# BLG 336E Analysis of Algorithms II

Lecture 9:

**Dynamic Programming II** 

DNA Sequencing, Knapsack Problem

#### Last time



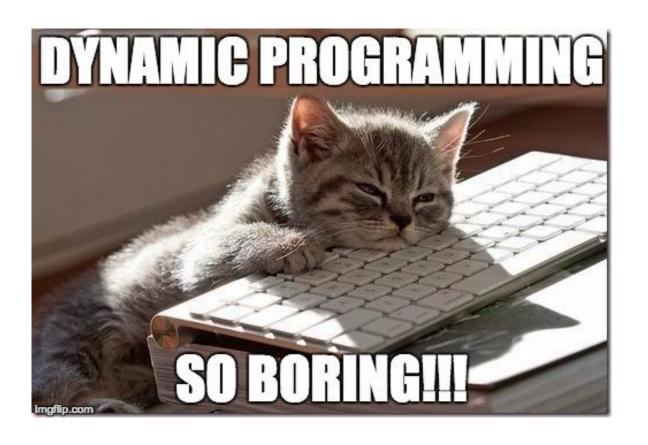
- Dynamic programming is an algorithm design paradigm.
- Basic idea:
  - Identify optimal sub-structure
    - Optimum to the big problem is built out of optima of small sub-problems
  - Take advantage of overlapping sub-problems
    - Only solve each sub-problem once, then use it again and again
  - Keep track of the solutions to sub-problems in a table as you build to the final solution.

## Today

- Examples of dynamic programming:
  - 1. Longest common subsequence
  - 2. Knapsack problem
    - Two versions!
  - 3. Independent sets in trees
    - If we have time...
    - (If not the slides will be there as a reference)

## The goal of this lecture

For you to get really bored of dynamic programming



## Longest Common Subsequence

How similar are these two species?



DNA:

AGCCCTAAGGGCTACCTAGCTT



DNA:
GACAGCCTACAAGCGTTAGCTTG

## Longest Common Subsequence

How similar are these two species?



**AGCCCTAAGGGCTACCTAGCTT** 



Pretty similar, their DNA has a long common subsequence:

**AGCCTAAGCTTAGCTT** 

DNA:

## Longest Common Subsequence

- Subsequence:
  - BDFH is a subsequence of ABCDEFGH
- If X and Y are sequences, a **common subsequence** is a sequence which is a subsequence of both.
  - BDFH is a common subsequence of ABCDEFGH and of ABDFGHI
- A longest common subsequence...
  - ...is a common subsequence that is longest.
  - The longest common subsequence of ABCDEFGH and ABDFGHI is ABDFGH.

#### We sometimes want to find these

Applications in bioinformatics





- The unix command diff
- Merging in version control
  - svn, git, etc...

```
[DN0a22a660:~ mary$ cat file1
[DN0a22a660:~ mary$ cat file2
[DN0a22a660:~ mary$ diff file1 file2
3d2
5d3
DN0a22a660:~ mary$ ■
```

### Recipe for applying Dynamic Programming

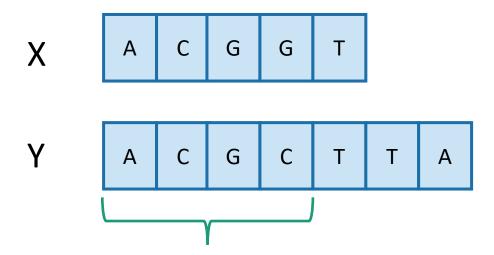
• Step 1: Identify optimal substructure.



- Step 2: Find a recursive formulation for the length of the longest common subsequence.
- Step 3: Use dynamic programming to find the length of the longest common subsequence.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual LCS.
- Step 5: If needed, code this up like a reasonable person.

## Step 1: Optimal substructure

#### Prefixes:



**Notation**: denote this prefix **ACGC** by Y<sub>4</sub>

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let C[i,j] = length\_of\_LCS(X<sub>i</sub>, Y<sub>i</sub>)

## Optimal substructure ctd.

- Subproblem:
  - finding LCS's of prefixes of X and Y.
- Why is this a good choice?
  - There's some relationship between LCS's of prefixes and LCS's of the whole things.
  - These subproblems overlap a lot.

To see this formally, on to...

## Recipe for applying Dynamic Programming

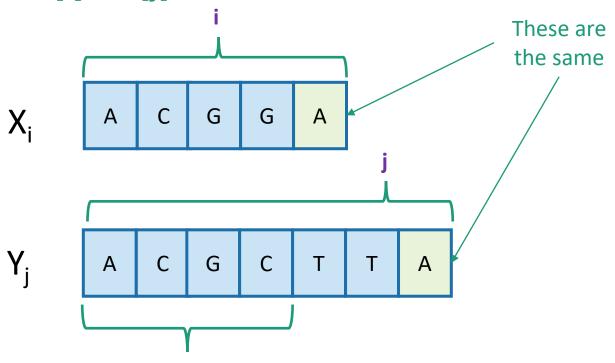
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#### Two cases

Case 1: X[i] = Y[j]

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let C[i,j] = length\_of\_LCS(X<sub>i</sub>, Y<sub>j</sub>)



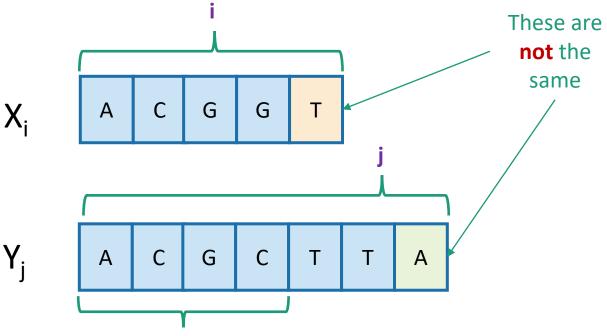
**Notation**: denote this prefix **ACGC** by Y<sub>4</sub>

- Then C[i,j] = 1 + C[i-1,j-1].
  - because  $LCS(X_i,Y_j) = LCS(X_{i-1},Y_{j-1})$  followed by

#### Two cases

Case 2: X[i] != Y[j]

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let C[i,j] = length\_of\_LCS(X<sub>i</sub>, Y<sub>i</sub>)



**Notation**: denote this prefix **ACGC** by Y<sub>4</sub>

- Then C[i,j] = max{ C[i-1,j], C[i,j-1] }.
  - either  $LCS(X_i,Y_j) = LCS(X_{i-1},Y_j)$  and  $\top$  is not involved,
  - or  $LCS(X_i,Y_i) = LCS(X_i,Y_{i-1})$  and A is not involved,

# Recursive formulation of the optimal solution

•  $C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$ 

X<sub>i</sub> A C G G A

Y<sub>i</sub> A C G C T T A

Case 1

X<sub>i</sub> A C G G T

Case 2

## Recipe for applying Dynamic Programming

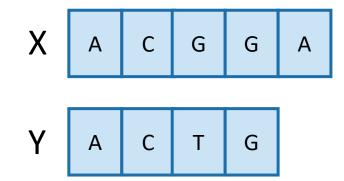
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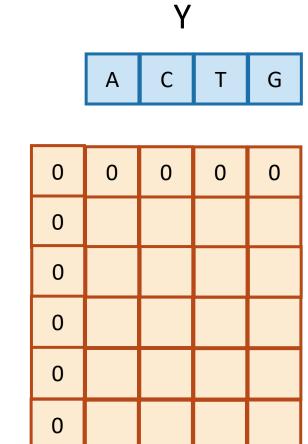
#### LCS DP omg bbq

- LCS(X, Y):
  - C[i,0] = C[0,j] = 0 for all i = 1,...,m, j=1,...n.
  - **For** i = 1,...,m and j = 1,...,n:
    - **If** X[i] = Y[j]:
      - C[i,j] = C[i-1,j-1] + 1
    - Else:
      - C[i,j] = max{ C[i,j-1], C[i-1,j] }

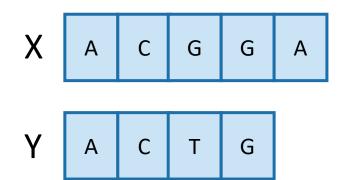
Running time: O(nm)

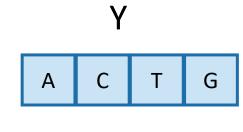
$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$





$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$





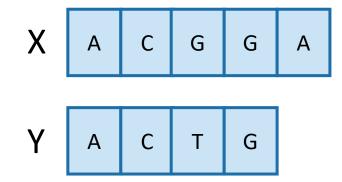
0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

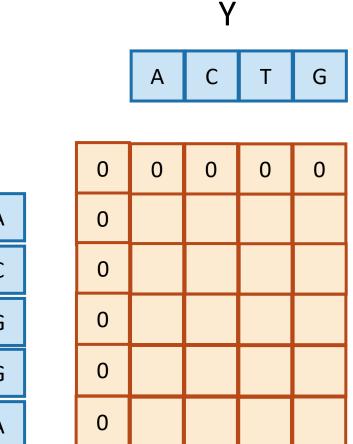
So the LCM of X and Y has length 3.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1]+1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

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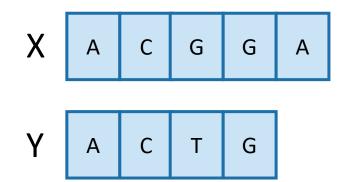
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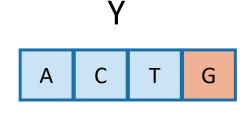
X A C G G A
Y A C T G

Y				
Α	С	Т	G	

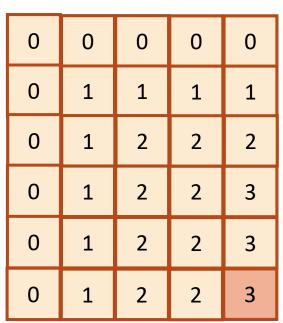
0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
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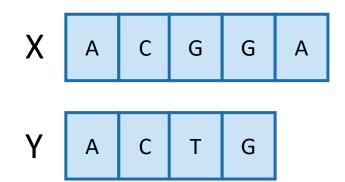


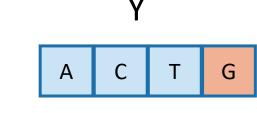


 Once we've filled this in, we can work backwards.



