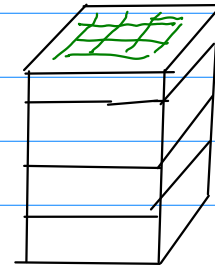


Fields institute mini-course : Lecture 2

"Numerical techniques for simulating collective and coherent quantum states"
Chris Anderson (UCLA Department of Mathematics)

"dimension reduction."

Schroedinger - Poisson.



periodic
or infinite.

(0) Determine ϕ_D such that

in transverse
directions.

$$\Delta_x \phi_D = -\rho_D \quad \phi_D(z_A) = g_A(x, y) \quad \phi_D(z_B) = g_B(x, y)$$

(1) Determine $\tilde{\phi}(\vec{x})$, $\rho_e(\vec{x})$ so that

$$\Delta_k \tilde{\phi} = -\rho_e \quad \tilde{\phi}(z_A) = 0 \quad \tilde{\phi}(z_B) = 0$$

$$\left[\Delta_m + [\tilde{\phi} + \phi_D + \phi_B] \right] \psi_j = \lambda_j \psi_j$$

$$\rho_e(\vec{x}) = \sum_{|\lambda_j - E_F|} \psi_j^2(\vec{x}) \psi_j(x)$$

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Tasks require solving 3D Poisson problems and 3D eigensystem problems.

For some problems - notably those in which the potential applied at the gates is constant, or only depends on one coordinate, e.g.

$g_{A,B}(x, y) = \text{constant}$ or $g_{A,B}(x, y) = g_{A,B}(y)$ one can reduce the dimensionality of the tasks to 2D or 1D computational work. With such boundary conditions one can create solutions of the 3D problem by combining analytical solutions with 1D or 2D computational work.

(I) When g_A, g_B are constant and uniform, and $\rho_D(x, y, z) = \rho_D(z)$ (domain periodic)
 ϕ_B : only a function of z

ϕ_D : only a function of z and satisfies

$$\frac{d}{dz} \kappa(z) \frac{d\phi_D}{dz} = -\rho_D(z) \quad \phi(z_A) = g_A \quad \phi(z_B) = g_B.$$

$\tilde{\phi}$: only a function of z (assume ρ_e is only a function of z) and satisfies

$$\frac{d}{dz} \kappa(z) \frac{d\tilde{\phi}}{dz} = -\rho_e(z) \quad \tilde{\phi}(z_A) = 0 \quad \tilde{\phi}(z_B) = 0$$

So 1D Poisson problems.

What about Schrodinger's equation? Assume ϕ only a function of \vec{z} .

$$-\frac{\hbar^2}{2} \left[\frac{\partial}{\partial z} \left(\frac{1}{m_r(z)} \frac{\partial}{\partial z} \right) + \frac{1}{m_r(z)} \frac{\partial^2}{\partial y^2} + \frac{1}{m_r(z)} \frac{\partial^2}{\partial x^2} \right] \psi_j + \phi(z) \psi_j = \lambda_j \psi_j$$

A separable operator \Rightarrow eigenfunctions are given by products of eigenfunctions of x, y, z separately.

$$\psi_j(x, y, z) = \alpha_p(z) \beta_g(y) \gamma_r(x)$$

$$\lambda_j = \lambda_p + \lambda_g + \lambda_r$$

Note:
 $m_r(z)$ is
 constant in
 each layer

(*) $\left\{ \begin{aligned} -\frac{\hbar^2}{2m_r(z)} \frac{d^2 \beta_g}{dy^2} &= \lambda_g \beta_g(y) \end{aligned} \right.$

$$-\frac{\hbar^2}{2m_r(z)} \frac{d^2 \gamma_r}{dx^2} = \lambda_r \gamma_r(x).$$

$$\left[-\frac{\hbar^2}{2} \frac{d}{dz} \left(\frac{1}{m_r(z)} \frac{d}{dz} \right) + \phi(z) \right] \alpha_p(z) = \lambda_p \alpha_p(z)$$

Why? Plug in formally, factor out $\alpha_p(z) \beta_g(y) \gamma_r(x)$ to verify eigenfunctions.

Assume periodic with domain size L .

