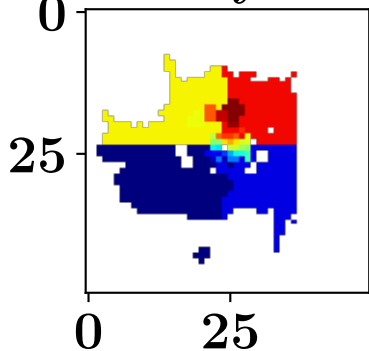


Velocity Map



150

100

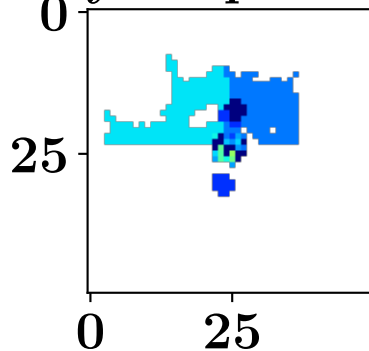
50

0

-50

-100

Velocity Dispersion Map



200

150

100

50