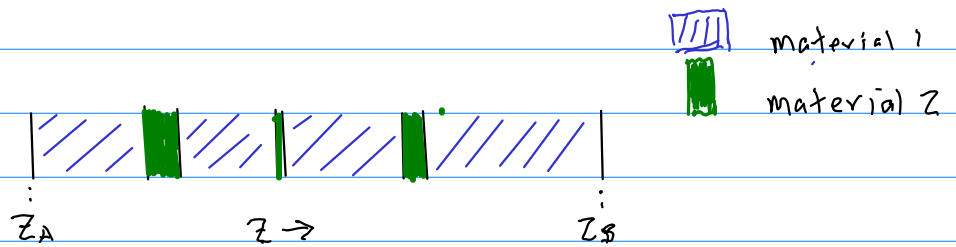


Fields institute mini-course : Lecture #3

Numerical methods for the 1D Schrodinger - Poisson equation

Equations



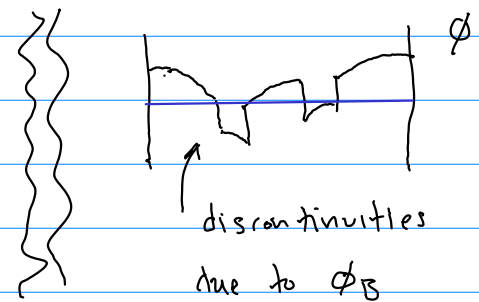
$\chi(z)$ = dielectric factor - piecewise constant, constant over each layer

$\phi_B(z)$ = "bandshift" - piecewise constant, constant over each layer

$$\frac{d}{dz} \chi(z) \frac{d}{dz} \phi_D = -\rho_D(z) \quad \phi_D(z_A) = q_A \quad \phi_D(z_B) = q_B \quad \rho_D = \text{fixed charge}$$

$$\frac{d}{dz} \chi(z) \frac{d}{dz} \tilde{\phi} = -\rho_e(z) \quad \tilde{\phi}(z_A) = 0 \quad \tilde{\phi}(z_B) = 0$$

$$\phi(z) = \tilde{\phi}(z) + \phi_D(z) + \phi_B(z)$$



$\rho_e(z)$:

$m_e(z)$ = effective mass - piecewise constant, constant over each layer

$$-\frac{\hbar^2}{2} \left[\frac{d}{dz} \left(\frac{1}{m_e(z)} \frac{d}{dz} \right) + [\tilde{\phi}(z) + \phi_D(z) + \phi_B(z)] \right] \psi_j = \lambda_j \psi_j$$

$$\rho_e(z) = \sum_{\lambda_j < E_f} \psi_j^*(z) \psi_j(z) W(\lambda_j, E_f) \quad \left\{ (E_f - \lambda_j) \frac{m_r(z)}{2\pi\hbar^2} \right.$$

First computational task.

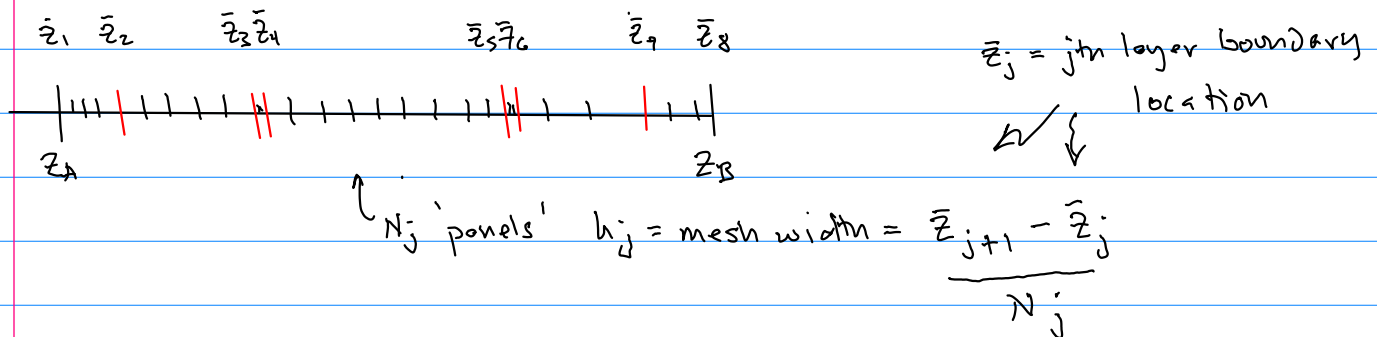
Solve problems of the form

$$\frac{d}{dz} \left(a(z) \frac{du}{dz} \right) = f(z) \quad u(z_A) = g_A \quad u(z_B) = g_B \quad a(z) \text{ piecewise constant.}$$

General approach: set up a linear system of equations whose solution gives values that approximate the exact solution values.

