

First-Order Differential Equations

Differential Equations and Mathematical Models

An equation relating an unknown function and one or more of its derivatives is called a differential equation.

The differential equation

$$\frac{dx}{dt} = x^2 + t^2$$

involves both the unknown function $x(t)$ and its first derivative $x'(t) = dx/dt$. The differential equation

$$\frac{d^2y}{dx^2} + 3\frac{dy}{dx} + 7y = 0$$

involves the unknown function y of the independent variable x and the first two derivatives y' and y'' of y . ■

The study of differential equations has three principal goals:

1. To discover the differential equation that describes a specified physical situation.
2. To find—either exactly or approximately—the appropriate solution of that equation.
3. To interpret the solution that is found.

If C is a constant and

$$\underline{y(x) = Ce^{x^2}}, \quad (1)$$

then

$$\frac{dy}{dx} = C(2xe^{x^2}) = (2x)(Ce^{x^2}) = 2xy.$$

Thus every function $y(x)$ of the form in Eq. (1) *satisfies*—and thus is a solution of—the differential equation

$$\underline{\frac{dy}{dx} = 2xy} \quad (2)$$

for all x . In particular, Eq. (1) defines an *infinite* family of different solutions of this differential equation, one for each choice of the arbitrary constant C .

This is typical of differential equations. It is also fortunate, because it may allow us to use additional information to select from among all these solutions a particular one that fits the solution under study.

Terminology and Classification

i) Ordinary and partial differential equations:

An ordinary differential equation (ODE) means that the unknown function (dependent variable) depends on only a single independent variables. If the dependent variable is a function of two or more independent variables, then partial derivatives are likely to be involved; if they are, the equation is called a partial differential equation (PDE)

$$\frac{dx}{dt} = x^2 + t^2 \quad (\text{ODE})$$

$$\frac{\partial y}{\partial t} = k \cdot \frac{\partial^2 y}{\partial x^2} \quad (\text{PDE})$$

2) System of differential equations:

If there are two or more unknown functions then a system of equations is required

$$\frac{dx}{dt} = x(\alpha - \beta y)$$

$$\frac{dy}{dt} = -y(\gamma - \delta x).$$

3) Order: The order of a differential equation is the order of the highest derivative that appears in it.

$$\frac{du}{dt} + u = t^2 \quad \text{1st order ODE}$$

$$y^{(4)} + x^2 y^{(3)} + x^2 y = \sin x \quad \text{4th order ODE}$$

$F(x, y, y', y'', \dots, y^{(n)}) = 0$ (*) is the most general form of an n -th order differential equation with independent variable x and unknown function $y = y(x)$.

4) **solution:** We say that the continuous function $u=u(x)$ is a solution of the differential equation (*) on the interval I provided that the derivatives $u', u'', \dots, u^{(n)}$ exist on I and

$$F(x, u, u', u'', \dots, u^{(n)}) = 0 \quad \text{for all } x \text{ in } I.$$

Example: $y(x) = 2x^{\frac{1}{2}} - x^{\frac{1}{2}} \ln x$ is a solution of the equation $4x^2 y'' + y = 0$ for all $x > 0$.

• $y(x) = A\cos 3x + B\sin 3x$ is a two-parameter family of the solutions of the equation $y'' + gy = 0$.

5) Initial value problem (IVP):

IVP consists of a differential equation

$$y^{(n)} = f(x, y, y', \dots, y^{(n-1)})$$

together with an initial conditions $y(x_0) = y_0, y'(x_0) = y'_0, y^{(n-1)}(x_0) = y^{(n-1)}_0, \dots, y^{(n-2)}(x_0) = y^{(n-2)}_0$.