$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1]+1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$



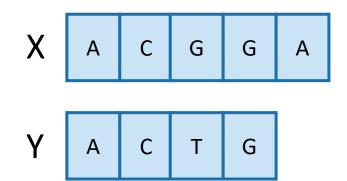


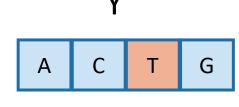
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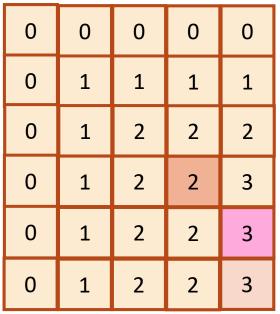
0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

That 3 must have come from the 3 above it.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$







- Once we've filled this in, we can work backwards.
- A diagonal jump means that we found an element of the LCS!

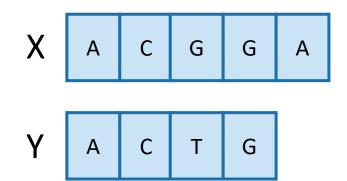
This 3 came from that 2 – we found a match!

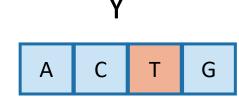
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C X G

G

Α

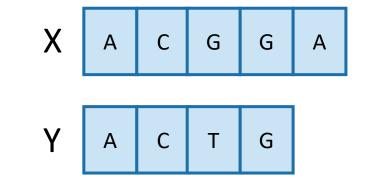


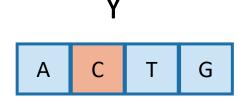


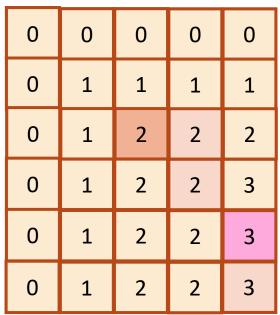
- Once we've filled this in, we can work backwards.
- A diagonal jump means that we found an element of the LCS!

That 2 may as well have come from this other 2.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1]+1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$



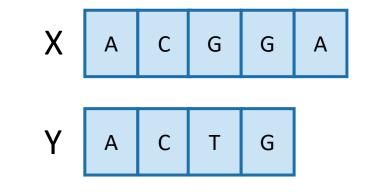


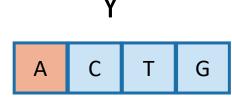


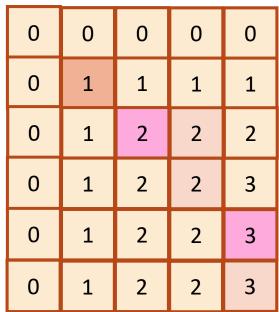
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G

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1]+1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$







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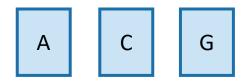
C G

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- C

- Once we've filled this in, we can work backwards.
- A diagonal jump means that we found an element of the LCS!



This is the LCS!

G

G

Α

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1],C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

This gives an algorithm to recover the actual LCS not just its length

- It runs in time O(n + m)
  - We walk up and left in an n-by-m array
  - We can only do that for n + m steps.
- So actually recovering the LCS from the table is much faster than building the table was.
- We can find LCS(X,Y) in time O(mn).

### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
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#### This pseudocode actually isn't so bad

- If we are only interested in the length of the LCS:
  - Since we go across the table one-row-at-a-time, we can only keep two rows if we want.
  - If we want to recover the LCS, we need to keep the whole table.
- Can we do better than O(mn) time?
  - A bit better.
    - By a log factor or so.
  - But doing much better (polynomially better) is an open problem!
    - If you can do it let me know:D

#### What have we learned?

- We can find LCS(X,Y) in time O(nm)
  - if |Y|=n, |X|=m
- We went through the steps of coming up with a dynamic programming algorithm.
  - We kept a 2-dimensional table, breaking down the problem by decrementing the length of X and Y.

## Example 2: Knapsack Problem

We have n items with weights and values:

 Item:
 <th

- And we have a knapsack:
  - it can only carry so much weight:



Capacity: 10



Capacity: 10











Weight:

Item:

6

2

4

3

11

Value:

20

8

14

13

35

#### Unbounded Knapsack:

- Suppose I have infinite copies of all of the items.
- What's the most valuable way to fill the knapsack?









Total weight: 10 Total value: 42

#### • 0/1 Knapsack:

- Suppose I have only one copy of each item.
- What's the most valuable way to fill the knapsack?

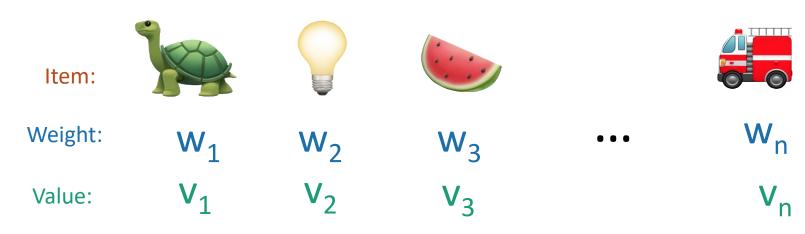






Total weight: 9
Total value: 35

#### Some notation





Capacity: W

• Step 1: Identify optimal substructure.

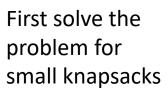


- Step 2: Find a recursive formulation for the value of the optimal solution.
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## Optimal substructure

- Sub-problems:
  - Unbounded Knapsack with a smaller knapsack.







Then larger knapsacks



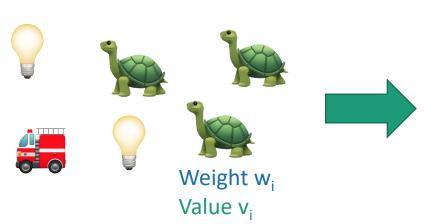
Then larger knapsacks

# Optimal substructure



Suppose this is an optimal solution for capacity x:

Say that the optimal solution contains at least one copy of item i.



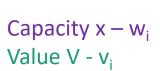


Then this optimal for capacity x - w<sub>i</sub>:





If I could do better than the second solution, then adding a turtle to that improvement would improve the first solution.



- Step 1: Identify optimal substructure.
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## Recursive relationship

• Let K[x] be the optimal value for capacity x.

$$K[x] = \max_i \left\{ \begin{array}{c} + \\ \\ \end{array} \right\}$$
 The maximum is over all i so that  $w_i \leq x$ . Optimal way to fill the smaller knapsack

$$K[x] = \max_{i} \{ K[x - w_{i}] + v_{i} \}$$

- (And K[x] = 0 if the maximum is empty).
  - That is, there are no i so that  $w_i \leq x$

- Step 1: Identify optimal substructure.
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### Let's write a bottom-up DP algorithm

- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
  - return K[W]

Running time: O(nW)

```
K[x] = \max_{i} \{ \left\{ \left[ \mathbf{x} - \mathbf{w}_{i} \right] + \mathbf{v}_{i} \right\}
= \max_{i} \left\{ K[\mathbf{x} - \mathbf{w}_{i}] + \mathbf{v}_{i} \right\}
```

Why does this work?
Because our recursive relationship makes sense.

#### Can we do better?

- We only need log(W) bits to write down the input W and to write down all the weights.
- Maybe we could have an algorithm that runs in time O(nlog(W)) instead of O(nW)?
- Or even O( n<sup>1000000</sup> log<sup>1000000</sup>(W) )?

- Open problem!
  - (But probably the answer is no...otherwise P = NP)

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      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
  - return K[W]

```
K[x] = \max_{i} \{ \left[ \left[ x - w_{i} \right] + \frac{v_{i}}{v_{i}} \right] \}
```

## Let's write a bottom-up DP algorithm

UnboundedKnapsack(W, n, weights, values):

```
• K[0] = 0

• ITEMS[0] = \emptyset

• for x = 1, ..., W:

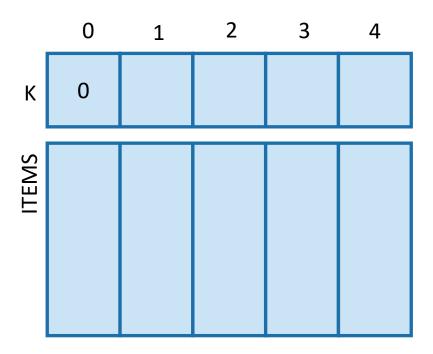
• K[x] = 0

• for i = 1, ..., n:

• if w_i \le x:
```

- $K[x] = \max\{K[x], K[x w_i] + v_i\}$
- If K[x] was updated:
  - ITEMS[x] = ITEMS[x w<sub>i</sub>] U { item i }
- return ITEMS[W]

```
K[x] = \max_{i} \{ || \mathbf{K}[x - \mathbf{w}_{i}] + \mathbf{v}_{i} \}
= \max_{i} \{ |\mathbf{K}[x - \mathbf{w}_{i}] + \mathbf{v}_{i} \}
```

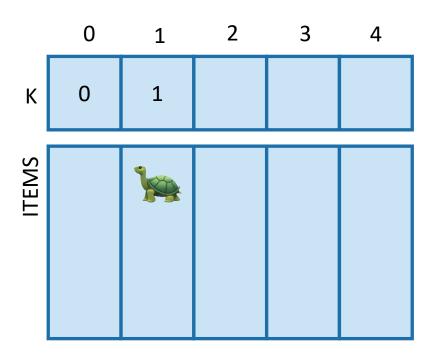


- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - ITEMS $[0] = \emptyset$
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
        - If K[x] was updated:
          - ITEMS[x] = ITEMS[x w<sub>i</sub>] U { item
  - return ITEMS[W]





Capacity: 4

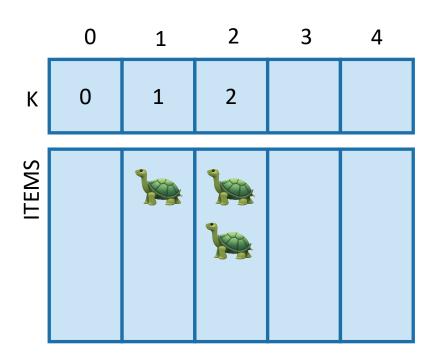


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  - return ITEMS[W]





