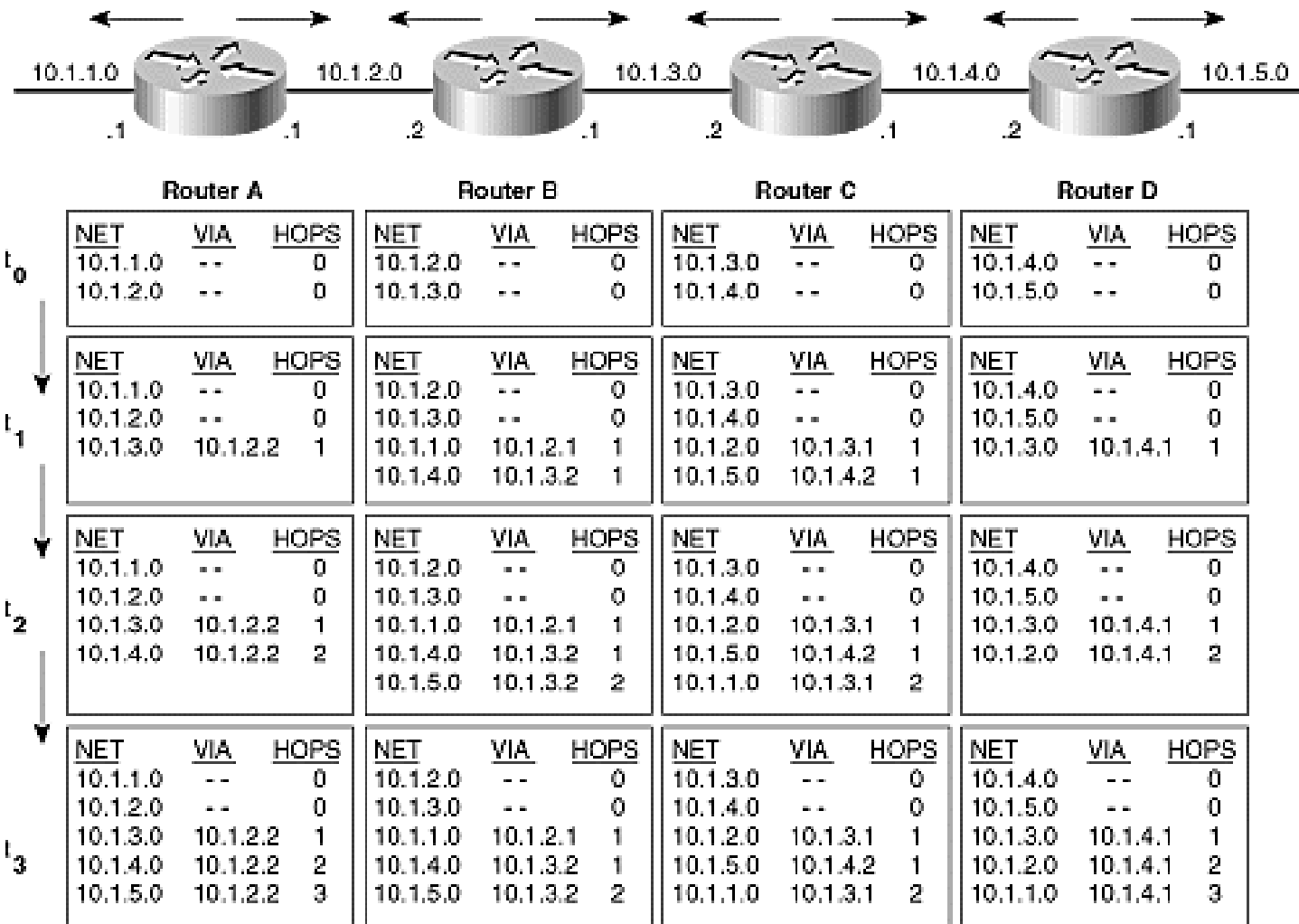


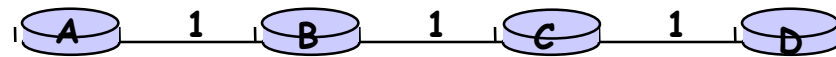
## Example [ Distributed Bellman-Ford Algorithm ]



## Example [ DBF Algorithm – reaction to link failure ]

**DBF algorithm may react very slowly to a link failure!**

For example, consider the following topology, with node D as the destination.