6) Linear and Nonlinear Equations:

The general form of an n -th order linear differential equation is

$$a_0(t) y^{(n)} + a_1(t) y^{(n-1)} + a_2(t) y^{(n-2)} + \dots + a_n(t) y = g(t).$$

otherwise, it is said to be nonlinear ODE.

$$\frac{dy}{dt} + ty = 0 \quad \text{linear}$$

$$\frac{d^3y}{dt^3} + t \cdot \frac{dy}{dt} + (\cos^2 t) \cdot y = t^3 \quad \text{linear}$$

$$\underline{y \cdot y'} + (\cos t)y = \sin t \quad \text{nonlinear}$$

$$\underline{y'' + \sin(x+y)} = \sin t \quad \text{nonlinear}$$

In this chapter, we concentrate on first-order differential equations of the form $\frac{dy}{dx} = f(x, y)$.

Integrals as General and Particular Solutions

The first-order equation $dy/dx = f(x, y)$ takes an especially simple form if the right-hand-side function f does not actually involve the dependent variable y , so

$$\frac{dy}{dx} = f(x). \quad (1)$$

In this special case we need only integrate both sides of Eq. (1) to obtain

$$y(x) = \int f(x) dx + C. \quad (2)$$

This is a **general solution** of Eq. (1), meaning that it involves an arbitrary constant C , and for every choice of C it is a solution of the differential equation in (1). If $G(x)$ is a particular antiderivative of f —that is, if $G'(x) \equiv f(x)$ —then

$$y(x) = G(x) + C. \quad (3)$$

To satisfy an initial condition $y(x_0) = y_0$, we need only substitute $x = x_0$ and $y = y_0$ into Eq. (3) to obtain $y_0 = G(x_0) + C$, so that $C = y_0 - G(x_0)$. With this choice of C , we obtain the **particular solution** of Eq. (1) satisfying the initial value problem

$$\frac{dy}{dx} = f(x), \quad y(x_0) = y_0.$$

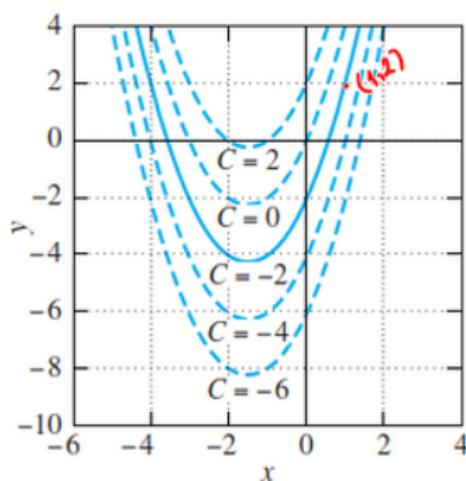
Example: Solve the initial value problem

$$\frac{dy}{dx} = 2x + 3, \quad y(1) = 2.$$

$$\frac{dy}{dx} = 2x + 3 \Rightarrow y(x) = \int (2x+3) dx = x^2 + 3x + C$$

$$y(1) = 1 + 3 \cdot 1 + C = 2 \Rightarrow C = -2$$

$y(x) = x^2 + 3x - 2$. is the solution
of IVP.



Existence and Uniqueness of Solutions

Example: (Failure of existence) The initial value problem

$$y' = \frac{1}{x}, \quad y(0) = 0$$

has no solution, because no solution $y(x) = \int \frac{1}{x} dx = \ln|x| + C$ of the differential equation is defined at $x=0$.

Example: (Failure of uniqueness) Verify that the initial value problem $y' = 2\sqrt{y}, \quad x > 0, \quad y(0) = 0$.

has two different solutions $y_1(x) = x^2$ and $y_2(x) = 0$.

$$y_1(x) = x^2 \quad y'_1 = 2x = 2\sqrt{x^2} = 2\sqrt{y}, \quad y_1(0) = 0.$$
$$y_2(x) = 0, \quad y'_2 = 0 = 2\sqrt{y_2}, \quad y_2(0) = 0.$$

THEOREM 1 Existence and Uniqueness of Solutions

Suppose that both the function $f(x, y)$ and its partial derivative $D_y f(x, y)$ are continuous on some rectangle R in the xy -plane that contains the point (a, b) in its interior. Then, for some open interval I containing the point a , the initial value problem

$$\frac{dy}{dx} = f(x, y), \quad y(a) = b$$

has one and only one solution that is defined on the interval I .

