Mar	s Rover Ground Station	Sub T Tasks P	Task Prog.
0	Full-Screen Mode		0%
1	Dark UI Theme	(0%
2	Two Monitors Minimum	(0%
3	Rover Connection	(0%
4	Arm Connection	(0%
5	IMU Visualizer	(0%
6	Rover Computer	(0%
7	Display Data Collection Sensors	(0%
8	Arm Joint Positions	(0%
9	Joystick Connection	(0%
10	Camera Presence	(0%
11	Rover Battery		0%
12	Rover Joystick Arm		0%
13	GPS Status		0%
14	Rover Voltage		0%
15	GPS Satellites Connected		0%
16	GPS Accuracy		0%
17			0%
	Map Visualizer Rover Speed		0%
18	Rover Heading		0%
19	Rover Heading Rosio Connection		
20	Bogie Connection		0%
21	Current Radio Signal Strength		0%
22	Rover Joystick Driving		0%
23	Rover RTT		0%
24	Rover Network Potential Throughput		0%
25	Estimated Rover Distance		0%
26	Rover Speed Limit	(0%
27	Rover Speed Limit Control	(0%
28	Autonomy Switch	(0%
29	Video Stream Displays	(0%
30	Camera Source Selection	(0%
31	Camera Quality Adjustments	(0%
32	Video Stream FPS Counter	(0%
33	Way-point Placement	(0%
34	Autonomy Streams Overlay	(0%
35	Way-point Editing	(0%
36	Way-point Re-Ordering	(0%
37	Way-point Navigation Path	(0%
38	Active Way-point Selection	(0%
39	Autonomy Indicator	(0%
40	Log File Viewing	(0%
41	Getting Started Document		0%
42	3D Rover Arm Visualization		0%
43 44	Quick Deploy Case Automatic Video Stream Quality Adjustment		0%