

## CS 340 - Assignment 4

### Exercise 9.1

s G D A B H E I F C t

### Exercise 9.3

Source code and explanation are submitted as cpp file separately.

### Exercise 9.5

a.

v	known	d <sub>v</sub>	p <sub>v</sub>
A	F	0	0
B	F	∞	0
C	F	∞	0
D	F	∞	0
E	F	∞	0
F	F	∞	0
G	F	∞	0

v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	F	5	A
C	F	3	A
D	F	∞	0
E	F	∞	0
F	F	∞	0
G	F	∞	0

v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	F	5	A
C	T	3	A
D	F	10	C
E	F	10	C
F	F	∞	0
G	F	∞	0

v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	5	A
C	T	3	A
D	F	10	C
E	F	8	B
F	F	∞	0
G	F	6	B

v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	5	A
C	T	3	A
D	F	10	C
E	F	7	G
F	F	∞	0
G	T	6	B

v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	5	A
C	T	3	A
D	F	9	E
E	T	7	G
F	F	8	E
G	T	6	B

v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	5	A
C	T	3	A
D	F	9	E
E	T	7	G
F	T	8	E
G	T	6	B

v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	5	A
C	T	3	A
D	T	9	E
E	T	7	G
F	T	8	E
G	T	6	B

Shortest paths from A to other vertices:

AB

AC

ABGED

ABGE

ABGEF

ABG

b.

v	known	d <sub>v</sub>	p <sub>v</sub>
A	F	∞	0
B	F	0	0
C	F	∞	0
D	F	∞	0
E	F	∞	0
F	F	∞	0
G	F	∞	0

v	known	d <sub>v</sub>	p <sub>v</sub>
A	F	∞	0
B	T	0	0
C	F	1	B
D	F	∞	0
E	F	1	B
F	F	∞	0
G	F	1	B

v	known	d <sub>v</sub>	p <sub>v</sub>
A	F	∞	0
B	T	0	0
C	T	1	B
D	F	2	C
E	T	1	B
F	F	2	E
G	T	1	B

v	known	d <sub>v</sub>	p <sub>v</sub>
A	F	3	D
B	T	0	0
C	T	1	B
D	T	2	C
E	T	1	B
F	T	2	E
G	T	1	B

v	known	$d_v$	$p_v$
A	T	3	D
B	T	0	0
C	T	1	B
D	T	2	C
E	T	1	B
F	T	2	E
G	T	1	B

Shortest paths from B to other vertices:

BCDA

BC

BCD

BE

BEF

BG

## Exercise 9.6

The worst-case running time of Dijkstra's algorithm when implemented with d-heaps is  $O(|E| \log_d |V|)$

## Exercise 9.8

The distances of vertices are kept in a priority queue. At any time, the keys in the priority queue are in the set  $\{D + 1, D + 2, \dots, D + |E|\}$ , where  $D$  is the value of the last key removed from the priority queue. Since the sequence of keys removed by the algorithm is increasing, every key is at least  $D + 1$  and at most  $D + |E|$ .

The priority queue can be implemented with a circular array  $A[0 \dots |E|-1]$  of size  $|E|$ . Each vertex with key  $k$  in the bucket in cell  $A[h(k)]$  where  $h(k) = k \bmod (|E|) + 1$ . Operations on priority queue will be modified as follow:

- delete-min: while  $A[h(D)]$  is empty, increment  $D$ . Then delete and return a vertex from  $A[h(D)]$ .

- insert with key  $k$ : Add to  $A[h(k)]$ .

- decrease-key  $k$  to  $k'$ : Move the vertex from  $A[h(k)]$  to  $A[h(k')]$

Insert and decrease-key are constant-time operators, so the total time spent in those operations will be  $O(|V| + |E|)$ . The total time spent in delete-min will be  $O(|V|)$  plus the final value of  $D$ .

The final value of  $D$  is the maximum distance from the source to any vertex. The maximum distance is at most  $|E|(|V| - 1)$  because each path has at most  $|V| - 1$  edges. Thus, the total time spent by the algorithm is  $O(|E||V| + |E|)$ .

