Report Generated by Test Manager

Title: AHRS_voter SIL REQ-Based Tests

Author:

Date: 14-May-2020 08:49:44

Test Environment

Platform: PCWIN64 MATLAB: (R2019b)

Summary

Name	Outcome	Duration (Seconds)
Results: 2020-May-14 08:49:17	32	24.512
AHRS_voter_REQ_Based_Test	32	24.512
AHRS Voting Test Suite	3❷	24.512
Mid Value Voting Test Case	Ø	7.738
Average Value Voting Test Case	Ø	9.269
☐ Single Value Voting Test Case	⊘	7.42

Results: 2020-May-14 08:49:17

Result Type: Result Set

Parent: None

Start Time: 14-May-2020 08:49:17 End Time: 14-May-2020 08:49:42 Outcome: Total: 3, Passed: 3

Aggregated Coverage Results

Analyzed Model	Sim Mode	Complexity	Decision	Function	Function call	Execution
AHRS_voter	ModelRefSIL	23	93%	100%	100%	95%

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AHRS_voter_REQ_Based_Test

Test Result Information

Result Type: Test File Result

Parent: <u>Results: 2020-May-14 08:49:17</u>

Start Time: 14-May-2020 08:49:17 End Time: 14-May-2020 08:49:42 Outcome: Total: 3, Passed: 3

Description:

Checksum when compiled as referenced model: 274277033 2770558437 1049845676 2563622565

Checksum when compiled as top model: 1951542874 3450456451 46553782 3275149564

Test Suite Information

Name: AHRS_voter_REQ_Based_Test

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AHRS Voting Test Suite

Test Result Information

Result Type: Test Suite Result

Parent: <u>AHRS_voter_REQ_Based_Test</u>

Start Time: 14-May-2020 08:49:17 End Time: 14-May-2020 08:49:42 Outcome: Total: 3, Passed: 3

Test Suite Information

Name: AHRS Voting Test Suite

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Mid Value Voting Test Case

Test Result Information

Result Type: Test Case Result

Parent: AHRS Voting Test Suite
Start Time: 14-May-2020 08:49:17
End Time: 14-May-2020 08:49:25

Outcome: Passed

Description:

Test the mid value voting algorithm with three valid AHRS.

Test Case Information

Name: Mid Value Voting Test Case

Type: Simulation Test

Test Case Requirements

Description: HLR_11: AHRS Voting for Triple Sensors (HelicopterSoftwareR

equirements#15)

Document: HelicopterSoftwareRequirements.slreqx

Description: HLR_9: AHRS Validity Check (HelicopterSoftwareRequirement

s#13)

Document: HelicopterSoftwareRequirements.slreqx

Verify Result

Name
Test Sequence/step_1:verify(abs(voted_fb(1)) <tol)< p=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(2)) <tol)< p=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(3)) <tol)< td=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(4)) <tol)< td=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(5)) <tol)< td=""></tol)<>
Test Sequence/step_3:verify((voted_fb(1)-AHRS1.theta) <tol)< td=""></tol)<>
Test Sequence/step_3:verify((voted_fb(2)-AHRS2.phi) <tol)< p=""></tol)<>

