

Dual 32-bit Arm[®] Cortex[®]-M7 up to 480MHz and -M4 MCUs, 2MB flash, 1MB RAM, 46 com. and analog interfaces, SMPS, crypto

Datasheet - production data

Features

Includes ST state-of-the-art patented technology

Dual core

- 32-bit Arm[®] Cortex[®]-M7 core with double-precision FPU and L1 cache: 16 Kbytes of data and 16 Kbytes of instruction cache; frequency up to 480 MHz, MPU, 1027 DMIPS/2.14 DMIPS/MHz (Dhrystone 2.1), and DSP instructions
- 32-bit Arm[®] 32-bit Cortex[®]-M4 core with FPU, Adaptive real-time accelerator (ART Accelerator) for internal flash memory and external memories, frequency up to 240 MHz, MPU, 300 DMIPS/1.25 DMIPS /MHz (Dhrystone 2.1), and DSP instructions

Memories

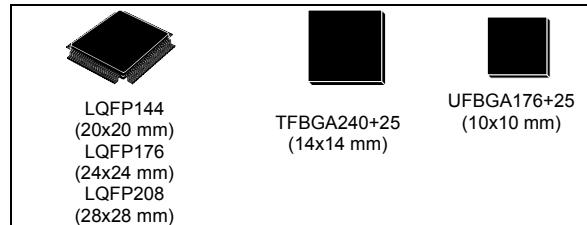
- 2 Mbytes of flash memory with read-while-write support
- 1 Mbyte of RAM: 192 Kbytes of TCM RAM (inc. 64 Kbytes of ITCM RAM + 128 Kbytes of DTCM RAM for time critical routines), 864 Kbytes of user SRAM, and 4 Kbytes of SRAM in Backup domain
- Dual mode Quad-SPI memory interface running up to 133 MHz
- Flexible external memory controller with up to 32-bit data bus: SRAM, PSRAM, SDRAM/LPSDR SDRAM, NOR/NAND flash memory clocked up to 125 MHz in Synchronous mode
- CRC calculation unit

Security

- ROP, PC-ROP, active tamper, secure firmware upgrade support, Secure access mode

General-purpose input/outputs

- Up to 168 I/O ports with interrupt capability



Reset and power management

- 3 separate power domains which can be independently clock-gated or switched off:
 - D1: high-performance capabilities
 - D2: communication peripherals and timers
 - D3: reset/clock control/power management
- 1.62 to 3.6 V application supply and I/Os
- POR, PDR, PVD and BOR
- Dedicated USB power embedding a 3.3 V internal regulator to supply the internal PHYs
- Embedded regulator (LDO) to supply the digital circuitry
- High power-efficiency SMPS step-down converter regulator to directly supply V_{CORE} and/or external circuitry
- Voltage scaling in Run and Stop mode (6 configurable ranges)
- Backup regulator (~0.9 V)
- Voltage reference for analog peripheral/ V_{REF+}
- 1.2 to 3.6 V V_{BAT} supply
- Low-power modes: Sleep, Stop, Standby and V_{BAT} supporting battery charging

Low-power consumption

- V_{BAT} battery operating mode with charging capability
- CPU and domain power state monitoring pins
- 2.95 μ A in Standby mode (Backup SRAM OFF, RTC/LSE ON)

Clock management

- Internal oscillators: 64 MHz HSI, 48 MHz HSI48, 4 MHz CSI, 32 kHz LSI
- External oscillators: 4-48 MHz HSE, 32.768 kHz LSE
- 3x PLLs (1 for the system clock, 2 for kernel clocks) with Fractional mode

Interconnect matrix

- 3 bus matrices (1 AXI and 2 AHB)
- Bridges (5x AHB2-APB, 2x AXI2-AHB)

4 DMA controllers to unload the CPU

- 1x high-speed master direct memory access controller (MDMA) with linked list support
- 2x dual-port DMAs with FIFO
- 1x basic DMA with request router capabilities

Up to 35 communication peripherals

- 4x I2Cs FM+ interfaces (SMBus/PMBus)
- 4x USARTs/4x UARTs/1LPUART (ISO7816 interface, LIN, IrDA, up to 12.5 Mbit/s)
- 6 SPI (+1 with Quad-SPI + 4 with USART): 3 with muxed duplex I2S audio class accuracy via internal audio PLL or external clock, 1x I2S in LP domain (up to 150 MHz) and up to 4 additional SPI from 4 USART/UART when configured in synchronous mode.
- SPDIFRX interface
- SWPMI single-wire protocol master I/F
- MDIO Slave interface
- 2x SD/SDIO/MMC interfaces (up to 125 MHz)
- 2x CAN controllers: 2 with CAN FD, 1 with time-triggered CAN (TT-CAN)
- 2x USB OTG interfaces (1FS, 1HS/FS) crystal-less solution with LPM and BCD
- Ethernet MAC interface with DMA controller
- HDMI-CEC
- 8- to 14-bit camera interface (up to 80 MHz)

11 analog peripherals

- 3x ADCs with 16-bit max. resolution (up to 36 channels, up to 3.6 MSPS)
- 1x temperature sensor
- 2x 12-bit D/A converters (1 MHz)
- 2x ultra-low-power comparators

- 2x operational amplifiers (7.3 MHz bandwidth)
- 1x digital filters for sigma delta modulator (DFSDM) with 8 channels/4 filters

Graphics

- LCD-TFT controller up to XGA resolution
- Chrom-ART graphical hardware Accelerator (DMA2D) to reduce CPU load
- Hardware JPEG Codec

Up to 22 timers and watchdogs

- 1x high-resolution timer (2.1 ns max resolution)
- 2x 32-bit timers with up to 4 IC/OC/PWM or pulse counter and quadrature (incremental) encoder input (up to 240 MHz)
- 2x 16-bit advanced motor control timers (up to 240 MHz)
- 10x 16-bit general-purpose timers (up to 240 MHz)
- 5x 16-bit low-power timers (up to 240 MHz)
- 4x watchdogs (independent and window)
- 2x SysTick timers
- RTC with sub-second accuracy and hardware calendar

Cryptographic acceleration

- AES 128, 192, 256, TDES
- HASH (MD5, SHA-1, SHA-2), HMAC
- True random number generators

Debug mode

- SWD & JTAG interfaces
- 4-Kbyte embedded trace buffer

96-bit unique ID

All packages are ECOPACK2 compliant

Optional support of extended temperature range up to 125 °C (specific part numbers)

Table 1. Device summary

Reference	Part number
STM32H755xl	STM32H755ZI, STM32H755II, STM32H755BI, STM32H755XI

Contents

1	Introduction	12
2	Description	13
3	Functional overview	19
3.1	Dual Arm® Cortex® cores	19
3.1.1	Arm® Cortex®-M7 with FPU	19
3.1.2	Arm® Cortex®-M4 with FPU	20
3.2	Memory protection unit (MPU)	20
3.3	Memories	20
3.3.1	Embedded flash memory	20
3.3.2	Secure access mode	21
3.3.3	Embedded SRAM	22
3.3.4	ART accelerator	22
3.4	Boot modes	23
3.5	Power supply management	24
3.5.1	Power supply scheme	24
3.5.2	Power supply supervisor	25
3.5.3	Voltage regulator (SMPS step-down converter and LDO)	26
3.5.4	SMPS step-down converter	26
3.6	Low-power strategy	27
3.7	Reset and clock controller (RCC)	28
3.7.1	Clock management	28
3.7.2	System reset sources	29
3.8	General-purpose input/outputs (GPIOs)	29
3.9	Bus-interconnect matrix	29
3.10	DMA controllers	31
3.11	Chrom-ART Accelerator (DMA2D)	31
3.12	Nested vectored interrupt controller (NVIC)	32
3.13	Extended interrupt and event controller (EXTI)	32
3.14	Cyclic redundancy check calculation unit (CRC)	32
3.15	Flexible memory controller (FMC)	33
3.16	Quad-SPI memory interface (QUADSPI)	33

3.17	Analog-to-digital converters (ADCs)	33
3.18	Temperature sensor	34
3.19	V_{BAT} operation	34
3.20	Digital-to-analog converters (DAC)	35
3.21	Ultra-low-power comparators (COMP)	35
3.22	Operational amplifiers (OPAMP)	35
3.23	Digital filter for sigma-delta modulators (DFSDM)	36
3.24	Digital camera interface (DCMI)	37
3.25	LCD-TFT controller	38
3.26	JPEG Codec (JPEG)	38
3.27	True random number generator (RNG)	38
3.28	Cryptographic acceleration (CRYP and HASH)	39
3.29	Timers and watchdogs	39
3.29.1	High-resolution timer (HRTIM1)	41
3.29.2	Advanced-control timers (TIM1, TIM8)	42
3.29.3	General-purpose timers (TIMx)	42
3.29.4	Basic timers TIM6 and TIM7	43
3.29.5	Low-power timers (LPTIM1, LPTIM2, LPTIM3, LPTIM4, LPTIM5)	43
3.29.6	Independent watchdogs	43
3.29.7	Window watchdogs	43
3.29.8	SysTick timer	43
3.30	Real-time clock (RTC), backup SRAM and backup registers	44
3.31	Inter-integrated circuit interface (I^2C)	45
3.32	Universal synchronous/asynchronous receiver transmitter (USART)	45
3.33	Low-power universal asynchronous receiver transmitter (LPUART)	46
3.34	Serial peripheral interfaces (SPI)/integrated interchip sound interfaces (I2S)	47
3.35	Serial audio interfaces (SAI)	47
3.36	SPDIFRX Receiver Interface (SPDIFRX)	48
3.37	Single wire protocol master interface (SWPMI)	48
3.38	Management Data Input/Output (MDIO) slaves	49
3.39	SD/SDIO/MMC card host interfaces (SDMMC)	49
3.40	Controller area network (FDCAN1, FDCAN2)	49
3.41	Universal serial bus on-the-go high-speed (OTG_HS)	50

3.42	Ethernet MAC interface with dedicated DMA controller (ETH)	50
3.43	High-definition multimedia interface (HDMI) - consumer electronics control (CEC)	51
3.44	Debug infrastructure	51
4	Memory mapping	53
5	Pinout, pin description and alternate functions	54
6	Electrical characteristics	99
6.1	Parameter conditions	99
6.1.1	Minimum and maximum values	99
6.1.2	Typical values	99
6.1.3	Typical curves	99
6.1.4	Loading capacitor	99
6.1.5	Pin input voltage	99
6.1.6	Power supply scheme	100
6.1.7	Current consumption measurement	101
6.2	Absolute maximum ratings	101
6.3	Operating conditions	103
6.3.1	General operating conditions	103
6.3.2	VCAP external capacitor	106
6.3.3	SMPS step-down converter	106
6.3.4	Operating conditions at power-up / power-down	108
6.3.5	Embedded reset and power control block characteristics	109
6.3.6	Embedded reference voltage	110
6.3.7	Supply current characteristics	111
6.3.8	Wakeup time from low-power modes	131
6.3.9	External clock source characteristics	132
6.3.10	Internal clock source characteristics	136
6.3.11	PLL characteristics	139
6.3.12	Memory characteristics	141
6.3.13	EMC characteristics	142
6.3.14	Absolute maximum ratings (electrical sensitivity)	144
6.3.15	I/O current injection characteristics	145
6.3.16	I/O port characteristics	146
6.3.17	NRST pin characteristics	153

6.3.18	FMC characteristics	153
6.3.19	Quad-SPI interface characteristics	174
6.3.20	Delay block (DLYB) characteristics	177
6.3.21	16-bit ADC characteristics	177
6.3.22	DAC characteristics	186
6.3.23	Voltage reference buffer characteristics	190
6.3.24	Temperature sensor characteristics	191
6.3.25	Temperature and V _{BAT} monitoring	192
6.3.26	Voltage booster for analog switch	192
6.3.27	Comparator characteristics	193
6.3.28	Operational amplifier characteristics	194
6.3.29	Digital filter for Sigma-Delta Modulators (DFSDM) characteristics	196
6.3.30	Camera interface (DCMI) timing specifications	199
6.3.31	LCD-TFT controller (LTDC) characteristics	200
6.3.32	Timer characteristics	202
6.3.33	Communication interfaces	202
7	Package information	222
7.1	Device marking	222
7.2	LQFP144 package information (1A)	223
7.3	LQFP176 package information (1T)	227
7.4	LQFP208 package information (UH)	231
7.5	UFBGA(176+25) package information (A0E7)	234
7.6	TFBGA240+25 package information (A07U)	236
7.7	Thermal characteristics	239
7.7.1	Reference documents	240
8	Ordering information	241
9	Important security notice	242
10	Revision history	243

List of tables

Table 1.	Device summary	2
Table 2.	STM32H755xl features and peripheral counts	14
Table 3.	System vs domain low-power mode	28
Table 4.	DFSDM implementation	37
Table 5.	Timer feature comparison	39
Table 6.	USART features	46
Table 7.	Legend/abbreviations used in the pinout table	59
Table 8.	STM32H755xl pin/ball definition	60
Table 9.	Alternate functions	87
Table 10.	Voltage characteristics	101
Table 11.	Current characteristics	102
Table 12.	Thermal characteristics	102
Table 13.	General operating conditions	103
Table 14.	Supply voltage and maximum frequency configuration	105
Table 15.	VCAP operating conditions	106
Table 16.	Characteristics of SMPS step-down converter external components	107
Table 17.	SMPS step-down converter characteristics for external usage	107
Table 18.	Operating conditions at power-up / power-down (regulator ON)	108
Table 19.	Reset and power control block characteristics	109
Table 20.	Embedded reference voltage	110
Table 21.	Internal reference voltage calibration values	111
Table 22.	Typical and maximum current consumption in Run mode, code with data processing running from ITCM for Cortex-M7 core, and flash memory for Cortex-M4 (ART accelerator ON), LDO regulator ON	112
Table 23.	Typical and maximum current consumption in Run mode, code with data processing running from ITCM for Arm Cortex-M7 and flash memory for Arm Cortex-M4, ART accelerator ON, SMPS regulator	112
Table 24.	Typical and maximum current consumption in Run mode, code with data processing running from flash memory, both cores running, cache ON, ART accelerator ON, LDO regulator ON	113
Table 25.	Typical and maximum current consumption in Run mode, code with data processing running from flash memory, both cores running, cache OFF, ART accelerator OFF, LDO regulator ON	113
Table 26.	Typical and maximum current consumption in Run mode, code with data processing running from ITCM, only Arm Cortex-M7 running, LDO regulator ON	114
Table 27.	Typical and maximum current consumption in Run mode, code with data processing running from ITCM, only Arm Cortex-M7 running, SMPS regulator	115
Table 28.	Typical and maximum current consumption in Run mode, code with data processing running from flash memory, only Arm Cortex-M7 running, cache ON, LDO regulator ON	115
Table 29.	Typical and maximum current consumption in Run mode, code with data processing running from flash memory, only Arm Cortex-M7 running, cache OFF, LDO regulator ON	116
Table 30.	Typical and maximum current consumption batch acquisition mode, LDO regulator ON	116
Table 31.	Typical and maximum current consumption in Run mode, code with data processing running from flash memory, only Arm Cortex-M4 running, ART accelerator ON, LDO regulator ON	117

Table 32.	Typical and maximum current consumption in Run mode, code with data processing running from flash bank 2, only Arm Cortex-M4 running, ART accelerator ON, SMPS regulator	117
Table 33.	Typical and maximum current consumption in Stop, LDO regulator ON	118
Table 34.	Typical and maximum current consumption in Stop, SMPS regulator	119
Table 35.	Typical and maximum current consumption in Sleep mode, LDO regulator ON	120
Table 36.	Typical and maximum current consumption in Sleep mode, SMPS regulator	120
Table 37.	Typical and maximum current consumption in Standby	121
Table 38.	Typical and maximum current consumption in VBAT mode	121
Table 39.	Peripheral current consumption in Run mode	126
Table 40.	Low-power mode wakeup timings	131
Table 41.	High-speed external user clock characteristics	132
Table 42.	Low-speed external user clock characteristics	133
Table 43.	4–48 MHz HSE oscillator characteristics	134
Table 44.	Low-speed external user clock characteristics	135
Table 45.	HSI48 oscillator characteristics	136
Table 46.	HSI oscillator characteristics	137
Table 47.	CSI oscillator characteristics	137
Table 48.	LSI oscillator characteristics	138
Table 49.	PLL characteristics (wide VCO frequency range)	139
Table 50.	PLL characteristics (medium VCO frequency range)	140
Table 51.	Flash memory characteristics	141
Table 52.	Flash memory programming	141
Table 53.	Flash memory endurance and data retention	142
Table 54.	EMS characteristics	142
Table 55.	EMI characteristics for fHSE = 8 MHz and fCPU = 400 MHz	143
Table 56.	ESD absolute maximum ratings	144
Table 57.	Electrical sensitivities	144
Table 58.	I/O current injection susceptibility	145
Table 59.	I/O static characteristics	146
Table 60.	Output voltage characteristics for all I/Os except PC13, PC14, PC15 and PI8	148
Table 61.	Output voltage characteristics for PC13, PC14, PC15 and PI8	149
Table 62.	Output timing characteristics (HSLV OFF)	150
Table 63.	Output timing characteristics (HSLV ON)	152
Table 64.	NRST pin characteristics	153
Table 65.	Asynchronous non-multiplexed SRAM/PSRAM/NOR read timings	155
Table 66.	Asynchronous non-multiplexed SRAM/PSRAM/NOR read-NWAIT timings	155
Table 67.	Asynchronous non-multiplexed SRAM/PSRAM/NOR write timings	157
Table 68.	Asynchronous non-multiplexed SRAM/PSRAM/NOR write-NWAIT timings	157
Table 69.	Asynchronous multiplexed PSRAM/NOR read timings	159
Table 70.	Asynchronous multiplexed PSRAM/NOR read-NWAIT timings	159
Table 71.	Asynchronous multiplexed PSRAM/NOR write timings	160
Table 72.	Asynchronous multiplexed PSRAM/NOR write-NWAIT timings	160
Table 73.	Synchronous multiplexed NOR/PSRAM read timings	162
Table 74.	Synchronous multiplexed PSRAM write timings	164
Table 75.	Synchronous non-multiplexed NOR/PSRAM read timings	166
Table 76.	Synchronous non-multiplexed PSRAM write timings	168
Table 77.	Switching characteristics for NAND flash read cycles	170
Table 78.	Switching characteristics for NAND flash write cycles	170
Table 79.	SDRAM read timings	172
Table 80.	LPSDR SDRAM read timings	172
Table 81.	SDRAM Write timings	173

Table 82.	LPSDR SDRAM Write timings	174
Table 83.	QUADSPI characteristics in SDR mode	175
Table 84.	QUADSPI characteristics in DDR mode	176
Table 85.	Delay Block characteristics	177
Table 86.	ADC characteristics	177
Table 87.	Minimum sampling time vs R _{AIN}	181
Table 88.	ADC accuracy	183
Table 89.	DAC characteristics	186
Table 90.	DAC accuracy	188
Table 91.	VREFBUF characteristics	190
Table 92.	Temperature sensor characteristics	191
Table 93.	Temperature sensor calibration values	191
Table 94.	V _{BAT} monitoring characteristics	192
Table 95.	V _{BAT} charging characteristics	192
Table 96.	Temperature monitoring characteristics	192
Table 97.	Voltage booster for analog switch characteristics	192
Table 98.	COMP characteristics	193
Table 99.	Operational amplifier characteristics	194
Table 100.	DFSDM measured timing - 1.62-3.6 V	197
Table 101.	DCMI characteristics	199
Table 102.	LTDC characteristics	200
Table 103.	TIMx characteristics	202
Table 104.	Minimum i2c_ker_ck frequency in all I2C modes	203
Table 105.	I2C analog filter characteristics	203
Table 106.	USART (SPI mode) characteristics	204
Table 107.	SPI dynamic characteristics	206
Table 108.	I ² S dynamic characteristics	209
Table 109.	SAI characteristics	210
Table 110.	MDIO Slave timing parameters	212
Table 111.	Dynamics characteristics: SD / MMC characteristics, VDD = 2.7 to 3.6 V	213
Table 112.	Dynamics characteristics: eMMC characteristics VDD = 1.71V to 1.9V	214
Table 113.	USB OTG_FS electrical characteristics	216
Table 114.	Dynamics characteristics: USB ULPI	216
Table 115.	Dynamics characteristics: Ethernet MAC signals for SMI	217
Table 116.	Dynamics characteristics: Ethernet MAC signals for RMII	218
Table 117.	Dynamics characteristics: Ethernet MAC signals for MII	219
Table 118.	Dynamics JTAG characteristics	220
Table 119.	Dynamics SWD characteristics:	220
Table 120.	LQFP144 - Mechanical data	224
Table 121.	LQFP176 - Mechanical data	228
Table 122.	LQFP208 - Mechanical data	232
Table 123.	UFBGA(176+25) - Mechanical data	234
Table 124.	UFBGA(176+25) - Example of PCB design rules (0.65 mm pitch BGA)	235
Table 125.	TFBGA240+25 - Mechanical data	237
Table 126.	TFBGA240+25 - Tolerance of form and position	237
Table 127.	Tolerance of form and position definitions	238
Table 128.	TFBGA240+25 - Example of PCB design rules	239
Table 129.	Thermal characteristics	240
Table 130.	Document revision history	243

List of figures

Figure 1.	STM32H755xl block diagram	17
Figure 2.	TFBGA240+25 ball assignment differences	18
Figure 3.	ART accelerator schematic and environment	23
Figure 4.	Power-up/power-down sequence	25
Figure 5.	STM32H755xl bus matrix	30
Figure 6.	LQFP144 pinout	54
Figure 7.	LQFP176 pinout	55
Figure 8.	UFBGA176+25 ballout	56
Figure 9.	LQFP208 pinout	57
Figure 10.	TFBGA240+25 ballout	58
Figure 11.	Pin loading conditions	99
Figure 12.	Pin input voltage	99
Figure 13.	Power supply scheme	100
Figure 14.	Current consumption measurement scheme	101
Figure 15.	External capacitor C_{EXT}	106
Figure 16.	External components for SMPS step-down converter	107
Figure 17.	Typical SMPS efficiency (%) vs load current (A) in Run mode at $T_J = 30\text{ }^{\circ}\text{C}$	122
Figure 18.	Typical SMPS efficiency (%) vs load current (A) in Run mode at $T_J = TJ_{max}$	122
Figure 19.	Typical SMPS efficiency (%) vs load current (A) in low-power mode at $T_J = 30\text{ }^{\circ}\text{C}$	123
Figure 20.	Typical SMPS efficiency (%) vs load current (A) in low-power mode at $T_J = TJ_{max}$	124
Figure 21.	High-speed external clock source AC timing diagram	132
Figure 22.	Low-speed external clock source AC timing diagram	133
Figure 23.	Typical application with an 8 MHz crystal	135
Figure 24.	Typical application with a 32.768 kHz crystal	136
Figure 25.	VIL/VIH for all I/Os except BOOT0	147
Figure 26.	Recommended NRST pin protection	153
Figure 27.	Asynchronous non-multiplexed SRAM/PSRAM/NOR read waveforms	154
Figure 28.	Asynchronous non-multiplexed SRAM/PSRAM/NOR write waveforms	156
Figure 29.	Asynchronous multiplexed PSRAM/NOR read waveforms	158
Figure 30.	Synchronous multiplexed NOR/PSRAM read timings	161
Figure 31.	Synchronous multiplexed PSRAM write timings	163
Figure 32.	Synchronous non-multiplexed NOR/PSRAM read timings	165
Figure 33.	Synchronous non-multiplexed PSRAM write timings	167
Figure 34.	NAND controller waveforms for read access	169
Figure 35.	NAND controller waveforms for write access	170
Figure 36.	SDRAM read access waveforms ($CL = 1$)	171
Figure 37.	SDRAM write access waveforms	173
Figure 38.	QUADSPI timing diagram - SDR mode	176
Figure 39.	Quad-SPI timing diagram - DDR mode	177
Figure 40.	ADC accuracy characteristics	184
Figure 41.	Typical connection diagram when using the ADC with FT/TT pins featuring analog switch function	184
Figure 42.	Power supply and reference decoupling (V_{REF+} not connected to V_{DDA})	185
Figure 43.	Power supply and reference decoupling (V_{REF+} connected to V_{DDA})	185
Figure 44.	12-bit buffered /non-buffered DAC	189
Figure 45.	Channel transceiver timing diagrams	198
Figure 46.	DCMI timing diagram	199
Figure 47.	LCD-TFT horizontal timing diagram	201

Figure 48.	LCD-TFT vertical timing diagram	201
Figure 49.	USART timing diagram in SPI master mode.	204
Figure 50.	USART timing diagram in SPI slave mode	205
Figure 51.	SPI timing diagram - slave mode and CPHA = 0	207
Figure 52.	SPI timing diagram - slave mode and CPHA = 1	207
Figure 53.	SPI timing diagram - master mode	208
Figure 54.	I ² S slave timing diagram (Philips protocol) ⁽¹⁾	209
Figure 55.	I ² S master timing diagram (Philips protocol) ⁽¹⁾	210
Figure 56.	SAI master timing waveforms	212
Figure 57.	SAI slave timing waveforms	212
Figure 58.	MDIO Slave timing diagram	213
Figure 59.	SDIO high-speed mode	215
Figure 60.	SD default mode	215
Figure 61.	DDR mode	215
Figure 62.	ULPI timing diagram	217
Figure 63.	Ethernet SMI timing diagram	218
Figure 64.	Ethernet RMII timing diagram	218
Figure 65.	Ethernet MII timing diagram	219
Figure 66.	JTAG timing diagram	220
Figure 67.	SWD timing diagram	221
Figure 68.	LQFP144 - Outline ⁽¹⁵⁾	223
Figure 69.	LQFP144 - Footprint example	226
Figure 70.	LQFP176 - Outline ⁽¹⁵⁾	227
Figure 71.	LQFP176 - Footprint example	230
Figure 72.	LQFP208 - Outline ⁽¹⁵⁾	231
Figure 73.	LQFP208 - footprint example	233
Figure 74.	UFBGA(176+25) - Outline	234
Figure 75.	UFBGA(176+25) - Footprint example	235
Figure 76.	TFBGA240+25 - Outline	236
Figure 77.	TFBGA240+25 - Footprint example	239

1 Introduction

This document provides information on STM32H755xl microcontrollers, such as description, functional overview, pin assignment and definition, electrical characteristics, packaging, and ordering information.

This document should be read in conjunction with the STM32H755xl reference manual (RM0399), available from the STMicroelectronics website www.st.com.

For information on the device errata with respect to the datasheet and reference manual, refer to the STM32H755xl errata sheet (ES0445), available on the STMicroelectronics website www.st.com.

For information on the Arm® Cortex®-M7 core and Arm® Cortex®-M4 core, please refer to the Cortex®-M7 Technical Reference Manual, available from the <http://www.arm.com> website.

arm

Note: Arm and Cortex are registered trademarks of Arm Limited (or its subsidiaries or affiliates) in the US and/or elsewhere.

The Arm word and logo are trademarks of Arm Limited (or its subsidiaries) in the US and/or elsewhere. All rights reserved.

2 Description

STM32H755xl devices are based on the high-performance Arm® Cortex®-M7 and Cortex®-M4 32-bit RISC cores. The Cortex®-M7 core operates at up to 480 MHz and the Cortex®-M4 core at up to 240 MHz. Both cores feature a floating point unit (FPU) which supports Arm® single- and double-precision (Cortex®-M7 core) operations and conversions (IEEE 754 compliant), including a full set of DSP instructions and a memory protection unit (MPU) to enhance application security.

STM32H755xl devices incorporate high-speed embedded memories with a dual-bank flash memory of 2 Mbytes, up to 1 Mbyte of RAM (including 192 Kbytes of TCM RAM, up to 864 Kbytes of user SRAM and 4 Kbytes of backup SRAM), as well as an extensive range of enhanced I/Os and peripherals connected to APB buses, AHB buses, 2x32-bit multi-AHB bus matrix and a multi layer AXI interconnect supporting internal and external memory access.

All the devices offer three ADCs, two DACs, two ultra-low power comparators, a low-power RTC, a high-resolution timer, 12 general-purpose 16-bit timers, two PWM timers for motor control, five low-power timers, a true random number generator (RNG), and a cryptographic acceleration cell. The devices support four digital filters for external sigma-delta modulators (DFSDM). They also feature standard and advanced communication interfaces.

- Standard peripherals
 - Four I²Cs
 - Four USARTs, four UARTs and one LPUART
 - Six SPIs, three I2Ss in Half-duplex mode. To achieve audio class accuracy, the I2S peripherals can be clocked by a dedicated internal audio PLL or by an external clock to allow synchronization.
 - Four SAI serial audio interfaces
 - One SPDIFRX interface
 - One SWPPI (Single Wire Protocol Master Interface)
 - Management Data Input/Output (MDIO) slaves
 - Two SDMMC interfaces
 - A USB OTG full-speed and a USB OTG high-speed interface with full-speed capability (with the ULPI)
 - One FDCAN plus one TT-FDCAN interface
 - An Ethernet interface
 - Chrom-ART Accelerator
 - HDMI-CEC
- Advanced peripherals including
 - A flexible memory control (FMC) interface
 - A Quad-SPI flash memory interface
 - A camera interface for CMOS sensors
 - An LCD-TFT display controller
 - A JPEG hardware compressor/decompressor

Refer to [Table 2: STM32H755xl features and peripheral counts](#) for the list of peripherals available on each part number.

STM32H755xl devices operate in the –40 to +85 °C temperature range from a 1.62 to 3.6 V power supply. The supply voltage can drop down to 1.62 V by using an external power supervisor (see [Section 3.5.2: Power supply supervisor](#)) and connecting the PDR_ON pin to V_{SS}. Otherwise the supply voltage must stay above 1.71 V with the embedded power voltage detector enabled.

Dedicated supply inputs for USB (OTG_FS and OTG_HS) are available on all packages to allow a greater power supply choice.

A comprehensive set of power-saving modes allows the design of low-power applications.

STM32H755xl devices are offered in 5 packages ranging from 144 pins to 240 pins/balls. The set of included peripherals changes with the device chosen.

These features make STM32H755xl microcontrollers suitable for a wide range of applications:

- Motor drive and application control
- Medical equipment
- Industrial applications: PLC, inverters, circuit breakers
- Printers, and scanners
- Alarm systems, video intercom, and HVAC
- Home audio appliances
- Mobile applications, Internet of Things
- Wearable devices: smart watches.

[Figure 1](#) shows the device block diagram.

Table 2. STM32H755xl features and peripheral counts

Peripherals	STM32H755ZI	STM32H755II	STM32H755BI	STM32H755 XI			
Flash memory in Kbytes	2 x 1 Mbyte						
SRAM in Kbytes	SRAM mapped onto AXI bus	512					
	SRAM1 (D2 domain)	128					
	SRAM2 (D2 domain)	128					
	SRAM3 (D2 domain)	32					
	SRAM4 (D3 domain)	64					
TCM RAM in Kbytes	ITCM RAM (instruction)	64					
	DTCM RAM (data)	128					
Backup SRAM (Kbytes)	4						
FMC	Yes						
General-purpose input/outputs	97	119/128	148	168			
Quad-SPI	Yes						
Ethernet	Yes						

Table 2. STM32H755xl features and peripheral counts (continued)

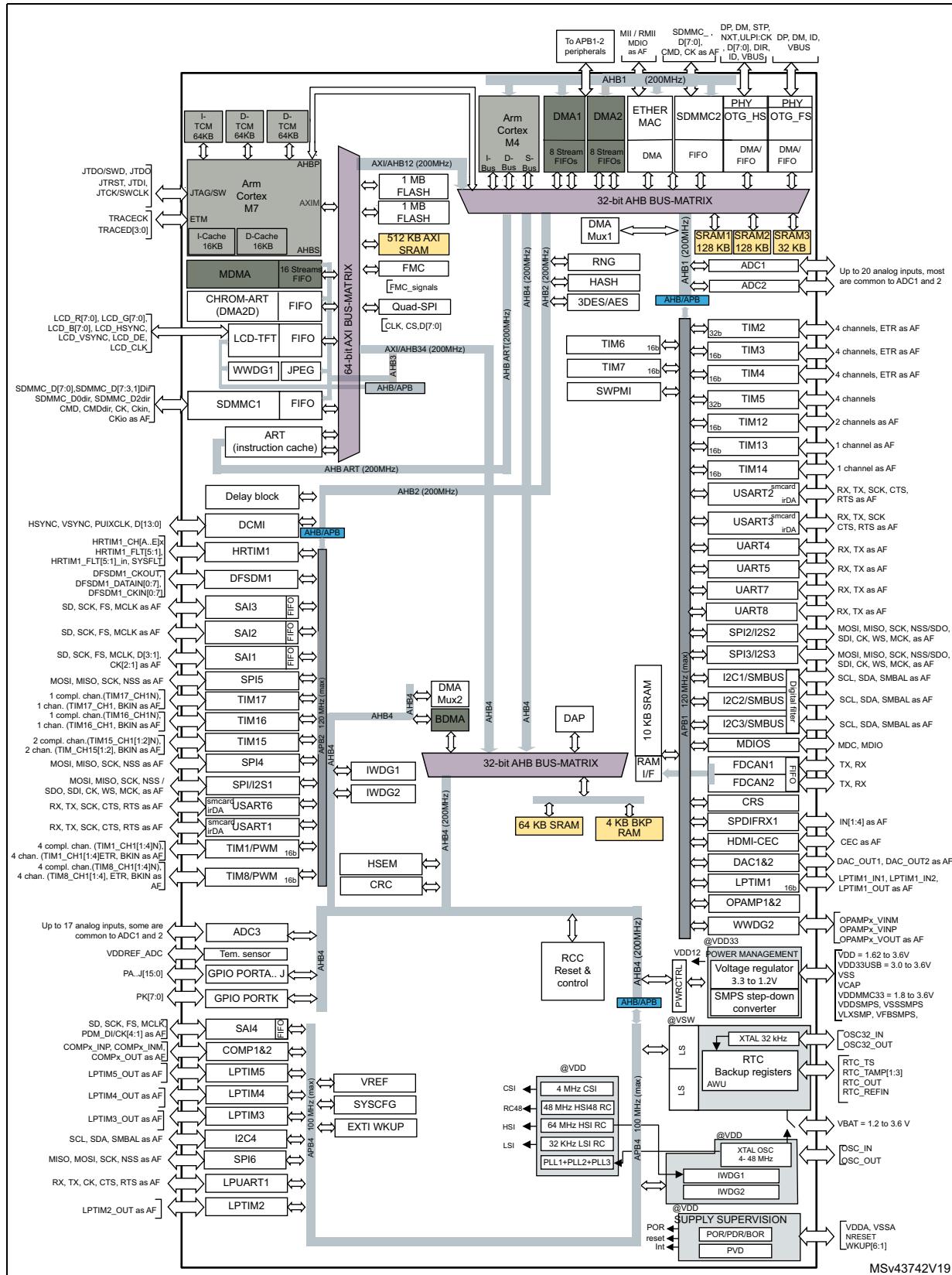
Peripherals		STM32H755ZI	STM32H755II	STM32H755BI	STM32H755 XI	
Timers	High-resolution	1				
	General-purpose	10				
	Advanced-control (PWM)	2				
	Basic	2				
	Low-power	5				
Wakeup pins	4	6				
	2	3				
Random number generator	Yes					
Cryptographic accelerator	Yes					
Communication interfaces	SPI / I2S	6/3 ⁽¹⁾				
	I2C	4				
	USART/ UART/ LPUART	4/4/ 1				
	SAI	4				
	SPDIFRX	4 inputs				
	SWPFI	Yes				
	MDIO	Yes				
	SDMMC	2				
	FDCAN/TT-FDCAN	1/1				
	USB OTG_FS	Yes				
USB OTG_HS	Yes					
	Yes					
Camera interface	Yes					
LCD-TFT	Yes					
JPEG Codec	Yes					
Chrom-ART Accelerator (DMA2D)	Yes					
16-bit ADCs	3					
	2	2	4	2	4	
	6	9	9	9	9	
	15	17	23	21	23	
12-bit DAC	Yes					
	2					
Comparators	2					
Operational amplifiers	2					
DFSDM	Yes					

Table 2. STM32H755xi features and peripheral counts (continued)

Peripherals		STM32H755ZI	STM32H755II	STM32H755BI	STM32H755 XI	
Maximum CPU frequency		480 MHz ⁽²⁾				
		400 MHz ⁽³⁾				
		300 MHz ⁽⁴⁾				
Operating voltage		1.62 to 3.6 V ⁽⁵⁾				
Operating temperatures	Ambient temperature	−40 up to +85 °C ⁽⁶⁾				
	Junction temperature	−40 to + 125 °C				
Extended operating temperatures	Ambient temperature	−40 to + 125 °C ⁽⁴⁾⁽⁷⁾				
	Junction temperature	−40 to + 140 °C ⁽⁸⁾				
Package		LQFP144	LQFP 176	UFBGA 176+ 25	LQFP208	TFBGA240+ 25

1. The SPI1, SPI2 and SPI3 interfaces give the flexibility to work in an exclusive way in either the SPI mode or the I2S audio mode.
2. The product junction temperature must be kept within the −40 to +105 °C range.
3. The product junction temperature must be kept within the −40 to +125 °C range.
4. Up to 300 MHz for STM32H755xxx3 sales types (extended industrial temperature range).
5. V_{DD}/V_{DDA} can drop down to 1.62 V by using an external power supervisor (see [Section 3.5.2: Power supply supervisor](#)) and connecting PDR_ON pin to V_{SS} . Otherwise the supply voltage must stay above 1.71 V with the embedded power voltage detector enabled.
6. Using appropriate cooling methods to guarantee that the maximum junction temperature (125 °C) is not exceeded, the maximum ambient temperature (85°C) can be exceeded.
7. The product junction temperature must be kept within the −40 to +140 °C range.
8. It is mandatory to use the SMPS step-down converter when the maximum junction temperature is higher than 125 °C.

Figure 1. STM32H755xl block diagram



Compatibility throughout the family

STM32H755xl devices are not pin-to-pin compatible with STM32H7x3 devices (single core product line):

- The TFBGA240+25 ballout is compatible with STM32H7x3 devices, except for a few I/O balls as shown in [Figure 2](#).
- LQFP208 and LQFP176 pinouts, as well as UFBGA176+25 ballout are not compatible with STM32H7x3 devices.

Figure 2. TFBGA240+25 ball assignment differences

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
A	VSS	PI6	PI5	PI4	PB5	VDDLD0	VCAP	PK5	PG10	PG9	PD5	PD4	PC10	PA15	PI1	PI0	VSS
B	VBAT	VSS	PI7	PE1	PB6	VSS	PB4	PK4	PG11	PJ15	PD6	PD3	PC11	PA14	PI2	PH15	PH14
C	PC15-OSC32_OUT	PC14-OSC32_IN	PE2	PE0	PB7	PB3	PK6	PK3	PG12	VSS	PD7	PC12	VSS	PI3	PA13	VSS	VDDLD0
D	PE5	PE4	PE3	PB9	PB8	PG15	PK7	PG14	PG13	PJ14	PJ12	PD2	PD0	PA10	PA9	PH13	VCAP
E		PI9	PC13	PI8	PE6	VDD	PDR_ON	BOOT0	VDD	PJ13	VDD	PD1	PC8	PC9	PA8	PA12	PA11
F			PI10	PI11	VDD								PC7	PC6	PG8	PG7	VDD33_USB
G	PF2		PF1	PF0	VDD		VSS	VSS	VSS	VSS		VDD	PG5	PG6	VSS	VDD50_USB	
H	PI12	PI13	PI14	PF3	VDD		VSS	VSS	VSS	VSS		VDD	PG4	PG3	PG2	PK2	
J	PH1-OSC_OUT	PH0-OSC_IN	VSS	PF5	PF4		VSS	VSS	VSS	VSS		VDD	PK0	PK1	VSS	VSS	
K	NRST	PF6	PF7	PF8	VDD		VSS	VSS	VSS	VSS		VDD	PJ11	VSS	NC	NC	
L	VDDA	PC0	PF10	PF9	VDD		VSS	VSS	VSS	VSS		VDD	PJ10	VSS	NC	NC	
M	VREF+	PC1	PC2	PC3	VDD							VDD	PJ9	VSS	NC	NC	
N	VREF-	PH2	PA2	PA1	PA0	PJ0	VDD	VDD	PE10	VDD	VDD	VDD	PJ8	PJ7	PJ6	VSS	NC
P	VSSA	PH3	PH4	PH5	PI15	PJ1	PF13	PF14	PE9	PE11	PB10	PB11	PH10	PH11	PD15	PD14	VDD
R	PC2_C	PC3_C	PA6	VSS	PA7	PB2	PF12	VSS	PF15	PE12	PE15	PJ5	PH9	PH12	PD11	PD12	PD13
T	PA0_C	PA1_C	PA5	PC4	PB1	PJ2	PF11	PG0	PE8	PE13	PH6	VSS	PH8	PB12	PB15	PD10	PD9
U	VSS	PA3	PA4	PC5	PB0	PJ3	PJ4	PG1	PE7	PE14	VCAP	VDDLD0	PH7	PB13	PB14	PD8	VSS

STM32H7x5				STM32H7x3											
<table border="1" style="display: inline-table; vertical-align: middle;"> <tr><td>VLX SMPS</td><td>PI9</td></tr> <tr><td>VDD SMPS</td><td>VSS SMPS</td></tr> <tr><td>PF2</td><td>VFB SMPS</td></tr> </table>		VLX SMPS	PI9	VDD SMPS	VSS SMPS	PF2	VFB SMPS	<table border="1" style="display: inline-table; vertical-align: middle;"> <tr><td>NC</td><td>PI9</td></tr> <tr><td>NC</td><td>NC</td></tr> <tr><td>PF2</td><td>NC</td></tr> </table>		NC	PI9	NC	NC	PF2	NC
VLX SMPS	PI9														
VDD SMPS	VSS SMPS														
PF2	VFB SMPS														
NC	PI9														
NC	NC														
PF2	NC														
MSv48801V2															

- The balls highlighted in gray correspond to different signals on STM32H755xl and STM32H7x3 devices.

3 Functional overview

3.1 Dual Arm® Cortex® cores

The industrial STM32H755xl devices embed two Arm® cores, a Cortex®-M7 and a Cortex®-M4. The Cortex®-M4 offers optimal performance for real-time applications while the Cortex®-M7 core can execute high-performance tasks in parallel.

The two cores belong to separate power domains. This allows designing gradual high-power efficiency solutions in combination with the low-power modes already available on all STM32 microcontrollers.

3.1.1 Arm® Cortex®-M7 with FPU

The Arm® Cortex®-M7 with double-precision FPU processor is the latest generation of Arm processors for embedded systems. It was developed to provide a low-cost platform that meets the needs of MCU implementation, with a reduced pin count and optimized power consumption, while delivering outstanding computational performance and low interrupt latency.

The Cortex®-M7 processor is a highly efficient high-performance featuring:

- Six-stage dual-issue pipeline
- Dynamic branch prediction
- Harvard architecture with L1 caches (16 Kbytes of I-cache and 16 Kbytes of D-cache)
- 64-bit AXI interface
- 64-bit ITCM interface
- 2x32-bit DTCM interfaces

The following memory interfaces are supported:

- Separate Instruction and Data buses (Harvard Architecture) to optimize CPU latency
- Tightly Coupled Memory (TCM) interface designed for fast and deterministic SRAM accesses
- AXI Bus interface to optimize Burst transfers
- Dedicated low-latency AHB-Lite peripheral bus (AHBP) to connect to peripherals.

