STAT 154: Homework 7 solution

Release date: Sunday, April 21

Due by: 11 PM, Friday, May 10

The honor code

(a)	Please state the names of people who you worked with for this homework. You can also provide your comments about the homework here.
(b)	Please type/write the following sentences yourself and sign at the end. We want to make it extra clear that nobody cheats even unintentionally.
	I hereby state that all of my solutions were entirely in my words and were written by me. I have not looked at another students solutions and I have fairly credited all external sources in this write up.

Submission instructions

- It is a good idea to revisit your notes, slides and reading; and synthesize their main points BEFORE doing the homework.
- You need to submit the following:
 - 1. A pdf of your write-up to "HW7 write-up".
 - 2. No separate code submission is required for this HW.
- Although, we have provided an extra week, we recommend you to finish the homework in two weeks so as to have enough time for revision.

Homework Overview

This homework covers support vector machines (SVM), logistic regression and decision trees.

1 True or False (8 pts)

State whether the given statements are True or False and provide a brief justification.

1. Logistic regression assumes that each class's points are generated from a Gaussian distribution.

Ans. False. Logistic regression puts no assumptions on how the data points are generated

2. Logistic regression cannot be kernelized.

Ans. False. See lab discussions.

3. Logistic Regression can be used for regression (when the response y take continuous value in \mathbb{R}).

Ans. False. The Bernoulli distribution can not handle continuous output.

- 4. Hard-margin SVM still return a classifier if the training data is not linearly separable.

 Ans. False. The optimization problem is no longer feasible if the training data is not linearly separable.
- 5. In hard-margin SVM, support vectors are the only data points necessary to compute the fit $f(x) = w^{T}x + b$.

Ans. True. In any constrained optimization, the constraints that are not satisfied are not necessary to compute the final solution.

6. In a soft-margin support vector machine, if we increase C (same notation as in note $\mathbf{n20_svm.pdf}$), there will be more points inside the margin (i.e. between the two margin-defining hyperplanes).

Ans. False. There will be less points. In the regime, where C tends to infinity, we get the hard-margin SVM, which allows no point inside the margin.

7. As C approaches 0, the soft margin SVM solution approaches that of the hard margin SVM.

Ans. False.

8. Recall that in the usual formulation of soft-margin SVMs, each training sample has a slack variable $\xi_i \geq 0$ and we impose a regularization term $C \sum_{i=1}^n \xi_i$. Consider an alternative formulation where we impose the additional constraints $\xi_i = \xi_j$ for all $(i, j) \in \{1, \ldots, n\}^2$. The minimum objective value $||w||_2^2 + C \sum_{i=1}^n \xi_i$ of the new formulation will be smaller than that of the original soft-margin SVM.

Ans. False. Since we have more constraints, the optimal solution will be a feasible solution in the original soft-margin SVM. As a consequence, the minimum objective value is equal or larger.

2 SVM on simple data (6 pts)

We would like to understand how SVM works on a trivial dataset of four data points in \mathbb{R}^2 :

$$x_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix},$$
 $x_2 = \begin{bmatrix} 1 \\ 5 \end{bmatrix},$ $x_3 = \begin{bmatrix} 5 \\ 1 \end{bmatrix},$ $x_4 = \begin{bmatrix} 5 \\ 5 \end{bmatrix}$
 $y_1 = -1,$ $y_2 = 1,$ $y_3 = 1,$ $y_4 = 1$

Recall from the lecture that in SVM, we want find a maximal-margin separating hyperplane of the form

$$f(x) = x^{\top} w + b$$

 $1.\ (1\ \mathrm{pt})$ Use pen and paper to draw the location of the maximal margin separating hyperplane for the given dataset and its two margin-defining hyperplanes.