Example:

$$\frac{dy}{dx} = -y$$

$$\frac{dy}{dx} = f(x,y)$$

$f(x,y) = -y$ are $\frac{\partial f}{\partial y} = -1$ continuous everywhere,

so Theorem implies the existence of a unique solution for any initial data (a,b) .

Example:

$$\frac{dy}{dx} = 2\sqrt{y}$$

$f(x,y) = 2\sqrt{y}$ is continuous wherever $y \geq 0$, but the partial derivative $\frac{\partial f}{\partial y} = \frac{1}{\sqrt{y}}$ is discontinuous when $y=0$, and hence at the point $(0,0)$. This is why it is possible for there to exist two different solutions $y_1(x) = x^2$ and $y_2(x) = 0$, each of which satisfies the initial condition $y(0) = 0$.

Example: $\frac{dy}{dx} = y^2$, $y(0) = 1$.

$f(x,y) = y^2$ $\frac{\partial f}{\partial y} = 2y \Rightarrow$ Both of them are continuous
everywhere in the xy -plane. Theorem guarantees a
unique solution of IVP. Indeed, this is the solution
 $y(x) = \frac{1}{1-x}$. But $y(x) = \frac{1}{1-x}$ is discontinuous at
 $x=1$, so our unique continuous solution does not
exist $-2 < x < 2$. Thus the solution interval I of theorem
may not be as wide as the rectangle R where f
and $\frac{\partial f}{\partial y}$ are continuous.

Example: Consider the differential equation

$$x \frac{dy}{dx} = 2y$$

a) Apply the theorem of existence and uniqueness :

$$\frac{dy}{dx} = \frac{2y}{x}, \quad f(x,y) = \frac{2y}{x}, \quad \frac{\partial f}{\partial y} = \frac{2}{x}.$$

f and $\frac{\partial f}{\partial y}$ are continuous in the xy -plane where $x \neq 0$.
So, there is a unique solution near any point in
the xy -plane where $x \neq 0$.

b) Verify that $y = cx^2$ is a solution of the
differential equation given in (a).

$$y(x) = cx^2 \quad \frac{dy}{dx} = 2cx = 2c \frac{x^2}{x} = \frac{2y}{x}.$$

c) For what values of a and b does the IVP

$$x \frac{dy}{dx} = 2y, \quad y(a) = b$$

i) a unique solution ($a \neq 0$)

ii) no solution ($a=0$ and $b \neq 0$)

iii) infinitely many solutions ($a=0$ and $b=0$)

$$y(x) = cx^2 \quad y(a) = b \Rightarrow y(a) = ca^2 = b$$

$$x=a, y=b$$



$$c = \frac{b}{a^2}$$

$$b = ca^2 \Rightarrow c = \frac{b}{a^2}$$

$$y(x) = \frac{b}{a^2}x^2$$

For all c , $y(x) = cx^2$ is a solution of the IVP.
Thus, it has infinitely many solutions when $a=b=0$.

Separable Equations and Applications

The first-order differential equation

$$\frac{dy}{dx} = H(x, y) \quad (1)$$

is called **separable** provided that $H(x, y)$ can be written as the product of a function of x and a function of y :

$$\frac{dy}{dx} = g(x) \cdot h(y) = \frac{g(x)}{f(y)}, \text{ where } h(y) = \frac{1}{f(y)}$$

$$\int f(y) dy = \int g(x) dx$$

$$\Rightarrow F(y) = G(x) + C, \text{ where } F'(y) = f(y) \text{ and} \\ G'(x) = g(x).$$

Example:

