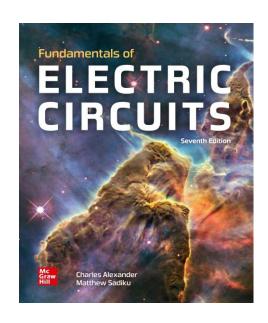
# EHB 211E Basics of Electrical Circuits

Asst. Prof. Onur Kurt

## **Second-Order Circuits**

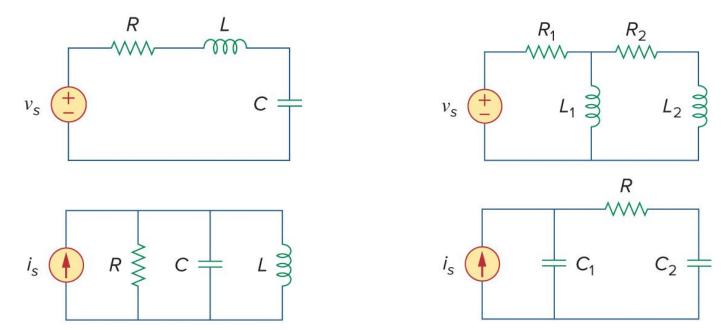




## Introduction

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- Circuit with single storage element such as capacitor or inductor: first-order circuit.
  - □ response is first-order differential equation
- Circuit containing two storage elements together with capacitor and inductor: second-order circuit.
  - □ Response is second order differential equation.
- Typical example of second-order circuits: RLC circuits
  - □ Two storage elements of different type
  - □ Two storage elements of same type (cannot represented by an equivalent single element)



# Finding Initial and Final Values



• To solve second order differential equation of a second-order circuit, the following parameters must be found:

$$v(0)$$
 ,  $i(0)$  ,  $\frac{dv(0)}{dt}$  ,  $\frac{di(0)}{dt}$  ,  $v(\infty)$  ,  $i(\infty)$ 

- Recall:
  - □ Capacitor voltage is continuous

$$v(0^+) = v(0^-)$$

□ Inductor current is continuous

0<sup>-</sup>: time just before switching event

0<sup>+</sup>: time just after switching event

$$i(0^+) = i(0^-)$$

## Example 1



The switch in the circuit shown below has been closed for a long time. It is open at t=0. Find a-)  $i(0^+)$ ,  $v(0^+)$ , b-)  $di(0^+)/dt$ ,  $dv(0^+)/dt$ , c-)  $i(\infty)$ ,  $v(\infty)$ .

#### **Solution:**

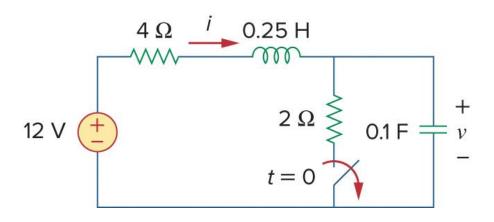
- At t < 0, the switch is closed.
- At t=0, the circuit has reached dc steady-state.
- Under dc condition, the inductor acts as short circuit and the capacitor acts as open circuit.

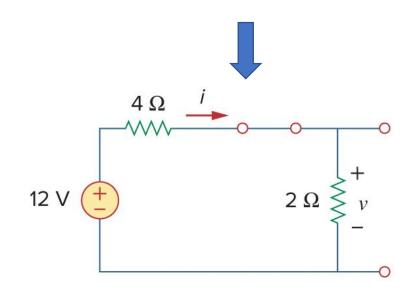
a-) At 
$$t < 0$$
,

$$i(0^{-}) = \frac{12}{4+2} = 2 \text{ A}, \quad v(0^{-}) = 2i(0^{-}) = 4 \text{ V}$$

Inductor current and capacitor voltage cannot change suddenly,

$$i(0^+) = i(0^-) = 2 \text{ A}, \quad v(0^+) = v(0^-) = 4 \text{ V}$$







## b-) At $t = 0^+$ , the switch is open

$$i_C(0^+) = i(0^+) = 2 \text{ A}$$

Since 
$$C dv/dt = i_C$$
,  $dv/dt = i_C/C$ ,

$$\frac{dv(0^+)}{dt} = \frac{i_C(0^+)}{C} = \frac{2}{0.1} = 20 \text{ V/s}$$

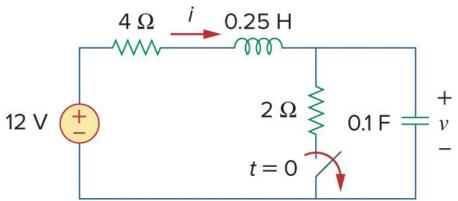
Similarly, since  $L di/dt = v_L$ ,  $di/dt = v_L/L$ .

### Obtain $v_L$ by applying KVL (clockwise):

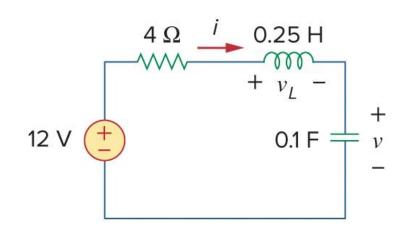
$$-12 + 4i(0^+) + v_L(0^+) + v(0^+) = 0$$

$$v_L(0^+) = 12 - 8 - 4 = 0$$

$$\frac{di(0^+)}{dt} = \frac{v_L(0^+)}{L} = \frac{0}{0.25} = 0 \text{ A/s}$$





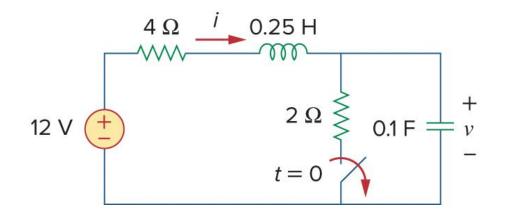


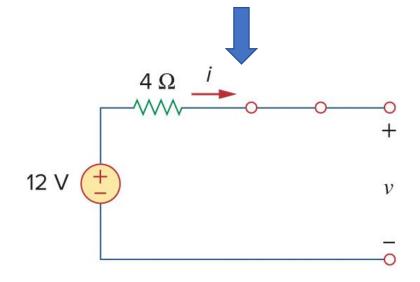


c-) At t > 0: as  $t \to \infty$ , the circuit reaches steady-state again. Under dc condition, inductor acts as short circuit and capacitor acts as open circuit.

$$i(\infty) = 0 A \longrightarrow \text{No current flows}$$

Same as applied voltage as they are parallel (No voltage drop across 
$$4\Omega$$
 resistor).





## Example 2

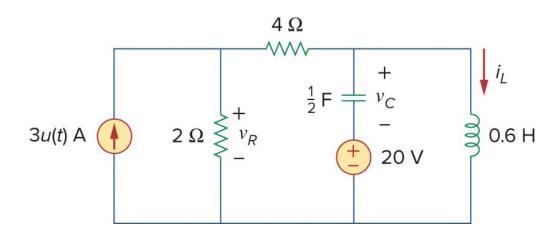


In the circuit shown below, calculate a-)  $i_L(0^+)$ ,  $v_C(0^+)$ ,  $v_R(0^+)$ , b-)  $\mathrm{d}i_L(0^+)/dt$ ,  $\mathrm{d}v_C(0^+)/dt$ ,  $\mathrm{d}v_R(0^+)/dt$ , c-) $i_L(\infty)$ ,  $v_C(\infty)$ ,  $v_R(\infty)$ .

