

STT 843: Multivariate Analysis

11. Multivariate Linear Regression (Chapter 7.7)

Guanqun Cao

Department of Statistics and Probability
Michigan State University

Spring 2026

Outline

- 1 New observation
- 2 Model Corrected for Means
- 3 Subset Selection

Unbiased estimate of $\text{var}(\mathbf{y}_i) = \text{var}(\mathbf{e}_i) = \Sigma$

$$\begin{aligned}\mathbf{S} &= \frac{\mathbf{E}}{n - q - 1} = \frac{(\mathbf{Y} - \mathbf{X}\hat{\mathbf{B}})^\top (\mathbf{Y} - \mathbf{X}\hat{\mathbf{B}})}{n - q - 1} = \frac{\hat{\Xi}^\top \hat{\Xi}}{n - q - 1} \\ &= \frac{1}{n - q - 1} \left(\mathbf{Y}^\top \mathbf{Y} - \hat{\mathbf{B}}^\top \mathbf{X}^\top \mathbf{Y} \right)\end{aligned}$$

Proof:

$$\begin{aligned}E\left\{\hat{\Xi}_{n \times p}\right\} &= E\{\mathbf{Y} - \mathbf{X}\hat{\mathbf{B}}\} \\ &= E\left\{\left(\mathbf{I}_n - \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top\right) \mathbf{Y}\right\} \\ &= \left(\mathbf{I}_n - \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top\right) E\{\mathbf{X}\mathbf{B} + \Xi\} \\ &= \left(\mathbf{I}_n - \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top\right) E\{\Xi\} \\ &= \mathbf{0}\end{aligned}$$

$$\begin{aligned}
E \{ \hat{\mathbf{e}}_{.i}^T \hat{\mathbf{e}}_{.j} \} &= E \left\{ \left[\left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \mathbf{y}_{.i} \right]^T \left[\left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \mathbf{y}_{.j} \right] \right\} \\
&= E \left\{ \left[\left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \mathbf{e}_{.i} \right]^T \left[\left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \mathbf{e}_{.j} \right] \right\} \\
&= E \{ \underbrace{\mathbf{e}_{.i}^T \left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \mathbf{e}_{.j}}_{\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T} \} \\
&= E \left\{ \text{tr} \left\{ \left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \mathbf{e}_{.j} \mathbf{e}_{.i}^T \right\} \right\} \\
&= \text{tr} \left\{ \left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \underbrace{E \{ \mathbf{e}_{.j} \mathbf{e}_{.i}^T \}}_{\sigma_{ij} \mathbf{I}_n} \right\} \\
&= \sigma_{ij} \text{tr} \left\{ \left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \right\} \\
&= \sigma_{ij} \left(\text{tr} \{ \mathbf{I}_n \} - \text{tr} \left\{ \mathbf{X}^T \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \right\} \right) \\
&= \sigma_{ij} (n - (q + 1)) \\
\therefore E \left\{ \frac{1}{n - q - 1} \hat{\Sigma}^T \hat{\Sigma} \right\} &= \Sigma = (\sigma_{ij})
\end{aligned}$$

Note: If \mathbf{X} is not full rank, we can obtain similar results based on $\hat{\mathbf{B}} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{Y} \dots$ we'll leave that discussion for "linear models"

Another note: $\widehat{\text{var}}\{\mathbf{e}_{np \times 1}\} = \left(\frac{1}{n-q-1} \mathbf{E}\right) \otimes \mathbf{I}_n$

and $E\left\{\left(\frac{1}{n-q-1} \mathbf{E}\right) \otimes \mathbf{I}_n\right\} = \boldsymbol{\Sigma} \otimes \mathbf{I}_n$