Solve the initial value problem

$$\frac{dy}{dx} = -6xy, \quad y(0) = 7.$$

$$\frac{dy}{dx} = -6xy \Rightarrow \int \frac{dy}{y} = -6 \int x dx$$

$$\ln|y| = -3x^2 + C.$$

$$|y| = e^{-3x^2+C} = e^{-3x^2} \cdot e^C = e^{-3x^2} \cdot C$$

$$\Rightarrow y = \pm C \cdot e^{-3x^2}$$

$$\Rightarrow y = A \cdot e^{-3x^2}, \text{ where } A = \pm C.$$

$$y(0) = 7 \Rightarrow y(0) = A = 7 \Rightarrow A = 7$$

$$y(x) = 7 \cdot e^{-3x^2}.$$

! A solution of a differential equation that contains an "arbitrary constant" (like the constant C) is commonly called a general solution of the differential equation; any particular choice of a specific value for C yields a single particular solution of the equation.

It is common for a nonlinear first-order differential equation to have both a general solution involving an arbitrary constant C and one or several particular solutions that cannot be obtained by selecting a value of C . These exceptional solutions are cannot be obtained by selecting a value for C . These exceptional solutions are frequently called singular solutions.

Example: Find all solutions of the differential equation

$$\frac{dy}{dx} = 6x(y-1)^{\frac{2}{3}}$$

$$\int \frac{1}{3(y-1)^{\frac{2}{3}}} dy = \int 2x dx$$
$$(y-1)^{\frac{1}{3}} = x^2$$

$\Rightarrow (y-1)^{\frac{1}{3}} = x^2 + C$ is a general solution, but
 $y(x) = 1$ is also a solution. No value of C gives
the singular solution $y(x) = 1$. Hence the solution of
the given differential equation with the initial
condition $y(1) = 1$ is not unique and the function

$f(x,y) = 6x(y-1)^{\frac{2}{3}}$ is not differentiable.

Example: Solve IVP

$$\frac{dy}{dx} = \frac{4-2x}{3y^2-5}, \quad y(1) = 3.$$

$$\int (3y^2 - 5) dy = \int (4-2x) dx$$

$$\Rightarrow y^3 - 5y = 4x - x^2 + C$$

$$y(1) = 3 \Rightarrow 3^3 - 5 \cdot 3 = 4 \cdot 1 - 1^2 + C \Rightarrow C = 9$$

$$y^3 - 5y = 4x - x^2 + 9$$

This equation is not readily solved for y as an explicit function of x .

The equation $K(x, y) = 0$ is commonly called an **implicit solution** of a differential equation if it is satisfied (on some interval) by some solution $y = y(x)$ of the differential equation. But note that a particular solution $y = y(x)$ of $K(x, y) = 0$ may or may not satisfy a given initial condition. For example, differentiation of $x^2 + y^2 = 4$ yields

$$x + y \frac{dy}{dx} = 0,$$

so $x^2 + y^2 = 4$ is an implicit solution of the differential equation $x + yy' = 0$. But only the first of the two explicit solutions

$$\underbrace{y(x) = +\sqrt{4 - x^2}} \quad \text{and} \quad \underbrace{y(x) = -\sqrt{4 - x^2}}$$

satisfies the initial condition $\underbrace{y(0) = 2}$

$$\begin{aligned} x^2 + y^2 &= 4 \\ 2x + 2y \frac{dy}{dx} &= 0 \\ \frac{dy}{dx} &= -\frac{x}{y} \end{aligned}$$

$$\begin{aligned} x^2 + y^2 &= 4 \\ y^2 &= 4 - x^2 \\ |y| &= \sqrt{4 - x^2} \\ y &= \pm \sqrt{4 - x^2} \end{aligned}$$