#### **Solution:**

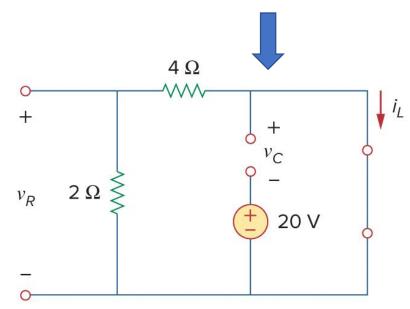
a-) At 
$$t < 0$$
,  $3u(t) = 0$  since  $u(t) = 0$ 

$$u(t) = \begin{cases} 0 & t < 0 \\ 1 & t > 0 \end{cases}$$



- At  $t = 0^-$ , the circuit reaches steady-state.
- The inductor acts as short circuit and the capacitor acts as open circuit.

$$i_L(0^-) = 0, v_R(0^-) = 0, v_C(0^-) = -20 \text{ V}$$



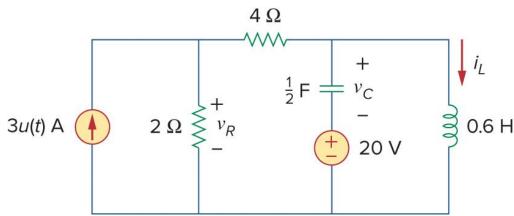


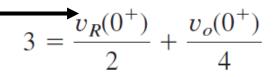
• At t > 0, 3u(t) = 3 since u(t) = 1

$$i_L(0^+) = i_L(0^-) = 0, v_C(0^+) = v_C(0^-) = -20 \text{ V}$$

• Apply KCL at node a:

$$\sum i_{in} = \sum i_{out}$$



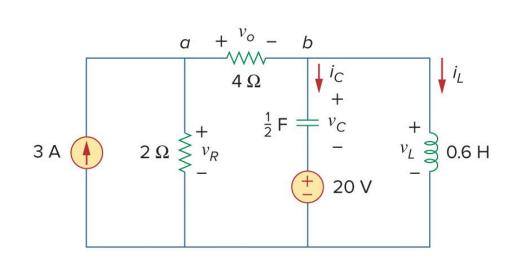


 $v_R(0^+) = v_0(0^+) = 4 \text{ V}$ 

• Apply KVL to the middle mesh:

$$-v_R(0^+) + v_o(0^+) + v_C(0^+) + 20 = 0$$
$$v_C(0^+) = -20 \text{ V} \qquad v_R(0^+) = v_o(0^+)$$

$$\sum_{m=1}^{n} v_m = 0$$





b-) Since 
$$L di_L/dt = v_L$$
,  $\frac{di_L(0^+)}{dt} = \frac{v_L(0^+)}{L}$ 

### Apply KVL to the right mesh:

$$v_L(0^+) = v_C(0^+) + 20$$

$$v_C(0^+) = -20 \text{ V}$$

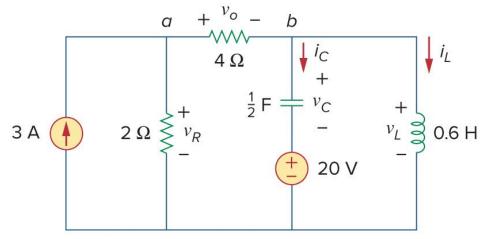
$$\frac{di_L(0^+)}{dt} = 0$$

since  $C dv_C/dt = i_C$ , then  $dv_C/dt = i_C/C$ .

Apply KCL at node b: 
$$\frac{v_o(0^+)}{4} = i_C(0^+) + i_L(0^+)$$

Since 
$$v_o(0^+) = 4$$
 and  $i_L(0^+) = 0$ ,  $i_C(0^+) = 4/4 = 1$  A.

$$\frac{dv_C(0^+)}{dt} = \frac{i_C(0^+)}{C} = \frac{1}{0.5} = 2 \text{ V/s}$$



## Apply KCL at node a:

$$3 = \frac{v_R}{2} + \frac{v_o}{4} \longrightarrow \text{Take derivative}$$
 of both sides

$$0 = 2\frac{dv_R(0^+)}{dt} + \frac{dv_o(0^+)}{dt}$$

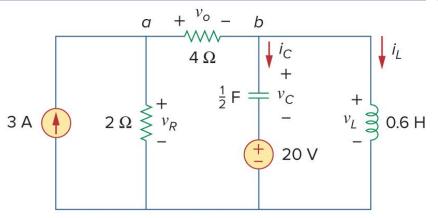
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## Apply KVL to the middle mesh:

$$-v_R + v_C + 20 + v_o = 0$$
 Take derivative of both sides

$$-\frac{dv_R(0^+)}{dt} + \frac{dv_C(0^+)}{dt} + \frac{dv_o(0^+)}{dt} = 0 \qquad dv_C(0^+)/dt = 2$$

$$\frac{dv_R(0^+)}{dt} = 2 + \frac{dv_o(0^+)}{dt} \qquad \frac{dv_R(0^+)}{dt} = \frac{2}{3} \text{ V/s}$$



c-) As  $t \to \infty$  ( $t = \infty$ ), the circuit reaches steady-state. (inductor: short circuit and capacitor: open circuit).

#### **Current division**

$$i_L(\infty) = \frac{2}{2+4} 3 \text{ A} = 1 \text{ A}$$
  $v_R(\infty) = \frac{4}{2+4} 3 \text{ A} \times 2 = 4 \text{ V},$   $v_C(\infty) = -20 \text{ V}$ 



 The circuit is being excited by the energy initially stored in the capacitor and inductor.

$$V_0$$
 = initial capacitor voltage  $I_0$  = initial inductor current

$$I_0$$
 = initial inductor current

- At t = 0,  $v(0) = V_0$  and  $i(0) = I_0$
- At t>0, excitation of the circuit is due to the energy stored in the capacitor and the inductor.

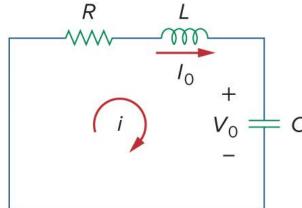
$$\sum_{m=1} v_m = 0$$

• Apply KVL: 
$$\sum_{m=1}^{\infty} v_m = 0 \qquad \qquad Ri + L \frac{di}{dt} + \frac{1}{C} \int_0^t i(t) dt = 0 \longrightarrow \text{To eliminate the integral, differentiate w.r.t } t$$

$$R\frac{di}{dt} + L\frac{d^2i}{dt^2} + \frac{i}{C} = 0 \implies \frac{d^2i}{dt^2} + \frac{R}{L}\frac{di}{dt} + \frac{i}{LC} = 0$$



Second-order differential equation. This is why RLC circuit is called the second-order circuit





$$\frac{d^2i}{dt^2} + \frac{R}{L}\frac{di}{dt} + \frac{i}{LC} = 0$$

- To solve second-order differential equation, initial conditions should be obtained:
  - □ Initial value of *i*
  - $\Box$  Initial value of v
  - $\Box$  Initial value of the first derivative of i

Using KVL: 
$$Ri + L\frac{di}{dt} + \frac{1}{c}\int_0^t i(t)dt = 0$$
 
$$Ri(0) + L\frac{di(0)}{dt} + V_0 = 0$$
 
$$i(0) = I_0$$
 
$$v(0) = V_0$$

$$\frac{di(0)}{dt} = -\frac{1}{L}(RI_0 + V_0)$$

• With these initial conditions, the 2<sup>nd</sup> order differential equation can be solved.



