

Applied Mathematics 003 – Solving systems of linear equations

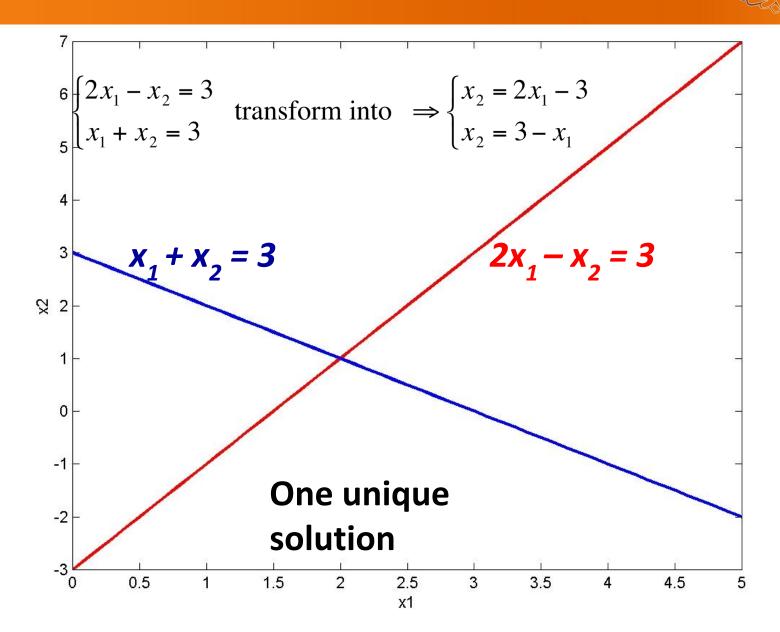
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Small Matrices

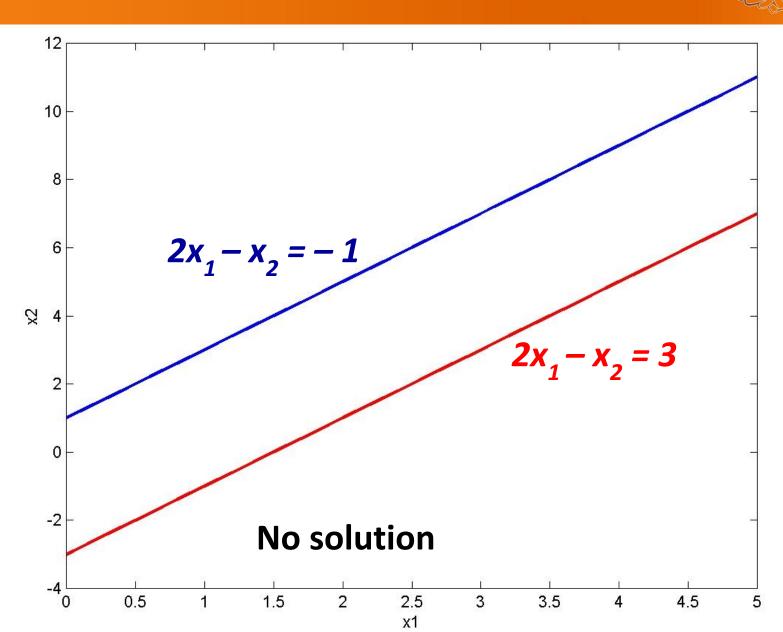


$$\begin{cases} a_{11}x_1 & +a_{12}x_2 & +\cdots & +a_{1n}x_n & =b_1 \\ a_{21}x_1 & +a_{22}x_2 & +\cdots & +a_{2n}x_n & =b_2 \\ & & & & & & & \\ a_{n1}x_1 & +a_{n2}x_2 & +\cdots & +a_{nn}x_n & =b_n \end{cases}$$

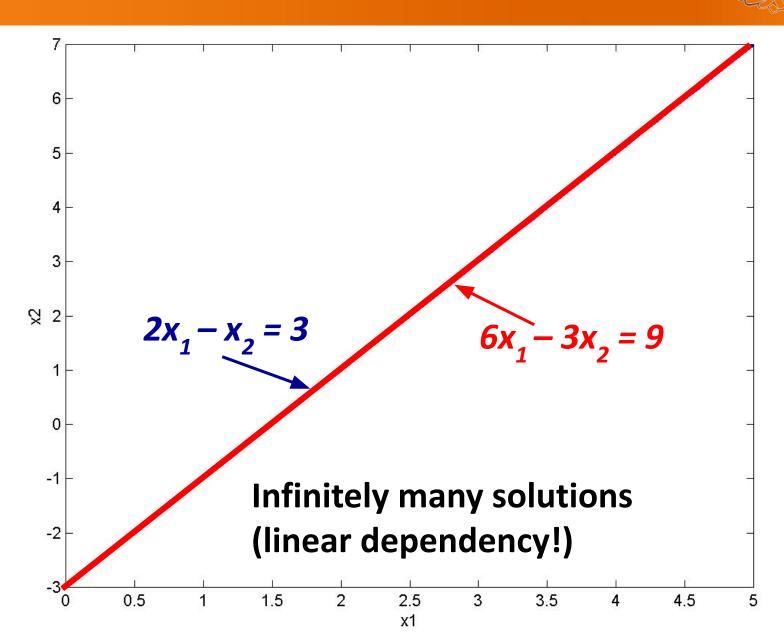
- Such systems are called linear systems of equations
 - linear = linear in x!, or Ax = b
- Three solution methods
 - Graphical solution (only for small 2x2, or 3x3 systems)
 - Cramer's rule (only practical for small systems)
 - Gaussian Elimination (general method)



