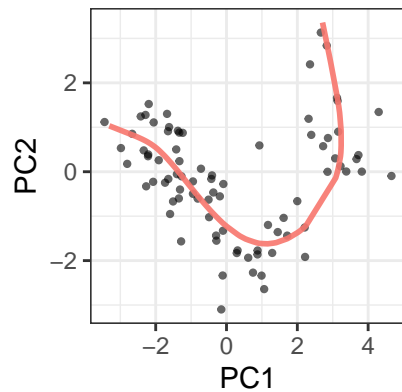
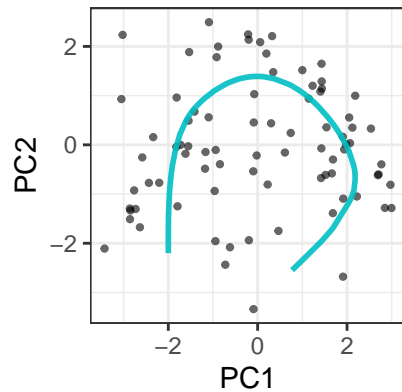


Trajectories X and Y



Trajectory Y aligned to X

