	Fields institute mini-course: Lecture #3
	Numerical methods for the ID Schroedinger - Poisson equation
	material?
	Equations material ?
	Z_{A} $Z \rightarrow Z_{S}$
	Σ <u>μ</u> (, '))
	X(2) = dielectric factor - piecewise constant, constant over each layer
	ØB(2) = bondshift - piecewise constant, constant over each layer
	$\frac{d \times 12) d \otimes p = -\beta_{D}(2) \otimes \beta_{D}(2) = \beta_{A} \otimes \beta_{D}(2) = \beta_{B} \beta_{D} = fixed$ $\frac{d \times 12) d \otimes p = -\beta_{D}(2) \otimes \beta_{D}(2) = \beta_{A} \otimes \beta_{D}(2) = \beta_{B} \beta_{D} = fixed$ $\frac{d \times 12) d \otimes p = -\beta_{D}(2) \otimes \beta_{D}(2) = \beta_{A} \otimes \beta_{D}(2) = \beta_{B} \beta_{D} = fixed$ $\frac{d \times 12) d \otimes p = -\beta_{D}(2) \otimes \beta_{D}(2) = \beta_{A} \otimes \beta_{D}(2) = \beta_{B} \beta_{D} = fixed$ $\frac{d \times 12) d \otimes \beta_{D}(2) \otimes \beta_{D}(2) = \beta_{D}(2) \otimes \beta_{D}(2) \otimes \beta_{D}(2) = \beta_{D}(2) \otimes \beta_{D}(2)$
	$\frac{d \times (2)}{d7} \frac{d \hat{\phi}}{d7} = -g_{e}(2) \tilde{\phi}(7A) = 0 \tilde{\phi}(7B) = 0$
	$\phi(\mathfrak{T}) = \phi(\mathfrak{T}) + \phi_{\mathfrak{D}}(\mathfrak{T}) + \phi_{\mathfrak{F}}(\mathfrak{T})$
_	Pe(7): discontinuitles the to \$\phi_{\beta}\$
	Me(7) = effective mass - piecewise constant, constant over each layer
	$\frac{1}{2} \left[\frac{d}{dz} \left(\frac{1}{m_{e}(z)} \frac{d}{dz} \right) + \left[\frac{\sqrt{p}(z)}{\varphi(z)} + \varphi_{D}(z) + \varphi_{B}(z) \right] \right] \psi_{j} = \lambda_{j} \psi_{j}$
_	$Pe(2) = 2 \frac{2}{5} + \frac{1}{5}(2) + \frac{1}{5}(2$
	'J'-+ ZTh

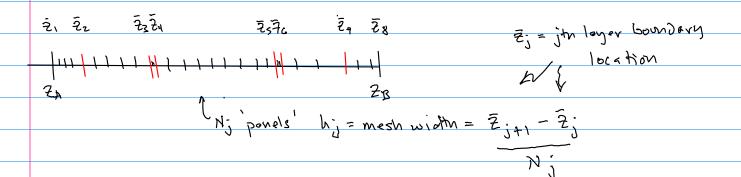
First computational task. Solve problems of the form

$$\frac{d}{dt}\left(\alpha(t)\frac{du}{dt}\right) = f(t) u(t) = gA u(t) = gB aut) pieurise constant.$$

General approach: set up a linear system of equations whose solution gives volves that approximate the exact sulvition volves.