**Exercise 9.9** Source code and explanation are submitted as cpp file separately.

## Exercise 9.15

Prim's algorithm

v	known	d <sub>v</sub>	p <sub>v</sub>
A	F	0	0
B	F	∞	0
C	F	∞	0
D	F	∞	0
E	F	∞	0
F	F	∞	0
G	F	∞	0
H	F	∞	0
I	F	∞	0
J	F	∞	0
v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	3	A
C	F	10	B
D	F	4	A
E	F	2	B
F	F	3	B
G	F	∞	0
H	F	∞	0
I	F	∞	0
J	F	∞	0

v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	F	3	A
C	F	∞	0
D	F	4	A
E	F	4	A
F	F	∞	0
G	F	∞	0
H	F	∞	0
I	F	∞	0
J	F	∞	0
v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	3	A
C	F	10	B
D	F	4	A
E	T	2	B
F	F	3	B
G	F	∞	0
H	F	2	E
I	F	1	E
J	F	∞	0

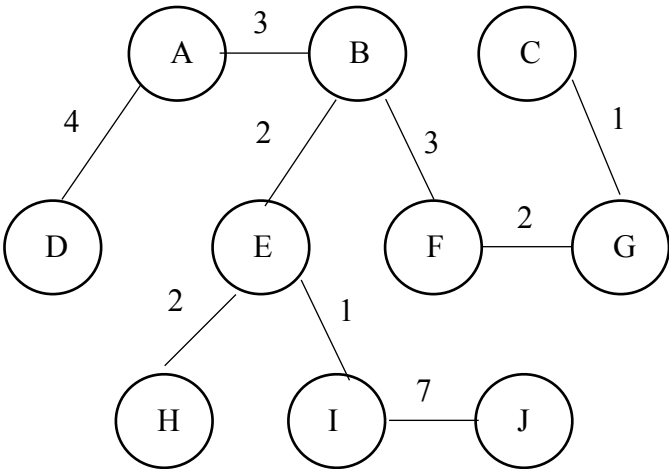
v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	3	A
C	F	10	B
D	F	4	A
E	T	2	B
F	F	3	B
G	F	∞	0
H	F	2	E
I	T	1	E
J	F	7	I
v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	3	A
C	F	6	F
D	F	4	A
E	T	2	B
F	T	3	B
G	F	2	F
H	T	2	E
I	T	1	E
J	F	7	I

v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	3	A
C	F	10	B
D	F	4	A
E	T	2	B
F	F	3	B
G	F	∞	0
H	T	2	E
I	T	1	E
J	F	7	I
v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	3	A
C	F	1	G
D	F	4	A
E	T	2	B
F	T	3	B
G	T	2	F
H	T	2	E
I	T	1	E
J	F	7	I

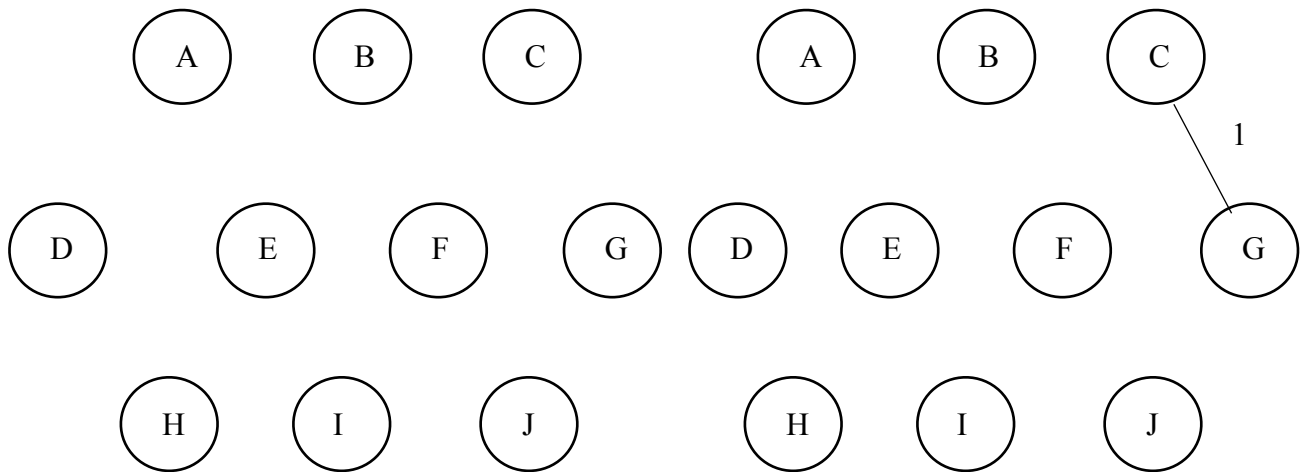
v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	3	A
C	T	1	G
D	F	4	A
E	T	2	B
F	T	3	B
G	T	2	F
H	T	2	E
I	T	1	E
J	F	7	I