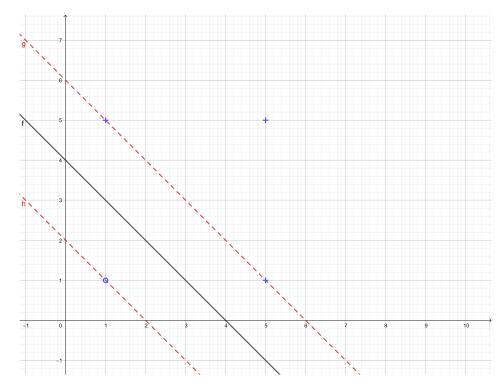


Figure 1: Figure for 5.1

2. (1 pt) By visual examination, guess the coordinates of the weight vector w (up to a constant).

Ans. $(1,1)^{\top}$ up to constant factor (previous solution had a mistake here).

3. (2 pts) Next, find the length of the normal $||w||_2$, such that would assure that the closest training points are located at the margin-defining hyperplanes ± 1 . For this, note

that the distance between those two margin-defining hyperplanes is equal to $d = 2/\|w\|_2$.

Ans. By visual inspection, the distance between the two margin-defining hyperplanes is $2\sqrt{2}$. Thus we should take $\|w\|_2 = \frac{1}{\sqrt{2}}$. With the direction from previous question, we have $w = (\frac{1}{2}, \frac{1}{2})^{\top}$.

4. (2 pts) Rescale the w you guessed in Step 2 to have length you computed in Step 3 and then compute the corresponding intercept b by using the fact that $f(x_1) = -1$.

Ans. $w = (\frac{1}{2}, \frac{1}{2})^{\mathsf{T}}$. Plugging in $f(x_1) = -1$, we have

$$\begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix}^\top \begin{bmatrix} 1 \\ 1 \end{bmatrix} + b = -1.$$

Thus b = -2. And thus the equation of the solid line is

$$x_1 + x_2 - 4 = 0.$$

And once again, it can be computed directly from the graph.

3 Perceptron and Pegasos (17 pts)

Given a **convex** function $f: \mathbb{R}^d \to \mathbb{R}$, a vector $g_w \in \mathbb{R}^d$ is said to be the subgradient of f at w, if

$$f(z) \ge f(w) + g_w^{\top}(z - w)$$
 for all $z \in \mathbb{R}^d$. (1)

When the function is differentiable at w, the sub-gradient g_w is unique and is equal to the gradient, i.e., $g_w = \nabla_w f(w)$. In simple words, sub-gradient is a generalized gradient (to do math with non-differentiable functions). There could be 0, 1, or infinitely many subgradients at any point. The sub-differential of f at a point w is the set of all subgradients of f at w and is denoted by $\partial f(w)$, .¹

1. (2 pts) [Subgradients for point-wise maximum of functions] Suppose $f_1, \ldots, f_m : \mathbb{R}^d \to \mathbb{R}$ are convex functions, and

$$f(w) = \max_{i=1,\dots,m} f_i(w).$$

Let k be any index for which $f_k(w) = f(w)$, and choose $g_w \in \partial f_k(w)$. [We are using the fact that a convex function on \mathbb{R}^d has a non-empty sub-differential at all points.] Show using the definition (1) that g_w is a valid subgradient of f at w, i.e., $g_w \in \partial f(w)$.

Ans. Let k be an index of the function $f_k(w)$ that achieves the maximum at w. Since $g_w \in \partial f_k(w)$, we have

$$f_k(z) \ge f_k(w) + g_w^{\top}(z-w)$$
 for all $z \in \mathbb{R}^d$.

¹In case you are more curious, see https://stanford.edu/class/ee364b/lectures/subgradients_notes.pdf by Boyd *et al.* for more details.

Since $f(z) \ge f_k(z)$ and $f(w) = f_k(w)$, we conclude that

$$f(z) \ge f(w) + g_w^{\top}(z - w)$$
 for all $z \in \mathbb{R}^d$.

This, by definition, means that g_w is a valid subgradient of f at w.

2. (2 pts) [Subgradient of hinge loss for linear prediction] Find a subgradient g_w of the function $f: \mathbb{R}^d \to \mathbb{R}$ where

$$f(w) = \max\left\{0, 1 - yw^{\top}x\right\},\,$$

with $x \in \mathbb{R}^d$ and $y \in \{-1, 1\}$ as fixed.

