

# **MAT281E HW3**

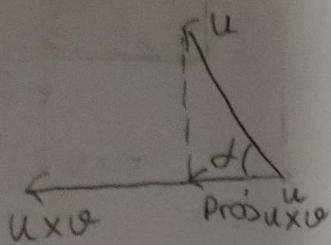
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1) 2)

1)

$$\text{Proj}_{u \times v}^u = \mathbf{0}$$



$$\text{Proj}_{u \times v}^u = \frac{\overset{\circ}{(u \times v), u}}{\|u \times v\|^2} \cdot u \times v$$

$$\text{Proj}_{u \times v}^u = \mathbf{0}$$

$$\|\text{Proj}_{u \times v}^u\| = 0$$

$$2) \|u - v\|^2 = (\sqrt{3})^2$$

$$(u - v) \cdot (u - v) = 3$$

$$\underbrace{u \cdot u - 2u \cdot v + v \cdot v}_{\|u\|^2 - 2u \cdot v + \|v\|^2} = 3 \rightarrow u \cdot v = \frac{-1}{2}$$

$$\underbrace{u \cdot v}_{-\frac{1}{2}} = \underbrace{\|u\|}_{1} \cdot \underbrace{\|v\|}_{1} \cdot \cos \alpha$$
$$\cos \alpha = -\frac{1}{2}$$

$$\|u \times v\| = \underbrace{\|u\|}_{1} \cdot \underbrace{\|v\|}_{1} \cdot \underbrace{\sin \alpha}_{\frac{\sqrt{3}}{2}} \rightarrow (\|u \times v\| \text{ cannot be negative.})$$

$$\|u \times v\| = \frac{\sqrt{3}}{2}$$

3)

$$3) \sum_{n=1}^{\infty} (\bar{a}^n)^2 \rightarrow (\bar{a}^2)^{-1} \rightarrow \frac{\bar{a}^2}{\bar{a}^2 - 1}$$

Cauchy-Schwarz Ineq:

$$\sum_{i=1}^N a_i b_i \leq \sqrt{\sum_{i=1}^N a_i^2} \cdot \sqrt{\sum_{i=1}^N b_i^2}$$

$$\sum_{n=1}^{\infty} \frac{e^{-n}}{n} \leq \sqrt{\sum_{i=1}^{\infty} e^{-2n}} \cdot \sqrt{\sum_{i=1}^{\infty} \frac{1}{n^2}}$$

$$\leq \frac{e}{\sqrt{e^2 - 1}} \cdot \frac{\pi}{\sqrt{6}}$$

$$\leq \frac{e\pi}{\sqrt{6e^2 - 6}}$$

—————  
7

4) 5)

$$4) k_1(1, 1, 2, 1) + k_2(1, -2, -2, 0) + k_3(0, 1, 1, -2) = (3, -1, 1, 4)$$

$$\left[ \begin{array}{cccc|c} 1 & 1 & 0 & 3 \\ 1 & -2 & 1 & -1 \\ 2 & -2 & 1 & 1 \\ 1 & 0 & -2 & 4 \end{array} \right] \xrightarrow{\text{RREF}} \left[ \begin{array}{cccc|c} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \begin{aligned} k_1 &= 2 \\ k_2 &= 1 \\ k_3 &= -1 \end{aligned}$$

5)

$$\begin{aligned} w_1 &= -x_1 - x_2 + x_3 \\ w_2 &= 2x_1 - x_2 - 3x_3 \\ w_3 &= -3x_2 - x_3 \end{aligned} \quad \left. \begin{array}{c} T: \underset{\text{domain}}{R^3} \rightarrow \underset{\text{codomain}}{R^3} \\ \downarrow \end{array} \right.$$

$$\left[ \begin{array}{ccc} -1 & -1 & 1 \\ 2 & -1 & -3 \\ 0 & -3 & -1 \end{array} \right] \left[ \begin{array}{c} x_1 \\ x_2 \\ x_3 \end{array} \right] \left[ \begin{array}{c} w_1 \\ w_2 \\ w_3 \end{array} \right]$$

A

x

w

$\downarrow$

Standard matrix ( $[T]$ )

The range of a matrix is column space of its standard matrix.