The processor supports a set of DSP instructions which allow efficient signal processing and complex algorithm execution.

It also supports single and double precision FPU (floating point unit) speeds up software development by using metalanguage development tools, while avoiding saturation.

Figure 1 shows the general block diagram of the STM32H755xl family.

Note: Cortex®-M7 with FPU core is binary compatible with the Cortex®-M4 core.

3.1.2 Arm® Cortex®-M4 with FPU

The Arm® Cortex®-M4 processor is a high-performance embedded processor which supports DSP instructions. It was developed to provide an optimized power consumption MCU, while delivering outstanding computational performance and low interrupt latency.

The Arm® Cortex®-M4 processor is a highly efficient MCU featuring:

- 3-stage pipeline with branch prediction
- Harvard architecture
- 32-bit System (S-BUS) interface
- 32-bit I-BUS interface
- 32-bit D-BUS interface

The Arm® Cortex®-M4 processor also features a dedicated hardware adaptive real-time accelerator (ART Accelerator). This is an instruction cache memory composed of sixty-four 256-bit lines, a 256-bit cache buffer connected to the 64-bit AXI interface and a 32-bit interface for non-cacheable accesses.

3.2 Memory protection unit (MPU)

The devices feature two memory protection units. Each MPU manages the CPU access rights and the attributes of the system resources. It has to be programmed and enabled before use. Its main purposes are to prevent an untrusted user program to accidentally corrupt data used by the OS and/or by a privileged task, but also to protect data processes or read-protect memory regions.

The MPU defines access rules for privileged accesses and user program accesses. It allows defining up to 16 protected regions that can in turn be divided into up to 8 independent subregions, where region address, size, and attributes can be configured. The protection area ranges from 32 bytes to 4 Gbytes of addressable memory.

When an unauthorized access is performed, a memory management exception is generated.

3.3 Memories

3.3.1 Embedded flash memory

The STM32H755xl devices embed 2 Mbytes of flash memory that can be used for storing programs and data.

The flash memory is organized as 266-bit flash words memory that can be used for storing both code and data constants. Each word consists of:

- One flash word (8 words, 32 bytes or 256 bits)
- 10 ECC bits.

The flash memory is divided into two independent banks. Each bank is organized as follows:

- 1 Mbyte of user flash memory block containing eight user sectors of 128 Kbytes (4 K flash memory words)
- 128 Kbytes of System flash memory from which the device can boot
- 2 Kbytes (64 flash words) of user option bytes for user configuration

3.3.2 Secure access mode

In addition to other typical memory protection mechanism (RDP, PCROP), STM32H755xI devices introduce the Secure access mode, a new enhanced security feature. This mode allows developing user-defined secure services by ensuring, on the one hand code and data protection and on the other hand code safe execution.

Two types of secure services are available:

- STMicroelectronics Root Secure Services:

These services are embedded in System memory. They provide a secure solution for firmware and third-party modules installation. These services rely on cryptographic algorithms based on a device unique private key.

- User-defined secure services:

These services are embedded in user flash memory. Examples of user secure services are proprietary user firmware update solution, secure flash integrity check or any other sensitive applications that require a high level of protection.

The secure firmware is embedded in specific user flash memory areas configured through option bytes.

Secure services are executed just after a reset and preempt all other applications to guarantee protected and safe execution. Once executed, the corresponding code and data are no more accessible.

The above secure services are available only for Cortex®-M7 core operating in Secure access mode. The other masters cannot access the option bytes involved in Secure access mode settings or the flash secured areas.

3.3.3 Embedded SRAM

All devices feature around 1 Mbyte of RAM with hardware ECC. The RAM is divided as follows:

- 512 Kbytes of AXI-SRAM mapped onto AXI bus on D1 domain.
- SRAM1 mapped on D2 domain: 128 Kbytes
- SRAM2 mapped on D2 domain: 128 Kbytes
- SRAM3 mapped on D2 domain: 32 Kbytes
- SRAM4 mapped on D3 domain: 64 Kbytes
- 4 Kbytes of backup SRAM

The content of this area is protected against possible unwanted write accesses, and is retained in Standby or V_{BAT} mode.

- RAM mapped to TCM interface (ITCM and DTCM):

Both ITCM and DTCM RAMs are 0 wait state memories. They can be accessed either from the Arm® Cortex®-M7 CPU or the MDMA (even in Sleep mode) through a specific AHB slave of the Cortex®-M7(AHBS):

- 64 Kbytes of ITCM-RAM (instruction RAM)

This RAM is connected to ITCM 64-bit interface designed for execution of critical real-times routines by the Cortex®-M7.

- 128 Kbytes of DTCM-RAM (2x 64-Kbyte DTCM-RAMs on 2x32-bit DTCM ports)

The DTCM-RAM could be used for critical real-time data, such as interrupt service routines or stack/heap memory. Both DTCM-RAMs can be used in parallel (for load/store operations) thanks to the Cortex®-M7 dual issue capability.

The MDMA can be used to load code or data in ITCM or DTCM RAMs.

Error code correction (ECC)

Over the product lifetime, and/or due to external events such as radiations, invalid bits in memories may occur. They can be detected and corrected by ECC. This is an expected behavior that has to be managed at final-application software level in order to ensure data integrity through ECC algorithms implementation.

SRAM data are protected by ECC:

- 7 ECC bits are added per 32-bit word.
- 8 ECC bits are added per 64-bit word for AXI-SRAM and ITCM-RAM.

The ECC mechanism is based on the SECDED algorithm. It supports single-error correction and double-error detection.

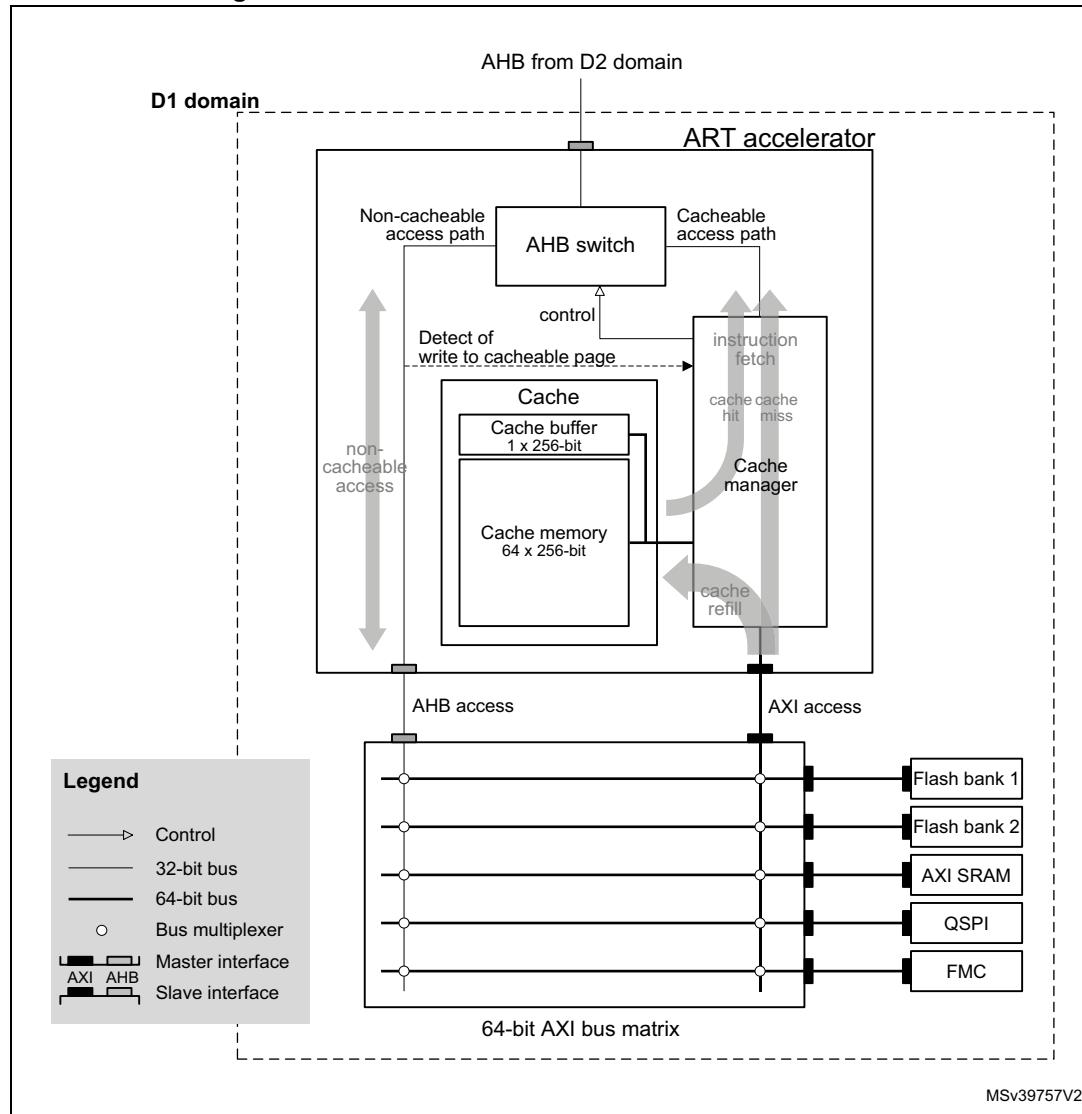
3.3.4 ART accelerator

The ART (adaptive real-time) accelerator block speeds up instruction fetch accesses of the Cortex®-M4 core from D1-domain internal memories (flash memory bank 1, flash memory bank 2, AXI SRAM) and from D1-domain external memories attached via Quad-SPI controller and Flexible memory controller (FMC).

The ART accelerator is a 256-bit cache line using 64-bit WRAP4 accesses from the 64-bit AXI D1 domain. The acceleration is achieved by loading selected code into an embedded cache and making it instantly available to Cortex®-M4 core, thus avoiding latency due to memory wait states.

Figure 3. shows the block schematic and the environment of the ART accelerator.

Figure 3. ART accelerator schematic and environment



3.4 Boot modes

By default, the boot codes are executed simultaneously by both cores. However, by programming the appropriate flash user option byte, it is possible to boot from one core while clock-gating the other core.

At startup, the boot memory space is selected by the BOOT pin and BOOT_ADDx option bytes, allowing to program any boot memory address from 0x0000 0000 to 0x3FFF FFFF which includes:

- All flash address space
- Flash memory and SRAMs (except for ITCM /DTCM RAMs which cannot be accessed by the Cortex®-M4 core)

The bootloader is located in non-user System memory. It is used to reprogram the flash memory through one of the following interfaces: FDCAN, USART, I2C, SPI, USB-DFU, FDCAN. Refer to *STM32 microcontroller System memory Boot mode* application note (AN2606) for details.

3.5 Power supply management

3.5.1 Power supply scheme

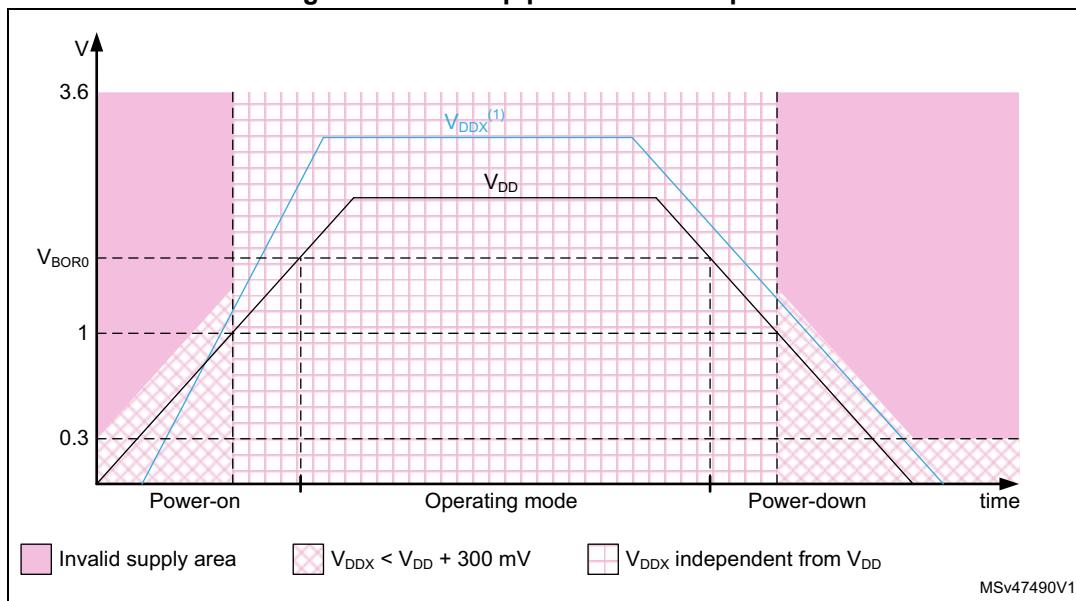
STM32H755xl power supply voltages are the following:

- $V_{DD} = 1.62$ to 3.6 V: external power supply for I/Os, provided externally through V_{DD} pins.
- $V_{DDLDO} = 1.62$ to 3.6 V: supply voltage for the internal regulator supplying V_{CORE} .
- $V_{DDA} = 1.62$ to 3.6 V: external analog power supplies for ADC, DAC, COMP and OPAMP.
- $V_{DD33USB}$ and $V_{DD50USB}$:
 $V_{DD50USB}$ can be supplied through the USB cable to generate the $V_{DD33USB}$ via the USB internal regulator. This allows supporting a V_{DD} supply different from 3.3 V.
The USB regulator can be bypassed to supply directly $V_{DD33USB}$ with $V_{DD33USB} \approx 3.3$ V (see electrical characteristics).
- $V_{BAT} = 1.2$ to 3.6 V: power supply for the V_{SW} domain when V_{DD} is not present.
- V_{CAP} : V_{CORE} supply voltage, which values depend on voltage scaling (1.0 V, 1.1 V, 1.2 V or 1.35 V). They are configured through VOS bits in PWR_D3CR register and ODEN bit in the SYSCFG_PWRCR register. The V_{CORE} domain is split into the following power domains that can be independently switch off.
 - D1 domain containing some peripherals and the Cortex®-M7 core.
 - D2 domain containing a large part of the peripherals and the Cortex®-M4 core.
 - D3 domain containing some peripherals and the system control.
- $V_{DDSMPS} = 1.62$ V to 3.6 V: SMPS step-down converter power supply
 V_{DDSMPS} must be kept at the same voltage level as V_{DD} .
- V_{LXSMPS} = SMPS step-down converter output coupled to an inductor.
- $V_{FBSMPS} = V_{CORE}$, 1.8 V or 2.5 V external SMPS step-down converter feedback voltage sense input.

During power-up and power-down phases, the following power sequence requirements must be respected (see [Figure 4](#)):

- When V_{DD} is below 1 V, other power supplies (V_{DDA} , $V_{DD33USB}$, $V_{DD50USB}$) must remain below $V_{DD} + 300$ mV.
- When V_{DD} is above 1 V, all power supplies are independent (except for V_{DDSMPS} , which must remain at the same level as V_{DD}).

During the power-down phase, V_{DD} can temporarily become lower than other supplies only if the energy provided to the microcontroller remains below 1 mJ. This allows external decoupling capacitors to be discharged with different time constants during the power-down transient phase.

Figure 4. Power-up/power-down sequence

1. V_{DDX} refers to any power supply among V_{DDA} , $V_{DD33\text{USB}}$, $V_{DD50\text{USB}}$.
2. V_{DD} and V_{DDSMPS} must be wired together into order to follow the same voltage sequence.

3.5.2 Power supply supervisor

The devices have an integrated power-on reset (POR)/ power-down reset (PDR) circuitry coupled with a Brownout reset (BOR) circuitry:

- Power-on reset (POR)

The POR supervisor monitors V_{DD} power supply and compares it to a fixed threshold. The devices remain in Reset mode when V_{DD} is below this threshold.
- Power-down reset (PDR)

The PDR supervisor monitors V_{DD} power supply. A reset is generated when V_{DD} drops below a fixed threshold. The PDR supervisor can be enabled/disabled through PDR_ON pin.
- Brownout reset (BOR)

The BOR supervisor monitors V_{DD} power supply. Three BOR thresholds (from 2.1 to 2.7 V) can be configured through option bytes. A reset is generated when V_{DD} drops below this threshold.

3.5.3 Voltage regulator (SMPS step-down converter and LDO)

The same voltage regulator supplies the 3 power domains (D1, D2 and D3). D1 and D2 can be independently switched off.

Voltage regulator output can be adjusted according to application needs through 6 power supply levels:

- Run mode (VOS0 to VOS3)
 - Scale 0: boosted performance (available only with LDO regulator)
 - Scale 1: high performance
 - Scale 2: medium performance and consumption
 - Scale 3: optimized performance and low-power consumption

Note:

For STM32H755xxx3 sales types (industrial temperature range) the voltage regulator output can be set only to VOS2 or VOS3 in Run mode (VOS0 and VOS1 are not allowed for the extended temperature range when respectively $T_J > 105^\circ\text{C}$ and $T_J > 125^\circ\text{C}$).

- Stop mode (SVOS3 to SVOS5)
 - Scale 3: peripheral with wakeup from Stop mode capabilities (UART, SPI, I2C, LPTIM) are operational
 - Scale 4 and 5 where the peripheral with wakeup from Stop mode is disabled
The peripheral functionality is disabled but wakeup from Stop mode is possible through GPIO or asynchronous interrupt.

3.5.4 SMPS step-down converter

The built-in SMPS step-down converter is a highly power-efficient DC/DC non-linear switching regulator that provides lower power consumption than a conventional voltage regulator (LDO).

The SMPS step-down converter can be used for the following purposes:

- Direct supply of the V_{CORE} domain
 - the SMPS step-down converter operating modes follow the device system operating modes (Run, Stop, Standby).
 - the SMPS step-down converter output voltage are set according to the selected VOS and SVOS bits (voltage scaling)
- Delivery of an intermediate voltage level to supply the internal voltage regulator (LDO)
 - SMPS step-down converter operating modes

When the SDEXTHP bit is equal to 0 in the PWR_CR3 register, the SMPS step-down converter follows the device system operating modes (Run, Stop and Standby).

When the SDEXTHP bit is equal to 1 in PWR_CR3, the SMPS step-down converter is forced to High-performance mode and does not follow the device system operating modes (Run, Stop and Standby).
 - The SMPS step-down converter output equals 1.8 V or 2.5 V according to the selected SD level
- Delivery of an external supply
 - The SMPS step-down converter is forced to High-performance mode (provided SDEXTHP bit is equal to 1 in PWR_CR3)
 - The SMPS step-down converter output equals 1.8 V or 2.5 V according to the selected SD level

3.6 Low-power strategy

There are several ways to reduce power consumption on STM32H755xl:

- Select the SMPS step-down converter as V_{CORE} supply voltage source, as it allows to enhance power efficiency.
- Select the adequate voltage scaling
- Decrease the dynamic power consumption by slowing down the system clocks even in Run mode, and by individually clock gating the peripherals that are not used.
- Save power consumption when one or both CPUs are idle, by selecting among the available low-power mode according to the user application needs. This allows achieving the best compromise between short startup time, low-power consumption, as well as available wakeup sources.

The devices feature several low-power modes:

- CSleep (CPU clock stopped)
- CStop (CPU sub-system clock stopped)
- DStop (Domain bus matrix clock stopped)
- Stop (System clock stopped)
- DStandby (Domain powered down)
- Standby (System powered down)

CSleep and CStop low-power modes are entered by the MCU when executing the WFI (Wait for Interrupt) or WFE (Wait for Event) instructions, or when the SLEEPONEXIT bit of the Cortex[®]-Mx core is set after returning from an interrupt service routine.

A domain can enter low-power mode (DStop or DStandby) when the processor, its subsystem and the peripherals allocated in the domain enter low-power mode. For instance D1 or D2 domain enters DStop/DStandby mode when the CPU of the domain is in CStop mode AND the other CPU has no peripheral allocated in that domain, or if it is in CStop mode too. D3 domain can enter DStop/DStandby mode if both core subsystems do not have active peripherals in D3 domain, and D3 is not forced in Run mode.

If part of the domain is not in low-power mode, the domain remains in the current mode.

Finally the system can enter Stop or Standby when all EXTI wakeup sources are cleared and the power domains are in DStop or DStandby mode.

The clock system can be re-initialized by a master CPU (either the Cortex®-M4 or -M7) after exiting Stop mode while the slave CPU is held in low-power mode. Once the master CPU has re-initialized the system, the slave CPU can receive a wakeup interrupt and proceed with the interrupt service routine.

Table 3. System vs domain low-power mode

System power mode	D1 domain power mode	D2 domain power mode	D3 domain power mode
Run	DRun/DStop/DStandby	DRun/DStop/DStandby	DRun
Stop	DStop/DStandby	DStop/DStandby	DStop
Standby	DStandby	DStandby	DStandby

3.7 Reset and clock controller (RCC)

The clock and reset controller is located in D3 domain. The RCC manages the generation of all the clocks, as well as the clock gating and the control of the system and peripheral resets. It provides a high flexibility in the choice of clock sources and allows to apply clock ratios to improve the power consumption. In addition, on some communication peripherals that are capable to work with two different clock domains (either a bus interface clock or a kernel peripheral clock), the system frequency can be changed without modifying the baudrate.

3.7.1 Clock management

The devices embed four internal oscillators, two oscillators with external crystal or resonator, two internal oscillators with fast startup time and three PLLs.

The RCC receives the following clock source inputs:

- Internal oscillators:
 - 64 MHz HSI clock
 - 48 MHz RC oscillator
 - 4 MHz CSI clock
 - 32 kHz LSI clock
- External oscillators:
 - HSE clock: 4-50 MHz (generated from an external source) or 4-48 MHz(generated from a crystal/ceramic resonator)
 - LSE clock: 32.768 kHz

The RCC provides three PLLs: one for system clock, two for kernel clocks.

The system starts on the HSI clock. The user application can then select the clock configuration.

3.7.2 System reset sources

Power-on reset initializes all registers while system reset reinitializes the system except for the debug, part of the RCC and power controller status registers, as well as the backup power domain.

A system reset is generated in the following cases:

- Power-on reset (pwr_por_rst)
- Brownout reset
- Low level on NRST pin (external reset)
- Independent watchdog 1 (from D1 domain)
- Independent watchdog 2 (from D2 domain)
- Window watchdog 1 (from D1 domain)
- Window watchdog 2 (from D2 domain)
- Software reset
- Low-power mode security reset
- Exit from Standby

3.8 General-purpose input/outputs (GPIOs)

Each of the GPIO pins can be configured by software as output (push-pull or open-drain, with or without pull-up or pull-down), as input (floating, with or without pull-up or pull-down) or as peripheral alternate function. Most of the GPIO pins are shared with digital or analog alternate functions. All GPIOs are high-current-capable and have speed selection to better manage internal noise, power consumption and electromagnetic emission.

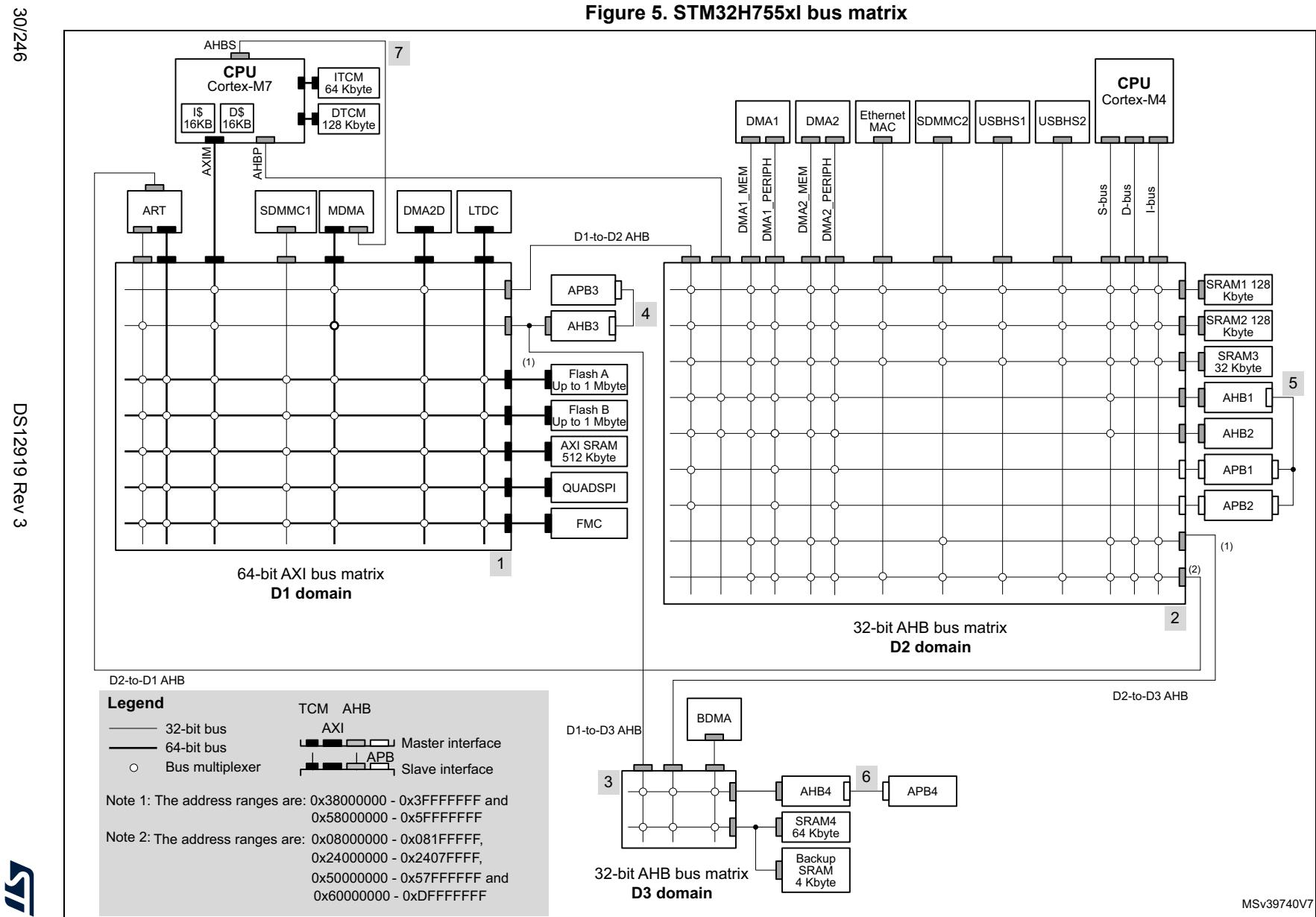
After reset, all GPIOs (except debug pins) are in Analog mode to reduce power consumption (refer to GPIOs register reset values in the device reference manual).

The I/O configuration can be locked if needed by following a specific sequence in order to avoid spurious writing to the I/Os registers.

3.9 Bus-interconnect matrix

The devices feature an AXI bus matrix, two AHB bus matrices and bus bridges that allow interconnecting bus masters with bus slaves (see [Figure 5](#)).

Figure 5. STM32H755xI bus matrix



3.10 DMA controllers

The devices feature four DMA instances to unload CPU activity:

- A master direct memory access (MDMA)

The MDMA is a high-speed DMA controller, which is in charge of all types of memory transfers (peripheral to memory, memory to memory, memory to peripheral), without any CPU action. It features a master AXI interface and a dedicated AHB interface to access Cortex®-M7 TCM memories.

The MDMA is located in D1 domain. It is able to interface with the other DMA controllers located in D2 domain to extend the standard DMA capabilities, or can manage peripheral DMA requests directly.

Each of the 16 channels can perform single block transfers, repeated block transfers and linked list transfers.

- Two dual-port DMAs (DMA1, DMA2) located in D2 domain, with FIFO and request router capabilities.
- One basic DMA (BDMA) located in D3 domain, with request router capabilities.

The DMA request router could be considered as an extension of the DMA controller. It routes the DMA peripheral requests to the DMA controller itself. This allowing managing the DMA requests with a high flexibility, maximizing the number of DMA requests that run concurrently, as well as generating DMA requests from peripheral output trigger or DMA event.

3.11 Chrom-ART Accelerator (DMA2D)

The Chrom-Art Accelerator (DMA2D) is a graphical accelerator which offers advanced bit blitting, row data copy and pixel format conversion. It supports the following functions:

- Rectangle filling with a fixed color
- Rectangle copy
- Rectangle copy with pixel format conversion
- Rectangle composition with blending and pixel format conversion

Various image format coding are supported, from indirect 4bpp color mode up to 32bpp direct color. It embeds dedicated memory to store color lookup tables. The DMA2D also supports block based YCbCr to handle JPEG decoder output.

An interrupt can be generated when an operation is complete or at a programmed watermark.

All the operations are fully automatized and are running independently from the CPU or the DMAs.

3.12 Nested vectored interrupt controller (NVIC)

Both Cortex®-M7 (CPU1) and Cortex®-M4 (CPU2) cores have their own nested vector interrupt controller (respectively NVIC1 and NVIC2). Each NVIC instance is able to manage 16 priority levels, and handle up to 150 maskable interrupt channels plus the 16 interrupt lines of the Cortex®-M7 with FPU core.

- Closely coupled NVIC gives low-latency interrupt processing
- Interrupt entry vector table address passed directly to the core
- Allows early processing of interrupts
- Processing of late arriving, higher-priority interrupts
- Support tail chaining
- Processor context automatically saved on interrupt entry, and restored on interrupt exit with no instruction overhead

This hardware block provides flexible interrupt management features with minimum interrupt latency.

3.13 Extended interrupt and event controller (EXTI)

The EXTI controller performs interrupt and event management. In addition, it can wake up the processors, power domains and/or D3 domain from Stop mode.

The EXTI handles up to 89 independent event/interrupt lines split as 28 configurable events and 61 direct events (including two interrupt lines for inter-core management).

Configurable events have dedicated pending flags, active edge selection, and software trigger capable.

Direct events provide interrupts or events from peripherals having a status flag.

3.14 Cyclic redundancy check calculation unit (CRC)

The CRC (cyclic redundancy check) calculation unit is used to get a CRC code using a programmable polynomial.

Among other applications, CRC-based techniques are used to verify data transmission or storage integrity. In the scope of the EN/IEC 60335-1 standard, they offer a means of verifying the flash memory integrity. The CRC calculation unit helps compute a signature of the software during runtime, to be compared with a reference signature generated at link-time and stored at a given memory location.

3.15 Flexible memory controller (FMC)

The FMC controller main features are the following:

- Interface with static-memory mapped devices including:
 - Static random access memory (SRAM)
 - NOR flash memory/OneNAND flash memory
 - PSRAM (4 memory banks)
 - NAND flash memory with ECC hardware to check up to 8 Kbytes of data
- Interface with synchronous DRAM (SDRAM/Mobile LPDDR SDRAM) memories
- 8-,16-,32-bit data bus width
- Independent Chip Select control for each memory bank
- Independent configuration for each memory bank
- Write FIFO
- Read FIFO for SDRAM controller
- The maximum FMC_CLK/FMC_SDCLK frequency for synchronous accesses is the FMC kernel clock divided by 2.

3.16 Quad-SPI memory interface (QUADSPI)

All devices embed a Quad-SPI memory interface, which is a specialized communication interface targeting Single, Dual or Quad-SPI flash memories. It supports both single and double datarate operations.

It can operate in any of the following modes:

- Direct mode through registers
- External flash status register polling mode
- Memory mapped mode.

Up to 256 Mbytes of external flash memory can be mapped, and 8-, 16- and 32-bit data accesses are supported as well as code execution.

The opcode and the frame format are fully programmable.

3.17 Analog-to-digital converters (ADCs)

The STM32H755xl devices embed three analog-to-digital converters, which resolution can be configured to 16, 14, 12, 10 or 8 bits.

Each ADC shares up to 20 external channels, performing conversions in the Single-shot or Scan mode. In Scan mode, automatic conversion is performed on a selected group of analog inputs.

Additional logic functions embedded in the ADC interface allow:

- Simultaneous sample and hold
- Interleaved sample and hold

The ADC can be served by the DMA controller, thus allowing to automatically transfer ADC converted values to a destination location without any software action.

In addition, an analog watchdog feature can accurately monitor the converted voltage of one, some or all selected channels. An interrupt is generated when the converted voltage is outside the programmed thresholds.

To synchronize A/D conversion and timers, the ADCs could be triggered by any of TIM1, TIM2, TIM3, TIM4, TIM6, TIM8, TIM15, HRTIM1 and LPTIM1 timer.

3.18 Temperature sensor

STM32H755xl devices embed a temperature sensor that generates a voltage (V_{TS}) that varies linearly with the temperature. This temperature sensor is internally connected to ADC3_IN18. The conversion range is between 1.7 V and 3.6 V. It can measure the device junction temperature ranging from -40 up to $+140$ °C.

The temperature sensor have a good linearity, but it has to be calibrated to obtain a good overall accuracy of the temperature measurement. As the temperature sensor offset varies from chip to chip due to process variation, the uncalibrated internal temperature sensor is suitable for applications that detect temperature changes only. To improve the accuracy of the temperature sensor measurement, each device is individually factory-calibrated by ST. The temperature sensor factory calibration data are stored by ST in the System memory area, which is accessible in Read-only mode.

3.19 V_{BAT} operation

The V_{BAT} power domain contains the RTC, the backup registers and the backup SRAM.

To optimize battery duration, this power domain is supplied by V_{DD} when available or by the voltage applied on V_{BAT} pin (when V_{DD} supply is not present). V_{BAT} power is switched when the PDR detects that V_{DD} dropped below the PDR level.

The voltage on the V_{BAT} pin could be provided by an external battery, a supercapacitor or directly by V_{DD} , in which case, the V_{BAT} mode is not functional.

V_{BAT} operation is activated when V_{DD} is not present.

The V_{BAT} pin supplies the RTC, the backup registers and the backup SRAM.

Note: When the microcontroller is supplied from V_{BAT} , external interrupts and RTC alarm/events do not exit it from V_{BAT} operation.

When PDR_ON pin is connected to V_{SS} (Internal Reset OFF), the V_{BAT} functionality is no more available and V_{BAT} pin should be connected to V_{DD} .

3.20 Digital-to-analog converters (DAC)

The two 12-bit buffered DAC channels can be used to convert two digital signals into two analog voltage signal outputs.

This dual digital Interface supports the following features:

- two DAC converters: one for each output channel
- 8-bit or 12-bit monotonic output
- left or right data alignment in 12-bit mode
- synchronized update capability
- noise-wave generation
- triangular-wave generation
- dual DAC channel independent or simultaneous conversions
- DMA capability for each channel including DMA underrun error detection
- external triggers for conversion
- input voltage reference V_{REF+} or internal VREFBUF reference.

The DAC channels are triggered through the timer update outputs that are also connected to different DMA streams.

3.21 Ultra-low-power comparators (COMP)

STM32H755xl devices embed two rail-to-rail comparators (COMP1 and COMP2). They feature programmable reference voltage (internal or external), hysteresis and speed (low speed for low-power) as well as selectable output polarity.

The reference voltage can be one of the following:

- An external I/O
- A DAC output channel
- An internal reference voltage or submultiple (1/4, 1/2, 3/4).

All comparators can wake up from Stop mode, generate interrupts and breaks for the timers, and be combined into a window comparator.

3.22 Operational amplifiers (OPAMP)

STM32H755xl devices embed two rail-to-rail operational amplifiers (OPAMP1 and OPAMP2) with external or internal follower routing and PGA capability.

The operational amplifier main features are:

- PGA with a non-inverting gain ranging of 2, 4, 8 or 16 or inverting gain ranging of -1, -3, -7 or -15
- One positive input connected to DAC
- Output connected to internal ADC
- Low input bias current down to 1 nA
- Low input offset voltage down to 1.5 mV
- Gain bandwidth up to 7.3 MHz

The devices embeds two operational amplifiers (OPAMP1 and OPAMP2) with two inputs and one output each. These three I/Os can be connected to the external pins, thus enabling any type of external interconnections. The operational amplifiers can be configured internally as a follower, as an amplifier with a non-inverting gain ranging from 2 to 16 or with inverting gain ranging from -1 to -15.

3.23 Digital filter for sigma-delta modulators (DFSDM)

The devices embed one DFSDM with 4 digital filters modules and 8 external input serial channels (transceivers) or alternately 8 internal parallel inputs support.

The DFSDM peripheral is dedicated to interface the external $\Sigma\Delta$ modulators to microcontroller and then to perform digital filtering of the received data streams (which represent analog value on $\Sigma\Delta$ modulators inputs). DFSDM can also interface PDM (Pulse Density Modulation) microphones and perform PDM to PCM conversion and filtering in hardware. DFSDM features optional parallel data stream inputs from internal ADC peripherals or microcontroller memory (through DMA/CPU transfers into DFSDM).

DFSDM transceivers support several serial interface formats (to support various $\Sigma\Delta$ modulators). DFSDM digital filter modules perform digital processing according user selected filter parameters with up to 24-bit final ADC resolution.

The DFSDM peripheral supports:

- 8 multiplexed input digital serial channels:
 - configurable SPI interface to connect various SD modulator(s)
 - configurable Manchester coded 1 wire interface support
 - PDM (Pulse Density Modulation) microphone input support
 - maximum input clock frequency up to 20 MHz (10 MHz for Manchester coding)
 - clock output for SD modulator(s): 0..20 MHz
- alternative inputs from 8 internal digital parallel channels (up to 16 bit input resolution):
 - internal sources: ADC data or memory data streams (DMA)
- 4 digital filter modules with adjustable digital signal processing:
 - Sinc^X filter: filter order/type (1..5), oversampling ratio (up to 1..1024)
 - integrator: oversampling ratio (1..256)
- up to 24-bit output data resolution, signed output data format
- automatic data offset correction (offset stored in register by user)
- continuous or single conversion
- start-of-conversion triggered by:
 - software trigger
 - internal timers
 - external events
 - start-of-conversion synchronously with first digital filter module (DFSDM0)
- analog watchdog feature:
 - low value and high value data threshold registers
 - dedicated configurable Sincx digital filter (order = 1..3, oversampling ratio = 1..32)
 - input from final output data or from selected input digital serial channels
 - continuous monitoring independently from standard conversion

- short circuit detector to detect saturated analog input values (bottom and top range):
 - up to 8-bit counter to detect 1..256 consecutive 0's or 1's on serial data stream
 - monitoring continuously each input serial channel
- break signal generation on analog watchdog event or on short circuit detector event
- extremes detector:
 - storage of minimum and maximum values of final conversion data
 - refreshed by software
- DMA capability to read the final conversion data
- interrupts: end of conversion, overrun, analog watchdog, short circuit, input serial channel clock absence
- “regular” or “injected” conversions:
 - “regular” conversions can be requested at any time or even in Continuous mode without having any impact on the timing of “injected” conversions
 - “injected” conversions for precise timing and with high conversion priority

Table 4. DFSDM implementation

DFSDM features	DFSDM1
Number of filters	4
Number of input transceivers/channels	8
Internal ADC parallel input	X
Number of external triggers	16
Regular channel information in identification register	X

3.24 Digital camera interface (DCMI)

The devices embed a camera interface that can connect with camera modules and CMOS sensors through an 8-bit to 14-bit parallel interface, to receive video data. The camera interface can achieve a data transfer rate up to 105 Mbyte/s using a 60 MHz pixel clock. It features:

- Programmable polarity for the input pixel clock and synchronization signals
- Parallel data communication can be 8-, 10-, 12- or 14-bit
- Supports 8-, 10-, 12- and 14-bit progressive video monochrome or raw bayer format, YCbCr 4:2:2 progressive video, RGB 565 progressive video or compressed data (like JPEG)
- Supports Continuous mode or Snapshot (a single frame) mode
- Capability to automatically crop the image

3.25 LCD-TFT controller

The LCD-TFT display controller provides a 24-bit parallel digital RGB (Red, Green, Blue) and delivers all signals to interface directly to a broad range of LCD and TFT panels up to XGA (1024x768) resolution with the following features:

- 2 display layers with dedicated FIFO (64x64-bit)
- Color Look-Up table (CLUT) up to 256 colors (256x24-bit) per layer
- Up to 8 input color formats selectable per layer
- Flexible blending between two layers using alpha value (per pixel or constant)
- Flexible programmable parameters for each layer
- Color keying (transparency color)
- Up to 4 programmable interrupt events
- AXI master interface with burst of 16 words

3.26 JPEG Codec (JPEG)

The JPEG Codec can encode and decode a JPEG stream as defined in the **ISO/IEC 10918-1** specification. It provides an fast and simple hardware compressor and decompressor of JPEG images with full management of JPEG headers.

The JPEG codec main features are as follows:

- 8-bit/channel pixel depths
- Single clock per pixel encoding and decoding
- Support for JPEG header generation and parsing
- Up to four programmable quantization tables
- Fully programmable Huffman tables (two AC and two DC)
- Fully programmable minimum coded unit (MCU)
- Encode/decode support (non simultaneous)
- Single clock Huffman coding and decoding
- Two-channel interface: Pixel/Compress In, Pixel/Compressed Out
- Support for single greyscale component
- Ability to enable/disable header processing
- Fully synchronous design
- Configuration for High-speed decode mode

3.27 True random number generator (RNG)

The RNG is a true random number generator that provides full entropy outputs to the application as 32-bit samples. It is composed of a live entropy source (analog) and an internal conditioning component.

3.28 Cryptographic acceleration (CRYP and HASH)

The devices embed a cryptographic processor that supports the advanced cryptographic algorithms usually required to ensure confidentiality, authentication, data integrity and non-repudiation when exchanging messages with a peer:

- Encryption/Decryption
 - DES/TDES (data encryption standard/triple data encryption standard): ECB (electronic codebook) and CBC (cipher block chaining) chaining algorithms, 64-, 128- or 192-bit key
 - AES (advanced encryption standard): ECB, CBC, GCM, CCM, and CTR (Counter mode) chaining algorithms, 128, 192 or 256-bit key
- Universal HASH
 - SHA-1 and SHA-2 (secure HASH algorithms)
 - MD5
 - HMAC

The cryptographic accelerator supports DMA request generation.

3.29 Timers and watchdogs

The devices include one high-resolution timer, two advanced-control timers, ten general-purpose timers, two basic timers, five low-power timers, two watchdogs and a SysTick timer.

All timer counters can be frozen in Debug mode.

[Table 5](#) compares the features of the advanced-control, general-purpose and basic timers.