Ans. f is the maximum of two functions $f_1: w \mapsto 0$ and $f_2: w \mapsto 1 - yw^{\top}x$. Both functions are convex and differentiable, with

$$\nabla f_1(w) = 0$$
 and $\nabla f_2(w) = -yx$.

According to result from the previous question, the subgradient of f will depend on which function achieves the maximum. Hence, one subgradient is

$$g_w = \begin{cases} 0, & \text{if } 0 \ge 1 - yw^\top x. \\ -yx, & \text{otherwise.} \end{cases}$$

We now work on deriving the perceptron algorithm, which is one of the first classification algorithms in machine learning. Suppose we have a labeled training set $\{(x_i, y_i) \in \mathbb{R}^d \times \{-1, 1\}\}_{i=1}^n$. In the perceptron algorithm, we are looking for a hyperplane that perfectly separates the two classes, i.e., we try to find a vector $w \in \mathbb{R}^d$ and an intercept $b \in \mathbb{R}$ such that

$$w^{\top}x + b \begin{cases} > 0 & \text{if } y_i = 1 \\ < 0 & \text{if } y_i = -1 \end{cases} \iff y_i(w^{\top}x + b) > 0 \quad \forall i \in \{1, \dots, n\}$$
 (2)

For simplicity, in the following questions, we are leaving off the intercept term b.² Visually, all the data points with label y = 1 will lie on one side of the hyperplance and all the data points with label y = -1 will lie on the other side. When such a hyperplane exists, we say that the data are linearly separable. The perceptron algorithm is described in Algorithm 1

Give an estimator \hat{y} for a label y, we define the **perceptron loss** as

$$\ell(\hat{y}, y) = \max\left\{0, -\hat{y}y\right\}. \tag{3}$$

Equivalently, we can assume that our feature vectors $\widetilde{x} = [x^{\top}, 1]^{\top} \in \mathbb{R}^{d+1}$ have a constant term 1 and we are looking to optimize over $\widetilde{w}^{\top} = [w^{\top}, b]^{\top} \in \mathbb{R}^{d+1}$ such that $y_i(\widetilde{w}^{\top}\widetilde{x}) > 0$.

Algorithm 1: Perceptron Algorithm

```
Input: Training set (x_1, y_1), \ldots, (x_n, y_n) \in \mathbb{R}^d \times \{-1, 1\}

Initialize w^{(0)}, k = 0;

while allCorrect == FALSE do

allCorrect = TRUE;

// Loop over all data points

for i = 1, 2, \ldots, n do

if y_i x_i^\top w^{(k)} \leq 0 then

w^{(k+1)} = w^{(k)} + y_i x_i;

allCorrect = FALSE

else

w^{(k+1)} = w^{(k)}

end

w^{(k+1)} = w^{(k)}

end

output: w^{(k)}
```

3. (2 pts) Discuss why the perceptron loss (3) is meaningful and would capture mismatch between \hat{y} and y. Define the average perceptron loss of w on the training set $\mathcal{D} = \{(x_1, y_1), ..., (x_n, y_n)\}$, as

$$\mathcal{L}(w; \mathcal{D}) = \frac{1}{n} \sum_{i=1}^{n} \ell(x_i^{\top} w, y_i).$$

Show that if $\{x|\widehat{w}^{\top}x=0\}$ is a separating hyperplane (2) for the training set \mathcal{D} then the average perceptron loss $\mathcal{L}(\widehat{w};\mathcal{D})$ is 0. In other words, any separating hyperplane of \mathcal{D} minimizes the average perceptron loss on the training set.

Ans. A classfier based on the sign of \hat{y} is correct if the predicted response \hat{y} to have the same sign as y. The Perceptron loss is zero if if \hat{y} and y have the same sign and is non-zero otherwise. A classifier with perceptron loss zero will also achieve zero classification error.