$$\left[ \begin{array}{ccc} -1 & -1 & 1 \\ 2 & -1 & -3 \\ 0 & -3 & -1 \end{array} \right] \xrightarrow{\text{RREF}} \left[ \begin{array}{ccc} 1 & 0 & -4/3 \\ 0 & 1 & 1/3 \\ 0 & 0 & 0 \end{array} \right] \quad c_1 \text{ and } c_2 \text{ contain lead 1's}$$

$$\underline{\text{Range}(TA) = \left\{ \left[ \begin{array}{c} -1 \\ 2 \\ 0 \end{array} \right], \left[ \begin{array}{c} -1 \\ -1 \\ -3 \end{array} \right] \right\}}$$

6)

6)

$$a) \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \underbrace{\begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix}}_T$$

$$b) \begin{array}{l} x+z=0 \text{ plane} \\ \vec{n} = (1, 0, 1) \end{array}$$

Standard basis vectors for  $\mathbb{R}^3$ :

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$u \quad v \quad z$

$$u - \left( u \cdot \frac{\vec{n}}{\|\vec{n}\|} \cdot \frac{\vec{n}}{\|\vec{n}\|} \right) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 1/2 \\ 0 \\ 1/2 \end{bmatrix} = \begin{bmatrix} 1/2 \\ 0 \\ -1/2 \end{bmatrix}$$

$$v - \left( v \cdot \frac{\vec{n}}{\|\vec{n}\|} \cdot \frac{\vec{n}}{\|\vec{n}\|} \right) = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} -$$

$$z - \left( z \cdot \frac{\vec{n}}{\|\vec{n}\|} \cdot \frac{\vec{n}}{\|\vec{n}\|} \right) = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} 1/2 \\ 0 \\ 1/2 \end{bmatrix} = \begin{bmatrix} -1/2 \\ 0 \\ 1/2 \end{bmatrix}$$

$$[T] = \begin{bmatrix} 1/2 & 0 & -1/2 \\ 0 & 1 & 0 \\ -1/2 & 0 & 1/2 \end{bmatrix}$$

$$\begin{bmatrix} 1/2 & 0 & -1/2 \\ 0 & 1 & 0 \\ -1/2 & 0 & 1/2 \end{bmatrix} \begin{bmatrix} 1 \\ -3 \\ 1 \end{bmatrix} = \underbrace{\begin{bmatrix} 0 \\ -3 \\ 0 \end{bmatrix}}_T$$

6)

c)

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 5 \end{bmatrix} = \underbrace{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}}$$

6)

d)

Reflection around  $z=y$  plane:

Standard basis:

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$x \quad y \quad z$

reflection of basis:

$$\left. \begin{array}{l} y \rightarrow \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \\ z \rightarrow \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \\ x \rightarrow \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \end{array} \right\} [T_1] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$[T_2] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos 60 & -\sin 60 \\ 0 & \sin 60 & \cos 60 \end{bmatrix}$$

$$[T] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos 60 & -\sin 60 \\ 0 & \sin 60 & \cos 60 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$[T] \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix} = \begin{bmatrix} -2 \\ 3+2\sqrt{3} \\ 3\sqrt{3}-2 \end{bmatrix}$$

6)

e)

$$[T] = \begin{bmatrix} 1/2 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1/2 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos 60 & -\sin 60 \\ 0 & \sin 60 & \cos 60 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$[T] \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix} = \underbrace{\begin{bmatrix} 0 \\ -1 - 3\sqrt{3}/2 \\ -1 \end{bmatrix}}_{\text{?}}$$

7)

7)

$$[T_1] = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[T_2] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos\theta & -\sin\theta \\ 0 & \sin\theta & \cos\theta \end{bmatrix}$$

$$[T_1][T_2] = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & \sin\theta & \cos\theta \end{bmatrix}$$

$$[T_2][T_1] = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & -\sin\theta \\ 0 & 0 & \cos\theta \end{bmatrix}$$

$[T_1][T_2]x \neq [T_2][T_1]x$

$\underbrace{T_1 \circ T_2 \neq T_2 \circ T_1}_{\nearrow}$

8)

8)

a) If a linear transformation is one-to-one, then standard matrix is invertible and vice versa.

$$\left[ \begin{array}{ccc} 1 & 1 & -1 \\ 2 & -3 & -1 \\ 5 & 6 & -4 \end{array} \right] \rightarrow \left[ \begin{array}{ccc} 1 & 1 & -1 \\ 0 & -5 & 1 \\ 0 & 0 & 6/5 \end{array} \right] \rightarrow \text{matrix is invertible, transformation is one-to-one } (\det \neq 0)$$

$$\left[ \begin{array}{ccc|ccc} 1 & 1 & -1 & 1 & 0 & 0 \\ 2 & -3 & -1 & 0 & 1 & 0 \\ 5 & 6 & -4 & 0 & 0 & 1 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -3 & 1/3 & 2/3 \\ 0 & 1 & 0 & -1/2 & -1/6 & 1/6 \\ 0 & 0 & 1 & -9/2 & 1/6 & 5/6 \end{array} \right]$$