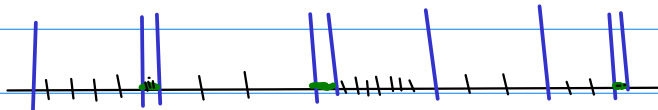
Derive the discrete equations using a simple, but very useful technique "finite volume discretization".

Grid: Uniform mesh with N_j panels the j th layer



Why a semi-uniform grid?

Some problems consist of a mixture of very thin layers and very thick layers; we don't want a small mesh width in the thin layers to dictate the mesh widths in all the other layers.



Background: Finite volume discretization.

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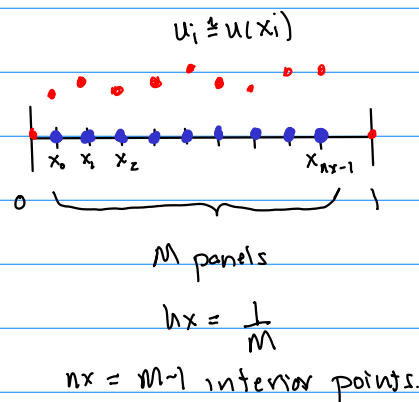
Single uniform grid

$$(1D) \frac{\partial}{\partial x} (a(x) \frac{\partial u}{\partial x}) = f(x) \quad x \in [0,1] \quad u(0) = u(1) = 0 \quad (*)$$

Seek approximate values $u_i \approx u(x_i)$

at interior grid points x_i .

$$x_i = (i+1)h_x \quad i = 0, 1, 2, \dots, n_x-1 \quad \text{and} \quad h_x = \frac{1}{n_x}.$$

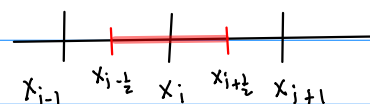


Obtain an equation for each u_i by requiring an integral approximation to $(*)$ hold in a finite volume

$$[x_{i-1/2}, x_{i+1/2}] \quad \left(x_{i+1/2} = x_i + \frac{h_x}{2} \quad x_{i-1/2} = x_i - \frac{h_x}{2} \right)$$

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$$\frac{d}{dx} (a(x) \frac{du}{dx}) = f(x) \Rightarrow \int_{x_{i-1/2}}^{x_{i+1/2}} \frac{d}{dx} (a(x) \frac{du}{dx}) dx = \int_{x_{i-1/2}}^{x_{i+1/2}} f(x) dx.$$



$$\Rightarrow a(x) \frac{du}{dx} \Big|_{x_{i-1/2}}^{x_{i+1/2}} = \int_{x_{i-1/2}}^{x_{i+1/2}} f(x) dx.$$

Obtain equations by approximating this exact relation, with $\frac{du}{dx} \Big|_{x_{i+1/2}} \approx \frac{u_{i+1} - u_i}{h_x}$, $\frac{du}{dx} \Big|_{x_{i-1/2}} \approx \frac{u_i - u_{i-1}}{h_x}$ and the

midpoint rule for the integral of f .