By definition, a separting hyperplance correctly classifies all training data points. This means that \hat{y}_i and y_i always have the same sign. Thus the perceptron loss is zero.

4. (4 pts) Consider running stochastic subgradient descent (SSGD, subgradient descent on the loss for one data point at a time) to minimize the average perceptron loss. Show that the perceptron algorithm is doing exactly SSGD with a constant step size 1. We terminate when our training data are separated, we cycle through the data points one by one and we make the right choice of subgradient.

Hint: If g_k is the subgradient to be used at k-th step, then the update looks like

$$w^{(k+1)} = w^{(k)} - \alpha g_k,$$

where α is the step-size. To derive the sub-gradient, use results from questions 2.1 and 2.2.

Ans. We first derive the subgradient for the perceptron loss for one data point

$$f_i = \ell(x_i^\top w, y_i) = \max\left\{0, -yx_i^\top w\right\}.$$

Applying the same reasoning we used in question 2.1, we obtain a subgradient of f_i

$$g_{i,w} = \begin{cases} -yx_i, & \text{if } -yx_i^\top w \le 0\\ 0, & \text{otherwise} \end{cases}$$

We observe that the if-else in Algorithm 1 is exactly following the two cases in the subgradient calculation. The for-loop does subgradient descent on the loss for one data point at a time. The *allCorrect* variable ensures that the algorithm terminates when all data points are correctly classified.

5. (2 pts) Suppose the perceptron algorithm returns \widehat{w} . Show that w is a linear combination of the input points, i.e., we can write $\widehat{w} = \sum_{i=1}^{n} \alpha_i x_i$ for some $\alpha \in \mathbb{R}^n$.

Ans. The perceptron algorithm in each step either adds $y_i x_i$ (for some i) to the weight w or does nothing. Thus we can conclude that the final weight is of the form

$$\hat{w} = \sum_{i=1}^{n} \alpha_i x_i.$$

Next, we try to solve SVM using the Pegasos algorithm (Pegasos: Primal Estimated sub-GrAdient SOlver for SVM). To be consistent with the paper, we consider the following ℓ_2 -regularized formulation of the SVM objective

$$\min_{w \in \mathbb{R}^d} \mathcal{J}(w) \quad \text{where } \mathcal{J}(w) = \frac{\lambda}{2} \|w\|_2^2 + \frac{1}{n} \sum_{i=1}^n \max \left\{ 0, 1 - y_i w^\top x_i \right\}.$$

Again the intercept term is left out for simplicity. The Pegasos algorithm works as follows.

Algorithm 2: Pegasos Algorithm for SVM

```
Input: Training set (x_1, y_1), \ldots, (x_n, y_n) \in \mathbb{R}^d \times \{-1, 1\}

Initialize w^{(0)}, k = 0;

while not converged do

// Loop over all data points

for i = 1, 2, \ldots, n do

k = k + 1;

\eta = 1/(k\lambda);

if y_i x_i^{\top} w^{(k)} < 1 then

w^{(k+1)} = (1 - \eta\lambda)w^{(k)} + \eta y_i x_i;

else

w^{(k+1)} = (1 - \eta\lambda)w^{(k)}

end

end

Output: w^{(k)}
```

6. (2 pts) Note that $\mathcal{J}(w) = \frac{1}{n} \sum_{i=1}^{n} J_i(w)$ where $J_i(w)$ denotes the SVM objective on a single data point:

$$J_i(w) = \frac{\lambda}{2} \|w\|_2^2 + \max \{0, 1 - y_i w^\top x_i\}.$$

Using the fact that J_i is a maximum of two convex functions, show that a subgradient of J_i with respect to w is given by

$$g_w = \begin{cases} \lambda w - y_i x_i & \text{for } y_i w^\top x_i < 1\\ \lambda w & \text{for } y_i w^\top x_i \ge 1. \end{cases}$$

Hint: Use results from questions 2.1 and 2.2.