:	ence/step_3:verify((voted_fb(3)-AHRS3.r) <tol)< th=""><th>_</th><th></th></tol)<>	_	
Test Sec	ence/step_3:verify((voted_fb(4)-AHRS3.q) <tol)< td=""><td>_</td><td></td></tol)<>	_	
Test Sec	ence/step_3:verify((voted_fb(5)-AHRS1.p) <tol)< td=""><td></td><td></td></tol)<>		
Test Sec	ence/step_5:verify((voted_fb(1)-AHRS2.theta) <tol)< td=""><td></td><td></td></tol)<>		
Test Sec	ence/step_5:verify((voted_fb(2)-AHRS1.phi) <tol)< td=""><td></td><td></td></tol)<>		
Test Sec	ence/step_5:verify((voted_fb(3)-AHRS2.r) <tol)< td=""><td></td><td></td></tol)<>		
Test Sec	ence/step_5:verify((voted_fb(4)-AHRS2.q) <tol)< td=""><td></td><td></td></tol)<>		
Test Sec	ence/step_5:verify((voted_fb(5)-AHRS3.p) <tol)< td=""><td></td><td></td></tol)<>		
Test Sec	ence/step_7:verify((voted_fb(1)-AHRS3.theta) <tol)< td=""><td></td><td></td></tol)<>		
Test Sec	ence/step_7:verify((voted_fb(2)-AHRS3.phi) <tol)< td=""><td></td><td></td></tol)<>		
Test Sec	ence/step_7:verify((voted_fb(3)-AHRS1.r) <tol)< td=""><td>_</td><td></td></tol)<>	_	
Test Sec	ence/step_7:verify((voted_fb(4)-AHRS1.q) <tol)< td=""><td>_</td><td></td></tol)<>	_	
Test Sec	ence/step_7:verify((voted_fb(5)-AHRS2.p) <tol)< td=""><td>_</td><td></td></tol)<>	_	

Simulation

System Under Test Information

Model: AHRS_voter

Harness: AHRS_voter_Harness_triple_sensor

Harness Owner: AHRS_voter

Simulation Mode: software-in-the-loop (sil)

Override SIL or PIL Mod 0

e:

Configuration Set: Configuration1

Start Time: 0 Stop Time: 10

Checksum: 3126753826 1062275525 336322258 2830877220

Simulink Version: 10.0 Model Version: 1.7

Model Author: bpotter

Date: Wed May 13 13:30:04 2020

User ID: bpotter

Model Path: C:\Users\bpotter\MATLAB\Projects\ARP_DO_Proje

ct\DO_03_Design\AHRS_voter\specification\AHRS_

voter_Harness_triple_sensor.slx

Machine Name: AH-BPOTTER Solver Name: FixedStepDiscrete

Solver Type: Fixed-Step

Fixed Step Size: 0.01

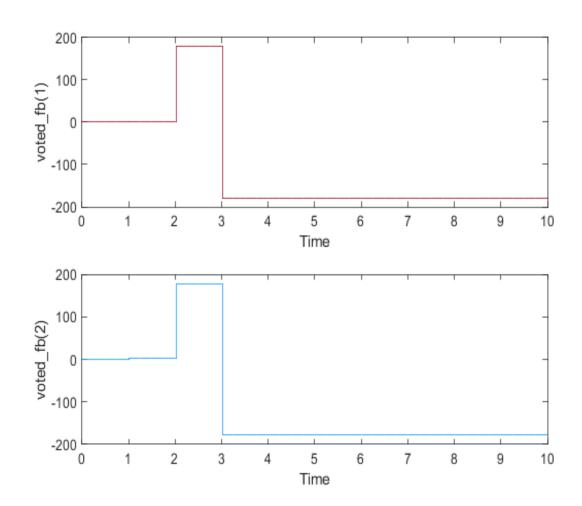
Simulation Start Time: 2020-05-14 08:49:18 Simulation Stop Time: Platform: 2020-05-14 08:49:24

