

## Reducible Second-Order Equations

A *second-order differential equation* involves the second derivative of the unknown function  $y(x)$ , and thus has the general form

$$F(x, y, y', y'') = 0. \quad (32)$$

If *either* the dependent variable  $y$  or the independent variable  $x$  is missing from a second-order equation, then it is easily reduced by a simple substitution to a first-order equation that may be solvable by the methods of this chapter.

**Dependent variable  $y$  missing.** If  $y$  is missing, then Eq. (32) takes the form

$$F(x, y', y'') = 0. \quad (33)$$

Then the substitution

$$p = y' = \frac{dy}{dx}, \quad y'' = \frac{dp}{dx} \quad (34)$$

results in the *first-order* differential equation

$$F(x, p, p') = 0.$$

If we can solve this equation for a general solution  $p(x, C_1)$  involving an arbitrary constant  $C_1$ , then we need only write

$$y(x) = \int y'(x) dx = \int p(x, C_1) dx + C_2$$

to get a solution of Eq. (33) that involves two arbitrary constants  $C_1$  and  $C_2$  (as is to be expected in the case of a second-order differential equation).

Example:

Solve the equation  $xy'' + 2y' = 6x$  in which the dependent variable  $y$  is missing.

$$p = y' \quad y'' = p' \quad \Rightarrow \quad xp' + 2p = 6x$$

$$\begin{aligned} y + p(x)y &= Q(x) & \Rightarrow & \quad p' + \frac{2}{x}p = 6 & \text{linear 1st order ODE.} \\ p(x) &= e^{\int p(x)dx} & \int p(x)dx &= \int \frac{2}{x}dx & = 2\ln x & = \ln x^2 \\ p(x) &= e & = e &= e &= e &= x^2 \end{aligned}$$

$$x^2p' + 2xp = 6x^2$$

$$p_x(x^2p) = 6x^2 \quad \Rightarrow \quad x^2p = 2x^3 + C_1 \quad \Rightarrow \quad p = 2x + \frac{C_1}{x^2}$$

$$p = y' \Rightarrow y(x) = \int p dx = x^2 - \frac{C_1}{x} + C_2$$

**Independent variable  $x$  missing.** If  $x$  is missing, then Eq. (32) takes the form

$$F(y, y', y'') = 0. \quad (35)$$

Then the substitution

$$\begin{aligned} p &= y' = \frac{dy}{dx}, & y'' &= \frac{dp}{dx} = \frac{dp}{dy} \frac{dy}{dx} = p \frac{dp}{dy} \\ \underline{p} &= \underline{p(y)} \end{aligned} \quad (36)$$

results in the *first-order* differential equation

$$F\left(y, p, p \frac{dp}{dy}\right) = 0$$

for  $p$  as a function of  $y$ . If we can solve this equation for a general solution  $p(y, C_1)$  involving an arbitrary constant  $C_1$ , then (assuming that  $y' \neq 0$ ) we need only write

$$x(y) = \int \frac{dx}{dy} dy = \int \frac{1}{dy/dx} dy = \int \frac{1}{p} dy = \int \frac{dy}{p(y, C_1)} + C_2.$$

If the final integral  $P = \int (1/p) dy$  can be evaluated, the result is an implicit solution  $x(y) = P(y, C_1) + C_2$  of our second-order differential equation.

Example:

$$, \quad y^7 = (y')^2$$

Solve the equation  $yy'' = (y')^2$  in which the independent variable  $x$  is missing.

$$\rho = y^1, \quad y'' = \rho \cdot \frac{d\rho}{dy}$$

$$y \cdot \rho \frac{d\rho}{dy} = \rho^2, \quad \rho \neq 0$$

$$\frac{d\rho}{\rho} = \frac{dy}{y} \Rightarrow \ln \rho = \ln y + \ln C_1$$
$$\rho = C_1 y$$

$$\rho = y^1 \Rightarrow \frac{dy}{dx} = C_1 y \Rightarrow \frac{dy}{y} = C_1 dx$$
$$\Rightarrow \ln y = C_1 x + \ln C_2$$
$$y = C_2 e^{C_1 x}$$