Table 5. Timer feature comparison

Timer type	Timer	Counter resolution	Counter type	Prescaler factor	DMA request generation	Capture/compare channels	Complementary output	Max interface clock (MHz)	Max timer clock (MHz) ⁽¹⁾⁽²⁾
High-resolution timer	HRTIM1	16-bit	Up	/1 /2 /4 (x2 x4 x8 x16 x32, with DLL)	Yes	10	Yes	480 ⁽²⁾	480
Advanced -control	TIM1, TIM8	16-bit	Up, Down, Up/down	Any integer between 1 and 65536	Yes	4	Yes	120	240

Table 5. Timer feature comparison (continued)

Timer type	Timer	Counter resolution	Counter type	Prescaler factor	DMA request generation	Capture/compare channels	Complementary output	Max interface clock (MHz)	Max timer clock (MHz) (1)(2)
General purpose	TIM2, TIM5	32-bit	Up, Down, Up/down	Any integer between 1 and 65536	Yes	4	No	120	240
	TIM3, TIM4	16-bit	Up, Down, Up/down	Any integer between 1 and 65536	Yes	4	No	120	240
	TIM12	16-bit	Up	Any integer between 1 and 65536	No	2	No	120	240
	TIM13, TIM14	16-bit	Up	Any integer between 1 and 65536	No	1	No	120	240
	TIM15	16-bit	Up	Any integer between 1 and 65536	Yes	2	1	120	240
	TIM16, TIM17	16-bit	Up	Any integer between 1 and 65536	Yes	1	1	120	240
Basic	TIM6, TIM7	16-bit	Up	Any integer between 1 and 65536	Yes	0	No	120	240
Low-power timer	LPTIM1, LPTIM2, LPTIM3, LPTIM4, LPTIM5	16-bit	Up	1, 2, 4, 8, 16, 32, 64, 128	No	0	No	120	240

1. The maximum timer clock is up to 480 MHz depending on TIMPRE bit in the RCC_CFGR register and D2PRE1/2 bits in RCC_D2CFG register.
2. On STM32H755xxx3 sales types (extended industrial temperature range), the maximum clock frequency is 300 MHz for the high-resolution timer and 150 MHz for the other timers.

3.29.1 High-resolution timer (HRTIM1)

The high-resolution timer (HRTIM1) allows generating digital signals with high-accuracy timings, such as PWM or phase-shifted pulses.

It consists of 6 timers, 1 master and 5 slaves, totaling 10 high-resolution outputs, which can be coupled by pairs for deadtime insertion. It also features 5 fault inputs for protection purposes and 10 inputs to handle external events such as current limitation, zero voltage or zero current switching.

The HRTIM1 timer is made of a digital kernel clocked at 480 MHz^(a). The high-resolution is available on the 10 outputs in all operating modes: variable duty cycle, variable frequency, and constant ON time.

The slave timers can be combined to control multiswitch complex converters or operate independently to manage multiple independent converters.

The waveforms are defined by a combination of user-defined timings and external events such as analog or digital feedbacks signals.

HRTIM1 timer includes options for blanking and filtering out spurious events or faults. It also offers specific modes and features to offload the CPU: DMA requests, Burst mode controller, Push-pull and Resonant mode.

It supports many topologies including LLC, Full bridge phase shifted, buck or boost converters, either in voltage or current mode, as well as lighting application (fluorescent or LED). It can also be used as a general purpose timer, for instance to achieve high-resolution PWM-emulated DAC.

a. Up to 300 MHz for STM32H755xxx3 sales types (extended industrial temperature range).

3.29.2 Advanced-control timers (TIM1, TIM8)

The advanced-control timers (TIM1, TIM8) can be seen as three-phase PWM generators multiplexed on 6 channels. They have complementary PWM outputs with programmable inserted dead times. They can also be considered as complete general-purpose timers. Their 4 independent channels can be used for:

- Input capture
- Output compare
- PWM generation (Edge- or Center-aligned modes)
- One-pulse mode output

If configured as standard 16-bit timers, they have the same features as the general-purpose TIMx timers. If configured as 16-bit PWM generators, they have full modulation capability (0-100%).

The advanced-control timer can work together with the TIMx timers via the Timer Link feature for synchronization or event chaining.

TIM1 and TIM8 support independent DMA request generation.

3.29.3 General-purpose timers (TIMx)

There are ten synchronizable general-purpose timers embedded in the STM32H755xl devices (see [Table 5](#) for differences).

- **TIM2, TIM3, TIM4, TIM5**

The devices include 4 full-featured general-purpose timers: TIM2, TIM3, TIM4 and TIM5. TIM2 and TIM5 are based on a 32-bit auto-reload up/downcounter and a 16-bit prescaler while TIM3 and TIM4 are based on a 16-bit auto-reload up/downcounter and a 16-bit prescaler. All timers feature 4 independent channels for input capture/output compare, PWM or One-pulse mode output. This gives up to 16 input capture/output compare/PWMs on the largest packages.

TIM2, TIM3, TIM4 and TIM5 general-purpose timers can work together, or with the other general-purpose timers and the advanced-control timers TIM1 and TIM8 via the Timer Link feature for synchronization or event chaining.

Any of these general-purpose timers can be used to generate PWM outputs.

TIM2, TIM3, TIM4, TIM5 all have independent DMA request generation. They are capable of handling quadrature (incremental) encoder signals and the digital outputs from 1 to 4 hall-effect sensors.

- **TIM12, TIM13, TIM14, TIM15, TIM16, TIM17**

These timers are based on a 16-bit auto-reload upcounter and a 16-bit prescaler. TIM13, TIM14, TIM16 and TIM17 feature one independent channel, whereas TIM12 and TIM15 have two independent channels for input capture/output compare, PWM or One-pulse mode output. They can be synchronized with the TIM2, TIM3, TIM4, TIM5 full-featured general-purpose timers or used as simple timebases.

3.29.4 Basic timers TIM6 and TIM7

These timers are mainly used for DAC trigger and waveform generation. They can also be used as a generic 16-bit time base.

TIM6 and TIM7 support independent DMA request generation.

3.29.5 Low-power timers (LPTIM1, LPTIM2, LPTIM3, LPTIM4, LPTIM5)

The low-power timers have an independent clock and is running also in Stop mode if it is clocked by LSE, LSI or an external clock. It is able to wakeup the devices from Stop mode.

This low-power timer supports the following features:

- 16-bit up counter with 16-bit autoreload register
- 16-bit compare register
- Configurable output: pulse, PWM
- Continuous / One-shot mode
- Selectable software / hardware input trigger
- Selectable clock source:
- Internal clock source: LSE, LSI, HSI or APB clock
- External clock source over LPTIM input (working even with no internal clock source running, used by the Pulse Counter Application)
- Programmable digital glitch filter
- Encoder mode

3.29.6 Independent watchdogs

There are two independent watchdogs, one per domain. Each independent watchdog is based on a 12-bit downcounter and 8-bit prescaler. It is clocked from an independent 32 kHz internal RC and as it operates independently from the main clock, it can operate in Stop and Standby modes. It can be used either as a watchdog to reset the device when a problem occurs, or as a free-running timer for application timeout management. It is hardware- or software-configurable through the option bytes.

3.29.7 Window watchdogs

There are two window watchdogs, one per domain. Each window watchdog is based on a 7-bit downcounter that can be set as free-running. It can be used as a watchdog to reset the device or each respective domain (configurable in the RCC register), when a problem occurs. It is clocked from the main clock. It has an early warning interrupt capability and the counter can be frozen in Debug mode.

3.29.8 SysTick timer

The devices feature two SysTick timers, one per CPU. These timers are dedicated to real-time operating systems, but could also be used as a standard downcounter. It features:

- A 24-bit downcounter
- Autoreload capability
- Maskable system interrupt generation when the counter reaches 0
- Programmable clock source.

3.30 Real-time clock (RTC), backup SRAM and backup registers

The RTC is an independent BCD timer/counter. It supports the following features:

- Calendar with subsecond, seconds, minutes, hours (12 or 24 format), week day, date, month, year, in BCD (binary-coded decimal) format.
- Automatic correction for 28, 29 (leap year), 30, and 31 days of the month.
- Two programmable alarms.
- On-the-fly correction from 1 to 32767 RTC clock pulses. This can be used to synchronize it with a master clock.
- Reference clock detection: a more precise second source clock (50 or 60 Hz) can be used to enhance the calendar precision.
- Digital calibration circuit with 0.95 ppm resolution, to compensate for quartz crystal inaccuracy.
- Three anti-tamper detection pins with programmable filter.
- Timestamp feature which can be used to save the calendar content. This function can be triggered by an event on the timestamp pin, or by a tamper event, or by a switch to V_{BAT} mode.
- 17-bit auto-reload wakeup timer (WUT) for periodic events with programmable resolution and period.

The RTC and the 32 backup registers are supplied through a switch that takes power either from the V_{DD} supply when present or from the V_{BAT} pin.

The backup registers are 32-bit registers used to store 128 bytes of user application data when V_{DD} power is not present. They are not reset by a system or power reset, or when the device wakes up from Standby mode.

The RTC clock sources can be:

- A 32.768 kHz external crystal (LSE)
- An external resonator or oscillator (LSE)
- The internal low-power RC oscillator (LSI, with typical frequency of 32 kHz)
- The high-speed external clock (HSE) divided by 32.

The RTC is functional in V_{BAT} mode and in all low-power modes when it is clocked by the LSE. When clocked by the LSI, the RTC is not functional in V_{BAT} mode, but is functional in all low-power modes.

All RTC events (Alarm, Wakeup Timer, Timestamp or Tamper) can generate an interrupt and wakeup the device from the low-power modes.

3.31 Inter-integrated circuit interface (I2C)

STM32H755xl devices embed four I²C interfaces.

The I²C bus interface handles communications between the microcontroller and the serial I²C bus. It controls all I²C bus-specific sequencing, protocol, arbitration and timing.

The I²C peripheral supports:

- I²C-bus specification and user manual rev. 5 compatibility:
 - Target and controller modes, multicontroller capability
 - Standard-mode (Sm), with a bitrate up to 100 kbit/s
 - Fast-mode (Fm), with a bitrate up to 400 kbit/s
 - Fast-mode Plus (Fm+), with a bitrate up to 1 Mbit/s and 20 mA output drive I/Os
 - 7-bit and 10-bit addressing mode, multiple 7-bit target addresses
 - Programmable setup and hold times
 - Optional clock stretching
- System Management Bus (SMBus) specification rev 2.0 compatibility:
 - Hardware PEC (Packet Error Checking) generation and verification with ACK control
 - Address resolution protocol (ARP) support
 - SMBus alert
- Power System Management Protocol (PMBusTM) specification rev 1.1 compatibility
- Independent clock: a choice of independent clock sources allowing the I²C communication speed to be independent from the PCLK reprogramming.
- Wakeup from Stop mode on address match
- Programmable analog and digital noise filters
- 1-byte buffer with DMA capability

3.32 Universal synchronous/asynchronous receiver transmitter (USART)

STM32H755xl devices have four embedded universal synchronous receiver transmitters (USART1, USART2, USART3 and USART6) and four universal asynchronous receiver transmitters (UART4, UART5, UART7 and UART8). Refer to [Table 6](#) for a summary of USARTx and UARTx features.

These interfaces provide asynchronous communication, IrDA SIR ENDEC support, multiprocessor communication mode, single-wire Half-duplex communication mode and have LIN Master/Slave capability. They provide hardware management of the CTS and RTS signals, and RS485 Driver Enable. They are able to communicate at speeds of up to 12.5 Mbit/s.

USART1, USART2, USART3 and USART6 also provide Smartcard mode (ISO 7816 compliant) and SPI-like communication capability.

The USARTs embed a Transmit FIFO (TXFIFO) and a Receive FIFO (RXFIFO). FIFO mode is enabled by software and is disabled by default.

All USART have a clock domain independent from the CPU clock, allowing the USARTx to wake up the MCU from Stop mode. The wakeup from Stop mode is programmable and can be done on:

- Start bit detection
- Any received data frame
- A specific programmed data frame
- Specific TXFIFO/RXFIFO status when FIFO mode is enabled.

All USART interfaces can be served by the DMA controller.

Table 6. USART features

USART modes/features ⁽¹⁾	USART1/2/3/6	UART4/5/7/8
Hardware flow control for modem	X	X
Continuous communication using DMA	X	X
Multiprocessor communication	X	X
Synchronous SPI mode (master/slave)	X	-
Smartcard mode	X	-
Single-wire Half-duplex communication	X	X
IrDA SIR ENDEC block	X	X
LIN mode	X	X
Dual clock domain and wakeup from low power mode	X	X
Receiver timeout interrupt	X	X
Modbus communication	X	X
Auto baud rate detection	X	X
Driver Enable	X	X
USART data length	7, 8 and 9 bits	
Tx/Rx FIFO	X	X
Tx/Rx FIFO size	16	

1. X = supported.

3.33 Low-power universal asynchronous receiver transmitter (LPUART)

The device embeds one Low-Power UART (LPUART1). The LPUART supports asynchronous serial communication with minimum power consumption. It supports half duplex single wire communication and modem operations (CTS/RTS). It allows multiprocessor communication.

The LPUARTs embed a Transmit FIFO (TXFIFO) and a Receive FIFO (RXFIFO). FIFO mode is enabled by software and is disabled by default.

The LPUART has a clock domain independent from the CPU clock, and can wakeup the system from Stop mode. The wakeup from Stop mode are programmable and can be done on:

- Start bit detection
- Any received data frame
- A specific programmed data frame
- Specific TXFIFO/RXFIFO status when FIFO mode is enabled.

Only a 32.768 kHz clock (LSE) is needed to allow LPUART communication up to 9600 baud. Therefore, even in Stop mode, the LPUART can wait for an incoming frame while having an extremely low energy consumption. Higher speed clock can be used to reach higher baudrates.

LPUART interface can be served by the DMA controller.

3.34 Serial peripheral interfaces (SPI)/integrated interchip sound interfaces (I²S)

The devices feature up to six SPIs (SPI2S1, SPI2S2, SPI2S3, SPI4, SPI5 and SPI6) that allow communicating up to 150 Mbits/s in Master and Slave modes, in Half-duplex, Full-duplex and Simplex modes. The 3-bit prescaler gives 8 master mode frequencies and the frame is configurable from 4 to 16 bits. All SPI interfaces support NSS pulse mode, TI mode, Hardware CRC calculation and 8x 8-bit embedded Rx and Tx FIFOs with DMA capability.

Three standard I²S interfaces (multiplexed with SPI1, SPI2 and SPI3) are available. They can be operated in Master or Slave mode, in Simplex or Full-duplex communication mode, and can be configured to operate with a 16-/32-bit resolution as an input or output channel. Audio sampling frequencies from 8 kHz up to 192 kHz are supported. When either or both of the I²S interfaces is/are configured in Master mode, the master clock can be output to the external DAC/CODEC at 256 times the sampling frequency. All I²S interfaces support 16x 8-bit embedded Rx and Tx FIFOs with DMA capability.

3.35 Serial audio interfaces (SAI)

The devices embed 4 SAIs (SAI1, SAI2, SAI3 and SAI4) that allow designing many stereo or mono audio protocols such as I²S, LSB or MSB-justified, PCM/DSP, TDM or AC'97. An SPDIF output is available when the audio block is configured as a transmitter. To bring this level of flexibility and reconfigurability, the SAI contains two independent audio sub-blocks. Each block has its own clock generator and I/O line controller.

Audio sampling frequencies up to 192 kHz are supported.

In addition, up to 6 microphones can be supported thanks to an embedded PDM interface. The SAI can work in master or slave configuration. The audio sub-blocks can be either receiver or transmitter and can work synchronously or asynchronously (with respect to the other one). The SAI can be connected with other SAIs to work synchronously.

3.36 SPDIFRX Receiver Interface (SPDIFRX)

The SPDIFRX peripheral is designed to receive an S/PDIF flow compliant with IEC-60958 and IEC-61937. These standards support simple stereo streams up to high sample rate, and compressed multi-channel surround sound, such as those defined by Dolby or DTS (up to 5.1).

The main SPDIFRX features are the following:

- Up to 4 inputs available
- Automatic symbol rate detection
- Maximum symbol rate: 12.288 MHz
- Stereo stream from 32 to 192 kHz supported
- Supports Audio IEC-60958 and IEC-61937, consumer applications
- Parity bit management
- Communication using DMA for audio samples
- Communication using DMA for control and user channel information
- Interrupt capabilities

The SPDIFRX receiver provides all the necessary features to detect the symbol rate, and decode the incoming data stream. The user can select the wanted SPDIF input, and when a valid signal will be available, the SPDIFRX will re-sample the incoming signal, decode the Manchester stream, recognize frames, sub-frames and blocks elements. It delivers to the CPU decoded data, and associated status flags.

The SPDIFRX also offers a signal named `spdif_frame_sync`, which toggles at the S/PDIF sub-frame rate that will be used to compute the exact sample rate for clock drift algorithms.

3.37 Single wire protocol master interface (SWPMI)

The Single wire protocol master interface (SWPMI) is the master interface corresponding to the Contactless Frontend (CLF) defined in the ETSI TS 102 613 technical specification. The main features are:

- Full-duplex communication mode
- automatic SWP bus state management (active, suspend, resume)
- configurable bitrate up to 2 Mbit/s
- automatic SOF, EOF and CRC handling

SWPMI can be served by the DMA controller.

3.38 Management Data Input/Output (MDIO) slaves

The devices embed an MDIO slave interface it includes the following features:

- 32 MDIO Registers addresses, each of which is managed using separate input and output data registers:
 - 32 x 16-bit firmware read/write, MDIO read-only output data registers
 - 32 x 16-bit firmware read-only, MDIO write-only input data registers
- Configurable slave (port) address
- Independently maskable interrupts/events:
 - MDIO Register write
 - MDIO Register read
 - MDIO protocol error
- Able to operate in and wake up from Stop mode

3.39 SD/SDIO/MMC card host interfaces (SDMMC)

Two SDMMC host interfaces are available. They support *MultiMediaCard System Specification Version 4.51* in three different databus modes: 1 bit (default), 4 bits and 8 bits.

Both interfaces support the *SD memory card specifications version 4.1.* and the *SDIO card specification version 4.0.* in two different databus modes: 1 bit (default) and 4 bits.

Each SDMMC host interface supports only one SD/SDIO/MMC card at any one time and a stack of MMC Version 4.51 or previous.

The SDMMC host interface embeds a dedicated DMA controller allowing high-speed transfers between the interface and the SRAM.

3.40 Controller area network (FDCAN1, FDCAN2)

The controller area network (CAN) subsystem consists of two CAN modules, a shared message RAM memory and a clock calibration unit.

Both CAN modules (FDCAN1 and FDCAN2) are compliant with ISO 11898-1 (CAN protocol specification version 2.0 part A, B) and CAN FD protocol specification version 1.0.

FDCAN1 supports time triggered CAN (TT-FDCAN) specified in ISO 11898-4, including event synchronized time-triggered communication, global system time, and clock drift compensation. The FDCAN1 contains additional registers, specific to the time triggered feature. The CAN FD option can be used together with event-triggered and time-triggered CAN communication.

A 10-Kbyte message RAM memory implements filters, receive FIFOs, receive buffers, transmit event FIFOs, transmit buffers (and triggers for TT-FDCAN). This message RAM is shared between the two FDCAN1 and FDCAN2 modules.

The common clock calibration unit is optional. It can be used to generate a calibrated clock for both FDCAN1 and FDCAN2 from the HSI internal RC oscillator and the PLL, by evaluating CAN messages received by the FDCAN1.

3.41 Universal serial bus on-the-go high-speed (OTG_HS)

The devices embed two USB OTG high-speed (up to 480 Mbit/s) device/host/OTG peripheral. OTG_HS1 supports both full-speed and high-speed operations, while OTG_HS2 supports only full-speed operations. They both integrate the transceivers for full-speed operation (12 Mbit/s) and are able to operate from the internal HSI48 oscillator. OTG_HS1 features a UTMI low-pin interface (ULPI) for high-speed operation (480 Mbit/s). When using the USB OTG_HS1 in HS mode, an external PHY device connected to the ULPI is required.

The USB OTG HS peripherals are compliant with the USB 2.0 specification and with the OTG 2.0 specification. They have software-configurable endpoint setting and supports suspend/resume. The USB OTG controllers require a dedicated 48 MHz clock that is generated by a PLL connected to the HSE oscillator.

The main features are:

- Combined Rx and Tx FIFO size of 4 Kbytes with dynamic FIFO sizing
- Supports the session request protocol (SRP) and host negotiation protocol (HNP)
- 9 bidirectional endpoints (including EP0)
- 16 host channels with periodic OUT support
- Software configurable to OTG1.3 and OTG2.0 modes of operation
- USB 2.0 LPM (Link Power Management) support
- Battery Charging Specification Revision 1.2 support
- Internal FS OTG PHY support
- External HS or HS OTG operation supporting ULPI in SDR mode (OTG_HS1 only)
The OTG PHY is connected to the microcontroller ULPI port through 12 signals. It can be clocked using the 60 MHz output.
- Internal USB DMA
- HNP/SNP/IP inside (no need for any external resistor)
- For OTG/Host modes, a power switch is needed in case bus-powered devices are connected

3.42 Ethernet MAC interface with dedicated DMA controller (ETH)

The devices provide an IEEE-802.3-2002-compliant media access controller (MAC) for ethernet LAN communications through an industry-standard medium-independent interface (MII) or a reduced medium-independent interface (RMII). The microcontroller requires an external physical interface device (PHY) to connect to the physical LAN bus (twisted-pair, fiber, etc.). The PHY is connected to the device MII port using 17 signals for MII or 9 signals for RMII, and can be clocked using the 25 MHz (MII) from the microcontroller.

The devices include the following features:

- Supports 10 and 100 Mbit/s rates
- Dedicated DMA controller allowing high-speed transfers between the dedicated SRAM and the descriptors
- Tagged MAC frame support (VLAN support)
- Half-duplex (CSMA/CD) and full-duplex operation
- MAC control sublayer (control frames) support
- 32-bit CRC generation and removal
- Several address filtering modes for physical and multicast address (multicast and group addresses)
- 32-bit status code for each transmitted or received frame
- Internal FIFOs to buffer transmit and receive frames. The transmit FIFO and the receive FIFO are both 2 Kbytes.
- Supports hardware PTP (precision time protocol) in accordance with IEEE 1588 2008 (PTP V2) with the time stamp comparator connected to the TIM2 input
- Triggers interrupt when system time becomes greater than target time

3.43 High-definition multimedia interface (HDMI) - consumer electronics control (CEC)

The devices embed a HDMI-CEC controller that provides hardware support for the Consumer Electronics Control (CEC) protocol (Supplement 1 to the HDMI standard).

This protocol provides high-level control functions between all audiovisual products in an environment. It is specified to operate at low speeds with minimum processing and memory overhead. It has a clock domain independent from the CPU clock, allowing the HDMI-CEC controller to wakeup the MCU from Stop mode on data reception.

3.44 Debug infrastructure

The devices offer a comprehensive set of debug and trace features on both cores to support software development and system integration.

- Breakpoint debugging
- Code execution tracing
- Software instrumentation
- JTAG debug port
- Serial-wire debug port
- Trigger input and output
- Serial-wire trace port
- Trace port
- Arm® CoreSight™ debug and trace components

The debug can be controlled via a JTAG/Serial-wire debug access port, using industry standard debugging tools. The debug infrastructure allows debugging one core at a time, or both cores in parallel.

The trace port performs data capture for logging and analysis.

A 4-Kbyte embedded trace FIFO (ETF) allows recording data and sending them to any com port. In Trace mode, the trace is transferred by DMA to system RAM or to a high-speed interface (such as SPI or USB). It can even be monitored by a software running on one of the cores. Unlike hardware FIFO mode, this mode is invasive since it uses system resources which are shared by the processors.

4 Memory mapping

Refer to the product line reference manual for details on the memory mapping as well as the boundary addresses for all peripherals.

5 Pinout, pin description and alternate functions

Figure 6. LQFP144 pinout

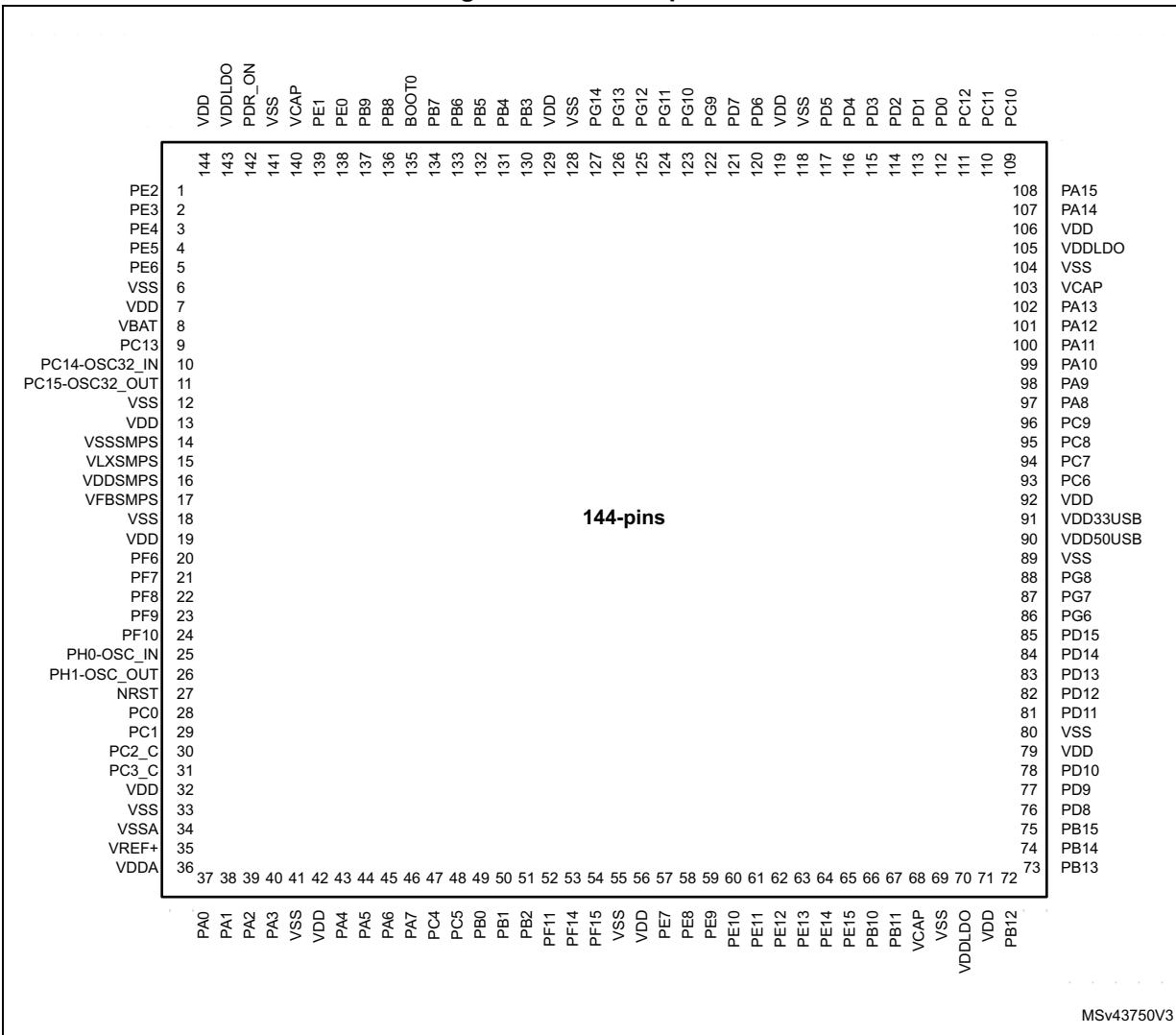
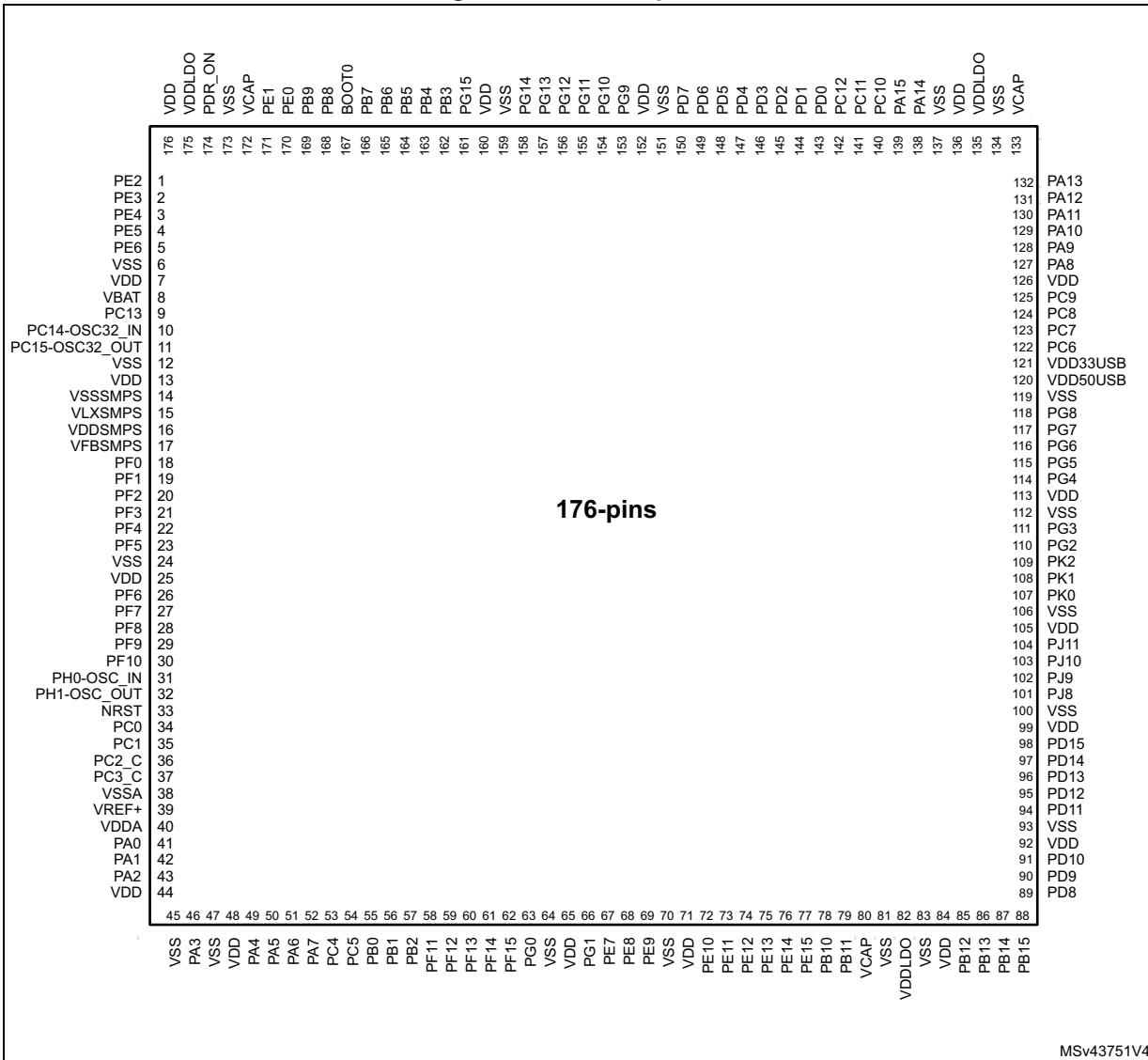


Figure 7. LQFP176 pinout



1. The above figure shows the package top view.

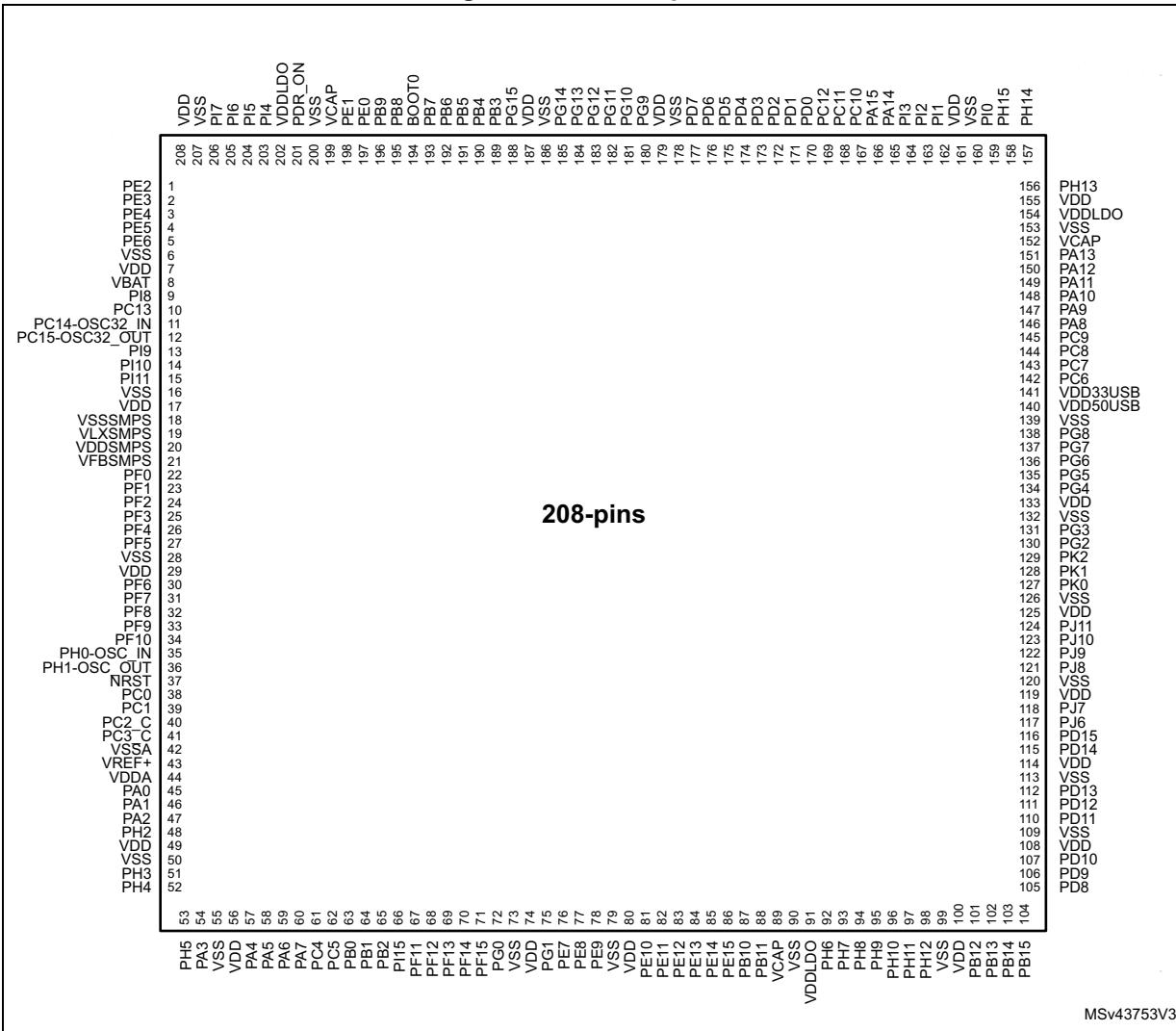
Figure 8. UFBGA176+25 ballout

	1	2	3	4	5	6	7	8	9	10	11	12		13	14	15
A	VSS	PB8	VDD LDO	VCAP	PB6	PB3	PG11	PG9	PD3	PD1	PA15	PA14	VDD LDO	VCAP	VSS	
B	PE4	PE3	PB9	PE0	PB7	PB4	PG13	PD7	PD5	PD2	PC12	PH14	PA13	PA8	PA12	
C	PC13	VSS	PE2	PE1	BOOT0	PB5	PG14	PG10	PD4	PD0	PC11	PC10	PH13	PA10	PA11	
D	PC15-OSC32_OUT	PC14-OSC32_IN	PE5	PDR_ON	VDD	VSS	PG15	PG12	PD6	VSS	VDD	PH15	PA9	PC8	PC7	
E	VSS	VBAT	PE6	VDD								VDD	PC9	PC6	VDD50 USB	
F	VLX SMPS	VSS SMPS	PF1	PF0		VSS	VSS	VSS	VSS	VSS		VSS	VDD33 USB	PG6	PG5	
G	VDD SMPS	VFB SMPS	PF2	VDD		VSS	VSS	VSS	VSS	VSS		PG8	PG7	PG4	PG2	
H	PF6	PF4	PF5	PF3		VSS	VSS	VSS	VSS	VSS		VDD	PG3	PD14	PD13	
J	PH0-OSC_IN	PF8	PF7	PF9		VSS	VSS	VSS	VSS	VSS		PD15	PD11	VSS	PD12	
K	PH1-OSC_OUT	VSS	PF10	VDD		VSS	VSS	VSS	VSS	VSS		VSS	PD9	PB15	PB14	
L	NRST	PC0	PC1	VREF-								VDD	PD10	PD8	PB13	
M	PC2	PC3	VREF+	VDDA	VDD	VSS	PC5	PB1	VDD	VSS	PH7	PE14	PH11	PH9	PB12	
N	PC2_C	PC3_C	VSSA	PH2	PA3	PA7	PF11	PE8	PG1	PF15	PF13	PB10	PH8	PH10	PH12	
P	PA0	PA1	PA1_C	PH4	PA4	PA5	PB2	PG0	PE7	PB11	PF12	PE12	PE13	PE15	PH6	
R	VSS	PA2	PA0_C	PH3	PH5	PC4	PA6	PB0	PE10	PF14	PE9	PE11	VCAP	VDD LDO	VSS	

MSv43752V4

- The above figure shows the package top view.

Figure 9. LQFP208 pinout



1. The above figure shows the package top view.

MSv43753V3

Figure 10. TFBGA240+25 ballout

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
A	VSS	PI6	PI5	PI4	PB5	VDD LDO	VCAP	PK5	PG10	PG9	PD5	PD4	PC10	PA15	PI1	PI0	VSS
B	VBAT	VSS	PI7	PE1	PB6	VSS	PB4	PK4	PG11	PJ15	PD6	PD3	PC11	PA14	PI2	PH15	PH14
C	PC15- OSC32_ OUT	PC14- OSC32_ IN	PE2	PE0	PB7	PB3	PK6	PK3	PG12	VSS	PD7	PC12	VSS	PI3	PA13	VSS	VDD LDO
D	PE5	PE4	PE3	PB9	PB8	PG15	PK7	PG14	PG13	PJ14	PJ12	PD2	PD0	PA10	PA9	PH13	VCAP
E	VLX SMPS	PI9	PC13	PI8	PE6	VDD	PDR _ON	BOOT0	VDD	PJ13	VDD	PD1	PC8	PC9	PA8	PA12	PA11
F	VDD SMPS	VSS SMPS	PI10	PI11	VDD								PC7	PC6	PG8	PG7	VDD 33USB
G	PF2	VFB SMPS	PF1	PF0	VDD		VSS	VSS	VSS	VSS	VSS		VDD	PG5	PG6	VSS	VDD 50USB
H	PI12	PI13	PI14	PF3	VDD		VSS	VSS	VSS	VSS	VSS		VDD	PG4	PG3	PG2	PK2
J	PH1- OSC_ OUT	PH0- OSC IN	VSS	PF5	PF4		VSS	VSS	VSS	VSS	VSS		VDD	PK0	PK1	VSS	VSS
K	NRST	PF6	PF7	PF8	VDD		VSS	VSS	VSS	VSS	VSS		VDD	PJ11	VSS	NC	NC
L	VDDA	PC0	PF10	PF9	VDD		VSS	VSS	VSS	VSS	VSS		VDD	PJ10	VSS	NC	NC
M	VREF+	PC1	PC2	PC3	VDD								VDD	PJ9	VSS	NC	NC
N	VREF-	PH2	PA2	PA1	PA0	PJ0	VDD	VDD	PE10	VDD	VDD	VDD	PJ8	PJ7	PJ6	VSS	NC
P	VSSA	PH3	PH4	PH5	PI15	PJ1	PF13	PF14	PE9	PE11	PB10	PB11	PH10	PH11	PD15	PD14	VDD
R	PC2_C	PC3_C	PA6	VSS	PA7	PB2	PF12	VSS	PF15	PE12	PE15	PK5	PH9	PH12	PD11	PD12	PD13
T	PA0_C	PA1_C	PA5	PC4	PB1	PJ2	PF11	PG0	PE8	PE13	PH6	VSS	PH8	PB12	PB15	PD10	PD9
U	VSS	PA3	PA4	PC5	PB0	PJ3	PJ4	PG1	PE7	PE14	VCAP	VDD LDO	PH7	PB13	PB14	PD8	VSS

MSv43744V3

- The above figure shows the package top view.

