CSCI 3308 Software Development Methods and Tools Project Final Submission

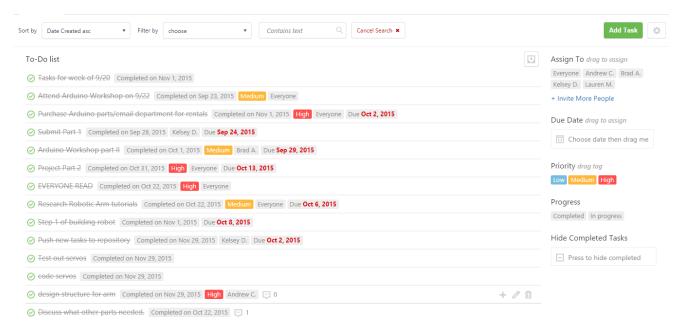
Title: Robotic Arm

Who: Bradley Arnot

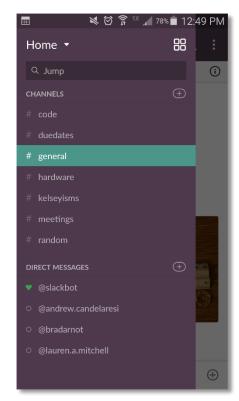
Andrew Candelaresi Kelsey Dowd Lauren Mitchell

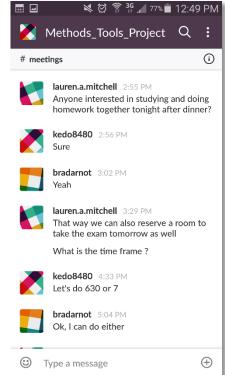
Project Tracking Software: Freedcamp, and Slack for communication https://freedcamp.com/Laurens Projects Dz5/Software Method 3iw/todos

In order to gain access to our Freedcamp, we have invited you to make an account and view our project tracker. If this doesn't work, we also exported our tasks to an excel document and that is also on GitHub, titled exported list of project tracker tasks.



Freedcamp screenshot: part of our ToDo list





Some example Slack screenshots: Left are all of our channels, Right is an example conversation

Video:

Final Demo Video: https://www.youtube.com/watch?v=jfNERC8yszY
The rest of the videos for our project are on the video document on github.

Deployment: Since this is a hardware project, you need to have the robot arm assembled to use it. Once you have the robot, you can plug it in to use it. You must plug in both the power to the Arduino and the power to the shield (explained in the demo video). Finally, the Arduino code is already uploaded to the Arduino, but if the user would like to change the code or functionality of the robot, they must download and install the Arduino IDE (open source), and use the adafruit PWM shield library.

Auto-documentation: For auto-documentation, we used Doxygen.

Link to HTML: http://htmlpreview.github.io/?https://github.com/candeladd/Methods-

Tools_ProjectFall2015/blob/master/Source_Code/docs/html/index.html

Link to PDF: https://github.com/candeladd/Methods-

Tools ProjectFall2015/blob/master/Source Code/docs/latex/refman.pdf

VCS: github

https://github.com/candeladd/Methods-Tools_ProjectFall2015.git

Kelsey's commits: kedo8480 Brad's commits: arcticwaffle Lauren's commits: laurenmitchell Andrew's commits: candeladd