Capacity: 4

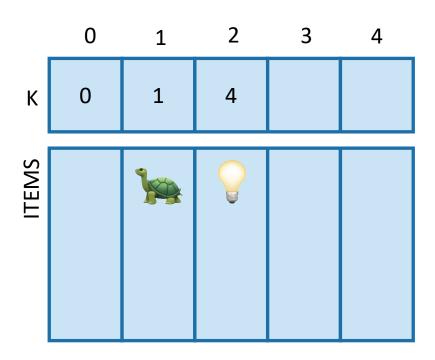


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  - for x = 1, ..., W:
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    - **for** i = 1, ..., n:
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        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
        - If K[x] was updated:
          - ITEMS[x] = ITEMS[x w<sub>i</sub>] U { item
  - return ITEMS[W]





Capacity: 4

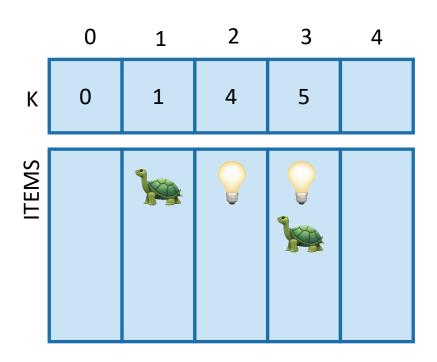


$$ITEMS[2] = ITEMS[0] +$$

- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - ITEMS $[0] = \emptyset$
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
        - If K[x] was updated:
          - ITEMS[x] = ITEMS[x w<sub>i</sub>] U { item
  - return ITEMS[W]





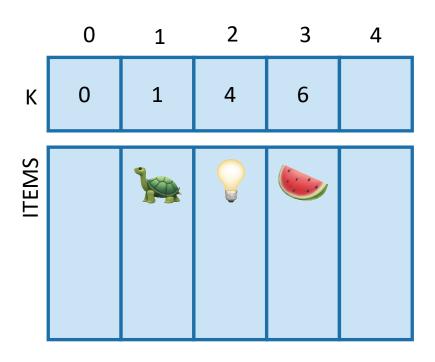


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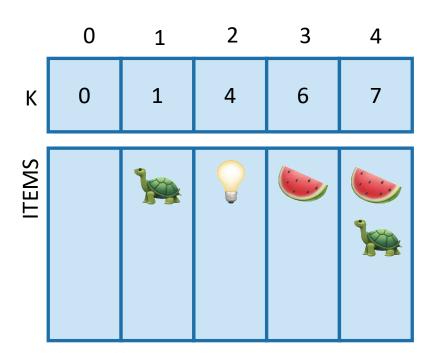
Capacity: 4



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    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
        - If K[x] was updated:
          - ITEMS[x] = ITEMS[x  $w_i$ ] U { item
  - return ITEMS[W]



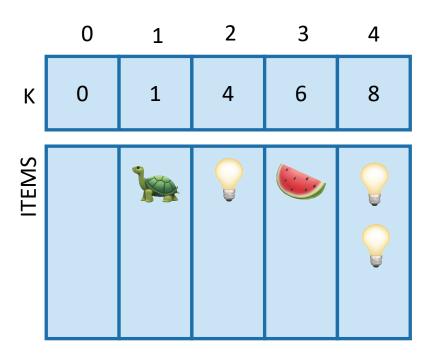




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  - return ITEMS[W]







$$ITEMS[4] = ITEMS[2] +$$

- UnboundedKnapsack(W, n, weights, values):
  - K[0] = 0
  - ITEMS $[0] = \emptyset$
  - for x = 1, ..., W:
    - K[x] = 0
    - **for** i = 1, ..., n:
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x w_i] + v_i\}$
        - If K[x] was updated:
          - ITEMS[x] = ITEMS[x w<sub>i</sub>] U { item
  - return ITEMS[W]





- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

(Pass)

### What have we learned?

- We can solve unbounded knapsack in time O(nW).
  - If there are n items and our knapsack has capacity W.

- We again went through the steps to create DP solution:
  - We kept a one-dimensional table, creating smaller problems by making the knapsack smaller.



Capacity: 10











Weight:

Item:

Value:

20

14

13

35

#### Unbounded Knapsack:

- Suppose I have infinite copies of all of the items.
- What's the most valuable way to fill the knapsack?









Total weight: 10 Total value: 42



#### • 0/1 Knapsack:

- Suppose I have only one copy of each item.
- What's the most valuable way to fill the knapsack?







Total weight: 9 Total value: 35

• Step 1: Identify optimal substructure.

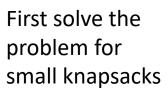


- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

# Optimal substructure: try 1

- Sub-problems:
  - Unbounded Knapsack with a smaller knapsack.







Then larger knapsacks



Then larger knapsacks

# This won't quite work...

- We are only allowed one copy of each item.
- The sub-problem needs to "know" what items we've used and what we haven't.





# Optimal substructure: try 2

• Sub-problems:

• 0/1 Knapsack with fewer items.

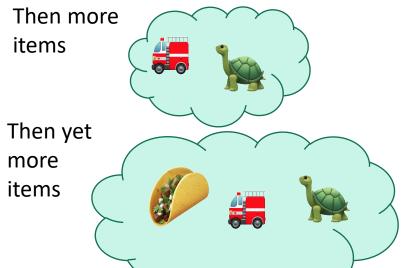




First solve the problem with few items



We'll still increase the size of the knapsacks.



(We'll keep a two-dimensional table).

# Our sub-problems:

Indexed by x and j





Capacity x

#### Two cases



- Case 1: Optimal solution for j items does not use item j.
- Case 2: Optimal solution for j items does use item j.

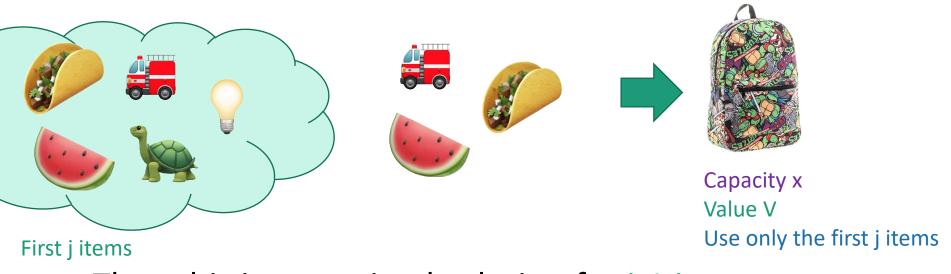


Capacity x

### Two cases



Case 1: Optimal solution for j items does not use item j.



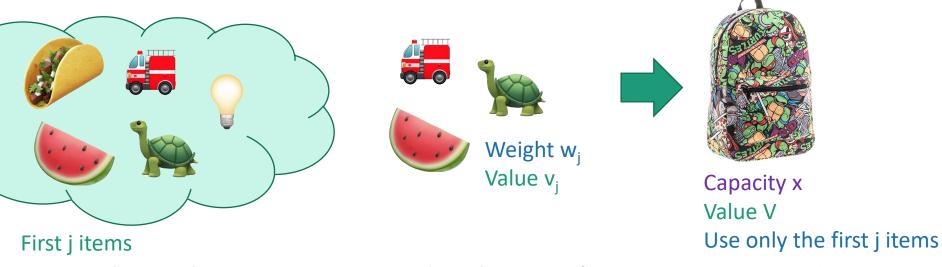
• Then this is an optimal solution for j-1 items:



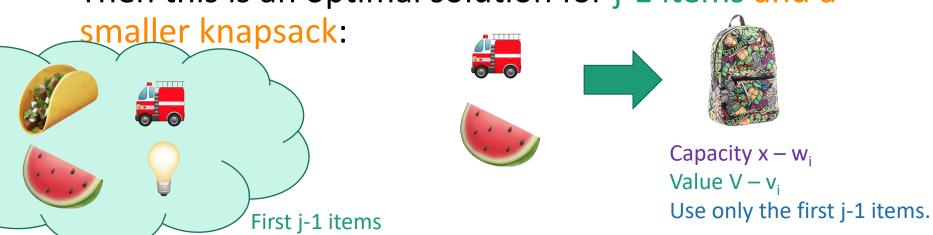
### Two cases



• Case 2: Optimal solution for j items uses item j.



Then this is an optimal solution for j-1 items and a



- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

### Recursive relationship

- Let K[x,j] be the optimal value for:
  - capacity x,
  - with j items.

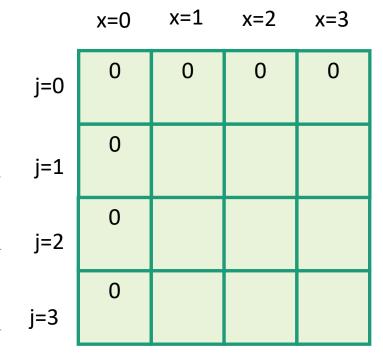
$$K[x,j] = max\{K[x, j-1], K[x - w_{j,} j-1] + v_{j}\}$$
Case 1
Case 2

• (And K[x,0] = 0 and K[0,j] = 0).

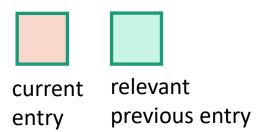
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- Step 5: If needed, code this up like a reasonable person.