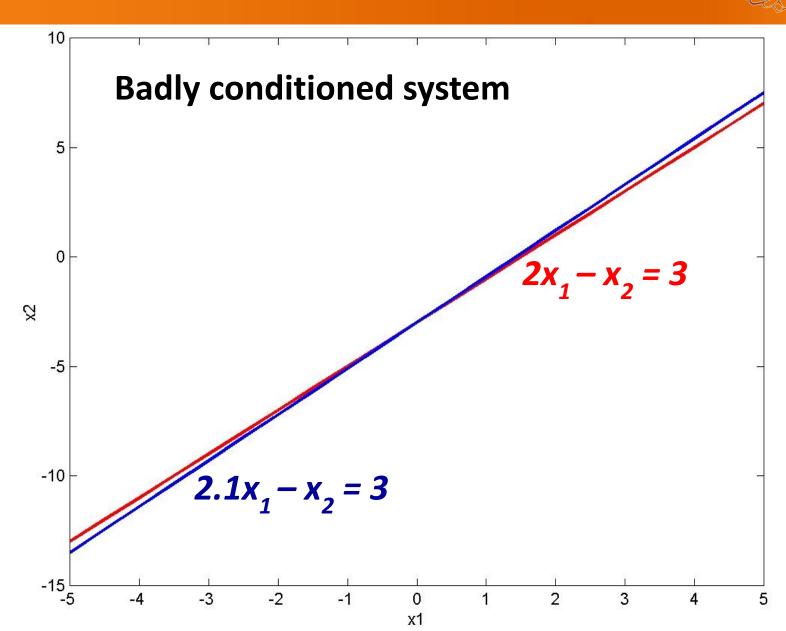












Cramer's Rule



- Use the determinant D of the matrices
- 2 x 2 matrix

• 3 x 3 matrix

$$D = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11}a_{22} - a_{12}a_{21}$$

$$D = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$$

$$= a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

Cramer's Rule



To find x_k for the following system

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

 $a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$

...

$$a_{n1}x_1 + a_{n2}x_2 + ... + a_{nn}x_n = b_n$$

- Make a new matrix, where k^{th} column of a's is simply replaced with b's (i.e., $a_{ik} \leftarrow b_i$)
- Then, the solutions x_k are given by: $x_k = \frac{D(new\ matrix)}{D(a_{ii})}$

Example



3 x 3 matrix

$$x_{1} = \frac{D_{1}}{D} = \frac{1}{D} \begin{vmatrix} b_{1} & a_{12} & a_{13} \\ b_{2} & a_{22} & a_{23} \\ b_{3} & a_{32} & a_{33} \end{vmatrix}$$

$$D = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$$

$$D = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} \qquad x_2 = \frac{D_2}{D} = \frac{1}{D} \begin{vmatrix} a_{11} & b_1 & a_{13} \\ a_{21} & b_2 & a_{23} \\ a_{31} & b_3 & a_{33} \end{vmatrix}$$

$$x_3 = \frac{D_3}{D} = \frac{1}{D} \begin{vmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \\ a_{31} & a_{32} & b_3 \end{vmatrix}$$

Ill-Conditioned System



- What happens if the determinant D is very small or zero?
 - $-D = det(A) \sim 0$
- Either there will be a division by zero
 - this happens, if the system is linearly dependent
- Or we will divide by a small number resulting in numerical instabilities

Simple Elimination Method



$$\begin{cases} a_{11}x_1 + a_{12}x_2 = b_1 \\ a_{21}x_1 + a_{22}x_2 = b_2 \end{cases}$$
Eliminate $x_2 \Rightarrow \begin{cases} a_{22}a_{11}x_1 + a_{22}a_{12}x_2 = a_{22}b_1 \\ a_{12}a_{21}x_1 + a_{12}a_{22}x_2 = a_{12}b_2 \end{cases}$

Subtract to get

$$a_{22}a_{11}x_1 - a_{12}a_{21}x_1 = a_{22}b_1 - a_{12}b_2$$

$$x_1 = \frac{a_{22}b_1 - a_{12}b_2}{a_{22}a_{11} - a_{12}a_{21}} \Rightarrow x_2 = \frac{a_{11}b_2 - a_{21}b_1}{a_{11}a_{22} - a_{12}a_{21}}$$

Not very practical for large number (> 4) of equations



- Manipulate equations to eliminate one of the unknowns
- Develop algorithm to do this recursively
- At the end, we will get an upper triangular matrix

• From this, we can easily find solution by back substitution

Naive Gauss Elimination



- Direct method (no iteration required)
- Consists of the following steps
 - Forward elimination
 - Column-by-column elimination of the below-diagonal elements
 - Reduce to upper triangular matrix
 - Back-substitution

Naive Gauss Elimination



Using

$$a_{11}x_1 + a_{12}x_2 + ... + a_{1n}x_n = b_1$$

 $a_{21}x_1 + a_{22}x_2 + ... + a_{2n}x_n = b_2$

...

$$a_{n1}x_1 + a_{n2}x_2 + ... + a_{nn}x_n = b_n$$

• Multiply the first equation by a_{21} / a_{11} and subtract from second equation

$$a_{11}x_1 + a_{12}x_2 + \dots + a_nx_n = b_1$$

$$\left(a_{21} - \frac{a_{21}}{a_{11}}a_{11}\right)x_1 + \left(a_{22} - \frac{a_{21}}{a_{11}}a_{12}\right)x_2 + \dots + \left(a_{2n} - \frac{a_{21}}{a_{11}}a_{1n}\right)x_n = b_2 - \frac{a_{21}}{a_{11}}b_1$$

...

$$a_{n1}x_1 + a_{n2}x_2 + ... + a_{nn}x_n = b_n$$



This will give:

$$a_{11}x_1 + a_{12}x_2 + ... + a_{1n}x_n = b_1$$

 $a'_{22}x_2 + ... + a'_{2n}x_n = b'_2$

...