Ans. We apply the same reasoning we used in question 2.1. $J_i(w)$ is the maximum of two functions $f_1(w) = \frac{\lambda}{2} \|w\|_2^2$ and $f_2(w) = \frac{\lambda}{2} \|w\|_2^2 + 1 - y_i w^\top x_i$. Both functions are convex and differentiable,

$$\nabla f_1(w) = \lambda w$$
 and $\nabla f_2(w) = \lambda w - y_i x_i$.

We conclude using the fact the subgradient of the subfunction that achieves the maximum is also a subgradient of the function J_i .

7. (3 pts) Explain why the Pegasus algorithm is just stochastic subgradient descent (SSGD) on the regularized SVM loss \mathcal{J} with decreasing step-size $\eta = 1/(k\lambda)$.

Hint: Use the hints from 2.4.

Ans. The subgradient update for *i*-th data point with step-size η is as follows,

$$w \leftarrow w - \eta q_{i,w}$$
.

Plugging in the subgradient from 2.6, we obtain

$$w \leftarrow \begin{cases} w - \eta \left(\lambda w - y_i x_i \right) & \text{if } 1 - y_i w^\top x_i > 0 \\ w - \eta \cdot \lambda w. \end{cases}$$

Simplying the update equation, we get exactly the updates in the Pegasos algorithm.

4 Logistic Regression (10 pts)

We now work through some key steps for the IRWLS algorithm used for solving logistic regression. Given a dataset $\mathcal{D} = \{(x_i, y_i) \in \mathbb{R}^d \times \{0, 1\}\}_{i=1}^n$, (2-class) logistic regression maximizes the conditional probability of the labels $\mathbb{P}(y_1, \ldots, y_n | x_1, \ldots, x_n; \beta)$ assuming that (a) the data points are independent and that (b) for one data point, the conditional probability takes the form:

$$\mathbb{P}(Y_i = y_i | x_i; \beta) = \frac{e^{y_i \beta^\top x_i}}{1 + e^{\beta^\top x_i}}, \quad \text{for } y_i \in \{0, 1\}.$$
 (4)

1. (3 pts) Derive the expression for the logistic loss as a function of β , which is defined as the negative conditional log-likelihood of the data:

$$\mathcal{L}(\beta) = -\log \mathbb{P}(y_1, \dots, y_n | x_1, \dots, x_n; \beta)$$

Also derive the expression for its gradient $\nabla_{\beta} \mathcal{L}(\beta)$ and the Hessian $\nabla_{\beta}^2 \mathcal{L}(\beta)$. You may use the shorthand notation $p_i = \mathbb{P}(y_i = 1 | x_i; \beta)$.

Ans. Using the fact that data is i.i.d. generated and the conditional likelihood for one data point in equation (4), we have the negative conditional log-likelihood for all data points,

$$\mathcal{L}(\beta) = -\log \mathbb{P}(y_1, \dots, y_n | x_1, \dots, x_n; \beta)$$

$$= -\sum_{i=1}^n \log \mathbb{P}(Y_i = y_i | x_i; \beta)$$

$$= -\log \left(\frac{e^{y_i \beta^\top x_i}}{1 + e^{\beta^\top x_i}}\right), \quad \text{for } y_i \in \{0, 1\}$$

$$= -y_i \beta^\top x_i + \log \left(1 + e^{\beta^\top x_i}\right).$$

The gradient is

$$\nabla_{\beta} \mathcal{L}(\beta) = \sum_{i=1}^{n} -y_i x_i + \frac{e^{\beta^{\top} x_i}}{1 + e^{\beta^{\top} x_i}} x_i.$$

Let $f(t) = \frac{e^t}{1+e^t} = 1 - \frac{1}{1+e^t}$. We have

$$f'(t) = \frac{e^t}{(1 + e^t)^2}.$$

Hence for the Hessian, we have

$$\nabla_{\beta}^{2} \mathcal{L}(\beta) = \sum_{i=1}^{n} \frac{e^{\beta^{\top} x_{i}}}{(1 + e^{\beta^{\top} x_{i}})^{2}} x_{i} x_{i}^{\top} = \sum_{i=1}^{n} p_{i} (1 - p_{i}) x_{i} x_{i}^{\top}.$$

