Non-linear Dimensionality Reduction

t-Distributed Stochastic Neighbor Embedding

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Dimensionality Reduction

Dimensionality Reduction

Definition of dimensionality reduction:

Given a set of data $X = [\mathbf{x}_1, \dots, \mathbf{x}_m]$, $\mathbf{x}_i \in \mathbb{R}^n$, find a map $f : \mathbb{R}^n \to \mathbb{R}^d$, make $\mathbf{y}_i = f(\mathbf{x}_i)$ and $d \ll n$. Where $f = (f_1, \dots, f_n)$, $f_i : \mathbb{R}^n \to \mathbb{R}$

Linear Dimensionality Reduction

If
$$f_i$$
 is a linear map, $f = P = [\mathbf{p}_1, \dots, \mathbf{p}_n], \mathbf{y}_i = P^T \mathbf{x}_i$

Dimensionality reduction: Some Assumptions

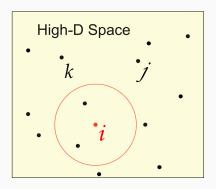
- 1. High-dimensional data often lies on or near a much lower dimensional, curved manifold
- 2. A good way to represent data points is by their low-dimensional coordinates.
- 3. The low-dimensional representation of the data should capture information about high-dimensional pairwise distances.

Dimensionality Reduction

- Linear Dimensionality Reduction: PCA(Principal Components Analysis), LDA(Linear Discriminant Analysis), MDS(Classical Multidimensional Scaling)
- None-Linear Dimensionality Reduction: Isomap(Isometric Mapping), LLE(Locally Linear Embedding), LE(Laplacian Eigenmaps), tSNE(t-Distributed Stochastic Neighbor Embedding)

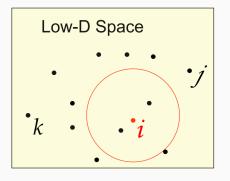
Define the similarity of data point \mathbf{x}_i in original space as conditional probability $p_{j|i}$. It is the probability that \mathbf{x}_i would pick \mathbf{x}_j as its neighbor under a Gaussian centered at \mathbf{x}_i

$$p_{j|i} = \frac{\exp(-\|\mathbf{x}_i - \mathbf{x}_j\|^2 / 2\sigma_i^2)}{\sum_{k \neq i} \exp(-\|\mathbf{x}_i - \mathbf{x}_k\|^2 / 2\sigma_i^2)}$$



In low-dimensional space, define the similarity $q_{j\mid i}$

$$q_{j|i} = \frac{\exp\left(-\|\mathbf{y}_i - \mathbf{y}_j\|^2\right)}{\sum_{k \neq i} \exp\left(-\|\mathbf{y}_i - \mathbf{y}_k\|^2\right)}$$



Cost function of SNE

If the map points \mathbf{y}_i and \mathbf{y}_j correctly model the similarity between the high-diminsional datapoints \mathbf{x}_i and \mathbf{x}_j , the conditional probability $p_{j|i}$ and $q_{j|i}$ will be equal. Use the Kullback-Leibler divergences to minimize the mismatch:

$$Cost = \sum_{i} KL(P_i||Q_i) = \sum_{i} \sum_{j} p_{j|i} \log \frac{p_{j|i}}{q_{j|i}}$$

To minimize the cost function using gradient descent:

$$\frac{\partial \textit{Cost}}{\partial \mathbf{y}_i} = 2\sum_{j} (p_{j|i} - q_{j|i} + p_{i|j} - q_{i|j})(\mathbf{y}_i - \mathbf{y}_j)$$

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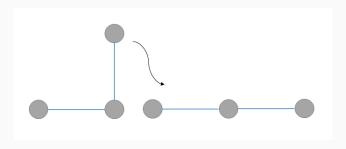
About the cost function:

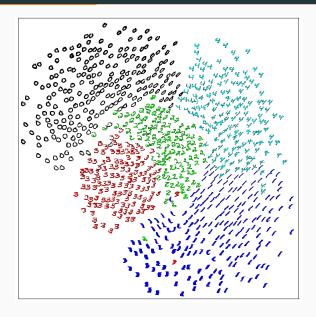
$$Cost = \sum_{i} KL(P_i||Q_i) = \sum_{i} \sum_{j} p_{j|i} \log \frac{p_{j|i}}{q_{j|i}}$$

- Large $p_{i|i}$ modeled by small $q_{i|i}$, Big penalty!
- Small $p_{i|i}$ modeled by large $q_{i|i}$, Small penalty !
- It is asymmetric and mainly preserves local similarity structure of data!