$T^{-1}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  and  $[T]^{-1}$

For the range:

Range of  $T_A$  is the column space of A:

$$\left[ \begin{array}{ccc} 1 & 1 & -1 \\ 2 & -3 & -1 \\ 5 & 6 & -4 \end{array} \right] \xrightarrow{\text{RREF}} \left[ \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right] \quad c_1, c_2 \text{ and } c_3 \text{ contain lead 1's}$$

$$\text{Range}(T) = \left\{ \begin{bmatrix} 1 \\ 2 \\ 5 \end{bmatrix}, \begin{bmatrix} 1 \\ -3 \\ 6 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ -4 \end{bmatrix} \right\}$$

Codomain  $\rightarrow \underline{\mathbb{R}^3}$

The range is a subset of codomain.

8)

b)

$$\begin{bmatrix} 1 & -3 & -1 \\ 1 & 1 & -1 \\ 1 & 0 & -1 \end{bmatrix} = [T] \rightarrow \begin{bmatrix} 1 & -3 & -1 \\ 0 & 4 & 0 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \det = 0$$

the matrix is many-to-one

There is no inverse transformation. ↙

Range:

$$\begin{bmatrix} 1 & -3 & -1 \\ 1 & 1 & -1 \\ 1 & 0 & -1 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

c<sub>1</sub> and c<sub>2</sub> contain lead 1's

$$\text{Range}(TA) = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -3 \\ 1 \\ 0 \end{bmatrix} \right\}$$

codomain is  $\mathbb{R}^3$

the range is a subset of the codomain. ↘

9)

9) Let  $\vec{u}$  and  $\vec{v}$  in  $\mathbb{R}^2$ ,  $c$  and  $d$  are scalar.

$$T(c\vec{u} + d\vec{v}) = T\left(\begin{bmatrix} cu_1 + dv_1 \\ cu_2 + dv_2 \end{bmatrix}\right) = \begin{bmatrix} 2(cu_1 + dv_1) + cu_2 + dv_2 \\ 1 - (cu_1 + dv_1) \end{bmatrix}$$

$$\begin{aligned} T(c\vec{u}) + T(d\vec{v}) &= T\left(\begin{bmatrix} cu_1 \\ cu_2 \end{bmatrix}\right) + T\left(\begin{bmatrix} dv_1 \\ dv_2 \end{bmatrix}\right) \\ &= \begin{bmatrix} 2cu_1 + cu_2 \\ 1 - cu_1 \end{bmatrix} + \begin{bmatrix} 2dv_1 + dv_2 \\ 1 - dv_1 \end{bmatrix} \\ &= \begin{bmatrix} 2cu_1 + cu_2 + 2dv_1 + dv_2 \\ 2 - cu_1 - dv_1 \end{bmatrix} \end{aligned}$$

$$\begin{bmatrix} 2cu_1 + 2dv_1 + cu_2 + dv_2 \\ 1 - cu_1 - dv_1 \end{bmatrix} \neq \begin{bmatrix} 2cu_1 + cu_2 + 2dv_1 + dv_2 \\ 2 - cu_1 - dv_1 \end{bmatrix}$$

$$T(c\vec{u} + d\vec{v}) \neq T(c\vec{u}) + T(d\vec{v})$$

Transformation is not linear

10)

(O)

$$A(x) = [T]x + t$$

$$A(x) = \begin{bmatrix} T_1 & T_2 & T_3 \\ T_4 & T_5 & T_6 \\ T_7 & T_8 & T_9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} t_1 \\ t_2 \\ t_3 \end{bmatrix}$$

$$A(x) = \begin{bmatrix} T_1 x_1 + T_2 x_2 + T_3 x_3 + t_1 \\ T_4 x_1 + T_5 x_2 + T_6 x_3 + t_2 \\ T_7 x_1 + T_8 x_2 + T_9 x_3 + t_3 \end{bmatrix}$$

$$\begin{bmatrix} A(x) \\ 1 \end{bmatrix} = \begin{bmatrix} T_1 & T_2 & T_3 & t_1 \\ T_4 & T_5 & T_6 & t_2 \\ T_7 & T_8 & T_9 & t_3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ 1 \end{bmatrix}$$