Table 7. Legend/abbreviations used in the pinout table

Name	Abbreviation	Definition
Pin name	Unless otherwise specified in brackets below the pin name, the pin function during and after reset is the same as the actual pin name	
Pin type	S	Supply pin
	I	Input only pin
	I/O	Input / output pin
	ANA	Analog-only Input
I/O structure	FT	5 V tolerant I/O
	TT	3.3 V tolerant I/O
	B	Dedicated BOOT0 pin
	RST	Bidirectional reset pin with embedded weak pull-up resistor
	Option for TT and FT I/Os	
	_f	I2C FM+ option
	a	analog option (supplied by V{DDA})
	u	USB option (supplied by $V{DD33USB}$)
	_h	High-speed low-voltage I/O
Notes	Unless otherwise specified by a note, all I/Os are set as floating inputs during and after reset.	
Pin functions	Alternate functions	Functions selected through GPIOx_AFR registers
	Additional functions	Functions directly selected/enabled through peripheral registers

Table 8. STM32H755xl pin/ball definition

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
1	C3	1	1	C3	PE2	I/O	FT_h	-	TRACECLK, SAI1_CK1, SPI4_SCK, SAI1_MCLK_A, SAI4_MCLK_A, QUADSPI_BK1_IO2, SAI4_CK1, ETH_MII_TXD3, FMC_A23, EVENTOUT	-
2	B2	2	2	D3	PE3	I/O	FT_h	-	TRACED0, TIM15_BKIN, SAI1_SD_B, SAI4_SD_B, FMC_A19, EVENTOUT	-
3	B1	3	3	D2	PE4	I/O	FT_h	-	TRACED1, SAI1_D2, DFSDM1_DATIN3, TIM15_CH1N, SPI4_NSS, SAI1_FS_A, SAI4_FS_A, SAI4_D2, FMC_A20, DCMI_D4, LCD_B0, EVENTOUT	-
4	D3	4	4	D1	PE5	I/O	FT_h	-	TRACED2, SAI1_CK2, DFSDM1_CKIN3, TIM15_CH1, SPI4_MISO, SAI1_SCK_A, SAI4_SCK_A, SAI4_CK2, FMC_A21, DCMI_D6, LCD_G0, EVENTOUT	-
5	E3	5	5	E5	PE6	I/O	FT_h	-	TRACED3, TIM1_BKIN2, SAI1_D1, TIM15_CH2, SPI4_MOSI, SAI1_SD_A, SAI4_SD_A, SAI4_D1, SAI2_MCLK_B, TIM1_BKIN2_COMP12, FMC_A22, DCMI_D7, LCD_G1, EVENTOUT	-
6	A1	6	6	A1	VSS	S	-	-	-	-
7	D5	7	7	-	VDD	S	-	-	-	-
8	E2	8	8	B1	VBAT	S	-	-	-	-
-	A15	-	-	B2	VSS	S	-	-	-	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
-	-	-	9	E4	PI8	I/O	FT	-	EVENTOUT	RTC_TAMP2/WK_UP3
9	C1	9	10	E3	PC13	I/O	FT	-	EVENTOUT	RTC_OUT/RTC_TAMP1/RTC_TS/WKUP4
-	C2	-	-	-	VSS	S	-	-	-	-
10	D2	10	11	C2	PC14-OSC32_IN(O SC32_IN) ⁽¹⁾	I/O	FT	-	EVENTOUT	OSC32_IN
11	D1	11	12	C1	PC15-OSC32_OUT(OSC32_OUT) ⁽¹⁾	I/O	FT	-	EVENTOUT	OSC32_OUT
-	-	-	13	E2	PI9	I/O	FT_h	-	UART4_RX, FDCAN1_RX,FMC_D30, LCD_VSYNC, EVENTOUT	-
-	-	-	14	F3	PI10	I/O	FT_h	-	ETH_MII_RX_ER, FMC_D31,LCD_HSYNC, EVENTOUT	-
-	-	-	15	F4	PI11	I/O	FT	-	LCD_G6, OTG_HS_ULPI_DIR, EVENTOUT	WKUP5
12	D10	12	16	A17	VSS	S	-	-	-	-
13	D11	13	17	E6	VDD	S	-	-	-	-
14	F2	14	18	F2	VSSMPS	S	-	-	-	-
15	F1	15	19	E1	VLXSMPS	S	-	-	-	-
16	G1	16	20	F1	VDDSMPS	S	-	-	-	-
17	G2	17	21	G2	VFBSPS	S	-	-	-	-
-	F4	18	22	G4	PF0	I/O	FT_f	-	I2C2_SDA, FMC_A0, EVENTOUT	-
-	F3	19	23	G3	PF1	I/O	FT_f	-	I2C2_SCL, FMC_A1, EVENTOUT	-
-	G3	20	24	G1	PF2	I/O	FT	-	I2C2_SMBA, FMC_A2, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
-	-	-	-	H1	PI12	I/O	FT	-	ETH_TX_ER, LCD_HSYNC, EVENTOUT	-
-	-	-	-	H2	PI13	I/O	FT	-	LCD_VSYNC, EVENTOUT	-
-	-	-	-	H3	PI14	I/O	FT_h	-	LCD_CLK, EVENTOUT	-
-	H4	21	25	H4	PF3	I/O	FT_ha	-	FMC_A3, EVENTOUT	ADC3_INP5
-	H2	22	26	J5	PF4	I/O	FT_ha	-	FMC_A4, EVENTOUT	ADC3_INN5, ADC3_INP9
-	H3	23	27	J4	PF5	I/O	FT_ha	-	FMC_A5, EVENTOUT	ADC3_INP4
18	E1	24	28	C10	VSS	S	-	-	-	-
19	E4	25	29	E9	VDD	S	-	-	-	-
20	H1	26	30	K2	PF6	I/O	FT_ha	-	TIM16_CH1, SPI5_NSS, SAI1_SD_B, UART7_RX, SAI4_SD_B, QUADSPI_BK1_IO3, EVENTOUT	ADC3_INN4, ADC3_INP8
21	J3	27	31	K3	PF7	I/O	FT_ha	-	TIM17_CH1, SPI5_SCK, SAI1_MCLK_B, UART7_TX, SAI4_MCLK_B, QUADSPI_BK1_IO2, EVENTOUT	ADC3_INP3
22	J2	28	32	K4	PF8	I/O	FT_ha	-	TIM16_CH1N, SPI5_MISO, SAI1_SCK_B, UART7_RTS/UART7_DE, SAI4_SCK_B, TIM13_CH1, QUADSPI_BK1_IO0, EVENTOUT	ADC3_INN3, ADC3_INP7
23	J4	29	33	L4	PF9	I/O	FT_ha	-	TIM17_CH1N, SPI5_MOSI, SAI1_FS_B, UART7_CTS, SAI4_FS_B, TIM14_CH1, QUADSPI_BK1_IO1, EVENTOUT	ADC3_INP2

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
24	K3	30	34	L3	PF10	I/O	FT_ha	-	TIM16_BKIN, SAI1_D3, QUADSPI_CLK, SAI4_D3, DCMI_D11, LCD_DE, EVENTOUT	ADC3_INN2, ADC3_INP6
25	J1	31	35	J2	PH0- OSC_IN(PH 0)	I/O	FT	-	EVENTOUT	OSC_IN
26	K1	32	36	J1	PH1- OSC_OUT(P H1)	I/O	FT	-	EVENTOUT	OSC_OUT
27	L1	33	37	K1	NRST	I/O	RST	-	-	-
28	L2	34	38	L2	PC0	I/O	FT_a	-	DFSDM1_CKIN0, DFSDM1_DATIN4, SAI2_FS_B, OTG_HS_ULPI_STP, FMC_SDNWE, LCD_R5, EVENTOUT	ADC123_INP10
29	L3	35	39	M2	PC1	I/O	FT_ha	-	TRACED0, SAI1_D1, DFSDM1_DATIN0, DFSDM1_CKIN4, SPI2_MOSI/I2S2_SDO, SAI1_SD_A, SAI4_SD_A, SDMMC2_CK, SAI4_D1, ETH_MDC, MDIOS_MDC, EVENTOUT	ADC123_INN10, ADC123_INP11, RTC_TAMP3/WK UP6
-	M1	-	-	M3 ⁽²⁾	PC2	I/O	FT_a	-	C1DSLEEP, DFSDM1_CKIN1, SPI2_MISO/I2S2_SDI, DFSDM1_CKOUT, OTG_HS_ULPI_DIR, ETH_MII_TXD2, FMC_SDNE0, EVENTOUT	ADC123_INN11, ADC123_INP12
30 ⁽³⁾	N1 ⁽³⁾	36 ⁽³⁾	40 ⁽³⁾	R1 ⁽²⁾	PC2_C	ANA	TT_a	-	-	ADC3_INN1, ADC3_INP0

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
-	M2	-	-	M4 ⁽²⁾	PC3	I/O	FT_a	-	C1SLEEP, DFSDM1_DATIN1, SPI2_MOSI/I2S2_SDO, OTG_HS_ULPI_NXT, ETH_MII_TX_CLK, FMC_SDCKE0, EVENTOUT	ADC12_INN12, ADC12_INP13
31 ⁽³⁾	N2 ⁽³⁾	37 ⁽³⁾	41 ⁽³⁾	R2 ⁽²⁾	PC3_C	ANA	TT_a	-	-	ADC3_INP1
32	E12	-	-	E11	VDD	S	-	-	-	-
33	F6	-	-	C13	VSS	S	-	-	-	-
34	N3	38	42	P1	VSSA	S	-	-	-	-
-	L4	-	-	N1	VREF-	S	-	-	-	-
35	M3	39	43	M1	VREF+	S	-	-	-	-
36	M4	40	44	L1	VDDA	S	-	-	-	-
37	P1	41	45	N5 ⁽²⁾	PA0	I/O	FT_a	-	TIM2_CH1/TIM2_ETR, TIM5_CH1, TIM8_ETR, TIM15_BKIN, USART2_CTS/USART2_NSS, UART4_TX, SDMMC2_CMD, SAI2_SD_B, ETH_MII_CRS, EVENTOUT	ADC1_INP16, WKUP1
-	R3	-	-	T1 ⁽²⁾	PA0_C	ANA	TT_a	-	-	ADC12_INN1, ADC12_INP0
38	P2	42	46	N4 ⁽²⁾	PA1	I/O	FT_ha	-	TIM2_CH2, TIM5_CH2, LPTIM3_OUT, TIM15_CH1N, USART2_RTS/USART2_DE, UART4_RX, QUADSPI_BK1_IO3, SAI2_MCLK_B, ETH_MII_RX_CLK/ETH_RMII_REF_CLK, LCD_R2, EVENTOUT	ADC1_INN16, ADC1_INP17
-	P3	-	-	T2 ⁽²⁾	PA1_C	ANA	TT_a	-	-	ADC12_INP1

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
39	R2	43	47	N3	PA2	I/O	FT_a	-	TIM2_CH3, TIM5_CH3, LPTIM4_OUT, TIM15_CH1, USART2_TX, SAI2_SCK_B, ETH_MDIO, MDIOS_MDIO, LCD_R1, EVENTOUT	ADC12_INP14, WKUP2
-	N4	-	48	N2	PH2	I/O	FT_ha	-	LPTIM1_IN2, QUADSPI_BK2_IO0, SAI2_SCK_B, ETH_MII_CRS, FMC_SDCKE0, LCD_R0, EVENTOUT	ADC3_INP13
-	G4	44	49	F5	VDD	S	-	-	-	-
-	F7	45	50	C16	VSS	S	-	-	-	-
-	R4	-	51	P2	PH3	I/O	FT_ha	-	QUADSPI_BK2_IO1, SAI2_MCLK_B, ETH_MII_COL, FMC_SDNE0, LCD_R1, EVENTOUT	ADC3_INN13, ADC3_INP14
-	P4	-	52	P3	PH4	I/O	FT_fa	-	I2C2_SCL, LCD_G5, OTG_HS_ULPI_NXT, LCD_G4, EVENTOUT	ADC3_INN14, ADC3_INP15
-	R5	-	53	P4	PH5	I/O	FT_fa	-	I2C2_SDA, SPI5_NSS, FMC_SDNWE, EVENTOUT	ADC3_INN15, ADC3_INP16
40	N5	46	54	U2	PA3	I/O	FT_ha	-	TIM2_CH4, TIM5_CH4, LPTIM5_OUT, TIM15_CH2, USART2_RX, LCD_B2, OTG_HS_ULPI_D0, ETH_MII_COL, LCD_B5, EVENTOUT	ADC12_INP15
41	F8	47	55	-	VSS	S	-	-	-	-
42	H12	48	56	G5	VDD	S	-	-	-	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
43	P5	49	57	U3	PA4	I/O	TT_a	-	D1PWREN, TIM5_ETR, SPI1_NSS/I2S1_WS, SPI3_NSS/I2S3_WS, USART2_CK, SPI6 NSS, OTG_HS_SOF, DCMI_HSYNC, LCD_VSYNC, EVENTOUT	ADC12_INP18, DAC1_OUT1
44	P6	50	58	T3	PA5	I/O	TT_ha	-	D2PWREN, TIM2_CH1/TIM2_ETR, TIM8_CH1N, SPI1_SCK/I2S1_CK, SPI6_SCK, OTG_HS_ULPI_CK, LCD_R4, EVENTOUT	ADC12_INN18, ADC12_INP19, DAC1_OUT2
45	R7	51	59	R3	PA6	I/O	FT_a	-	TIM1_BKIN, TIM3_CH1, TIM8_BKIN, SPI1_MISO/I2S1_SDI, SPI6_MISO, TIM13_CH1, TIM8_BKIN_COMP12, MDIOS_MDC, TIM1_BKIN_COMP12, DCMI_PIXCLK, LCD_G2, EVENTOUT	ADC12_INP3
46	N6	52	60	R5	PA7	I/O	TT_a	-	TIM1_CH1N, TIM3_CH2, TIM8_CH1N, SPI1_MOSI/I2S1_SDO, SPI6_MOSI, TIM14_CH1, ETH_MII_RX_DV/ETH_R MII_CRS_DV, FMC_SDNWE, EVENTOUT	ADC12_INN3, ADC12_INP7, OPAMP1_VINM
47	R6	53	61	T4	PC4	I/O	TT_a	-	C2DSLEEP, DFSDM1_CKIN2, I2S1_MCK, SPDIFRX1_IN3, ETH_MII_RXD0/ETH_R MII_RXD0, FMC_SDNE0, EVENTOUT	ADC12_INP4, OPAMP1_VOUT, COMP1_INM

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
48	M7	54	62	U4	PC5	I/O	TT_a	-	C2SLEEP, SAI1_D3, DFSDM1_DATIN2, SPDIFRX1_IN4, SAI4_D3, ETH_MII_RXD1/ETH_R MII_RXD1, FMC_SDCKE0, COMP1_OUT, EVENTOUT	ADC12_INN4, ADC12_INP8, OPAMP1_VINM
-	K4	-	-	G13	VDD	S	-	-	-	-
-	F9	-	-	R4	VSS	S	-	-	-	-
49	R8	55	63	U5	PB0	I/O	FT_a	-	TIM1_CH2N, TIM3_CH3, TIM8_CH2N, DFSDM1_CKOUT, UART4_CTS, LCD_R3, OTG_HS_ULPI_D1, ETH_MII_RXD2, LCD_G1, EVENTOUT	ADC12_INN5, ADC12_INP9, OPAMP1_VINP, COMP1_INP
50	M8	56	64	T5	PB1	I/O	TT_a	-	TIM1_CH3N, TIM3_CH4, TIM8_CH3N, DFSDM1_DATIN1, LCD_R6, OTG_HS_ULPI_D2, ETH_MII_RXD3, LCD_G0, EVENTOUT	ADC12_INP5, COMP1_INM
51	P7	57	65	R6	PB2	I/O	FT_ha	-	RTC_OUT, SAI1_D1, DFSDM1_CKIN1, SAI1_SD_A, SPI3_MOSI/I2S3_SDO, SAI4_SD_A, QUADSPI_CLK, SAI4_D1, ETH_TX_ER, EVENTOUT	COMP1_INP
-	-	-	66	P5	PI15	I/O	FT	-	LCD_G2, LCD_R0, EVENTOUT	-
-	-	-	-	N6	PJ0	I/O	FT	-	LCD_R7, LCD_R1, EVENTOUT	-
-	-	-	-	P6	PJ1	I/O	FT	-	LCD_R2, EVENTOUT	-
-	-	-	-	T6	PJ2	I/O	FT	-	LCD_R3, EVENTOUT	-
-	-	-	-	U6	PJ3	I/O	FT	-	LCD_R4, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
-	-	-	-	U7	PJ4	I/O	FT	-	LCD_R5, EVENTOUT	-
52	N7	58	67	T7	PF11	I/O	FT_a	-	SPI5_MOSI, SAI2_SD_B, FMC_SDNRAS, DCMI_D12, EVENTOUT	ADC1_INP2
-	P11	59	68	R7	PF12	I/O	FT_ha	-	FMC_A6, EVENTOUT	ADC1_INN2, ADC1_INP6
-	F10	-	-	J3	VSS	S	-	-	-	-
-	L12	-	-	H5	VDD	S	-	-	-	-
-	N11	60	69	P7	PF13	I/O	FT_ha	-	DFSDM1_DATIN6, I2C4_SMBA, FMC_A7, EVENTOUT	ADC2_INP2
53	R10	61	70	P8	PF14	I/O	FT_fha	-	DFSDM1_CKIN6, I2C4_SCL, FMC_A8, EVENTOUT	ADC2_INN2, ADC2_INP6
54	N10	62	71	R9	PF15	I/O	FT_fh	-	I2C4_SDA, FMC_A9, EVENTOUT	-
-	P8	63	72	T8	PG0	I/O	FT_h	-	FMC_A10, EVENTOUT	-
55	F12	64	73	J16	VSS	S	-	-	-	-
56	M5	65	74	H13	VDD	S	-	-	-	-
-	N9	66	75	U8	PG1	I/O	TT_h	-	FMC_A11, EVENTOUT	OPAMP2_VINM
57	P9	67	76	U9	PE7	I/O	TT_ha	-	TIM1_ETR, DFSDM1_DATIN2, UART7_RX, QUADSPI_BK2_IO0, FMC_D4/FMC_DA4, EVENTOUT	OPAMP2_VOUT, COMP2_INM
58	N8	68	77	T9	PE8	I/O	TT_ha	-	TIM1_CH1N, DFSDM1_CKIN2, UART7_TX, QUADSPI_BK2_IO1, FMC_D5/FMC_DA5, COMP2_OUT, EVENTOUT	OPAMP2_VINM

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
59	R11	69	78	P9	PE9	I/O	TT_ha	-	TIM1_CH1, DFSDM1_CKOUT, UART7_RTS/UART7_DE, QUADSPI_BK2_IO2, FMC_D6/FMC_DA6, EVENTOUT	OPAMP2_VINP, COMP2_INP
-	G6	70	79	J17	VSS	S	-	-	-	-
-	M9	71	80	J13	VDD	S	-	-	-	-
60	R9	72	81	N9	PE10	I/O	FT_ha	-	TIM1_CH2N, DFSDM1_DATIN4, UART7_CTS, QUADSPI_BK2_IO3, FMC_D7/FMC_DA7, EVENTOUT	COMP2_INM
61	R12	73	82	P10	PE11	I/O	FT_ha	-	TIM1_CH2, DFSDM1_CKIN4, SPI4_NSS, SAI2_SD_B, FMC_D8/FMC_DA8, LCD_G3, EVENTOUT	COMP2_INP
62	P12	74	83	R10	PE12	I/O	FT_h	-	TIM1_CH3N, DFSDM1_DATIN5, SPI4_SCK, SAI2_SCK_B, FMC_D9/FMC_DA9, COMP1_OUT, LCD_B4, EVENTOUT	-
63	P13	75	84	T10	PE13	I/O	FT_h	-	TIM1_CH3, DFSDM1_CKIN5, SPI4_MISO, SAI2_FS_B, FMC_D10/FMC_DA10, COMP2_OUT, LCD_DE, EVENTOUT	-
-	G7	-	-	T12	VSS	S	-	-	-	-
-	-	-	-	K13	VDD	S	-	-	-	-
64	M12	76	85	U10	PE14	I/O	FT_h	-	TIM1_CH4, SPI4_MOSI, SAI2_MCLK_B, FMC_D11/FMC_DA11, LCD_CLK, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
65	P14	77	86	R11	PE15	I/O	FT_h	-	TIM1_BKIN, FMC_D12/FMC_DA12, TIM1_BKIN_COMP12/C OMP_TIM1_BKIN, LCD_R7, EVENTOUT	-
66	N12	78	87	P11	PB10	I/O	FT_f	-	TIM2_CH3, HRTIM_SCOUT, LPTIM2_IN1, I2C2_SCL, SPI2_SCK/I2S2_CK, DFSDM1_DATIN7, USART3_TX, QUADSPI_BK1_NCS, OTG_HS_ULPI_D3, ETH_MII_RX_ER, LCD_G4, EVENTOUT	-
67	P10	79	88	P12	PB11	I/O	FT_f	-	TIM2_CH4, HRTIM_SCIN, LPTIM2_ETR, I2C2_SDA, DFSDM1_CKIN7, USART3_RX, OTG_HS_ULPI_D4, ETH_MII_TX_EN/ETH_R MII_TX_EN, LCD_G5, EVENTOUT	-
68	R13	80	89	U11	VCAP	S	-	-	-	-
69	M10	81	90	-	VSS	S	-	-	-	-
70	R14	82	91	U12	VDDLD0 ⁽⁴⁾	S	-	-	-	-
71	-	-	-	L13	VDD	S	-	-	-	-
-	-	-	-	R12	PJ5	I/O	FT	-	LCD_R6, EVENTOUT	-
-	P15	-	92	T11	PH6	I/O	FT	-	TIM12_CH1, I2C2_SMBA, SPI5_SCK, ETH_MII_RXD2, FMC_SDNE1, DCMI_D8, EVENTOUT	-
-	M11	-	93	U13	PH7	I/O	FT_f_a	-	I2C3_SCL, SPI5_MISO, ETH_MII_RXD3, FMC_SDCKE1, DCMI_D9, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
-	N13	-	94	T13	PH8	I/O	FT_f ha	-	TIM5_ETR, I2C3_SDA, FMC_D16, DCMI_HSYNC, LCD_R2, EVENTOUT	-
-	G9	-	-	-	VSS	S	-	-	-	-
-	-	-	-	M13	VDD	S	-	-	-	-
-	M14	-	95	R13	PH9	I/O	FT_h	-	TIM12_CH2, I2C3_SMBA, FMC_D17, DCMI_D0, LCD_R3, EVENTOUT	-
-	N14	-	96	P13	PH10	I/O	FT_h	-	TIM5_CH1, I2C4_SMBA, FMC_D18, DCMI_D1, LCD_R4, EVENTOUT	-
-	M13	-	97	P14	PH11	I/O	FT_f h	-	TIM5_CH2, I2C4_SCL, FMC_D19, DCMI_D2, LCD_R5, EVENTOUT	-
-	N15	-	98	R14	PH12	I/O	FT_f h	-	TIM5_CH3, I2C4_SDA, FMC_D20, DCMI_D3, LCD_R6, EVENTOUT	-
-	G10	83	99	N16	VSS	S	-	-	-	-
-	-	84	100	-	VDD	S	-	-	-	-
72	M15	85	101	T14	PB12 ⁽⁵⁾	I/O	FT_u	-	TIM1_BKIN, I2C2_SMBA, SPI2_NSS/I2S2_WS, DFSDM1_DATIN1, USART3_CK, FDCAN2_RX, OTG_HS_ULPI_D5, ETH_MII_TXD0/ETH_R MII_TXD0, OTG_HS_ID, TIM1_BKIN_COMP12, UART5_RX, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
73	L15	86	102	U14	PB13 ⁽⁵⁾	I/O	FT_u	-	TIM1_CH1N, LPTIM2_OUT, SPI2_SCK/I2S2_CK, DFSDM1_CKIN1, USART3_CTS/USART3_NSS, FDCAN2_TX, OTG_HS_ULPI_D6, ETH_MII_TXD1/ETH_R MII_TXD1, UART5_TX, EVENTOUT	OTG_HS_VBUS
74	K15	87	103	U15	PB14	I/O	FT_u	-	TIM1_CH2N, TIM12_CH1, TIM8_CH2N, USART1_TX, SPI2_MISO/I2S2_SD1, DFSDM1_DATIN2, USART3_RTS/USART3_DE, UART4_RTS/UART4_DE , SDMMC2_D0, OTG_HS_DM, EVENTOUT	-
75	K14	88	104	T15	PB15	I/O	FT_u	-	RTC_REFIN, TIM1_CH3N, TIM12_CH2, TIM8_CH3N, USART1_RX, SPI2_MOSI/I2S2_SDO, DFSDM1_CKIN2, UART4_CTS, SDMMC2_D1, OTG_HS_DP, EVENTOUT	-
76	L14	89	105	U16	PD8	I/O	FT_h	-	DFSDM1_CKIN3, SAI3_SCK_B, USART3_TX, SPDIFRX1_IN2, FMC_D13/FMC_DA13, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
77	K13	90	106	T17	PD9	I/O	FT_h	-	DFSDM1_DATIN3, SAI3_SD_B, USART3_RX, FMC_D14/FMC_DA14, EVENTOUT	-
78	L13	91	107	T16	PD10	I/O	FT_h	-	DFSDM1_CKOUT, SAI3_FS_B, USART3_CK, FMC_D15/FMC_DA15, LCD_B3, EVENTOUT	-
79	-	92	108	N12	VDD	S	-	-	-	-
80	H6	93	109	U17	VSS	S	-	-	-	-
81	J13	94	110	R15	PD11	I/O	FT_h	-	LPTIM2_IN2, I2C4_SMBA, USART3_CTS/USART3_NSS, QUADSPI_BK1_IO0, SAI2_SD_A, FMC_A16, EVENTOUT	-
82	J15	95	111	R16	PD12	I/O	FT_f_h	-	LPTIM1_IN1, TIM4_CH1, LPTIM2_IN1, I2C4_SCL, USART3_RTS/USART3_DE, QUADSPI_BK1_IO1, SAI2_FS_A, FMC_A17, EVENTOUT	-
83	H15	96	112	R17	PD13	I/O	FT_f_h	-	LPTIM1_OUT, TIM4_CH2, I2C4_SDA, QUADSPI_BK1_IO3, SAI2_SCK_A, FMC_A18, EVENTOUT	-
-	R1	-	113	-	VSS	S	-	-	-	-
-	-	-	114	N11	VDD	S	-	-	-	-
84	H14	97	115	P16	PD14	I/O	FT_h	-	TIM4_CH3, SAI3_MCLK_B, UART8_CTS, FMC_D0/FMC_DA0, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
85	J12	98	116	P15	PD15	I/O	FT_h	-	TIM4_CH4, SAI3_MCLK_A, UART8_RTS/UART8_DE , FMC_D1/FMC_DA1, EVENTOUT	-
-	-	-	117	N15	PJ6	I/O	FT	-	TIM8_CH2, LCD_R7, EVENTOUT	-
-	-	-	118	N14	PJ7	I/O	FT	-	TRGIN, TIM8_CH2N, LCD_G0, EVENTOUT	-
-	-	99	119	N10	VDD	S	-	-	-	-
-	D6	100	120	R8	VSS	S	-	-	-	-
-	-	101	121	N13	PJ8	I/O	FT	-	TIM1_CH3N, TIM8_CH1, UART8_TX, LCD_G1, EVENTOUT	-
-	-	102	122	M14	PJ9	I/O	FT	-	TIM1_CH3, TIM8_CH1N, UART8_RX, LCD_G2, EVENTOUT	-
-	-	103	123	L14	PJ10	I/O	FT	-	TIM1_CH2N, TIM8_CH2, SPI5_MOSI, LCD_G3, EVENTOUT	-
-	-	104	124	K14	PJ11	I/O	FT	-	TIM1_CH2, TIM8_CH2N, SPI5_MISO, LCD_G4, EVENTOUT	-
-	-	105	125	N8	VDD	S	-	-	-	-
-	-	-	-	P17	VDD	S	-	-	-	-
-	R15	106	126	U1	VSS	S	-	-	-	-
-	-	-	-	N17	NC	-	-	-	-	-
-	-	-	-	M16	NC	-	-	-	-	-
-	-	-	-	M17	NC	-	-	-	-	-
-	-	-	-	K15	VSS	S	-	-	-	-
-	-	-	-	L16	NC	-	-	-	-	-
-	-	-	-	L17	NC	-	-	-	-	-
-	-	-	-	K16	NC	-	-	-	-	-
-	-	-	-	K17	NC	-	-	-	-	-
-	-	-	-	L15	VSS	S	-	-	-	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
-	-	107	127	J14	PK0	I/O	FT	-	TIM1_CH1N, TIM8_CH3, SPI5_SCK, LCD_G5, EVENTOUT	-
-	-	108	128	J15	PK1	I/O	FT	-	TIM1_CH1, TIM8_CH3N, SPI5_NSS, LCD_G6, EVENTOUT	-
-	-	109	129	H17	PK2	I/O	FT	-	TIM1_BKIN, TIM8_BKIN, TIM8_BKIN_COMP12, TIM1_BKIN_COMP12, LCD_G7, EVENTOUT	-
-	G15	110	130	H16	PG2	I/O	FT_h	-	TIM8_BKIN, TIM8_BKIN_COMP12, FMC_A12, EVENTOUT	-
-	H13	111	131	H15	PG3	I/O	FT_h	-	TIM8_BKIN2, TIM8_BKIN2_COMP12, FMC_A13, EVENTOUT	-
-	H10	112	132	-	VSS	S	-	-	-	-
-	-	113	133	N7	VDD	S	-	-	-	-
-	G14	114	134	H14	PG4	I/O	FT_h	-	TIM1_BKIN2, TIM1_BKIN2_COMP12, FMC_A14/FMC_BA0, EVENTOUT	-
-	F15	115	135	G14	PG5	I/O	FT_h	-	TIM1_ETR, FMC_A15/FMC_BA1, EVENTOUT	-
86	F14	116	136	G15	PG6	I/O	FT_h	-	TIM17_BKIN, HRTIM_CHE1, QUADSPI_BK1_NCS, FMC_NE3, DCMI_D12, LCD_R7, EVENTOUT	-
87	G13	117	137	F16	PG7	I/O	FT_h	-	HRTIM_CHE2, SAI1_MCLK_A, USART6_CK, FMC_INT, DCMI_D13, LCD_CLK, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
88	G12	118	138	F15	PG8	I/O	FT_h	-	TIM8_ETR, SPI6_NSS, USART6_RTS/USART6_DE, SPDIFRX1_IN3, ETH_PPS_OUT, FMC_SDCLK, LCD_G7, EVENTOUT	-
89	J6	119	139	G16	VSS	S	-	-	-	-
90	E15	120	140	G17	VDD50USB ⁽⁶⁾	S	-	-	-	-
91	F13	121	141	F17	VDD33USB	S	-	-	-	-
92	-	-	-	M5	VDD	S	-	-	-	-
93	E14	122	142	F14	PC6	I/O	FT_h	-	HRTIM_CHA1, TIM3_CH1, TIM8_CH1, DFSDM1_CKIN3, I2S2_MCK, USART6_TX, SDMMC1_D0DIR, FMC_NWAIT, SDMMC2_D6, SDMMC1_D6, DCMI_D0, LCD_HSYNC, EVENTOUT	SWPMI_IO
94	D15	123	143	F13	PC7	I/O	FT_h	-	TRGIO, HRTIM_CHA2, TIM3_CH2, TIM8_CH2, DFSDM1_DATIN3, I2S3_MCK, USART6_RX, SDMMC1_D123DIR, FMC_NE1, SDMMC2_D7, SWPMI_TX, SDMMC1_D7, DCMI_D1, LCD_G6, EVENTOUT	-
95	D14	124	144	E13	PC8	I/O	FT_h	-	TRACED1, HRTIM_CHB1, TIM3_CH3, TIM8_CH3, USART6_CK, UART5_RTS/UART5_DE, FMC_NE2/FMC_NCE, SWPMI_RX, SDMMC1_D0, DCMI_D2, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
96	E13	125	145	E14	PC9	I/O	FT_f_h	-	MCO2, TIM3_CH4, TIM8_CH4, I2C3_SDA, I2S_CKIN, UART5_CTS, QUADSPI_BK1_IO0, LCD_G3, SWPMI_SUSPEND, SDMMC1_D1, DCMI_D3, LCD_B2, EVENTOUT	-
-	J7	-	-	-	VSS	S	-	-	-	-
-	-	126	-	L5	VDD	S	-	-	-	-
97	B14	127	146	E15	PA8	I/O	FT_f_ha	-	MCO1, TIM1_CH1, HRTIM_CHB2, TIM8_BKIN2, I2C3_SCL, USART1_CK, OTG_FS_SOF, UART7_RX, TIM8_BKIN2_COMP12, LCD_B3, LCD_R6, EVENTOUT	-
98	D13	128	147	D15	PA9	I/O	FT_u	-	TIM1_CH2, HRTIM_CHC1, LPUART1_TX, I2C3_SMBA, SPI2_SCK/I2S2_CK, USART1_TX, ETH_TX_ER, DCMI_D0, LCD_R5, EVENTOUT	OTG_FS_VBUS
99	C14	129	148	D14	PA10	I/O	FT_u	-	TIM1_CH3, HRTIM_CHC2, LPUART1_RX, USART1_RX, OTG_FS_ID, MDIOS_MDIO, LCD_B4, DCMI_D1, LCD_B1, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
100	C15	130	149	E17	PA11	I/O	FT_u	-	TIM1_CH4, HRTIM_CHD1, LPUART1_CTS, SPI2_NSS/I2S2_WS, UART4_RX, USART1_CTS/USART1_NSS, FDCAN1_RX, OTG_FS_DM, LCD_R4, EVENTOUT	-
101	B15	131	150	E16	PA12	I/O	FT_u	-	TIM1_ETR, HRTIM_CHD2, LPUART1 RTS/LPUART1_DE, SPI2_SCK/I2S2_CK, UART4_TX, USART1 RTS/USART1_DE, SAI2_FS_B, FDCAN1_TX, OTG_FS_DP, LCD_R5, EVENTOUT	-
102	B13	132	151	C15	PA13(JTMS/SWDIO)	I/O	FT	-	JTMS-SWDIO, EVENTOUT	-
103	A14	133	152	D17	VCAP	S	-	-	-	-
104	M6	134	153	-	VSS	S	-	-	-	-
105	A13	135	154	C17	VDDLD0 ⁽⁴⁾	S	-	-	-	-
106	-	136	155	K5	VDD	S	-	-	-	-
-	C13	-	156	D16	PH13	I/O	FT_h	-	TIM8_CH1N, UART4_TX, FDCAN1_TX, FMC_D21, LCD_G2, EVENTOUT	-
-	B12	-	157	B17	PH14	I/O	FT_h	-	TIM8_CH2N, UART4_RX, FDCAN1_RX, FMC_D22, DCMI_D4, LCD_G3, EVENTOUT	-
-	D12	-	158	B16	PH15	I/O	FT_h	-	TIM8_CH3N, FMC_D23, DCMI_D11, LCD_G4, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
-	-	-	159	A16	PI0	I/O	FT_h	-	TIM5_CH4, SPI2 NSS/I2S2_WS, FMC_D24, DCMI_D13, LCD_G5, EVENTOUT	-
-	J9	-	160	-	VSS	S	-	-	-	-
-	-	-	161	-	VDD	S	-	-	-	-
-	-	-	162	A15	PI1	I/O	FT_h	-	TIM8_BKIN2, SPI2_SCK/I2S2_CK, TIM8_BKIN2_COMP12, FMC_D25, DCMI_D8, LCD_G6, EVENTOUT	-
-	-	-	163	B15	PI2	I/O	FT_h	-	TIM8_CH4, SPI2_MISO/I2S2_SDI, FMC_D26, DCMI_D9, LCD_G7, EVENTOUT	-
-	-	-	164	C14	PI3	I/O	FT_h	-	TIM8_ETR, SPI2_MOSI/I2S2_SDO, FMC_D27, DCMI_D10, EVENTOUT	-
-	J10	137	-	-	VSS	S	-	-	-	-
107	A12	138	165	B14	PA14(JTCK/ SWCLK)	I/O	FT	-	JTCK-SWCLK, EVENTOUT	-
108	A11	139	166	A14	PA15(JTDI)	I/O	FT	-	JTDI, TIM2_CH1/TIM2_ETR, HRTIM_FLT1, CEC, SPI1_NSS/I2S1_WS, SPI3_NSS/I2S3_WS, SPI6_NSS, UART4_RTS/UART4_DE , UART7_TX, EVENTOUT	-
109	C12	140	167	A13	PC10	I/O	FT_ha	-	HRTIM_EEV1, DFSDM1_CKIN5, SPI3_SCK/I2S3_CK, USART3_TX, UART4_TX, QUADSPI_BK1_IO1, SDMMC1_D2, DCMI_D8, LCD_R2, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
110	C11	141	168	B13	PC11	I/O	FT_h	-	HRTIM_FLT2, DFSDM1_DATIN5, SPI3_MISO/I2S3_SDI, USART3_RX, UART4_RX, QUADSPI_BK2_NCS, SDMMC1_D3, DCMI_D4, EVENTOUT	-
111	B11	142	169	C12	PC12	I/O	FT_h	-	TRACED3, HRTIM_EEV2, SPI3_MOSI/I2S3_SDO, USART3_CK, UART5_TX, SDMMC1_CK, DCMI_D9, EVENTOUT	-
-	J14	-	-	-	VSS	S	-	-	-	-
112	C10	143	170	D13	PD0	I/O	FT_h	-	DFSDM1_CKIN6, SAI3_SCK_A, UART4_RX, FDCAN1_RX, FMC_D2/FMC_DA2, EVENTOUT	-
113	A10	144	171	E12	PD1	I/O	FT_h	-	DFSDM1_DATIN6, SAI3_SD_A, UART4_TX, FDCAN1_TX, FMC_D3/FMC_DA3, EVENTOUT	-
114	B10	145	172	D12	PD2	I/O	FT_h	-	TRACED2, TIM3_ETR, UART5_RX, SDMMC1_CMD, DCMI_D11, EVENTOUT	-
115	A9	146	173	B12	PD3	I/O	FT_h	-	DFSDM1_CKOUT, SPI2_SCK/I2S2_CK, USART2_CTS/USART2_NSS, FMC_CLK, DCMI_D5, LCD_G7, EVENTOUT	-
116	C9	147	174	A12	PD4	I/O	FT_h	-	HRTIM_FLT3, SAI3_FS_A, USART2_RTS/USART2_DE, FMC_NOE, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
117	B9	148	175	A11	PD5	I/O	FT_h	-	HRTIM_EEV3, USART2_TX, FMC_NWE, EVENTOUT	-
118	K2	-	-	-	VSS	S	-	-	-	-
119	-	-	-	-	VDD	S	-	-	-	-
120	D9	149	176	B11	PD6	I/O	FT_h	-	SAI1_D1, DFSDM1_CKIN4, DFSDM1_DATIN1, SPI3_MOSI/I2S3_SDO, SAI1_SD_A, USART2_RX, SAI4_SD_A, SAI4_D1, SDMMC2_CK, FMC_NWAIT, DCMI_D10, LCD_B2, EVENTOUT	-
121	B8	150	177	C11	PD7	I/O	FT_h	-	DFSDM1_DATIN4, SPI1_MOSI/I2S1_SDO, DFSDM1_CKIN1, USART2_CK, SPDIFRX1_IN1, SDMMC2_CMD, FMC_NE1, EVENTOUT	-
-	-	-	-	D11	PJ12	I/O	FT	-	TRGOUT, LCD_G3, LCD_B0, EVENTOUT	-
-	-	-	-	E10	PJ13	I/O	FT	-	LCD_B4, LCD_B1, EVENTOUT	-
-	-	-	-	D10	PJ14	I/O	FT	-	LCD_B2, EVENTOUT	-
-	-	-	-	B10	PJ15	I/O	FT	-	LCD_B3, EVENTOUT	-
-	K6	151	178	-	VSS	S	-	-	-	-
-	-	152	179	-	VDD	S	-	-	-	-
122	A8	153	180	A10	PG9	I/O	FT_h	-	SPI1_MISO/I2S1_SDI, USART6_RX, SPDIFRX1_IN4, QUADSPI_BK2_IO2, SAI2_FS_B, FMC_NE2/FMC_NCE, DCMI_VSYNC, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
123	C8	154	181	A9	PG10	I/O	FT_h	-	HRTIM_FLT5, SPI1_NSS/I2S1_WS, LCD_G3, SAI2_SD_B, FMC_NE3, DCMI_D2, LCD_B2, EVENTOUT	-
124	A7	155	182	B9	PG11	I/O	FT_h	-	LPTIM1_IN2, HRTIM_EEV4, SPI1_SCK/I2S1_CK, SPDIFRX1_IN1, SDMMC2_D2, ETH_MII_TX_EN/ETH_R MII_TX_EN, DCMI_D3, LCD_B3, EVENTOUT	-
125	D8	156	183	C9	PG12	I/O	FT_h	-	LPTIM1_IN1, HRTIM_EEV5, SPI6_MISO, USART6 RTS/USART6_DE, SPDIFRX1_IN2, LCD_B4, ETH_MII_TXD1/ETH_R MII_TXD1, FMC_NE4, LCD_B1, EVENTOUT	-
126	B7	157	184	D9	PG13	I/O	FT_h	-	TRACED0, LPTIM1_OUT, HRTIM_EEV10, SPI6_SCK, USART6_CTS/USART6_NSS, ETH_MII_TXD0/ETH_R MII_TXD0, FMC_A24, LCD_R0, EVENTOUT	-
127	C7	158	185	D8	PG14	I/O	FT_h	-	TRACED1, LPTIM1_ETR, SPI6_MOSI, USART6_TX, QUADSPI_BK2_IO3, ETH_MII_TXD1/ETH_R MII_TXD1, FMC_A25, LCD_B0, EVENTOUT	-
-	K7	159	186	-	VSS	S	-	-	-	-
-	-	160	187	-	VDD	S	-	-	-	-
-	-	-	-	C8	PK3	I/O	FT	-	LCD_B4, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
-	-	-	-	B8	PK4	I/O	FT	-	LCD_B5, EVENTOUT	-
-	-	-	-	A8	PK5	I/O	FT	-	LCD_B6, EVENTOUT	-
-	-	-	-	C7	PK6	I/O	FT	-	LCD_B7, EVENTOUT	-
-	-	-	-	D7	PK7	I/O	FT	-	LCD_DE, EVENTOUT	-
128	K8	-	-	-	VSS	S	-	-	-	-
129	-	-	-	-	VDD	S	-	-	-	-
-	D7	161	188	D6	PG15	I/O	FT_h	-	USART6_CTS/USART6_NSS, FMC_SDNCAS, DCMI_D13, EVENTOUT	-
130	A6	162	189	C6	PB3(JTDO/T RACESWO)	I/O	FT	-	JTDO/TRACESWO, TIM2_CH2, HRTIM_FLT4, SPI1_SCK/I2S1_CK, SPI3_SCK/I2S3_CK, SPI6_SCK, SDMMC2_D2, CRS_SYNC, UART7_RX, EVENTOUT	-
131	B6	163	190	B7	PB4(NJTRS T)	I/O	FT	-	NJTRST, TIM16_BKIN, TIM3_CH1, HRTIM_EEV6, SPI1_MISO/I2S1_SDI, SPI3_MISO/I2S3_SDI, SPI2_NSS/I2S2_WS, SPI6_MISO, SDMMC2_D3, UART7_TX, EVENTOUT	-
132	C6	164	191	A5	PB5	I/O	FT	-	TIM17_BKIN, TIM3_CH2, HRTIM_EEV7, I2C1_SMBA, SPI1_MOSI/I2S1_SDO, I2C4_SMBA, SPI3_MOSI/I2S3_SDO, SPI6_MOSI, FDCAN2_RX, OTG_HS_ULPI_D7, ETH_PPS_OUT, FMC_SDCKE1, DCMI_D10, UART5_RX, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
-	K9	-	-	-	VSS	S	-	-	-	-
133	A5	165	192	B5	PB6	I/O	FT_f	-	TIM16_CH1N, TIM4_CH1, HRTIM_EEV8, I2C1_SCL, CEC, I2C4_SCL, USART1_TX, LPUART1_TX, FDCAN2_TX, QUADSPI_BK1_NCS, DFSDM1_DATIN5, FMC_SDNE1, DCMI_D5, UART5_TX, EVENTOUT	-
134	B5	166	193	C5	PB7	I/O	FT_f_a	-	TIM17_CH1N, TIM4_CH2, HRTIM_EEV9, I2C1_SDA, I2C4_SDA, USART1_RX, LPUART1_RX, DFSDM1_CKIN5, FMC_NL, DCMI_VSYNC, EVENTOUT	PVD_IN
135	C5	167	194	E8	BOOT0	I	B	-	-	VPP
136	A2	168	195	D5	PB8	I/O	FT_f_h	-	TIM16_CH1, TIM4_CH3, DFSDM1_CKIN7, I2C1_SCL, I2C4_SCL, SDMMC1_CKIN, UART4_RX, FDCAN1_RX, SDMMC2_D4, ETH_MII_TXD3, SDMMC1_D4, DCMI_D6, LCD_B6, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
137	B3	169	196	D4	PB9	I/O	FT_f_h	-	TIM17_CH1, TIM4_CH4, DFSDM1_DATIN7, I2C1_SDA, SPI2 NSS/I2S2_WS, I2C4_SDA, SDMMC1_CDIR, UART4_TX, FDCAN1_TX, SDMMC2_D5, I2C4_SMBA, SDMMC1_D5, DCMI_D7, LCD_B7, EVENTOUT	-
138	B4	170	197	C4	PE0	I/O	FT_h	-	LPTIM1_ETR, TIM4_ETR, HRTIM_SCIN, LPTIM2_ETR, UART8_RX, SAI2_MCLK_A, FMC_NBL0, DCMI_D2, EVENTOUT	-
139	C4	171	198	B4	PE1	I/O	FT_h	-	LPTIM1_IN2, HRTIM_SCOUT, UART8_TX, FMC_NBL1, DCMI_D3, EVENTOUT	-
140	A4	172	199	A7	VCAP	S	-	-	-	-
141	K10	173	200	B6	VSS	S	-	-	-	-
142	D4	174	201	E7	PDR_ON	I	FT	-	-	-
143	A3	175	202	A6	VDDLDO ⁽⁴⁾	S	-	-	-	-
-	-	-	203	A4	PI4	I/O	FT_h	-	TIM8_BKIN, SAI2_MCLK_A, TIM8_BKIN_COMP12, FMC_NBL2, DCMI_D5, LCD_B4, EVENTOUT	-
-	-	-	204	A3	PI5	I/O	FT_h	-	TIM8_CH1, SAI2_SCK_A, FMC_NBL3, DCMI_VSYNC, LCD_B5, EVENTOUT	-
-	-	-	205	A2	PI6	I/O	FT_h	-	TIM8_CH2, SAI2_SD_A, FMC_D28, DCMI_D6, LCD_B6, EVENTOUT	-

Table 8. STM32H755xl pin/ball definition (continued)

Pin/ball name					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP144	UFBGA176+25	LQFP176	LQFP208	TFBGA240+25						
-	-	-	206	B3	PI7	I/O	FT_h	-	TIM8_CH3, SAI2_FS_A, FMC_D29, DCMI_D7, LCD_B7, EVENTOUT	-
-	K12	-	207	-	VSS	S	-	-	-	-
144	-	176	208	-	VDD	S	-	-	-	-
-	-	-	-	M15	VSS	S	-	-	-	-

1. When this pin/ball was previously configured as an oscillator, the oscillator function is kept during and after a reset. This is valid for all resets except for power-on reset.
2. Pxy_C and Pxy pins/balls are two separate pads (analog switch open). The analog switch is configured through a SYSCFG register. Refer to the product reference manual for a detailed description of the switch configuration bits.
3. There is a direct path between Pxy_C and Pxy pins/balls, through an analog switch. Pxy alternate functions are available on Pxy_C when the analog switch is closed. The analog switch is configured through a SYSCFG register. Refer to the product reference manual for a detailed description of the switch configuration bits.
4. When it is not available on a package, the VDDLDO pin is internally tied to VDD.
5. When the pin is used in USB configuration (OTG_HS_ID/OTG_HS_VBUS), the I/O is supplied by V_{DD33USB}, otherwise it is supplied by V_{DD}.
6. When it is not available on a package, the VDD50USB pin is internally tied to VDD33USB.

