac{\Delta V_o}{V_o} = \frac{1 - 2D}{32L_x C f^2} \end{bmatrix}$$

$$\Delta V_{o,ESR} = \Delta i_{L_x} r_C = \begin{bmatrix} \frac{V_o \left(\frac{1}{2} - D\right)}{L_x f} \end{bmatrix} r_C$$

Figure 5: Push Pull Formulas

$$\boxed{ V_o = V_s \left( \frac{D}{1 - D} \right) \quad \Delta V_{C_1} = \frac{I_o DT}{C} = \frac{V_o D}{R C_1 f} }$$

$$\Delta i_{L_1} = \frac{V_s DT}{L_1} = \frac{V_s D}{L_1 f} \quad \Delta V_o = \Delta V_{C_2} = \frac{V_o D}{R C_2 f}$$

$$\Delta i_{L_2} = \frac{V_s DT}{L_2} = \frac{V_s D}{L_2 f} \quad C_1 = \frac{D}{R (\Delta V_{C_1} / V_o) f}$$

$$\boxed{ C_2 = \frac{D}{R (\Delta V_o / V_o) f} }$$

Figure 6: Sepic Converter Formulas

$$\begin{split} V_o &= -V_s \bigg( \frac{D}{1-D} \bigg) \, \Bigg| \, \frac{\Delta V_o}{V_o} &= \frac{1-D}{8L_2C_2f^2} \\ \Delta v_{C1} &\approx \frac{1}{C_1} \int\limits_{DT}^{T} I_{L_1} d(t) = \frac{I_{L1}}{C_1} (1-D)T = \frac{V_s}{RC_1f} \bigg( \frac{D^2}{1-D} \bigg) \\ & \qquad \qquad \qquad \Delta v_{C1} \approx \frac{V_oD}{RC_1f} \\ \\ \Delta i_{L1} &= \frac{V_sDT}{L_1} = \frac{V_sD}{L_1f} \, \Bigg| \, \Delta i_{L2} &= \frac{V_sDT}{L_2} = \frac{V_sD}{L_2f} \\ \\ L_{1,\,\text{min}} &= \frac{(1-D)^2R}{2Df} \quad L_{2,\,\text{min}} = \frac{(1-D)R}{2f} \end{split}$$

Figure 7: Cuk Converter Formulas

Figure 8: Full and Half Bridge Relations