$$a_{n1}x_1 + a_{n2}x_2 + ... + a_{nn}x_n = b_n$$

• Repeat this "forward elimination" for every row until:

$$a_{11}x_1 + a_{12}x_2 + ... + a_{1n}x_n = b_1$$

 $a'_{22}x_2 + ... + a'_{2n}x_n = b'_2$

. . .

$$a'_{n2}x_2 + ... + a'_{nn}x_n = b'_n$$



- First equation is pivot equation
- a₁₁ is **pivot element**
- Now multiply second equation by a'₃₂ /a'₂₂ and subtract from third equation

$$a_{11}x_{1} + a_{12}x_{2} + a_{13}x_{3} + \dots + a_{1n}x_{n} = b_{1}$$

$$a'_{22}x_{2} + a'_{23}x_{3} + \dots + a'_{2n}x_{n} = b'_{2}$$

$$\left(a'_{33} - \frac{a'_{32}}{a'_{22}}a'_{23}\right)x_{3} + \mathbb{X} + \left(a'_{3n} - \frac{a'_{32}}{a'_{22}}a'_{2n}\right)x_{n} = \left(b'_{3} - \frac{a'_{32}}{a'_{22}}b'_{2}\right)$$

. . .

Repeat the elimination of a'₁₂ and get

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1$$

$$a'_{22}x_2 + a'_{23}x_3 + \dots + a'_{2n}x_n = b'_2$$

$$a''_{33}x_3 + \dots + a''_{3n}x_n = b''_3$$

. . .

Continue and get

$$a_{n3}''x_3 + \cdots + a_{nn}''x_n = b_n''$$

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1$$

$$a'_{22}x_2 + a'_{23}x_3 + \dots + a'_{2n}x_n = b'_2$$

$$a''_{33}x_3 + \dots + a''_{3n}x_n = b''_3$$

. . .

$$a_{nn}^{(n-1)}x_n=b_n^{(n-1)}$$

Back Substitution



- Now we can perform back substitution to get x_k
- By simple division

$$x_{n} = \frac{b_{n}^{(n-1)}}{a_{nn}^{(n-1)}}$$

Substitute this into (n-1)th equation

$$a_{n-1,n-1}^{(n-2)} x_{n-1} + a_{n-1,n}^{(n-2)} x_n = b_{n-1}^{(n-2)}$$

• Solve for x_{n-1}

Back Substitution



- Back substitution: start with x_n
- Repeat the process to solve for x_{n-2} , x_{n-3} , ..., x_2 , x_1

$$x_{n} = \frac{b_{n}^{(n-1)}}{a_{nn}^{(n-1)}}$$

$$x_{i} = \frac{b_{i}^{(i-1)} - \sum_{j=i+1}^{n} a_{ij}^{(i-1)} x_{j}}{a_{ii}^{(i-1)}}$$

$$a_{ii}^{(i-1)} \neq 0$$

Elimination of first column



$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} & b_{1} \\ a_{21} & a_{22} & a_{23} & a_{24} & b_{2} \\ a_{31} & a_{32} & a_{33} & a_{34} & b_{3} \\ a_{41} & a_{42} & a_{43} & a_{44} & b_{4} \end{bmatrix} \qquad f_{21} = a_{21} / a_{11} \\ f_{31} = a_{31} / a_{11} \\ f_{41} = a_{41} / a_{11}$$

$$egin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} & b_1 \ 0 & a'_{22} & a'_{23} & a'_{24} & b'_2 \ 0 & a'_{32} & a'_{33} & a'_{34} & b'_3 \ 0 & a'_{42} & a'_{43} & a'_{44} & b'_4 \ \end{bmatrix}$$

$$f_{21} = a_{21} / a_{11}$$
 $f_{31} = a_{31} / a_{11}$
 $f_{41} = a_{41} / a_{11}$

$$(2)-f_{21}\times(1)$$

$$(3)-f_{31}\times(1)$$

$$(4) - f_{41} \times (1)$$

Elimination of second column



$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} & b_{1} \\ 0 & a'_{22} & a'_{23} & a'_{24} & b'_{2} \\ 0 & a'_{32} & a'_{33} & a'_{34} & b'_{3} \\ 0 & a'_{42} & a'_{43} & a'_{44} & b'_{4} \end{bmatrix} \qquad f_{32} = a'_{32} / a'_{22} \\ \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} & b_{1} \\ 0 & a'_{22} & a'_{23} & a'_{24} & b'_{2} \\ 0 & 0 & a''_{33} & a''_{34} & b''_{3} \\ 0 & 0 & a''_{43} & a''_{44} & b''_{4} \end{bmatrix} \qquad (3) - f_{32} \times (2) \\ 0 & 0 & a''_{43} & a''_{44} & b''_{4} \end{bmatrix} \qquad (4) - f_{42} \times (2)$$

Elimination of third column



$$egin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} & b_1 \ 0 & a'_{22} & a'_{23} & a'_{24} & b'_2 \ 0 & 0 & a''_{33} & a''_{34} & a''_3 \ 0 & 0 & a''_{43} & a''_{44} & a''_4 \end{bmatrix}$$

$$f_{43} = a_{43}'' / a_{33}''$$

Upper triangular matrix

$$(4) - f_{43} \times (3)$$

Back-Substitution



$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} & b_1 \\ 0 & a'_{22} & a'_{23} & a'_{24} & b'_2 \\ 0 & 0 & a''_{33} & a''_{34} & b''_3 \\ 0 & 0 & 0 & a'''_{44} & b'''_4 \end{bmatrix}$$