The "Crowding" problem

- Try to model the local structure of data in the map!
- Dissimilar points have to be modeled as too far apart in the map!
- SNE does not have gaps between classes!





t-Distributed Stochastic

Neighbor Embedding

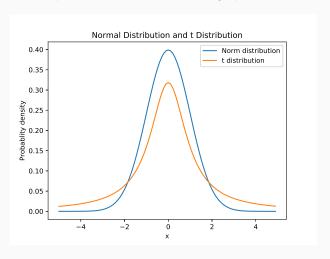
Symmetric SNE by using joint probability distribution instead of conditional probability distribution.

$$p_{ij} = \frac{p_{i|j} + p_{j|i}}{2m}$$

Cost function becomes:

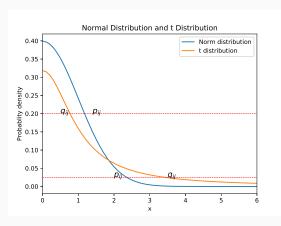
$$Cost = KL(P||Q) = \sum_{i} \sum_{j} p_{ji} \log \frac{p_{ji}}{q_{ji}}$$

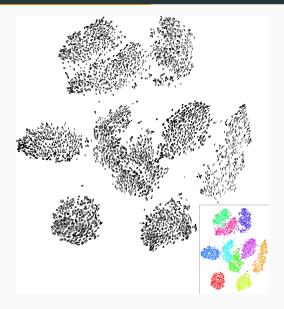
Use t distribution (Heavy-tailed distribution) to model similarity in low-dimensional space to release the "Crowding" problem



The joint probabilities q_{ij} are defined as

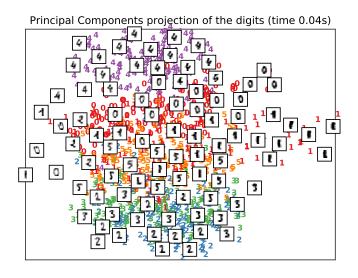
$$q_{ij} = \frac{(1 + \|\mathbf{y}_i - \mathbf{y}_j\|^2)^{-1}}{\sum_{k!=l} (1 + \|\mathbf{y}_k - \mathbf{y}_l\|^2)^{-1}}$$

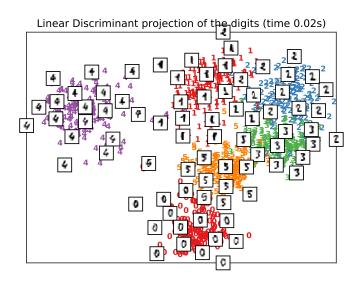


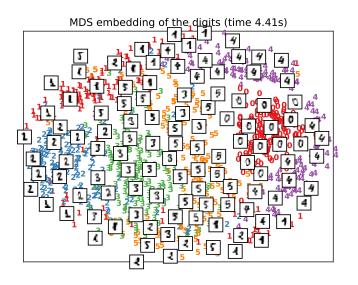


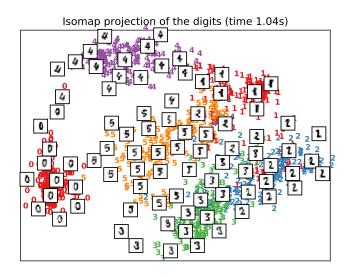
A selection from the 64-dimensional digits dataset

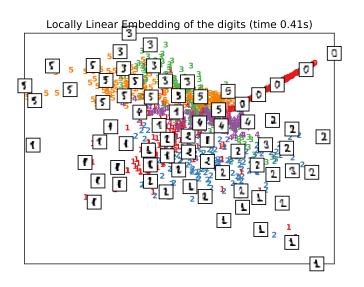


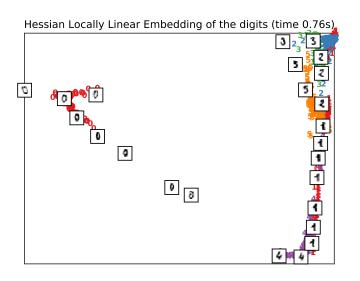


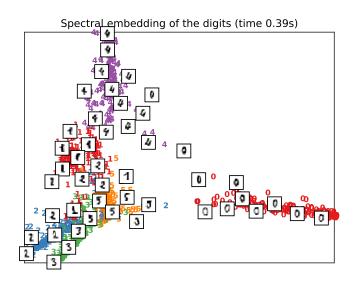


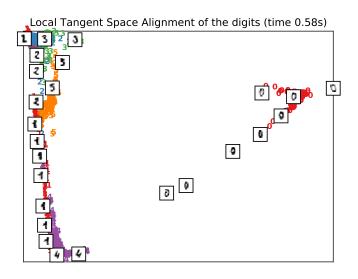


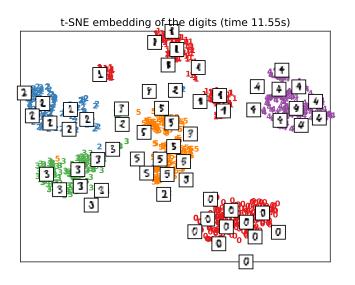












Demo

Demo

Hero images visualization:

https://onefoldmedia.com/sites/default/super_t-sne

Resource

Resource

- Stochastic Neighbor Embedding
- isualizing Data using t-SNE
- Local Linear Embedding
- scikit-learn

Thanks!

Thank you!