Variance of $\hat{\beta}$ (i.e., $\text{var}\{\text{vec } \hat{\mathbf{B}}\}$)

$$\begin{aligned}\text{var} \left\{ \begin{matrix} \hat{\beta} \\ rp \times 1 \end{matrix} \right\} &= \text{var} \left\{ [(\mathbf{I} \otimes \mathbf{X})^T (\mathbf{I} \otimes \mathbf{X})]^{-1} (\mathbf{I} \otimes \mathbf{X})^T \text{vec } \mathbf{Y} \right\} \\&= \left[\mathbf{I}_p \otimes (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right] \text{var}\{\text{vec } \mathbf{Y}\} \left[\mathbf{I}_p \otimes (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right]^T \\&= \left[\mathbf{I}_p \otimes (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right] \text{var}\{\text{vec } \Xi\} \left[\mathbf{I}_p \otimes (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right]^T \\&= \left[\mathbf{I}_p \otimes (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right] (\Sigma \otimes \mathbf{I}_n) \left[\mathbf{I}_p \otimes \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \right] \\&= \Sigma \otimes \left[(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{I}_n \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \right] \\&= \Sigma \otimes (\mathbf{X}^T \mathbf{X})^{-1}\end{aligned}$$

Notes:

$$(a) \widehat{\text{var}}\{\hat{\boldsymbol{\beta}}\} = \overbrace{\left(\frac{1}{n-q-1}\mathbf{E}\right)}^{\text{"S"}} \otimes (\mathbf{X}^T\mathbf{X})^{-1}$$

$$(b) \text{cov}\left\{\hat{\beta}_{.i}, \hat{\beta}_{.j}\right\} = \sigma_{ij} (\mathbf{X}^T\mathbf{X})^{-1}$$

(c)

$$\begin{aligned} & \text{cov} \left\{ \hat{\beta}_{\cdot i}, \hat{\mathbf{e}}_{\cdot j} \right\} \\ &= \text{cov} \left\{ (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}_{\cdot i}, \left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \mathbf{y}_{\cdot j} \right\} \\ &= \text{cov} \left\{ (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{e}_{\cdot i}, \left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \mathbf{e}_{\cdot j} \right\} \\ &= (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \sigma_{ij} \mathbf{I}_n \left(\mathbf{I}_n - \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right) \\ &= \sigma_{ij} \left[(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T - (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \right] \\ &= \mathbf{0}_{r \times n} \end{aligned}$$

New observation

(d) Estimating mean of $\mathbf{x}_0^\top \mathbf{B}$
 $1 \times r^{r \times p}$

- $\mathbf{x}_0^\top \hat{\mathbf{B}}$ is an unbiased estimator of $\mathbf{x}_0^\top \mathbf{B}$
- $\text{var} \left\{ \mathbf{x}_0^\top \hat{\mathbf{B}} \right\} = \underbrace{\boldsymbol{\Sigma} (\mathbf{x}_0^\top (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{x}_0)}_{\text{scalar}}$

(e) Estimating a new observation \mathbf{y}_0 using \mathbf{x}_0
 $\mathbf{y}_0^\top = \mathbf{x}_0^\top \mathbf{B} + \mathbf{e}_0^\top$

- $\mathbf{x}_0^T \hat{\mathbf{B}}$ is an unbiased estimator of \mathbf{y}_0
- $\text{var} \left\{ \mathbf{y}_0^T - \mathbf{x}_0^T \hat{\mathbf{B}} \right\} \leftarrow$ "forecast error variance"
- Note that

$$\begin{aligned}
 \text{cov} \left\{ \mathbf{y}_0^T, \mathbf{x}_0^T \hat{\mathbf{B}} \right\} &= \text{cov} \left\{ \mathbf{e}_0^T, \mathbf{x}_0^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T (\mathbf{X} \mathbf{B} + \mathbf{\Xi}) \right\} \\
 &= \text{cov} \left\{ \mathbf{e}_0^T, \mathbf{x}_0^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{\Xi} \right\} \\
 &= \mathbf{0}_{p \times p} \quad \text{since } \mathbf{e}_0^T \text{ is indep. of } \mathbf{\Xi} = \begin{bmatrix} \mathbf{e}_1^T \\ \vdots \\ \mathbf{e}_n^T \end{bmatrix}
 \end{aligned}$$