$$\underbrace{\begin{bmatrix} A(x) \\ 1 \end{bmatrix}}_{Ax} = \underbrace{\begin{bmatrix} [T] & t \\ 0 \dots 0 & 1 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x \\ 1 \end{bmatrix}}_x$$

$$A_{4 \times 4} = \begin{bmatrix} [T] & t \\ 0 \dots 0 & 1 \end{bmatrix}$$

11)

$$(1) \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \xrightarrow{\text{projection onto } x-z \text{ plane}} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \xrightarrow{\text{Rotation around } y \text{ axis by } 60^\circ} \begin{bmatrix} \cos 60 & 0 & \sin 60 \\ 0 & 1 & 0 \\ -\sin 60 & 0 & \cos 60 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1/2 \\ 0 \\ -\sqrt{3}/2 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \xrightarrow{\text{projection onto } x-z \text{ plane}} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \xrightarrow{\text{Rotation around } y \text{ axis by } 60^\circ} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \xrightarrow{\text{projection onto } x-z \text{ plane}} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \xrightarrow{\text{Rotation around } y \text{ axis by } 60^\circ} \begin{bmatrix} \cos 60 & 0 & \sin 60 \\ 0 & 1 & 0 \\ -\sin 60 & 0 & \cos 60 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} \sqrt{3}/2 \\ 0 \\ 1/2 \end{bmatrix}$$

$$[T] = \underbrace{\begin{bmatrix} 1/2 & 0 & \sqrt{3}/2 \\ 0 & 0 & 0 \\ -\sqrt{3}/2 & 0 & 1/2 \end{bmatrix}}_7$$

12)

(2) If the standard matrix of the linear transformation is invertible, the transformation is one-to-one. If standard matrix is not invertible, then transformation is many-to-one.

$[T_1]$  is singular,  $[T_2]$  has an inverse.

$$\det = 0 \quad \det \neq 0$$

$$\det([T_1][T_2]) = \underbrace{\det([T_1])}_{0} \cdot \det([T_2]) = 0$$

$T_1 \circ T_2$  is not invertible.

$$\det([T_2][T_1]) = \det([T_2]) \cdot \underbrace{\det([T_1])}_{0} = 0$$

$T_2 \circ T_1$  is not invertible.

13)

(3)

a) The set is a vector space. Every plane through the origin is a vector space.

c) There is no zero vector. The set cannot be a vector space.

b) The set contains only single object which is zero vector  $(0,0,0)$ . All of axioms are satisfied. The set is a vector space which is called zero vector space.

d) The set cannot be a vector space. If  $k$  is any scalar and  $u$  is in  $V$ ,  $ku$  must be in  $V$ .

Ex:  $u = \left(\frac{1}{2}, 0\right)$   $k=10$

$\underline{u = (5,0)}$  is not in  $V$

14)

(14)

a)  $\begin{bmatrix} a_1 & b_1 \\ a_1+b_1 & 0 \end{bmatrix} + \begin{bmatrix} a_2 & b_2 \\ a_2+b_2 & 0 \end{bmatrix} = \begin{bmatrix} a_1+a_2 & b_1+b_2 \\ a_1+b_1+a_2+b_2 & 0 \end{bmatrix}$

$$\begin{array}{c} a \\ a_1+a_2 \\ a_1+b_1+a_2+b_2 \\ a+b \end{array}$$

✓

$k \begin{bmatrix} a_1 & b_1 \\ a_1+b_1 & 0 \end{bmatrix} = \begin{bmatrix} ka_1 & kb_1 \\ k(a_1+b_1) & 0 \end{bmatrix}$

✓

$\begin{bmatrix} a & b \\ a+b & 0 \end{bmatrix}$  is a subset of all  $2 \times 2$  matrices.

b)  $k \begin{bmatrix} a_1 & b_1 \\ a_1+a_2 & 0 \end{bmatrix} = \begin{bmatrix} ka_1 & kb_1 \\ ka_1+b_1 & 0 \end{bmatrix}$  → The matrix is not a subset.

$ka_1+b_1 = k^2a_1+b_1$  cannot hold except  $\frac{k=1}{k=0}$

c)  $k \begin{bmatrix} a_1 & b_1 \\ a_1+b_1 & 1 \end{bmatrix} = \begin{bmatrix} ka_1 & kb_1 \\ ka_1+b_1 & k \end{bmatrix}$  → The matrix is not a subset.

$k=1$  cannot hold except  $k=1$

15)

(15)

Let  $f(x)$  is discontinuous at the origin,

$g(x) = -f(x)$  which is discontinuous at the origin,

$$g(x) + f(x) = 0 \quad \text{and} \quad y=0 \notin W.$$

The set of functions with discontinuity at the origin cannot form a subspace.

