ESE 605 Homework 4

Xi Cao

Problems from Boyd & Vandenberghe: 5.13.

(a) The Lagrange dual is:

$$L(x, \nu, \lambda) = c^T x + \sum_i \nu_i x_i (1 - x_i) + \lambda^T (Ax - b)$$
$$= -x^T \operatorname{diag}(\nu) x + (c + \nu + A^T \lambda)^T x - \lambda^T b$$

To find the lower boundary of L, set:

$$\frac{\partial L}{\partial x} = -2\operatorname{diag}(\nu)^T x + (c + \nu + A^T \lambda) = 0$$
$$x = \frac{c + \nu + A^T \lambda}{2\operatorname{diag}(\nu)}$$

The dual function is:

$$\begin{split} g(\nu,\lambda) &= \inf_{x} L(x,\nu,\lambda) \\ &= \begin{cases} \frac{(c+\nu+A^T\lambda)^2}{4\mathrm{diag}(\nu)} - \lambda^T b & \nu \leq 0 \\ -\infty & \text{otherwise} \end{cases} \end{split}$$

So the dual problem is:

maximize
$$\frac{(c+\nu+A^T\lambda)^2}{4\mathrm{diag}(\nu)} - \lambda^T b$$
 subject to: $\nu \leq 0$ $\lambda \geq 0$

We can also write this problem as:

maximize
$$1/4 \left(\sum_{i} (c_i + \nu_i + a_i^T \lambda)^2 / \nu_i \right) - \lambda^T b$$

subject to: $\nu \leq 0$
 $\lambda \succeq 0$

Look at $(c_i + \nu_i + a_i^T \lambda)^2 / \nu_i$. Since $(c_i + \nu_i + a_i^T \lambda)^2 \ge 0$ and $\nu_i \le 0$, $(c_i + \nu_i + a_i^T \lambda)^2 / \nu_i \le 0$. If $c_i + a_i^T \lambda \ge 0$, then we can find ν_i such that $c_i + \nu_i + a_i^T \lambda = 0$, its maximum is 0. Otherwise, it reaches its maximum when:

$$\frac{\partial}{\partial \nu_i} (c_i + \nu_i + a_i^T \lambda)^2 / \nu_i = 1 - (c_i + a_i^T \lambda)^2 / \nu_i = 0$$

$$\nu_i = (c_i + a_i^T \lambda)^2$$

$$\text{maximum} = 4(c_i + a_i^T \lambda)$$

Therefore the maximum value of the dual problem is:

$$\begin{cases} -\lambda^T b & c_i + a_i^T \lambda \ge 0 \\ c_i + a_i^T \lambda - \lambda^T b & c_i + a_i^T \lambda \le 0 \end{cases}$$

We can write the dual problem as:

maximize
$$-\lambda^T b + \sum_i \min\{0, c_i + a_i^T \lambda\}$$

subject to: $\lambda \succeq 0$

(b) First we want to derive the dual of the LP relaxation.

The Lagrange dual is:

$$L(x, \nu_1, \nu_2, \nu_3) = c^T x + \nu_1^T (Ax - b) + \nu_2^T (-x) + \nu_3^T (x - 1)$$

= $(c + A^T \nu_1 - \nu_2 + \nu_3)^T x + (-b^T \nu_1 - 1^T \nu_3)$

The dual function:

$$\begin{split} g(\nu_1, \nu_2, \nu_3) &= \inf_x L(x, \nu_1, \nu_2, \nu_3) \\ &= \begin{cases} -b^T \nu_1 - 1^T \nu_3 & c + A^T \nu_1 - \nu_2 + \nu_3 = 0 \\ -\infty & \text{otherwise} \end{cases} \end{split}$$

So the dual problem is:

maximize
$$-b^T \nu_1 - 1^T \nu_3$$

subject to: $c + A^T \nu_1 - \nu_2 + \nu_3 = 0$
 $\nu_1 \succeq 0, \ \nu_2 \succeq 0, \ \nu_3 \succeq 0$

If we set:

$$\nu_1 = \lambda$$

$$\nu_{3i} = -(c_i + a_i^T \lambda)$$

$$\nu_2 = 0$$

Then the dual problem of the LP relaxation will give us the same lower bound as the Lagrangian relaxation.