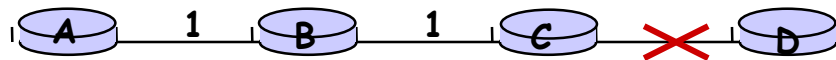


routing-table entries for D only, at A, B, C

Update	Node A	Node B	Node C
before break	(D,3,B)	(D,2,C)	(D,1,D)

Suppose after the algorithm stabilizes, link (C,D) breaks. Recompute the minimum cost from each node to the destination node (node D).

Update packets bounce back and fourth between B and A/C until the minimum cost is  $\infty$  (or very large, in practice). At that point the algorithm realizes that node D is unreachable.



**“count to infinity” problem !!!**

**solution: stop when cost = 16**

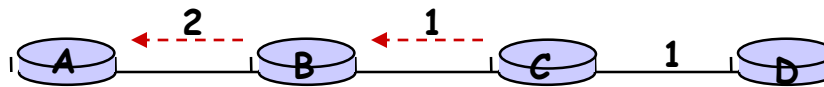
updates for D only

Update	Node A	Node B	Node C
	(D, 3)	(D, 2)	$\infty$
1	(D, 3)	(D, 2)	(D, 3)
2	(D, 3)	(D, 4)	(D, 3)
3	(D, 5)	(D, 4)	(D, 5)
4	(D, 5)	(D, 6)	(D, 5)
5	(D, 7)	(D, 6)	(D, 7)
...	...	...	...

**Count to Infinity Problem** – slow convergence to a change in topology

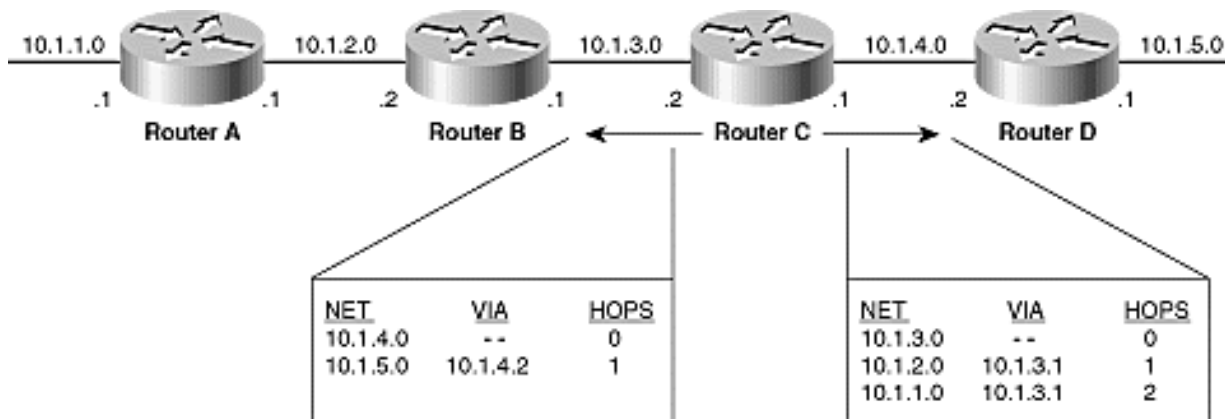
- could be partially avoided using “**split horizon**” and “**split horizon with poisoned reverse**”

**Split Horizon** – minimum cost to a given destination should NOT be sent to a neighbour if neighbour is next node along the shortest path



B should **not** advertise any route to C for which C is the next hop.