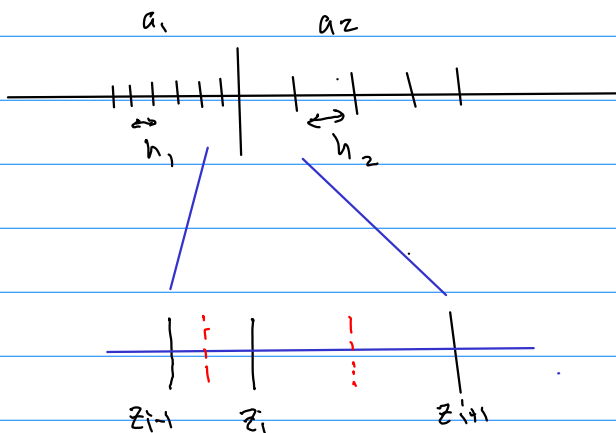
$$\boxed{a_{i+1/2} \frac{u_{i+1} - u_i}{h_x} - a_{i-1/2} \frac{u_i - u_{i-1}}{h_x} = f_i h_x} \quad u_0, u_{n_x} \text{ given}$$

$$\begin{bmatrix} (a_{1/2} + a_{3/2}) & a_{3/2} & & & \\ a_{3/2} & (a_{3/2} + a_{5/2}) & a_{5/2} & & \\ & a_{5/2} & \ddots & \ddots & \\ & & \ddots & \ddots & a_{n_x-1/2} \\ & & & & a_{n_x-1/2} \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_{n_x-1} \end{bmatrix} = (h_x) \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_{n_x-1} \end{bmatrix} + \begin{bmatrix} -(a_{1/2} u_0)/h_x \\ \\ \\ -(a_{n_x-1/2} u_{n_x})/h_x \end{bmatrix}$$

"symmetric tri diagonal"

What changes have to be made when one is using a semi-uniform mesh?

The only change has to do with the creation of the equations at points that are lower boundaries.



$$\int_{z_{i-1/2}}^{z_{i+1/2}} \frac{d}{dz} a(z) \frac{du}{dz} dz = \int_{z_{i-1/2}}^{z_{i+1/2}} f(z) dz$$

$$\Rightarrow a_2 \left. \frac{du}{dz} \right|_{z_{i+1/2}} - a_1 \left. \frac{du}{dz} \right|_{z_{i-1/2}} = \int_{z_{i-1/2}}^{z_{i+1/2}} f(z) dz$$

$$a_2 \left(\frac{u_{i+1} - u_i}{h_2} \right) - a_1 \left(\frac{u_i - u_{i-1}}{h_1} \right) \approx f(z_i) \left(\frac{h_1}{2} + \frac{h_2}{2} \right)$$

This leads to a system of equations that is symmetric tri-diagonal, which, when one includes the modification of the right hand side that is due to the boundary conditions, has the form

$$\begin{bmatrix} \ddots & & 0 \\ & \ddots & \\ 0 & & \ddots \end{bmatrix} \vec{u} = D \vec{f} - \vec{f}_{\text{bary}} \quad D = \begin{bmatrix} n_1 h_1 & & \\ & n_2 h_2 & \\ & & \ddots \\ & & & n_N h_N \end{bmatrix}$$

due to the change in mesh sizes.

So, solution procedure for

$$\frac{d}{dz} \kappa(z) \frac{d}{dz} \phi = f \quad \phi(z_a) = g_a \quad \phi(z_b) = g_b$$

- (1) Construct matrices associated with the discrete approximation obtained using finite volume based discretizations.

Grid specification \leadsto L (tri-diagonal matrix)
 $+ \quad D$ (diagonal matrix of mesh weights).

$\kappa(z)$

(2) Given f , form $f^* = Df - \begin{bmatrix} \kappa_1 \frac{d\phi(z_a)}{dz} \\ n_1 \\ 0 \\ \vdots \\ 0 \\ \kappa_m \phi(z_b) \end{bmatrix}$ \swarrow Boundary value forcing term.

$\underbrace{\hspace{10em}}_{h_m}$

(3) Solve $L \vec{\phi} = f^*$ to obtain $\phi; \hat{=} \phi(z_i)$.

Note: L is symmetric tri-diagonal so using a standard tri-diagonal solver, $L \vec{\phi} = f^*$ can be obtained in $O(n)$ operations where $n = \text{dimension of } L$.

\swarrow (calls the solver for you.)

In Matlab or Octave, use $\phi = L \setminus f^*$ or, you can write your own tri-diagonal solver (a typical exercise given in numerical analysis classes).

A significant point: When setting up linear systems of equations that are discrete approximations to self-adjoint operators, one strives to choose techniques so that the resulting matrix problem is symmetric. In finite elements, this is automatic, but using finite difference methods it's not.