16)

16)

Let  $A$  and  $A'$  is singular:

$$\det(A) = \det(A') = 0$$

$$A = \begin{bmatrix} a & 0 \\ 0 & 0 \end{bmatrix} \rightarrow \det(A) = \begin{vmatrix} a & 0 \\ 0 & 0 \end{vmatrix} = 0 \quad \left. \begin{array}{l} \\ \end{array} \right) A + A' = \begin{bmatrix} a & 0 \\ 0 & c \end{bmatrix} \rightarrow \begin{vmatrix} a & 0 \\ 0 & c \end{vmatrix} \neq 0$$
$$A' = \begin{bmatrix} 0 & 0 \\ 0 & c \end{bmatrix} \rightarrow \det(A') = \begin{vmatrix} 0 & 0 \\ 0 & c \end{vmatrix} = 0 \quad \left. \begin{array}{l} \\ \end{array} \right)$$

Set of singular matrices with  $n \times n$  cannot be a subspace.

Let  $B$  and  $B'$  is invertible:

$$B = \begin{bmatrix} a & 0 \\ 0 & x \end{bmatrix} \quad \left. \begin{array}{l} \\ \end{array} \right) B + B' = \begin{bmatrix} a & a \\ x & x \end{bmatrix} \rightarrow \begin{vmatrix} a & a \\ x & x \end{vmatrix} = 0$$
$$B' = \begin{bmatrix} 0 & a \\ x & 0 \end{bmatrix} \quad \left. \begin{array}{l} \\ \end{array} \right)$$

Set of invertible matrices with  $n \times n$  cannot be a subspace.

17)

(17)

a)

$$\begin{bmatrix} 1 & 0 & -2 & 2 \\ 2 & 1 & 4 & -4 \\ 1 & -1 & 3 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -2 & 2 & 0 \\ 2 & 1 & 4 & -4 & 0 \\ 1 & -1 & 3 & 0 & 0 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 0 & 6/13 & 0 \\ 0 & 1 & 0 & -24/13 & 0 \\ 0 & 0 & 1 & -10/13 & 0 \end{bmatrix}$$

$$w=t$$

$$z=10t/13$$

$$y=24t/13$$

$$x=-6t/13$$

$$\begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = t \begin{bmatrix} -6/13 \\ 24/13 \\ 10/13 \\ 1 \end{bmatrix}$$

1 free variable,

The solution space is the line through the origin and parallel to the vector  $v = (-\frac{6}{13}, \frac{24}{13}, \frac{10}{13}, 1)$

$$x = -6t/13$$

$$y = 24t/13$$

$$z = 10t/13$$

$$w = t$$

Parametric equations of the line.

(17)

b)

$$A = \left[ \begin{array}{cccc|c} 1 & 0 & -2 & 2 & 0 \\ 2 & 1 & 4 & -4 & 0 \end{array} \right] \xrightarrow{\text{RREF}} \left[ \begin{array}{cccc|c} 1 & 0 & -2 & 2 & 0 \\ 0 & 1 & 8 & -8 & 0 \end{array} \right]$$

$$w = t$$

$$z = s$$

$$y = 8t - 8s$$

$$x = 2s - 2t$$

$$\begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = s \begin{bmatrix} 2 \\ -8 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -2 \\ 8 \\ 0 \\ 1 \end{bmatrix}$$

Two free variable,

The solution space is a plane.

$$(2s - 2t, 8t - 8s, s, t)$$

(17)

c)  $\left[ \begin{array}{cccc} 1 & 0 & -2 & 2 \\ 2 & 1 & 4 & -4 \\ 0 & 1 & 6 & -6 \end{array} \right] \xrightarrow{\text{RREF}} \left[ \begin{array}{cccc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{array} \right]$

$w = s$

$z = s$

$y = 0$

$x = 0$

$\left[ \begin{array}{c} x \\ y \\ z \\ w \end{array} \right] = s \left[ \begin{array}{c} 0 \\ 0 \\ 1 \\ 1 \end{array} \right]$

1 free variable,

The solution space is the line through the origin and parallel to the vector  $v = (0, 0, 1, 1)$

$$\left. \begin{array}{l} x=0 \\ y=0 \\ z=t \\ w=t \end{array} \right\}$$
 Parametric equation of the line.