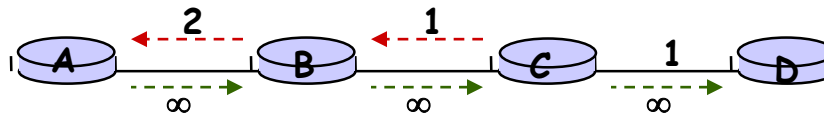
**Example** [ split horizon ]



**Split Horizon works by suppressing information!!!**

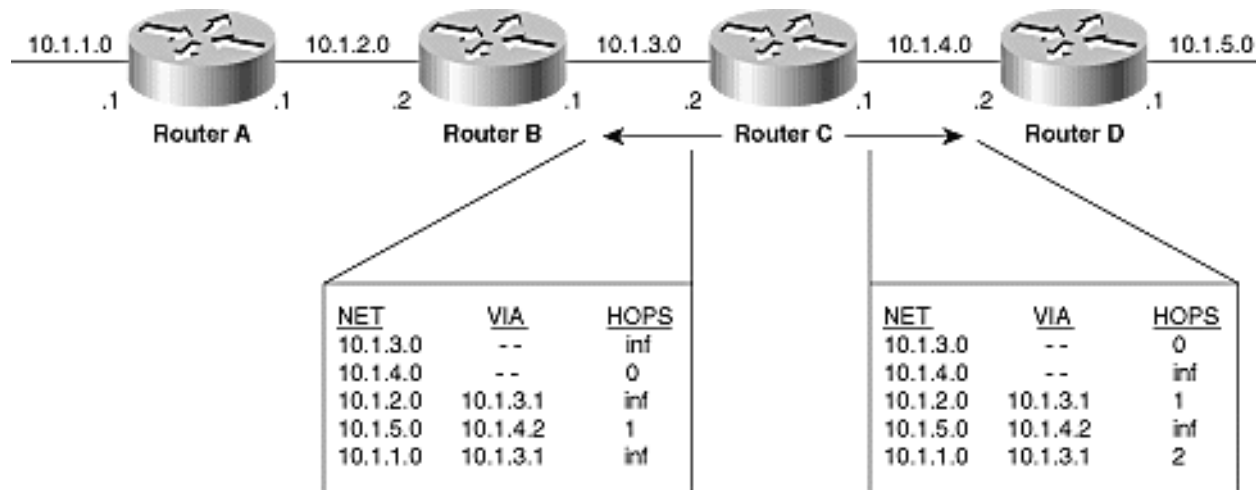
## Split Horizon with Poison Reverse

- a node sends the minimum cost to all its neighbours; but, **the minimum cost to a given destination is set to infinity ( $\infty=16$ , in practice) if the neighbour is the next node along the shortest path**
- if two routers have routes pointing at each other, advertising reverse routes with a metric of  $\infty=16$  breaks the loop immediately



B advertises to C the route to D as a route of cost  $\infty=16$

## Example [ poisoned reverse ]



## Link State vs. Distance Vector

	Link State	Distance Vector
<b>size of (update) routing info</b>	small, contains only neighbours' link costs 😊	potentially long distance vectors
<b>communication overhead</b>	flood to all nodes – overhead $O(N \cdot E)$ , where $N = \# \text{ of nodes}$ , $E = \# \text{ of edges}$	send distance vectors only to neighbours – $O(N \cdot K)$ if each of $N$ routers has $K$ neighbours 😊
<b>convergence speed</b>	do NOT need to recalculate LSP's before forwarding $\Rightarrow$ faster 😊	takes a while to propagate changes to rest of network
<b>space requirements</b>	maintains entire topology in a link database – $O(N \cdot K)$ if each of $N$ routers has $K$ neighbours	maintains only neighbours' states – $O(K)$ distance vectors 😊
<b>computational complexity per one destination</b>	$O(N \cdot (N-1)/2) = O(N^2)$	$O(N \cdot K \cdot \text{Diameter})$ 😊
<b>computational robustness</b>	each router computes paths on its own – no error propagation 😊	routers compute paths collectively – errors propagate
<b>security / fault tolerance</b>	false/corrupt LSPs can be flooded to all routers	false/corrupt LSPs can be flooded to all routers