• Based on our experience from previous lecture,  $1^{st}$  order circuit suggests that the solution is of exponential form.

$$i = Ae^{st}$$
 A and S are constants to be determined

• Substitute above current equation into 2<sup>nd</sup> order differential equation:

$$\frac{d^2(Ae^{st})}{dt^2} + \frac{R}{L}\frac{d(Ae^{st})}{dt} + \frac{Ae^{st}}{LC} = 0 \implies As^2e^{st} + \frac{AR}{L}se^{st} + \frac{A}{LC}e^{st} = 0$$

$$Ae^{st}\left(s^2 + \frac{R}{L}s + \frac{1}{LC}\right) = 0$$
 Since  $i = Ae^{st}$ ,  $Ae^{st}$  cannot be zero

$$s^2 + \frac{R}{L}s + \frac{1}{LC} = 0$$
 Characteristic equation of the 2<sup>nd</sup> order differential equation



$$s^2 + \frac{R}{L}s + \frac{1}{LC} = 0$$

$$s_1 = -\frac{R}{2L} + \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

$$s_2 = -\frac{R}{2L} - \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

#### <u>Recall:</u>

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Two roots

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}$$
 where  $\alpha = \frac{R}{2L}$  and  $\omega_0 = \frac{1}{\sqrt{LC}}$  
$$s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$$

Ratio of  $\frac{\alpha}{\omega_0}$ : damping ratio

- $s_1$  and  $s_2$ : natural frequency, measured in nepers per sec (Np/s)
- $\alpha$ : neper frequency or damping factor, measured in nepers per sec (Np/s)
- $\omega_0$ : resonant frequency or undamped natural frequency (rad/sec)

Damping: decrease in amplitude of oscillation



Characteristic equation can be written as:

$$s^2 + 2\alpha s + \omega_0^2 = 0$$

• Two possible solution due to two roots ( $s_1 \& s_2$ )

$$i_1 = Ae^{s_1 t} \qquad i_2 = Ae^{s_2 t}$$

• Complete or total solution of  $2^{
m nd}$  order differential equation is linear combination of  $i_1 \ \& \ i_2$ 

$$i(t) = A_1 e^{S_1 t} + A_2 e^{S_2 t}$$

• Constant will be determined from the initial values i(0) and  $\frac{di(0)}{dt}$ 



$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}$$

$$s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$$

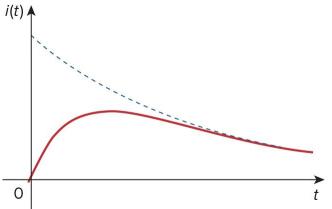
- Based on the above equations, three types of solutions:
  - 1. If  $\alpha > \omega_0$ , we have the overdamped case
  - 2. If  $\alpha = \omega_0$ , we have the critically damped case
  - 3. If  $\alpha < \omega_0$ , we have the underdamped case.

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## $\triangleright$ Overdamped case ( $\alpha > \omega_0$ ):

- Both roots ( $s_1$  and  $s_2$ ) are negative and real.
- The response is:

$$i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$
  $\longrightarrow$  As t increases  $(t \to \infty)$ ,  $i(t)$  decays and approaches zero



System returns to equilibrium position very slowly without any oscillation

## $\triangleright$ Critically damped case ( $\alpha = \omega_0$ ):

•  $s_1 = s_2 = -\alpha$  (Both roots are equal)

$$i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} = A_1 e^{-\alpha t} + A_2 e^{-\alpha t} = A_3 e^{-\alpha t}$$

Where 
$$A_3 = A_1 + A_2$$

• This cannot be solution as two initial conditions cannot be satisfied with the single constant  $A_3$ . This means our assumption of an exponential solution is incorrect for the critical case.



$$\alpha = \frac{R}{2L}$$
 and  $\omega_0 = \frac{1}{\sqrt{LC}}$  and  $\alpha = \omega_0$  for critically damped case

$$\frac{d^2i}{dt^2} + \frac{R}{L}\frac{di}{dt} + \frac{i}{LC} = 0 \implies \frac{d^2i}{dt^2} + 2\alpha\frac{di}{dt} + \alpha^2i = 0 \implies \frac{d^2i}{dt^2} + \alpha\frac{di}{dt} + \alpha\frac{di}{dt} + \alpha^2i = 0$$

$$\frac{d}{dt}\left(\frac{di}{dt} + \alpha i\right) + \alpha \left(\frac{di}{dt} + \alpha i\right) = 0 \qquad \text{Let } \frac{di}{dt} + \alpha i = f$$

$$\frac{df}{dt} + \alpha f = 0 \longrightarrow 1^{st}$$
 order differential equation

Solution of 1<sup>st</sup> order differential equation 
$$f = A_1 e^{-\alpha t}$$
 where  $A_1$  is constant Product rule

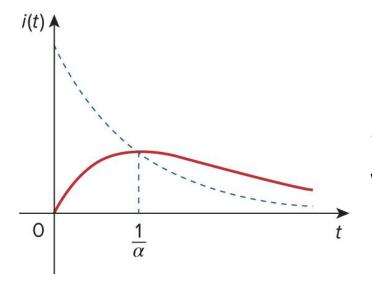
$$\frac{df}{dt} + \alpha f = 0 \implies \frac{di}{dt} + \alpha i = A_1 e^{-\alpha t} \implies e^{\alpha t} \frac{di}{dt} + (e^{\alpha t} \alpha i) = A_1 \implies \frac{d}{dt} (e^{\alpha t} i) = A_1$$



$$\frac{d}{dt}(e^{\alpha t}i) = A_1 \quad \text{Integrate} \qquad \qquad e^{\alpha t}i = A_1t + A_2 \quad \Longrightarrow \quad i = (A_1t + A_2)e^{-\alpha t}$$

$$i(t) = (A_2 + A_1 t)e^{-\alpha t}$$
 The natural response of the critically damped circuit

System returns to its equilibrium position in the shortest possible time without any oscillation



It reaches its max value of  $\frac{e^{-1}}{\alpha}$  at  $t=\frac{1}{\alpha}$  and then decays all the way zero.



- Underdamped case ( $\alpha < \omega_0$ ):
- Roots may be written as:

$$s_1 = -\alpha + \sqrt{-(\omega_0^2 - \alpha^2)} = -\alpha + j\omega_d$$
 where  $j = \sqrt{-1}$  and  $\omega_d = \sqrt{(\omega_0^2 - \alpha^2)}$  
$$s_2 = -\alpha - \sqrt{-(\omega_0^2 - \alpha^2)} = -\alpha - j\omega_d$$
 Damping frequency or damped natural frequency

Natural response is given by:

$$i(t) = A_1 e^{-(\alpha - j\omega_d)t} + A_2 e^{-(\alpha + j\omega_d)t}$$
  $\longrightarrow$   $i(t) = e^{-\alpha t} (A_1 e^{j\omega_d t} + A_2 e^{-j\omega_d t})$ 

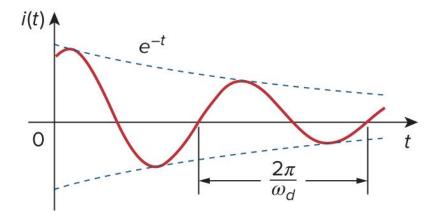
Using Euler's identities:

$$e^{j\theta} = \cos\theta + j\sin\theta$$
  $e^{-j\theta} = \cos\theta - j\sin\theta$ 



$$i(t) = e^{-\alpha t} (B_1 cos \omega_d t + B_2 sin \omega_d t)$$

Natural response is exponentially damped and oscillatory due to the presence of sin and cos



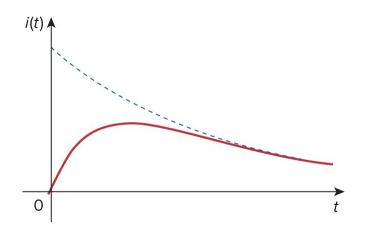
- Once the current i(t) is found for RLC series circuit, other quantities can easily be found.
  - $\square$  Resistor voltage as v(t) = Ri(t)
  - □ Inductor voltage as  $v(t) = L \frac{di(t)}{dt}$