5.17.

We can write $\sup_{a \in \mathcal{P}_i} a^T x$ as a LP:

$$\begin{array}{ll}
\text{maximize} & a^T x \\
\text{subject to:} & C_i a \leq d_i
\end{array}$$

The Lagrange dual is:

$$L(x,\nu) = a^T x + \nu^T (C_i a - d_i)$$
$$= (x + C_i^T \nu)^T a - d_i^T \nu$$

And the dual function is:

$$g(\nu) = \inf_{a} L(x, \nu)$$

$$= \begin{cases} -d_i^T \nu & x + C_i^T \nu = 0 \\ -\infty & \text{otherwise} \end{cases}$$

So the dual problem is:

Without loss of generality, we can name the optimal solution $-z_i$, so that:

$$\sup_{a \in \mathcal{P}_i} a^T x = d_i^T z_i$$

$$C_i^T z_i = x$$

$$z_i \succ 0$$

Then the robust LP is equivalent to:

minimize
$$c^T x$$

subject to: $d_i^T z_i \leq b_i$
 $C_i^T z_i = x$
 $z_i \succeq 0$

5.21.

(a) We know that exponential functions are convex, so e^{-x} is a convex function. Also, since y > 0, x^2/y is convex over x. Since $x^2 \ge 0$, x^2/y is convex over y. We have verified this is a convex optimization problem.

Since e^{-x} is monotonically decreasing, minimize it is to maximize x. Also, the problem restricts $x^2/y \le 0$, and from domain restriction, $x^2/y \ge 0$, so $x^2/y = 0$ and x = 0. The optimal value is $e^0 = 1$.

(b) The Lagrange dual is:

$$L(x, y, \lambda) = e^{-x} + \lambda(x^2/y)$$

And the dual function is:

$$g(\lambda) = \inf_{x,y} L(x, y, \lambda)$$

To find the infimum of L,

$$L_x = -e^{-x} + 2\lambda x/y$$
$$L_y = -\lambda x^2/y^2$$

The above two equation cannot both be zero, so L has no extreme points.

If $\lambda < 0$, by setting x large enough and y small enough, the minimum of L can reach $-\infty$. If $\lambda \geq 0$, we know that $e^{-x} \geq 0$ and $\lambda(x^2/y) \geq 0$, so $L(x, y, \lambda) \geq 0$. Also $L(x, y, \lambda)$ can be zero when x goes to infinity and $\lambda = 0$.

So the dual problem is:

$$\begin{array}{ll} \underset{\lambda}{\text{maximize}} & 0 \\ \text{subject to:} & \lambda \succeq 0 \end{array}$$

The optimal value $d^* = 0$, and the optimal duality gap is 1.

- (c) From (a) we know the optimal solution of x is $x^* = 0$, then $x^2/y = 0$ and the constraint is not satisfied with strict inequalities. So Slater's condition does not hold for this problem.
- (d) When u = 0, from (a) we know $p^*(u) = 1$.

When u > 0, Slater's condition holds for this perturbed problem, so from (b) we know $p^*(u) = 0$.

When u < 0, the problem is infeasible, so $p^*(u) = \infty$.

The global sensitivity inequality does not hold when u > 0.

$$0 = p^*(u) < p^*(0) - \lambda^* u = 1 - 0 = 1$$

5.24.

We know that

$$\sup_{z \in Z} \left(\inf_{w \in W} f(w, z) \right) - \epsilon \le \inf_{w \in W} f(w, z^*)$$

for some $z^* \in Z$ and any $\epsilon > 0$. And the inequation holds even if Z is not feasible. Also,

$$\inf_{w \in W} f(w, z^*) \le \inf_{w \in W} \left(\sup_{z \in Z} f(w, z) \right)$$

From chain rule we have

$$\sup_{z \in Z} \left(\inf_{w \in W} f(w, z) \right) - \epsilon \le \inf_{w \in W} \left(\sup_{z \in Z} f(w, z) \right)$$

for any $\epsilon > 0$. Therefore,

$$\sup_{z \in Z} \inf_{w \in W} f(w, z) \le \inf_{w \in W} \sup_{z \in Z} f(w, z)$$

5.31.

