Cheat Sheet for EE464

$$FormFactor = rac{V_{rms}}{V_{avg}}$$
 $CrestFactor = rac{V_{peak}}{V_{rms}}$ $DistortionFactor = rac{I_{1rms}}{I_{rms}}$

 ϕ : phase difference between fundamentals of current and voltage $Displacement Power Factor = \cos(\phi)$

$$TruePowerFactor = \frac{P}{S} = DPF \frac{I_{1,RMS}}{I_{RMS}}$$

$$THD = \sqrt{(\frac{I_{rms}}{I_{1rms}})^2 - 1}$$

Converters

Figure 1: Flyback Formulas

$$\begin{bmatrix} V_o = V_s D \bigg(\frac{N_2}{N_1} \bigg) & \frac{\Delta V_o}{V_o} = \frac{1 - D}{8L_x C f^2} \\ \Delta V_{o, \text{ESR}} = \Delta i_C r_C = \Delta i_{L_x} r_C = \bigg[\frac{V_o (1 - D)}{L_x f} \bigg] r_C \\ \Delta i_{L_m} = \frac{V_s D T}{L_m}$$

Figure 2: Forward (single switched) Converter Formulas

$$\begin{bmatrix} V_o = 2V_s \left(\frac{N_S}{N_P}\right) D \end{bmatrix} \begin{bmatrix} \frac{\Delta V_o}{V_o} = \frac{1 - 2D}{32L_x C f^2} \end{bmatrix}$$

$$\Delta V_{o,ESR} = \Delta i_{L_x} r_C = \begin{bmatrix} \frac{V_o(\frac{1}{2} - D)}{L_x f} \end{bmatrix} r_C$$

Figure 3: Push Pull Formulas

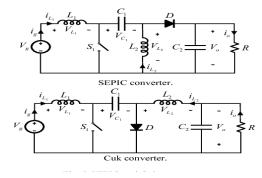


Figure 4: Sepic and Cuk Converter Schematics

$$SwitchUtilization = \frac{Po}{Psw} = \frac{Io.Vo}{q.Vswmax.Iswmax}$$

$$m_f = \frac{f_s}{f_1}, m_a = \frac{V_{control}}{V_{triangle}}$$

$$\begin{bmatrix} V_o = V_s \left(\frac{D}{1 - D} \right) \end{bmatrix} \Delta V_{C_1} = \frac{I_o D T}{C} = \frac{V_o D}{R C_1 f}$$

$$\Delta i_{L_1} = \frac{V_s D T}{L_1} = \frac{V_s D}{L_1 f} \begin{bmatrix} \Delta V_o = \Delta V_{C_2} = \frac{V_o D}{R C_2 f} \end{bmatrix}$$

$$\Delta i_{L_2} = \frac{V_s D T}{L_2} = \frac{V_s D}{L_2 f} \begin{bmatrix} C_1 = \frac{D}{R (\Delta V_{C_1} / V_o) f} \end{bmatrix}$$

$$C_2 = \frac{D}{R (\Delta V_o / V_o) f}$$

Figure 5: Sepic Converter Formulas

$$\begin{split} \boxed{ V_o = -V_s \bigg(\frac{D}{1-D} \bigg) } & \boxed{ \frac{\Delta V_o}{V_o} = \frac{1-D}{8L_2C_2f^2} } \\ \Delta v_{C1} \approx \frac{1}{C_1} \int_{DT}^{T} I_{L1} d(t) = \frac{I_{L1}}{C_1} (1-D)T = \frac{V_s}{RC_1f} \bigg(\frac{D^2}{1-D} \bigg) } \\ & \boxed{ \Delta v_{C1} \approx \frac{V_oD}{RC_1f} } \\ \Delta i_{L1} = \frac{V_sDT}{L_1} = \frac{V_sD}{L_1f} & \boxed{ \Delta i_{L2} = \frac{V_sDT}{L_2} = \frac{V_sD}{L_2f} } \\ \hline \\ L_{1, \min} = \frac{(1-D)^2R}{2Df} & L_{2, \min} = \frac{(1-D)R}{2f} \end{split}$$

Figure 6: Cuk Converter Formulas

Switch Selection

Dook Switch Current

$$\hat{I}_{sw} = rac{1}{(1-D)}rac{N_2}{N_1}I_o + rac{N_1}{N_2}rac{(1-D)T_s}{2L_m}V_o$$

Peak Switch Voltag

$$\hat{V}_{sw} = V_d + rac{N_1}{N_2} V_o = rac{V_d}{(1-D)}$$

Figure 7: Flyback switch considerations

Figure 8: Full and Half Bridge Relations

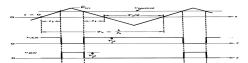


Figure 9: Bipolar Switching

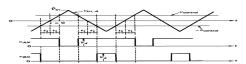


Figure 10: Unipolar switching

 $m_a < 1: linear, m_a > 1: overmodulation$

$$(V_o)_h = \frac{1}{\sqrt{2}} \cdot 2 \cdot \frac{V_d}{2} \frac{(\hat{V}_{Ao})_h}{V_{d}/2} = \frac{V_d}{\sqrt{2}} \frac{(\hat{V}_{Ao})_h}{V_{d}/2}$$

Figure 11: Rms Voltage of Harmonics Full Bridge Inverter

Cuk Converter

(1)

$$Vc1 = Vo + Vd \tag{2}$$

Transformer Analysis

$$V_{rms} = \frac{2\pi}{\sqrt{2}} . N_2 . f. B_{max} . A$$
 (3)

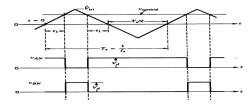


Figure 12: Bipolar Switching

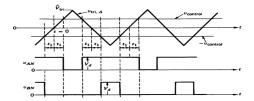


Figure 13: Unipolar switching