Upper triangular matrix

$$x_{4} = b_{4}^{m} / a_{44}^{m}$$

$$x_{3} = (b_{3}^{n} - a_{34}^{n} x_{4}) / a_{33}^{n}$$

$$a_{11}, a_{22}^{\prime}, a_{33}^{n}, a_{44}^{m} \neq 0$$

$$x_{2} = (b_{2}^{\prime} - a_{23}^{\prime} x_{3} - a_{24}^{\prime} x_{4}) / a_{22}^{\prime}$$

$$x_{1} = (b_{1} - a_{12} x_{2} - a_{13} x_{3} - a_{14} x_{4}) / a_{11}$$

Example



$$\begin{bmatrix} 1 & 0 & 2 & 3 & 1 \\ -1 & 2 & 2 & -3 & -1 \\ 0 & 1 & 1 & 4 & 2 \\ 6 & 2 & 2 & 4 & 1 \end{bmatrix} \quad f_{21} = -1$$

$$\begin{bmatrix} 1 & 0 & 2 & 3 & 1 \\ 0 & 2 & 4 & 0 & 0 \\ 0 & 1 & 1 & 4 & 2 \\ 0 & 2 & -10 & -14 & +5 \end{bmatrix} \quad (2) - (1) \times f_{21}$$

$$(3) - (1) \times f_{31}$$

$$(4) - (1) \times f_{41}$$

Forward Elimination



$$\begin{bmatrix} 1 & 0 & 2 & 3 & 1 \\ 0 & 2 & 4 & 0 & 0 \\ 0 & 1 & 1 & 4 & 2 \\ 0 & 2 & -10 & -14 & -5 \end{bmatrix} \quad f_{32} = 1/2$$

$$\begin{bmatrix} 1 & 0 & 2 & 3 & 1 \\ 0 & 2 & 4 & 0 & 0 \\ 0 & 0 & -1 & 4 & 2 \\ 0 & 0 & -14 & -14 & -5 \end{bmatrix} \quad (3) - (2) \times f_{32}$$

$$(4) - (2) \times f_{42}$$

Upper Triangular Matrix



$$\begin{bmatrix} 1 & 0 & 2 & 3 & 1 \\ 0 & 2 & 4 & 0 & 0 \\ 0 & 0 & -1 & 4 & 2 \\ 0 & 0 & -14 & -14 & -5 \end{bmatrix} \quad f_{43} = 14$$

$$\begin{bmatrix} 1 & 0 & 2 & 3 & 1 \\ 0 & 2 & 4 & 0 & 0 \\ 0 & 0 & -1 & 4 & 2 \\ 0 & 0 & 0 & -70 & -33 \end{bmatrix} \quad (4) - (3) \times f_{43}$$

Back-Substitution



$$egin{bmatrix} 1 & 0 & 2 & 3 & 1 \ 0 & 2 & 4 & 0 & 0 \ 0 & 0 & -1 & 4 & 2 \ 0 & 0 & 0 & -70 & -33 \end{bmatrix}$$

$$x_4 = -33/-70 = 33/70$$

 $x_3 = 4x_4 - 2 = -4/35$
 $x_2 = -2x_3 = 8/35$
 $x_1 = 1 - 2x_3 - 3x_4 = -13/70$





 Finding where planes (one linear equation determines a plane!) intersect

Problem Find the point of intersection of the planes x-y=2, 2x-y-z=3, and x+y+z=6 in \mathbb{R}^3 .

$$\begin{cases} x - y = 2 \\ 2x - y - z = 3 \\ x + y + z = 6 \end{cases}$$



Finding constrained solutions for polynomials

Problem Find a quadratic polynomial p(x) such that p(1) = 4, p(2) = 3, and p(3) = 4.

Suppose that
$$p(x) = ax^2 + bx + c$$
. Then $p(1) = a + b + c$, $p(2) = 4a + 2b + c$, $p(3) = 9a + 3b + c$.

$$\begin{cases} a+b+c = 4 \\ 4a+2b+c = 3 \\ 9a+3b+c = 4 \end{cases}$$



Breaking apart complex functions:

Problem Evaluate
$$\int_0^1 \frac{x(x-3)}{(x-1)^2(x+2)} dx.$$

To evaluate the integral, we need to decompose the rational function $R(x) = \frac{x(x-3)}{(x-1)^2(x+2)}$ into the sum of simple fractions:

$$R(x) = \frac{a}{x-1} + \frac{b}{(x-1)^2} + \frac{c}{x+2}$$

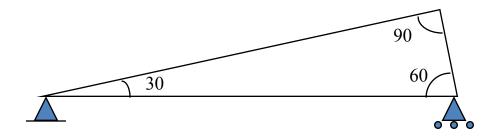
$$= \frac{a(x-1)(x+2) + b(x+2) + c(x-1)^2}{(x-1)^2(x+2)}$$

$$= \frac{(a+c)x^2 + (a+b-2c)x + (-2a+2b+c)}{(x-1)^2(x+2)}.$$

$$\begin{cases} a+c=1\\ a+b-2c=-3\\ -2a+2b+c=0 \end{cases}$$



- Consider a problem in structural engineering
- Find the forces and reactions associated with a statically determinant truss