Since f_0 is convex,

$$f_0(x) \ge f_0(x^*) + \nabla f_0(x^*)^T (x - x^*)$$

$$\nabla f_0(x^*)^T(x - x^*) = -\sum_{i=1}^m \lambda_i^* \nabla f_i(x^*) (x - x^*)$$

$$= -\sum_{i=1}^m \lambda_i^* f_i(x^*) - \sum_{i=1}^m \lambda_i^* \nabla f_i(x^*) (x - x^*)$$

$$= -\sum_{i=1}^m \lambda_i^* (f_i(x^*) + \nabla f_i(x^*) (x - x^*))$$

Since $f_i(x^*) \leq 0$, $f_i(x) \leq 0$, and f_i is convex,

$$f_i(x^*) + \nabla f_i(x^*)(x - x^*) \le f_i(x) \le 0$$

Therefore,

$$\nabla f_0 \left(x^* \right)^T \left(x - x^* \right) \ge 0$$

6.7.

(a)

$$\begin{split} f(x) &= \|Ax - b\|_2^2 + \delta \|x\|_2^2 \\ &= x^T A^T A X - 2 b^T A x + b^T b + \delta x^T x \\ &= x^T V \mathbf{diag}(\sigma)^T U^T U \mathbf{diag}(\sigma) V x - 2 U \mathbf{diag}(\sigma) V^T b x + b^T b + \delta x^T x \\ &= x^T \mathbf{diag}(\sigma)^T \mathbf{diag}(\sigma) x - 2 b^T U \mathbf{diag}(\sigma) V x + b^T b + \delta x^T x \\ &= \sum_{i=1}^r (\sigma_i^2 + \delta) x_i^2 - 2 \sigma_i u_i v_i^T b_i x_i + b_i^2 \end{split}$$

Take the derivatives,

$$\frac{\partial}{\partial x_i} f(x) = 2(\sigma_i^2 + \delta)x_i - 2b_i \sigma_i u_i v_i^T$$

So the solution is

$$x_i^* = \frac{\sigma_i u_i v_i^T b_i}{\sigma_i^2 + \delta}$$
$$x^* = \sum_{i=1}^r \frac{\sigma_i u_i v_i^T b_i}{\sigma_i^2 + \delta}$$

(b) First consider the unconstrained problem:

$$||Ax - b||_2^2 = \sum_{i=1}^r \sigma_i^2 x_i^2 - 2\sigma_i u_i v_i^T b_i x_i + b_i^2$$
$$x_i^* = \frac{u_i v_i^T b_i}{\sigma_i}$$

If $||x^*||_2^2 = \sum_{i=1}^r (\frac{u_i v_i^T b_i}{\sigma_i})^2 \le \gamma$, since rank $(A) = r < \min\{m, n\}$, we can find

$$||x^*||_2^2 = \sum_{i=1}^r \left(\frac{u_i v_i^T b_i}{\sigma_i}\right)^2 + \sum_{i=r+1}^n x_i^2 = r$$

So the solution is equal to the unconstrained solution:

$$x_i^* = \frac{u_i v_i^T b_i}{\sigma_i}$$

If $||x^*||_2^2 = \sum_{i=1}^r (\frac{u_i v_i^T b_i}{\sigma_i})^2 \ge \gamma$, the optimal solution is similar to the solution in (a):

$$\sum_{i=1}^{n} x_i^2 = \left(\frac{\sigma_i u_i v_i^T b_i}{\sigma_i^2 + \delta}\right)^2 = \gamma$$
$$x_i^* = \frac{\sigma_i u_i v_i^T b_i}{\sigma_i^2 + \delta}$$
$$x^* = \sum_{i=1}^{n} \frac{\sigma_i u_i v_i^T b_i}{\sigma_i^2 + \delta}$$

A6.19.