1st order DE

$$\frac{dy}{dx} = f(x,y)$$

Separable

$$y' = F(x) \cdot g(y)$$

Linear

$$\frac{dy}{dx} + P(x)y = Q(x)$$

$$P(x) = e^{\int p(x) dx}$$

$$D_x(P(x) \cdot y) = P(x)Q(x)$$

$$P(x) \cdot y = \int P(x)Q(x) dx$$

Substitution

Homogeneous

$$y' = f\left(\frac{y}{x}\right)$$

$$v = \frac{y}{x}, y = vx$$

$$v + xv' = f(v)$$

$$\frac{dv}{f(v)-v} = \frac{dx}{x}$$

separable

Bernoulli

$$\frac{dy}{dx} + P(x)y = Q(x)y^n$$

$$v = y^{1-n}$$

$$v' = (1-n)y^{-n} \cdot y'$$

$$v' + (1-n)vPv = (1-n)Q$$

↓  
Linear 1st order

Exact

$$\int \frac{dy}{G(y)} = \int \frac{dx}{F(x)}$$

$$P(x) \cdot y = \int P(x)Q(x) dx$$

$$P(x) = e^{\int p(x) dx}$$

$$P(x)Q(x) = \int P(x)Q(x) dx$$

$$P(x)Q(x) = \int P(x)Q(x) dx$$

$$M(x,y)dx + N(x,y)dy = 0$$

$$My = Nx \text{. Find } F(x,y) \text{ such that } F_x = M, F_y = N.$$

$$F_x = M \Rightarrow F(x,y) = \int M(x,y) dx + g(y) \quad F_y = N \Rightarrow \frac{d}{dy} \left( \int M(x,y) dx + g(y) \right) = N$$

$$F(x,y) = C.$$

## Review Problems

Find general solutions of the following differential equations.

①  $2x^2y - x^3y' = y^3$

$$y' = \frac{2x^2y - y^3}{x^3} = 2 \cdot \frac{y}{x} - \left(\frac{y}{x}\right)^3 \quad \text{homogeneous.}$$

$$v = \frac{y}{x}, \quad y = vx \quad \frac{dy}{dx} = \frac{dv}{dx} \cdot x + v = 2v - v^3$$

$$x \frac{dv}{dx} = v - v^3 \Rightarrow \frac{dv}{v-v^3} = \frac{dx}{x} \quad \frac{dv}{v(v-1)(v+1)} = -\frac{dx}{x}$$

separable

$$\frac{1}{v(v-1)(v+1)} = \frac{A}{v} + \frac{B}{v-1} + \frac{C}{v+1}$$

$$1 = A(v^2-1) + B(v^2+v) + C(v^2-v)$$

$$v=0 \Rightarrow A=-1, \quad v=1 \Rightarrow B=1/2, \quad v=-1 \Rightarrow C=1/2$$

Factor in denominator	Term in partial fraction decomposition
$ax + b$	$\frac{A}{ax + b}$
$(ax + b)^k$	$\frac{A_1}{ax + b} + \frac{A_2}{(ax + b)^2} + \cdots + \frac{A_k}{(ax + b)^k}, k = 1, 2, 3, \dots$
$ax^2 + bx + c$	$\frac{Ax + B}{ax^2 + bx + c}$
$(ax^2 + bx + c)^k$	$\frac{A_1x + B_1}{ax^2 + bx + c} + \frac{A_2x + B_2}{(ax^2 + bx + c)^2} + \cdots + \frac{A_kx + B_k}{(ax^2 + bx + c)^k}, k = 1, 2, 3, \dots$

$$-\int \frac{dv}{v} + \frac{1}{2} \int \frac{dv}{v-1} + \frac{1}{2} \int \frac{dv}{v+1} = -\int \frac{dx}{x}$$

$$-\ln|v| + \frac{1}{2} \ln|v-1| + \frac{1}{2} \ln|v+1| = -\ln|x| + \frac{\ln C}{2}.$$