#### • Summarize:

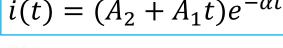
Overdamped case

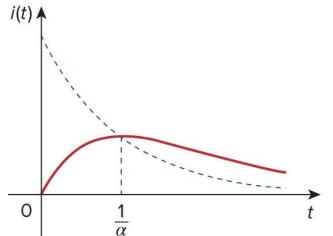
$$i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$



Critically damped case

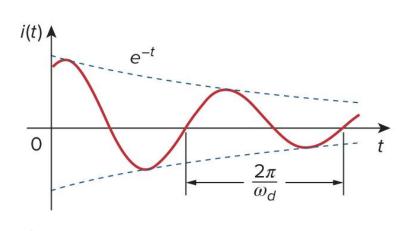
$$i(t) = (A_2 + A_1 t)e^{-\alpha t}$$

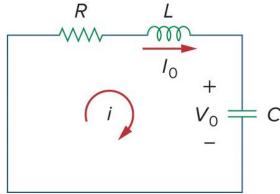




Underdamped case

$$i(t) = e^{-\alpha t} (B_1 cos \omega_d t + B_2 sin \omega_d t)$$





# Example 3



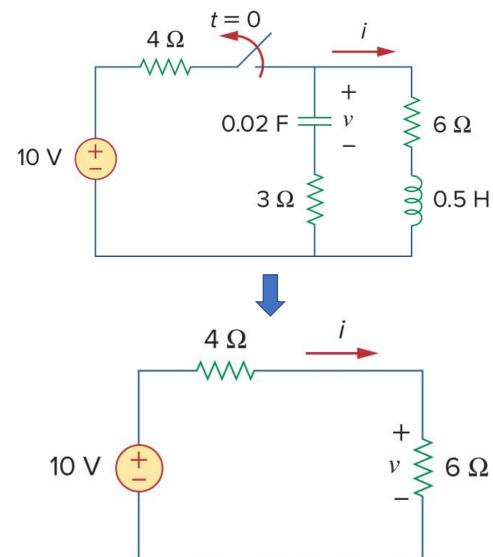
Find i(t) in the circuit shown below. Assume that the circuit has reached steady state at  $t=0^-$ .

#### **Solution:**

- First, we need to calculate initial values of inductor and capacitor.
- For t < 0, the switch is closed.
- Under dc condition, the inductor acts as short circuit and the capacitor acts as open circuit.
- Capacitor voltage and inductor current cannot change instantly.

$$i(0) = \frac{10}{4+6} = 1 \text{ A}, \qquad v(0) = 6i(0) = 6 \text{ V}$$

• i(0) and v(0) are initial inductor current and initial capacitor voltage at t=0, respectively.



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- For t > 0, the switch is opened.
- Voltage source is disconnected.
- To determine which type of response or case the circuit has, characteristics roots of the circuit should be obtained.

$$\alpha = \frac{R}{2L} = \frac{9}{2(\frac{1}{2})} = 9,$$
  $\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{\frac{1}{2} \times \frac{1}{50}}} = 10$ 

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -9 \pm \sqrt{81 - 100}$$
  $s_{1,2} = -9 \pm j4.359$ 

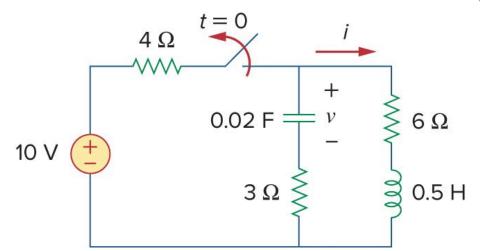
the response is underdamped ( $\alpha < \omega$ ); that is,

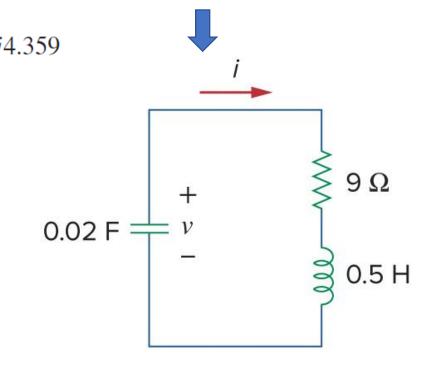
$$i(t) = e^{-9t} (A_1 \cos 4.359t + A_2 \sin 4.359t)$$

obtain  $A_1$  and  $A_2$  using the initial conditions. At t = 0,

$$i(0) = 1 = A_1$$
  $v(0) = V_0 = -6 \text{ V}$ 

$$\frac{di}{dt}\Big|_{t=0} = -\frac{1}{L}[Ri(0) + v(0)] = -2[9(1) - 6] = -6 \text{ A/s}$$







$$\frac{di}{dt} = -9e^{-9t}(A_1\cos 4.359t + A_2\sin 4.359t) + e^{-9t}(4.359)(-A_1\sin 4.359t + A_2\cos 4.359t)$$

at 
$$t = 0$$

$$-6 = -9(A_1 + 0) + 4.359(-0 + A_2)$$
  $A_1 = 1$ 

$$-6 = -9 + 4.359A_2 \implies A_2 = 0.6882$$

$$i(t) = e^{-9t}(\cos 4.359t + 0.6882 \sin 4.359t)$$
 A

## Source-Free Parallel RLC Circuit



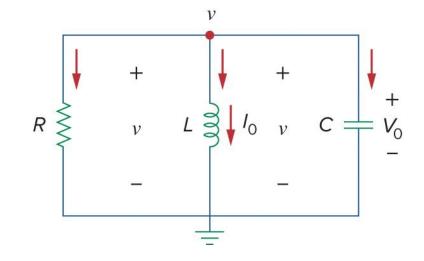
• Assume initial inductor current:  $I_0$  and initial capacitor voltage:  $V_0$ 

$$i(0) = I_0 = \frac{1}{L} \int_{-\infty}^{0} v(t)dt$$
  $v(0) = V_0$ 

• Apply KCL at the top node:  $\frac{v}{R} + \frac{1}{L} \int_{t}^{\infty} v(t) dt + C \frac{dv}{dt} = 0$  Take derivative and divide entire equation by C

$$\frac{d^2v}{dt^2} + \frac{1}{RC}\frac{dv}{dt} + \frac{1}{LC}v = 0 \longrightarrow 2^{\text{nd}} \text{ order differential equation}$$

$$s^2 + \frac{1}{RC}s + \frac{1}{LC} = 0$$
 Characteristic equation of the 2<sup>nd</sup> order differential equation



$$s_{1,2} = -\frac{1}{2RC} \pm \sqrt{\left(\frac{1}{2RC}\right)^2 - \frac{1}{LC}}$$
  $s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$  where  $\alpha = \frac{1}{2RC}$  and  $\omega_0 = \frac{1}{\sqrt{LC}}$ 

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

where 
$$lpha=rac{1}{2RC}$$
 and  $\omega_0=rac{1}{\sqrt{LC}}$ 

## Source-Free Parallel RLC Circuit



- Three possible solutions depending on the value of lpha and  $\omega_0$ 
  - 1. Overdamped case ( $\alpha > \omega_0$ )
    - $\square \alpha > \omega_0$  when  $L > 4R^2C$
    - □ Roots of the characteristics equations are real and negative. The response is:

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

- 2. Critically damped case ( $\alpha = \omega_0$ )
  - $\square \alpha = \omega_0$  when  $L = 4R^2C$
  - □ Roots of the characteristics equations are real and equal. The response is:

$$v(t) = (A_1 + A_2 t)e^{-\alpha t}$$

- 3. Underdamped case ( $\alpha < \omega_0$ )
  - $\square \alpha < \omega_0$  when  $L < 4R^2C$
  - □ Roots of the characteristics equations are complex and expressed as:

$$s_{1,2} = -\alpha \pm j\omega_d$$
 where  $\omega_d = \sqrt{\omega_0 - \alpha^2}$ 

□ The response:  $v(t) = e^{-\alpha t} (A_1 cos \omega_d t + A_2 sin \omega_d t)$ 

Constant  $A_1$  and  $A_2$  in each case determined from initial conditions

# Example 4



In the parallel circuit given below, find v(t) for t>0, assuming v(0)=5 V, i(0)=0, L=1 H, and C=10 mF. Consider these cases: R=1.923  $\Omega$ , R=5  $\Omega$ , and R=6.25  $\Omega$ .