We can see this as the weighted version of the covariance matrix.

$$\nabla_{\beta}^2 \mathcal{L}(\beta) = \mathbf{X}^{\top} \mathbf{W} \mathbf{X},$$

where $\mathbf{X} = \begin{bmatrix} x_1^\top \\ \vdots \\ x_n^\top \end{bmatrix}$ is the design matrix and the diagonal weight matrix $\mathbf{W} =$

diag $(p_1(1-p_1), \dots, p_n(1-p_n))$. Using this matrix notation, the gradient can be writen as

$$\nabla_{\beta} \mathcal{L}(\beta) = \mathbf{X}^{\top} (\mathbf{p} - \mathbf{y}),$$

where
$$\mathbf{p} = \begin{bmatrix} p_1 \\ \vdots \\ p_n \end{bmatrix}$$
 and $\mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$.

2. (2 pts) Show that the logistic loss $\beta \to \mathcal{L}(\beta)$ is convex.

Hint: You may have to simply show some property for the Hessian.

Ans. Since W has nonnegative diagonal values, the hessian matrix $\nabla^2_{\beta} \mathcal{L}(\beta) = \mathbf{X}^{\top} \mathbf{W} \mathbf{X}$ is a positive-semidefinite matrix. Thus the loss is convex.

3. (3 pts) Newton's method is effective for minimizing a convex function or maximizing a concave function. Given an iterate β , derive the Newton's updates for the logistic loss. Use the vector matrix notation:

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}_{1}^{\top} \\ \mathbf{x}_{2}^{\top} \\ \vdots \\ \mathbf{x}_{n}^{\top} \end{bmatrix} \in \mathbb{R}^{n \times d}, \quad \mathbf{y} = \begin{bmatrix} y_{1} \\ y_{2} \\ \vdots \\ y_{n} \end{bmatrix} \in \{0, 1\}^{n}, \quad \mathbf{p} = \begin{bmatrix} p_{1} \\ p_{2} \\ \vdots \\ p_{n} \end{bmatrix} \in [0, 1]^{n},$$

$$\mathbf{W} = \begin{bmatrix} p_{1}(1 - p_{1}) & & & \\ & p_{2}(1 - p_{2}) & & \\ & & \ddots & \\ & & & p_{n}(1 - p_{n}) \end{bmatrix} \in \mathbb{R}^{n \times n}.$$

where $p_i = \mathbb{P}(y_i = 1|x_i; \beta)$.

Ans. The Newton's method updates the weight iteratively with the equation

$$\beta \leftarrow \beta - \eta \left(\nabla_{\beta}^2 \mathcal{L}(\beta) \right)^{-1} \nabla_{\beta} \mathcal{L}(\beta),$$

where η is the step-size. Plugging the gradient and hessian expression from previous question, we obtain the update equation.

$$\beta \leftarrow \beta + \eta \left(\mathbf{X}^{\top} \mathbf{W} \mathbf{X} \right)^{-1} \mathbf{X}^{\top} \left(\mathbf{y} - \mathbf{p} \right),$$

4. (2 pts) Justify why this method is called iteratively re-weighted least squares (IRWLS/IRLS) for short.

Ans. We define the weighted design matrix $\tilde{\mathbf{X}}$ and the weighted response $\tilde{\mathbf{y}}$ as follows,

$$\tilde{\mathbf{X}} = \sqrt{\mathbf{W}}\mathbf{X}$$
 and $\tilde{\mathbf{y}} = \sqrt{\mathbf{W}}^{-1}\left(\mathbf{y} - \mathbf{p}\right)$.