$$-2\ln|v| + \ln|v-1| + \ln|v+1| = -2\ln|x| + \ln C.$$

$$\ln \frac{|v^2-1|}{v^2} = \ln \frac{C}{x^2} \Rightarrow \frac{|v^2-1|}{v^2} = \frac{C}{x^2}$$

$$\left| x^2 \left( 1 - \frac{1}{v^2} \right) \right| = C \Rightarrow x^2 \left( 1 - \frac{1}{v^2} \right) = D : C = \mp D$$

$$v = \frac{y}{x} \Rightarrow x^2 \cdot \left( 1 - \frac{x^2}{y^2} \right) = D \Rightarrow x^2 (y^2 - x^2) = y^2 D$$

$$\Rightarrow (x^2 - D) y^2 = x^4$$

$$\Rightarrow y^2 = \frac{x^4}{x^2 - D} \Rightarrow y = \mp \sqrt{\frac{x^4}{x^2 - D}} \Rightarrow y(x) = \mp \frac{x^2}{\sqrt{x^2 - D}}$$

Q2

$$2x^2y - x^3y' = y^3$$

$$y' - \frac{2}{x}y = -\frac{1}{x^3}y^3$$

Bernoulli Equation.

$$v = y^{1-n} = y^{-2} \quad \frac{dv}{dx} = -2 \cdot y^{-3} \cdot y'$$

$$\frac{dv}{dx} + \frac{4}{x}v = \frac{2}{x^3} \quad (\text{Linear Equation})$$

$$f(x) = \exp \left( \int \frac{4}{x} dx \right) = \exp(4 \ln x) = \exp(\ln x^4) = x^4$$

$$x^4 \frac{dv}{dx} + 4x^3v = 2x \quad , \quad \frac{d}{dx}(x^4 \cdot v) = 2x \Rightarrow x^4 \cdot v = x^2 + C$$

$$v(x) = \frac{1}{x^2} + \frac{C}{x^4}$$

$$\frac{1}{(y(x))^2} = \frac{1}{x^2} + \frac{C}{x^4} \Rightarrow (y(x))^{-2} = \frac{x^2 + C}{x^4} \Rightarrow y(x) = \pm \sqrt{\frac{x^4}{x^2 + C}}$$

$$\Rightarrow y(x) = \pm \frac{x^2}{\sqrt{x^2 + C}}$$

$$② e^y + y \cos x + (x e^y + \sin x) y' = 0$$

$$\underbrace{(e^y + y \cos x)}_M dx + \underbrace{(x e^y + \sin x)}_N dy = 0$$

$$M = e^y + y \cos x, \quad N = x e^y + \sin x \\ M_y = e^y + \cos x, \quad N_x = e^y + \cos x \Rightarrow M_y = N_x \\ \text{exact.}$$

Find  $F(x, y)$  such that  $F_x = M, F_y = N$ .

$$F_x = M = e^y + y \cos x \Rightarrow F(x, y) = \underbrace{x e^y + y \sin x}_{} + g(y)$$

$$F_y = x e^y + \sin x + g'(y) = N = \underbrace{x e^y + \sin x}_{} \Rightarrow g'(y) = 0 \\ g(y) = C_1$$

$$\Rightarrow x e^y + y \sin x = C. \quad (F(x, y) = C).$$

$$③ (x^2 - 1) y' + (x-1) y = 1$$

$$y' + \frac{1}{x+1} y = \frac{1}{x^2 - 1}, \quad x \neq \pm 1 \quad (\text{linear})$$

$p(x)$        $Q(x)$

$$p(x) = \frac{1}{x+1} \quad f(x) = \exp\left(\int p(x) dx\right) = \exp\left(\int \frac{1}{x+1} dx\right)$$

$$= e^{\ln(x+1)} = x+1$$

$$(x+1)y' + y = \frac{1}{x-1}$$

$$\frac{d}{dx}((x+1) \cdot y) = \frac{1}{x-1} \Rightarrow (x+1)y = \ln|x-1| + C$$