#### **Solution:**

• Case 1:  $R = 1.923 \Omega$ .

$$\alpha = \frac{1}{2RC} = \frac{1}{2 \times 1.923 \times 10 \times 10^{-3}} = 26$$

$$\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{1 \times 10 \times 10^{-3}}} = 10$$

•  $\alpha > \omega_0$ , the response is overdamped

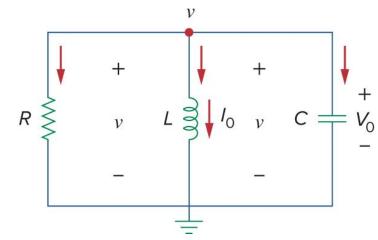
$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -2, -50$$

• Response for overdamped case:

$$v(t) = A_1 e^{S_1 t} + A_2 e^{S_2 t} = A_1 e^{-2t} + A_2 e^{-50t}$$

• Apply initial condition to get  $A_1$  and  $A_2$ 

$$v(0) = 5 = A_1 + A_2 \longrightarrow 1$$



Apply KCL at the top node:

$$\frac{dv(0)}{dt} = -\frac{v(0) + Ri(0)}{RC} = -\frac{5 + 0}{1.923 \times 10 \times 10^{-3}} = -260$$

$$\frac{dv}{dt} = -2A_1 e^{-2t} - 50A_2 e^{-50t}$$
At  $t = 0$ ,  $-260 = -2A_1 - 50A_2 \longrightarrow 2$ 

From equation 1 & 2:  $A_1 = -0.2083$  and  $A_2 = 5.208$ .

$$v(t) = -0.2083e^{-2t} + 5.208e^{-50t}$$



• Case 2:  $R = 5 \Omega$ .

$$\alpha = \frac{1}{2RC} = \frac{1}{2 \times 5 \times 10 \times 10^{-3}} = 10$$
  $\omega_0 = 10$ 

- $\alpha = \omega_0$ , the response is critically damped:  $s_1 = s_2 = -10$
- Response for critically damped case:  $v(t) = (A_1 + A_2 t)e^{-10t}$
- Apply initial conditions:  $v(0) = 5 = A_1$

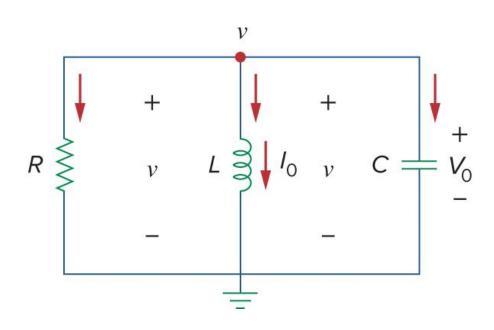
$$\frac{dv(0)}{dt} = -\frac{v(0) + Ri(0)}{RC} = -\frac{5 + 0}{5 \times 10 \times 10^{-3}} = -100$$

At 
$$t = 0$$
,  $\frac{dv}{dt} = (-10A_1 - 10A_2t + A_2)e^{-10t}$ 

$$-100 = -10A_1 + A_2$$

$$A_1 = 5$$
 and  $A_2 = -50$ .

$$v(t) = (5 - 50t)e^{-10t} V$$





• Case 3:  $R = 6.25 \Omega$ .

$$\alpha = \frac{1}{2RC} = \frac{1}{2 \times 6.25 \times 10 \times 10^{-3}} = 8$$
  $\omega_0 = 10$ 

- $\alpha < \omega_0$ , the response is underdamped:  $s_{1,2} = -\alpha \pm \sqrt{\alpha^2 \omega_0^2} = -8 \pm j6$
- Response for underdamped case:  $v(t) = (A_1 \cos 6t + A_2 \sin 6t)e^{-8t}$
- Apply initial conditions:  $v(0) = 5 = A_1$

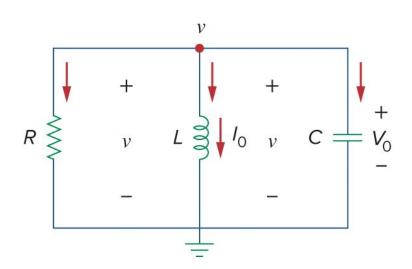
$$\frac{dv(0)}{dt} = -\frac{v(0) + Ri(0)}{RC} = -\frac{5 + 0}{6.25 \times 10 \times 10^{-3}} = -80$$

$$\frac{dv}{dt} = (-8A_1 \cos 6t - 8A_2 \sin 6t - 6A_1 \sin 6t + 6A_2 \cos 6t)e^{-8t}$$

At 
$$t = 0$$
,  $-80 = -8A_1 + 6A_2$ 

$$A_1 = 5$$
 and  $A_2 = -6.667$ .

$$v(t) = (5\cos 6t - 6.667\sin 6t)e^{-8t}$$



# Example 5



### Find v(t) for t > 0 in the RLC circuit shown below.

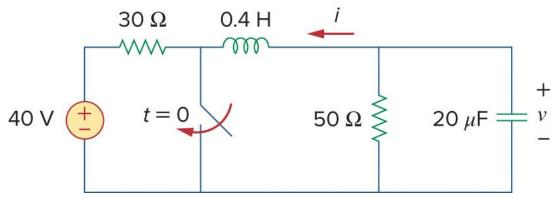
#### **Solution:**

- First, find initial value of inductor current and capacitor voltage.
- At t < 0, switch is opened. Inductor acts like short circuit and capacitor acts like open circuit.

$$v(0) = \frac{50}{30 + 50}(40) = \frac{5}{8} \times 40 = 25 \text{ V}$$

$$i(0) = -\frac{40}{30 + 50} = -0.5 \,\text{A}$$

$$\frac{dv(0)}{dt} = -\frac{v(0) + Ri(0)}{RC} = -\frac{25 - 50 \times 0.5}{50 \times 20 \times 10^{-6}} = 0$$



At t > 0, switch is closed. The voltage source along with  $30\Omega$  is disconnected.

$$\alpha = \frac{1}{2RC} = \frac{1}{2 \times 50 \times 20 \times 10^{-6}} = 500$$

$$\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{0.4 \times 20 \times 10^{-6}}} = 354$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$= -500 \pm \sqrt{250,000 - 124,997.6} = -500 \pm 354$$

$$s_1 = -854, \qquad s_2 = -146$$



•  $\alpha > \omega_0$ , the response is overdamped

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$
  $v(t) = A_1 e^{-854t} + A_2 e^{-146t}$   
At  $t = 0$ ,  
 $v(0) = 25 = A_1 + A_2 \implies A_2 = 25 - A_1$ 

$$\frac{dv}{dt} = -854A_1e^{-854t} - 146A_2e^{-146t}$$

$$\frac{dv(0)}{dt} = 0 = -854A_1 - 146A_2$$

$$0 = 854A_1 + 146A_2$$

$$A_1 = -5.156, \qquad A_2 = 30.16$$

• The complete solution:

$$v(t) = -5.156e^{-854t} + 30.16e^{-146t} V$$

# Step Response of a Series RLC Circuit



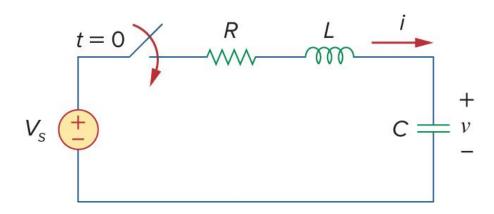
- Recall: Step response is obtained by the sudden application of a dc source.
- Apply KVL:

$$-V_S + Ri + L\frac{di}{dt} + v = 0 \Rightarrow V_S = L\frac{di}{dt} + Ri + v \qquad i = C\frac{di}{dt}$$

$$V_{S} = L \frac{d}{dt} \left( C \frac{dv}{dt} \right) + R \left( C \frac{dv}{dt} \right) + v \implies V_{S} = LC \frac{d^{2}v}{dt^{2}} + RC \frac{dv}{dt} + v$$

$$\frac{d^2v}{dt^2} + \frac{R}{L}\frac{dv}{dt} + \frac{v}{LC} = \frac{V_S}{LC}$$

- The solution of the equation has two components:
- The transient response:  $v_t(t)$
- The steady-state response  $v_{ss}(t)$