## Bottom-up DP algorithm

```
Zero-One-Knapsack(W, n, w, v):
   • K[x,0] = 0 for all x = 0,...,W
   • K[0,i] = 0 for all i = 0,...,n
   • for x = 1,...,W:
       • for j = 1,...,n:
                               Case 1
           • K[x,i] = K[x, i-1]
           • if w_i \leq x:
                                                Case 2
               • K[x,j] = max\{ K[x,j], K[x-w_i, j-1] + v_i \}
   return K[W,n]
```



- Zero-One-Knapsack(W, n, w, v):
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  - K[0,i] = 0 for all i = 0,...,n
  - for x = 1,...,W:
    - **for** j = 1,...,n:
      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
        - $K[x,j] = max\{ K[x,j],$  $K[x - w_{i}, j-1] + v_{i}$
  - return K[W,n]





Weight: Value:







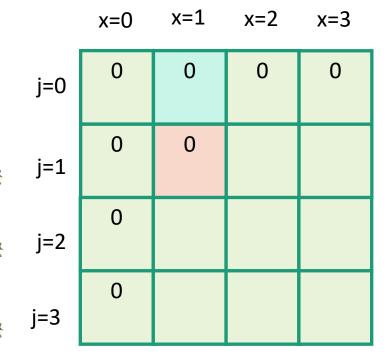
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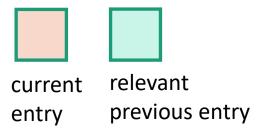


6

Capacity: 3



- Zero-One-Knapsack(W, n, w, v):
  - K[x,0] = 0 for all x = 0,...,W
  - K[0,i] = 0 for all i = 0,...,n
  - for x = 1,...,W:
    - **for** j = 1,...,n:
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      - if  $w_i \le x$ :
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  - return K[W,n]















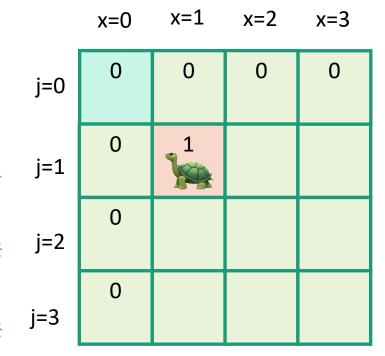




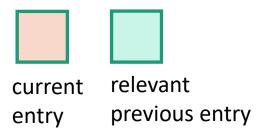
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Capacity: 3



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      - if  $w_i \le x$ :
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  - return K[W,n]











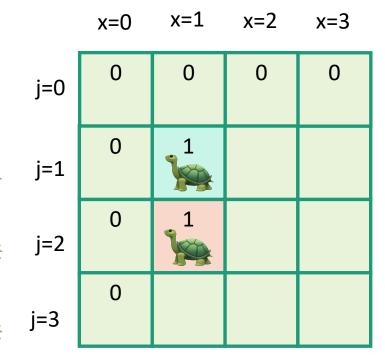
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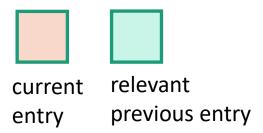


6





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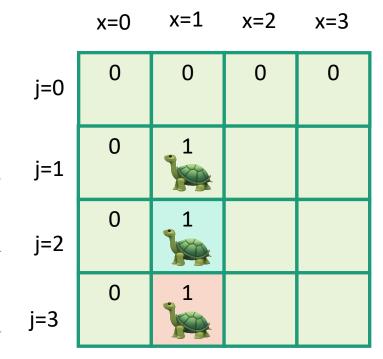


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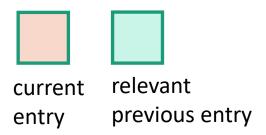
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. 4



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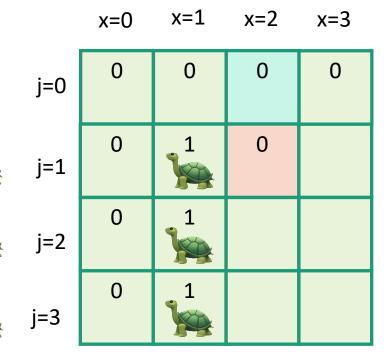


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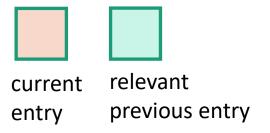




6



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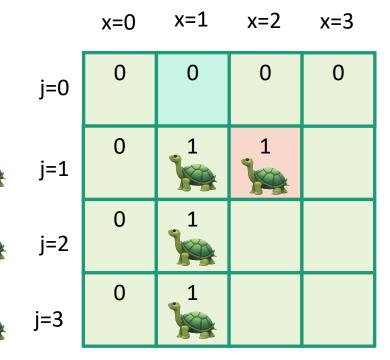


Capacity: 3

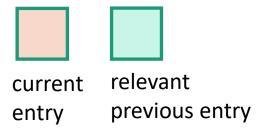
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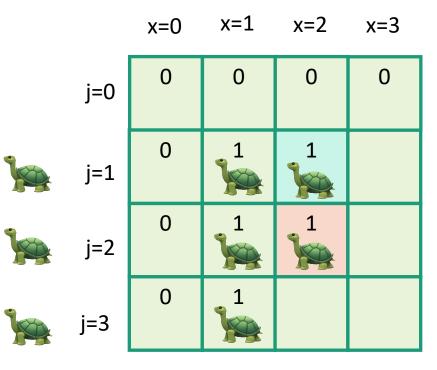




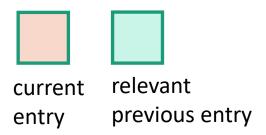
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Capacity: 3



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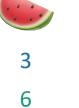




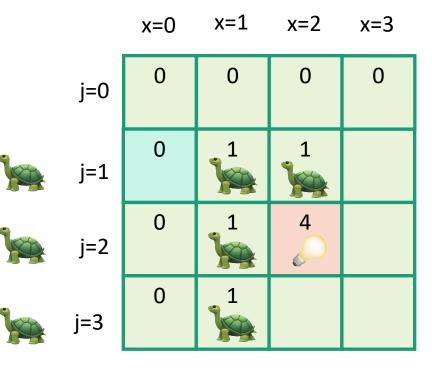


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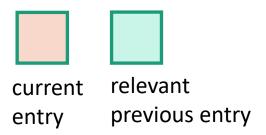








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4

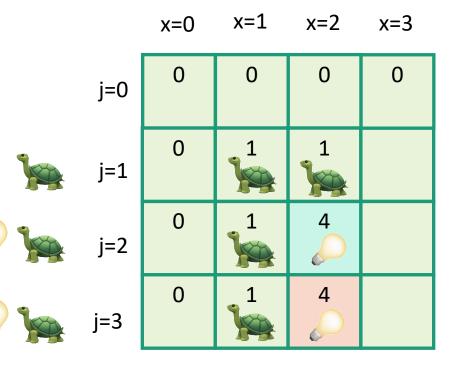




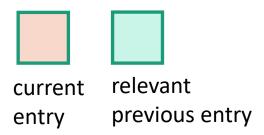
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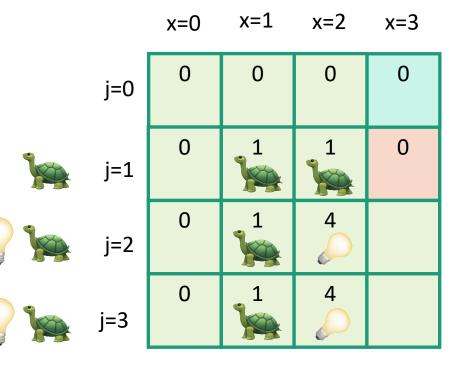


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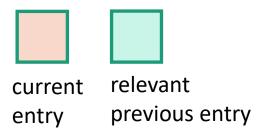








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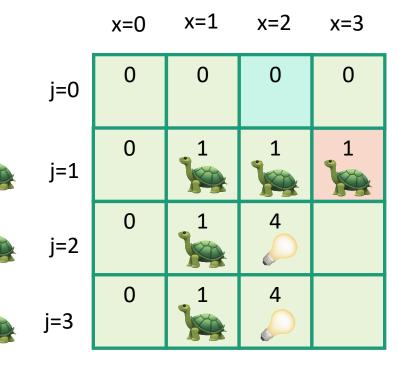
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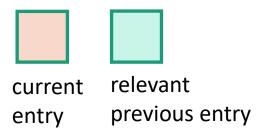




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  - return K[W,n]





Weight: Value:







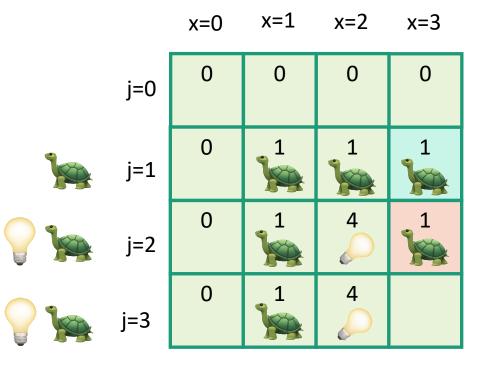
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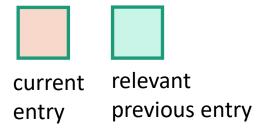




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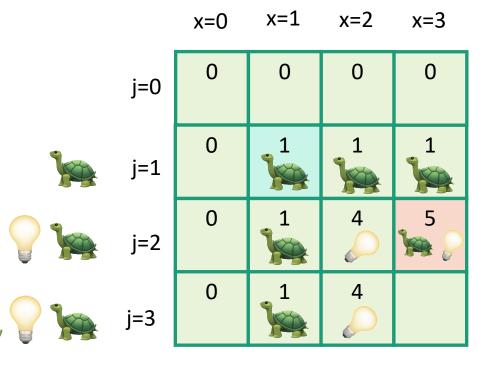




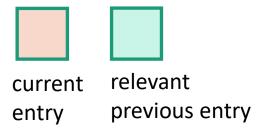
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6

Capacity: 3



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  - K[x,0] = 0 for all x = 0,...,W
  - K[0,i] = 0 for all i = 0,...,n
  - **for** x = 1,...,W:
    - **for** j = 1,...,n:
      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
        - $K[x,j] = max\{K[x,j],$  $K[x - w_{i}, j-1] + v_{i}$
  - return K[W,n]



Item:

Weight:









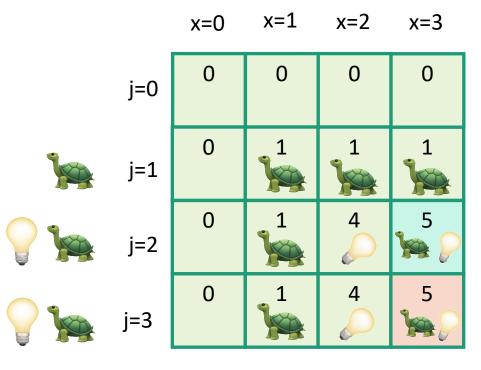




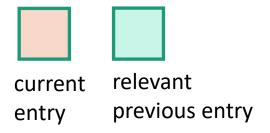
Value:

4

Capacity: 3



- Zero-One-Knapsack(W, n, w, v):
  - K[x,0] = 0 for all x = 0,...,W
  - K[0,i] = 0 for all i = 0,...,n
  - **for** x = 1,...,W:
    - **for** j = 1,...,n:
      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
        - $K[x,j] = max\{K[x,j],$  $K[x - w_{i}, j-1] + v_{i}$
  - return K[W,n]