(a) The optimal objective value is 341.96.

```
import cvxpy as cp
rows, cols, colors = img.shape
given = np.array([R_given.T,G_given.T,B_given.T]).T

variables = []
constraints = []
for i in range(colors):
    U = cp.Variable(shape=(rows, cols))
    variables.append(U)
    constraints.append(U[known_ind] == given[:, :, i][known_ind])
    constraints.append(U<=1)
    constraints.append(U>=0)

constraints.append(0.299*variables[0]+0.587*variables[1]+0.114*variables[2] == M)

prob = cp.Problem(cp.Minimize(cp.tv(*variables)), constraints)
prob.solve(verbose=True, solver=cp.ECOS) #'ECOS', 'SCS', or 'OSQP'.
print("optimal objective value: {}".format(prob.value))
```

C→ optimal objective value: 341.96404500840214







A7.3.

(a) In this case,

$$a(\theta) = \left(\int_{\mathbf{R}_{+}^{n}} \exp\left(\theta^{T} x\right) dx \right)^{-1}$$
$$= \left(\frac{\exp\left(\theta^{T} x\right)}{\prod_{i=1}^{n} \theta_{i}} \Big|_{x=0}^{\infty} \right)^{-1}$$
$$= \begin{cases} \prod_{i=1}^{n} -\theta_{i} & \theta < 0\\ 0 & \text{otherwise} \end{cases}$$

For θ to be valid,

$$\theta < 0$$

$$a(\theta) = \prod_{i=1}^{n} -\theta_{i}$$

$$p_{\theta}(x) = \prod_{i=1}^{n} (-\theta_{i}) \exp(\theta^{T} x)$$

The associated family of densities is independent exponential distribution.

(b) In this case,

$$a(\theta) = (1 + \exp(\theta))^{-1} = \frac{1}{1 + \exp(\theta)}$$
$$p_{\theta}(0) = \frac{1}{1 + \exp(\theta)}$$
$$p_{\theta}(1) = \frac{\exp(\theta)}{1 + \exp(\theta)}$$

The associated family of densities is Bernoulli distribution. The valid value of θ is $\theta \in \mathbf{R}$.

(c) If $x \in \mathcal{N}(\mu, \Sigma)$, then it has the density function:

$$p(x) = \frac{1}{(2\pi)^{\frac{n}{2}}|\Sigma|^{-\frac{1}{2}}} e^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)}$$

$$= \frac{1}{(2\pi)^{\frac{n}{2}}|\Sigma|^{-\frac{1}{2}}} e^{(x^T \Sigma^{-1} \mu - \frac{1}{2} x^T \Sigma^{-1} x - \frac{1}{2} \mu^T \Sigma^{-1} \mu)}$$

$$= \frac{e^{-\frac{1}{2} \mu^T \Sigma^{-1} \mu}}{(2\pi)^{\frac{n}{2}}|\Sigma|^{-\frac{1}{2}}} e^{(x^T \Sigma^{-1} \mu - \frac{1}{2} x^T \Sigma^{-1} x)}$$

If we use parameter $(z, Y) = (\Sigma^{-1}\mu, \Sigma^{-1})$, then,

$$\theta^T c(x) = x^T \Sigma^{-1} \mu - \frac{1}{2} (x + \mu)^T \Sigma^{-1} (x + \mu)$$
$$= z^T x + \mathbf{tr}(Y) (-\frac{1}{2} x x^T)$$

And the density function can be written as:

$$p_{\theta}(x) = \frac{e^{-\frac{1}{2}z^{T}Y^{-1}z}}{(2\pi)^{\frac{n}{2}}|Y|^{\frac{1}{2}}} \exp\left(z^{T}x + \mathbf{tr}(Y)(-\frac{1}{2}xx^{T})\right)$$

The valid value of z is \mathbf{R}^n , and the valid value of Y is \mathbf{S}^n_{++}

(d) Consider the case when \mathcal{D} is finite and discrete,

$$\log p_{\theta}(x) = \log a(\theta) + \theta^{T} c(x)$$
$$= -\log \sum_{x \in \mathcal{D}} \exp (\theta^{T} c(x)) + \theta^{T} c(x)$$

Since $\theta^T c(x)$ is affine, and we have shown in class that log-sum-exp function is convex, we now have shown that $\log p_{\theta}(x)$ is concave.