• The complete response:

$$v(t) = v_t(t) + v_{ss}(t)$$

# Step Response of a Series RLC Circuit



• The complete response:  $v(t) = v_t(t) + v_{ss}(t)$ 

$$v_t(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$
 — Overdamped  $v_t(t) = (A_1 + A_2 t) e^{-\alpha t}$  — Critically damped

$$v_t(t) = (A_1 cos \omega_d t + A_2 sin \omega_d t)e^{-\alpha t}$$
 — Underdamped

- The steady-state response: final value of  $v_{ss}(t) = v(\infty) = V_s$
- The complete solution for all cases:

$$v(t) = V_S + A_1 e^{S_1 t} + A_2 e^{S_2 t}$$
 — Overdamped 
$$v(t) = V_S + (A_1 + A_2 t) e^{-\alpha t}$$
 — Critically damped 
$$v(t) = V_S + (A_1 cos \omega_d t + A_2 sin \omega_d t) e^{-\alpha t}$$
 — Underdamped

• Constants  $A_1$  and  $A_2$  are obtained from the initial conditions.

## Example 6



For the circuit given below, find v(t) and i(t) for t>0. Consider these cases: R=5  $\Omega$ , R=4  $\Omega$ , and R=1  $\Omega$ .

#### **Solution:**

- Case 1:  $R = 5 \Omega$
- First, find initial value of inductor current and capacitor voltage.
- At t < 0, switch is closed. Inductor acts like short circuit and capacitor acts like open circuit.

$$i(0) = \frac{24}{5+1} = 4 \text{ A}$$
  $v(0) = 1i(0) = 4 \text{ V}$ 

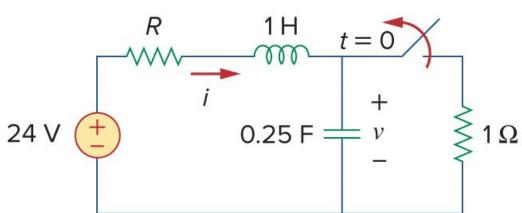
• At t > 0, switch is opened 1  $\Omega$  resistor is disconnected.

$$\alpha = \frac{R}{2L} = \frac{5}{2 \times 1} = 2.5, \quad \omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{1 \times 0.25}} = 2$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -1, -4$$

 $\alpha > \omega_0$ , we have the overdamped natural response.

$$v(t) = v_{ss} + (A_1 e^{-t} + A_2 e^{-4t})$$



 $v_{ss}$  is the steady-state response.

$$v_f = 24 \text{ V}.$$
  
 $v(0) = 4 = 24 + A_1 + A_2$   
 $-20 = A_1 + A_2$ 

$$i(0) = C \frac{dv(0)}{dt} = 4 \Rightarrow \frac{dv(0)}{dt} = \frac{4}{C} = \frac{4}{0.25} = 16$$



$$\frac{dv}{dt} = -A_1 e^{-t} - 4A_2 e^{-4t}$$

At 
$$t = 0$$
,

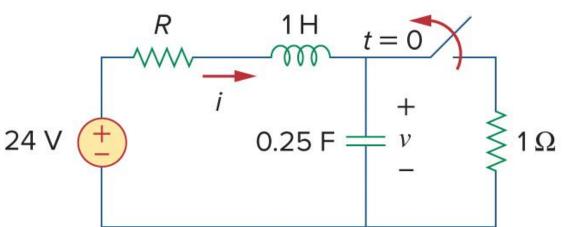
$$\frac{dv(0)}{dt} = 16 = -A_1 - 4A_2$$

$$A_1 = -64/3$$
 and  $A_2 = 4/3$ .

$$v(t) = 24 + \frac{4}{3}(-16e^{-t} + e^{-4t}) \text{ V}$$

$$i(t) = C \frac{dv}{dt}$$

$$i(t) = \frac{4}{3}(4e^{-t} - e^{-4t})$$
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- Case 2:  $R = 4 \Omega$
- First, find initial value of inductor current and capacitor voltage.
- At t < 0, switch is closed. Inductor acts like short circuit and capacitor acts like open circuit.

$$i(0) = \frac{24}{4+1} = 4.8 \text{ A}$$
  $v(0) = 1i(0) = 4.8 \text{ V}$ 

$$\alpha = \frac{R}{2L} = \frac{4}{2 \times 1} = 2 \qquad \omega_0 = 2$$

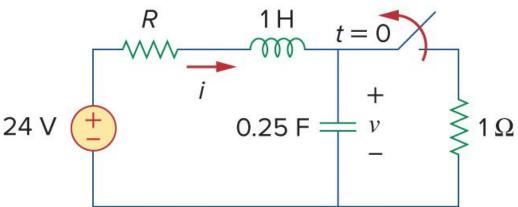
 $s_1 = s_2 = -\alpha = -2$ , the critically damped natural response.

$$v(t) = v_{ss} + (A_1 + A_2 t)e^{-2t}$$
  $v_{ss} = 24 \text{ V},$ 

$$v(t) = 24 + (A_1 + A_2 t)e^{-2t}$$

$$v(0) = 4.8 = 24 + A_1 \implies A_1 = -19.2$$

Since 
$$i(0) = C dv(0)/dt = 4.8$$
 
$$\frac{dv(0)}{dt} = \frac{4.8}{C} = 19.2$$



$$\frac{dv}{dt} = (-2A_1 - 2tA_2 + A_2)e^{-2t}$$

At 
$$t = 0$$
,  $\frac{dv(0)}{dt} = 19.2 = -2A_1 + A_2$ 

$$A_1 = -19.2$$
 and  $A_2 = -19.2$ .

$$v(t) = 24 - 19.2(1 + t)e^{-2t} V$$

$$i(t) = C\frac{dv}{dt}$$

$$i(t) = (4.8 + 9.6t)e^{-2t} A$$

#### • Case 3: $R = 1 \Omega$

$$i(0) = \frac{24}{1+1} = 12 \text{ A}$$
  $v(0) = 1i(0) = 12 \text{ V}$ 

$$\alpha = \frac{R}{2L} = \frac{1}{2 \times 1} = 0.5$$

 $\alpha = 0.5 < \omega_0 = 2$ , we have the underdamped response

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -0.5 \pm j1.936$$

$$v(t) = 24 + (A_1 \cos 1.936t + A_2 \sin 1.936t)e^{-0.5t}$$

$$v(0) = 12 = 24 + A_1 \implies A_1 = -12$$

Since 
$$i(0) = C dv(0)/dt = 12$$
,

$$\frac{dv(0)}{dt} = \frac{12}{C} = 48$$

$$\frac{dv}{dt} = e^{-0.5t}(-1.936A_1 \sin 1.936t + 1.936A_2 \cos 1.936t)$$
$$-0.5e^{-0.5t}(A_1 \cos 1.936t + A_2 \sin 1.936t)$$

