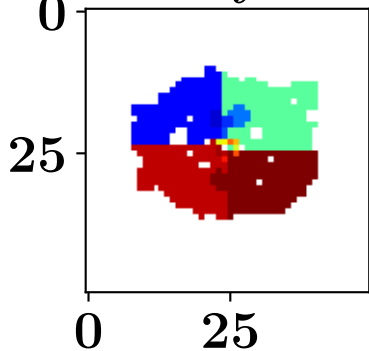


Velocity Map



100

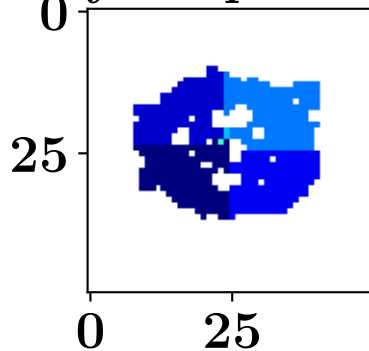
50

0

-50

-100

Velocity Dispersion Map



200

175

150

125

100

75

50