$$y(x) = \frac{\ln|x-1| + C}{x+1}$$

(4)  $y' = \sqrt{x+y}$

$$v = x+y \Rightarrow \frac{dv}{dx} = 1 + \frac{dy}{dx} = 1 + \sqrt{x+y} = 1 + \sqrt{v}$$

$$\frac{dv}{dx} = 1 + \sqrt{v} \Rightarrow \frac{dv}{1 + \sqrt{v}} = dx \quad (\text{separable})$$

$$\frac{\sqrt{v}}{1 + \sqrt{v}} \cdot \frac{dv}{\sqrt{v}} = dx \quad \sqrt{v} = t \Rightarrow \frac{dv}{2\sqrt{v}} = dt \Rightarrow \frac{dv}{\sqrt{v}} = 2dt$$

$$\frac{t}{1+t} 2dt = dx \quad \Rightarrow 2 \left(1 - \frac{1}{1+t}\right) dt = dx$$

$$\Rightarrow 2(t - \ln|1+t|) = x + C.$$

$$\Rightarrow 2(\sqrt{v} - \ln|1+\sqrt{v}|) = x + C \Rightarrow 2(\sqrt{x+y} + \ln|1+\sqrt{x+y}|) = x + C.$$

(5)

$$\frac{dy}{dx} = \frac{2xy + 2x}{x^2 + 1}$$

$$\frac{dy}{dx} - \frac{2x}{x^2+1}y = \frac{2x}{(x^2+1)^2} \quad \text{linear}$$

$$y(x) = \exp\left(-\int \frac{2x}{x^2+1} dx\right) = \exp\left(-\ln(x^2+1)\right) = \frac{1}{x^2+1}$$

$$\frac{1}{x^2+1} \frac{dy}{dx} - \frac{2x}{(x^2+1)^2}y = \frac{2x}{(x^2+1)^2} \Rightarrow \frac{d}{dx}\left(\frac{1}{x^2+1}y\right) = \frac{2x}{(x^2+1)^2}$$

$$\Rightarrow \frac{y}{x^2+1} = -\frac{1}{x^2+1} + C \Rightarrow y(x) = -1 + C(x^2+1).$$

or  $\frac{dy}{dx} = \frac{2x}{x^2+1} (1+y) \Rightarrow \frac{dy}{y+1} = \frac{2x}{x^2+1} dx$  separable

$$\Rightarrow \ln|y+1| = \ln|x^2+1| + \ln C.$$

$$|y+1| = C \cdot |x^2+1|$$

$$\Rightarrow y+1 = D \cdot (x^2+1), \text{ where } D \neq \mp C.$$

$$y(x) = -1 + D(x^2+1).$$

$$⑥ \frac{dy}{dx} = \frac{x+3y}{y-3x}$$

$$\frac{dy}{dx} = \frac{1+3(y/x)}{(y/x)-3} \quad \text{homogeneous.}$$

$$y = vx \Rightarrow \frac{dy}{dx} = v + x \cdot \frac{dv}{dx} = \frac{1+3v}{v-3} \Rightarrow x \frac{dv}{dx} = \frac{1+6v-v^2}{v-3}$$

$$\Rightarrow \frac{v-3}{v^2+6v-v^2} dv = -\frac{dx}{x} \quad \Rightarrow \frac{1}{2} \cdot \frac{2v-6}{v^2-6v-1} dv = -\frac{dx}{x}$$

$$\Rightarrow \frac{1}{2} \ln |v^2-6v-1| = -\ln|x| + \frac{\ln C}{2}$$

$$\Rightarrow \ln |x^2(v^2-6v-1)| = \ln C$$

$$\Rightarrow |x^2(v^2-6v-1)| = C$$

$$\Rightarrow x^2(v^2-6v-1) = D, D = \pm C$$

$$\Rightarrow x^2 \left( \left(\frac{y}{x}\right)^2 - 6\left(\frac{y}{x}\right) - 1 \right) = D \quad \Rightarrow y^2 - 6xy - x^2 = D.$$