v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	3	A
C	T	1	G
D	T	4	A
E	T	2	B
F	T	3	B
G	T	2	F
H	T	2	E
I	T	1	E
J	T	7	I

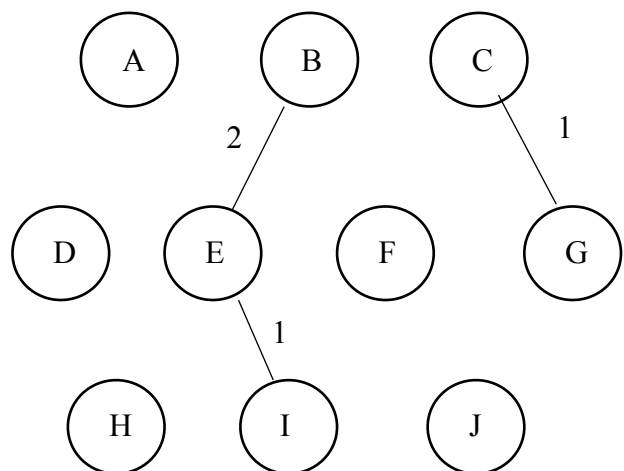
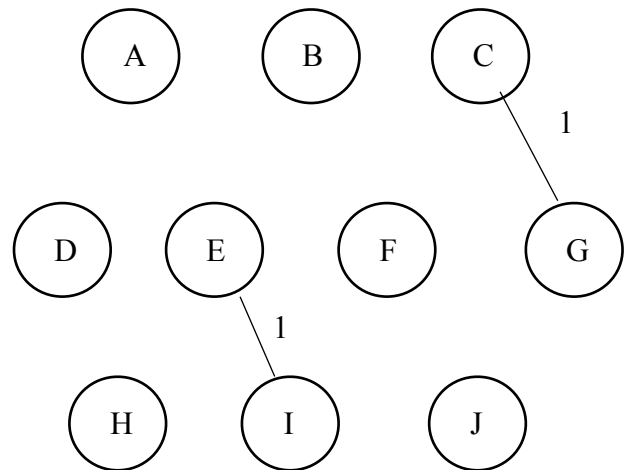
v	known	d <sub>v</sub>	p <sub>v</sub>
A	T	0	0
B	T	3	A
C	T	1	G
D	T	4	A
E	T	2	B
F	T	3	B
G	T	2	F
H	T	2	E
I	T	1	E
J	F	7	I