So

$$\begin{aligned}
 \text{var} \left\{ \mathbf{y}_0^\top - \mathbf{x}_0^\top \hat{\mathbf{B}} \right\} &= \text{var} \left\{ \mathbf{y}_0^\top \right\} + \text{var} \left\{ \mathbf{x}_0^\top \hat{\mathbf{B}} \right\} - 2 \text{cov} \left\{ \mathbf{y}_0^\top, \mathbf{x}_0^\top \hat{\mathbf{B}} \right\} \\
 &= \boldsymbol{\Sigma} + \boldsymbol{\Sigma} \cdot \left(\mathbf{x}_0^\top (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{x}_0 \right) + \mathbf{0} \\
 &= \boldsymbol{\Sigma} \cdot \left[1 + \mathbf{x}_0^\top (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{x}_0 \right]
 \end{aligned}$$

MLE's of \mathbf{B} and $\mathbf{\Sigma}$ $r \times p$

Thus far, we have assumed $E\{\mathbf{e}\} = \mathbf{0}$ and $\text{var}\{\mathbf{e}\} = \mathbf{\Sigma} \otimes \mathbf{I}_n \text{ vec } \Xi$
If we assume:

$$\mathbf{e}_{np \times 1} \sim N_{np}(\mathbf{0}, \mathbf{\Sigma} \otimes \mathbf{I}_n)$$

then MLE's of \mathbf{B} and $\mathbf{\Sigma}$ are

$$\hat{\mathbf{B}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$$

and

$$\hat{\mathbf{\Sigma}}_{p \times p} = \frac{1}{n} \hat{\Xi}^T \hat{\Xi} = \frac{1}{n} \mathbf{E}$$

where

$$\mathbf{E} \sim W_p(n - q - 1, \mathbf{\Sigma})$$

Proof: omitted.

Model Corrected for Means

Rewrite

$$\mathbf{Y} = \underset{n \times r}{\mathbf{X}} \mathbf{B} + \mathbf{\Xi}$$

as

$$\underset{n \times p}{\mathbf{Y}_c} = \underset{n \times q}{\mathbf{X}_c} \underset{q \times p}{\mathbf{B}_c} + \mathbf{\Xi} \text{ where } q = \# \text{ of predictors} = r - 1$$

and

$$\mathbf{Y}_c = \begin{bmatrix} y_{11} - \bar{y}_{\cdot 1} & y_{12} - \bar{y}_{\cdot 2} & \cdots & y_{1p} - \bar{y}_{\cdot p} \\ \vdots & & & \vdots \\ y_{n1} - \bar{y}_{\cdot 1} & y_{n2} - \bar{y}_{\cdot 2} & \cdots & y_{np} - \bar{y}_{\cdot p} \end{bmatrix}$$

$$\mathbf{X}_c = \begin{bmatrix} x_{11} - \bar{x}_{\cdot 1} & \cdots & x_{1q} - \bar{x}_{\cdot q} \\ \vdots & & \vdots \\ x_{n1} - \bar{x}_{\cdot 1} & \cdots & x_{nq} - \bar{x}_{\cdot q} \end{bmatrix}$$

- Then $\hat{\mathbf{B}}_c = \mathbf{S}_{xx}^{-1} \mathbf{S}_{xy}$ where $\mathbf{S} = \begin{bmatrix} \mathbf{S}_{yy} & \mathbf{S}_{yx} \\ \mathbf{S}_{xy} & \mathbf{S}_{xx} \end{bmatrix}$ is the sample covariance matrix of the $p + q$ variables $(y_1, \dots, y_p, x_1, \dots, x_q)$
- $\hat{\mathbf{Y}} = [\bar{y}_{\cdot 1} \mathbf{1}_n, \dots, \bar{y}_{\cdot p} \mathbf{1}_n] + \underset{n \times q}{\mathbf{X}}_c \underset{q \times p}{\hat{\mathbf{B}}}_c$