(17)

d)

$\left[ \begin{array}{cccc} 1 & 0 & -2 & 0 \\ 2 & 0 & -4 & 0 \\ 0 & 1 & 6 & 0 \\ -1 & 0 & 8 & 0 \end{array} \right] \xrightarrow{\text{RREF}} \left[ \begin{array}{cccc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$

$z = 0$

$y = 0$

$x = 0$

$\left[ \begin{array}{c} x \\ y \\ z \\ w \end{array} \right] = \left[ \begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array} \right]$

the Solution space is origin  $\{0\}$

18)

(18) a)

$$\left[ \begin{array}{ccc|c} 4 & -2 & 0 & x \\ 3 & 0 & 3 & y \\ 2 & -1 & 0 & z \\ 1 & 0 & 1 & w \end{array} \right] \xrightarrow{\text{RREF}} \left[ \begin{array}{cccc} 1 & 0 & 1 & -y/3 \\ 0 & 1 & 2 & (-x/2) + (2y/3) \\ 0 & 0 & 0 & (-x/2) + z \\ 0 & 0 & 0 & w - y/3 \end{array} \right]$$

$$E = \left\{ (x, y, z, w) \in \mathbb{R}^4 \mid w - \frac{y}{3} = 0 \text{ ; } \frac{-x}{2} + z = 0 \right\}$$

b)

$$\left[ \begin{array}{ccc|c} 4 & -2 & 0 & k_1 \\ 3 & 0 & 3 & k_2 \\ 2 & -1 & 0 & k_3 \\ 1 & 0 & 1 & 0 \end{array} \right] \xrightarrow{4 \times 3} \left[ \begin{array}{c} k_1 \\ k_2 \\ k_3 \\ 0 \end{array} \right] = \left[ \begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array} \right]$$

$$\left[ \begin{array}{cccc} 4 & -2 & 0 & 0 \\ 3 & 0 & 3 & 0 \\ 2 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{array} \right] \xrightarrow{\text{RREF}} \left[ \begin{array}{cccc} 1 & 0 & 1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\begin{pmatrix} k_3 = t \\ k_2 = -2t \\ k_1 = -t \end{pmatrix} \quad \begin{matrix} \text{Inf. Many solution} \\ \text{vectors are linearly} \\ \text{dependent.} \end{matrix}$$

18)

c)  $v_1$  and  $v_2$  are linearly independent.  $v_1, v_2$  and 2 standard basis vectors can be used as basis for  $\mathbb{R}^4$

$$S = \left\{ \left[ \begin{array}{c} 4 \\ 3 \\ 2 \\ 1 \end{array} \right], \left[ \begin{array}{c} -2 \\ 0 \\ -1 \\ 0 \end{array} \right], \left[ \begin{array}{c} 0 \\ 0 \\ 0 \\ 1 \end{array} \right], \left[ \begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array} \right] \right\}$$

19)

(9)

$$W = \begin{vmatrix} \cos 2x & \cos^2 x - \sin^2 x \\ -2\sin 2x & -4\sin x \cdot \cos x \end{vmatrix}$$

$$= -4 \cdot \sin x \cdot \cos x = -2 \cdot \sin 2x$$

$$W = \cancel{-2 \cdot \sin 2x} (\cos 2x) - \cancel{(-2 \sin x)} (\cos^2 x - \sin^2 x)$$

$$W = \cos 2x - (\cos^2 x - \sin^2 x)$$

$W = 0 \rightarrow f_1(x)$  and  $f_2(x)$  are linearly dependent.

20)

$$20) \begin{bmatrix} 1 & 1 & 1 & 0 \\ -2 & 2 & 0 & 0 \\ 0 & 4 & -1 & 7 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 0 & 7/6 \\ 0 & 1 & 0 & 7/6 \\ 0 & 0 & 1 & -7/3 \end{bmatrix}$$

$c_1, c_2$  and  $c_3$  are linearly independent.  
(lead 1's)

set of basis  $S = \left\{ \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \right\}$ .

$$u_4 = \begin{bmatrix} 0 \\ 0 \\ 7 \end{bmatrix} = \frac{7}{6}u_1 + \frac{7}{6}u_2 - \frac{7}{3}u_3$$

$\dim(W) = \text{Number of vectors in a basis} \neq 3$  vector

21) 22)

21) Let  $u_1, u_2, u_3$  are independent vectors and  $u_4 = u_1 + u_2 + u_3$   
 $S = \{u_1, u_2, u_3, u_4\}$  is linearly dependent set since,

$$k_1 u_1 + k_2 u_2 + k_3 u_3 + k_4 u_4 = 0$$

$$k_1 u_1 + k_2 u_2 + k_3 u_3 + k_4 u_1 + k_4 u_2 + k_4 u_3 = 0$$

$$\begin{cases} k_1 = -s \\ k_2 = -s \\ k_3 = -s \\ k_4 = s \end{cases}$$

There are inf many solutions.