Table 9. Alternate functions

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
	SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/TIM8/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/4/5/6/USART1/2/3/6/UART7/SDMMC1	SPI1/2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SAI2/4/UART4/5/8/UART7/SDMMC1/SPDIFRX1	SPI16/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SAI2/4/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/SWPMI1/TIM18/DFSDM/SDMMC2/MDIOS/ETH	UART7/SWPMI1/TIM18/DFSDM/SDMMC2/MDIOS/ETH	FMC/SDMMC1/MDIOS/OTG_FS1/LCD	TIM1/DCMI/LCD/COMP	UART5/LCD	SYS
PortA	PA0	-	TIM2_CH1/TIM2_ETR	TIM5_CH1	TIM8_ETR	TIM15_BKIN	-	-	USART2_CTS/USART2_NSS	UART4_TX	SDMMC2_CMD	SAI2_SD_B	ETH_MII_CRS	-	-	-	EVENT OUT
	PA1	-	TIM2_CH2	TIM5_CH2	LPTIM3_OUT	TIM15_CH1N	-	-	USART2_RTS/USART2_DE	UART4_RX	QUADSPI_BK1_IO3	SAI2_MCLK_B	ETH_MII_RX_CLK/ETH_RMII_REF_CLK	-	-	LCD_R2	EVENT OUT
	PA2	-	TIM2_CH3	TIM5_CH3	LPTIM4_OUT	TIM15_CH1	-	-	USART2_TX	SAI2_SCK_B	-	-	ETH_MDIO	MDIOS_MDIO	-	LCD_R1	EVENT OUT
	PA3	-	TIM2_CH4	TIM5_CH4	LPTIM5_OUT	TIM15_CH2	-	-	USART2_RX	-	LCD_B2	OTG_HS_ULPI_D0	ETH_MII_COL	-	-	LCD_B5	EVENT OUT
	PA4	D1PWREN	-	TIM5_ETR	-	-	SPI1_NSS/I2S1_WS	SPI3_NSS/I2S3_WS	USART2_CK	SPI6_NSS	-	-	-	OTG_HS_SOFTWARE	DCMI_HSYNC	LCD_VSYNC	EVENT OUT
	PA5	D2PWREN	TIM2_CH1/TIM2_ETR	-	TIM8_CH1N	-	SPI1_SCK/I2S1_CK	-	-	SPI6_SCK	-	OTG_HS_ULPI_CLOCK	-	-	-	LCD_R4	EVENT OUT
	PA6	-	TIM1_BKIN	TIM3_CH1	TIM8_BKIN	-	SPI1_MISO/I2S1_SDI	-	-	SPI6_MISO	TIM13_CH1	TIM8_BKIN_COMP12	MDIOS_MDC	TIM1_BKIN_COMP12	DCMI_PIXCLK	LCD_G2	EVENT OUT
	PA7	-	TIM1_CH1N	TIM3_CH2	TIM8_CH1N	-	SPI1_MOSI/I2S1_SDO	-	-	SPI6_MOSI	TIM14_CH1	-	ETH_MII_RX_DV/ETH_RMII_CRS_DV	FMC_SDNWE	-	-	EVENT OUT
	PA8	MCO1	TIM1_CH1	HRTIM_CHB2	TIM8_BKIN2	I2C3_SCL	-	-	USART1_CK	-	-	OTG_FS_SOFTWARE	UART7_RX	TIM8_BKIN2_COMP12	LCD_B3	LCD_R6	EVENT OUT
	PA9	-	TIM1_CH2	HRTIM_CHC1	LPUART1_TX	I2C3_SMBA	SPI2_SCK/I2S2_CK	-	USART1_TX	-	-	-	ETH_TX_ER	-	DCMI_D0	LCD_R5	EVENT OUT
	PA10	-	TIM1_CH3	HRTIM_CHC2	LPUART1_RX	-	-	-	USART1_RX	-	-	OTG_FS_ID	MDIOS_MDIO	LCD_B4	DCMI_D1	LCD_B1	EVENT OUT
	PA11	-	TIM1_CH4	HRTIM_CHD1	LPUART1_CTS	-	SPI2_NSS/I2S2_WS	UART4_RX	USART1_CTS/USART1_NSS	-	FDCAN1_RX	OTG_FS_DM	-	-	-	LCD_R4	EVENT OUT

Pinout, pin description and alternate functions

STM32H755xI

Table 9. Alternate functions

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
Port A	SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/TIM8/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/SAI1/3/I2C4/UART4/DFSDM	SPI2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SAI2/4/USART4/5/8/LPUART/SDMMC1/SPDIFRX1	SAI4/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SAI2/4/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/TIM8/DFSDM/SDMMC2/MDIOS/ETH	TIM1/8/FMC/SDMMC1/MDIOS/OTG_FS1/LCD	TIM1/DCMI/LCD/COMP	UART5/LCD	SYS	
	PA12	-	TIM1_ETR	HRTIM_CHD2	LPUART1_RTS/LPUART1_DE	-	SPI2_SCK/I2S2_CK	UART4_TX	USART1_RTS/USART1_DE	SAI2_FS_B	FDCAN1_TX	OTG_FS_DPin	-	-	-	LCD_R5	EVENT OUT
	PA13	JTMS-SWDIO	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENT OUT
	PA14	JTCK-SWCLK	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENT OUT
	PA15	JTDI	TIM2_CH1/TIM2_ETR	HRTIM_FLT1	-	CEC	SPI1_NSS/I2S1_WS	SPI3_NSS/I2S3_WS	SPI6_NSS	UART4_RTS/UART4_DE	-	-	UART7_TX	-	-	-	EVENT OUT
	PB0	-	TIM1_CH2N	TIM3_CH3	TIM8_CH2N	-	-	DFSDM1_CKOUT	-	UART4_CTS	LCD_R3	OTG_HS_ULPI_D1	ETH_MII_RXD2	-	-	LCD_G1	EVENT OUT
	PB1	-	TIM1_CH3N	TIM3_CH4	TIM8_CH3N	-	-	DFSDM1_DATIN1	-	-	LCD_R6	OTG_HS_ULPI_D2	ETH_MII_RXD3	-	-	LCD_G0	EVENT OUT
	PB2	RTC_OUT	-	SAI1_D1	-	DFSDM1_CKIN1	-	SAI1_SD_A	SPI3_MOSI/I2S3_SDO	SAI4_SD_A	QUADSPI_CLK	SAI4_D1	ETH_TX_ER	-	-	-	EVENT OUT
	PB3	JTDO/TRACE SWO	TIM2_CH2	HRTIM_FLT4	-	-	SPI1_SCK/I2S1_CK	SPI3_SCK/I2S3_CK	-	SPI6_SCK	SDMMC2_D2	CRS_SYNC	UART7_RX	-	-	-	EVENT OUT
	PB4	NJTRST	TIM16_BKIN	TIM3_CH1	HRTIM_EEV6	-	SPI1_MISO/I2S1_SDI	SPI3_MISO/I2S3_SDI	SPi2_NSS/I2S2_WS	SPI6_MISO	SDMMC2_D3	-	UART7_TX	-	-	-	EVENT OUT
Port B	PB5	-	TIM17_BKIN	TIM3_CH2	HRTIM_EEV7	I2C1_SMB ^A	SPI1_MOSI/I2S1_SDO	I2C4_SMB ^A	SPI3_MOSI/I2S3_SDO	SPI6_MOSI	FDCAN2_RX	OTG_HS_ULPI_D7	ETH_PPS_OUT	FMC_SDCKE1	DCMI_D10	UART5_RX	EVENT OUT
	PB6	-	TIM16_CH1N	TIM4_CH1	HRTIM_EEV8	I2C1_SCL	CEC	I2C4_SCL	USART1_TX	LPUART1_TX	FDCAN2_TX	QUADSPI_BK1_NCS	DFSDM1_DATIN5	FMC_SDNE1	DCMI_D5	UART5_TX	EVENT OUT
	PB7	-	TIM17_CH1N	TIM4_CH2	HRTIM_EEV9	I2C1_SDA	-	I2C4_SDA	USART1_RX	LPUART1_RX	-	-	DFSDM1_CKIN5	FMC_NL	DCMI_VSYNC	-	EVENT OUT
	PB8	-	TIM16_CH1	TIM4_CH3	DFSDM1_CKIN7	I2C1_SCL	-	I2C4_SCL	SDMMC1_CKIN	UART4_RX	FDCAN1_RX	SDMMC2_D4	ETH_MII_TXD3	SDMMC1_D4	DCMI_D6	LCD_B6	EVENT OUT
	PB9	-	TIM17_CH1	TIM4_CH4	DFSDM1_DATIN7	I2C1_SDA	SPI2_NSS/I2S2_WS	I2C4_SDA	SDMMC1_CDIN	UART4_TX	FDCAN1_TX	SDMMC2_D5	I2C4_SMBA	SDMMC1_D5	DCMI_D7	LCD_B7	EVENT OUT

Table 9. Alternate functions

		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
Port	SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/TIM8/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/SPI1/3/I2C4/UART4/DFSDM	SPI2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SPI2/4/USART4/5/8/LPUART/SDMMC1/SPDIFRX1	SAI4/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SAI2/4/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/SWPMI1/TIM18/DFSDM/SDMMC2/MDIOS/ETH	TIM1/8/FMC/SDMMC1/TIM18/DFSDM/SDMMC2/MDIOS/OTG_FS1/LCD	TIM1/DCMI/LCD/COMP	UART5/LCD	SYS	
Port B	PB10	-	TIM2_CH3	HRTIM_SCOUT	LPTIM2_IN1	I2C2_SCL	SPI2_SCK/I2S2_CK	DFSDM1_DATIN7	USART3_TX	-	QUADSPI_BK1_NCS	OTG_HS_ULPI_D3	ETH_MII_RX_ER	-	-	LCD_G4	EVENT OUT
	PB11	-	TIM2_CH4	HRTIM_SCIN	LPTIM2_ETR	I2C2_SDA	-	DFSDM1_CKIN7	USART3_RX	-	-	OTG_HS_ULPI_D4	ETH_MII_TX_EN/ETH_RMIITX_EN	-	-	LCD_G5	EVENT OUT
	PB12	-	TIM1_BKIN	-	-	I2C2_SMBA	SPI2 NSS/I2S2_WS	DFSDM1_DATIN1	USART3_CK	-	FDCAN2_RX	OTG_HS_ULPI_D5	ETH_MII_TXD0/ETH_RMIITXD0	OTG_HS_ID	TIM1_BKIN_COMP12	UART5_RX	EVENT OUT
	PB13	-	TIM1_CH1N	-	LPTIM2_OUT	-	SPI2_SCK/I2S2_CK	DFSDM1_CKIN1	USART3_CTS/USART3_NSS	-	FDCAN2_TX	OTG_HS_ULPI_D6	ETH_MII_TXD1/ETH_RMIITXD1	-	-	UART5_TX	EVENT OUT
	PB14	-	TIM1_CH2N	TIM12_CH1	TIM8_CH2N	USART1_TX	SPI2_MISO/I2S2_SDI	DFSDM1_DATIN2	USART3_RTS/USART3_DE	UART4_RTS/USART4_DE	SDMMC2_D0	-	-	OTG_HS_DM	-	-	EVENT OUT
	PB15	RTC_REFIN	TIM1_CH3N	TIM12_CH2	TIM8_CH3N	USART1_RX	SPI2_MOSI/I2S2_SDO	DFSDM1_CKIN2	-	UART4_CTS	SDMMC2_D1	-	-	OTG_HS_DP	-	-	EVENT OUT
Port C	PC0	-	-	-	DFSDM1_CKIN0	-	-	DFSDM1_DATIN4	-	SAI2_FS_B	-	OTG_HS_ULPI_STP	-	FMC_SDNWE	-	LCD_R5	EVENT OUT
	PC1	TRACED0	-	SAI1_D1	DFSDM1_DATIN0	DFSDM1_CKIN4	SPI2_MOSI/I2S2_SDO	SAI1_SD_A	-	SAI4_SD_A	SDMMC2_CK	SAI4_D1	ETH_MDC	MDIOS_MDC	-	-	EVENT OUT
	PC2	C1DSLEEP	-	-	DFSDM1_CKIN1	-	SPI2_MISO/I2S2_SDI	DFSDM1_CKOUT	-	-	-	OTG_HS_ULPI_DIR	ETH_MII_TXD2	FMC_SDNE0	-	-	EVENT OUT
	PC3	C1SLEEP	-	-	DFSDM1_DATIN1	-	SPI2_MOSI/I2S2_SDO	-	-	-	-	OTG_HS_ULPI_NXT	ETH_MII_TX_CLK	FMC_SDCKE0	-	-	EVENT OUT
	PC4	C2DSLEEP	-	-	DFSDM1_CKIN2	-	I2S1_MCK	-	-	-	SPDIFRX1_IN3	-	ETH_MII_RXD0/ETH_RMIIRXD0	FMC_SDNE0	-	-	EVENT OUT
	PC5	C2SLEEP	-	SAI1_D3	DFSDM1_DATIN2	-	-	-	-	-	SPDIFRX1_IN4	SAI4_D3	ETH_MII_RXD1/ETH_RMIIRXD1	FMC_SDCKE0	COMP1_OUT	-	EVENT OUT



Table 9. Alternate functions

STM32H755xI

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/TIM8/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/SPI1/3/I2C4/UART4/DFSDM	SPI2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SPI2/4/USART4/5/8/LPUART/SDMMC1/SPDIFRX1	SAI4/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SAI2/4/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS/ETH	TIM1/8/FMC/SDMMC1/MDIOS/OTG_FS1/LCD	TIM1/DCMI/LCD/COMP	UART5/LCD	SYS
Port C	PC6	-	HRTIM_CHA1	TIM3_CH1	TIM8_CH1	DFSDM1_CKIN3	I2S2_MCK	-	USART6_TX	SDMMC1_DODIR	FMC_NWAIT	SDMMC2_D6	-	SDMMC1_D6	DCMI_D0	LCD_HSYNC	EVENT OUT
	PC7	TRGIO	HRTIM_CHA2	TIM3_CH2	TIM8_CH2	DFSDM1_DATIN3	-	I2S3_MCK	USART6_RX	SDMMC1_D123DIR	FMC_NE1	SDMMC2_D7	SWPMI_TX	SDMMC1_D7	DCMI_D1	LCD_G6	EVENT OUT
	PC8	TRACED1	HRTIM_CHB1	TIM3_CH3	TIM8_CH3	-	-	-	USART6_CK	UART5_RTS/UART5_DE	FMC_NE2/FMC_NCE	-	SWPMI_RX	SDMMC1_D0	DCMI_D2	-	EVENT OUT
	PC9	MCO2	-	TIM3_CH4	TIM8_CH4	I2C3_SDA	I2S_CKIN	-	-	UART5_CTS	QUADSPI_BK1_IO0	LCD_G3	SWPMI_SUSPEND	SDMMC1_D1	DCMI_D3	LCD_B2	EVENT OUT
	PC10	-	-	HRTIM_EEV1	DFSDM1_CKIN5	-	-	SPI3_SCK/I2S3_CK	USART3_TX	UART4_TX	QUADSPI_BK1_IO1	-	-	SDMMC1_D2	DCMI_D8	LCD_R2	EVENT OUT
	PC11	-	-	HRTIM_FLT2	DFSDM1_DATIN5	-	-	SPI3_MISO/I2S3_SDI	USART3_RX	UART4_RX	QUADSPI_BK2_NCS	-	-	SDMMC1_D3	DCMI_D4	-	EVENT OUT
	PC12	TRACED3	-	HRTIM_EEV2	-	-	-	SPI3_MOSI/I2S3_SDO	USART3_CK	UART5_TX	-	-	-	SDMMC1_CK	DCMI_D9	-	EVENT OUT
	PC13	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENT OUT
	PC14	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENT OUT
	PC15	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENT OUT
Port D	PD0	-	-	-	DFSDM1_CKIN6	-	-	SAI3_SCK_A	-	UART4_RX	FDCAN1_RX	-	-	FMC_D2/FMC_DA2	-	-	EVENT OUT
	PD1	-	-	-	DFSDM1_DATIN6	-	-	SAI3_SD_A	-	UART4_TX	FDCAN1_TX	-	-	FMC_D3/FMC_DA3	-	-	EVENT OUT
	PD2	TRACED2	-	TIM3_ETR	-	-	-	-	-	UART5_RX	-	-	-	SDMMC1_CMD	DCMI_D11	-	EVENT OUT
	PD3	-	-	-	DFSDM1_CKOUT	-	SPI2_SCK/I2S2_CK	-	USART2_CTS/USART2_NSS	-	-	-	-	FMC_CLK	DCMI_D5	LCD_G7	EVENT OUT
	PD4	-	-	HRTIM_FLT3	-	-	-	SAI3_FS_A	USART2_RTS/USART2_DE	-	-	-	-	FMC_NOE	-	-	EVENT OUT

Table 9. Alternate functions

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/TIM8/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/SAI1/3/I2C4/UART4/DFSDM	SPI2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SAI2/4/USART4/5/8/LPUART/SDMMC1/SPDIFRX1	SPI4/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SPI2/4/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS/ETH	TIM1/8/FMC/SDDMMC1/MDIOS/OTG_FS1/LCD	TIM1/DCMI/SDDMMC1/MDIOS/OTG_FS1/LCD	UART5/LCD	SYS	
PD5	-	-	HRTIM_EEV3	-	-	-	-	USART2_TX	-	-	-	-	FMC_NWE	-	-	EVENT OUT
PD6	-	-	SAI1_D1	DFSDM1_CKIN4	DFSDM1_DATIN1	SPI3_MOS_I/I2S3_SDO	SAI1_SD_A	USART2_RX	SAI4_SD_A	-	SAI4_D1	SDMMC2_CK	FMC_NWAIT	DCMI_D10	LCD_B2	EVENT OUT
PD7	-	-	-	DFSDM1_DATIN4	-	SPI1_MOS_I/I2S1_SDO	DFSDM1_CKIN1	USART2_CK	-	SPDIFRX1_IN1	-	SDMMC2_CMD	FMC_NE1	-	-	EVENT OUT
PD8	-	-	-	DFSDM1_CKIN3	-	-	SAI3_SCK_B	USART3_TX	-	SPDIFRX1_IN2	-	-	FMC_D13/FMC_DA13	-	-	EVENT OUT
PD9	-	-	-	DFSDM1_DATIN3	-	-	SAI3_SD_B	USART3_RX	-	-	-	-	FMC_D14/FMC_DA14	-	-	EVENT OUT
PD10	-	-	-	DFSDM1_CKOUT	-	-	SAI3_FS_B	USART3_CK	-	-	-	-	FMC_D15/FMC_DA15	-	LCD_B3	EVENT OUT
PD11	-	-	-	LPTIM2_IN2	I2C4_SMBA	-	-	USART3_CTS/USART3_NSS	-	QUADSPI_BK1_IO0	SAI2_SD_A	-	FMC_A16	-	-	EVENT OUT
PD12	-	LPTIM1_IN1	TIM4_CH1	LPTIM2_IN1	I2C4_SCL	-	-	USART3_RTS/USART3_DE	-	QUADSPI_BK1_IO1	SAI2_FS_A	-	FMC_A17	-	-	EVENT OUT
PD13	-	LPTIM1_OUT	TIM4_CH2	-	I2C4_SDA	-	-	-	-	QUADSPI_BK1_IO3	SAI2_SCK_A	-	FMC_A18	-	-	EVENT OUT
PD14	-	-	TIM4_CH3	-	-	SAI3_MCLK_B	-	UART8_CTS	-	-	-	-	FMC_D0/FMC_DA0	-	-	EVENT OUT
PD15	-	-	TIM4_CH4	-	-	SAI3_MCLK_A	-	UART8_RTS/UART8_DE	-	-	-	-	FMC_D1/FMC_DA1	-	-	EVENT OUT

Pinout, pin description and alternate functions

STM32H755xI

Table 9. Alternate functions

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15	
SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/LTIM8/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/SAI1/3/I2C4/UART4/DFSDM	SPI2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SAI2/4/USART4/5/8/LPUART/SDMMC1/SPDIFRX1	SPI4/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SAI2/4/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS/ETH	TIM1/8/FMC/SDDMMC1/MDIOS/OTG_FS1/LCD	TIM1/DCMI/LCD/COMP	UART5/LCD	SYS		
E I/O	PE0	-	LPTIM1_ETR	TIM4_ETR	HRTIM_SCIN	LPTIM2_ETR	-	-	-	UART8_RX	-	SAI2_MCLK_A	-	FMC_NBL0	DCMI_D2	-	EVENT OUT
	PE1	-	LPTIM1_IN2	-	HRTIM_SCOUT	-	-	-	-	UART8_TX	-	-	-	FMC_NBL1	DCMI_D3	-	EVENT OUT
	PE2	TRACE CLK	-	SAI1_CK1	-	-	SPI4_SCK	SAI1_MCLK_A	-	SAI4_MCLK_A	QUADSPI_BK1_IO2	SAI4_CK1	ETH_MII_TXD3	FMC_A23	-	-	EVENT OUT
	PE3	TRACED0	-	-	-	TIM15_BKIN	-	SAI1_SD_B	-	SAI4_SD_B	-	-	-	FMC_A19	-	-	EVENT OUT
	PE4	TRACED1	-	SAI1_D2	DFSDM1_DATIN3	TIM15_CH1N	SPI4 NSS	SAI1_FS_A	-	SAI4_FS_A	-	SAI4_D2	-	FMC_A20	DCMI_D4	LCD_B0	EVENT OUT
	PE5	TRACED2	-	SAI1_CK2	DFSDM1_CKIN3	TIM15_CH1	SPI4_MISO	SAI1_SCK_A	-	SAI4_SCK_A	-	SAI4_CK2	-	FMC_A21	DCMI_D6	LCD_G0	EVENT OUT
	PE6	TRACED3	TIM1_BKIN2	SAI1_D1	-	TIM15_CH2	SPI4_MOSI	SAI1_SD_A	-	SAI4_SD_A	SAI4_D1	SAI2_MCL_K_B	TIM1_BKIN2_COMP12	FMC_A22	DCMI_D7	LCD_G1	EVENT OUT
	PE7	-	TIM1_ETR	-	DFSDM1_DATIN2	-	-	-	UART7_RX	-	-	QUADSPI_BK2_IO0	-	FMC_D4/FMC_DA4	-	-	EVENT OUT
	PE8	-	TIM1_CH1N	-	DFSDM1_CKIN2	-	-	-	UART7_TX	-	-	QUADSPI_BK2_IO1	-	FMC_D5/FMC_DA5	COMP2_OUT	-	EVENT OUT
	PE9	-	TIM1_CH1	-	DFSDM1_CKOUT	-	-	-	UART7_RTS/UART7_DE	-	-	QUADSPI_BK2_IO2	-	FMC_D6/FMC_DA6	-	-	EVENT OUT
	PE10	-	TIM1_CH2_N	-	DFSDM1_DATIN4	-	-	-	UART7_CTS	-	-	QUADSPI_BK2_IO3	-	FMC_D7/FMC_DA7	-	-	EVENT OUT
	PE11	-	TIM1_CH2	-	DFSDM1_CKIN4	-	SPI4 NSS	-	-	-	-	SAI2_SD_B	-	FMC_D8/FMC_DA8	-	LCD_G3	EVENT OUT
	PE12	-	TIM1_CH3	-	DFSDM1_DATIN5	-	SPI4_SCK	-	-	-	-	SAI2_SCK_B	-	FMC_D9/FMC_DA9	COMP1_OUT	LCD_B4	EVENT OUT
	PE13	-	TIM1_CH3	-	DFSDM1_CKIN5	-	SPI4_MISO	-	-	-	-	SAI2_FS_B	-	FMC_D10/FMC_DA10	COMP2_OUT	LCD_DE	EVENT OUT
	PE14	-	TIM1_CH4	-	-	-	SPI4_MOS_I	-	-	-	-	SAI2_MCL_K_B	-	FMC_D11/FMC_DA11	-	LCD_CLK	EVENT OUT
	PE15	-	TIM1_BKIN	-	-	-	-	-	-	-	-	-	-	FMC_D12/FMC_DA12	TIM1_BKIN_COMP12/COMP_TIM1_BKIN	LCD_R7	EVENT OUT

Table 9. Alternate functions

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
	SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SAI2/4/UART4/5/8/LPUART/SDMMC1/SPDIFRX1	SPI14/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SPI2/4/UART7/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/TIM8/SWPMI1/TIM18/DFSDM/SDMMC2/MDIOS/OTG_FS1/LCD/ETH	TIM1/8/FMC/SDMMC1/MDIOS/OTG_FS1/LCD	TIM1/DCMI/LCD/COMP	UART5/LCD	SYS		
Port F	PF0	-	-	-	-	I2C2_SDA	-	-	-	-	-	-	FMC_A0	-	-	EVENT OUT	
	PF1	-	-	-	-	I2C2_SCL	-	-	-	-	-	-	FMC_A1	-	-	EVENT OUT	
	PF2	-	-	-	-	I2C2_SMBA	-	-	-	-	-	-	FMC_A2	-	-	EVENT OUT	
	PF3	-	-	-	-	-	-	-	-	-	-	-	FMC_A3	-	-	EVENT OUT	
	PF4	-	-	-	-	-	-	-	-	-	-	-	FMC_A4	-	-	EVENT OUT	
	PF5	-	-	-	-	-	-	-	-	-	-	-	FMC_A5	-	-	EVENT OUT	
	PF6	-	TIM16_CH1	-	-	-	SPI5_NSS	SAI1_SD_B	UART7_RX	SAI4_SD_B	QUADSPI_BK1_IO3	-	-	-	-	EVENT OUT	
	PF7	-	TIM17_CH1	-	-	-	SPI5_SCK	SAI1_MCLK_B	UART7_TX	SAI4_MCLK_B	QUADSPI_BK1_IO2	-	-	-	-	EVENT OUT	
	PF8	-	TIM16_CH1N	-	-	-	SPI5_MISO	SAI1_SCK_B	UART7_RTS_UART7_DE	SAI4_SCK_B	TIM13_CH1	QUADSPI_BK1_IO0	-	-	-	EVENT OUT	
	PF9	-	TIM17_CH1N	-	-	-	SPI5_MOSI	SAI1_FS_B	UART7_CTS	SAI4_FS_B	TIM14_CH1	QUADSPI_BK1_IO1	-	-	-	EVENT OUT	
	PF10	-	TIM16_BKIN	SAI1_D3	-	-	-	-	-	-	QUADSPI_CLK	SAI4_D3	-	-	DCMI_D11	LCD_DE	EVENT OUT
	PF11	-	-	-	-	-	SPI5_MOSI	-	-	-	SAI2_SD_B	-	FMC_SDNRAS	DCMI_D12	-	EVENT OUT	
	PF12	-	-	-	-	-	-	-	-	-	-	-	FMC_A6	-	-	EVENT OUT	
	PF13	-	-	-	DFSDM1_DATIN6	I2C4_SMBA	-	-	-	-	-	-	FMC_A7	-	-	EVENT OUT	
	PF14	-	-	-	DFSDM1_CKIN6	I2C4_SCL	-	-	-	-	-	-	FMC_A8	-	-	EVENT OUT	
	PF15	-	-	-	-	I2C4_SDA	-	-	-	-	-	-	FMC_A9	-	-	EVENT OUT	

Pinout, pin description and alternate functions

STM32H755xI

Table 9. Alternate functions

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15		
Port G	SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/TIM8/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/SAI1/3/I2C4/UART4/DFSDM	SPI2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SAI2/4/UART4/5/8/LPUART/SDMMC1/SPDIFRX1	SAI4/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SAI2/4/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/SWPMI1/TIM18/DFSDM/SDMMC2/MDIOS/ETH	TIM1/8/FMC/SDMMC1/MDIOS/OTG_FS1/LCD	TIM1/DCMI/LCD/COMP	UART5/LCD	SYS		
	PG0	-	-	-	-	-	-	-	-	-	-	-	FMC_A10	-	-	EVENT OUT		
	PG1	-	-	-	-	-	-	-	-	-	-	-	FMC_A11	-	-	EVENT OUT		
	PG2	-	-	-	TIM8_BKIN	-	-	-	-	-	-	-	TIM8_BKIN_COMP12	FMC_A12	-	-	EVENT OUT	
	PG3	-	-	-	TIM8_BKIN2	-	-	-	-	-	-	-	TIM8_BKIN2_COMP12	FMC_A13	-	-	EVENT OUT	
	PG4	-	TIM1_BKIN2	-	-	-	-	-	-	-	-	-	TIM1_BKIN2_COMP12	FMC_A14/FMC_BA0	-	-	EVENT OUT	
	PG5	-	TIM1_ETR	-	-	-	-	-	-	-	-	-	-	FMC_A15/FMC_BA1	-	-	EVENT OUT	
	PG6	-	TIM17_BKIN	HRTIM_CHE1	-	-	-	-	-	-	-	-	QUADSPI_BK1_NCS	-	FMC_NE3	DCMI_D12	LCD_R7	EVENT OUT
	PG7	-	-	HRTIM_CHE2	-	-	-	SAI1_MCLK_A	USART6_CK	-	-	-	-	FMC_INT	DCMI_D13	LCD_CLK	EVENT OUT	
	PG8	-	-	-	TIM8_ETR	-	SPI6 NSS	-	USART6 RTS/USART6 DE	SPDIFRX1_IN3	-	-	ETH_PPS_OUT	FMC_SDC_LK	-	LCD_G7	EVENT OUT	
	PG9	-	-	-	-	-	SPI1_MISO/I2S1_SD1	-	USART6_RX	SPDIFRX1_IN4	QUADSPI_BK2_IO2	SAI2_FS_B	-	FMC_NE2/FMC_NCE	DCMI_VSYNC	-	EVENT OUT	
	PG10	-	-	HRTIM_FLT5	-	-	SPI1 NSS/I2S1 WS	-	-	-	LCD_G3	SAI2_SD_B	-	FMC_NE3	DCMI_D2	LCD_B2	EVENT OUT	
	PG11	-	LPTIM1_IN2	HRTIM_EEV4	-	-	SPI1 SCK/I2S1 CK	-	-	SPDIFRX1_IN1	-	SDMMC2_D2	ETH_MII_TX_EN/ETH_RMII_TX_EN	-	DCMI_D3	LCD_B3	EVENT OUT	

Table 9. Alternate functions

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/TIM8/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/SAI1/3/I2C4/UART4/DFSDM	SPI2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SAI2/4/USART4/5/8/LPUART/SDMMC1/SPDIFRX1	SAI4/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SAI2/4/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/SWPMI1/TIM18/DFSDM/SDMMC2/MDIOS/OTG_FS1/LCD/ETH	TIM1/8/FMC/SDMMC1/MDIOS/OTG_FS1/LCD	TIM1/DCMI/LCD/COMP	UART5/LCD	SYS
Port G	PG12	-	LPTIM1_IN1	HRTIM_EEV5	-	-	SPI6_MISO	-	USART6_RTS_USART6_DE	SPDIFRX1_IN2	LCD_B4	-	ETH_MII_TXD1/ETH_RMIITXD1	FMC_NE4	-	LCD_B1	EVENT OUT
	PG13	TRACED0	LPTIM1_OUT	HRTIM_EEV10	-	-	SPI6_SCK	-	USART6_CTS_USART6_NSS	-	-	-	ETH_MII_TXD0/ETH_RMIITXD0	FMC_A24	-	LCD_R0	EVENT OUT
	PG14	TRACED1	LPTIM1_ETR	-	-	-	SPI6_MOSI	-	USART6_TX	-	QUADSPI_BK2_IO3	-	ETH_MII_TXD1/ETH_RMIITXD1	FMC_A25	-	LCD_B0	EVENT OUT
	PG15	-	-	-	-	-	-	-	USART6_CTS_USART6_NSS	-	-	-	-	FMC_SDNCAS	DCMI_D13	-	EVENT OUT
Port H	PH0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENT OUT
	PH1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENT OUT
	PH2	-	LPTIM1_IN2	-	-	-	-	-	-	-	QUADSPI_BK2_IO0	SAI2_SCK_B	ETH_MII_CRS	FMC_SDCKE0	-	LCD_R0	EVENT OUT
	PH3	-	-	-	-	-	-	-	-	-	QUADSPI_BK2_IO1	SAI2_MCLK_B	ETH_MII_COL	FMC_SDNE0	-	LCD_R1	EVENT OUT
	PH4	-	-	-	-	I2C2_SCL	-	-	-	-	LCD_G5	OTG_HS_ULPI_NXT	-	-	-	LCD_G4	EVENT OUT
	PH5	-	-	-	-	I2C2_SDA	SPI5_NSS	-	-	-	-	-	-	FMC_SDNWE	-	-	EVENT OUT
	PH6	-	-	TIM12_CH1	-	I2C2_SMBA	SPI5_SCK	-	-	-	-	-	ETH_MII_RXD2	FMC_SDNE1	DCMI_D8	-	EVENT OUT
	PH7	-	-	-	-	I2C3_SCL	SPI5_MISO	-	-	-	-	-	ETH_MII_RXD3	FMC_SDC KE1	DCMI_D9	-	EVENT OUT
	PH8	-	-	TIM5_ETR	-	I2C3_SDA	-	-	-	-	-	-	-	FMC_D16	DCMI_HSYNC	LCD_R2	EVENT OUT
	PH9	-	-	TIM12_CH2	-	I2C3_SMBA	-	-	-	-	-	-	-	FMC_D17	DCMI_D0	LCD_R3	EVENT OUT

Pinout, pin description and alternate functions

STM32H755xI

Table 9. Alternate functions

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/TIM8/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/SAI1/3/I2C4/UART4/DFSDM	SPI2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SAI2/4/UART4/5/8/LPUART/SDMMC1/SPDIFRX1	SAI4/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SAI2/4/UART7/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS/ETH	SWPMI1/TIM1/8/DFSDM/SDMMC2/MDIOS/OTG_FS1/LCD	FMC_D18/DCMI_D1	DCMI_D2	LCD_R5	UART5/LCD	SYS
Port H	PH10	-	-	TIM5_CH1	-	I2C4_SMBA	-	-	-	-	-	-	-	FMC_D18	DCMI_D1	LCD_R4	EVENT OUT
	PH11	-	-	TIM5_CH2	-	I2C4_SCL	-	-	-	-	-	-	-	FMC_D19	DCMI_D2	LCD_R5	EVENT OUT
	PH12	-	-	TIM5_CH3	-	I2C4_SDA	-	-	-	-	-	-	-	FMC_D20	DCMI_D3	LCD_R6	EVENT OUT
	PH13	-	-	-	TIM8_CH1N	-	-	-	-	UART4_TX	FDCAN1_TX	-	-	FMC_D21	-	LCD_G2	EVENT OUT
	PH14	-	-	-	TIM8_CH2N	-	-	-	-	UART4_RX	FDCAN1_RX	-	-	FMC_D22	DCMI_D4	LCD_G3	EVENT OUT
	PH15	-	-	-	TIM8_CH3N	-	-	-	-	-	-	-	-	FMC_D23	DCMI_D11	LCD_G4	EVENT OUT
	PI0	-	-	TIM5_CH4	-	-	SPI2_NSS/I2S2_WS	-	-	-	-	-	-	FMC_D24	DCMI_D13	LCD_G5	EVENT OUT
	PI1	-	-	-	TIM8_BKIN2	-	SPI2_SCK/I2S2_CK	-	-	-	-	-	TIM8_BKIN2_COMP12	FMC_D25	DCMI_D8	LCD_G6	EVENT OUT
	PI2	-	-	-	TIM8_CH4	-	SPI2_MISO/I2S2_SD1	-	-	-	-	-	-	FMC_D26	DCMI_D9	LCD_G7	EVENT OUT
	PI3	-	-	-	TIM8_ETR	-	SPI2_MOSI/I2S2_SDO	-	-	-	-	-	-	FMC_D27	DCMI_D10	-	EVENT OUT
Port I	PI4	-	-	-	TIM8_BKIN	-	-	-	-	-	SAI2_MCLK_A	TIM8_BKIN_COMP12	FMC_NBL2	DCMI_D5	LCD_B4	EVENT OUT	
	PI5	-	-	-	TIM8_CH1	-	-	-	-	-	SAI2_SCK_A	-	FMC_NBL3	DCMI_VSYNC	LCD_B5	EVENT OUT	
	PI6	-	-	-	TIM8_CH2	-	-	-	-	-	SAI2_SD_A	-	FMC_D28	DCMI_D6	LCD_B6	EVENT OUT	
	PI7	-	-	-	TIM8_CH3	-	-	-	-	-	SAI2_FS_A	-	FMC_D29	DCMI_D7	LCD_B7	EVENT OUT	
	PI8	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVENT OUT	

Table 9. Alternate functions

Port	AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/LTIM8/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/SAI1/3/I2C4/UART4/DFSDM	SPI2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SAI2/4/UART4/5/8/LPUART/SDMMC1/SPDIFRX1	SPI14/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SPI2/4/SAI2/4/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/SWPMI1/TIM18/DFSDM/SDMMC2/MDIOS/ETH	TIM1/8/FMC/SDMMC1/MDIOS/OTG_FS1/LCD	TIM1/DCMI/LCD/COMP	UART5/LCD	SYS
Port I	PI9	-	-	-	-	-	-	-	UART4_RX	FDCAN1_RX	-	-	FMC_D30	-	LCD_VSYNC	EVENT OUT
	PI10	-	-	-	-	-	-	-	-	-	-	ETH_MII_RX_ER	FMC_D31	-	LCD_HSYNC	EVENT OUT
	PI11	-	-	-	-	-	-	-	-	LCD_G6	OTG_HS_ULPI_DIR	-	-	-	-	EVENT OUT
	PI12	-	-	-	-	-	-	-	-	-	-	ETH_TX_ER	-	-	LCD_HSYNC	EVENT OUT
	PI13	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_VSYNC	EVENT OUT
	PI14	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_CLK	EVENT OUT
	PI15	-	-	-	-	-	-	-	-	LCD_G2	-	-	-	-	LCD_R0	EVENT OUT
Port J	PJ0	-	-	-	-	-	-	-	-	LCD_R7	-	-	-	-	LCD_R1	EVENT OUT
	PJ1	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R2	EVENT OUT
	PJ2	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R3	EVENT OUT
	PJ3	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R4	EVENT OUT
	PJ4	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R5	EVENT OUT
	PJ5	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_R6	EVENT OUT
	PJ6	-	-	-	TIM8_CH2	-	-	-	-	-	-	-	-	-	LCD_R7	EVENT OUT
	PJ7	TRGIN	-	-	TIM8_CH2N	-	-	-	-	-	-	-	-	-	LCD_G0	EVENT OUT
	PJ8	-	TIM1_CH3N	-	TIM8_CH1	-	-	-	-	UART8_TX	-	-	-	-	LCD_G1	EVENT OUT

Pinout, pin description and alternate functions

STM32H755xI

Table 9. Alternate functions

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
SYS	TIM1/2/16/17/LPTIM1/HRTIM1	SAI1/TIM3/4/5/12/HRTIM1	LPUART/LPTIM2/3/4/5/HRTIM1/DFSDM	I2C1/2/3/4/USART1/TIM15/LPTIM2/DFSDM/CEC	SPI1/2/3/4/5/6/CEC	SPI2/3/SAI1/3/I2C4/UART4/DFSDM	SPI2/3/6/USART1/2/3/6/UART7/SDMMC1	SPI6/SAI2/4/UART4/5/8/LPUART/SDMMC1/SPDIFRX1	SAI4/FDCAN1/FDACN2/TIM13/14/QUADSPI/SDMMC2/FMC/SDMMC2/LCD/SPDIFRX1	SAI2/4/TIM8/QUADSPI/SDMMC2/OTG_HS1/OTG_FS2/LCD/CRS	I2C4/UART7/SWPMI1/TIM18/DFSDM/SDMMC2/MDIOS/ETH	TIM1/8/FMC/SDMMC1/MDIOS/OTG_FS1/LCD	TIM1/DCMI/LCD/COMP	UART5/LCD	SYS		
Port J	PJ9	-	TIM1_CH3	-	TIM8_CH1N	-	-	-	-	UART8_RX	-	-	-	-	-	LCD_G2	EVENT OUT
	PJ10	-	TIM1_CH2N	-	TIM8_CH2	-	SPI5_MOSI	-	-	-	-	-	-	-	-	LCD_G3	EVENT OUT
	PJ11	-	TIM1_CH2	-	TIM8_CH2N	-	SPI5_MISO	-	-	-	-	-	-	-	-	LCD_G4	EVENT OUT
	PJ12	TRGOUT	-	-	-	-	-	-	-	-	LCD_G3	-	-	-	-	LCD_B0	EVENT OUT
	PJ13	-	-	-	-	-	-	-	-	-	LCD_B4	-	-	-	-	LCD_B1	EVENT OUT
	PJ14	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B2	EVENT OUT
	PJ15	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B3	EVENT OUT
Port K	PK0	-	TIM1_CH1N	-	TIM8_CH3	-	SPI5_SCK	-	-	-	-	-	-	-	-	LCD_G5	EVENT OUT
	PK1	-	TIM1_CH1	-	TIM8_CH3N	-	SPI5_NSS	-	-	-	-	-	-	-	-	LCD_G6	EVENT OUT
	PK2	-	TIM1_BKIN	-	TIM8_BKIN	-	-	-	-	-	TIM8_BKIN_COMP12	TIM1_BKIN_COMP12	-	-	-	LCD_G7	EVENT OUT
	PK3	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B4	EVENT OUT
	PK4	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B5	EVENT OUT
	PK5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B6	EVENT OUT
	PK6	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_B7	EVENT OUT
	PK7	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LCD_DE	EVENT OUT

6 Electrical characteristics

6.1 Parameter conditions

Unless otherwise specified, all voltages are referenced to V_{SS}.

6.1.1 Minimum and maximum values

Unless otherwise specified the minimum and maximum values are guaranteed in the worst conditions of junction temperature, supply voltage and frequencies by tests in production on 100% of the devices with an junction temperature at T_J = 25 °C and T_J = T_{Jmax} (given by the selected temperature range).