Hypothesis Tests (assuming $\mathbf{e} \sim N_{np} \{\mathbf{0}, \boldsymbol{\Sigma} \otimes \mathbf{I}_r\}$)

$$H_0 : \underset{q \times p}{\mathbf{B}_1} = \mathbf{0} \quad (\text{Test of overall regression})$$

where $\underset{r \times p}{\mathbf{B}} = \begin{bmatrix} \beta_0^\top \\ \mathbf{B}_1 \end{bmatrix} \begin{matrix} \leftarrow 1 \times p \text{ vector of intercepts} \\ \leftarrow q \times p \end{matrix}$

Partition the total SS and CP matrix

$$\begin{aligned}\mathbf{Y}^T\mathbf{Y} &= (\mathbf{Y} - \mathbf{X}\hat{\mathbf{B}})^T(\mathbf{Y} - \mathbf{X}\hat{\mathbf{B}}) + \hat{\mathbf{B}}^T\mathbf{X}^T\mathbf{Y}^T \\ &= \mathbf{E} + \hat{\mathbf{B}}^T\mathbf{X}^T\mathbf{Y}^T\end{aligned}$$

To avoid inclusion of $\beta_0^T = \mathbf{0}^T$ as part of the null hypothesis, we subtract $n\overline{\mathbf{Y}}\overline{\mathbf{Y}}^T$:

$$\underbrace{\mathbf{Y}^T\mathbf{Y} - n\overline{\mathbf{Y}}\overline{\mathbf{Y}}^T}_{\text{corrected total SS \& CP}} = \underbrace{\mathbf{Y}^T\mathbf{Y} - \hat{\mathbf{B}}^T\mathbf{X}^T\mathbf{Y}^T}_{\mathbf{E}_{p \times p}} + \underbrace{\hat{\mathbf{B}}^T\mathbf{X}^T\mathbf{Y}^T - n\overline{\mathbf{Y}}\overline{\mathbf{Y}}^T}_{\mathbf{H}_{p \times p}}$$

$$\Lambda = \frac{|\mathbf{E}|}{|\mathbf{E} + \mathbf{H}|} = \frac{|\mathbf{Y}^T\mathbf{Y} - \hat{\mathbf{B}}^T\mathbf{X}^T\mathbf{Y}^T|}{|\mathbf{Y}^T\mathbf{Y} - n\overline{\mathbf{Y}}\overline{\mathbf{Y}}^T|} \sim \Lambda_{p, \underbrace{q}_{r-1}, \underbrace{n-q-1}_{n-r}}$$

- \mathbf{H} is "large" when $\hat{\beta}_{ij}$'s are large
- The 4 MANOVA statistics can be calculated as functions of the eigenvalues of $\mathbf{E}^{-1}\mathbf{H}, (\lambda_1, \dots, \lambda_s)$:
 - Wilks': $\Lambda = \prod_{i=1}^s \frac{1}{1+\lambda_i}$
 - Roy's: $\theta = \lambda_1$
 - Pillai's Trace: $V = \sum_{i=1}^s \frac{\lambda_i}{1+\lambda_i}$
 - Lawley-Hotelling Trace: $U = \sum_{i=1}^s \lambda_i$

Critical values (and p -values) based on approximate F -distributions given on the MANOVA pages

$$s = \min(p, q)$$

$$m = \frac{1}{2}(|q - p| - 1)$$

$$N = \frac{1}{2}(n - q - p - 2)$$

Essential dimensionality of $\underbrace{\mathbf{E}^{-1}\mathbf{H}}_{p \times p}$ is the essential dimensionality of

\mathbf{B}_1 . For example, a single non-zero eigenvalue (i.e., rank of \mathbf{B}_1 is 1) $q \times p$ could be due to several causes:

- ① \mathbf{B}_1 has only one nonzero row \Rightarrow only one of the \mathbf{X} 's predicts the \mathbf{Y} 's
- ② \mathbf{B}_1 has only one nonzero column \Rightarrow only one of the \mathbf{Y} 's is predicted by the \mathbf{X} 's
- ③ All of the rows of \mathbf{B}_1 are linear combinations of each other \Rightarrow \mathbf{X} 's act alike in predicting \mathbf{Y} 's [or, in other words]
- ④ All of the columns of \mathbf{B}_1 are linear combinations of each other \Rightarrow only one dimension in the \mathbf{Y} 's as they relate to \mathbf{X} 's