If  $S - u_4 \rightarrow S' = \{u_1, u_2, u_3\}$  will be a linearly independent set.

$S'$  cannot be a basis, because 3 vectors cannot span  $\mathbb{R}^4$

22) Let  $u_1 = \begin{bmatrix} x \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad u_2 = \begin{bmatrix} 0 \\ y \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad u_3 = \begin{bmatrix} 0 \\ 0 \\ z \\ 0 \\ 0 \end{bmatrix} \quad u_4 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ t \\ 0 \end{bmatrix}$

$S = \{u_1, u_2, u_3, u_4\}$  is linearly independent set.

If  $u_5 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ q \end{bmatrix}$  is added to  $S \rightarrow S' = \{u_1, u_2, u_3, u_4, u_5\}$

is also a linear independent set. Since,

if  $\begin{bmatrix} k_1 x \\ k_2 y \\ k_3 z \\ k_4 t \\ k_5 q \end{bmatrix} = 0$ , Only solution is  $k_1 = k_2 = k_3 = k_4 = k_5 = 0$

23)

23)  $\text{Proj}_{u \times v}^w$  has the same direction with  $u \times v$ . Because of  $u \times v \perp u$  and  $v$ ,  $\text{Proj}_{u \times v}^w \perp u, v$  (same direction with  $u \times v$ ).  
 $u$  and  $v$  are linearly independent then  $\text{Proj}_{u \times v}^w, u$  and  $v$  must be linearly independent.

24)

24)  $2 \times 2$  matrices can contain maximum 4 independent matrices. Other matrix must be obtained as linear combination of other independent matrices.

Ex:

$$a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

can be  
any matrix.

$3 \times 3$  matrices can contain maximum 9 independent matrices.

$3 \times 3$  matrices can contain maximum 9 independent matrices.

If there are 4 independent matrices, last matrix may be 5.

independent matrix. Therefore every  $3 \times 3$  matrix may not be obtained as linear combination of other four matrices.

Ex:

$$a \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \neq$$

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

25)

25)

a)  $\vartheta_1 + \vartheta_2 + \vartheta_3 + \vartheta_4 = 0 \rightarrow k_1\vartheta_1 + k_2\vartheta_2 + k_3\vartheta_3 + k_4\vartheta_4 = 0 \rightarrow k_1 = 1, k_2 = 0, k_3 = 0, k_4 = 0$  } Vectors  
the set cannot be basis. } are linearly depended.

b)  $k_1(-x, y) + k_2(x, -y) = 0$

$$\begin{matrix} k_1 = -1 & k_2 = 1 \\ k_1 = -2 & k_2 = 2 \\ | & | \end{matrix} \left. \begin{array}{l} \text{inf. many constants. Vectors are linearly} \\ \text{dependent. The set } \underline{\text{cannot be basis}} \end{array} \right. \begin{array}{l} \text{the set cannot be basis} \\ \hline \end{array}$$

c)

$$\begin{bmatrix} 1 & 1 & -1 \\ 2 & 2 & 2 \\ 3 & 0 & 6 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \text{Vectors are linearly independent. } \checkmark$$

# independent vectors = dimension of vector space  $\checkmark$

the set can be basis.

25)

d)

the set of vectors that contains zero vector is always a linearly dependent: ~~the set cannot be basis.~~

If  $u$  is zero vector,

$$k_1u + k_2v + k_3z \dots = 0 \rightarrow k_1 \text{ can be any real number.}$$

the set cannot be basis.

26)

26)

$$x_1 \cdot (2, -2, 0) + x_2 \cdot (0, 1, -1) + x_3 \cdot (1, 5, 4) = (1, 1, 1)$$

$$\begin{bmatrix} 2 & 0 & 1 \\ -2 & 1 & 5 \\ 0 & -1 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 0 & 1 & 1 \\ -2 & 1 & 5 & 1 \\ 0 & -1 & 4 & 1 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 0 & 7/20 \\ 0 & 1 & 0 & 1/5 \\ 0 & 0 & 1 & 3/10 \end{bmatrix}$$

$$x_1 = 7/20 \quad x_2 = 1/5 \quad x_3 = 3/10$$

$$\underline{w(s) = (7/20, 1/5, 3/10)}$$

27)