When \mathcal{D} is discrete but infinite or continuous, we can set,

$$\mathcal{D} = \mathcal{D}_1 + \dots + \mathcal{D}_n + \dots$$
$$= \lim_{n \to \infty} \sum_{i=1}^n \mathcal{D}_i$$

and for $x \in \mathcal{D}_i$, $\log p_{\theta}(x)$ is concave. So the sums of $\log p_{\theta}(x)$ is concave.

(e) Since the K samples are IID,

$$\ell_{\theta}(x_1, \dots, x_K) = \log \prod_{i=1}^K p_{\theta}(x_i)$$

$$= \sum_{i=1}^K \log p_{\theta}(x_i)$$

$$= \sum_{i=1}^K \left(-\log \sum_{x_i \in \mathcal{D}} \exp(\theta^T c(x_i)) + \theta^T c(x_i) \right)$$

Therefore,

$$\nabla_{\theta} \ell_{\theta}(x_1, \dots, x_K) = \sum_{i=1}^K \left(-\frac{\sum_{x_i \in \mathcal{D}} \exp(\theta^T c(x_i)) c(x_i)}{\sum_{x_i \in \mathcal{D}} \exp(\theta^T c(x_i))} + c(x_i) \right)$$
$$= -K \mathbf{E}_{\theta} c(x) + \sum_{i=1}^K c(x_i)$$

So that

$$(1/K)\nabla_{\theta}\ell_{\theta}(x_1,\cdots,x_K) = -\mathbf{E}_{\theta}c(x) + \frac{1}{K}\sum_{i=1}^{K}c(x_i)$$

A7.7.

```
[143] lam = cp.Variable(p)
  obj = 0
  for k in range(n):
    e = np.zeros(shape = (n, 1))
    e[k] = 1
    obj += 1/m * cp.matrix_frac(e, V @ cp.diag(lam) @ V.T)
    constraints = [cp.sum(lam)==1, cp.min(lam) >= 0]

prob = cp.Problem(cp.Minimize(obj),constraints)
  prob.solve(solver = cp.CVXOPT)

print("The optimal value is", prob.value)
```

The optimal value is 0.12810192899289358

```
low_bnd = prob.value

m_rnd = cp.pos(np.round(m*lam.value,decimals=1))
print(sum(m_rnd.value) == m)

up_bnd = 0
for k in range(n):
    e = np.zeros(shape = (n, 1))
    e[k] = 1
    up_bnd += 1/m * cp.matrix_frac(e, V @ cp.diag(m_rnd/m) @ V.T)

gap = up_bnd - low_bnd
gap_value = gap.value
print ('The gap between the upper and the lower bounds is:', gap_value)
```

The gap is really small, which means the relaxed could be a good approximation of

The gap between the upper and the lower bounds is: 4.5609239246735545e-06

A7.21.

(a) The ARX model can be written as:

discrete A-optimal experiment problem.

$$y_{t+1} = \varphi_{t+1}^T \beta + x_{t+1}$$

where,

$$\varphi_{t+1} = [y_t \cdots y_{t-M+1}]^T \in R^M$$
$$\beta = [\beta_1 \cdots \beta_M]^T \in R^M$$
$$x_{t+1} \sim \mathcal{N}(0, \sigma^2)$$

The goal of ARX is to identify β using M consecutive observations. The joint density function of M observations is:

$$f = \prod_{i=1}^{M} \frac{1}{\sqrt{2\pi}\sigma} \exp\left[\frac{-(y_i - \varphi_i^T \beta)^2}{2\sigma^2}\right]$$

The log-likelihood function is:

$$L(\beta, \sigma) = C - \sum_{i=1}^{M} \frac{(y_i - \varphi_i^T \beta)^2}{2\sigma^2}$$
$$= C - \frac{1}{2\sigma^2} \sum_{i=1}^{M} (y_i - \varphi_i^T \beta)^2$$

where C is constant regardless of the value of β .