OR

$$\frac{dy}{dx} = \frac{x+3y}{y-3x}$$

$$\Rightarrow (y-3x)dy - (x+3y)dx = 0$$

$$\Rightarrow \underbrace{(x+3y)}_M dx + \underbrace{(3x-y)}_N dy = 0$$

$$M = x+3y \quad N = 3x-y$$

$$My = 3 = N = 3 \quad \text{Exact}$$

$$F_x = M = x+3y \Rightarrow F(x,y) = \frac{x^2}{2} + 3xy + g(y)$$

$$F_y(x,y) = 3x + g'(y) = N = 3x-y$$

$$\Rightarrow g'(y) = -y \Rightarrow g(y) = -\frac{y^2}{2} + C_1$$

$$F(x,y) = \frac{x^2}{2} + 3xy - \frac{y^2}{2} + C_1 \Rightarrow x^2 + 6xy - y^2 = C. \quad (F(x,y) = C)$$

# Higher-Order Linear Differential Equations

## General Solutions of Linear Equations

Consider the general  $n$ th-order linear differential equation of the form

$$P_0(x)y^{(n)} + P_1(x)y^{(n-1)} + \cdots + P_{n-1}(x)y' + P_n(x)y = F(x). \quad (1)$$

Unless otherwise noted, we will always assume that the coefficient functions  $P_i(x)$  and  $F(x)$  are continuous on some open interval  $I$  (perhaps unbounded), where we wish to solve the equation. Under the additional assumption that  $P_0(x) \neq 0$  at each point of  $I$ , we can divide each term in Eq. (1) by  $P_0(x)$  to obtain an equation with leading coefficient 1, of the form

$$y^{(n)} + p_1(x)y^{(n-1)} + \cdots + p_{n-1}(x)y' + p_n(x)y = f(x). \quad (2)$$

The **homogeneous** linear equation **associated with** Eq. (2) is

$$y^{(n)} + p_1(x)y^{(n-1)} + \cdots + p_{n-1}(x)y' + p_n(x)y = 0. \quad (3)$$

## THEOREM 1 Existence and Uniqueness for Linear Equations

Suppose that the functions  $p_1, p_2, \dots, p_n$ , and  $f$  are continuous on the open interval  $I$  containing the point  $a$ . Then, given  $n$  numbers  $b_0, b_1, \dots, b_{n-1}$ , the  $n$ th-order linear equation [Eq. (2)]

$$y^{(n)} + p_1(x)y^{(n-1)} + \cdots + p_{n-1}(x)y' + p_n(x)y = f(x)$$

has a unique (that is, one and only one) solution on the entire interval  $I$  that satisfies the  $n$  initial conditions

$$y(a) = b_0, \quad y'(a) = b_1, \quad \dots, \quad y^{(n-1)}(a) = b_{n-1}. \quad (5)$$

Note that Theorem<sup>1</sup> implies that the trivial solution  $y(x) = 0$  is the only solution of the homogeneous equation

$$y^{(n)} + p_1(x)y^{(n-1)} + \cdots + p_{n-1}(x)y' + p_n(x)y = 0.$$

that satisfies the trivial initial conditions

$$y(a) = y'(a) = \cdots = y^{(n-1)}(a) = 0.$$

**Example:**  $x^2y'' - 4xy' + 6y = 0$        $y(0) = y'(0) = 0$

$$y'' - \frac{4}{x}y' + \frac{6}{x^2}y = 0$$

$p(x) = -\frac{4}{x}$ ,  $q(x) = \frac{6}{x^2}$  are not continuous on an open interval containing the point  $x=0$ .  
On the other hand,  $y_1(x) = x^2$  and  $y_2(x) = x^3$  are two different solutions. This is not contradict the uniqueness part of Theorem 1.