The Newton updates become

$$\beta \leftarrow \beta + \eta \left(\tilde{\mathbf{X}}^{\top} \tilde{\mathbf{X}} \right)^{-1} \tilde{\mathbf{X}}^{\top} \tilde{\mathbf{y}}.$$

The expression $(\tilde{\mathbf{X}}^{\top}\tilde{\mathbf{X}})^{-1}\tilde{\mathbf{X}}^{\top}\tilde{\mathbf{y}}$ is the solution of the least squares problem

$$\min_{\beta} \left\| \tilde{\mathbf{X}} \beta - \tilde{\mathbf{y}} \right\|_{2}^{2}.$$

Thus the Newton's method on the negative log-likelihood of the logistic regression can be seen as updating the β iteratively with the solution of a weighted least squares problem.

5 Decision Trees and Ada-boost (9 pts)

1. (3 pts) ISL Book: Problem 8.1 (Page 332)

Ans. Like Figures 8.1 and 8.2, we have a decision tree with 6 regions.

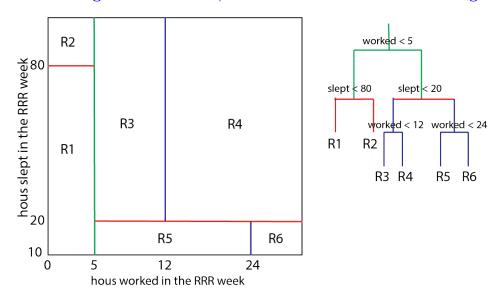


Figure 2: Figure for 5.1

2. (2 pts) ISL Book: Problem 8.2 (Page 332)

Ans. By definition of the Boosting algorithm (Algorithm 8.2), the result

from Boosting is always a sum of base learners. The only thing we need to explain is that why each base learner here only depneds on one feature X_j . This is because we are using depth-one trees (or stumps) as base learners. The single split in the depth-one tree only depends on one feature X_j . Hence after combining the functions depending on the same feature, the final output can be written as the following additive model

$$\sum_{j=1}^{p} f_j(X_j).$$

3. (2 pts) ESL Book: Problem 10.1 (Page 384)

Ans. According to equation (10.13), the minimized weighted error rate err_m is defined as

$$\mathbf{err}_{m} = \frac{\sum_{i=1}^{N} w_{i}^{(m)I(y_{i} \neq G_{m}(x_{i}))}}{\sum_{i=1}^{N} w_{i}^{(m)}}.$$

Taking derivative of equation (10.11) with respect to β , we obtain

$$\left(e^{\beta} + e^{-\beta}\right) \cdot \sum_{i=1}^{N} w_i^{(m)} I(y_i \neq G(x_i)) - e^{-\beta} \cdot \sum_{i=1}^{N} w_i^{(m)} = 0.$$

Dividing both sides by $e^{-\beta} \cdot \sum_{i=1}^{N} w_i^{(m)}$, we obtain

$$\left(e^{2\beta} + 1\right)\mathbf{err}_m - 1 = 0.$$

We solve for the optimal β and obtain

$$\beta_m = \frac{1}{2} \log \frac{1 - \mathbf{err}_m}{\mathbf{err}_m}.$$

4. (2 pts) ESL Book: Problem 10.2 (Page 384)

Ans.

$$\mathbb{E}_{Y|x} \left(e^{-Yf(x)} \right) = e^{-f(x)} \cdot \Pr(Y = 1 \mid x) + e^{f(x)} \cdot \Pr(Y = -1 \mid x).$$

Since the minimization over f allows any function f, we can simply consider the minimum of the following function

$$g: \mathbb{R} \to \mathbb{R}$$

 $t \mapsto e^{-t} \cdot \Pr(Y = 1|x) + e^{t} \cdot \Pr(Y = -1|x).$

Taking derivative of g, we have

$$g'(t) = -e^{-t} \cdot \Pr(Y = 1 \mid x) + e^{t} \cdot \Pr(Y = -1 \mid x)$$

Observe that g''(t) is nonnegative, the minimum is taken by solving g'(t)=0. Hence

$$f^*(x) = t^* = \frac{1}{2} \log \frac{\Pr(Y = 1 \mid x)}{\Pr(Y = -1 \mid x)}.$$