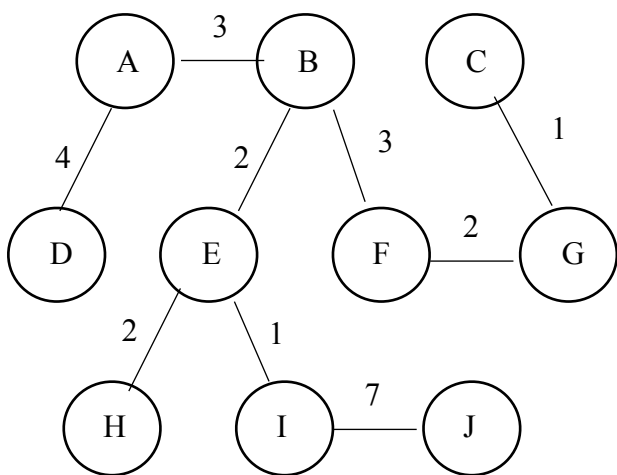
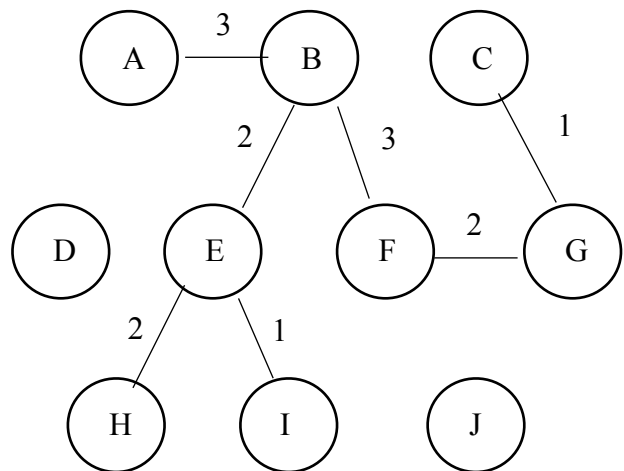
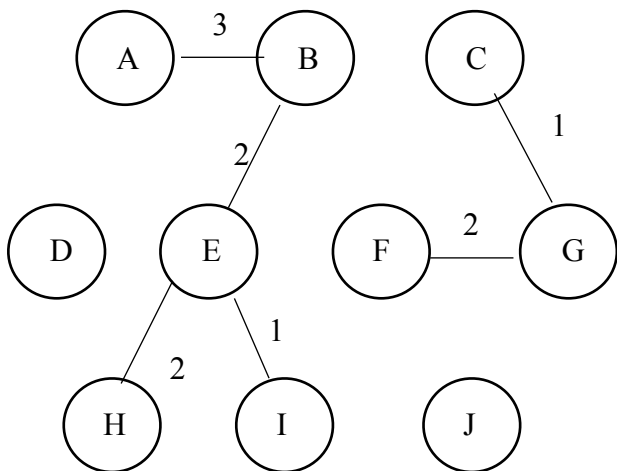
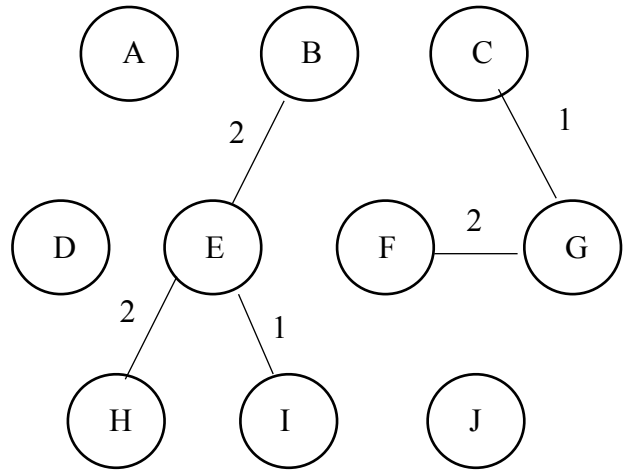
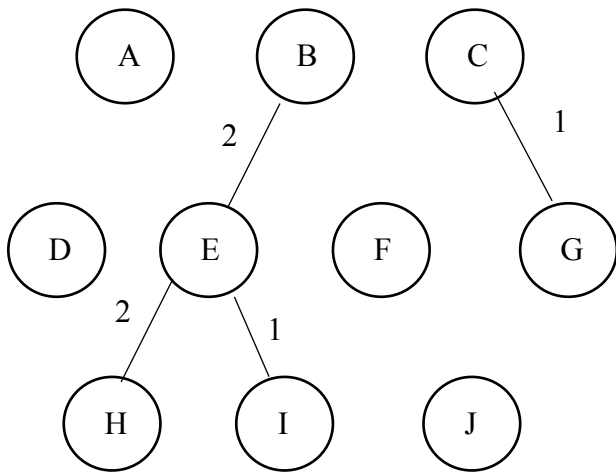
## Kruskal's algorithm



Edge	Weight	Action
(C,G)	1	Accepted
(E, I)	1	Accepted
(B,E)	2	Accepted
(E,H)	2	Accepted
(F,G)	2	Accepted
(A,B)	3	Accepted
(B,F)	3	Accepted
(F,I)	3	Rejected
(A,D)	4	Accepted
(A,E)	4	Rejected
(H,I)	4	Rejected
(D,E)	5	Rejected
(C,F)	6	Rejected
(D,H)	6	Rejected
(I,J)	7	Accepted







This minimum spanning tree is unique. Because the maximum weight edge in any cycle of the graph is unique, there is only one way to remove the cycle, which makes the MST is unique.

### Exercise 9.21

Articulation points: C, E, F