PCWIN64

Simulation Output

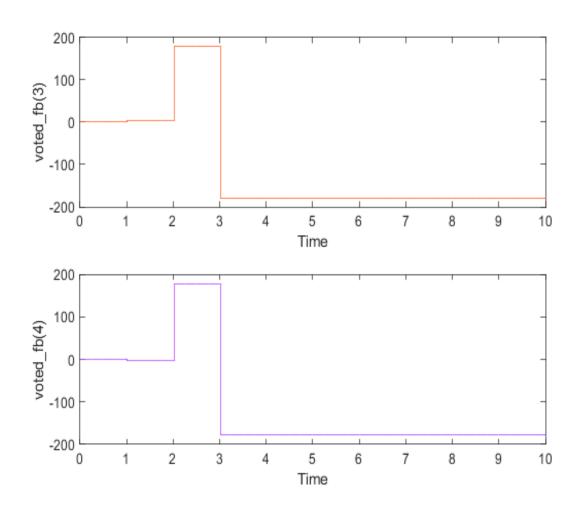
Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plot
voted_fb(1)	double		0.01	zoh	union	<u>Link</u>
voted_fb(2)	double		0.01	zoh	union	<u>Link</u>
voted_fb(3)	double	 L	0.01	zoh	union	<u>Link</u>
voted_fb(4)	double		0.01	zoh	union	<u>Link</u>
voted_fb(5)	double		0.01	zoh	union	<u>Link</u>

Name	Data Type	Units	Sample Time	Interp	Sync
voted_fb(1)	double		0.01	zoh	union
voted_fb(2)	double		0.01	zoh	union



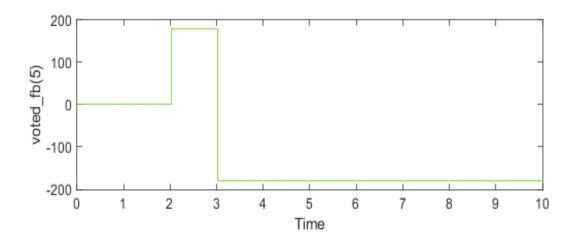
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Name	Data Type	Units	Sample Time	Interp	Sync
voted_fb(3)	double		0.01	zoh	union
voted_fb(4)	double	_	0.01	zoh	union



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Name	Data Type	Units	Sample Time	Interp	Sync
voted_fb(5)	double		0.01	zoh	union



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Average Value Voting Test Case

Test Result Information

Result Type: Test Case Result

Parent: AHRS Voting Test Suite
Start Time: 14-May-2020 08:49:25
End Time: 14-May-2020 08:49:34

Outcome: Passed

Description:

Test the average value voting algorithm with two valid AHRS.

Test Case Information

Name: Average Value Voting Test Case

Type: Simulation Test

Test Case Requirements

Description: HLR_12: AHRS Voting for Dual Sensors (HelicopterSoftwareRe

quirements#16)

Document: HelicopterSoftwareRequirements.slreqx

Description: HLR_9: AHRS Validity Check (HelicopterSoftwareRequirement

s#13)

Document: HelicopterSoftwareRequirements.slregx

Verify Result

Name
Test Sequence/step_1:verify(abs(voted_fb(1)-(AHRS1.theta+AHRS2.theta)/2) <tol)< td=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(2)-(AHRS1.phi+AHRS2.phi)/2) <tol)< td=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(3)-(AHRS1.r+AHRS2.r)/2) <tol)< td=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(4)-(AHRS1.q+AHRS2.q)/2) <tol)< td=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(5)-(AHRS1.p+AHRS2.p)/2) <tol)< td=""></tol)<>
Test Sequence/step_3:verify(abs(voted_fb(1)-(AHRS1.theta+AHRS3.theta)/2) <tol)< td=""></tol)<>
Test Sequence/step_3:verify(abs(voted_fb(2)-(AHRS1.phi+AHRS3.phi)/2) <tol)< td=""></tol)<>
Test Sequence/step_3:verify(abs(voted_fb(3)-(AHRS1.r+AHRS3.r)/2) <tol)< td=""></tol)<>
Test Sequence/step_3:verify(abs(voted_fb(4)-(AHRS1.q+AHRS3.q)/2) <tol)< td=""></tol)<>
Test Sequence/step_3:verify(abs(voted_fb(5)-(AHRS1.p+AHRS3.p)/2) <tol)< td=""></tol)<>
Test Sequence/step_5:verify(abs(voted_fb(1)-(AHRS3.theta+AHRS2.theta)/2) <tol)< td=""></tol)<>
Test Sequence/step_5:verify(abs(voted_fb(2)-(AHRS3.phi+AHRS2.phi)/2) <tol)< td=""></tol)<>
Test Sequence/step_5:verify(abs(voted_fb(3)-(AHRS3.r+AHRS2.r)/2) <tol)< td=""></tol)<>
Test Sequence/step_5:verify(abs(voted_fb(4)-(AHRS3.q+AHRS2.q)/2) <tol)< td=""></tol)<>
Test Sequence/step_5:verify(abs(voted_fb(5)-(AHRS3.p+AHRS2.p)/2) <tol)< td=""></tol)<>