Since eigenfunctions of (x) are $\beta(y) = \frac{e^{i \pm \sqrt{\lambda_g \frac{\hbar^2}{2m_r}} y}}{\sqrt{L}}$ $\gamma_r(x) = \frac{e^{i \pm \sqrt{\lambda_r \frac{\hbar^2}{2m_r}} x}}{\sqrt{L}}$

$$\Rightarrow \beta_g^*(y) \beta_g(y) = 1 \quad \text{and} \quad \gamma_r^*(x) \gamma_r(x) = 1$$

$$\infty \quad \psi_j^* \psi_j = \underbrace{(\alpha_p^*(z) \alpha_p(z)) (\beta_g^*(y) \beta_g(y)) (\gamma_r^*(x) \gamma_r(x))}_{\text{constant}} = \text{only a function of } z.$$

∞ ρ_e is only a function of z , e.g. $\rho_e = \rho_e(z)$.

Computation of $\rho_e(z)$?

Compute eigenvalues and eigenvectors of

$$\left[-\frac{\hbar^2}{2} \frac{d}{dz} \left(\frac{1}{m_r(z)} \frac{d}{dz} \right) + \phi(z) \right] \alpha_p(z) = \lambda_p \alpha_p(z)$$

$\beta(y)$'s, $\gamma(x)$'s unit L^2 norm

$$\rho_e(z) = \sum_{\lambda_p < E_f} \alpha_p^*(z) \alpha_p(z) \left(\sum_{\lambda_g + \lambda_r < E_f - \lambda_p} 1 \right)$$

In the limit as the periodic domain size \nearrow as then one gets.

$$\rho_e(z) = \sum_{\lambda_p < E_f} \alpha_p^*(z) \alpha_p(z) \cdot \underbrace{\left[\frac{1}{2\pi \hbar^2} m_r(z) \right]}_{\text{"density of states"}} (E_f - \lambda_p)$$

• If uniform g_A, g_B, ρ_D and the transverse domain is periodic or infinite \Rightarrow 1D Schrodinger - Poisson.

(0) Determine $\phi_D(z)$ so that

$$\frac{d}{dz} \kappa(z) \frac{d}{dz} \phi_D = -\rho_D(z) \quad \phi_D(z_A) = g_A \quad \phi_D(z_B) = g_B$$

(1) Determine $\tilde{\phi}(z), \rho_e(z)$ so that

$$\frac{d}{dz} \kappa(z) \frac{d}{dz} \tilde{\phi} = -\rho_e(z) \quad \tilde{\phi}(z_A) = 0 \quad \tilde{\phi}(z_B) = 0$$

$$-\frac{\hbar^2}{2} \frac{d}{dz} \frac{1}{m_r(z)} \frac{d}{dz} \alpha(z) = \lambda_p \alpha(z) \quad \alpha(z_A) = \alpha(z_B) = 0$$

$$\rho_e(z) = \sum_{\lambda_p < E_F} \alpha_p^*(z) \alpha_p(z) \cdot W(\lambda_p, E_F)$$

\uparrow weight factor due to energy contributions of transverse eigenfunctions.

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1D tasks for the solution of a 3D problem.

The dimension reduction is not obtained by 'averaging' over the transverse direction - it's obtained by using an analytic solution in the transverse directions.

Similarly if g_A, g_B only vary in one of the transverse directions then one only needs to compute the electrostatics and eigensystems for 2D problems.

= 2D Schrodinger - Poisson.

Building up simulation capability.

3D Schroedinger - Poisson \approx $\left. \begin{array}{l} \text{1D Poisson} \\ \text{1D Eigensystem} \end{array} \right\} \text{1D Schroedinger Poisson.}$
 $+$
 2D analytic solution.

3D Schroedinger - Poisson \approx $\left. \begin{array}{l} \text{2D Poisson} \\ \text{2D Eigensystem} \end{array} \right\} \text{2D Schroedinger Poisson.}$
 $+$
 1D analytic solution.

3D Schroedinger - Poisson \approx $\left. \begin{array}{l} \text{3D Poisson} \\ \text{3D Eigensystem} \end{array} \right\}$

DFT (Density Functional Theory) \approx $\left. \begin{array}{l} \text{3D Poisson} \\ \text{3D Eigensystem} \end{array} \right\}$

FCI (Full Configuration Interaction) \approx $\left. \begin{array}{l} \text{3D Poisson} \\ \text{3D Eigensystem} \end{array} \right\}$
 using Slater determinant wave functions.

1D? Useful for many problems

Executes quickly

A good place to start learning about numerical techniques

2D? 1D \rightarrow 2D, there are things to know about going from 1D \rightarrow 2D eigenproblems.

3D? You typically focus on computational efficiency.