Remark 1: You should not assume that every possible algebraic solution $y = y(x)$ of an implicit solution satisfies the same differential equation. For instance, if we multiply the implicit solution $x^2 + y^2 - 4 = 0$ by the factor $(y - 2x)$, then we get the new implicit solution

$$(y - 2x)(\underbrace{x^2 + y^2 - 4}_0) = 0$$

that yields (or “contains”) not only the previously noted explicit solutions $y = +\sqrt{4 - x^2}$ and $y = -\sqrt{4 - x^2}$ of the differential equation $\underline{x + yy' = 0}$, but also the additional function $y = 2x$ that does *not* satisfy this differential equation.

$$(y - 2x)(x^2 + y^2 - 4) = 0$$

$$(y^2 - 2y) \cdot (x^2 + y^2 - 4) + (y - 2x) \cdot (2x + 2y \cdot y') = 0$$

$$(x^2 + y^2 - 4 + 2y \cdot (y - 2x)) \cdot y' - 2(x^2 + y^2 - 4) + 2x(y - 2x) = 0$$

$$y' = \frac{2(3x^2 + y^2 - xy - 4)}{x^2 + 3y^2 - 4xy - 4}$$

$$\cancel{x + y \cdot y'} = \frac{\cancel{x^3 + 3xy^2 - 4x^2y - 4x} + 6x^2y + 2y^3 - 2xy^2 - 8y}{\cancel{x^2 + 3y^2 - 4xy - 4}} \neq 0.$$

Remark 2: Similarly, solutions of a given differential equation can be either gained or lost when it is multiplied or divided by an algebraic factor. For instance, consider the differential equation

$$(y - 2x)y \frac{dy}{dx} = -x(y - 2x) \quad (9)$$

having the obvious solution $y = 2x$. But if we divide both sides by the common factor $(y - 2x)$, then we get the previously discussed differential equation

$$y \frac{dy}{dx} = -x, \quad \text{or} \quad x + y \frac{dy}{dx} = 0, \quad (10)$$

of which $y = 2x$ is *not* a solution. Thus we “lose” the solution $y = 2x$ of Eq. (9) upon its division by the factor $(y - 2x)$; alternatively, we “gain” this new solution when we multiply Eq. (10) by $(y - 2x)$.

Linear First-Order Equations

To solve the equation

$$\frac{dy}{dx} = 2xy \quad (y > 0),$$

we multiply both sides by the factor $1/y$ to get

$$\frac{1}{y} \cdot \frac{dy}{dx} = 2x; \quad \text{that is, } D_x(\ln y) = D_x(x^2).$$

$$\Rightarrow \ln y = x^2 + C.$$

For this reason, the function $f(x) = \frac{1}{y}$ is called an integrating factor for the original equation.

Definition: An integrating factor for a differential equation is a function $f(x,y)$ such that the multiplication of each side of the differential equation by $f(x,y)$ yields an equation which each side is recognizable as derivative.

There is a standard technique for solving the linear first-order equation.

$$\frac{dy}{dx} + P(x)y = Q(x)$$

on an interval on which the coefficient functions $P(x)$ and $Q(x)$ are continuous.

$$e^{\int P(x)dx} \cdot \frac{dy}{dx} + P(x) \cdot e^{\int P(x)dx} \cdot y = Q(x) \cdot e^{\int P(x)dx}$$

$$D_x \left[y(x) \cdot e^{\int P(x)dx} \right] = Q(x) e^{\int P(x)dx}$$

because

$$D_x \left(\int P(x) dx \right) = P(x)$$

$$y(x) \cdot e^{\int P(x)dx} = \int Q(x) \cdot e^{\int P(x)dx} dx + C$$

$$y(x) = e^{-\int P(x)dx} \left[\int (Q(x) e^{\int P(x)dx}) dx + C \right].$$

Thus $Q(x) = e^{\int P(x)dx}$ is an integrating factor for the linear first-order differential equation.

Remark: You need not supply explicitly a constant of integration when you found $g(x)$

Let $\int p(x) dx = R(x) + K$

$$g(x) = e^{\int p(x) dx} = e^{R(x) + K} = e^K \cdot e^{R(x)}$$

e^K does not affect materially the result of multiplying both sides of the differential eqn. by $f(x)$, so we take $K=0$.