Data based on characterization results, design simulation and/or technology characteristics are indicated in the table footnotes. Based on characterization, the minimum and maximum values refer to sample tests and represent the mean value plus or minus three times the standard deviation (mean±3σ).

6.1.2 Typical values

Unless otherwise specified, typical data are based on T_J = 25 °C, V_{DD} = 3.3 V (for the 1.7 V ≤ V_{DD} ≤ 3.6 V voltage range). They are given only as design guidelines and are not tested.

Typical ADC accuracy values are determined by characterization of a batch of samples from a standard diffusion lot over the full temperature range, where 95% of the devices have an error less than or equal to the value indicated (mean±2σ).

6.1.3 Typical curves

Unless otherwise specified, all typical curves are given only as design guidelines and are not tested.

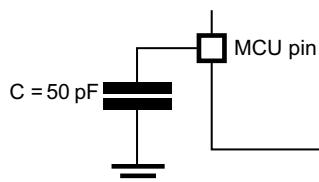
6.1.4 Loading capacitor

The loading conditions used for pin parameter measurement are shown in [Figure 11](#).

6.1.5 Pin input voltage

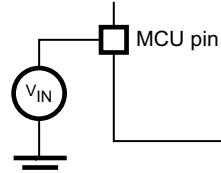
The input voltage measurement on a pin of the device is described in [Figure 12](#).

Figure 11. Pin loading conditions



MS19011V2

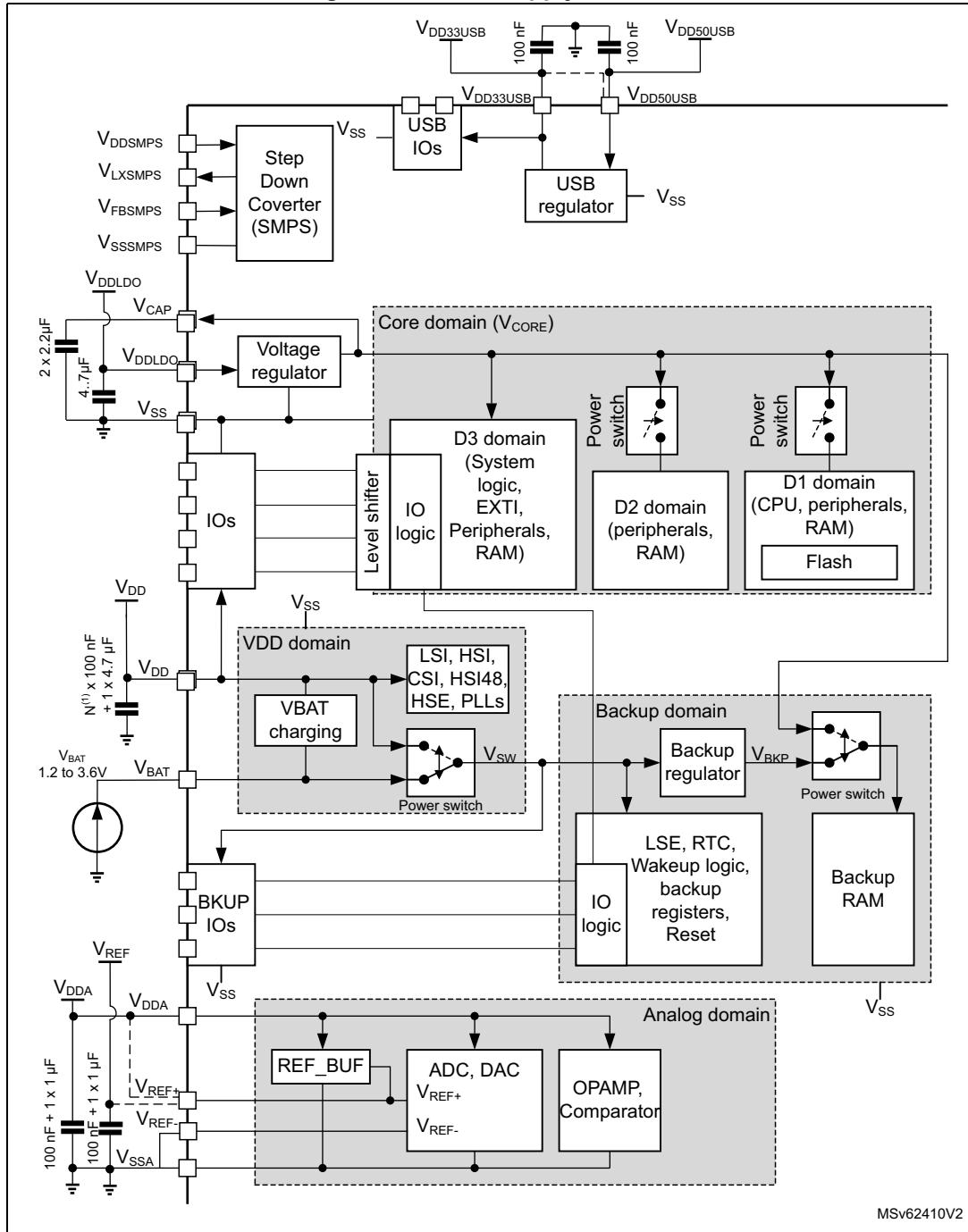
Figure 12. Pin input voltage



MS19010V2

6.1.6 Power supply scheme

Figure 13. Power supply scheme



1. N corresponds to the number of VDD pins available on the package.

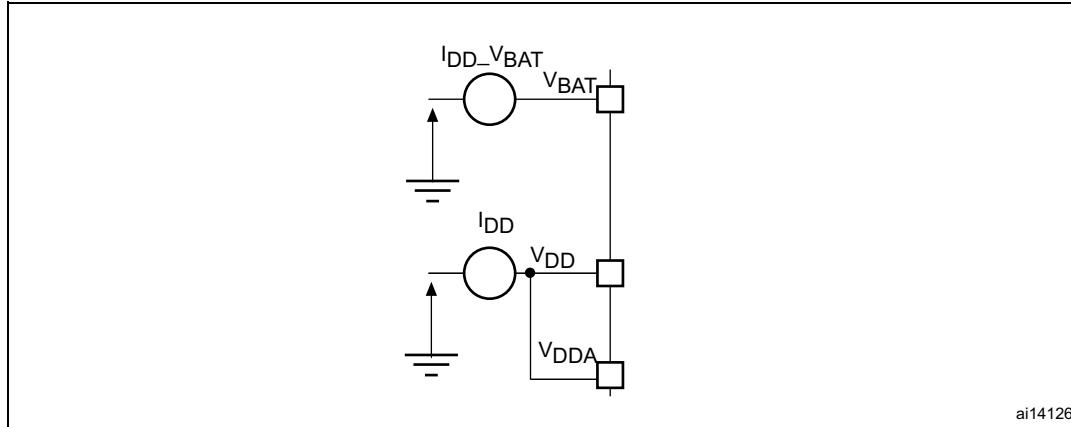
2. A tolerance of +/- 20% is acceptable on decoupling capacitors.

Caution: Each power supply pair (V_{DD}/V_{SS} , V_{DDA}/V_{SSA} ...) must be decoupled with filtering ceramic capacitors as shown above. These capacitors must be placed as close as possible to, or below, the appropriate pins on the underside of the PCB to ensure good operation of the

device. It is not recommended to remove filtering capacitors to reduce PCB size or cost. This might cause incorrect operation of the device.

6.1.7 Current consumption measurement

Figure 14. Current consumption measurement scheme



6.2 Absolute maximum ratings

Stresses above the absolute maximum ratings listed in [Table 10: Voltage characteristics](#), [Table 11: Current characteristics](#), and [Table 12: Thermal characteristics](#) may cause permanent damage to the device. These are stress ratings only and the functional operation of the device at these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability. Device mission profile (application conditions) is compliant with JEDEC JESD47 Qualification Standard, extended mission profiles are available on demand.

Note: For information on product lifetime estimation, refer to application note AN5337: Guidelines for estimating STM32H7 MCUs lifetime, available from the STMicroelectronics website www.st.com.

Table 10. Voltage characteristics ⁽¹⁾

Symbols	Ratings	Min	Max	Unit
$V_{DDX} - V_{SS}$	External main supply voltage (including V_{DD} , V_{DDLDO} , V_{DDSMPS} , V_{DDA} , $V_{DD33USB}$, V_{BAT})	-0.3	4.0	V
$V_{IN}^{(2)}$	Input voltage on FT_xxx pins	$V_{SS}-0.3$	Min(Min(V_{DD} , V_{DDA} , $V_{DD33USB}$, V_{BAT}) + 4.0, 6 V) ⁽³⁾⁽⁴⁾⁽⁵⁾	V
	Input voltage on TT_xx pins	$V_{SS}-0.3$	4.0	V
	Input voltage on BOOT0 pin	V_{SS}	9.0	V
	Input voltage on any other pins	$V_{SS}-0.3$	4.0	V
$ \Delta V_{DDX} $	Variations between different V_{DDX} power pins of the same domain	-	50	mV
$ V_{SSx}-V_{Ssl} $	Variations between all the different ground pins	-	50	mV

1. All main power (V_{DD} , V_{DDA} , $V_{DD33USB}$, V_{DDSMPS} , V_{BAT}) and ground (V_{SS} , V_{SSA}) pins must always be connected to the external power supply, in the permitted range.
2. V_{IN} maximum must always be respected. Refer to [Table 58: I/O current injection susceptibility](#) for the maximum allowed injected current values.
3. This formula has to be applied on power supplies related to the IO structure described by the pin definition table.
4. To sustain a voltage higher than 4V the internal pull-up/pull-down resistors must be disabled.
5. When an FT_a pin is used by an analog peripheral such as an ADC, the maximum V_{IN} is 4 V.

Table 11. Current characteristics

Symbols	Ratings	Max	Unit
ΣIV_{DD}	Total current into sum of all V_{DD} power lines (source) ⁽¹⁾	620	mA
ΣIV_{SS}	Total current out of sum of all V_{SS} ground lines (sink) ⁽¹⁾	620	
IV_{DD}	Maximum current into each V_{DD} power pin (source) ⁽¹⁾	100	
IV_{SS}	Maximum current out of each V_{SS} ground pin (sink) ⁽¹⁾	100	
I_{IO}	Output current sunk by any I/O and control pin, except Px_C	20	
	Output current sunk by Px_C pins	1	
$\Sigma I_{(PIN)}$	Total output current sunk by sum of all I/Os and control pins ⁽²⁾	140	
	Total output current sourced by sum of all I/Os and control pins ⁽²⁾	140	
$I_{INJ(PIN)}^{(3)(4)}$	Injected current on FT_xxx, TT_xx, RST and B pins except PA4, PA5	-5/+0	
	Injected current on PA4, PA5	-0/0	
$\Sigma I_{INJ(PIN)}$	Total injected current (sum of all I/Os and control pins) ⁽⁵⁾	± 25	

1. All main power (V_{DD} , V_{DDA} , $V_{DD33USB}$) and ground (V_{SS} , V_{SSA}) pins must always be connected to the external power supplies, in the permitted range.
2. This current consumption must be correctly distributed over all I/Os and control pins. The total output current must not be sunk/sourced between two consecutive power supply pins referring to high pin count QFP packages.
3. Positive injection is not possible on these I/Os and does not occur for input voltages lower than the specified maximum value.
4. A positive injection is induced by $V_{IN} > V_{DD}$ while a negative injection is induced by $V_{IN} < V_{SS}$. $I_{INJ(PIN)}$ must never be exceeded. Refer also to [Table 10: Voltage characteristics](#) for the maximum allowed input voltage values.
5. When several inputs are submitted to a current injection, the maximum $\Sigma I_{INJ(PIN)}$ is the absolute sum of the positive and negative injected currents (instantaneous values).

Table 12. Thermal characteristics

Symbol	Ratings	Value	Unit
T_{STG}	Storage temperature range	-65 to +150	°C
T_J	Maximum junction temperature	125 ⁽¹⁾	
		140 ⁽²⁾	

1. For industrial temperature range 6.
2. For extended industrial temperature range 3.

6.3 Operating conditions

6.3.1 General operating conditions

Table 13. General operating conditions

Symbol	Parameter	Operating conditions	Min	Typ	Max	Unit
V_{DD}	Standard operating voltage	-	1.62 ⁽¹⁾	-	3.6	V
V_{DDLDO}	Supply voltage for the internal regulator	$V_{DDLDO} \leq V_{DD}$	1.62 ⁽¹⁾	-	3.6	V
			1.2 ⁽²⁾	-	3.6	
V_{DDSMPS}	Supply voltage for the internal SMPS Step-down converter	$V_{DDSMPS} = V_{DD}$	1.62 ⁽¹⁾	-	3.6	V
$V_{DD33USB}$	Standard operating voltage, USB domain	USB used	3.0	-	3.6	V
		USB not used	0	-	3.6	
V_{DDA}	Analog operating voltage	ADC or COMP used	1.62	-	3.6	V
		DAC used	1.8	-		
		OPAMP used	2.0	-		
		VREFBUF used	1.8	-		
		ADC, DAC, OPAMP, COMP, VREFBUF not used	0	-		
V_{IN}	I/O Input voltage	TT_xx I/O	-0.3	-	$V_{DD} + 0.3$	V
		BOOT0	0	-	9	
		All I/O except BOOT0 and TT_xx	-0.3	-	$\text{Min}(V_{DD}, V_{DDA}, V_{DD33USB}) + 3.6V < 5.5V^{(3)(4)}$	

Table 13. General operating conditions (continued)

Symbol	Parameter	Operating conditions	Min	Typ	Max	Unit
V_{CORE}	Internal regulator ON (LDO)	VOS3 (max frequency 200 MHz)	0.95	1.0	1.05	V
		VOS2 (max frequency 300 MHz)	1.05	1.10	1.15	
		VOS1 (max frequency 400 MHz)	1.15	1.20	1.26	
		VOS0 ⁽⁵⁾ (max frequency 480 MHz) ⁽⁶⁾	1.26	1.35	1.40	
	Internal regulator ON (SMPS step-down converter) ⁽⁷⁾	VOS3 (max frequency 200 MHz)	0.95	1.0	1.05	
		VOS2 (max frequency 300 MHz)	1.05	1.10	1.15	
		VOS1 (max frequency 400 MHz)	1.15	1.20	1.26	
	Regulator OFF: external V_{CORE} voltage must be supplied from external regulator on two VCAP pins	VOS3 (max frequency 200 MHz)	0.98	1.03	1.08	
		VOS2 (max frequency 300 MHz)	1.08	1.13	1.17	
		VOS1 (max frequency 400 MHz)	1.17	1.23	1.26	
		VOS0 (max frequency 480 MHz)	1.37	1.38	1.40	
f_{CPU1}	Arm® Cortex®-M7 clock frequency	VOS3	-	-	200	MHz
		VOS2	-	-	300	
		VOS1	-	-	400	
		VOS0	-	-	480	
f_{CPU2}	Arm® Cortex®-M4 clock frequency	VOS3	-	-	100	MHz
		VOS2	-	-	150	
		VOS1	-	-	200	
		VOS0	-	-	240 ⁽⁶⁾	
f_{ACLK}	AXI clock frequency	VOS3	-	-	100	MHz
		VOS2	-	-	150	
		VOS1	-	-	200	
		VOS0	-	-	240 ⁽⁶⁾	
f_{HCLK}	AHB clock frequency	VOS3	-	-	100	MHz
		VOS2	-	-	150	
		VOS1	-	-	200	
		VOS0	-	-	240 ⁽⁶⁾	

Table 13. General operating conditions (continued)

Symbol	Parameter	Operating conditions	Min	Typ	Max	Unit
f_{PCLK}	APB clock frequency	VOS3	-	-	50 ⁽⁸⁾	MHz
		VOS2	-	-	75	
		VOS1	-	-	100	
		VOS0	-	-	120 ⁽⁶⁾	
TA	Ambient temperature for the suffix 6 version	Maximum power dissipation	-40	85	°C	
		Low-power dissipation ⁽⁹⁾	-40	105		
	Ambient temperature for the suffix 3 version	Maximum power dissipation	-40	125		
		Low-power dissipation ⁽⁹⁾	-40	130		

- When RESET is released functionality is guaranteed down to V_{BOR0} min
- Only for power-up sequence when the SMPS step-down converter is configured to supply the LDO and $T_{JMax} = 105$ °C.
- This formula has to be applied on power supplies related to the IO structure described by the pin definition table.
- For operation with voltage higher than Min (V_{DD} , V_{DDA} , $V_{DD33USB}$) +0.3V, the internal Pull-up and Pull-Down resistors must be disabled.
- VOS0 is available only when the LDO regulator is ON.
- $T_{JMax} = 105$ °C.
- At startup, the external V_{CORE} voltage must remain higher or equal to 1.10 V before disabling the internal regulator (LDO).
- Maximum APB clock frequency when at least one peripheral is enabled.
- In low-power dissipation state, TA can be extended to this range as long as T_J does not exceed T_{Jmax} (see [Section 7.7: Thermal characteristics](#)).

Table 14. Supply voltage and maximum frequency configuration

Power scale	V_{CORE} source	Max T_J (°C)	Max frequency (MHz)	Min V_{DDLDO} (V)
VOS0	LDO	105	480	1.7
	SMPS step-down converter ⁽¹⁾	-	-	-
VOS1	LDO	125	400	1.62
	SMPS step-down converter			
VOS2	LDO	125	300	1.62
	SMPS step-down converter	125		
		140		
VOS3	LDO ⁽²⁾	105	64	1.2 ⁽²⁾
	LDO	125	200	1.62
	SMPS step-down converter	125		
		140 ⁽³⁾		

Table 14. Supply voltage and maximum frequency configuration (continued)

Power scale	V_{CORE} source	Max T_J (°C)	Max frequency (MHz)	Min V_{DDLDO} (V)
SVOS4	LDO	105	N/A	1.62
	SMPS step-down converter	125		
		140 ⁽³⁾		
SVOS5	LDO	105	N/A	1.62
	SMPS step-down converter	125		
		140 ⁽³⁾		

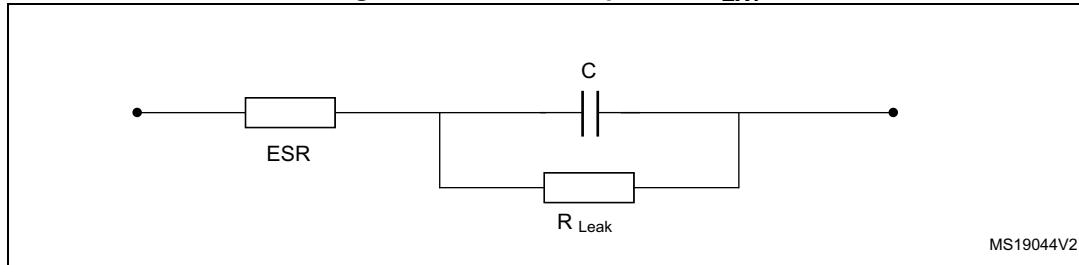
1. VOS0 (power scale 0) is not available when the SMPS step-down converter directly supplies V_{CORE} .

2. Only for power-up sequence when the SMPS step-down converter supplies the LDO.

3. Extended Industrial temperature range sales types (range 3).

6.3.2 VCAP external capacitor

Stabilization for the main regulator is achieved by connecting an external capacitor C_{EXT} to the VCAP pin. C_{EXT} is specified in [Table 15](#). Two external capacitors can be connected to VCAP pins.

Figure 15. External capacitor C_{EXT} 

MS19044V2

1. Legend: ESR is the equivalent series resistance.

Table 15. VCAP operating conditions⁽¹⁾

Symbol	Parameter	Conditions
C_{EXT}	Capacitance of external capacitor	2.2 μ F ⁽²⁾
ESR	ESR of external capacitor	< 100 m Ω

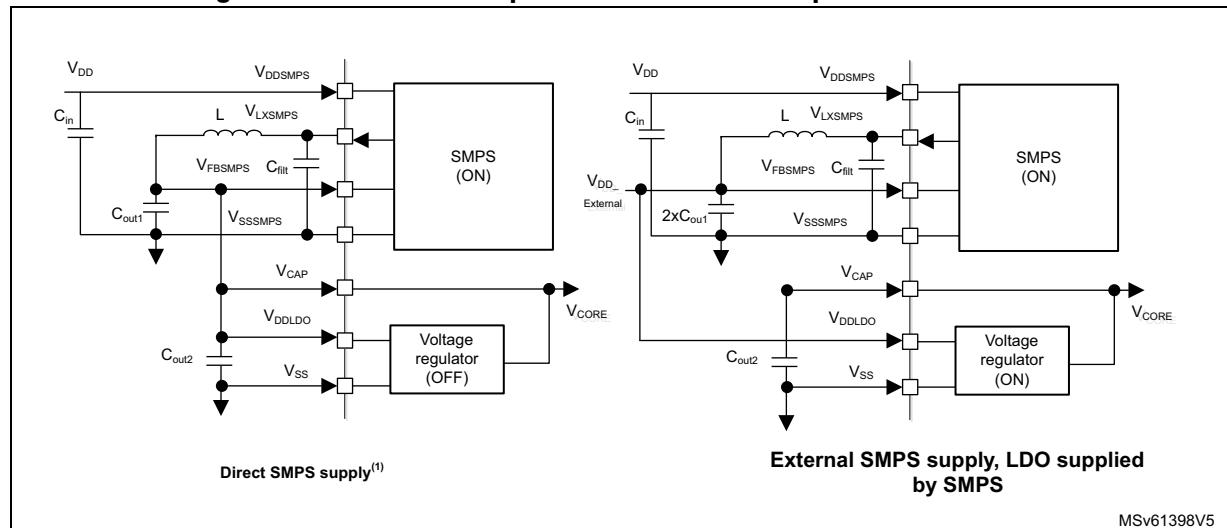
1. In bypass mode, the two 2.2 μ F VCAP capacitors are not required and should be replaced by two 100 nF decoupling capacitors

2. This value corresponds to C_{EXT} typical value. A variation of +/-20% is tolerated.

6.3.3 SMPS step-down converter

The devices embed a high power efficiency SMPS step-down converter. SMPS characteristics for external usage are given in [Table 17](#). The SMPS step-down converter requires external components that are specified in [Figure 16](#) and [Table 16](#).

Figure 16. External components for SMPS step-down converter



1. VOS0 cannot be selected in direct SMPS supply mode.

Table 16. Characteristics of SMPS step-down converter external components

Symbol	Parameter	Conditions
C_{in}	Capacitance of external capacitor on V_{DDSMPS}	4.7 μF
	ESR of external capacitor	100 m Ω
C_{filt}	Capacitance of external capacitor on V_{LXSMPS} pin	220 pF
C_{OUT}	Capacitance of external capacitor on V_{FBMPS} pin	10 μF
	ESR of external capacitor	20 m Ω
L	Inductance of external Inductor on V_{LXSMPS} pin	2.2 μH
-	Serial DC resistor	150 m Ω
I_{SAT}	DC current at which the inductance drops 30% from its value without current.	1.7 A
I_{RMS}	Average current for a 40 °C rise: rated current for which the temperature of the inductor is raised 40°C by DC current	1.4 A

Table 17. SMPS step-down converter characteristics for external usage

Parameters	Conditions	Min	Typ	Max	Unit
$V_{DDSMPS}^{(1)}$	$V_{OUT} = 1.8 \text{ V}$	2.3	-	3.6	V
	$V_{OUT} = 2.5 \text{ V}$	3	-	3.6	
$V_{OUT}^{(2)}$	$I_{out}=600 \text{ mA}$	2.25	2.5	2.75	V
		1.62	1.8	1.98	
I_{OUT}	internal and external usage	-	-	600	mA
	External usage only ⁽³⁾	-	-	600	
RDS_{ON}	-	-	100	120	m Ω

Table 17. SMPS step-down converter characteristics for external usage (continued)

Parameters	Conditions	Min	Typ	Max	Unit
I_{DDSMPS_Q}	Quiescent current	-	220	-	μA
T_{SMPS_START}	$V_{OUT} = 1.8 V$	-	-	225	μs
	$V_{OUT} = 2.5 V$	-	-	300	

1. The switching frequency is $2.4 \text{ MHz} \pm 10\%$
2. Including line transient and load transient.
3. These characteristics are given for SDEXTHP bit is set in the PWR_CR3 register.

6.3.4 Operating conditions at power-up / power-down

Subject to general operating conditions for T_A .

Table 18. Operating conditions at power-up / power-down (regulator ON)

Symbol	Parameter	Min	Max	Unit
t_{VDD}	V_{DD} rise time rate	0	∞	$\mu s/V$
	V_{DD} fall time rate	10	∞	
t_{VDDA}	V_{DDA} rise time rate	0	∞	$\mu s/V$
	V_{DDA} fall time rate	10	∞	
t_{VDDUSB}	V_{DDUSB} rise time rate	0	∞	$\mu s/V$
	V_{DDUSB} fall time rate	10	∞	

6.3.5 Embedded reset and power control block characteristics

The parameters given in [Table 19](#) are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#).

Table 19. Reset and power control block characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{RSTTEMPO}^{(1)}$	Reset temporization after BOR0 released	-	-	377	-	μs
$V_{BOR0/POR/PDR}$	Brown-out reset threshold 0 (V_{POR}/V_{PDR} thresholds)	Rising edge ⁽¹⁾	1.62	1.67	1.71	V
		Falling edge	1.58	1.62	1.68	
V_{BOR1}	Brown-out reset threshold 1	Rising edge	2.04	2.10	2.15	V
		Falling edge	1.95	2.00	2.06	
V_{BOR2}	Brown-out reset threshold 2	Rising edge	2.34	2.41	2.47	V
		Falling edge	2.25	2.31	2.37	
V_{BOR3}	Brown-out reset threshold 3	Rising edge	2.63	2.70	2.78	V
		Falling edge	2.54	2.61	2.68	
V_{PVD0}	Programmable Voltage Detector threshold 0	Rising edge	1.90	1.96	2.01	V
		Falling edge	1.81	1.86	1.91	
V_{PVD1}	Programmable Voltage Detector threshold 1	Rising edge	2.05	2.10	2.16	V
		Falling edge	1.96	2.01	2.06	
V_{PVD2}	Programmable Voltage Detector threshold 2	Rising edge	2.19	2.26	2.32	V
		Falling edge	2.10	2.15	2.21	
V_{PVD3}	Programmable Voltage Detector threshold 3	Rising edge	2.35	2.41	2.47	V
		Falling edge	2.25	2.31	2.37	
V_{PVD4}	Programmable Voltage Detector threshold 4	Rising edge	2.49	2.56	2.62	V
		Falling edge	2.39	2.45	2.51	
V_{PVD5}	Programmable Voltage Detector threshold 5	Rising edge	2.64	2.71	2.78	V
		Falling edge	2.55	2.61	2.68	
V_{PVD6}	Programmable Voltage Detector threshold 6	Rising edge	2.78	2.86	2.94	V
		Falling edge in Run mode	2.69	2.76	2.83	
$V_{hyst_BOR_PVD}$	Hysteresis voltage of BOR (unless BOR0) and PVD	Hysteresis in Run mode	-	100	-	mV
$I_{DD_BOR_PVD}^{(1)}$	BOR ⁽²⁾ (unless BOR0) and PVD consumption from V_{DD}	-	-	-	0.630	μA

Table 19. Reset and power control block characteristics (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{AVM_0}	Analog voltage detector for V_{DDA} threshold 0	Rising edge	1.66	1.71	1.76	V
		Falling edge	1.56	1.61	1.66	
V_{AVM_1}	Analog voltage detector for V_{DDA} threshold 1	Rising edge	2.06	2.12	2.19	V
		Falling edge	1.96	2.02	2.08	
V_{AVM_2}	Analog voltage detector for V_{DDA} threshold 2	Rising edge	2.42	2.50	2.58	V
		Falling edge	2.35	2.42	2.49	
V_{AVM_3}	Analog voltage detector for V_{DDA} threshold 3	Rising edge	2.74	2.83	2.91	V
		Falling edge	2.64	2.72	2.80	
V_{hyst_VDDA}	Hysteresis of V_{DDA} voltage detector	-	-	100	-	mV
I_{DD_PVM}	PVM consumption from $V_{DD(1)}$	-	-	-	0.25	μA
I_{DD_VDDA}	Voltage detector consumption on $V_{DDA}^{(1)}$	Resistor bridge	-	-	2.5	μA

1. Guaranteed by design.
2. BOR0 is enabled in all modes and its consumption is therefore included in the supply current characteristics tables (refer to [Section 6.3.7: Supply current characteristics](#)).

6.3.6 Embedded reference voltage

The parameters given in [Table 20](#) are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#).

Table 20. Embedded reference voltage

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{REFINT}	Internal reference voltages	$-40^{\circ}C < T_J < 140^{\circ}C$, $V_{DD} = 3.3\text{ V}$	1.180	1.216	1.255	V
$t_{S_vrefint}^{(1)(2)}$	ADC sampling time when reading the internal reference voltage	-	4.3	-	-	μs
$t_{S_vbat}^{(1)(2)}$	VBAT sampling time when reading the internal VBAT reference voltage	-	9	-	-	
$I_{refbuf}^{(2)}$	Reference Buffer consumption for ADC	$V_{DDA}=3.3\text{ V}$	9	13.5	23	μA
$\Delta V_{REFINT}^{(2)}$	Internal reference voltage spread over the temperature range	$-40^{\circ}C < T_J < 140^{\circ}C$	-	5	15	mV
$T_{coeff}^{(2)}$	Average temperature coefficient	Average temperature coefficient	-	20	70	$\text{ppm}/^{\circ}\text{C}$
$V_{DDcoeff}^{(2)}$	Average Voltage coefficient	$3.0\text{V} < V_{DD} < 3.6\text{V}$	-	10	1370	ppm/V

Table 20. Embedded reference voltage (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{REFINT_DIV1}	1/4 reference voltage	-	-	25	-	$\%$ V_{REFINT}
V_{REFINT_DIV2}	1/2 reference voltage	-	-	50	-	
V_{REFINT_DIV3}	3/4 reference voltage	-	-	75	-	

1. The shortest sampling time for the application can be determined by multiple iterations.
2. Guaranteed by design.

Table 21. Internal reference voltage calibration values

Symbol	Parameter	Memory address
V_{REFIN_CAL}	Raw data acquired at temperature of 30 °C, $V_{DDA} = 3.3$ V	1FF1E860 - 1FF1E861

6.3.7 Supply current characteristics

The current consumption is a function of several parameters and factors such as the operating voltage, ambient temperature, I/O pin loading, device software configuration, operating frequencies, I/O pin switching rate, program location in memory and executed binary code.

The current consumption is measured as described in [Figure 14: Current consumption measurement scheme](#).

All the run-mode current consumption measurements given in this section are performed with a CoreMark code.

Typical and maximum current consumption

The MCU is placed under the following conditions:

- All I/O pins are in analog input mode.
- All peripherals are disabled except when explicitly mentioned.
- The flash memory access time is adjusted with the minimum wait states number, depending on the f_{ACLK} frequency (refer to the table “Number of wait states according to CPU clock ($f_{rcc_c_ck}$) frequency and V_{CORE} range” available in the reference manual).
- When the peripherals are enabled, the AHB clock frequency is the CPU1 frequency divided by 2 and the APB clock frequency is AHB clock frequency divided by 2.

The parameters given in the below tables are derived from tests performed under ambient temperature and supply voltage conditions summarized in [Table 13: General operating conditions](#).

Table 22. Typical and maximum current consumption in Run mode, code with data processing running from ITCM for Cortex-M7 core, and flash memory for Cortex-M4 (ART accelerator ON), LDO regulator ON⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	Arm Cortex-M7 f _{CPU1} (MHz)	Arm Cortex-M4 f _{CPU2} (MHz)	Typ	Max ⁽³⁾					Unit	
						T _j = 25 °C	T _j = 85 °C	T _j = 105°C	T _j = 125°C	T _j = 140°C		
I _{DD}	Supply current in Run mode	All peripherals disabled	VOS0	480	240	179	272	387	498	-	-	mA
				400	200	151	-	-	-	-	-	
			VOS1	400	200	132	181	292	382	502	-	
			VOS2	300	150	91	122	211	281	377	-	
			VOS3	200	100	56	79	150	206	284	382	
		All peripherals enabled	VOS0	480	240	247	374	462	571	-	-	
				400	200	208	-	-	-	-	-	
			VOS1	400	200	181	232	337	422	541	-	
			VOS2	300	150	126	163	248	318	414	-	
			VOS3	200	100	78	104	173	229	307	406	

1. Data are in DTCM for best computation performance, the cache has no influence on consumption in this case.

2. The grayed cells correspond to the forbidden configurations.

3. Guaranteed by characterization results, unless otherwise specified.

Table 23. Typical and maximum current consumption in Run mode, code with data processing running from ITCM for Arm Cortex-M7 and flash memory for Arm Cortex-M4, ART accelerator ON, SMPS regulator⁽¹⁾

Symbol	Parameter	Conditions	Arm Cortex-M7 f _{CPU1} (MHz)	Arm Cortex-M4 f _{CPU2} (MHz)	Typ	Max					Unit	
						T _j = 25 °C	T _j = 85 °C	T _j = 105°C	T _j = 125°C	T _j = 140°C		
I _{DD}	Supply current in Run mode	All peripherals disabled	VOS1	400	200	58.3	79.0	129.0	175.1	236.0	-	mA
			VOS2	300	150	37.0	50.2	84.7	115.6	161.1	218.4	
			VOS3	200	100	21.5	29.9	56.1	77.1	107.6	152.3	
			All peripherals enabled	VOS1	400	200	78.1	100.1	148.9	193.4	254.3	
				VOS2	300	150	51.2	65.5	100.8	130.9	176.9	
				VOS3	200	100	29.5	39.4	63.9	86.7	116.3	

1. The parameters given in the above table for the SMPS regulator are derived by extrapolation from the LDO consumption and typical SMPS efficiency factors.

Table 24. Typical and maximum current consumption in Run mode, code with data processing running from flash memory, both cores running, cache ON, ART accelerator ON, LDO regulator ON⁽¹⁾

Symbol	Parameter	Conditions	Arm Cortex -M7 f _{CPU1} (MHz)	Arm Cortex-M4 f _{CPU2} (MHz)	Typ	Max ⁽²⁾					Unit
						T _j = 25 °C	T _j = 85 °C	T _j = 105°C	T _j = 125°C	T _j = 140°C	
I _{DD}	Supply current in Run mode	All peripherals disabled	VOS0	480	240	173	268	385	496	-	-
				400	200	147	-	-	-	-	-
			VOS1	400	200	128	175	288	379	499	-
			VOS2	300	150	88	120	209	279	374	-
			VOS3	200	100	55	77	149	205	283	381
		All peripherals enabled	VOS0	480	240	242	368	459	569	-	-
			VOS1	400	200	178	229 ⁽³⁾	334	419 ⁽³⁾	537	-
			VOS2	300	150	123	161	246	316	412	-
			VOS3	200	100	77	102	172	228	306	405

1. The grayed cells correspond to the forbidden configurations.
2. Guaranteed by characterization results, unless otherwise specified.
3. Guaranteed by tests in production.

Table 25. Typical and maximum current consumption in Run mode, code with data processing running from flash memory, both cores running, cache OFF, ART accelerator OFF, LDO regulator ON⁽¹⁾

Symbol	Parameter	Conditions	Arm Cortex -M7 f _{CPU1} (MHz)	Arm Cortex-M4 f _{CPU2} (MHz)	Typ	Max ⁽²⁾					Unit
						T _j = 25 °C	T _j = 85 °C	T _j = 105°C	T _j = 125°C	T _j = 140°C	
I _{DD}	Supply current in Run mode	All peripherals disabled	VOS0	480	240	109	191	330	444	-	-
			VOS1	400	200	96	149	256	347	468	-
			VOS2	300	150	67	95	187	257	354	-
			VOS3	200	100	43	62	136	192	270	368
		All peripherals enabled	VOS0	480	240	178	291	403	517	-	-
			VOS1	400	200	147	224	310	401	523	-
			VOS2	300	150	103	136	224	295	392	-
			VOS3	200	100	64	87	159	215	293	392

1. The grayed cells correspond to the forbidden configurations.
2. Guaranteed by characterization results, unless otherwise specified.

Table 26. Typical and maximum current consumption in Run mode, code with data processing running from ITCM, only Arm Cortex-M7 running, LDO regulator ON⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	f_{CPU1} (MHz)	Typ	Max ⁽³⁾					Unit	
					T _j =25 °C	T _j =85 °C	T _j =105 °C	T _j =125 °C	T _j =140 °C		
I_{DD}	Supply current in Run mode	All peripherals disabled	VOS0	480	148	226	307	390	-	-	mA
				400	125	-	-	-	-	-	
			VOS1	400	110	168	230	296	384	-	
				300	84	-	-	-	-	-	
			VOS2	300	76	114	170	224	297	-	
				216	56	88	152	205	278	-	
				200	53	-	-	-	-	-	
			VOS3	200	47	71	121	164	223	295	
				180	43	64	116	159	218	291	
				168	40	63	115	158	217	290	
				144	35	55	109	153	212	284	
				60	16	36	92	135	194	267	
				25	12	24	83	126	185	257	
		All peripherals enabled	VOS0	480	226	222	439	550	-	-	
				400	190	-	-	-	-	-	
			VOS1	400	167	222	327	416	536	-	
				300	135	-	-	-	-	-	
			VOS2	300	122	160	248	320	419	-	
				200	85	-	-	-	-	-	
			VOS3	200	76	103	174	233	313	413	

1. Data are in DTCM for best computation performance, the cache has no influence on consumption in this case.
2. The grayed cells correspond to the forbidden configurations.
3. Guaranteed by characterization results, unless otherwise specified.

Table 27. Typical and maximum current consumption in Run mode, code with data processing running from ITCM, only Arm Cortex-M7 running, SMPS regulator⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	f_{CPU1} (MHz)	Typ	Max					Unit	
					T _j =25 °C	T _j =85 °C	T _j =105 °C	T _j =125 °C	T _j =140 °C		
I_{DD}	Supply current in Run mode	All peripherals disabled	VOS1	400	48.6	73.3	100.4	132.4	176.0	-	mA
			VOS2	300	31.3	46.3	68.3	90.0	122.2	164.5	
			VOS3	200	18.0	26.9	45.3	60.6	82.4	111.7	
		All peripherals enabled	VOS1	400	72.9	95.8	144.5	190.7	252.0	-	
			VOS2	300	49.6	64.3	99.6	131.7	179.1	238.2	
			VOS3	200	28.8	38.5	64.3	88.3	118.6	164.7	

1. The parameters given in the above table for the SMPS regulator are derived by extrapolation from the LDO consumption and typical SMPS efficiency factors.

2. The grayed cells correspond to the forbidden configurations.

Table 28. Typical and maximum current consumption in Run mode, code with data processing running from flash memory, only Arm Cortex-M7 running, cache ON, LDO regulator ON⁽¹⁾

Symbol	Parameter	Conditions	f_{CPU1} (MHz)	Typ	Max ⁽²⁾					Unit	
					T _j =25 °C	T _j =85 °C	T _j =105 °C	T _j =125 °C	T _j =140 °C		
I_{DD}	Supply current in Run mode	All peripherals disabled	VOS0	480	110	222	304	388	-	-	mA
				400	91	-	-	-	-	-	
			VOS1	400	80	162	228	294	381	-	
				300	61.5	-	-	-	-	-	
			VOS2	300	55	111	168	222	294	-	
				200	38.5	-	-	-	-	-	
			VOS3	200	34.5	69	120	163	222	294	
		All peripherals enabled	VOS0	480	220	342	436	546	-	-	
				400	195	-	-	-	-	-	
			VOS1	400	175	264	336	424	544	-	
				300	135	-	-	-	-	-	
			VOS2	300	120	180	246	318	418	-	
				200	83	-	-	-	-	-	
			VOS3	200	75	114	173	232	312	412	

1. The grayed cells correspond to the forbidden configurations.

2. Guaranteed by characterization results, unless otherwise specified.

Table 29. Typical and maximum current consumption in Run mode, code with data processing running from flash memory, only Arm Cortex-M7 running, cache OFF, LDO regulator ON⁽¹⁾

Symbol	Parameter	Conditions	f_{CPU1} (MHz)	Typ	Max ⁽²⁾					Unit
					T _j =25°C	T _j =85°C	T _j =105°C	T _j =125°C	T _j =140°C	
I _{DD}	Supply current in Run mode	All peripherals disabled	VOS0	480	87	157	259	342	-	-
			VOS1	400	73	123	201	267	355	-
			VOS2	300	52	85	150	204	277	-
			VOS3	200	34	54	109	152	212	284
		All peripherals enabled	VOS0	480	168	276	390	504	-	-
			VOS1	400	135	224	308	397	519	-
			VOS2	300	100	154	228	301	401	-
			VOS3	200	70	103	167	226	307	407

1. The grayed cells correspond to the forbidden configurations.
2. Guaranteed by characterization results, unless otherwise specified.

Table 30. Typical and maximum current consumption batch acquisition mode, LDO regulator ON

Symbol	Parameter	Conditions	f_{HCLK} (MHz)	Typ	Max ⁽¹⁾					Unit	
					T _j =25°C	T _j =85°C	T _j =105°C	T _j =125°C	T _j =140°C		
I _{DD}	Supply current in batch acquisition mode	D1 Standby, D2 Standby, D3 Run	VOS3	64	2.7	4.7	12.9	19.0	27.5	37.8	mA
				8	1.1	-	-	-	-		
		D1 Stop, D2 Stop, D3 Run	VOS3	64	5.4	18.4	83.7	132.6	202.4	289.3	
				8	3.8	-	-	-	-		

1. Guaranteed by characterization results, unless otherwise specified.

Table 31. Typical and maximum current consumption in Run mode, code with data processing running from flash memory, only Arm Cortex-M4 running, ART accelerator ON, LDO regulator ON⁽¹⁾

Symbol	Parameter	Conditions	f_{CPU2} (MHz)	Typ	Max ⁽²⁾					Unit	
					T _j =25 °C	T _j =85 °C	T _j =105 °C	T _j =125 °C	T _j =140 °C		
I _{DD}	Supply current in Run mode	All peripherals disabled	VOS0	240	121	203	339	453	-	-	mA
				200	90	-	-	-	-	-	
			VOS1	200	79	123	234	323	444	-	
				150	61	-	-	-	-	-	
			VOS2	150	56	85	178	250	350	-	
			VOS3	100	35	59	131	189	269	369	
				240	190	303	412	525	-	-	
		All peripherals enabled	VOS0	200	146	-	-	-	-	-	
				200	129	195	287	376	499	-	
			VOS1	150	90	134	214	287	386	-	
			VOS2	100	61	100	158	216	297	398	
				240	190	303	412	525	-	-	

1. The grayed cells correspond to the forbidden configurations.
2. Guaranteed by characterization results, unless otherwise specified.

Table 32. Typical and maximum current consumption in Run mode, code with data processing running from flash bank 2, only Arm Cortex-M4 running, ART accelerator ON, SMPS regulator⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	Typ	Max					Unit	
				T _j =25 °C	T _j =85 °C	T _j =105 °C	T _j =125 °C	T _j =140 °C		
I _{DD}	Supply current in Run mode	All peripherals disabled	VOS1	35.3	54.3	102.1	144.4	203.5	-	mA
			VOS2	23.3	35.0	70.6	99.2	145.8	207.0	
			VOS3	13.6	22.3	49.0	69.8	101.9	147.1	
		All peripherals enabled	VOS1	57.0	84.1	126.8	172.3	234.6	-	
			VOS2	36.6	54.5	84.9	118.1	165.0	223.7	
			VOS3	23.1	37.4	58.4	79.8	112.5	158.7	

1. The parameters given in the above table for the SMPS regulator are derived by extrapolation from the LDO consumption and typical SMPS efficiency factors.
2. The grayed cells correspond to the forbidden configurations.