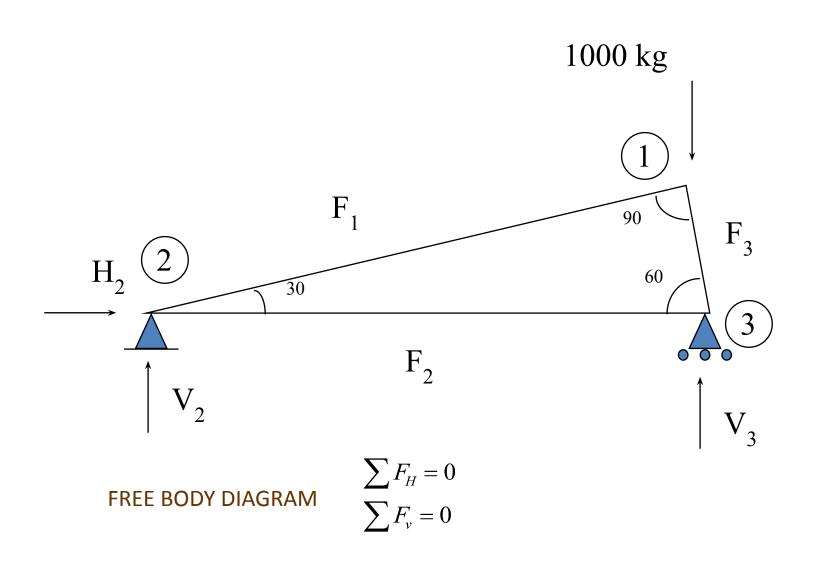


hinge: transmits both vertical and horizontal forces at the surface

roller: transmits vertical forces

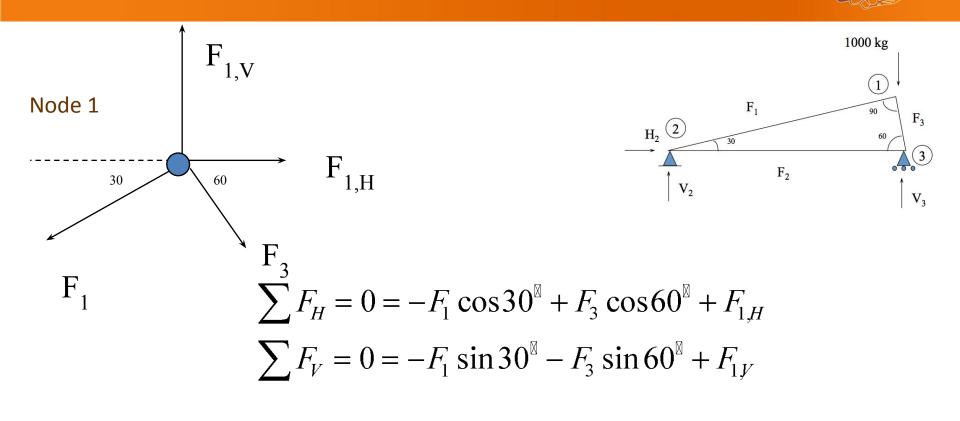
Truss – force equilibrium





Truss – node 1

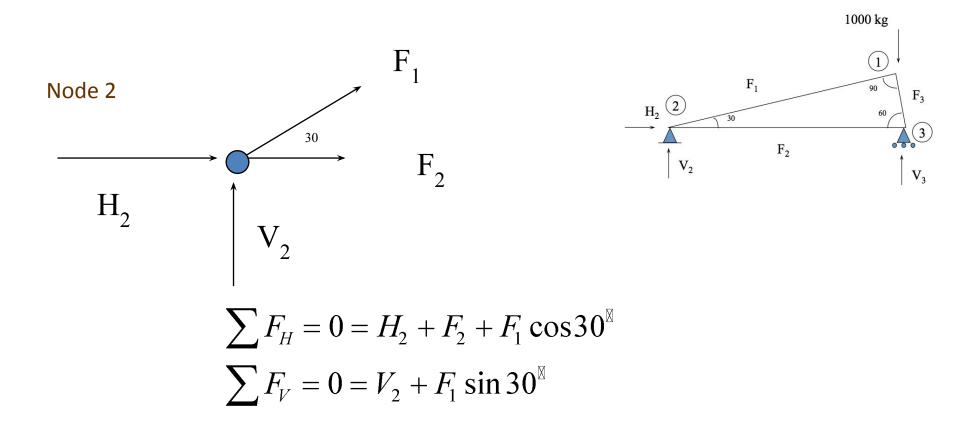




$$-F_1 \cos 30^{\text{M}} + F_3 \cos 60^{\text{M}} = 0$$
$$-F_1 \sin 30^{\text{M}} - F_3 \sin 60^{\text{M}} = -1000$$

Truss – node 2

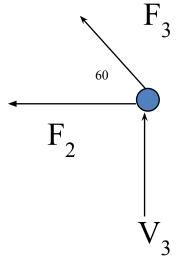




Truss – node 3

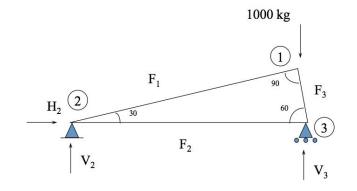






$$\sum F_H = 0 = -F_3 \cos 60^{\circ} - F_2$$

$$\sum F_V = 0 = F_3 \sin 60^{1} + V_3$$



Truss – all nodes combined



$$-F_1\cos 30^{\mathbb{N}} + F_3\cos 60^{\mathbb{N}} = 0$$

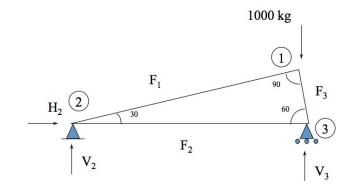
$$-F_1 \sin 30^{8} - F_3 \sin 60^{8} = -1000$$

$$H_2 + F_2 + F_1 \cos 30^{1} = 0$$

$$V_2 + F_1 \sin 30^{\mathbb{N}} = 0$$

$$-F_3 \cos 60^{\circ} - F_2 = 0$$

$$F_3 \sin 60^{1} + V_3 = 0$$



SIX EQUATIONS SIX UNKNOWNS

Truss – matrix form



F_1 F_2 F_3 H_2 V_2 V_3

-cos30 0 cos60 -sin30 0 -sin60 0 0 cos30 1 0 sin30 0 0 5 -cos60 0 0 0 sin60 0

0

-1000

0

0

0

0

Truss – matrix form



This is the basis for your matrices and the equation $[A]{x}={c}$

[-0.866]	0	0.5	O	0	0	$ F_1 $	$\begin{bmatrix} 0 \end{bmatrix}$	
-0.5	0	-0.866	0	0	0	$ F_2 $	-1000	1
0.866	1	0	1	0	0	$\int F_3 \int_{-\infty}^{\infty}$	0	Į
0.5	0	0	0	1	0	H_2	$\int_{0}^{\infty} 0$	>
0	-1	-0.5	0	0	0	$ V_2 $	0	
0	0	0.866	0	0	1	$ V_3 $	$\begin{bmatrix} 0 \end{bmatrix}$	

