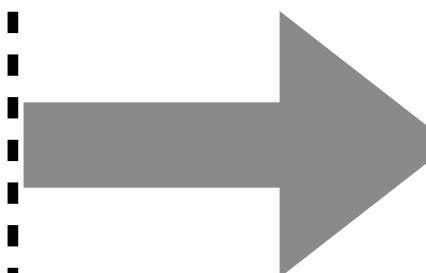




Y

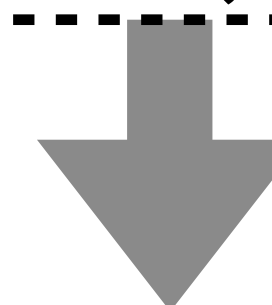
Store <x, orientation>

learning phase



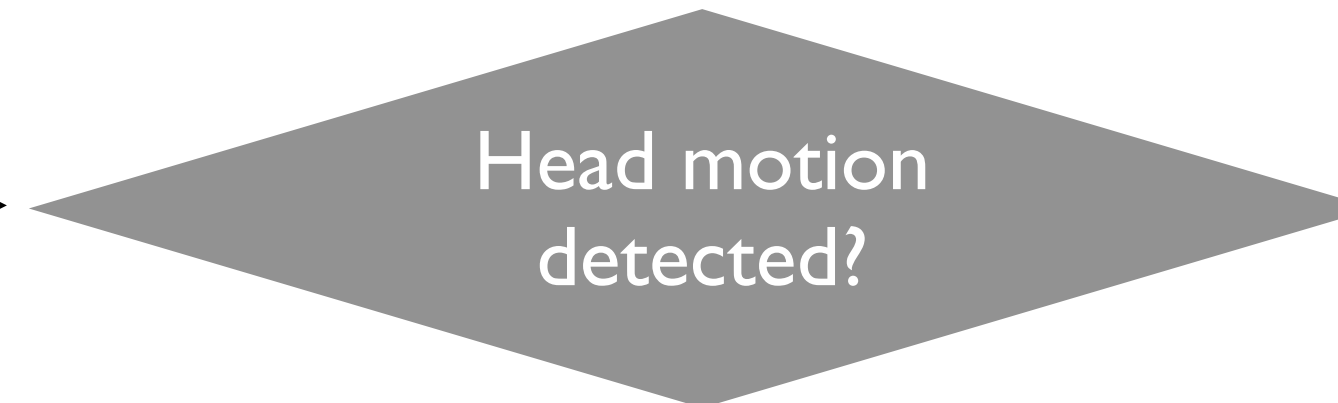
<1, orientation>
<2, orientation>
...

adjacency map



Y

y is the current selection
orientation(y) as reference point



Y

z is the next target
predicted using adjacency map

use z as y

prediction & update phase