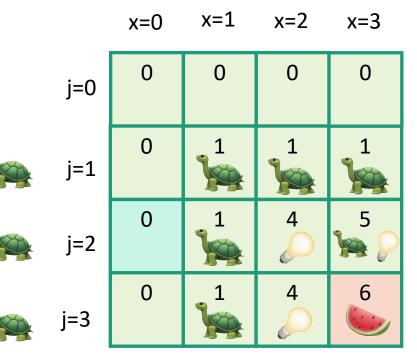




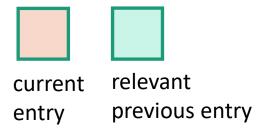


4

Capacity: 3



- Zero-One-Knapsack(W, n, w, v):
  - K[x,0] = 0 for all x = 0,...,W
  - K[0,i] = 0 for all i = 0,...,n
  - **for** x = 1,...,W:
    - **for** j = 1,...,n:
      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
        - $K[x,j] = max\{K[x,j],$  $K[x - w_{i}, j-1] + v_{i}$
  - return K[W,n]











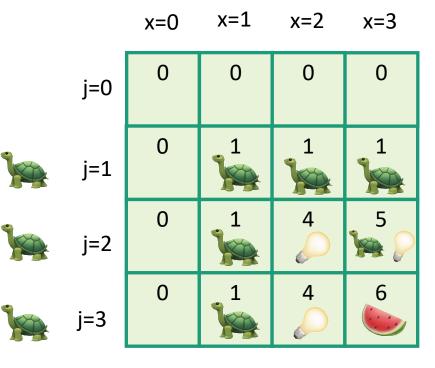


4



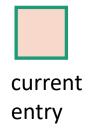


Capacity: 3



- Zero-One-Knapsack(W, n, w, v):
  - K[x,0] = 0 for all x = 0,...,W
  - K[0,i] = 0 for all i = 0,...,n
  - **for** x = 1,...,W:
    - **for** j = 1,...,n:
      - K[x,j] = K[x, j-1]
      - if  $w_i \le x$ :
        - $K[x,j] = max\{K[x,j],$  $K[x - w_i, j-1] + v_i$
  - return K[W,n]

So the optimal solution is to put one watermelon in your knapsack!





relevant previous entry



Weight: Value:













3



Capacity: 3

### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

### What have we learned?

- We can solve 0/1 knapsack in time O(nW).
  - If there are n items and our knapsack has capacity W.

- We again went through the steps to create DP solution:
  - We kept a two-dimensional table, creating smaller problems by restricting the set of allowable items.

### Question

 How did we know which substructure to use in which variant of knapsack?

Answer in retrospect:





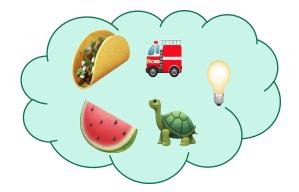


This one made sense for unbounded knapsack because it doesn't have any memory of what items have been used.

VS.





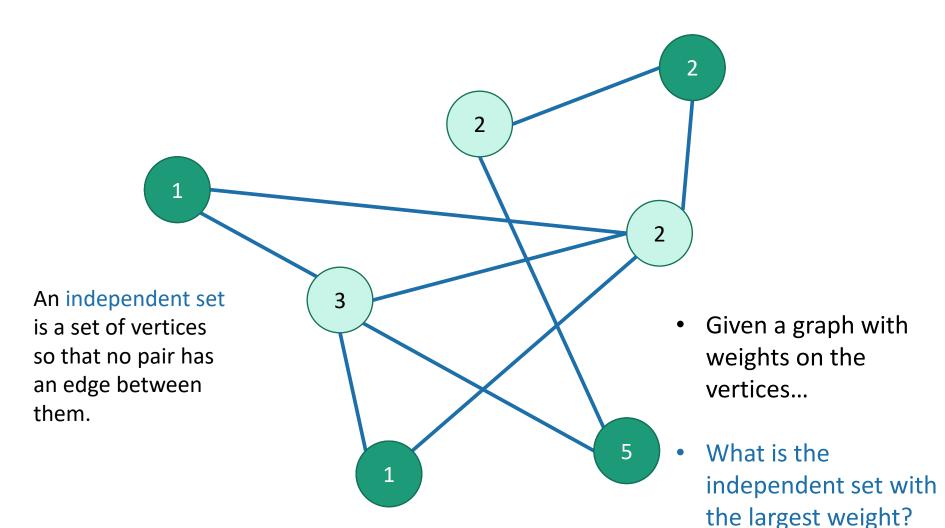


In 0/1 knapsack, we can only use each item once, so it makes sense to leave out one item at a time.

**Operational Answer**: try some stuff, see what works!

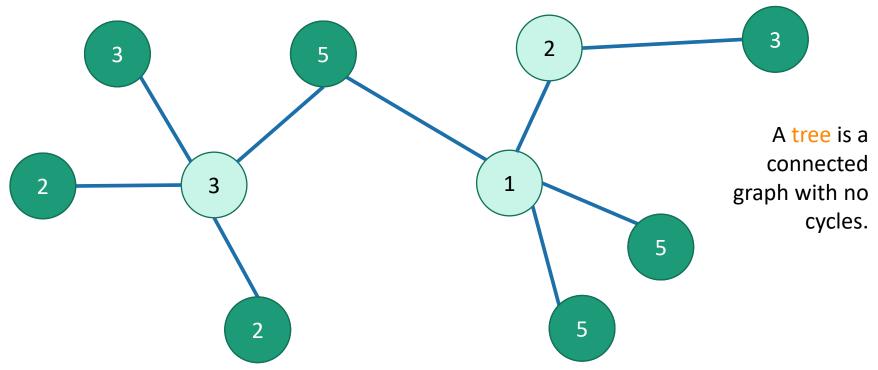
### Example 3: Independent Set

if we still have time



# Actually this problem is NP-complete. So we are unlikely to find an efficient algorithm

But if we also assume that the graph is a tree...



#### **Problem:**

find a maximal independent set in a tree (with vertex weights).

### Recipe for applying Dynamic Programming

• Step 1: Identify optimal substructure.



- Step 2: Find a recursive formulation for the value of the optimal solution
- Step 3: Use dynamic programming to find the value of the optimal solution
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

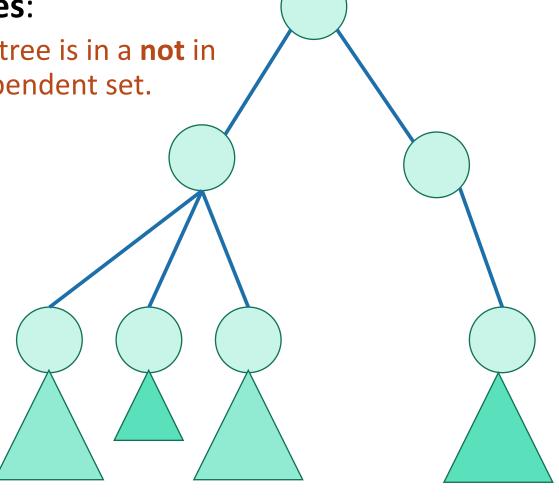
# Optimal substructure

• Subtrees are a natural candidate.



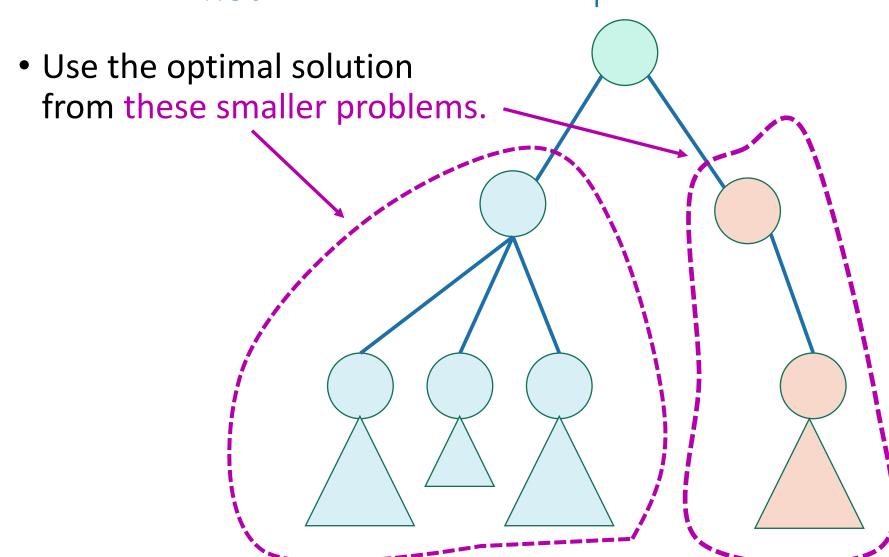
1. The root of this tree is in a **not** in a maximal independent set.

2. Or it is.

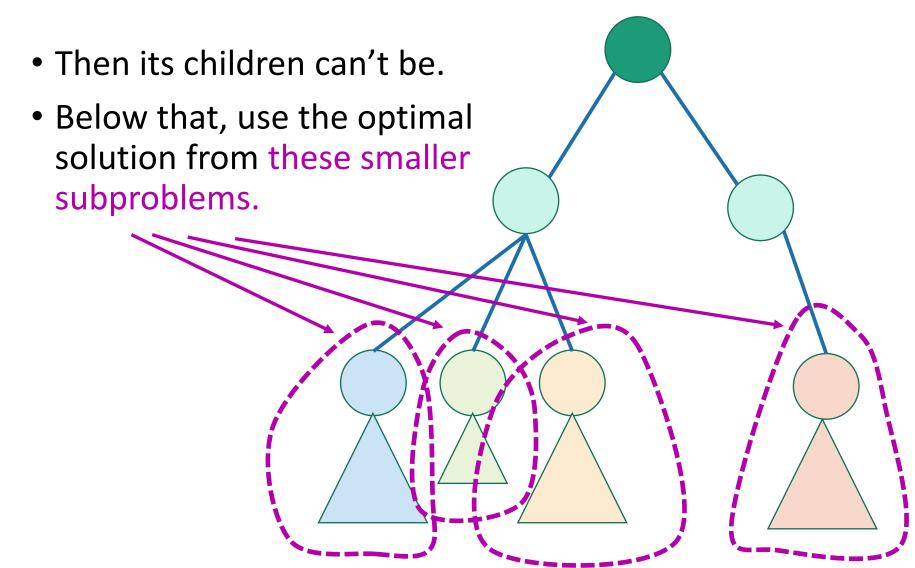


### Case 1:

the root is **not** in an maximal independent set



# Case 2: the root is in an maximal independent set



### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

# Recursive formulation: try 1

• Let A[u] be the weight of a maximal independent set in the tree rooted at u.