## **THEOREM 2** Principle of Superposition for Homogeneous Equations

Let  $y_1, y_2, \dots, y_n$  be  $n$  solutions of the homogeneous linear equation in (3) on the interval  $I$ . If  $c_1, c_2, \dots, c_n$  are constants, then the linear combination

$$y = c_1 y_1 + c_2 y_2 + \cdots + c_n y_n \quad (4)$$

is also a solution of Eq. (3) on  $I$ .

proof in case  $n=2$ : Let  $y_1$  and  $y_2$  be solutions of the equation

$$y'' + p(x)y' + q(x)y = 0$$

and  $y = c_1 y_1 + c_2 y_2$

$$\Rightarrow y' = c_1 y_1' + c_2 y_2' , \quad y'' = c_1 y_1'' + c_2 y_2''$$

$$\begin{aligned}
 y'' + p(x)y' + q(x)y &= (c_1 y_1'' + c_2 y_2'') + p(x)(c_1 y_1' + c_2 y_2') \\
 &\quad + q(x)(c_1 y_1 + c_2 y_2) \\
 &= c_1 \underbrace{(y_1'' + p(x)y_1' + q(x)y_1)}_{=0} \\
 &\quad + c_2 \underbrace{(y_2'' + p(x)y_2' + q(x)y_2)}_{=0}
 \end{aligned}$$

because  $y_1$  and  $y_2$  are solutions

$$\Rightarrow y'' + p(x)y' + q(x)y = 0$$

$\Rightarrow y$  is also a solution.

**Remark:** The set  $S$  of all solutions of the homogeneous linear equation is a subspace of the vector space of all functions on the real line  $\mathbb{R}$ . Therefore  $S$  is called the solution space of the differential equation.

**Example:** Verify that three functions

$$y_1(x) = e^{-3x}, \quad y_2(x) = \cos^2 x \quad \text{and} \quad y_3(x) = \sin^2 x$$

are solutions of the homogeneous third-order equation

$$y^{(3)} + 3y'' + 4y' + 12y = 0$$

on the entire real line.

$$y_1(x) = e^{-3x}, \quad y_1'(x) = -3 \cdot e^{-3x}, \quad y_1''(x) = 9e^{-3x}, \quad y_1'''(x) = -27e^{-3x}$$

$$y_1''' + 3y_1'' + 4y_1' + 12y_1 = -27e^{-3x} + 3 \cdot 9 \cdot 3^{-3x} + 4 \cdot (-3) \cdot e^{-3x} + 12 \cdot e^{-3x} = 0$$

Similarly, it is possible to show that

$$y_2''' + 3y_2'' + 4y_2' + 12y_2 = 0 \quad \text{and} \quad y_3''' + 3y_3'' + 4y_3' + 12y_3 = 0$$

Remark: 1)  $y(x) = -3y_1(x) + 3y_2(x) - 2y_3(x)$   
 $= 3e^{-3x} + 3\cos 2x - 2\sin 2x$

is also a solution on the entire real line by Principle  
of superposition. Thus a general solution is given by

$$y(x) = c_1 e^{-3x} + c_2 \cos 2x + c_3 \sin 2x.$$

2) Because its general solution involves the three arbitrary constants  $c_1, c_2$  and  $c_3$ , the third-order equation has a "three fold infinity" of solutions.

$$y(x) = c_1 e^{-3x}, \quad y(x) = c_2 \cos 2x, \quad y(x) = c_3 \sin 2x.$$

3) The particular solution  $y(x) = -3e^{-3x} + 3\cos 2x - 2\sin 2x$   
has initial values  $y(0) = 0, y'(0) = 9e^{-3x} - 4\cos 2x - 6\sin 2x \Big|_{x=0} = 5$ . Thus the solution  
 $y''(0) = -27e^{-3x} + 8\cos 2x - 12\sin 2x \Big|_{x=0} = -39$ . Thus the solution  
of I.V.P.  $y''' + 3y'' + 4y' + 12y = 0$   $y(0) = 0, y'(0) = 5, y''(0) = -39$   
is  $y(x) = -3e^{-3x} + 3\cos 2x - 2\sin 2x$ .

## Linear Independent Solutions :

### DEFINITION Linear Dependence of Functions

The  $n$  functions  $f_1, f_2, \dots, f_n$  are said to be **linearly dependent** on the interval  $I$  provided that there exist constants  $c_1, c_2, \dots, c_n$  not all zero such that

$$c_1 f_1 + c_2 f_2 + \cdots + c_n f_n = 0 \quad (7)$$

on  $I$ ; that is,

$$c_1 f_1(x) + c_2 f_2(x) + \cdots + c_n f_n(x) = 0$$

for all  $x$  in  $I$ .