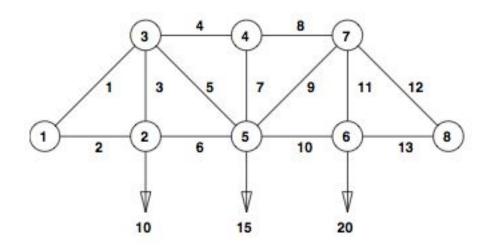
What's the answer?

see homework assignment!

Statics – force equilibrium



• Shown here is a "truss" having 13 members (the numbered lines) connecting 8 joints (the numbered circles). The indicated loads, in tons, are applied at joints 2, 5, and 6, and we want to determine the **resulting force** on each member of the truss.



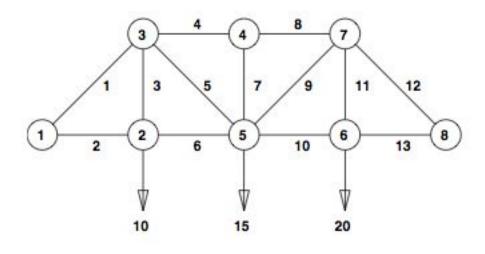
Statics – force equilibrium



- For the truss to be in static equilibrium, there must be no net force, horizontally or vertically, at any joint.
- Thus, we can determine the member forces by
 equating the horizontal forces to the left and right at
 each joint, and similarly equating the vertical forces
 upward and downward at each joint.
- For the eight joints, this would give 16 equations, which is more than the 13 unknown factors to be determined.
 - For the truss to be statically determinate, that is, for there to be a unique solution, we assume that joint 1 is rigidly fixed horizontally and vertically and that joint 8 is fixed vertically.

Force equations

- Equating the different forces yields the following system of equations
 - $\alpha = 1/sqrt(2) = sin(45deg) = cos(45)$



Joint 2:
$$f_2 = f_6,$$

 $f_3 = 10;$
Joint 3: $\alpha f_1 = f_4 + \alpha f_5,$
 $\alpha f_1 + f_3 + \alpha f_5 = 0;$
Joint 4: $f_4 = f_8,$
 $f_7 = 0;$
Joint 5: $\alpha f_5 + f_6 = \alpha f_9 + f_{10},$
 $\alpha f_5 + f_7 + \alpha f_9 = 15;$
Joint 6: $f_{10} = f_{13},$
 $f_{11} = 20;$
Joint 7: $f_8 + \alpha f_9 = \alpha f_{12},$
 $\alpha f_9 + f_{11} + \alpha f_{12} = 0;$
Joint 8: $f_{13} + \alpha f_{12} = 0.$



More on Solving Systems of Equations

Dangers with computers!



Solving Linear Systems

$$Ax = b$$

$$7x = 21$$

$$x = \frac{21}{7} = 3$$

$$x = 7^{-1} \times 21 = .142857 \times 21 = 2.99997$$



$$x = \pm (1+f) \cdot 2^e$$

$$0 \le f < 1$$

$$f = (integer < 2^{52})/2^{52}$$
 finite precision

$$-1022 \le e \le 1023$$
 finite range

$$e = integer$$



• eps is the distance from 1 to the next larger floating-point number.

```
- eps =
pow(2,(-52))=np.finfo(np.float64).eps
```

- Important: if you want to test for equality between two numbers, it is usually better to test whether the difference is around or smaller than (a multiple of) eps
- Given a, b as double:
 - if (a==b) is not good!
 - better: if (abs(a-b) < eps)</pre>



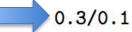
Some numbers cannot be expressed exactly!

A frequent instance of roundoff occurs with the simple

$$t = 0.1$$

The mathematical value t stored in t is not exactly 0.1 because expressing the decimal fraction 1/10 in binary requires an infinite series. In fact,

$$\frac{1}{10} = \frac{1}{2^4} + \frac{1}{2^5} + \frac{0}{2^6} + \frac{0}{2^7} + \frac{1}{2^8} + \frac{1}{2^9} + \frac{0}{2^{10}} + \frac{0}{2^{11}} + \frac{1}{2^{12}} + \cdots$$



is not exactly equal to 3 because the actual numerator is a little less than 0.3 and the actual denominator is a little greater than 0.1.



Some numbers cannot be expressed exactly!