• 
$$A[u] = \begin{cases} \sum_{v \in u.\text{children}} A[v] \end{cases}$$

max  $\begin{cases} \text{weight}(u) + \sum_{v \in u.\text{grandchildren}} A[v] \end{cases}$ 

When we implement this, how do we keep track of this term?

# Recursive formulation: try 2

Keep two arrays!

- Let A[u] be the weight of a maximal independent set in the tree rooted at u.
- Let  $B[u] = \sum_{v \in u. \text{children}} A[v]$

• 
$$A[u] = \max \begin{cases} \sum_{v \in u.\text{children}} A[v] \\ \text{weight}(u) + \sum_{v \in u.\text{children}} B[v] \end{cases}$$

### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

# A top-down DP algorithm

- MIS\_subtree(u):
  - if u is a leaf:
    - A[u] = weight(u)
    - B[u] = 0
  - else:
    - **for** v in u.children:
      - MIS\_subtree(v)
    - $A[u] = \max\{\sum_{v \in u, \text{children}} A[v], \text{ weight}(u) + \sum_{v \in u, \text{children}} B[v]\}$
    - $B[u] = \sum_{v \in u.\text{children}} A[v]$
- MIS(T):
  - MIS\_subtree(T.root)
  - return A[T.root]

Initialize global arrays A, B the recursive calls.

#### **Running time?**

- We visit each vertex once, and at every vertex we do O(1) work:
  - Make a recursive call
  - look stuff up in tables
- Running time is O(|V|)

### Why is this different from divide-and-conquer?

That's always worked for us with tree problems before...

- MIS\_subtree(u):
  - if u is a leaf:
    - **return** weight(u)
  - else:
    - **for** v in u.children:
      - MIS\_subtree(v)
    - return max{  $\sum_{v \in u. \text{children}} \text{MIS\_subtree}(v)$ ,

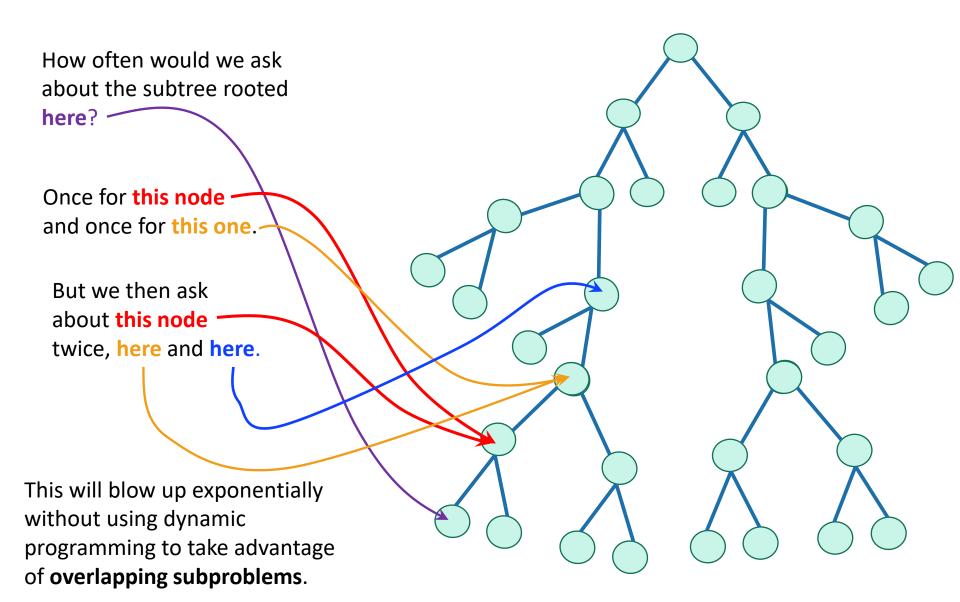
```
weight(u) + \sum_{v \in u.\text{grandchildren}} \text{MIS\_subtree}(v) }
```

- MIS(T):
  - return MIS\_subtree(T.root)

```
This is exactly the same pseudocode, except we've ditched the table and are just calling MIS_subtree(v) instead of looking up A[v] or B[v].
```

### Why is this different from divide-and-conquer?

That's always worked for us with tree problems before...



### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

### What have we learned?

 We can find maximal independent sets in trees in time O(|V|) using dynamic programming!

 For this example, it was natural to implement our DP algorithm in a top-down way.

### Recap

- Today we saw examples of how to come up with dynamic programming algorithms.
  - Longest Common Subsequence
  - Knapsack two ways
  - (If time) maximal independent set in trees.
- There is a **recipe** for dynamic programming algorithms.

### Recipe for applying Dynamic Programming

- Step 1: Identify optimal substructure.
- Step 2: Find a recursive formulation for the value of the optimal solution.
- Step 3: Use dynamic programming to find the value of the optimal solution.
- Step 4: If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- Step 5: If needed, code this up like a reasonable person.

### Recap



- Today we saw examples of how to come up with dynamic programming algorithms.
  - Longest Common Subsequence
  - Knapsack two ways
  - (If time) maximal independent set in trees.
- There is a **recipe** for dynamic programming algorithms.
- Sometimes coming up with the right substructure takes some creativity

# JON KLEINBERG • ÉVA TARDOS

SECTION 6.4

## 6. DYNAMIC PROGRAMMING

- weighted interval scheduling
- segmented least squares
- knapsack problem
- ► RNA secondary structure

Goal. Pack knapsack so as to maximize total value of items taken.

- There are n items: item i provides value  $v_i > 0$  and weighs  $w_i > 0$ .
- Value of a subset of items = sum of values of individual items.
- Knapsack has weight limit of W.
- Ex. The subset  $\{1, 2, 5\}$  has value \$35 (and weight 10).
- Ex. The subset { 3, 4 } has value \$40 (and weight 11).

Assumption. All values and weights are integral.



i	$v_i$	Wi
1	\$1	1 kg
2	\$6	2 kg
3	\$18	5 kg
4	\$22	6 kg
5	\$28	7 kg

weights and values can be arbitrary positive integers

knapsackinstance (weight limit W= 11)



#### Which algorithm solves knapsack problem?

- A. Greedy-by-value: repeatedly add item with maximum  $v_i$ .
- B. Greedy-by-weight: repeatedly add item with minimum  $w_i$ .
- C. Greedy-by-ratio: repeatedly add item with maximum ratio  $v_i/w_i$ .
- D. None of the above.



\$18 5 K9	\$22 6 kg
\$6 2 K9	
\$7 7 K9	\$28 7 K9

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i	$v_i$	$W_i$
1	\$1	1 kg
2	\$6	2 kg
3	\$18	5 kg
4	\$22	6 kg
5	\$28	7 kg

knapsadkinstance (weight limit W= 11)

## Dynamic programming: quiz 3



#### Which subproblems?

- A. OPT(w) = optimal value of knapsack problem with weight limit w.
- **B**. OPT(i) = optimal value of knapsack problem with items 1, ..., i.
- C. OPT(i, w) = optimal value of knapsack problem with items 1, ..., i subject to weight limit w.
- D. Any of the above.

## Dynamic programming: two variables

Def. OPT(i, w) = optimal value of knapsack problem with items 1, ..., i, subject to weight limit w.

Goal. OPT(n, W).

possibly because  $w_i > w_i$ 

Case 1. OPT(i, w) does not select item i.

• OPT(i, w) selects best of  $\{1, 2, ..., i-1\}$  subject to weight limit w.

Case 2. OPT(i, w) selects item i.

optimal substructure property (proof via exchange argument)

- Collect value  $v_i$ .
- New weight limit =  $w w_i$ .
- OPT(i, w) selects best of  $\{1, 2, ..., i-1\}$  subject to new weight limit.

#### Bellman equation.

$$OPT(i, w) = \begin{cases} 0 & \text{if } i = 0 \\ OPT(i - 1, w) & \text{if } w_i > w \\ \max \{ OPT(i - 1, w), \ v_i + OPT(i - 1, w - w_i) \} & \text{otherwise} \end{cases}$$

## Knapsack problem: bottom-up dynamic programming

KNAPSACK
$$(n, W, w_1, ..., w_n, v_1, ..., v_n)$$

FOR  $w = 0$  TO  $W$ 
 $M[0, w] \leftarrow 0$ .

FOR  $i = 1$  TO  $n$ 

FOR  $w = 0$  TO  $W$ 

IF  $(w_i > w)$   $M[i, w] \leftarrow M[i-1, w]$ .

ELSE

 $M[i, w] \leftarrow \max \{ M[i-1, w], v_i + M[i-1, w-w_i] \}$ .

RETURN  $M[n, W]$ .

$$OPT(i, w) = \begin{cases} 0 & \text{if } i = 0 \\ OPT(i-1, w) & \text{if } w_i > w \\ \max \{ OPT(i-1, w), \ v_i + OPT(i-1, w-w_i) \} & \text{otherwise} \end{cases}$$

## Knapsack problem: bottom-up dynamic programming demo

i	$v_i$	$w_i$		
1	\$1	1 kg		$\begin{cases} 0 \\ OPT(i-1, w) \\ \max \{OPT(i-1, w), v_i + OPT(i-1, w-w_i)\} \end{cases}$
2	\$6	2 kg	$OPT(i, w) = \langle \cdot \rangle$	OPT(i-1, w)
3	\$18	5 kg		$\max \{OPT(i-1, w), v_i + OPT(i-1, w-w_i)\}$
4	\$22	6 kg		(
5	\$28	7 kg		

#### weight limit w

	0	1	2	3	4	5	6	7	8	9	10	11
{ }	0	0	0	0	0	0	0	0	0	0	0	0
{1}	0	1	1	1	1	1	1	1	1	1	1	1
{ 1, 2 }	0 ←		6	7	7	7	7	7	7	7	7	7
{ 1, 2, 3 }	0	1	6	7	7	- 18 ∢	19	24	25	25	25	25
{ 1, 2, 3, 4 }	0	1	6	7	7	18	22	24	28	29	29	<b>-</b> 40
{ 1, 2, 3, 4, 5 }	0	1	6	7	7	18	22	28	29	34	35	40

subset of items 1, ..., i

OPT(i, w) = optimal value of knapsack problem with items 1, ..., i, subject to weight limit w

Truck – 10t capacity

## **Optimum cargo combination:**

- •Item 1: \$5 (3t)
- •Item 2: \$7 (4t)
- •Item 3: \$8 (5t)

Output function f(i,w)



Optimum output of a combination of items 1 to i with a cumulated weight of w or less.