At 
$$t = 0$$
,

$$\frac{dv(0)}{dt} = 48 = (-0 + 1.936A_2) - 0.5(A_1 + 0)$$

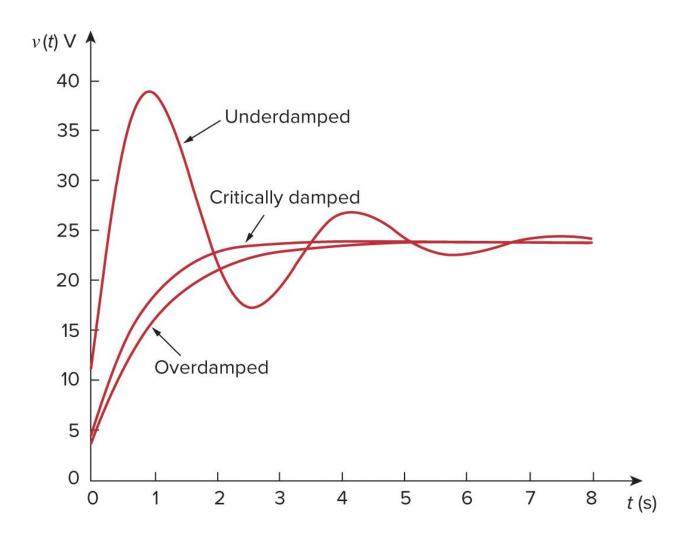
$$A_1 = -12$$
  $A_2 = 21.694,$ 

$$v(t) = 24 + (21.694 \sin 1.936t - 12 \cos 1.936t)e^{-0.5t} V$$

$$i(t) = C\frac{dv}{dt}$$

$$i(t) = (3.1 \sin 1.936t + 12 \cos 1.936t)e^{-0.5t} A$$

- Graph shown below plots the responses for the three cases. From this graph, we observe
  that the critically damped response approaches the step input of 24 V the fastest.
- The system returns to equilibrium position without oscillation for both overdamped and critically damped responses.
- The system returns to equilibrium position faster for critically damped response as compared to overdamped response.
- For underdamped response, the system crosses the equilibrium or steady-state position very quickly but will continue to oscillate around the final value.



# Step Response of a Parallel RLC Circuit



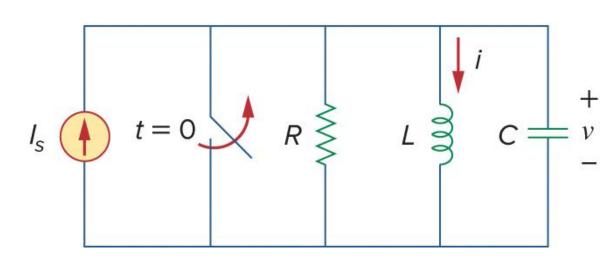
- Determine *i* due to a sudden application of a dc current.
- Apply KCL at the top node for t > 0.

$$I_{S} = \frac{v}{R} + i + C\frac{dv}{dt} \qquad v = L\frac{di}{dt} \qquad I_{S} = \frac{L\frac{di}{dt}}{R} + i + C\frac{d}{dt}\left(L\frac{di}{dt}\right)$$

$$\frac{d^2i}{dt^2} + \frac{1}{RC}\frac{di}{dt} + \frac{i}{LC} = \frac{I_s}{LC} \longrightarrow \begin{array}{c} 2^{\text{nd}} \text{ order differential} \\ \text{equation} \end{array}$$

- This equation has same characteristic equation as the source free parallel RLC circuit equation.
- Complete response:

$$i(t) = i_t(t) + i_{ss}(t)$$



# Step Response of a Parallel RLC Circuit



$$i(t)$$
: complete response  $i(t) = i_t(t) + i_{ss}(t)$   $i_t(t)$ : transient response  $i_{ss}(t) = i(\infty) = I_s$   $i_{ss}(t)$ : steady-state response

$$i(t) = I_S + A_1 e^{s_1 t} + A_2 e^{s_2 t} \longrightarrow \text{Overdamped}$$
  $i(t) = I_S + (A_1 + A_2 t) e^{-\alpha t} \longrightarrow \text{Critically damped}$   $i(t) = I_S + (A_1 cos \omega_d t + A_2 sin \omega_d t) e^{-\alpha t} \longrightarrow \text{Underdamped}$ 

• Similarly, constants  $A_1$  and  $A_2$  can be determined from the initial conditions.

# Example 7



In the circuit shown below, find i(t) and  $i_R(t)$  for t > 0.

#### **Solution:**

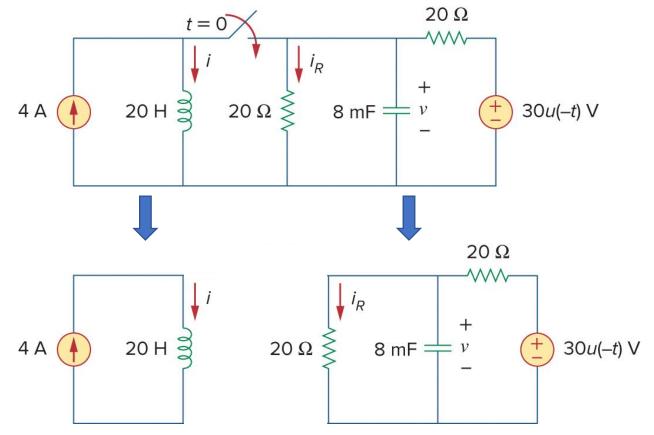
• For t < 0, switch is opened and circuit is partitioned into two independent subcircuits.

$$i(0) = 4 A$$

Recall: Step function of u(t)

$$u(t) = \begin{cases} 0 & t < 0 \\ \\ 1 & t > 0 \end{cases}$$

$$u(-t) = \begin{cases} 1 & t < 0 \\ 0 & t > 0 \end{cases}$$



When 
$$t < 0$$
,  $30u(-t) = 30$ 

When 
$$t > 0$$
,  $30u(-t) = 0$ 



• For t < 0, switch is opened and capacitor acts like open circuit.

$$v(0) = \frac{20}{20 + 20}(30) = 15 \text{ V}$$

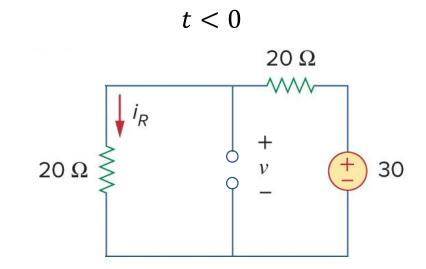
- For t > 0, switch is closed and we have a parallel RLC circuit with current source.
- For t > 0, voltage source is zero due to u(-t) = 0.

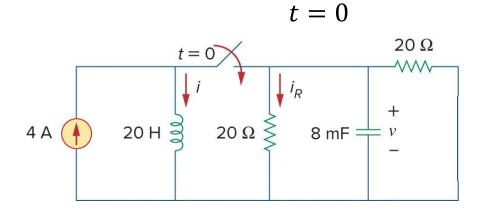
$$R = 20 \parallel 20 = 10 \Omega$$
.

$$\alpha = \frac{1}{2RC} = \frac{1}{2 \times 10 \times 8 \times 10^{-3}} = 6.25$$

$$\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{20 \times 8 \times 10^{-3}}} = 2.5$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -6.25 \pm \sqrt{39.0625 - 6.25}$$
  
= -6.25 \pm 5.7282





$$s_1 = -11.978, \qquad s_2 = -0.5218$$



Since  $\alpha > \omega_0$ , we have the overdamped case.

$$i(t) = I_s + A_1 e^{-11.978t} + A_2 e^{-0.5218t}$$

where  $I_s = 4$  is the final value of i(t).