Table 33. Typical and maximum current consumption in Stop, LDO regulator ON⁽¹⁾

Symbol	Parameter	Conditions	Typ	Max ⁽²⁾					Unit
				T _j =25°C	T _j =85°C	T _j =105 °C	T _j =125 °C	T _j =140 °C	
I _{DD} (Stop)	D1 Stop, D2 Stop, D3 Stop	Flash memory OFF, no IWDG	SVOS5	1.27	6.3	42.5	72.0	-	-
			SVOS4	1.96	9.4	57.4	94.6	-	-
			SVOS3	2.78	13.8 ⁽³⁾	75.9	121.3 ⁽³⁾	183.8	264.9
		Flash memory ON, no IWDG	SVOS5	1.27	6.3	42.5	72.0	-	-
			SVOS4	2.25	9.8	57.9	95.2	-	-
			SVOS3	3.07	14.1	76.4	122.0	184.8	266.5
	D1 Stop, D2 Standby, D3 Stop	Flash memory OFF, no IWDG	SVOS5	0.91	4.6	30.4	51.2	-	-
			SVOS4	1.42	6.8	41.1	67.3	-	-
			SVOS3	2.02	10.0	54.4	86.6	130.0	186.1
		Flash memory ON, no IWDG	SVOS5	0.91	4.6	30.4	51.2	-	-
			SVOS4	1.70	7.2	41.5	67.9	-	-
			SVOS3	2.31	10.3	54.9	87.1	130.8	187.2
	D1 Standby, D2 Stop, D3 Stop	Flash memory OFF, no IWDG	SVOS5	0.49	2.4	16.5	28.0	-	-
			SVOS4	0.76	3.6	22.2	36.6	-	-
			SVOS3	1.10	5.3	29.3	46.9	71.2	102.2
	D1 Standby, D2 Standby, D3 Stop	Flash memory OFF, no IWDG	SVOS5	0.15	0.7 ⁽³⁾	4.3	7.3 ⁽³⁾	-	-
			SVOS4	0.22	1.0	5.8	9.6	-	-
			SVOS3	0.35	1.5 ⁽³⁾	7.8	12.3 ⁽³⁾	18.6	26.6

1. The grayed cells correspond to the forbidden configurations.
2. Guaranteed by characterization results, unless otherwise specified.
3. Guaranteed by tests in production.

Table 34. Typical and maximum current consumption in Stop, SMPS regulator⁽¹⁾

Symbol	Parameter	Conditions	Typ	Max					Unit
				T _j =25°C	T _j =85°C	T _j =105 °C	T _j =125 °C	T _j =140 °C	
I _{DD} (Stop)	D1 Stop, D2 Stop, D3 Stop	Flash OFF, no IWDG	SVOS5	0.36	1.73	11.91	21.53	-	-
			SVOS4	0.63	3.05	19.57	33.51	-	-
			SVOS3	1.00	4.98	29.11	47.13	68.76	100.34
		Flash ON, no IWDG	SVOS5	0.36	1.73	11.91	21.53	-	-
			SVOS4	0.73	3.18	19.74	33.72	-	-
			SVOS3	1.11	5.09	29.31	47.40	69.14	100.95
	D1 Stop, D2 Standby, D3 Stop	Flash OFF, no IWDG	SVOS5	0.25	1.24	8.21	14.00	-	-
			SVOS4	0.46	2.21	14.01	22.94	-	-
			SVOS3	0.73	3.57	19.62	32.80	49.24	68.77
		Flash ON, no IWDG	SVOS5	0.25	1.24	8.21	14.00	-	-
			SVOS4	0.55	2.34	14.15	23.15	-	-
			SVOS3	0.83	3.67	19.81	32.99	49.55	69.18
	D1 Standby, D2 Stop, D3 Stop	Flash OFF, no IWDG	SVOS5	0.15	0.67	4.51	7.85	-	-
			SVOS4	0.26	1.17	7.21	12.32	-	-
			SVOS3	0.40	1.90	10.57	17.12	26.97	39.20
	D1 Standby, D2 Standby, D3 Stop	Flash ON, no IWDG	SVOS5	0.06	0.20	1.18	2.05	-	-
			SVOS4	0.08	0.33	1.90	3.11	-	-
			SVOS3	0.13	0.54	2.80	4.47	6.77	9.58

1. The parameters given in the above table for the SMPS regulator are derived by extrapolation from the LDO consumption and typical SMPS efficiency factors.

Table 35. Typical and maximum current consumption in Sleep mode, LDO regulator ON⁽¹⁾

Symbol	Parameter	Conditions	f_{HCLK} (MHz)	Typ	Max ⁽²⁾					Unit	
					T _j =25°C	T _j =85°C	T _j =105°C	T _j =125°C	T _j =140°C		
I_{DD} (Sleep)	Supply current in Sleep mode	All peripherals disabled	VOS0	480	50.7	96.3	253.4	366.1	-	-	mA
				400	43.4	87.8	245.5	357.9	-	-	
			VOS1	400	35.3	66.5	181.3	265.8	379.6	-	
				300	27.9	-	-	-	-	-	
			VOS2	300	24.6	47.3	139.1	207.3	300.4	-	
				200	18.8	-	-	-	-	-	
			VOS3	200	16.5	33.6	106.4	160.9	236.1	330.3	
		All peripherals enabled	VOS0	480	136.0	194.7	348.5	464.4	-	-	
				400	115.0	169.0	325.9	441.7	-	-	
			VOS1	400	97.7	138.2	251.3	338.4	456.4	-	
				300	74.9	-	-	-	-	-	
			VOS2	300	67.3	95.8	187.6	257.9	354.1	-	
				200	52.8	-	-	-	-	-	
			VOS3	200	47.1	69.3	141.4	197.7	275.1	372.8	

1. The grayed cells correspond to the forbidden configurations.

2. Guaranteed by characterization results, unless otherwise specified.

Table 36. Typical and maximum current consumption in Sleep mode, SMPS regulator⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	f_{HCLK} (MHz)	Typ	Max					Unit	
					T _j =25°C	T _j =85°C	T _j =105°C	T _j =125°C	T _j =140°C		
I_{DD} (Sleep)	Supply current in Sleep mode	All peripherals disabled	VOS1	400	15.93	29.69	79.01	118.72	173.80	-	mA
				300	12.58	-	-	-	-	-	
			VOS2	300	10.21	19.63	56.46	82.14	123.46	177.95	
				200	7.89	-	-	-	-	-	
			VOS3	200	6.50	12.98	39.73	59.35	87.10	125.00	
		All peripherals Enabled	VOS1	400	42.65	59.62	110.88	153.00	211.65	-	
			VOS2	300	27.70	38.94	75.26	102.22	147.38	208.16	
			VOS3	200	17.95	26.14	52.75	72.95	104.09	148.48	

1. The parameters given in the above table for the SMPS regulator are derived by extrapolation from the LDO consumption and typical SMPS efficiency factors.

2. The grayed cells correspond to the forbidden configurations.

Table 37. Typical and maximum current consumption in Standby

Symbol	Parameter	Conditions		Typ				Max ⁽¹⁾					Unit
				1.62 V	2.4 V	3 V	3.3 V	T _j =25 °C	T _j =85 °C	T _j =105 °C	T _j =125 °C	T _j =140 °C	
		Backup SRAM	RTC and LSE										
I _{DD} (Standby)	Supply current in Standby mode	OFF	OFF	1,92	1,95	2,06	2,16	4	18	40	90	140	μA
		ON	OFF	3,33	3,44	3,6	3,79	8.2	47	83	141	230	
		OFF	ON	2,43	2,57	2,77	2,95	-	-	-	-	-	
		ON	ON	3,82	4,05	4,31	4,55	-	-	-	-	-	

1. Guaranteed by characterization results, unless otherwise specified.

Table 38. Typical and maximum current consumption in V_{BAT} mode

Symbol	Parameter	Conditions		Typ				Max ⁽¹⁾					Unit
				1.2 V	2 V	3 V	3.4 V	T _j =25 °C	T _j =85 °C	T _j =105 °C	T _j =125 °C	T _j =140 °C	
		Backup SRAM	RTC and LSE										
I _{DD} (V _{BAT})	Supply current in V _{BAT} mode	OFF	OFF	0,02	0,02	0,03	0,05	0,5	4,1	10	24	47	μA
		ON	OFF	1,33	1,45	1,58	1,7	4,4	22	48	87	132	
		OFF	ON	0,46	0,57	0,75	0,87	-	-	-	-	-	
		ON	ON	1,77	2	2,3	2,5	-	-	-	-	-	

1. Guaranteed by characterization results, unless otherwise specified.

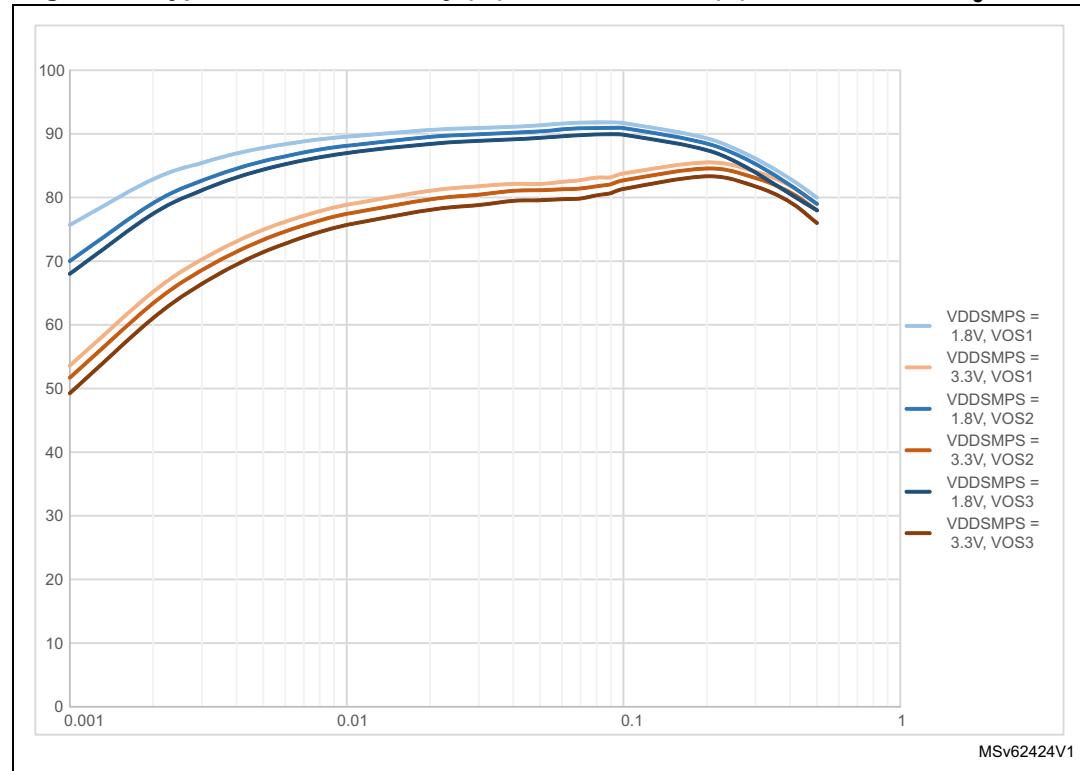
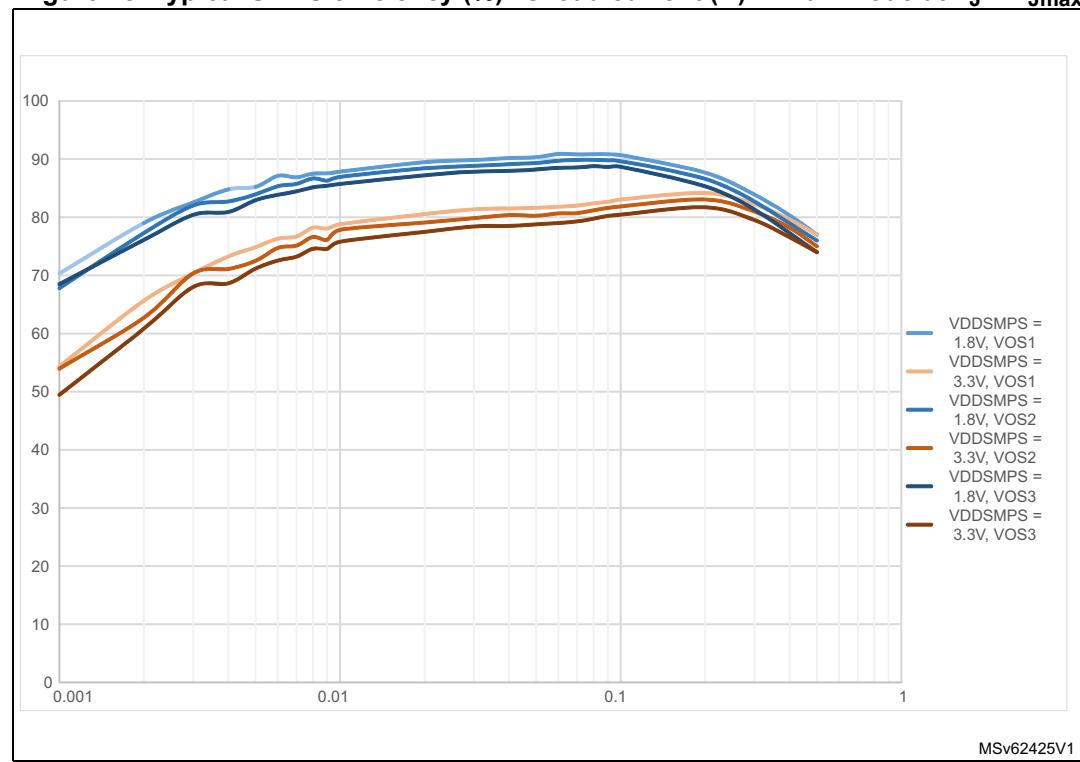
Typical SMPS efficiency versus load current and temperature**Figure 17. Typical SMPS efficiency (%) vs load current (A) in Run mode at $T_J = 30^\circ C$** **Figure 18. Typical SMPS efficiency (%) vs load current (A) in Run mode at $T_J = T_{Jmax}$** 

Figure 19. Typical SMPS efficiency (%) vs load current (A) in low-power mode at $T_J = 30^\circ\text{C}$

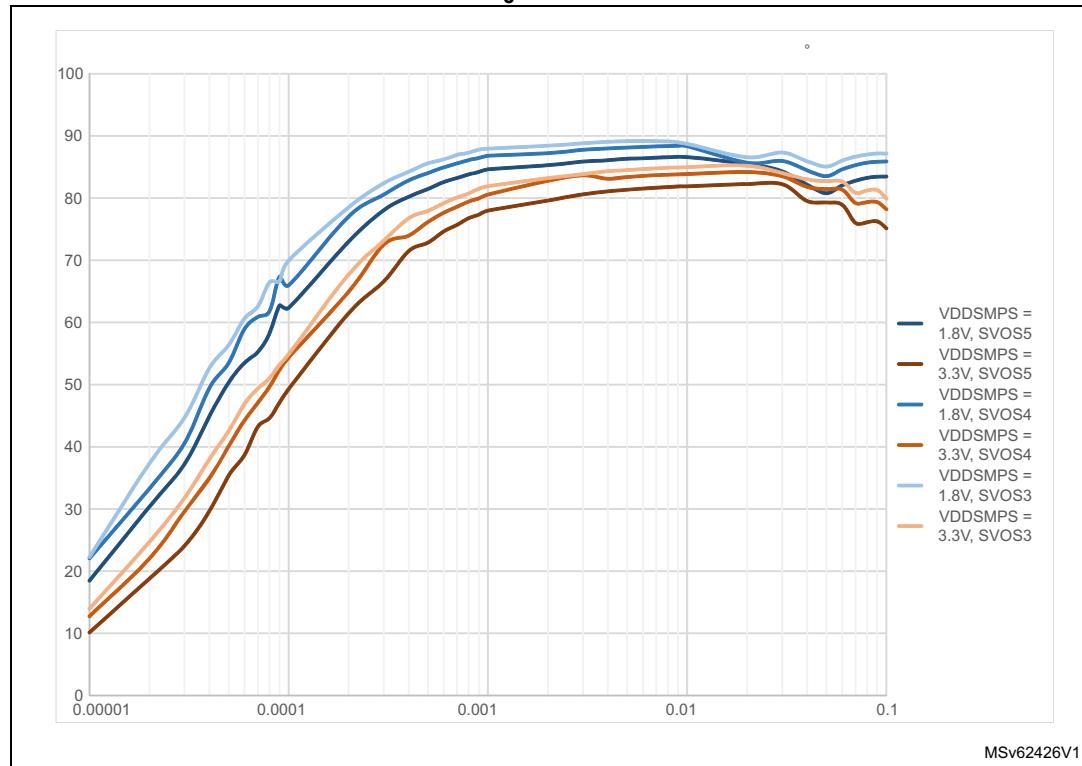
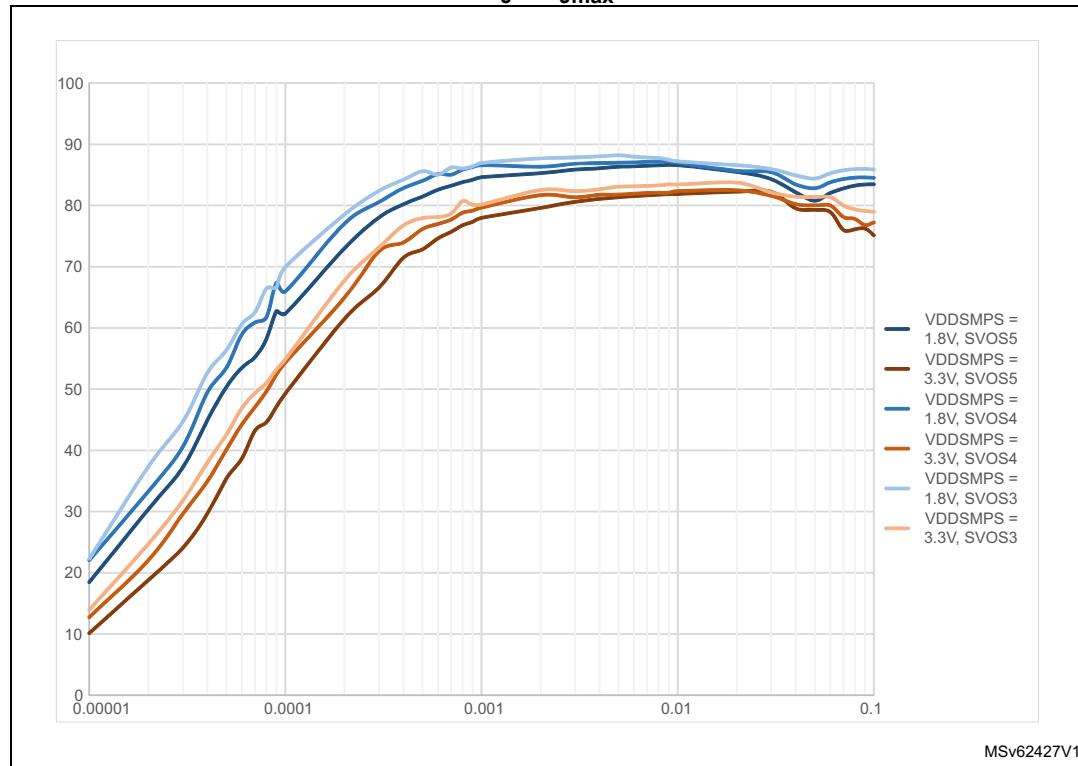


Figure 20. Typical SMPS efficiency (%) vs load current (A) in low-power mode at $T_J = T_{Jmax}$



I/O system current consumption

The current consumption of the I/O system has two components: static and dynamic.

I/O static current consumption

All the I/Os used as inputs with pull-up or pull-down generate a current consumption when the pin is externally held low. The value of this current consumption can be simply computed by using the pull-up/pull-down resistors values given in [Table 59: I/O static characteristics](#).

For the output pins, any internal or external pull-up or pull-down, and any external load must also be considered to estimate the current consumption.

An additional I/O current consumption is due to I/Os configured as inputs if an intermediate voltage level is externally applied. This current consumption is caused by the input Schmitt trigger circuits used to discriminate the input value. Unless this specific configuration is required by the application, this supply current consumption can be avoided by configuring these I/Os in analog mode. This is notably the case of ADC input pins which should be configured as analog inputs.

Caution: Any floating input pin can also settle to an intermediate voltage level or switch inadvertently, as a result of external electromagnetic noise. To avoid a current consumption related to floating pins, they must either be configured in analog mode, or forced internally to a definite digital value. This can be done either by using pull-up/down resistors or by configuring the pins in output mode.

I/O dynamic current consumption

In addition to the internal peripheral current consumption (see [Table 39: Peripheral current consumption in Run mode](#)), the I/Os used by an application also contribute to the current consumption. When an I/O pin switches, it uses the current from the MCU supply voltage to supply the I/O pin circuitry and to charge/discharge the internal or external capacitive load connected to the pin:

$$I_{SW} = V_{DDx} \times f_{SW} \times C_L$$

where

I_{SW} is the current sunk by a switching I/O to charge/discharge the capacitive load

V_{DDx} is the MCU supply voltage

f_{SW} is the I/O switching frequency

C_L is the total capacitance seen by the I/O pin: $C = C_{INT} + C_{EXT}$

The test pin is configured in push-pull output mode and is toggled by software at a fixed frequency.

On-chip peripheral current consumption

The MCU is placed under the following conditions:

- At startup, all I/O pins are in analog input configuration.
- All peripherals are disabled unless otherwise mentioned.
- The I/O compensation cell is enabled.
- $f_{rcc_c_ck}$ is the CPU clock. $f_{PCLK} = f_{rcc_c_ck}/4$, and $f_{HCLK} = f_{rcc_c_ck}/2$.
The given value is calculated by measuring the difference of current consumption
 - with all peripherals clocked off
 - with only one peripheral clocked on
 - $f_{rcc_c_ck} = 480$ MHz (Scale 0), $f_{rcc_c_ck} = 400$ MHz (Scale 1), $f_{rcc_c_ck} = 300$ MHz (Scale 2), $f_{rcc_c_ck} = 200$ MHz (Scale 3)
- The ambient operating temperature is 25 °C and $V_{DD}=3.3$ V.

Table 39. Peripheral current consumption in Run mode

Bus	Peripheral	VOS0	VOS1	VOS2	VOS3	Unit
AHB3	MDMA	4.6	3.8	3.4	3.2	µA/MHz
	DMA2D	2.9	2.4	2.1	1.9	
	JPGDEC	4.1	3.7	3.4	3.1	
	FLASH	17.0	15.0	14.0	12.0	
	FMC registers	0.9	1.1	0.9	0.8	
	FMC kernel	7.0	6.1	5.6	5.0	
	QUADSPI registers	1.5	1.5	1.4	1.3	
	QSPI kernel	1.0	0.9	0.8	0.7	
	SDMMC1 registers	8.2	7.2	6.7	6.0	
	SDMMC1 kernel	1.3	1.2	0.9	0.9	
	DTCM1	7.9	6.8	6.0	5.3	
	DTCM2	8.3	7.2	6.4	5.7	
	ITCM	7.0	6.3	5.6	5.1	
	D1SRAM1	13.0	11.0	9.9	8.7	
	AHB3 bridge	35.0	32.0	29.0	26.0	
Total AHB3		120	106	96	86	
AHB1	DMA1	54.0	48.0	41.0	37.0	µA/MHz
	DMA2	55.0	49.0	42.0	37.0	
	ADC12 registers	4.5	4.1	3.7	3.3	
	ADC12 kernel	1.0	0.7	0.4	0.6	
	ART accelerator	4.1	3.7	3.2	2.9	
	ETH1MAC	17.0	15.0	14.0	12.0	
	ETH1TX	0.1	0.1	0.1	0.1	
	ETH1RX	0.1	0.1	0.1	0.1	
	USB1 OTG registers	23.0	21.0	19.0	17.0	
	USB1 OTG kernel	8.2	0.5	8.3	8.2	
	USB1 ULPI	0.1	0.1	0.1	0.1	
	USB2 OTG registers	21.0	19.0	17.0	15.0	
	USB2 OTG kernel	8.5	0.4	8.6	8.3	
	USB2 ULPI	23.0	19.0	20.0	19.0	
	AHB1 bridge	0.1	0.1	0.1	0.1	
Total AHB1		220	181	178	161	

Table 39. Peripheral current consumption in Run mode (continued)

Bus	Peripheral	VOS0	VOS1	VOS2	VOS3	Unit
AHB2	DCMI	2.1	1.9	1.8	1.6	µA/MHz
	CRYPT	0.1	0.1	0.1	0.1	
	HASH	0.1	0.1	0.1	0.1	
	RNG registers	1.7	2.0	1.3	1.2	
	RNG kernel	11.0	0.1	9.7	9.4	
	SDMMC2 registers	47.0	41.0	37.0	34.0	
	SDMMC2 kernel	1.7	1.2	1.1	1.0	
	D2SRAM1	5.7	4.9	4.4	3.9	
	D2SRAM2	5.2	4.5	4.0	3.5	
	D2SRAM3	4.1	3.6	3.2	2.8	
	AHB2 bridge	0.1	0.1	0.1	0.1	
	Total AHB2	79	60	63	58	
AHB4	GPIOA	1.5	1.3	1.3	1.1	µA/MHz
	GPIOB	1.2	1.0	1.0	0.9	
	GPIOC	0.8	0.7	0.7	0.6	
	GPIOD	1.1	1.0	1.0	0.9	
	GPIOE	0.7	0.7	0.7	0.6	
	GPIOF	0.8	0.8	0.7	0.6	
	GPIOG	0.9	0.8	0.8	0.7	
	GPIOH	1.1	1.0	1.0	0.9	
	GPIOI	0.9	0.9	0.8	0.7	
	GPIOJ	0.8	0.8	0.7	0.7	
	GPIOK	0.7	0.8	0.7	0.6	
	CRC	0.4	0.5	0.4	0.3	
	BDMA	6.6	5.9	5.3	4.8	
	ADC3 registers	1.7	1.5	1.2	1.2	
	ADC3 kernel	0.4	0.3	0.5	0.2	
	BKPRAM	2.3	1.9	1.7	1.5	
	AHB4 bridge	0.1	0.1	0.1	0.1	
	Total AHB4	22	20	19	16	
APB3	WWDG1	0.7	0.5	0.5	0.2	µA/MHz
	LCD-TFT	81.0	36.0	33.0	30.0	
	APB3 bridge	0.3	0.2	0.1	0.1	
	Total APB3	87	41	38	34	

Table 39. Peripheral current consumption in Run mode (continued)

Bus	Peripheral	VOS0	VOS1	VOS2	VOS3	Unit
APB1	TIM2	7.7	3.6	3.3	3.0	µA/MHz
	TIM3	6.7	3.2	3.0	2.7	
	TIM4	6.3	3.1	2.8	2.5	
	TIM5	7.4	3.5	3.2	2.8	
	TIM6	1.4	0.7	0.8	0.6	
	TIM7	1.4	0.7	0.7	0.6	
	TIM12	3.2	1.5	1.5	1.3	
	TIM13	2.3	1.1	1.1	0.9	
	TIM14	2.1	1.1	1.1	0.9	
	LPTIM1 registers	0.7	0.5	0.8	0.7	
	LPTIM1 kernel	2.4	2.3	1.9	1.7	
	WWDG2	0.6	0.5	0.5	0.4	
	SPI2 registers	2.0	1.8	1.7	1.4	
	SPI2 kernel	0.8	0.6	0.5	0.6	
	SPI3 registers	1.8	1.6	1.6	1.3	
	SPI3 kernel	0.7	0.9	0.7	0.7	
	SPDIFRX1 registers	0.5	0.7	0.7	0.6	
	SPDIFRX1 kernel	3.5	2.8	2.4	2.2	
	USART2 registers	1.9	1.7	1.4	1.3	
	USART2 kernel	4.3	3.9	3.6	3.2	
	USART3 registers	1.9	1.7	1.4	1.3	
	USART3 kernel	4.4	3.9	3.5	3.2	
	UART4 registers	1.7	1.5	1.4	1.4	
	UART4 kernel	3.9	3.4	3.1	2.8	
	UART5 registers	1.6	1.4	1.4	1.3	
	UART5 kernel	3.8	3.4	3.0	2.7	
	I2C1 registers	1.1	0.8	0.9	0.8	
	I2C1 kernel	2.5	2.3	2.0	1.9	
	I2C2 registers	1.0	0.8	0.9	0.8	

Table 39. Peripheral current consumption in Run mode (continued)

Bus	Peripheral	VOS0	VOS1	VOS2	VOS3	Unit
APB1 (continued)	I2C2 kernel	2.3	2.2	1.9	1.7	µA/MHz
	I2C3 registers	0.8	1.0	0.8	0.8	
	I2C3 kernel	2.4	1.9	1.8	1.6	
	HDMI-CEC registers	0.7	0.5	0.6	0.5	
	HDMI-CEC kernel	0.1	0.1	3.2	0.1	
	DAC12	3.6	1.3	1.2	1.0	
	USART7 registers	1.8	1.8	1.6	1.4	
	USART7 kernel	4.0	3.3	3.0	2.8	
	USART8 registers	2.0	1.6	1.6	1.4	
	USART8 kernel	3.9	3.4	3.1	2.8	
	CRS	6.4	5.5	5.0	4.5	
	SWPMI registers	2.7	2.4	2.3	1.9	
	SWPMI kernel	0.1	0.1	0.1	0.1	
	OPAMP	0.2	0.3	0.3	0.2	
	MDIO	3.3	2.9	2.6	2.3	
	FDCAN registers	19.0	17.0	15.0	13.0	
	FDCAN kernel	9.1	7.9	6.9	6.4	
	APB1 bridge	0.1	0.1	0.1	0.1	
	Total APB1	142	108	102	88	
APB2	TIM1	11.0	5.0	4.5	4.0	
	TIM8	10.0	4.7	4.3	3.8	
	USART1 registers	3.6	2.5	2.7	2.9	
	USART1 kernel	0.1	0.1	0.1	0.1	
	USART6 registers	4.5	3.0	3.1	3.4	
	USART6 kernel	0.1	0.1	0.1	0.1	
	SPI1 registers	2.0	1.7	1.6	1.4	
	SPI1 kernel	0.9	0.8	0.7	0.6	
	SPI4 registers	2.1	1.7	1.6	1.5	
	SPI4 kernel	0.6	0.5	0.5	0.3	
	TIM15	5.5	2.5	2.3	2.1	
	TIM16	4.1	2.0	1.8	1.7	
	TIM17	4.1	1.9	1.8	1.6	
	SPI5 registers	2.0	1.8	1.6	1.3	
	SPI5 kernel	0.5	0.4	0.4	0.5	
	SAI1 registers	1.3	1.1	1.1	1.0	

Table 39. Peripheral current consumption in Run mode (continued)

Bus	Peripheral	VOS0	VOS1	VOS2	VOS3	Unit
APB2 (continued)	SAI1 kernel	1.4	1.1	1.0	0.8	µA/MHz
	SAI2 registers	1.5	1.3	1.2	1.0	
	SAI2 kernel	1.1	1.0	0.9	0.9	
	SAI3 registers	1.6	1.3	1.1	1.0	
	SAI3 kernel	1.1	1.2	1.1	0.9	
	DFSDM1 registers	6.5	5.8	5.2	4.7	
	DFSDM1 kernel	0.3	0.2	0.2	0.4	
	HRTIM	84.0	39.0	35.0	32.0	
	APB2 bridge	0.2	0.1	0.1	0.2	
	Total APB2	150	81	74	68	
APB4	SYSCFG	0.9	1.0	0.7	0.8	µA/MHz
	LPUART1 registers	1.1	1.3	1.0	0.8	
	LPUART1 kernel	2.9	2.2	2.2	2.1	
	SPI6 registers	1.8	1.6	1.4	1.3	
	SPI6 kernel	0.4	0.4	0.5	0.3	
	I2C4 registers	0.9	0.7	0.7	0.4	
	I2C4 kernel	2.2	2.1	1.9	1.8	
	LPTIM2 registers	0.8	0.6	0.7	0.5	
	LPTIM2 kernel	2.3	2.1	1.8	1.4	
	LPTIM3 registers	0.7	0.7	0.7	0.4	
	LPTIM3 kernel	2.1	1.7	1.6	1.5	
	LPTIM4 registers	0.8	0.4	0.6	0.4	
	LPTIM4 kernel	2.2	2.0	1.7	1.5	
	LPTIM5 registers	0.5	0.4	0.6	0.4	
	LPTIM5 kernel	2.0	1.8	1.5	1.2	
	COMP12	0.6	0.4	0.5	0.2	
	VREF	0.4	0.2	0.2	0.1	
	RTC	1.1	0.9	1.0	0.6	
	SAI4 registers	1.7	1.4	1.3	1.0	
	SAI4 kernel	2.0	2.0	1.8	1.6	
	APB4 bridge	0.1	0.1	0.1	0.1	
	Total APB4	28	24.4	22.4	18.9	

6.3.8 Wakeup time from low-power modes

The wakeup times given in [Table 40](#) are measured starting from the wakeup event trigger up to the first instruction executed by the CPU:

- For Stop or Sleep modes: the wakeup event is WFE.
- WKUP (PC1) pin is used to wakeup from Standby, Stop and Sleep modes.

All timings are derived from tests performed under ambient temperature and $V_{DD}=3.3$ V.

Table 40. Low-power mode wakeup timings⁽¹⁾

Symbol	Parameter	Conditions	Typ ⁽²⁾	Max ⁽²⁾	Unit
$t_{WUSLEEP}^{(3)}$	Wakeup from Sleep	-	9	10	CPU clock cycles
$t_{WUSTOP}^{(3)}$	Wakeup from Stop	VOS3, HSI, flash memory in normal mode	4.4	5.6	μ s
		VOS3, HSI, flash memory in low-power mode	12	15	
		VOS4, HSI, flash memory in normal mode	15	20	
		VOS4, HSI, flash memory in low-power mode	23	28	
		VOS5, HSI, flash memory in normal mode	39	71	
		VOS5, HSI, flash memory in low-power mode	39	47	
		VOS3, CSI, flash memory in normal mode	30	37	
		VOS3, CSI, flash memory in low power mode	36	50	
		VOS4, CSI, flash memory in normal mode	38	48	
		VOS4, CSI, flash memory in low-power mode	47	61	
		VOS5, CSI, flash memory in normal mode	68	75	
		VOS5, CSI, flash memory in low-power mode	68	77	
$t_{WUSTOP_KERON}^{(3)}$	Wakeup from Stop, clock kept running	VOS3, HSI, flash memory in normal mode	2.6	3.4	μ s
		VOS3, CSI, flash memory in normal mode	26	36	
$t_{WUSTDBY}^{(3)}$	Wakeup from Standby mode	-	390	500	

1. The wakeup timings is valid for both CPUs.
2. Guaranteed by characterization results.
3. The wakeup times are measured from the wakeup event to the point in which the application code reads the first instruction.

6.3.9 External clock source characteristics

High-speed external user clock generated from an external source

In bypass mode the HSE oscillator is switched off and the input pin is a standard I/O.

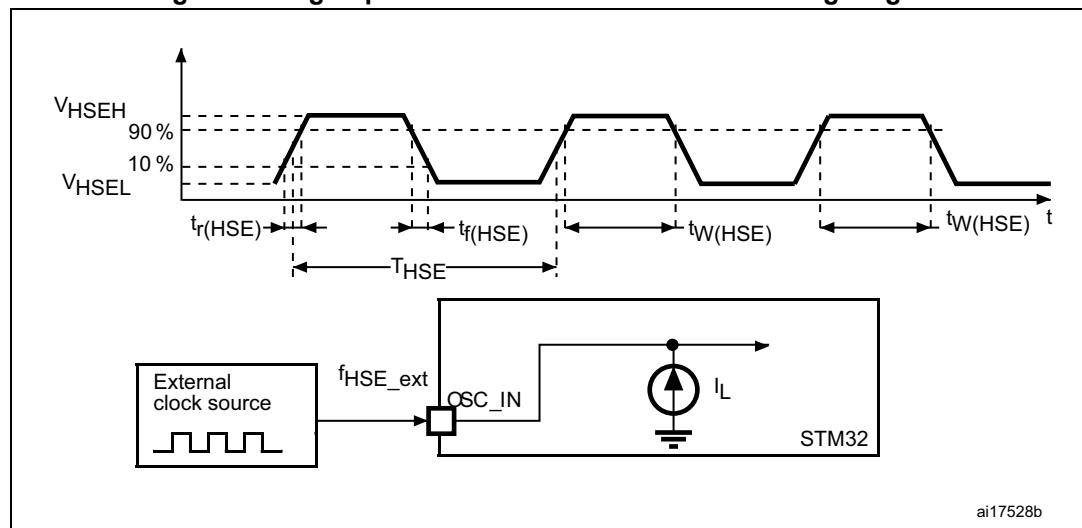
The external clock signal has to respect the [Table 59: I/O static characteristics](#). However, the recommended clock input waveform is shown in [Figure 21](#).

Table 41. High-speed external user clock characteristics⁽¹⁾

Symbol	Parameter	Min	Typ	Max	Unit
f_{HSE_ext}	User external clock source frequency	4	25	50	MHz
V_{HSEH}	Digital OSC_IN input high-level voltage	0.7 V_{DD}	-	V_{DD}	V
V_{HSEL}	Digital OSC_IN input low-level voltage	V_{SS}	-	0.3 V_{DD}	
$t_W(HSE)$	OSC_IN high or low time	7	-	-	ns

1. Guaranteed by design.

Figure 21. High-speed external clock source AC timing diagram



Low-speed external user clock generated from an external source

In bypass mode the LSE oscillator is switched off and the input pin is a standard I/O. The external clock signal has to respect the [Table 59: I/O static characteristics](#). However, the recommended clock input waveform is shown in [Figure 22](#).

Table 42. Low-speed external user clock characteristics⁽¹⁾

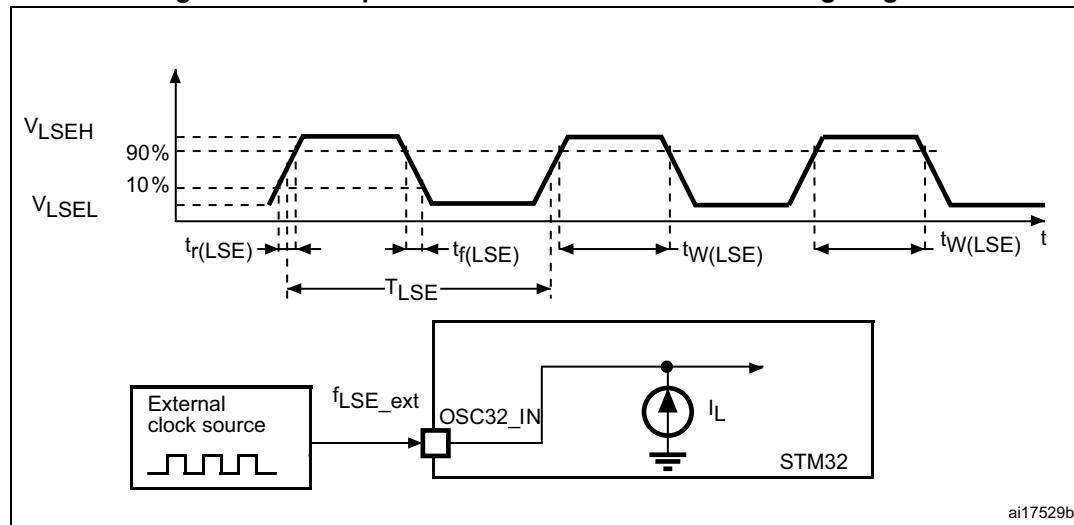
Symbol	Parameter	Min	Typ	Max	Unit
f_{LSE_ext}	User external clock source frequency	5	32.768	40	kHz
$V_{LSE_ext_PP}$	OSC32_IN peak-to-peak amplitude	0.3	-	$V_{SW}^{(2)}$	V
V_{LSE_ext}	OSC32_IN input range	0	-	$V_{SW}^{(2)}$	
$t_w(LSEH)$ $t_w(LSEL)$	OSC32_IN high or low time for square signal input	10	-	-	μs

1. Specified by design. Not tested in production.

2. $V_{SW} = V_{DD}$ when $V_{DD} > V_{BOR0}$; $V_{SW} = V_{BAT}$ when $V_{DD} < V_{BOR0}$. If the customer application includes V_{BAT} mode, OSC32_IN peak-to-peak must be lower than V_{BOR0} . Otherwise, the LSE frequency is not guaranteed during switching to/from V_{BAT} mode.

Note: For information on selecting the crystal, refer to the application note AN2867 "Oscillator design guide for STM8AL/AF/S, STM32 MCUs and MPUs" available from the ST website www.st.com.

Figure 22. Low-speed external clock source AC timing diagram



ai17529b

High-speed external clock generated from a crystal/ceramic resonator

The high-speed external (HSE) clock can be supplied with a 4 to 48 MHz crystal/ceramic resonator oscillator. All the information given in this paragraph are based on characterization results obtained with typical external components specified in [Table 43](#). In the application, the resonator and the load capacitors have to be placed as close as possible to the oscillator pins in order to minimize output distortion and startup stabilization time. Refer to the crystal resonator manufacturer for more details on the resonator characteristics (frequency, package, accuracy).

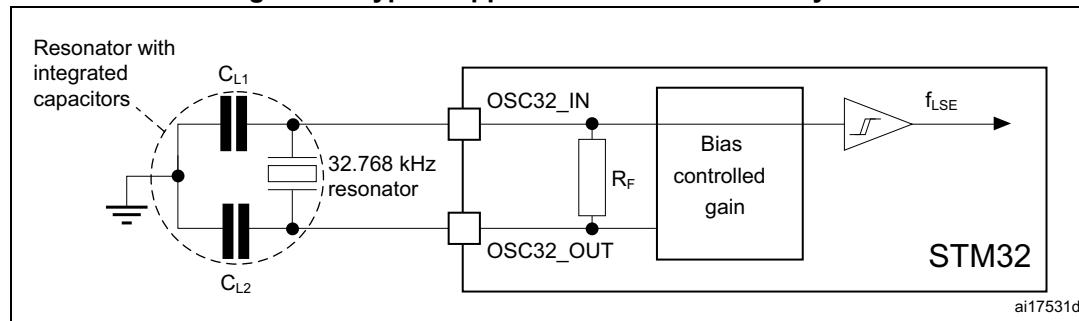
Table 43. 4-48 MHz HSE oscillator characteristics⁽¹⁾

Symbol	Parameter	Operating conditions ⁽²⁾	Min	Typ	Max	Unit
F	Oscillator frequency	-	4	-	48	MHz
R _F	Feedback resistor	-	-	200	-	kΩ
I _{DD(HSE)}	HSE current consumption	During startup ⁽³⁾	-	-	4	mA
		V _{DD} =3 V, R _m =30 Ω C _L =10 pF@4MHz	-	0.35	-	
		V _{DD} =3 V, R _m =30 Ω C _L =10 pF at 8 MHz	-	0.40	-	
		V _{DD} =3 V, R _m =30 Ω C _L =10 pF at 16 MHz	-	0.45	-	
		V _{DD} =3 V, R _m =30 Ω C _L =10 pF at 32 MHz	-	0.65	-	
		V _{DD} =3 V, R _m =30 Ω C _L =10 pF at 48 MHz	-	0.95	-	
Gm _{critmax}	Maximum critical crystal gm	Startup	-	-	1.5	mA/V
t _{SU} ⁽⁴⁾	Start-up time	V _{DD} is stabilized	-	2	-	ms

1. Guaranteed by design.
2. Resonator characteristics given by the crystal/ceramic resonator manufacturer.
3. This consumption level occurs during the first 2/3 of the t_{SU(HSE)} startup time.
4. t_{SU(HSE)} is the startup time measured from the moment it is enabled (by software) to a stabilized 8 MHz oscillation is reached. This value is measured for a standard crystal resonator and it can vary significantly with the crystal manufacturer.