Differentiation of the log-likelihood function is:

$$\frac{\partial}{\partial \beta} L(\beta, \sigma) = \frac{1}{2\sigma^2} \sum_{i=1}^{M} 2\varphi_i (y_i - \varphi_i^T \beta)$$

Set the differentiation equals zero, then we get:

$$\sum_{i=1}^{M} \varphi_i(y_i - \varphi_i^T \beta) = 0$$

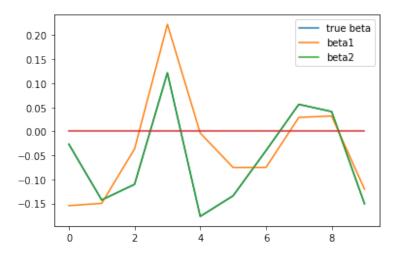
(b) We want to minimize the error and maximize the likelihood,

minimize
$$\|y - \varphi^T \beta\|_2^2$$

If x is sparse, we can use Lasso Regression as a simple model based on convex optimization. Since the number of equations are more than the number of variables, this is an over-constrained problem:

(c) We can see the results from part(b) is really close to the true β . In the figure below, they overlapped. According to my limited understanding, this is because we assumed x is sparse, and this prior condition can reduce the interference of noise.

```
(63] import cvxpy as cp
       beta_1 = cp.Variable(shape=(M,1))
       obj_1 = 0
       for i in range(0,T-M-1):
         y_pre = beta_1.T*y[i+M:i:-1]
         obj_1+=cp.square(y[i+M+1]-y_pre)
       prob_1 = cp.Problem(cp.Minimize(obj_1))
       prob_1.solve()
       48.65413037425698
[75] import cvxpy as cp
       beta_2 = cp.Variable(shape=(M,1))
       obj_2 = 0
       for i in range(0,T-M-1):
         y_pre = beta_2.T*y[i+M:i:-1]
         obj_2+=cp.abs(y[i+M+1]-y_pre)
       obj_2 = obj_1+0.1*obj_2
       prob_2 = cp.Problem(cp.Minimize(obj_2))
       prob_2.solve()
       52.187730968031445
```



A7.37.

(a) Since the N samples are IID, the joint density function is:

$$f = \prod_{i=1}^{N} p(x_i; \lambda)$$
$$= \prod_{i=1}^{N} \sum_{j=1}^{k} \lambda_j p_j(x)$$

The log-likelihood function is:

$$L(\lambda) = \sum_{i=1}^{N} \log \left(\sum_{j=1}^{k} \lambda_{j} p_{j}(x) \right)$$

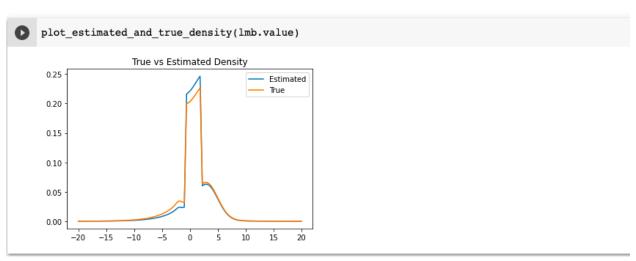
We want to maximize the log-likelihood:

minimize
$$-\sum_{i=1}^{N} \log \left(\sum_{j=1}^{k} \lambda_{j} p_{j}(x) \right)$$
 subject to
$$1^{T} \lambda = 1$$

$$\lambda \succeq 0$$

```
[ ] lmb = cp.Variable(shape=(k,1))
  obj = -cp.sum(cp.log(lmb.T @ densities.T))
  constraints = [sum(lmb)==1, lmb>=0]
  prob = cp.Problem(cp.Minimize(obj),constraints)
  prob.solve()
```

206.88181359033456



(b)

A6.5.