- •ltem 1: x1=\$5; w1=3t
- •Item 2: x2=\$7; w2=4t
- •Item 3: x3=\$8 : w3=5t

Output function f(i,w)

ONE Item i + optimum combination of weight w-wi

NO Item i + optimum combination items 1 to i-1

## **Table**

	1	2	3	4	5	6	7	8	9	10		W
1												
2												
3												
1											•	

**f**(**i**,**w**)

•Item 1: x1=\$5; w1=3t

•Item 2: x2=\$7; w2=4t

•Item 3: x3=\$8; w3=5t

•Item 2: x2=\$7; w2=4t

•Item 3: x3=\$8; w3=5t

# Knapsack Problem

	1	2	3	4	5	6	7	8	9	10	<b></b>
1			U	sing	j on	ly i	tem	1			
2											
3											





•Item 2: x2=\$7; w2=4t

•Item 3: x3=\$8; w3=5t

# Knapsack Problem

	1	2	3	4	5	6	7	8	9	10	
1											
2			Usiı	ng d	nly	ite	m 1	& 2			
3											





•Item 2: x2=\$7; w2=4t

•Item 3: x3=\$8; w3=5t

# Knapsack Problem

	1	2	3	4	5	6	7	8	9	10	W
1											
2											
3			Usi	ng	iten	ns 1	, 2	& 3			

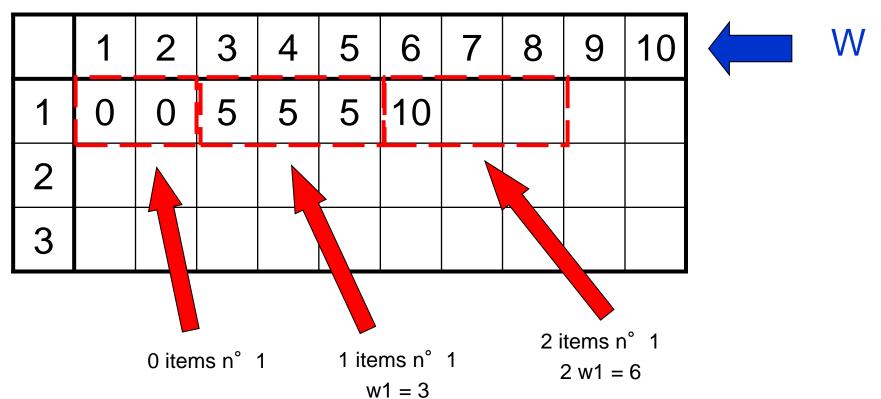


•Item 2: x2=\$7; w2=4t

•Item 3: x3=\$8; w3=5t

# Knapsack Problem





•Item 2: x2=\$7; w2=4t

•Item 3: x3=\$8; w3=5t

# Knapsack Problem

	1	2	3	4	5	6	7	8	9	10
1	0	0	5	5	5	10	10	10	15	15
2	0 ,	0	5	7						
3										

$$w - w2 = 5 - 4 = 1$$

$$f(i,w)=Max[xi + f(i,w-wi); f(i-1,w)]$$

•Item 2: x2=\$7; w2=4t

•Item 3: x3=\$8; w3=5t

# Knapsack Problem

	1	2	3	4	5	6	7	8	9	10
1	0	0	5	5	5	10	10	10	15	15
2	0 ,	0	5	7	7					
3										

$$+ x2 (= 7)$$

•Item 2: x2=\$7; w2=4t

•Item 3: x3=\$8; w3=5t

# Knapsack Problem

	1	2	3	4	5	6	7	8	9	10
1	0	0	5	5	5	10,	10	10	15	15
2	0	0,	5	7	7					
3										

$$w - w2 = 6 - 4 = 2$$

$$f(i,w)=Max[xi + f(i,w-wi); f(i-1,w)]$$

•Item 2: x2=\$7; w2=4t

•Item 3: x3=\$8; w3=5t

# Knapsack Problem

	1	2	3	4	5	6	7	8	9	10
1	0	0	5	5	5	10,	10	10	15	15
2	0	0,	5	7	7	10				
3										

$$+ x2 (= 7)$$

•Item 2: x2=\$7; w2=4t

•Item 3: x3=\$8; w3=5t

# Knapsack Problem

## **COMPLETED TABLE**

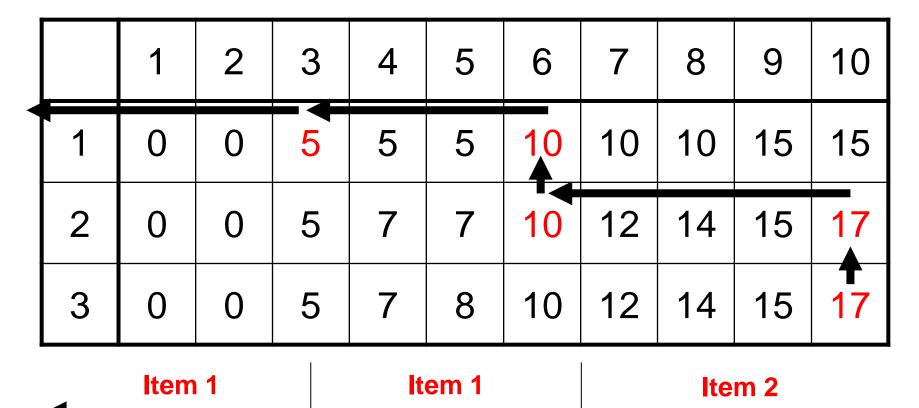
	1	2	3	4	5	6	7	8	9	10
1	0	0	5	5	5	10	10	10	15	15
2	0	0	5	7	7	10	12	14	15	17
3	0	0	5	7	8	10	12	14	15	17

•Item 1: x1=\$5; w1=3t •Item 2: x2=\$7; w2=4t

•Item 3: x3=\$8; w3=5t

## Knapsack Problem

## **Path**



## Knapsack problem: running time

Theorem. The DP algorithm solves the knapsack problem with n items and maximum weight W in  $\Theta(n|W)$  time and  $\Theta(n|W)$  space.

#### Pf.

- weights are integers between 1 and W
- Takes O(1) time per table entry.
- There are  $\Theta(n|W)$  table entries.
- After computing optimal values, can trace back to find solution: OPT(i, w) takes item i iff M[i, w] > M[i-1, w].

#### Remarks.

- Algorithm depends critically on assumption that weights are integral.
- Assumption that values are integral was not used.

## Knapsack Problem: Bottom-Up

Knapsack. Fill up an n-by-W array.

```
Input: n, w_1, ..., w_N, v_1, ..., v_N
for w = 0 to W
  M[0, w] = 0
for i = 1 to n
   for w = 1 to W
      if (w_i > w)
          M[i, w] = M[i-1, w]
      else
          M[i, w] = \max \{M[i-1, w], v_i + M[i-1, w-w_i]\}
return M[n, W]
```

## Knapsack Algorithm

\_\_\_\_\_ W + 1

		0	1	2	3	4	5	6	7	8	9	10	11
n + 1	ф	0	0	0	0	0	0	0	0	0	0	0	0
	{ 1 }	0	1	1	1	1	1	1	1	1	1	1	1
	{ 1, 2 }	0	1	6	7	7	7	7	7	7	7	7	7
	{ 1, 2, 3 }	0	1	6	7	7	18	19	24	25	25	25	25
	{1,2,3,4}	0	1	6	7	7	18	22	24	28	29	29	40
	{1,2,3,4,5}	0	1	6	7	7	18	22	28	29	34	34	40

OPT: { 4, 3 } value = 22 + 18 = 40

W = 11

Item	Value	Weight				
1	1	1				
2	6	2				
3	18	5				
4	22	6				
5	28	7				

## Dynamic programming: quiz 4



#### Does there exist a poly-time algorithm for the knapsack problem?

- A Yes, because the DP algorithm takes  $\Theta(n \ W)$  time.
- **B.** No, because  $\Theta(n \ W)$  is not a polynomial function of the input size.
- No, because the problem is **NP**-hard.
- Unknown.



## **COIN CHANGING**



Problem. Given n coin denominations  $\{c_1, c_2, ..., c_n\}$  and a target value V, find the fewest coins needed to make change for V (or report impossible).

Recall. Greedy cashier's algorithm is optimal for U.S. coin denominations, but not for arbitrary coin denominations.

Ex.  $\{1, 10, 21, 34, 70, 100, 350, 1295, 1500\}$ . Optimal.  $140 \neq 70 + 70$ .



















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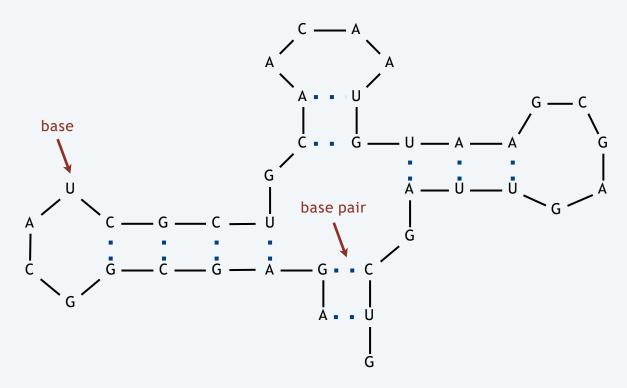
SECTION 6.5

## 6. DYNAMIC PROGRAMMING I

- weighted interval scheduling
- segmented least squares
- knapsack problem
- ► RNA secondary structure

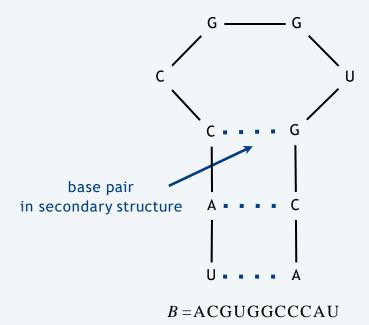
RNA. String  $B = b_1b_2...b_n$  over alphabet  $\{A, C, G, U\}$ .