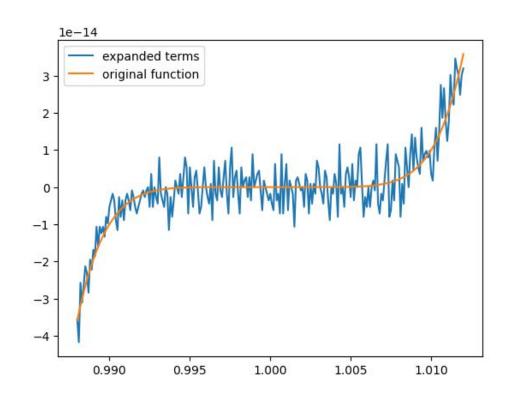
```
x = np.arange(0.988, 1.012, 0.0001)

y = pow(x, 7) - 7*pow(x, 6) + 21*pow(x, 5) - 35*pow(x, 4) + 35*pow(x, 3) - 21*pow(x, 2) + 7*x - 1
```

- This is definitely not a smooth polynomial
- If you use

```
y2 = pow((x-1), 7)
```

the plot looks smooth



A 3x3 example



$$\begin{pmatrix} 10 & -7 & 0 \\ -3 & 2 & 6 \\ 5 & -1 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 4 \\ 6 \end{pmatrix}$$

$$10x_1 - 7x_2 = 7$$

$$-3x_1 + 2x_2 + 6x_3 = 4$$

$$5x_1 - x_2 + 5x_3 = 6$$

A 3x3 example



$$\begin{pmatrix} 10 & -7 & 0 \\ 0 & -0.1 & 6 \\ 0 & 2.5 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 6.1 \\ 2.5 \end{pmatrix}$$

$$\begin{pmatrix} 10 & -7 & 0 \\ 0 & 2.5 & 5 \\ 0 & -0.1 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 2.5 \\ 6.1 \end{pmatrix}$$

$$\begin{pmatrix} 10 & -7 & 0 \\ 0 & 2.5 & 5 \\ 0 & 0 & 6.2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 2.5 \\ 6.2 \end{pmatrix}$$

A 3x3 example



$$6.2x_3 = 6.2$$

$$2.5x_2 + (5)(1) = 2.5.$$

$$10x_1 + (-7)(-1) = 7$$

$$x = \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} \qquad \begin{pmatrix} 10 & -7 & 0 \\ -3 & 2 & 6 \\ 5 & -1 & 5 \end{pmatrix} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 7 \\ 4 \\ 6 \end{pmatrix}$$

LU - Decomposition



$$L = \begin{pmatrix} 1 & 0 & 0 \\ 0.5 & 1 & 0 \\ -0.3 & -0.04 & 1 \end{pmatrix}$$

$$U = \begin{pmatrix} 10 & -7 & 0 \\ 0 & 2.5 & 5 \\ 0 & 0 & 6.2 \end{pmatrix}$$

$$P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$LU = PA$$

LU - Decomposition



$$U = M_{n-1}P_{n-1}\cdots M_2P_2M_1P_1A$$

$$L_1L_2\cdots L_{n-1}U = P_{n-1}\cdots P_2P_1A$$

$$L = L_1 L_2 \cdots L_{n-1}$$
$$P = P_{n-1} \cdots P_2 P_1$$

$$LU = PA$$

LU - Decomposition



$$A = \begin{pmatrix} 10 & -7 & 0 \\ -3 & 2 & 6 \\ 5 & -1 & 5 \end{pmatrix}$$

$$P_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \ M_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0.3 & 1 & 0 \\ -0.5 & 0 & 1 \end{pmatrix},$$

$$P_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, \ M_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0.04 & 1 \end{pmatrix},$$

$$L_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0.5 & 1 & 0 \\ -0.3 & 0 & 1 \end{pmatrix}, L_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -0.04 & 1 \end{pmatrix}$$

Solving on a computer with 3 digit resolution!



$$\begin{pmatrix} 10 & -7 & 0 \\ -3 & 2.099 & 6 \\ 5 & -1 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 3.901 \\ 6 \end{pmatrix} \qquad \begin{pmatrix} 10 & -7 & 0 \\ -3 & 2 & 6 \\ 5 & -1 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 4 \\ 6 \end{pmatrix}$$
same solution as previous system!

$$\begin{pmatrix} 10 & -7 & 0 \\ 0 & -0.001 & 6 \\ 0 & 2.5 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 6.001 \\ 2.5 \end{pmatrix}$$

$$(5 + (2.5 \cdot 10^3)(6))x_3 = (2.5 + (2.5 \cdot 10^3)(6.001))$$

$$(5+1.5000 \cdot 10^4)x_3 = (2.5+1.50025 \cdot 10^4)$$

$$1.5005 \cdot 10^4 x_3 = 1.5004 \cdot 10^4$$

Pivoting!



$$x_3 = \frac{1.5004 \cdot 10^4}{1.5005 \cdot 10^4} = 0.99993$$

$$-0.001x_2 + (6)(0.99993) = 6.001$$

$$x_2 = \frac{1.5 \cdot 10^{-3}}{-1.0 \cdot 10^{-3}} = -1.5$$

$$10x_1 + (-7)(-1.5) = 7$$

$$x_1 = -0.35$$



$$x = \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}$$



error

$$e = x - x_*$$

residual

$$r = b - Ax_*$$



$$\begin{pmatrix} 0.780 & 0.563 \\ 0.913 & 0.659 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0.217 \\ 0.254 \end{pmatrix}$$

$$\frac{0.780}{0.913} = 0.854$$
 (to three places)

$$\begin{pmatrix} 0.913 & 0.659 \\ 0 & 0.001 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0.254 \\ 0.001 \end{pmatrix}$$



$$x_2 = \frac{0.001}{0.001} = 1.00$$
 (exactly),

$$x_1 = \frac{0.254 - 0.659x_2}{0.913}$$

= -0.443 (to three places).

$$x_* = \begin{pmatrix} -0.443 \\ 1.000 \end{pmatrix}$$

$$r = b - Ax_* = \begin{pmatrix} 0.217 - ((0.780)(-0.443) + (0.563)(1.00)) \\ 0.254 - ((0.913)(-0.443) + (0.659)(1.00)) \end{pmatrix}$$

$$= \begin{pmatrix} -0.000460 \\ -0.000541 \end{pmatrix}$$
 very small residual at this resolution!



$$\begin{pmatrix} 0.913000 & 0.659000 \\ 0 & 0.000001 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0.254000 \\ -0.000001 \end{pmatrix}$$