They are linearly independent on  $I$  provided that  
the identity

$$c_1 f_1 + c_2 f_2 + \cdots + c_n f_n = 0$$

holds on  $I$  only in the trivial case

$$c_1 = c_2 = \cdots = c_n = 0.$$

**Example:** The functions

$$f_1(x) = \sin 2x \quad f_2(x) = \sin x \cos x \quad \text{and} \quad f_3(x) = e^x$$

are linearly dependent on the real line because.

$$(1) \cdot f_1 + (-2) f_2 + (0) f_3 = 0 \quad (\sin 2x = 2 \sin x \cos x)$$

**Example:** Show that the functions  $y_1(x) = e^{-3x}$

$y_2(x) = \cos 2x$  and  $y_3(x) = \sin 2x$  are linearly independent.

$$c_1 y_1 + c_2 y_2 + c_3 y_3 = 0$$

$$c_1 e^{-3x} + c_2 \cos 2x + c_3 \sin 2x = 0 \quad \text{for all } x \in \mathbb{R}.$$

$$-3c_1 e^{-3x} - 2c_2 \sin 2x + 2c_3 \cos 2x = 0$$

$$9c_1 e^{-3x} - 4c_2 \cos 2x - 4c_3 \sin 2x = 0.$$

$$\begin{vmatrix} -3x \\ e \\ -3e^{-3x} \\ g e^{-3x} \end{vmatrix} \begin{vmatrix} \cos 2x & \sin 2x \\ -2\sin 2x & 2\cos 2x \\ -4\cos 2x & -4\sin 2x \end{vmatrix}$$

$$= e^{-3x} \cdot \begin{vmatrix} \cos 2x & \sin 2x \\ -2\sin 2x & 2\cos 2x \\ -4\cos 2x & -4\sin 2x \end{vmatrix} - (-3)e^{-3x} \cdot \begin{vmatrix} \cos 2x & \sin 2x \\ -4\cos 2x & -4\sin 2x \end{vmatrix}$$

$$+ g \cdot e^{-3x} \cdot \begin{vmatrix} \cos 2x & \sin 2x \\ -2\sin 2x & 2\cos 2x \end{vmatrix} = 8e^{-3x} + 0 + 18e^{-3x} \\ = 26e^{-3x} \neq 0$$

Because  $W \neq 0$  everywhere,  $c_1 = c_2 = c_3 = 0$ .

$y_1, y_2, y_3$  are linearly independent.

### Theorem<sup>3</sup>: Wronskians of Solutions

Suppose that  $y_1, y_2, \dots, y_n$  are  $n$  solutions of the homogeneous  $n$ th-order linear equation

$$y^{(n)} + P_1(x)y^{(n-1)} + \dots + P_{n-1}(x)y' + P_n(x)y = 0$$

on an open interval  $I$  where each  $P_j$  is continuous.

Let

$$W = W(y_1, y_2, \dots, y_n) = \begin{vmatrix} y_1 & y_2 & \dots & y_n \\ y'_1 & y'_2 & \dots & y'_n \\ \vdots & & & \\ y_1^{(n-1)} & y_2^{(n-1)} & \dots & y_n^{(n-1)} \end{vmatrix}$$

(Wronskian of  $n$  functions  $y_1, y_2, \dots, y_n$ )

If  $y_1, y_2, \dots, y_n$  are linearly dependent, then  $W=0$  on  $I$ .

- a) If  $y_1, y_2, \dots, y_n$  are linearly independent, then  $W \neq 0$  at each point of  $I$ .
- b) If  $y_1, y_2, \dots, y_n$  are linearly independent, then  $W \neq 0$  at each point of  $I$ .