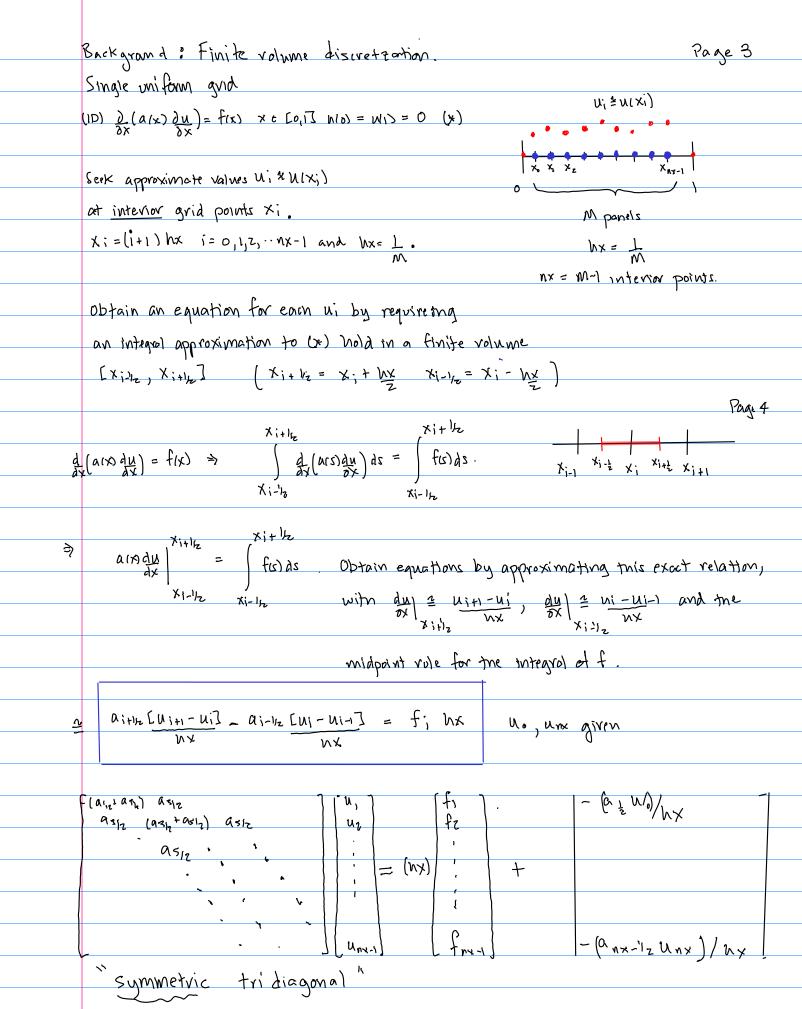
Derive the discrete equations using a simple, but very aseful technique finite volume discretization".

Grid: Uniform mesh with N; panols the jth layer

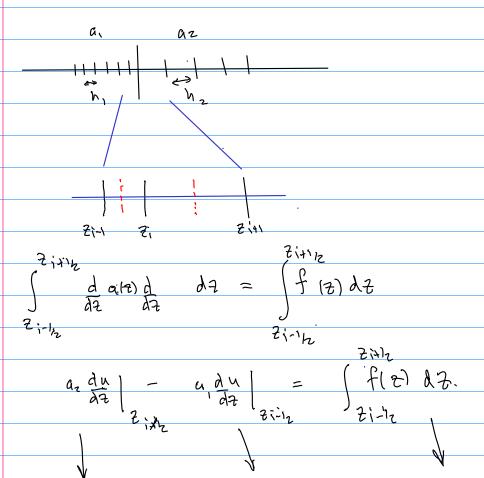


Why a semi-uniform grid?

Some problems consist of a mixture of very thin levers and very thick loyers; we don't wont a small mesh width in the Thin loyers to dictate the wesh widths in all the other layers.



What changes have to be made when one is using a semi-uniform mesh? The only change has to to with the creation of the equations at points that are loyer boundaries. ?



$$a_{z}\left(\frac{u_{ixi}-u_{i}}{v_{z}}\right) - a_{i}\left(\frac{u_{i}-u_{i-1}}{v_{i}}\right) \stackrel{?}{=} f(z_{i})\left(\frac{u_{a}+v_{b}}{z}\right)$$

This leads to a system of equations that is symmetric tri-diagonal, which, when one includes the modification of the right hand side that is due to the boundary conditions, has the form

So, solution procedure for $\frac{1}{12} \times (2)^2 \phi = \rho \quad \phi(7c) = g_a \quad o(7c) = g_b$

(1) Construct matrices associated with the discrete approximation obtained using finite volume based discretizations.

(2) Given g, form $g^{2} = Dg - \begin{bmatrix} x_{1} & d_{1}x_{4} \\ h_{1} \\ h_{2} \end{bmatrix}$ Volve forcing term. $k_{1} d_{1}x_{4} = k_{2} d_{1}x_{4} = k_{3} d_{4}x_{4} = k_{4} d_{5}x_{4} = k_{4} d_{5}x_{4} = k_{5} d_{5}x_{5} = k_{5} d_{5$

(3) Solve $\downarrow \phi = \rho$ to obtain $\phi : \phi = \phi (z_i)$.

Note: L is symmetric tri-diagonal so using a standard tri-diagonal solver, L\$\vec{d} = \hat{g}^* can be obtained in O(n) operations

Where n = dimension of L. (edls the solver)

Low you.

In Malab ar Octore, use phi = L \ p Stor
or, you can write your own tri-diagonal solver (a typical expectse
grown in numerical analysis alosses)

A significant point: When setting up linear systems of equations that are discrete approximations to self-adjoint operators, one strives to anouse techniques so that the resulting metrix problem is symmetric. In finite elements, this is automotic, but using finite difference methods its not.