Secondary structure. RNA is single-stranded so it tends to loop back and form base pairs with itself. This structure is essential for understanding behavior of molecule.

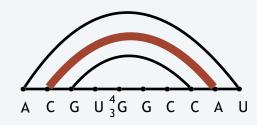


Secondary structure. A set of pairs  $S = \{(b_i, b_j)\}$  that satisfy:

■ [Watson-Crick] S is a matching and each pair in S is a Watson-Crick complement: A–U, U–A, C–G, or G–C.



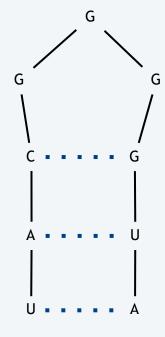
 $S = \{ (b_1, b_{10}), (b_2, b_9), (b_3, b_8) \}$ 



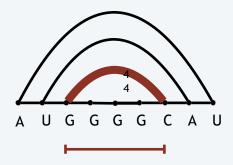
Ss not asecondary structure (CA is not avalid Watson-Orick pair)

Secondary structure. A set of pairs  $S = \{(b_i, b_i)\}$  that satisfy:

- [Watson-Crick] S is a matching and each pair in S is a Watson-Crick complement: A–U, U–A, C–G, or G–C.
- [No sharp turns] The ends of each pair are separated by at least 4 intervening bases. If  $(b_i, b_j) \in S$ , then i < j 4.



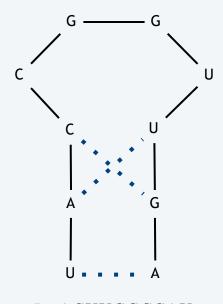
B = AUGGGGCAU $S = \{ (b_1, b_{10}), (b_2, b_9), (b_3, b_8) \}$ 



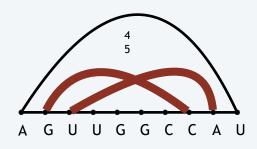
Sis not a secondary structure (≤4 intervening bases between Gand C)

Secondary structure. A set of pairs  $S = \{(b_i, b_i)\}$  that satisfy:

- [Watson-Crick] S is a matching and each pair in S is a Watson-Crick complement: A–U, U–A, C–G, or G–C.
- [No sharp turns] The ends of each pair are separated by at least 4 intervening bases. If  $(b_i, b_i) \in S$ , then i < j 4.
- [Non-crossing] If  $(b_i, b_j)$  and  $(b_k, b_\ell)$  are two pairs in S, then we cannot have  $i < k < j < \ell$ .



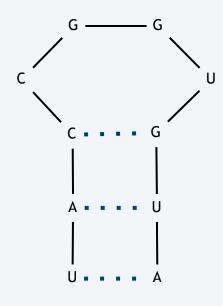
B = ACUUGGCCAU $S = \{ (b_1, b_{10}), (b_2, b_8), (b_3, b_9) \}$ 



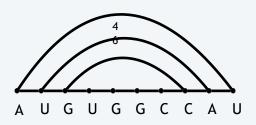
Sis not a secondary structure (G-Cand U-A cross)

Secondary structure. A set of pairs  $S = \{(b_i, b_i)\}$  that satisfy:

- [Watson-Crick] S is a matching and each pair in S is a Watson-Crick complement: A–U, U–A, C–G, or G–C.
- [No sharp turns] The ends of each pair are separated by at least 4 intervening bases. If  $(b_i, b_i) \in S$ , then i < j 4.
- [Non-crossing] If  $(b_i, b_j)$  and  $(b_k, b_\ell)$  are two pairs in S, then we cannot have  $i < k < j < \ell$ .



B = AUGUGGCCAU $S = \{ (b_1, b_{10}), (b_2, b_9), (b_3, b_8) \}$ 

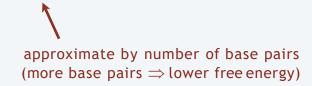


Sis a secondary structure (with 3 base pairs)

Secondary structure. A set of pairs  $S = \{(b_i, b_i)\}$  that satisfy:

- [Watson-Crick] S is a matching and each pair in S is a Watson-Crick complement: A–U, U–A, C–G, or G–C.
- [No sharp turns] The ends of each pair are separated by at least 4 intervening bases. If  $(b_i, b_i) \in S$ , then i < j 4.
- [Non-crossing] If  $(b_i, b_j)$  and  $(b_k, b_\ell)$  are two pairs in S, then we cannot have  $i < k < j < \ell$ .

Free-energy hypothesis. RNA molecule will form the secondary structure with the minimum total free energy.



Goal. Given an RNA molecule  $B = b_1b_2...b_n$ , find a secondary structure S that maximizes the number of base pairs.

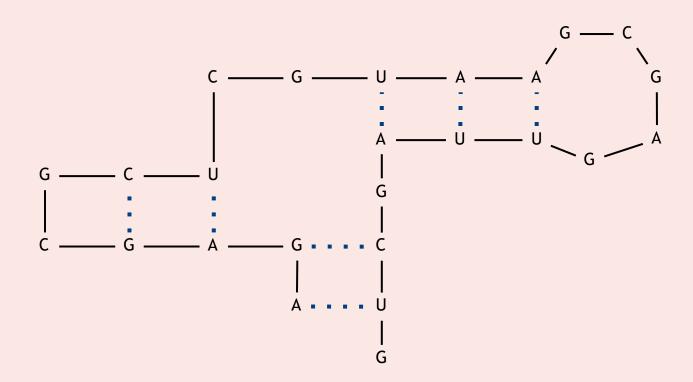


#### Is the following a secondary structure?

- A. Yes.
- B. No, violates Watson-Crick condition.
- C. No, violates no-sharp-turns condition.



D. No, violates no-crossing condition.



## Dynamic programming: quiz 6



#### Which subproblems?

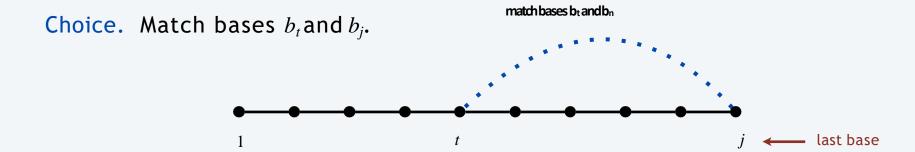
- A.  $OPT(j) = \max \text{ number of base pairs in secondary structure}$  of the substring  $b_1b_2...b_j$ .
- B.  $OPT(j) = \max \text{ number of base pairs in secondary structure}$  of the substring  $b_j b_{j+1} \dots b_n$ .
- C. Either A or B.
- D. Neither A nor B.



## RNA secondary structure: subproblems

First attempt.  $OPT(j) = \text{maximum number of base pairs in a secondary structure of the substring } b_1b_2 \dots b_j$ .

Goal. OPT(n).



Difficulty. Results in two subproblems (but one of wrong form).

- Find secondary structure in  $b_1b_2...b_{t-1}$ . ← OPT(t-1)
- Find secondary structure in  $b_{t+1}b_{t+2}\dots b_{j-1}$  need more subproblems (first base no longer  $b_1$ )

## Dynamic programming over intervals

Def. OPT(i, j) = maximum number of base pairs in a secondary structure of the substring  $b_i b_{i+1} \dots b_{j}$ .

Case 1. If  $i \ge j - 4$ .

• OPT(i, j) = 0 by no-sharp-turns condition.

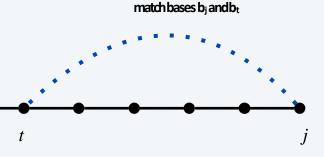
Case 2. Base  $b_j$  is not involved in a pair.

• OPT(i, j) = OPT(i, j-1).

Case 3. Base  $b_j$  pairs with  $b_t$  for some  $i \le t < j - 4$ .

- Non-crossing condition decouples resulting two subproblems.
- $OPT(i, j) = 1 + \max_{t} \{ OPT(i, t-1) + OPT(t+1, j-1) \}.$

take max over t such that  $i \le t < j-4$  and  $b_t$  and  $b_j$  are Watson-Crickcomplements





## In which order to compute OPT(i, j)?

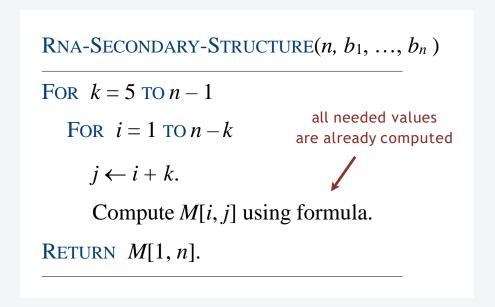
- A. Increasing i, then j.
- B. Increasing j, then i.

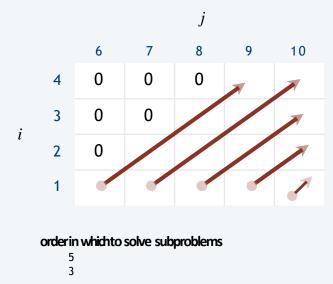


- C. Either A or B.
- D. Neither A nor B.

## Bottom-up dynamic programming over intervals

- Q. In which order to solve the subproblems?
- A. Do shortest intervals first—increasing order of 🖵 🗓





Theorem. The DP algorithm solves the RNA secondary structure problem in  $O(n^3)$  time and  $O(n^2)$  space.

## Dynamic programming summary

#### Outline.

typically, only a polynomial number of subproblems

- Define a collection of subproblems.
- Solution to original problem can be computed from subproblems.
  - Natural ordering of subproblems from "smallest" to "largest" that enables determining a solution to a subproblem from solutions to smaller subproblems.

#### Techniques.

- Binary choice: weighted interval scheduling.
- •Multiway choice: segmented least squares.
- Adding a new variable: knapsack problem.
- Intervals: RNA secondary structure.

Top-down vs. bottom-up dynamic programming. Opinions differ.

## NEXT LECTURE

- . Min-cut
- Karger's Algorithm