```
; Program pulse probe.s
 3
 4
   5
    ; EQU Directives
    8
    ;LABEL DIRECTIVE VALUE
                              COMMENTS
 9
  10
11 TIMER1 TAMR
19
    TIMER1_TAR
                     EQU 0x40031048; Timer register
20
   ;GPIO Registers
21
22
   GPIO PORTB DATA
                    EQU 0x40005040 ; Access PB4
                   EQU 0x40005400 ; Port Direction
2.3
   GPIO_PORTB_DIR
                   EQU 0x40005420 ; Alt Function enable EQU 0x4000551C ; Digital Enable EQU 0x40005528 ; Analog enable
24
   GPIO_PORTB_AFSEL
25
    GPIO PORTB DEN
26
   GPIO PORTB AMSEL
   GPIO PORTB_PCTL
27
                    EQU 0x4000552C; Alternate Functions
28
29
   ;System Registers
30
    SYSCTL RCGCGPIO
                     EQU 0x400FE608; GPIO Gate Control
                   EQU 0x400FE604 ; GPTM Gate Control
    SYSCTL RCGCTIMER
31
32
   33
   ; LABEL DIRECTIVE VALUE COMMENT
34
                      main, READONLY, CODE
35
              AREA
36
              THUMB
                      My_TimerOA_Handler
PULSE_INIT
37
              EXTERN
                                             ; Reference external subroutines
              EXTERN
                                             ;
                       PULSE PROBE
39
              EXTERN
                        My_Timer1A_Handler
40
              EXTERN
41
              EXTERN
                        CONVRT
42
              EXPORT
                                  ; Make available
                        __main
43
44
     main
                       PULSE INIT
45
              LDR R1, =SYSCTL RCGCGPIO; start GPIO clock
46
              LDR R0, [R1]
47
              ORR R0, R0, \#0x02; set bit 2 for port B
48
              STR R0, [R1]
50
              NOP ; allow clock to settle
51
              NOP
52
              NOP
53
              LDR R1, =GPIO_PORTB_DIR ; set direction of PB4
54
              LDR R0, [R1]
55
              BIC R0, #0x10
                                  ; clear bit 4 for INPUT
              STR R0, [R1]
56
57
58
              LDR R1, =GPIO PORTB AFSEL; enable port function
59
              LDR R0, [R1]
              ORR R0, #0x10
                             ; set bit4 for alternate fuction on PB4
61
              STR R0, [R1]
62
              ; Set bits 27:24 of PCTL to 7 to enable TIMER1A on PB4
63
              LDR R1, =GPIO PORTB PCTL
              LDR R0, [R1]
64
65
              ORR R0, R0, #0x00070000
66
              STR R0, [R1]
           ; clear AMSEL to disable analog
67
              LDR R1, =GPIO_PORTB_AMSEL MOV R0, #0
68
69
70
              STR R0, [R1]
71
72
              LDR R1, =GPIO_PORTB_DEN ; enable port digital
              LDR R0, [R1]
ORR R0, R0, #0x10
73
74
75
              STR R0, [R1]
76
77
              LDR R1, =SYSCTL RCGCTIMER; Start Timer1
```

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```
LDR R2, [R1]
 79
                   ORR R2, R2, \#0\times02
 80
                   STR R2, [R1]
 81
                   {\tt NOP} ; allow clock to settle
 83
                   NOP
 84
 85
                   LDR R1, =TIMER1 CTL; disable timer during setup
 86
                   LDR R2, [R1]
 87
                   BIC R2, R2, #0x01
 88
                   STR R2, [R1]
 89
               ; set to 16bit Timer Mode
 90
                   LDR R1, =TIMER1_CFG
                   MOV R2, \#0x04; set bits 2:0 to 0x04 for 16bit timer
 91
 92
                   STR R2, [R1]
               ; set to EDGE TIME, count DOWN
 94
                   LDR R1, =TIMER1 TAMR
 95
                   MOV R2, \#0x1F
 96
                   STR R2, [R1]
 97
               ; set edge detection to both
                   LDR R1, =TIMER1_CTL
 98
 99
                   LDR R2, [R1]
                   ORR R2, R2, \#0x0E; set bits 3:2 to 0x03
100
101
                   STR R2, [R1]
102
                   LDR R1, =TIMER1 TAPR
103
                   MOV R2, \#15; divide clock by 16 to
104
105
                   STR R2, [R1]; get lus clocks
106
                   ; set start value
107
                   LDR R1, =TIMER1 TAILR
                   LDR R2, =0 \times FFFFFFFFF
108
                   STR R2, [R1]
109
110
111
                   LDR R1, =TIMER1_IMR ; disable timeout interrupt
112
                   MOV R2, \#0x00
113
                   STR R2, [R1]
114
115
     ; Enable timer
                   LDR R1, =TIMER1_CTL
116
                   LDR R2, [R1]

ORR R2, R2, #0x01; set bit0 to enable, bit 1 to stall on debug
117
118
                   STR R2, [R1]; and bit2:3 to trigger on BOTH EDGES
119
120
121
122
                   ; Await edge capture event
                   LDR R1, =TIMER1_RIS
LDR R2, [R1]
123
      loop
124
125
                   ANDS R2, \#0x04; isolate CAERIS bit
126
                   BEQ loop; if no capture, then loop
127
128
                   LDR RO, =GPIO_PORTB_DATA
129
                   LDR R0, [R0]
                   AND R0, #0x10
130
131
                   CMP R0, #0x10
132
                   BNE negedge
133
      _posedge
                   LDR R1, =TIMER1 RIS
134
135
                   LDR R2, [R1]
136
                   ANDS R2, \#0x01; isolate TATORIS bit
137
                   BNE skip
138
139
      skip
                   LDR RO, =TIMER1 TAR
140
                   LDR R0, [R0]
141
                   MOV R11, R0
142
                   ; PULSE WIDTH
143
                   SUB R7, R12, R11
                   PUSH {LR}
144
145
                   BL CONVRT
                   POP {LR}
146
147
                   ; PERIOD
148
                   SUB R7, R11, R0
149
                   PUSH {LR}
150
                   BL CONVRT
151
                   POP {LR}
152
                   ; DUTY CYCLE
                   UDIV R7, R1, R7
153
154
                   MOV R2, #100
```

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```
MUL R7, R2
155
156
                   PUSH {LR}
157
                  BL CONVRT
158
                  POP {LR}
159
160
161
                  В
                      finish
162
163
      _negedge
164
                  LDR R1, =TIMER1_RIS
165
                  LDR R2, [R1]
166
                  ANDS R2, \#0\times01; isolate TATORIS bit
167
                  BNE skip
          ;
168
169
                  LDR RO, =TIMER1_TAR
170
                  LDR R0, [R0]
171
                  MOV R12, R0
172
173
                  LDR RO, =TIMER1_ICR; clear interrupt flag
      finish
                  MOV R1, #0x05
174
175
                  STR R1, [R0]
176
177
                      loop
178
179
                  END
180
181
```