At 
$$t = 0$$
,  $i(0) = 4 = 4 + A_1 + A_2 \implies A_2 = -A_1$ 

Taking the derivative of  $i(t) \implies \frac{di}{dt} = -11.978A_1e^{-11.978t} - 0.5218A_2e^{-0.5218t}$ 

At 
$$t = 0$$
,  $\frac{di(0)}{dt} = -11.978A_1 - 0.5218A_2$ 

$$L\frac{di(0)}{dt} = v(0) = 15 \implies \frac{di(0)}{dt} = \frac{15}{L} = \frac{15}{20} = 0.75$$

$$0.75 = (11.978 - 0.5218)A_2 \implies A_2 = 0.0655$$
  $A_1 = -0.0655$ 

$$i(t) = 4 + 0.0655(e^{-0.5218t} - e^{-11.978t}) A$$

$$v(t) = L \, di/dt$$

$$i_R(t) = \frac{v(t)}{20} = \frac{L}{20} \frac{di}{dt} = 0.785e^{-11.978t} - 0.0342e^{-0.5218t} A$$

## General Second-Order Circuits



- Other second-order circuits such as op amps
- For a given  $2^{nd}$  order circuit, determine its step response x(t) (which may be voltage or current source) by taking the following steps:
  - □ Determine the initial conditions and final value:

$$x(0) \qquad \frac{dx(0)}{dt} \qquad x(\infty)$$

- $\Box$  Turn off the independent sources and find the form of the transient response  $x_t(t)$  by applying KCL and KVL. When obtained 2<sup>nd</sup> order differential equation, determine its characteristics roots. Compare  $\alpha$  and  $\omega_0$  to figure it out what kind of response the circuit has.
- $\square$  Obtain steady-state response as  $x_{ss}(t) = x(\infty)$
- □ Total response is sum of the transient response and steady-state response:

$$x(t) = x_t(t) + x_{ss}(t)$$

 $\Box$  Finally, determine the constant of the transient response from the initial condition x(0) and  $\frac{dx(0)}{dt}$ 

# Example 8

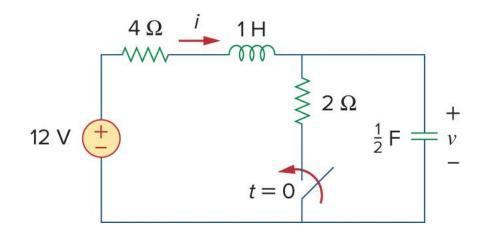


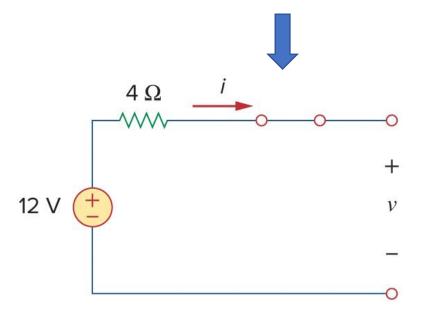
• Find the complete response v and i for t > 0 in the circuit shown below.

#### **Solution:**

- Find the initial and final values.
- $t = 0^-$ , the circuit is at steady-state and switch is opened.

$$v(0^-) = 12 \text{ V}, \qquad i(0^-) = 0$$







•  $t = 0^+$ , the switch is closed.

$$v(0^+) = v(0^-) = 12 \text{ V}, \qquad i(0^+) = i(0^-) = 0$$

• Find initial value of the 1<sup>st</sup> derivative of voltage  $\frac{dv}{dt}$ , i.e.,  $\frac{dv(0^+)}{dt}$ 

$$C dv/dt = i_C$$
 or  $dv/dt = i_C/C$ .

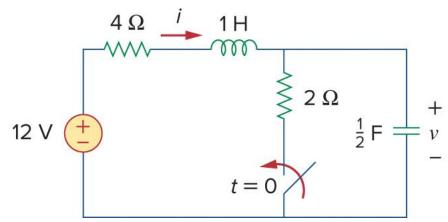
$$i(0^+) = i_C(0^+) + \frac{v(0^+)}{2}$$
 (Apply KCL at node a)

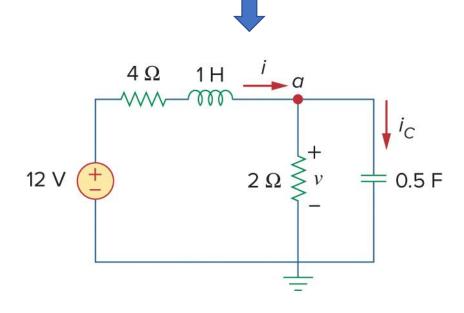
$$0 = i_C(0^+) + \frac{12}{2} \implies i_C(0^+) = -6 \text{ A}$$

$$\frac{dv(0^+)}{dt} = \frac{-6}{0.5} = -12 \text{ V/s}$$

Final value is obtained as:

$$i(\infty) = \frac{12}{4+2} = 2 \text{ A}, \qquad v(\infty) = 2i(\infty) = 4 \text{ V}$$







- Obtain transient response for t > 0 by turning of independent source
- Apply KCL at node a:

$$i = \frac{v}{2} + \frac{1}{2} \frac{dv}{dt}$$

Apply KVL to the left mesh:

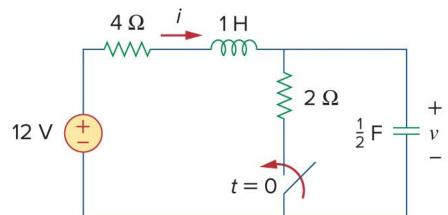
$$4i + 1\frac{di}{dt} + v = 0$$

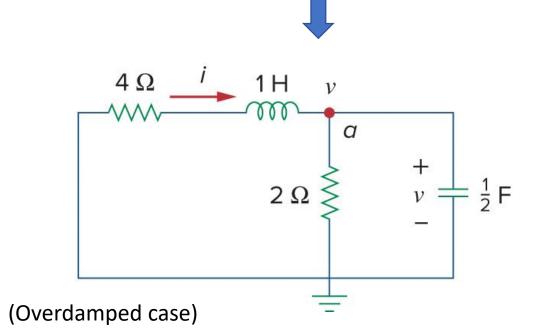
• Substitude *i* into KVL equation:

$$2v + 2\frac{dv}{dt} + \frac{1}{2}\frac{dv}{dt} + \frac{1}{2}\frac{d^2v}{dt^2} + v = 0$$

$$\frac{d^2v}{dt^2} + 5\frac{dv}{dt} + 6v = 0 \implies s^2 + 5s + 6 = 0$$

$$s = -2 \qquad s = -3$$







- Natural response:  $v_n(t) = Ae^{-2t} + Be^{-3t}$
- Steady-state response:  $v_{ss}(t) = v(\infty) = 4$
- Complete response:  $v(t) = v_t + v_{ss} = 4 + Ae^{-2t} + Be^{-3t}$

$$v(0) = 12$$
 at  $t = 0$   $12 = 4 + A + B \implies A + B = 8$ 

$$\frac{dv}{dt} = -2Ae^{-2t} - 3Be^{-3t}$$

$$-12 = -2A - 3B \implies 2A + 3B = 12$$
  $A = 12, B = -4$ 

$$v(t) = 4 + 12e^{-2t} - 4e^{-3t} V,$$

$$i = \frac{v}{2} + \frac{1}{2} \frac{dv}{dt} = 2 + 6e^{-2t} - 2e^{-3t} - 12e^{-2t} + 6e^{-3t}$$

$$= 2 - 6e^{-2t} + 4e^{-3t} A, t > 0$$