Simulation

System Under Test Information

Model: AHRS voter

Harness: AHRS_voter_Harness_dual_sensor

Harness Owner: AHRS_voter

Simulation Mode: software-in-the-loop (sil)

Override SIL or PIL Mod 0

e:

Configuration Set: Configuration 1

Start Time: 0 Stop Time: 10

Checksum: 4001394588 2910937263 1001402514 314995091

Simulink Version: 10.0 Model Version: 1.4 Model Author: bpotter

Date: Wed May 13 13:30:04 2020

User ID: bpotter

Model Path: C:\Users\bpotter\MATLAB\Projects\ARP_DO_Proje

ct\DO_03_Design\AHRS_voter\specification\AHRS_

voter_Harness_dual_sensor.slx

Machine Name: AH-BPOTTER Solver Name: FixedStepDiscrete

Solver Type: Fixed-Step

Fixed Step Size: 0.01

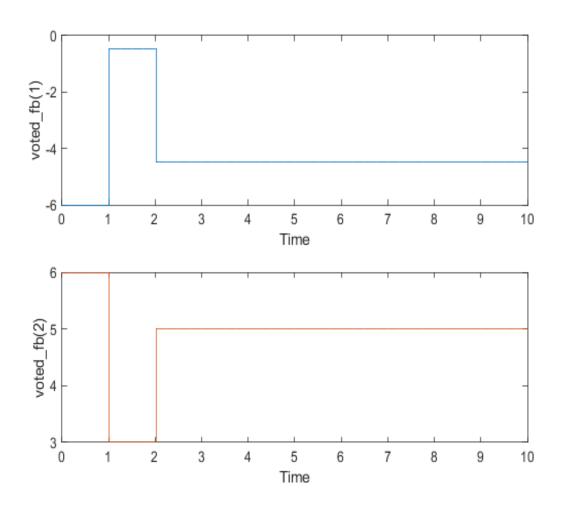
Simulation Start Time: 2020-05-14 08:49:25 Simulation Stop Time: 2020-05-14 08:49:34

Platform: PCWIN64

Simulation Output

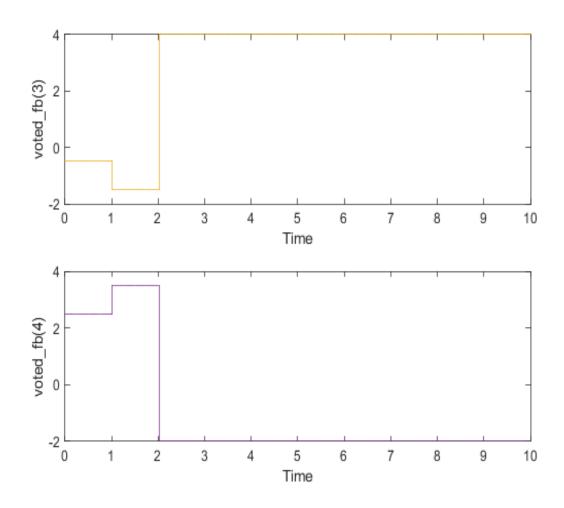
Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plot
voted_fb(1)	double		0.01	zoh	union	<u>Link</u>
voted_fb(2)	double		0.01	zoh	union	<u>Link</u>
voted_fb(3)	double		0.01	zoh	union	<u>Link</u>
voted_fb(4)	double		0.01	zoh	union	<u>Link</u>
voted_fb(5)	double		0.01	zoh	union	<u>Link</u>