METHOD: SOLUTION OF FIRST-ORDER EQUATIONS

1. Begin by calculating the integrating factor $\rho(x) = e^{\int P(x) dx}$.
2. Then multiply both sides of the differential equation by $\rho(x)$.
3. Next, recognize the left-hand side of the resulting equation as the derivative of a product:

$$D_x [\rho(x)y(x)] = \rho(x)Q(x).$$

4. Finally, integrate this equation,

$$\rho(x)y(x) = \int \rho(x)Q(x) dx + C,$$

then solve for y to obtain the general solution of the original differential equation.

Example: Solve the initial value problem

$$\frac{dy}{dx} - y = \frac{11}{8} e^{-x/3}, \quad y(0) = -1.$$

1. Begin by calculating the integrating factor $\rho(x) = e^{\int P(x) dx}$.

$$\rho(x) = e^{\int P(x) dx} = e^{\int (-1) dx} = e^{-x}$$

2. Then multiply both sides of the differential equation by $\rho(x)$.

$$e^{-x} \cdot \frac{dy}{dx} - e^{-x} y = \frac{11}{8} \cdot e^{-4x/3}$$

3. Next, recognize the left-hand side of the resulting equation as the derivative of a product:

$$D_x [\rho(x)y(x)] = \rho(x)Q(x).$$

$$\frac{d}{dx}(e^{-x}y) = \frac{11}{8} e^{-4x/3}$$

4. Finally, integrate this equation,

$$\rho(x)y(x) = \int \rho(x)Q(x)dx + C,$$

then solve for y to obtain the general solution of the original differential equation.

$$e^{-x} \cdot y = \int \frac{11}{8} \cdot e^{-4x/3} dx = -\frac{33}{32} e^{-4x/3} + C.$$

$$y(x) = -\frac{33}{32} e^{-x/3} + C \cdot e^x$$

5. Substitute an initial condition $y(x_0) = y_0$ into the general solution and solve for the value of C .

$$y(0) = -\frac{33}{32} + C = -1 \Rightarrow C = \frac{1}{32}$$

$$\Rightarrow y(x) = -\frac{33}{32} e^{-x/3} + \frac{1}{32} e^x.$$

Example: Find a general solution of

$$(x^2+1) \frac{dy}{dx} + 3xy = 6x$$

1) $\frac{dy}{dx} + \underbrace{\frac{3x}{x^2+1}}_{P(x)} y = \underbrace{\frac{6x}{x^2+1}}_{Q(x)}$

$$\begin{aligned} p(x) &= \exp \left(\int \frac{3x}{x^2+1} dx \right) = \exp \left(\frac{3}{2} \int \frac{2x dx}{x^2+1} \right) \\ &= \exp \left(\frac{3}{2} \cdot \ln(x^2+1) \right) \\ &= \exp \left(\ln(x^2+1)^{3/2} \right) \\ &= (x^2+1)^{3/2}. \end{aligned}$$

$$2) (x^2+1)^{3/2} \frac{dy}{dx} + 3x(x^2+1)^{1/2}y = 6x(x^2+1)^{3/2}$$

$$3) P_x \left[(x^2+1)^{3/2} \cdot y \right] = 6x(x^2+1)^{3/2}$$

$$4) (x^2+1)^{3/2} \cdot y = \int 6x(x^2+1)^{3/2} dx = 2 \cdot (x^2+1)^{3/2} + C$$

$$\Rightarrow y(x) = 2 + C \cdot (x^2+1)^{-3/2}$$

THEOREM 1 The Linear First-Order Equation

If the functions $P(x)$ and $Q(x)$ are continuous on the open interval I containing the point x_0 , then the initial value problem

$$\frac{dy}{dx} + P(x)y = Q(x), \quad y(x_0) = y_0 \quad (11)$$

has a unique solution $y(x)$ on I , given by the formula in Eq. (6) with an appropriate value of C .