- "Essential dimensionality" of $\mathbf{E}^{-1}\mathbf{H}$ is number of substantially non-zero eigenvalues and takes value less than or equal to $s = \min(p, q)$
- Λ can also be calculated from the partitioned sample covariance matrix of $(y_1, \dots, y_p, x_1, \dots, x_q)$

$$\mathbf{S}_{(p+q) \times (p+q)} = \begin{bmatrix} \mathbf{S}_{yy} & \mathbf{S}_{yx} \\ \mathbf{S}_{xy} & \mathbf{S}_{xx} \end{bmatrix}$$

$p \times p$ $p \times q$
 $q \times p$ $q \times q$

using

$$\frac{|\mathbf{S}|}{|\mathbf{S}_{xx}| |\mathbf{S}_{yy}|}$$

which is essentially a test of independence between \mathbf{y} and \mathbf{x} since

Independence of \mathbf{y} and $\mathbf{x} \Rightarrow |\mathbf{S}| = |\mathbf{S}_{yy}| |\mathbf{S}_{xx}|$

$H_0 : \mathbf{B}_a = \mathbf{0}$ Tests on a subset of the \mathbf{x}' s

Hypothesis states that the \mathbf{Y}' s do not depend on the last h of the \mathbf{X}' s. That is,

$$H_0 : \mathbf{B}_{\text{add}} = \mathbf{0}$$

where

$$\mathbf{B}_{r \times p} = \begin{bmatrix} \mathbf{B}_{\text{red}} \\ \mathbf{B}_{\text{add}} \end{bmatrix} \begin{matrix} \leftarrow (r-h) \times p \\ \leftarrow h \times p \end{matrix}$$

Compare SS and CP matrix for full and reduced models

$$\mathbf{H}_{\text{diff}} = \hat{\mathbf{B}}^T \mathbf{X}^T \mathbf{Y} - \hat{\mathbf{B}}_r^T \mathbf{X}_r^T \mathbf{Y} \quad \leftarrow \text{difference in regression SS and CP}$$

$p \times p$

$$\mathbf{E}_{\text{full}} = \mathbf{Y}^T \mathbf{Y} - \hat{\mathbf{B}}^T \mathbf{X}^T \mathbf{Y} \quad \leftarrow \mathbf{E} \text{ matrix based on full model}$$

$p \times p$

Then

$$\begin{aligned} \Lambda_{x_{q-h+1}, \dots, x_q | x_1, \dots, x_{q-h}} &= \frac{|\mathbf{E}_{\text{full}}|}{|\mathbf{E}_{\text{full}} + \mathbf{H}_{\text{diff}}|} = \frac{|\mathbf{E}_{\text{full}}|}{|\mathbf{E}_{\text{red}}|} \\ &= \frac{|\mathbf{Y}^T \mathbf{Y} - \hat{\mathbf{B}}^T \mathbf{X}^T \mathbf{Y}|}{|\mathbf{Y}^T \mathbf{Y} - \hat{\mathbf{B}}_{\text{red}}^T \mathbf{X}_{\text{red}}^T \mathbf{Y}|} \\ &\sim \Lambda_{p, h, n-q-1} \end{aligned}$$

$$\Lambda_{x_{q-h+1}, \dots, x_q | x_1, \dots, x_{q-h}} = \frac{\left(\frac{|\mathbf{Y}^T \mathbf{Y} - \hat{\mathbf{B}}^T \mathbf{X}^T \mathbf{Y}|}{|\mathbf{Y}^T \mathbf{Y} - n \bar{\mathbf{Y}}^T \bar{\mathbf{Y}}|} \right)}{\left(\frac{|\mathbf{Y}^T \mathbf{Y} - \hat{\mathbf{B}}_{\text{red}}^T \mathbf{X}_{\text{red}}^T \mathbf{Y}|}{|\mathbf{Y}^T \mathbf{Y} - n \bar{\mathbf{Y}} \bar{\mathbf{Y}}^T|} \right)} = \frac{\Lambda_{\text{full}}}{\Lambda_{\text{red}}}$$