Name	Data Type	Units	Sample Time	Interp	Sync
voted_fb(1)	double		0.01	zoh	union
voted_fb(2)	double		0.01	zoh	union



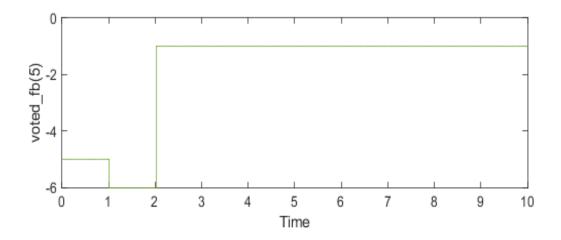
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Name	Data Type	Units	Sample Time	Interp	Sync
voted_fb(3)	double		0.01	zoh	union
voted_fb(4)	double		0.01	zoh	union



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Name	Data Type	Units	Sample Time	Interp	Sync
voted_fb(5)	double		0.01	zoh	union



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Single Value Voting Test Case

Test Result Information

Result Type: Test Case Result

Parent: AHRS Voting Test Suite
Start Time: 14-May-2020 08:49:34
End Time: 14-May-2020 08:49:42

Outcome: Passed

Description:

Test the single value voting algorithm with one valid AHRS.

Test Case Information

Name: Single Value Voting Test Case

Type: Simulation Test

Test Case Requirements

Description: HLR_13: AHRS Usage of Single Sensor (HelicopterSoftwareReq

uirements#17)

Document: HelicopterSoftwareRequirements.slreqx

Description: HLR_9: AHRS Validity Check (HelicopterSoftwareRequirement

s#13)

Document: HelicopterSoftwareRequirements.slreqx

Verify Result

Name
Test Sequence/step_1:verify(abs(voted_fb(1)-AHRS1.theta) <tol)< p=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(2)-AHRS1.phi) <tol)< td=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(3)-AHRS1.r) <tol)< p=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(4)-AHRS1.q) <tol)< td=""></tol)<>
Test Sequence/step_1:verify(abs(voted_fb(5)-AHRS1.p) <tol)< td=""></tol)<>
Test Sequence/step_3:verify(abs(voted_fb(1)-AHRS2.theta) <tol)< td=""></tol)<>
Test Sequence/step_3:verify(abs(voted_fb(2)-AHRS2.phi) <tol)< td=""></tol)<>
Test Sequence/step_3:verify(abs(voted_fb(3)-AHRS2.r) <tol)< td=""></tol)<>
Test Sequence/step_3:verify(abs(voted_fb(4)-AHRS2.q) <tol)< td=""></tol)<>
Test Sequence/step_3:verify(abs(voted_fb(5)-AHRS2.p) <tol)< td=""></tol)<>
Test Sequence/step_5:verify(abs(voted_fb(1)-AHRS3.theta) <tol)< td=""></tol)<>
Test Sequence/step_5:verify(abs(voted_fb(2)-AHRS3.phi) <tol)< td=""></tol)<>
Test Sequence/step_5:verify(abs(voted_fb(3)-AHRS3.r) <tol)< td=""></tol)<>
Test Sequence/step_5:verify(abs(voted_fb(4)-AHRS3.q) <tol)< td=""></tol)<>
Test Sequence/step_5:verify(abs(voted_fb(5)-AHRS3.p) <tol)< p=""></tol)<>

Simulation

System Under Test Information

Model: AHRS voter

Harness: AHRS_voter_Harness_single_sensor

Harness Owner: AHRS_voter

Simulation Mode: software-in-the-loop (sil)

Override SIL or PIL Mod 0

e:

Configuration Set: Configuration 1

Start Time: 0 Stop Time: 10

Checksum: 1248596253 747419020 2561291537 1643757328

Simulink Version: 10.0 Model Version: 1.6 Model Author: bpotter

Date: Wed May 13 13:30:04 2020

User ID: bpotter

Model Path: C:\Users\bpotter\MATLAB\Projects\ARP_DO_Proje

ct\DO_03_Design\AHRS_voter\specification\AHRS_

voter_Harness_single_sensor.slx

Machine Name: AH-BPOTTER Solver Name: FixedStepDiscrete

Solver Type: Fixed-Step

Fixed Step Size: 0.01

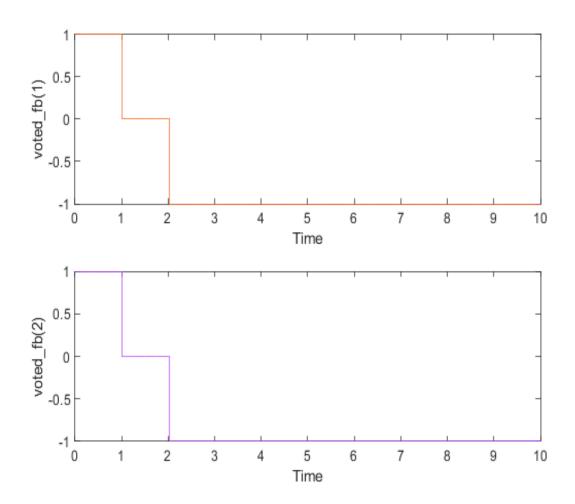
Simulation Start Time: 2020-05-14 08:49:35 Simulation Stop Time: 2020-05-14 08:49:41

Platform: PCWIN64

Simulation Output

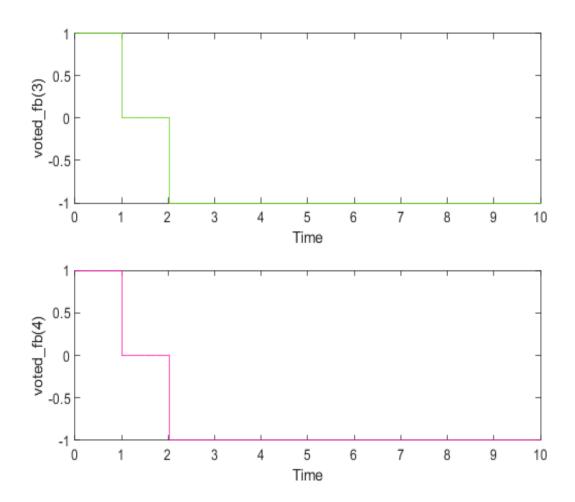
Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plot
voted_fb(1)	double		0.01	zoh	union	<u>Link</u>
voted_fb(2)	double		0.01	zoh	union	<u>Link</u>
voted_fb(3)	double		0.01	zoh	union	<u>Link</u>
voted_fb(4)	double		0.01	zoh	union	<u>Link</u>
voted_fb(5)	double		0.01	zoh	union	<u>Link</u>

Name	Data Type	Units	Sample Time	Interp	Sync
voted_fb(1)	double		0.01	zoh	union
voted_fb(2)	double		0.01	zoh	union



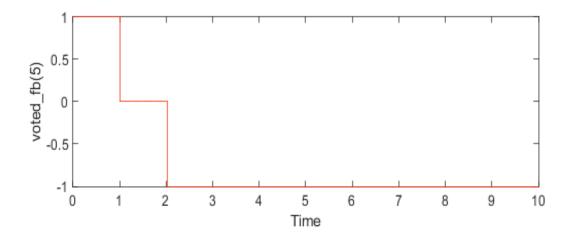
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Name	Data Type	Units	Sample Time	Interp	Sync
voted_fb(3)	double		0.01	zoh	union
voted_fb(4)	double		0.01	zoh	union



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Name	Data Type	Units	Sample Time	Interp	Sync	
voted_fb(5)	double		0.01	zoh	union	



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