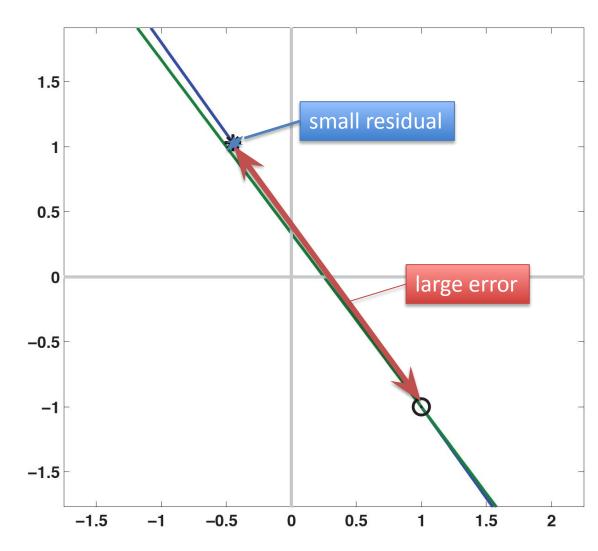
$$x_2 = \frac{-0.000001}{0.000001} = -1.00000,$$
 $x_* = \begin{pmatrix} -0.443 \\ 1.000 \end{pmatrix}$ $x_1 = \frac{0.254 - 0.659x_2}{0.913}$ $x_* = 1.000000,$ $x_* = \begin{pmatrix} -0.443 \\ 1.000 \end{pmatrix}$ very different from previous solution at 3-digit resolution at 3-digi

$$x_* = \begin{pmatrix} -0.443 \\ 1.000 \end{pmatrix}$$

very different from previous solution at 3-digit resolution!



 Ill-conditioned system describing two almost parallel lines!



Theoretical result



- Gaussian elimination with partial pivoting is guaranteed to produce small residuals (at machine resolution)
 - but NOT small error!!
- Therefore it is essential to check the results of your calculations carefully!

Partial Pivoting



- Problems with Gauss elimination
 - division by zero
 - round off errors
 - ill-conditioned systems
- Use pivoting to avoid this
 - Find the row with largest absolute coefficient below the pivot element
- Switch rows ("partial pivoting")
 - complete pivoting switches also columns (this is rarely used)

Gauss Elimination with Partial Pivoting



- Forward elimination
- for each equation j, j = 1 to n-1
 - find the maximum element in the current column
 - if the maximum element is not from the current row, then switch the current row with the maximum row (i.e., pivot)
 - Now perform the elimination
 - (a) multiply equation j by a_{kj}/a_{jj}
 - (b) subtract the result from equation

Partial (Row) Pivoting



$$\begin{aligned}
x_1 & +2x_3 & +3x_4 & = 1 \\
-x_1 & +2x_2 & +2x_3 & -3x_4 & = -1 \\
x_2 & +x_3 & +4x_4 & = 2 \\
6x_1 & +2x_2 & +2x_3 & +4x_4 & = 1
\end{aligned}$$

$$\begin{bmatrix} A & B \end{bmatrix} = \begin{bmatrix} 1 & 0 & 2 & 3 & 1 \\ -1 & 2 & 2 & -3 & -1 \\ 0 & 1 & 1 & 4 & 2 \\ 6 & 2 & 2 & 4 & 1 \end{bmatrix}$$

Forward Elimination



$$\begin{bmatrix} 6 & 2 & 2 & 4 & 1 \\ -1 & 2 & 2 & -3 & -1 \\ 0 & 1 & 1 & 4 & 2 \\ 1 & 0 & 2 & 3 & 1 \end{bmatrix}$$

Interchange rows 1 & 4

$$f_{21} = -1/6$$
 $f_{31} = 0$
 $f_{41} = 1/6$

$$\begin{bmatrix} 6 & 2 & 2 & 4 & 1 \\ 0 & 7/3 & 7/3 & -7/3 & -5/6 \\ 0 & 1 & 1 & 4 & 2 \\ 0 & -1/3 & 5/3 & 7/3 & 5/6 \end{bmatrix} (2) - (1) \times f_{21}$$

$$(3) - (1) \times f_{31}$$

$$(4) - (1) \times f_{41}$$

Forward Elimination



$$\begin{bmatrix} 6 & 2 & 2 & 4 & 1 \\ 0 & 7/3 & 7/3 & -7/3 & -5/6 \\ 0 & 1 & 1 & 4 & 2 \\ 0 & -1/3 & 5/3 & 7/3 & 5/6 \end{bmatrix}$$
No interchange required
$$f_{32} = 3/7$$

$$f_{42} = 1/7$$

$$\begin{bmatrix} 6 & 2 & 2 & 4 & 1 \\ 0 & 7/3 & 7/3 & -7/3 & -5/6 \\ 0 & 0 & 0 & 5 & 33/14 \\ 0 & 0 & 2 & 2 & 5/7 \end{bmatrix}$$

$$(3) - (2) \times f_{32}$$

$$(4) - (2) \times f_{42}$$

Back-Substitution



$$\begin{bmatrix} 6 & 2 & 2 & 4 & 1 \\ 0 & 7/3 & 7/3 & -7/3 & -5/6 \\ 0 & 0 & 2 & 2 & 5/7 \\ 0 & 0 & 0 & 5 & 33/14 \end{bmatrix} \text{ Interchange rows 3 & 4}$$

$$f_{43}=0$$

$$x_4 = (33/14)/5 = 33/70$$

$$x_3 = (5/7 - 2 x_4)/2 = -4/35$$

$$x_2 = (-5/6 + 7/3 x_4 - 7/3 x_3)/(7/3) = 8/35$$

$$x_1 = (1 - 4 x_4 - 2 x_3 - 2 x_2)/6 = -13/70$$