→ makes full vs. reduced testing simple to carry out

- Note: θ , V , and U can be calculated from eigenvalues of $\mathbf{E}_{\text{full}}^{-1} \mathbf{H}_{\text{diff}}$ with

$$s = \min(p, h)$$

$$m = \frac{1}{2}(|h - p| - 1)$$

$$N = \frac{1}{2}(n - h - p - 2)$$

Subset Selection

Finding a subset of the \mathbf{X} 's to include in a model

- Forward Selection

(Step 1)

Start with

$$\hat{\mathbf{B}}_i = \begin{bmatrix} \hat{\beta}_{01} & \hat{\beta}_{02} & \cdots & \hat{\beta}_{0p} \\ \hat{\beta}_{i1} & \hat{\beta}_{i2} & \cdots & \hat{\beta}_{ip} \end{bmatrix}$$

and calculate

$$\Lambda_{\mathbf{X}_i} = \frac{|\mathbf{Y}'\mathbf{Y} - \hat{\mathbf{B}}_i'\mathbf{X}_i'\mathbf{Y}|}{|\mathbf{Y}'\mathbf{Y} - n\overline{\mathbf{Y}\mathbf{Y}}'|} \sim \Lambda_{p,1,n-2}$$

for $i = 1, \dots, q$. Add the \mathbf{X}_i that minimizes $\Lambda_{\mathbf{X}_i}$ (as long as $\Lambda_{\mathbf{X}_i} < \Lambda_{\alpha,p,1,n-2}$ - stop otherwise)

(Step $j + 1, j = 1, 2, \dots$)

Let $\mathbf{X}_1, \dots, \mathbf{X}_j$ be the variables added in previous steps. Calculate

$$\Lambda_{\mathbf{X}_i|\mathbf{X}_1, \dots, \mathbf{X}_j} \sim \Lambda_{p, 1, n-j-1}$$

for all \mathbf{X}_i among the $q - j$ remaining candidate variables. For the \mathbf{X}_i that minimizes $\Lambda_{\mathbf{X}_i|\mathbf{X}_1, \dots, \mathbf{X}_j}$:

- add \mathbf{X}_i if $\Lambda_{\mathbf{X}_i|\mathbf{X}_1, \dots, \mathbf{X}_j} < \Lambda_{\alpha, p, 1, n-j-1}$
- stop the procedure if $\Lambda_{\mathbf{X}_i|\mathbf{X}_1, \dots, \mathbf{X}_j} > \Lambda_{\alpha, p, 1, n-j-1}$

Backward Elimination

Start with all \mathbf{X} 's and delete one at a time until the least valuable remaining \mathbf{X} is significant. For the m remaining \mathbf{X} 's after a given step, find the \mathbf{X}_i maximizing

$$\Lambda_{\mathbf{X}_i | \mathbf{x}_1, \dots, \mathbf{x}_{i-1}, \mathbf{x}_{i+1}, \dots, \mathbf{x}_m} \sim \Lambda_{p, 1, n-m-1}$$

- drop \mathbf{X}_i if $\Lambda_{\mathbf{X}_i | \mathbf{x}_1, \dots, \mathbf{x}_{i-1}, \mathbf{x}_{i+1}, \dots, \mathbf{x}_m} > \Lambda_{\alpha, p, 1, n-m-1}$
- stop the procedure if \mathbf{X}_i if $\Lambda_{\mathbf{X}_i | \mathbf{x}_1, \dots, \mathbf{x}_{i-1}, \mathbf{x}_{i+1}, \dots, \mathbf{x}_m} < \Lambda_{\alpha, p, 1, n-m-1}$

Stepwise

- Add most significant candidate \mathbf{X}_i if partial Λ is less than critical value
- Then, remove least significant selected \mathbf{X}_i if partial Λ is greater than critical value

Best Subsets

- Choose "best" subset of size ℓ , for $\ell = 1, \dots, q$, with respect to some criterion (e.g., a multivariate extension of Mallows's C_p , or $\text{tr}\{\mathbf{S}\}$, etc.)