Remark: To show that the functions  $f_1, f_2, \dots, f_n$  are linearly independent on the interval  $I$ , it suffices to show that their wronskian is nonzero at just one point of  $I$ .

$$\text{proof: } c_1 y_1 + c_2 y_2 + \dots + c_n y_n = 0$$

$$c_1 y'_1 + c_2 y'_2 + \dots + c_n y'_n = 0$$

:

$$c_1 y_1^{(n-1)} + c_2 y_2^{(n-1)} + \dots + c_n y_n^{(n-1)} = 0$$

- (a) A homogeneous  $n \times n$  linear system of equations has a nontrivial solution if and only if  $|W| = 0$ .
- (b) Assume that  $W(a) = 0$  at some point of  $I$ . Show that this implies the solutions  $y_1, y_2, \dots, y_n$  are linearly dependent  
 $\Rightarrow c_1, c_2, \dots, c_n$  are not all zero.

Define  $y(x) = c_1 y_1(x) + c_2 y_2(x) + \dots + c_n y_n(x)$  (particular solution)

$$\Rightarrow y(a) = y'(a) = \dots = y^{(n-1)}(a) = 0 \text{ on I}$$

$$\Rightarrow y(x) = 0.$$

**Example:** Show that the three solutions

$$y_1(x) = x, \quad y_2(x) = x \ln x, \quad y_3(x) = x^2$$

of the third-order equation

$$x^3 y''' - x^2 y'' + 2xy' - 2y = 0$$

are linearly independent on the open interval  $x > 0$ . Then find a particular solution that satisfies the initial conditions

$$y(1) = 3, \quad y'(1) = 2, \quad y''(1) = 1.$$

$$W = \begin{vmatrix} x & x \ln x & x^2 \\ 1 & \ln x + x \cdot \frac{1}{x} & 2x \\ 0 & \frac{1}{x} & 2 \end{vmatrix} = \begin{vmatrix} x & x \ln x & x^2 \\ 1 & \ln x + 1 & 2x \\ 0 & \frac{1}{x} & 2 \end{vmatrix}$$

$$\begin{aligned} &= x \cdot \begin{vmatrix} \ln x + 1 & 2x \\ \frac{1}{x} & 2 \end{vmatrix} - 1 \cdot \begin{vmatrix} x \ln x & x^2 \\ \frac{1}{x} & 2 \end{vmatrix} = x \cdot (2\ln x + 2 - 2 \cdot \frac{1}{x}) \\ &\quad - 1 \cdot (2x \ln x - \frac{1}{x} \cdot x^2) \\ &= 2x \ln x - 2x \ln x + x = x^2 \neq 0 \end{aligned}$$

Thus  $y_1, y_2$  and  $y_3$  are linearly independent on the interval  $x > 0$ .

$$y(x) = c_1 x + c_2 x \ln x + c_3 x^2 \quad \begin{matrix} y(1) = 3 \\ \Rightarrow c_1 + c_3 = 3 \end{matrix}$$

$$y'(x) = c_1 + c_2(1 + \ln x) + 2c_3 x \quad \begin{matrix} y'(1) = 2 \\ \Rightarrow c_1 + c_2 + 2c_3 = 2 \end{matrix}$$

$$y''(1) = 1$$

$$y''(x) = \frac{c_2}{x} + 2c_3 \quad \Rightarrow \quad c_2 + 2c_3 = 1$$

$$c_1 + 1 = 2 \Rightarrow c_1 = 1$$

$$c_1 + c_3 = 3 \Rightarrow c_3 = 2$$

$$c_2 + 2c_3 = 1 \Rightarrow c_2 = -3$$

$$y(x) = x - 2x \ln x + 2x^2.$$

## THEOREM 4 General Solutions of Homogeneous Equations

Let  $y_1, y_2, \dots, y_n$  be  $n$  linearly independent solutions of the homogeneous equation

$$y^{(n)} + p_1(x)y^{(n-1)} + \cdots + p_{n-1}(x)y' + p_n(x)y = 0 \quad (3)$$

on an open interval  $I$ , where the  $p_i$  are continuous. If  $Y$  is any solution whatsoever of Eq. (3), then there exist numbers  $c_1, c_2, \dots, c_n$  such that

$$Y(x) = c_1y_1(x) + c_2y_2(x) + \cdots + c_ny_n(x)$$

for all  $x$  in  $I$ .