27)

a)  $\begin{bmatrix} 2 & 0 & 1 & 1 \\ -1 & 1 & -1 & 0 \\ -1 & 3 & -2 & 1 \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \\ k_4 \end{bmatrix} = 0$

$$\begin{bmatrix} 2 & 0 & 1 & 1 & 0 \\ -1 & 1 & -1 & 0 & 0 \\ -1 & 3 & -2 & 1 & 0 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 1/2 & 1/2 & 0 \\ 0 & 1 & -1/2 & 1/2 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\left. \begin{array}{l} k_4 = s \\ k_3 = t \\ k_2 = t/2 - s/2 \\ k_1 = -t/2 - s/2 \end{array} \right\} \text{Inf. many solutions.}$$

$S = \{v_1, v_2, v_3, v_4\}$  is a linearly dependent set.

b)

$$\begin{bmatrix} 2 & 0 & 1 & 1 \\ -1 & 1 & -1 & 0 \\ -1 & 3 & -2 & 1 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 1/2 & 1/2 \\ 0 & 1 & -1/2 & 1/2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$c_1$  and  $c_2$  contains lead 1's.

basis of the space  $S = \left\{ \underbrace{\begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}} \right\}$

c)

dimension of the space = number of independent vectors

$$= \frac{2}{1}$$

27)

d)

$$\text{Span}\{v_1, v_2, v_3, v_4\} = \text{Span}\{v_1, v_2\}$$

$v_1$  and  $v_2$  spans a plane in  $\mathbb{R}^3$

$$(2, -1, -1) \times (0, 1, 3) = (-2, -6, 2) \rightarrow \text{normal of the plane}$$

$$-2x - 6y + 2z = 0 \rightarrow \text{plane.}$$

e) If vector  $w$  in the span,  $w$  can be expressible as linear combination of vectors:

$$\begin{bmatrix} 2 & 0 & 1 & 1 \\ -1 & 1 & -1 & 0 \\ -1 & 3 & -2 & 1 \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \\ k_4 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 0 & 1 & 1 & 2 \\ -1 & 1 & -1 & 0 & 2 \\ -1 & 3 & -2 & 1 & 0 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 1/2 & 1/2 & 0 \\ 0 & 1 & -1/2 & 1/2 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \rightarrow$$

There is no solution.  
 $w$  is not in span of the given vectors.

28)

28) By the definition, the plane must pass through the origin to be a vector space. Given plane is not through the origin, the basis cannot be found.

29)

29)

$$\begin{bmatrix} 1 & 1 & 1 & -1 & 0 \\ 2 & -1 & -1 & 2 & 0 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 0 & 1/3 & 0 \\ 0 & 1 & 1 & -4/3 & 0 \end{bmatrix}$$

$$w = t$$

$$z = s$$

$$y = \frac{4t}{3} - s$$

$$x = \frac{-t}{3}$$

$$\begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = t \begin{bmatrix} -1/3 \\ 4/3 \\ 0 \\ 1 \end{bmatrix} + s \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix}$$

$$\text{Basis} \rightarrow \left\{ \begin{bmatrix} -1/3 \\ 4/3 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} \right\}$$

$\dim(w) = \# \text{ basis vectors}$   
 $\Rightarrow 2$

30) 31)

30)

$$t = \frac{x+1}{3} + \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = x \begin{bmatrix} 1/3 \\ 1/3 \\ -1 \end{bmatrix}$$

$$y = \frac{x+1}{3} - \frac{1}{3} = \frac{x}{3}$$

$$z = 1 - 3\left(\frac{x+1}{3}\right) = -x$$

$$\text{Basis of line} \Rightarrow \begin{bmatrix} 1/3 \\ -1 \end{bmatrix}$$

31)

$$\begin{bmatrix} 1 & 3 & -1 & 1 \\ 0 & -2 & 1 & 2 \\ 1 & 1 & 0 & 3 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 1/2 & 4 \\ 0 & 1 & -1/2 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

basis

$$\text{set of basis } S = \left\{ 1+x^2, 3-2x+x^2 \right\}$$

dimension of subspace = 2

2 basis cannot span the space of second order polynomials

Any standard basis vector can be added to span  
the space of the second order polynomials.

$(\dim(P_2)=3)$

$$\text{basis of the second order polynomials } S = \left\{ 1+x^2, 3-2x+x^2, \underbrace{x^2+0x+0}_{[0 \ 0 \ 1]} \right\}$$