(a) The problem is:

minimize
$$||Ax - b||_{1.5}$$

= $\left(\sum_{i=1}^{k} |a_i^T x - b_i|^{3/2}\right)^{2/3}$

which is equivalent to:

$$\text{minimize } \sum_{i=1}^{k} |a_i^T x - b_i|^{3/2}$$

The gradient of this objective function is:

$$\nabla_x = \sum_{i=1}^k (3/2) \text{sign}(a_i^T x - b_i) |a_i^T x - b_i|^{1/2} a_i$$

Set the gradient equals zero, then the optimal condition is:

$$\sum_{i=1}^{k} \operatorname{sign}(a_i^T x - b_i) |a_i^T x - b_i|^{1/2} a_i = 0$$

(b) Combining the methods we used in ℓ_1 and ℓ_2 norms, we can write the problem as:

minimize
$$1^T t$$

subject to: $-s_i \leq a_i^T x - b_i \leq s_i$
 $s^{3/2} \leq t$

Now we have to reform the last constraint to make it a SDP problem.

$$s^{3/2} \leq t \Leftrightarrow s^2 \leq ts^{1/2}$$

$$\begin{bmatrix} \sqrt{s_i} & s_i \\ s_i & t \end{bmatrix} \succeq 0$$

To extract the square root function, we introduce y such that $0 \leq y \leq \sqrt{s}$, so that we can rewrite the above constraint as:

$$\begin{bmatrix} y_i & s_i \\ s_i & t_i \end{bmatrix} \succeq 0, \quad \begin{bmatrix} s_i & y_i \\ y_i & 1 \end{bmatrix} \succeq 0$$

Now we can formulate the $\ell_{1.5}$ norm approximation problem as an SDP:

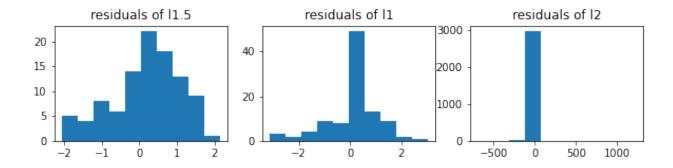
minimize
$$1^T t$$

subject to: $-s_i \leq a_i^T x - b_i \leq s_i$
 $\begin{bmatrix} y_i & s_i \\ s_i & t_i \end{bmatrix} \succeq 0, \begin{bmatrix} s_i & y_i \\ y_i & 1 \end{bmatrix} \succeq 0$

(c)

```
# 11.5
       x = cp.Variable(shape=(30,1))
       s = cp.Variable(shape=(100,1))
       obj = cp.mixed_norm(s, 2, 3)
       constraints = [s \ge cp.abs(A*x-b)]
       prob = cp.Problem(cp.Minimize(obj),constraints)
       prob.solve()
   □ 4.848858246643649
x_1 = cp.Variable(shape=(30,1))
       obj_1 = cp.norm(A*x_1-b,1)
       prob_1 = cp.Problem(cp.Minimize(obj_1))
       prob_1.solve()
       66.15897931542277

✓ [50] # 12
      x_2 = A/b
```



A7.13.

The density of x = Az + b is given by:

$$p_x(v) = \frac{1}{|\det A|} p_z(A^{-1}(v-b))$$
$$= \frac{1}{|\det A|} \exp -\phi \left(\|A^{-1}(v-b)\|_2 \right)$$

 x_1, \dots, x_N are independent samples, and the joint density is:

$$\left(\frac{1}{|\det A|}\right)^{N} \prod_{i=1}^{N} \exp(-\phi \left(\left\|A^{-1}(x_{i}-b)\right\|_{2}\right)\right)$$

The log-likelihood function is:

$$l(A, b) = -N \log(|\det A|) - \sum_{i=1}^{N} \phi(||A^{-1}(x_i - b)||_2)$$

We notice l(A, b) is not concave. In order to find the maximum value of l(A, b), we use:

$$B = A^{-1} \qquad c = A^{-1}b$$

Now the log-likelihood function becomes:

$$l(B, c) = N \log(\det B) - \sum_{i=1}^{N} \phi(\|B(x_i - c)\|_2)$$

Since l(B,c) is concave, we can find B^* , c^* such that

$$\frac{\partial}{\partial B}l(B^*, c) = 0$$
$$\frac{\partial}{\partial c}l(B, c^*) = 0$$

Therefor, we can get $A^* = (B^*)^{-1}$, $b^* = (B^*)^{-1}c^*$