Note: For information on selecting the crystal, refer to the application note AN2867 “Oscillator design guide for STM8AF/AL/S, STM32 MCUs and MPUs” available from the ST website www.st.com.

Figure 23. Typical application with an 8 MHz crystal



1. R_{EXT} value depends on the crystal characteristics.

Low-speed external clock generated from a crystal/ceramic resonator

The low-speed external (LSE) clock can be supplied with a 32.768 kHz crystal/ceramic resonator oscillator. All the information given in this paragraph are based on characterization results obtained with typical external components specified in [Table 44](#). In the application, the resonator and the load capacitors have to be placed as close as possible to the oscillator pins in order to minimize output distortion and startup stabilization time. Refer to the crystal resonator manufacturer for more details on the resonator characteristics (frequency, package, accuracy).

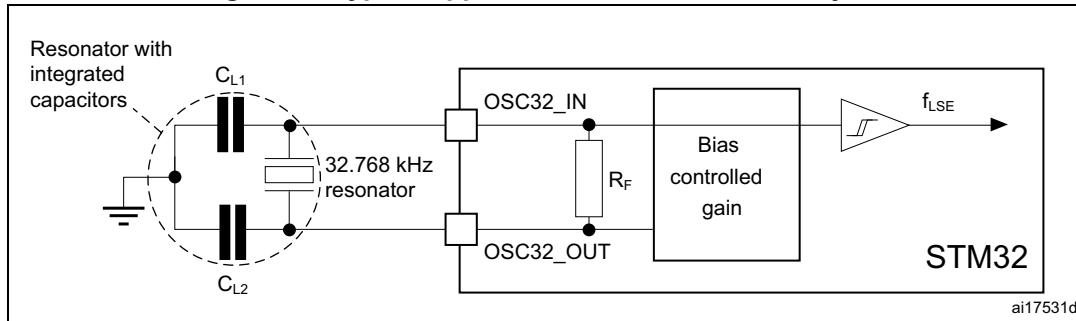
Table 44. Low-speed external user clock characteristics⁽¹⁾

Symbol	Parameter	Operating conditions ⁽²⁾	Min	Typ	Max	Unit
F	Oscillator frequency	-	-	32.768	-	kHz
I_{DD}	LSE current consumption	LSEDRV[1:0] = 00, Low drive capability	-	290	-	nA
		LSEDRV[1:0] = 01, Medium Low drive capability	-	390	-	
		LSEDRV[1:0] = 10, Medium high drive capability	-	550	-	
		LSEDRV[1:0] = 11, High drive capability	-	900	-	
$Gm_{critmax}$	Maximum critical crystal gm	LSEDRV[1:0] = 00, Low drive capability	-	-	0.5	$\mu A/V$
		LSEDRV[1:0] = 01, Medium Low drive capability	-	-	0.75	
		LSEDRV[1:0] = 10, Medium high drive capability	-	-	1.7	
		LSEDRV[1:0] = 11, High drive capability	-	-	2.7	
$t_{SU}^{(3)}$	Startup time	VDD is stabilized	-	2	-	s

- Guaranteed by design.
- Refer to the note and caution paragraphs below the table, and to the application note AN2867 "Oscillator design guide for STM8AL/AF/S, STM32 MCUs and MPUs".
- t_{SU} is the startup time measured from the moment it is enabled (by software) to a stabilized 32.768 kHz oscillation is reached. This value is measured for a standard crystal resonator and it can vary significantly with the crystal manufacturer.

Note: For information on selecting the crystal, refer to the application note AN2867 "Oscillator design guide for STM8AL/AF/S, STM32 MCUs and MPUs" available from the ST website www.st.com.

Figure 24. Typical application with a 32.768 kHz crystal



1. An external resistor is not required between OSC32_IN and OSC32_OUT and it is forbidden to add one.

6.3.10 Internal clock source characteristics

The parameters given in [Table 45](#) to [Table 48](#) are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#).

48 MHz high-speed internal RC oscillator (HSI48)

Table 45. HSI48 oscillator characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSI48}	HSI48 frequency	$V_{DD}=3.3\text{ V}, T_J=30\text{ }^\circ\text{C}$	47.5 ⁽¹⁾	48	48.5 ⁽¹⁾	MHz
TRIM ⁽²⁾	USER trimming step	-	-	0.175	-	%
USER TRIM COVERAGE ⁽³⁾	USER TRIMMING Coverage	± 32 steps	± 4.79	± 5.60	-	%
DuCy(HSI48) ⁽²⁾	Duty Cycle	-	45	-	55	%
ACCHSI48_REL ⁽³⁾⁽⁴⁾	Accuracy of the HSI48 oscillator over temperature (factory calibrated)	$T_J=-40$ to $125\text{ }^\circ\text{C}$	-4.5	-	3.5	%
		$T_J=-40$ to $140\text{ }^\circ\text{C}$	-4.5	-	4	
$\Delta V_{DD}(HSI48)^{(3)}$	HSI48 oscillator frequency drift with $V_{DD}^{(5)}$	$V_{DD}=3$ to 3.6 V	-	0.025	0.05	%
		$V_{DD}=1.62\text{ V}$ to 3.6 V	-	0.05	0.1	
$t_{su(HSI48)}^{(2)}$	HSI48 oscillator start-up time	-	-	2.1	4.0	μs
$I_{DD(HSI48)}^{(2)}$	HSI48 oscillator power consumption	-	-	350	400	μA
N_T jitter	Next transition jitter Accumulated jitter on 28 cycles ⁽⁶⁾	-	-	± 0.15	-	ns
P_T jitter	Paired transition jitter Accumulated jitter on 56 cycles ⁽⁶⁾	-	-	± 0.25	-	ns

1. Guaranteed by test in production.

2. Guaranteed by design.

3. Guaranteed by characterization.

4. $\Delta f_{HSI} = ACCHSI48_REL + \Delta_{VDD}$.
5. These values are obtained by using the formula: $(Freq(3.6V) - Freq(3.0V)) / Freq(3.0V)$ or $(Freq(3.6V) - Freq(1.62V)) / Freq(1.62V)$.
6. Jitter measurements are performed without clock source activated in parallel.

64 MHz high-speed internal RC oscillator (HSI)

Table 46. HSI oscillator characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSI}	HSI frequency	$V_{DD}=3.3\text{ V}, T_J=30\text{ }^\circ\text{C}$	63.7 ⁽²⁾	64	64.3 ⁽²⁾	MHz
TRIM	HSI user trimming step	Trimming is not a multiple of 32	-	0.24	0.32	%
		Trimming is 128, 256 and 384	-5.2	-1.8	-	
		Trimming is 64, 192, 320 and 448	-1.4	-0.8	-	
		Other trimming are a multiple of 32 (not including multiple of 64 and 128)	-0.6	-0.25	-	
DuCy(HSI)	Duty Cycle	-	45	-	55	%
ΔVDD (HSI)	HSI oscillator frequency drift over V_{DD} (reference is 3.3 V)	$V_{DD}=1.62$ to 3.6 V	-0.12	-	0.03	%
Δ_{TEMP} (HSI)	HSI oscillator frequency drift over temperature (reference is 64 MHz)	$T_J=-20$ to 105 $^\circ\text{C}$	-1 ⁽³⁾	-	1 ⁽³⁾	%
		$T_J=-40$ to T_Jmax $^\circ\text{C}$	-2 ⁽³⁾	-	1 ⁽³⁾	
t_{su} (HSI)	HSI oscillator start-up time	-	-	1.4	2	μs
t_{stab} (HSI)	HSI oscillator stabilization time	at 1% of target frequency	-	4	8	μs
I_{DD} (HSI)	HSI oscillator power consumption	-	-	300	400	μA

1. Guaranteed by design unless otherwise specified.
2. Guaranteed by test in production.
3. Guaranteed by characterization.

4 MHz low-power internal RC oscillator (CSI)

Table 47. CSI oscillator characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{CSI}	CSI frequency	$V_{DD}=3.3\text{ V}, T_J=30\text{ }^\circ\text{C}$	3.96 ⁽²⁾	4	4.04 ⁽²⁾	MHz
TRIM	Trimming step	-	-	0.35	-	%
DuCy(CSI)	Duty Cycle	-	45	-	55	%
Δ_{TEMP} (CSI)	CSI oscillator frequency drift over temperature	$T_J = 0$ to 85 $^\circ\text{C}$	-	-3.7 ⁽³⁾	4.5 ⁽³⁾	%
		$T_J = -40$ to 140 $^\circ\text{C}$	-	-11 ⁽³⁾	7.5 ⁽³⁾	

Table 47. CSI oscillator characteristics⁽¹⁾ (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
D _{VDD} (CSI)	CSI oscillator frequency drift over V _{DD}	V _{DD} = 1.62 to 3.6 V	-	-0.06	0.06	%
t _{su(CSI)}	CSI oscillator startup time	-	-	1	2	μs
t _{stab(CSI)}	CSI oscillator stabilization time (to reach ±3% of f _{CSI})	-	-	-	4	cycle
I _{DD(CSI)}	CSI oscillator power consumption	-	-	23	30	μA

1. Guaranteed by design.

2. Guaranteed by test in production.

3. Guaranteed by characterization.

Low-speed internal (LSI) RC oscillator**Table 48. LSI oscillator characteristics**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f _{LSI}	LSI frequency	V _{DD} = 3.3 V, T _J = 25 °C	31.4 ⁽¹⁾	32	32.6 ⁽¹⁾	kHz
		T _J = -40 to 110 °C, V _{DD} = 1.62 to 3.6 V	29.76 ⁽²⁾	-	33.6 ⁽²⁾	
		T _J = -40 to 125 °C, V _{DD} = 1.62 to 3.6 V	29.4	-	33.6	
		T _J = -40 to 140 °C, V _{DD} = 1.62 to 3.6 V	29.4	-	33.6	
t _{su(LSI)} ⁽³⁾	LSI oscillator startup time	-	-	80	130	μs
t _{stab(LSI)} ⁽³⁾	LSI oscillator stabilization time (5% of final value)	-	-	120	170	
I _{DD(LSI)} ⁽³⁾	LSI oscillator power consumption	-	-	130	280	nA

1. Guaranteed by test in production.

2. Guaranteed by characterization results.

3. Guaranteed by design.

6.3.11 PLL characteristics

The parameters given in [Table 49](#) are derived from tests performed under temperature and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#).

Table 49. PLL characteristics (wide VCO frequency range)⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	
f_{PLL_IN}	PLL input clock	-	2	-	16	MHz	
	PLL input clock duty cycle	-	10	-	90	%	
$f_{PLL_P_OUT}$	PLL multiplier output clock P	VOS0	1.5	-	480 ⁽²⁾	MHz	
		VOS1	1.5	-	400 ⁽²⁾		
		VOS2	1.5	-	300 ⁽²⁾		
		VOS3	1.5	-	200 ⁽²⁾		
f_{VCO_OUT}	PLL VCO output	-	192	-	960		
t_{LOCK}	PLL lock time	Normal mode	-	50 ⁽³⁾	150 ⁽³⁾	μs	
		Sigma-delta mode ($CKIN \geq 8$ MHz)	-	58 ⁽³⁾	166 ⁽³⁾		
Jitter	Cycle-to-cycle jitter ⁽⁴⁾	-	VCO = 192 MHz	-	134	$\pm ps$	
			VCO = 200 MHz	-	134		
			VCO = 400 MHz	-	76		
			VCO = 800 MHz	-	39		
	Long term jitter	Normal mode	VCO = 800 MHz	-	± 0.7	$\%$	
		Sigma-delta mode ($CKIN = 16$ MHz)	VCO = 800 MHz	-	± 0.8		
$I_{DD(PLL)}^{(3)}$	PLL power consumption on V_{DD}	VCO freq = 836 MHz	V_{DDA}	-	590	1500	μA
			V_{CORE}	-	720	-	
		VCO freq = 192 MHz	V_{DDA}	-	180	600	
			V_{CORE}	-	280	-	

1. Guaranteed by design unless otherwise specified.
2. This value must be limited to the maximum frequency due to the product limitation (480 MHz for VOS0, 400 MHz for VOS1, 300 MHz for VOS2, 200 MHz for VOS3).
3. Guaranteed by characterization results.
4. Integer mode only.

Table 50. PLL characteristics (medium VCO frequency range)⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	
f_{PLL_IN}	PLL input clock	-	1	-	2	MHz	
	PLL input clock duty cycle	-	10	-	90	%	
f_{PLL_OUT}	PLL multiplier output clock P, Q, R	VOS1	1.17	-	210	MHz	
		VOS2	1.17	-	210		
		VOS3	1.17	-	200		
f_{VCO_OUT}	PLL VCO output	-	150	-	420		
t_{LOCK}	PLL lock time	Normal mode	-	60 ⁽²⁾	100 ⁽²⁾	μs	
		Sigma-delta mode	forbidden				
Jitter	Cycle-to-cycle jitter ⁽³⁾	-	VCO = 150 MHz	-	145	-	$\pm ps$
			VCO = 300 MHz	-	91	-	
			VCO = 400 MHz	-	64	-	
			VCO = 420 MHz	-	63	-	
	Period jitter	$f_{PLL_OUT} = 50 MHz$	VCO = 150 MHz	-	55	-	$\pm ps$
			VCO = 400 MHz	-	30	-	
	Long term jitter	Normal mode	VCO = 400 MHz	-	± 0.3	-	%
$I_{(PLL)}^{(2)}$	PLL power consumption on V_{DD}	VCO freq = 420MHz	VDD	-	440	1150	μA
			VCORE	-	530	-	
		VCO freq = 150MHz	VDD	-	180	500	
			VCORE	-	200	-	

1. Guaranteed by design unless otherwise specified.

2. Guaranteed by characterization results.

3. Integer mode only.

6.3.12 Memory characteristics

Flash memory

The characteristics are given at $T_J = -40$ to 125°C unless otherwise specified.

The devices are shipped to customers with the flash memory erased.

Table 51. Flash memory characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_{DD}	Supply current	Write / Erase 8-bit mode	-	6.5	-	mA
		Write / Erase 16-bit mode	-	11.5	-	
		Write / Erase 32-bit mode	-	20	-	
		Write / Erase 64-bit mode	-	35	-	

Table 52. Flash memory programming

Symbol	Parameter	Conditions	Min ⁽¹⁾	Typ	Max ⁽¹⁾	Unit
t_{prog}	Word (266 bits) programming time	Program/erase parallelism x 8	-	290	580 ⁽²⁾	μs
		Program/erase parallelism x 16	-	180	360	
		Program/erase parallelism x 32	-	130	260	
		Program/erase parallelism x 64	-	100	200	
$t_{\text{ERASE128KB}}$	Sector (128 KB) erase time	Program/erase parallelism x 8	-	2	4	s
		Program/erase parallelism x 16	-	1.8	3.6	
		Program/erase parallelism x 32	-	1.1	2.2	
		Program/erase parallelism x 64	-	1	2	
t_{ME}	Mass erase time	Program/erase parallelism x 8	-	13	26	s
		Program/erase parallelism x 16	-	8	16	
		Program/erase parallelism x 32	-	6	12	
		Program/erase parallelism x 64	-	5	10	
V_{prog}	Programming voltage	Program parallelism x 8	1.62	-	3.6	V
		Program parallelism x 16				
		Program parallelism x 32				
		Program parallelism x 64	1.8	-	3.6	

1. Guaranteed by characterization results.

2. The maximum programming time is measured after 10K erase operations.

Table 53. Flash memory endurance and data retention

Symbol	Parameter	Conditions	Value	Unit
			Min ⁽¹⁾	
N _{END}	Endurance	T _J = -40 to +125 °C (6 suffix versions)	10	kcycles
t _{RET}	Data retention	1 kcycle at T _A = 85 °C	30	Years
		10 kcycles at T _A = 55 °C	20	

1. Guaranteed by characterization results.

6.3.13 EMC characteristics

Susceptibility tests are performed on a sample basis during device characterization.

Functional EMS (electromagnetic susceptibility)

While a simple application is executed on the device (toggling 2 LEDs through I/O ports), the device is stressed by two electromagnetic events until a failure occurs. The failure is indicated by the LEDs:

- **Electrostatic discharge (ESD)** (positive and negative) is applied to all device pins until a functional disturbance occurs. This test is compliant with the IEC 61000-4-2 standard.
- **FTB**: A burst of fast transient voltage (positive and negative) is applied to V_{DD} and V_{SS} through a 100 pF capacitor, until a functional disturbance occurs. This test is compliant with the IEC 61000-4-4 standard.

A device reset allows normal operations to be resumed.

The test results are given in [Table 54](#). They are based on the EMS levels and classes defined in application note AN1709.

Table 54. EMS characteristics

Symbol	Parameter	Conditions	Level/Class
V _{FESD}	Voltage limits to be applied on any I/O pin to induce a functional disturbance	V _{DD} = 3.3 V, T _A = +25 °C, UFBGA240, f _{rcc_c_ck} = 400 MHz, conforms to IEC 61000-4-2	3B
V _{FTB}	Fast transient voltage burst limits to be applied through 100 pF on V _{DD} and V _{SS} pins to induce a functional disturbance		5A

As a consequence, it is recommended to add a serial resistor (1 kΩ) located as close as possible to the MCU to the pins exposed to noise (connected to tracks longer than 50 mm on PCB).

Designing hardened software to avoid noise problems

EMC characterization and optimization are performed at component level with a typical application environment and simplified MCU software. It should be noted that good EMC performance is highly dependent on the user application and the software in particular.

Therefore it is recommended that the user applies EMC software optimization and prequalification tests in relation with the EMC level requested for his application.

Software recommendations

The software flowchart must include the management of runaway conditions such as:

- Corrupted program counter
- Unexpected reset
- Critical Data corruption (control registers...)

Prequalification trials

Most of the common failures (unexpected reset and program counter corruption) can be reproduced by manually forcing a low state on the NRST pin or the Oscillator pins for 1 second.

To complete these trials, ESD stress can be applied directly on the device, over the range of specification values. When unexpected behavior is detected, the software can be hardened to prevent unrecoverable errors occurring (see application note AN1015).

Electromagnetic Interference (EMI)

The electromagnetic field emitted by the device is monitored while a simple application, executing EEMBC code, is running. This emission test is compliant with SAE IEC61967-2 standard which specifies the test board and the pin loading.

Table 55. EMI characteristics for $f_{HSE} = 8 \text{ MHz}$ and $f_{CPU} = 400 \text{ MHz}$

Symbol	Parameter	Conditions	Monitored frequency band	Value	Unit
S_{EMI}	Peak ⁽¹⁾	$V_{DD} = 3.6 \text{ V}$, $T_A = 25^\circ\text{C}$, UFBGA240 package, compliant with IEC61967-2	0.1 MHz to 30 MHz	11	dB μ V
			30 MHz to 130 MHz	6	
			130 MHz to 1 GHz	12	
			1 GHz to 2 GHz	7	
	Level ⁽²⁾		0.1 MHz to 2 GHz	2.5	-

1. Refer to AN1709 "EMI radiated test" chapter.

2. Refer to AN1709 "EMI level classification" chapter.

6.3.14 Absolute maximum ratings (electrical sensitivity)

Based on three different tests (ESD, LU) using specific measurement methods, the device is stressed in order to determine its performance in terms of electrical sensitivity.

Electrostatic discharge (ESD)

Electrostatic discharges (a positive then a negative pulse) are applied to the pins of each sample according to each pin combination. This test conforms to the ANSI/ESDA/JEDEC JS-001 and ANSI/ESDA/JEDEC JS-002 standards.

Table 56. ESD absolute maximum ratings

Symbol	Ratings	Conditions	Packages	Class	Maximum value ⁽¹⁾	Unit
$V_{ESD(HBM)}$	Electrostatic discharge voltage (human body model)	$T_A = +25^\circ\text{C}$ conforming to ANSI/ESDA/JEDEC JS-001	All	1C	1000	V
$V_{ESD(CDM)}$	Electrostatic discharge voltage (charge device model)	$T_A = +25^\circ\text{C}$ conforming to ANSI/ESDA/JEDEC JS-002	All	C1	250	

1. Guaranteed by characterization results.

Static latchup

Two complementary static tests are required on six parts to assess the latchup performance:

- A supply overvoltage is applied to each power supply pin
- A current injection is applied to each input, output and configurable I/O pin

These tests are compliant with JESD78 IC latchup standard.

Table 57. Electrical sensitivities

Symbol	Parameter	Conditions	Class
LU	Static latchup class	$T_A = +25^\circ\text{C}$ conforming to JESD78	II level A

6.3.15 I/O current injection characteristics

As a general rule, a current injection to the I/O pins, due to external voltage below V_{SS} or above V_{DD} (for standard, 3.3 V-capable I/O pins) should be avoided during the normal product operation. However, in order to give an indication of the robustness of the microcontroller in cases when an abnormal injection accidentally happens, susceptibility tests are performed on a sample basis during the device characterization.

Functional susceptibility to I/O current injection

While a simple application is executed on the device, the device is stressed by injecting current into the I/O pins programmed in floating input mode. While current is injected into the I/O pin, one at a time, the device is checked for functional failures.

The failure is indicated by an out of range parameter: ADC error above a certain limit (higher than 5 LSB TUE), out of conventional limits of induced leakage current on adjacent pins (out of $-5 \mu A/+0 \mu A$ range), or other functional failure (for example reset, oscillator frequency deviation).

The following tables are the compilation of the SIC1/SIC2 and functional ESD results.

Negative induced A negative induced leakage current is caused by negative injection and positive induced leakage current by positive injection.

Table 58. I/O current injection susceptibility⁽¹⁾

Symbol	Description	Functional susceptibility		Unit
		Negative injection	Positive injection	
I_{INJ}	PA7, PC5, PG1, PB14, PJ7, PA11, PA12, PA13, PA14, PA15, PJ12, PB4	5	0	mA
	PA2, PH2, PH3, PE8, PA6, PA7, PC4, PE7, PE10, PE11	0	NA	
	PA0, PA_C, PA1, PA1_C, PC2, PC2_C, PC3, PC3_C, PA4, PA5, PH4, PH5, BOOT0	0	0	
	All other I/Os	5	NA	

- Guaranteed by characterization.

6.3.16 I/O port characteristics

General input/output characteristics

Unless otherwise specified, the parameters given in [Table 59: I/O static characteristics](#) are derived from tests performed under the conditions summarized in [Table 13: General operating conditions](#). All I/Os are CMOS and TTL compliant (except for BOOT0).

For information on GPIO configuration, refer to the application note AN4899 “STM32 GPIO configuration for hardware settings and low-power consumption” available from the ST website www.st.com.

Table 59. I/O static characteristics

Symbol	Parameter	Condition	Min	Typ	Max	Unit
V_{IL}	I/O input low level voltage except BOOT0	1.62 V < V_{DD} < 3.6 V	-	-	$0.3V_{DD}^{(1)}$	V
	I/O input low level voltage except BOOT0		-	-	$0.4V_{DD}^{(2)} - 0.1^{(2)}$	
	BOOT0 I/O input low level voltage		-	-	$0.19V_{DD}^{(2)} + 0.1^{(2)}$	
V_{IH}	I/O input high level voltage except BOOT0	1.62 V < V_{DD} < 3.6 V	$0.7V_{DD}^{(1)}$	-	-	V
	I/O input high level voltage except BOOT0		$0.47V_{DD}^{(2)} + 0.25^{(2)}$	-	-	
	BOOT0 I/O input high level voltage		$0.17V_{DD}^{(2)} + 0.6^{(2)}$	-	-	
$V_{HYS}^{(2)}$	TT_xx, FT_xxx and NRST I/O input hysteresis	1.62 V < V_{DD} < 3.6 V	-	250	-	mV
	BOOT0 I/O input hysteresis		-	200	-	
$I_{Ikg}^{(3)}$	FT_xx Input leakage current ⁽²⁾	$0 < V_{IN} \leq \text{Max}(V_{DDXXX})^{(8)}$	-	-	± 250	nA
		$\text{Max}(V_{DDXXX})^{(4)(5)(8)} < V_{IN} \leq 5.5 \text{ V}$	-	-	1500	
	FT_u IO	$0 < V_{IN} \leq \text{Max}(V_{DDXXX})^{(8)}$	-	-	± 350	
		$\text{Max}(V_{DDXXX})^{(4)(5)(8)} < V_{IN} \leq 5.5 \text{ V}$	-	-	5000 ⁽⁶⁾	
	TT_xx Input leakage current	$0 < V_{IN} \leq \text{Max}(V_{DDXXX})^{(8)}$	-	-	± 250	
	VPP (BOOT0 alternate function)	$0 < V_{IN} \leq V_{DD}$	-	-	15	
		$V_{DD} < V_{IN} \leq 9 \text{ V}$			35	
R_{PU}	Weak pull-up equivalent resistor ⁽⁷⁾	$V_{IN}=V_{SS}$	30	40	50	$k\Omega$
R_{PD}	Weak pull-down equivalent resistor ⁽⁷⁾	$V_{IN}=V_{DD}^{(8)}$	30	40	50	
C_{IO}	I/O pin capacitance	-	-	5	-	pF

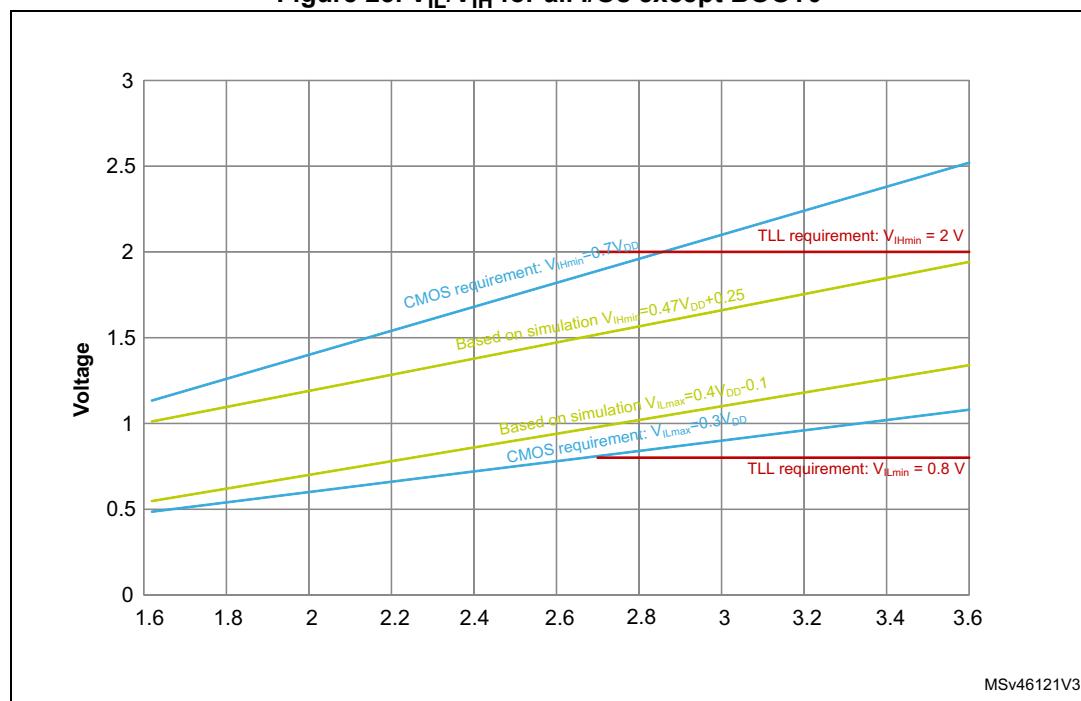
1. Compliant with CMOS requirements.

2. Guaranteed by design.

3. This parameter represents the pad leakage of the I/O itself. The total product pad leakage is provided by the following formula: $I_{Total_Ikg_max} = 10 \mu A + [\text{number of I/Os where } V_{IN} \text{ is applied on the pad}] \times I_{Ikg(\text{Max})}$.
4. All FT_xx IO except FT_Ju, FT_u and PC3.
5. V_{IN} must be less than Max(VDDXXX) + 3.6 V.
6. To sustain a voltage higher than MIN(V_{DD}, V_{DDA}, V_{DD33USB}) + 0.3 V, the internal pull-up and pull-down resistors must be disabled.
7. The pull-up and pull-down resistors are designed with a true resistance in series with a switchable PMOS/NMOS. This PMOS/NMOS contribution to the series resistance is minimal (~10% order).
8. Max(VDDXXX) is the maximum value of all the I/O supplies.

All I/Os are CMOS and TTL compliant (no software configuration required). Their characteristics cover more than the strict CMOS-technology or TTL parameters. The coverage of these requirements for FT I/Os is shown in [Figure 25](#).

Figure 25. V_{IL}/V_{IH} for all I/Os except BOOT0



Output driving current

The GPIOs (general purpose input/outputs) can sink or source up to ± 8 mA, and sink or source up to ± 20 mA (with a relaxed V_{OL}/V_{OH}).

In the user application, the number of I/O pins which can drive current must be limited to respect the absolute maximum rating specified in [Section 6.2](#). In particular:

- The sum of the currents sourced by all the I/Os on V_{DD} , plus the maximum Run consumption of the MCU sourced on V_{DD} , cannot exceed the absolute maximum rating ΣI_{VDD} (see [Table 11](#)).
- The sum of the currents sunk by all the I/Os on V_{SS} plus the maximum Run consumption of the MCU sunk on V_{SS} cannot exceed the absolute maximum rating ΣI_{VSS} (see [Table 11](#)).

Output voltage levels

Unless otherwise specified, the parameters given in [Table 60: Output voltage characteristics for all I/Os except PC13, PC14, PC15 and PI8](#) and [Table 61: Output voltage characteristics for PC13, PC14, PC15 and PI8](#) are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#). All I/Os are CMOS and TTL compliant.

Table 60. Output voltage characteristics for all I/Os except PC13, PC14, PC15 and PI8⁽¹⁾

Symbol	Parameter	Conditions ⁽³⁾	Min	Max	Unit
V_{OL}	Output low level voltage	CMOS port ⁽²⁾ $I_{IO}=8\text{ mA}$ $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	-	0.4	V
V_{OH}	Output high level voltage	CMOS port ⁽²⁾ $I_{IO}=-8\text{ mA}$ $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	$V_{DD}-0.4$	-	
$V_{OL}^{(3)}$	Output low level voltage	TTL port ⁽²⁾ $I_{IO}=8\text{ mA}$ $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	-	0.4	
$V_{OH}^{(3)}$	Output high level voltage	TTL port ⁽²⁾ $I_{IO}=-8\text{ mA}$ $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	2.4	-	
$V_{OL}^{(3)}$	Output low level voltage	$I_{IO}=20\text{ mA}$ $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	-	1.3	
$V_{OH}^{(3)}$	Output high level voltage	$I_{IO}=-20\text{ mA}$ $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	$V_{DD}-1.3$	-	
$V_{OL}^{(3)}$	Output low level voltage	$I_{IO}=4\text{ mA}$ $1.62\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	-	0.4	
$V_{OH}^{(3)}$	Output high level voltage	$I_{IO}=-4\text{ mA}$ $1.62\text{ V} \leq V_{DD} < 3.6\text{ V}$	$V_{DD}-0.4$	-	
$V_{OLFM+}^{(3)}$	Output low level voltage for an FTf I/O pin in FM+ mode	$I_{IO}=20\text{ mA}$ $2.3\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	-	0.4	
		$I_{IO}=10\text{ mA}$ $1.62\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	-	0.4	

- The IIO current sourced or sunk by the device must always respect the absolute maximum rating specified in [Table 10: Voltage characteristics](#), and the sum of the currents sourced or sunk by all the I/Os (I/O ports and control pins) must always respect the absolute maximum ratings ΣIIO .
- TTL and CMOS outputs are compatible with JEDEC standards JESD36 and JESD52.
- Guaranteed by design.

Table 61. Output voltage characteristics for PC13, PC14, PC15 and PI8⁽¹⁾

Symbol	Parameter	Conditions ⁽³⁾	Min	Max	Unit
V_{OL}	Output low level voltage	CMOS port ⁽²⁾ $I_{IO}=3\text{ mA}$ $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	-	0.4	V
V_{OH}	Output high level voltage	CMOS port ⁽²⁾ $I_{IO}=-3\text{ mA}$ $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	$V_{DD}-0.4$	-	
$V_{OL}^{(3)}$	Output low level voltage	TTL port ⁽²⁾ $I_{IO}=3\text{ mA}$ $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	-	0.4	
$V_{OH}^{(2)}$	Output high level voltage	TTL port ⁽²⁾ $I_{IO}=-3\text{ mA}$ $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	2.4	-	
$V_{OL}^{(2)}$	Output low level voltage	$I_{IO}=1.5\text{ mA}$ $1.62\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	-	0.4	
$V_{OH}^{(2)}$	Output high level voltage	$I_{IO}=-1.5\text{ mA}$ $1.62\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	$V_{DD}-0.4$	-	

1. The I/O current sourced or sunk by the device must always respect the absolute maximum rating specified in [Table 10: Voltage characteristics](#), and the sum of the currents sourced or sunk by all the I/Os (I/O ports and control pins) must always respect the absolute maximum ratings ΣI_{IO} .
2. TTL and CMOS outputs are compatible with JEDEC standards JESD36 and JESD52.
3. Guaranteed by design.

Output buffer timing characteristics (HSLV option disabled)

The HSLV bit of SYSCFG_CCCSR register can be used to optimize the I/O speed when the product voltage is below 2.7 V.

Table 62. Output timing characteristics (HSLV OFF)⁽¹⁾⁽²⁾

Speed	Symbol	Parameter	conditions	Min	Max	Unit
00	$F_{max}^{(3)}$	Maximum frequency	C=50 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	12	MHz
			C=50 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	3	
			C=30 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	12	
			C=30 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	3	
			C=10 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	16	
			C=10 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	4	
	$t_r/t_f^{(4)}$	Output high to low level fall time and output low to high level rise time	C=50 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	16.6	ns
			C=50 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	33.3	
			C=30 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	13.3	
			C=30 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	25	
			C=10 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	10	
			C=10 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	20	
01	$F_{max}^{(3)}$	Maximum frequency	C=50 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	60	MHz
			C=50 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	15	
			C=30 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	80	
			C=30 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	15	
			C=10 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	110	
			C=10 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	20	
	$t_r/t_f^{(4)}$	Output high to low level fall time and output low to high level rise time	C=50 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	5.2	ns
			C=50 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	10	
			C=30 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	4.2	
			C=30 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	7.5	
			C=10 pF, 2.7 V≤ V_{DD} ≤3.6 V	-	2.8	
			C=10 pF, 1.62 V≤ V_{DD} ≤2.7 V	-	5.2	

Table 62. Output timing characteristics (HSLV OFF)⁽¹⁾⁽²⁾ (continued)

Speed	Symbol	Parameter	conditions	Min	Max	Unit
10	$F_{max}^{(3)}$	Maximum frequency	C=50 pF, 2.7 V≤V _{DD} ≤3.6 V ⁽⁵⁾	-	85	MHz
			C=50 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁵⁾	-	35	
			C=30 pF, 2.7 V≤V _{DD} ≤3.6 V ⁽⁵⁾	-	110	
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁵⁾	-	40	
			C=10 pF, 2.7 V≤V _{DD} ≤3.6 V ⁽⁵⁾	-	166	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁵⁾	-	85	
11	$t_r/t_f^{(4)}$	Output high to low level fall time and output low to high level rise time	C=50 pF, 2.7 V≤V _{DD} ≤3.6 V ⁽⁵⁾	-	3.8	ns
			C=50 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁵⁾	-	6.9	
			C=30 pF, 2.7 V≤V _{DD} ≤3.6 V ⁽⁵⁾	-	2.8	
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁵⁾	-	5.2	
			C=10 pF, 2.7 V≤V _{DD} ≤3.6 V ⁽⁵⁾	-	1.8	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V ^V	-	3.3	
11	$F_{max}^{(3)}$	Maximum frequency	C=50 pF, 2.7 V≤V _{DD} ≤3.6 V ^V	-	100	MHz
			C=50 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁵⁾	-	50	
			C=30 pF, 2.7 V≤V _{DD} ≤3.6 V ^V	-	133	
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁵⁾	-	66	
			C=10 pF, 2.7 V≤V _{DD} ≤3.6 V ⁽⁵⁾	-	220	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁵⁾	-	100	
11	$t_r/t_f^{(4)}$	Output high to low level fall time and output low to high level rise time	C=50 pF, 2.7 V≤V _{DD} ≤3.6 V ⁽⁵⁾	-	3.3	ns
			C=50 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁵⁾	-	6.6	
			C=30 pF, 2.7 V≤V _{DD} ≤3.6 V ⁽⁵⁾	-	2.4	
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁵⁾	-	4.5	
			C=10 pF, 2.7 V≤V _{DD} ≤3.6 V ⁽⁵⁾	-	1.5	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁵⁾	-	2.7	

1. Guaranteed by design.
2. The frequency of the GPIOs that can be supplied in V_{BAT} mode (PC13, PC14, PC15 and PI8) is limited to 2 MHz
3. The maximum frequency is defined with the following conditions:
 $(t_r+t_f) \leq 2/3 T$
 Skew ≤ 1/20 T
 45% < Duty cycle < 55%
4. The fall and rise times are defined between 90% and 10% and between 10% and 90% of the output waveform, respectively.
5. Compensation system enabled.

Output buffer timing characteristics (HSLV option enabled)

Table 63. Output timing characteristics (HSLV ON)⁽¹⁾

Speed	Symbol	Parameter	conditions	Min	Max	Unit
00	$F_{\max}^{(2)}$	Maximum frequency	C=50 pF, 1.62 V≤V _{DD} ≤2.7 V	-	10	MHz
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V	-	10	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V	-	10	
	$t_r/t_f^{(3)}$	Output high to low level fall time and output low to high level rise time	C=50 pF, 1.62 V≤V _{DD} ≤2.7 V	-	11	ns
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V	-	9	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V	-	6.6	
01	$F_{\max}^{(2)}$	Maximum frequency	C=50 pF, 1.62 V≤V _{DD} ≤2.7 V	-	50	MHz
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V	-	58	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V	-	66	
	$t_r/t_f^{(3)}$	Output high to low level fall time and output low to high level rise time	C=50 pF, 1.62 V≤V _{DD} ≤2.7 V	-	6.6	ns
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V	-	4.8	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V	-	3	
10	$F_{\max}^{(2)}$	Maximum frequency	C=50 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	55	MHz
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	80	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	133	
	$t_r/t_f^{(3)}$	Output high to low level fall time and output low to high level rise time	C=50 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	5.8	ns
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	4	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	2.4	
11	$F_{\max}^{(2)}$	Maximum frequency	C=50 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	60	MHz
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	90	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	175	
	$t_r/t_f^{(3)}$	Output high to low level fall time and output low to high level rise time	C=50 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	5.3	ns
			C=30 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	3.6	
			C=10 pF, 1.62 V≤V _{DD} ≤2.7 V ⁽⁴⁾	-	1.9	

1. Guaranteed by design.
2. The maximum frequency is defined with the following conditions:
 $(t_r+t_f) \leq 2/3 T$
 Skew ≤ 1/20 T
 45% < Duty cycle < 55%
3. The fall and rise times are defined between 90% and 10% and between 10% and 90% of the output waveform, respectively.
4. Compensation system enabled.

6.3.17 NRST pin characteristics

The NRST pin input driver uses CMOS technology. It is connected to a permanent pull-up resistor, R_{PU} (see [Table 59: I/O static characteristics](#)).

Unless otherwise specified, the parameters given in [Table 64](#) are derived from tests performed under the ambient temperature and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#).

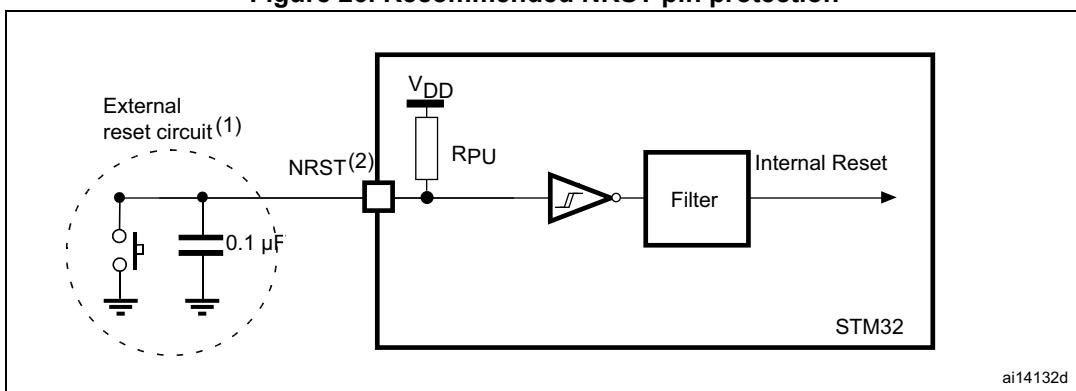
Table 64. NRST pin characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$R_{PU}^{(2)}$	Weak pull-up equivalent resistor ⁽¹⁾	$V_{IN} = V_{SS}$	30	40	50	kΩ
$V_{F(NRST)}^{(2)}$	NRST Input filtered pulse	$1.71 \text{ V} < V_{DD} < 3.6 \text{ V}$	-	-	50	ns
$V_{NF(NRST)}^{(2)}$	NRST Input not filtered pulse	$1.71 \text{ V} < V_{DD} < 3.6 \text{ V}$	300	-	-	
		$1.62 \text{ V} < V_{DD} < 3.6 \text{ V}$	1000	-	-	

1. The pull-up is designed with a true resistance in series with a switchable PMOS. This PMOS contribution to the series resistance must be minimum (~10% order).

2. Guaranteed by design.

Figure 26. Recommended NRST pin protection



ai14132d

1. The reset network protects the device against parasitic resets.
2. The user must ensure that the level on the NRST pin can go below the $V_{IL(NRST)}$ max level specified in [Table 59](#). Otherwise the reset is not taken into account by the device.

6.3.18 FMC characteristics

Unless otherwise specified, the parameters given in [Table 65](#) to [Table 78](#) for the FMC interface are derived from tests performed under the ambient temperature, f_{HCLK} frequency and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#), with the following configuration:

- Output speed is set to OSPEEDRy[1:0] = 11
- Measurement points are done at CMOS levels: $0.5V_{DD}$
- IO Compensation cell activated.
- HSLV activated when $V_{DD} \leq 2.7 \text{ V}$
- VOS level set to VOS1.

Refer to [Section 6.3.16: I/O port characteristics](#) for more details on the input/output alternate function characteristics.

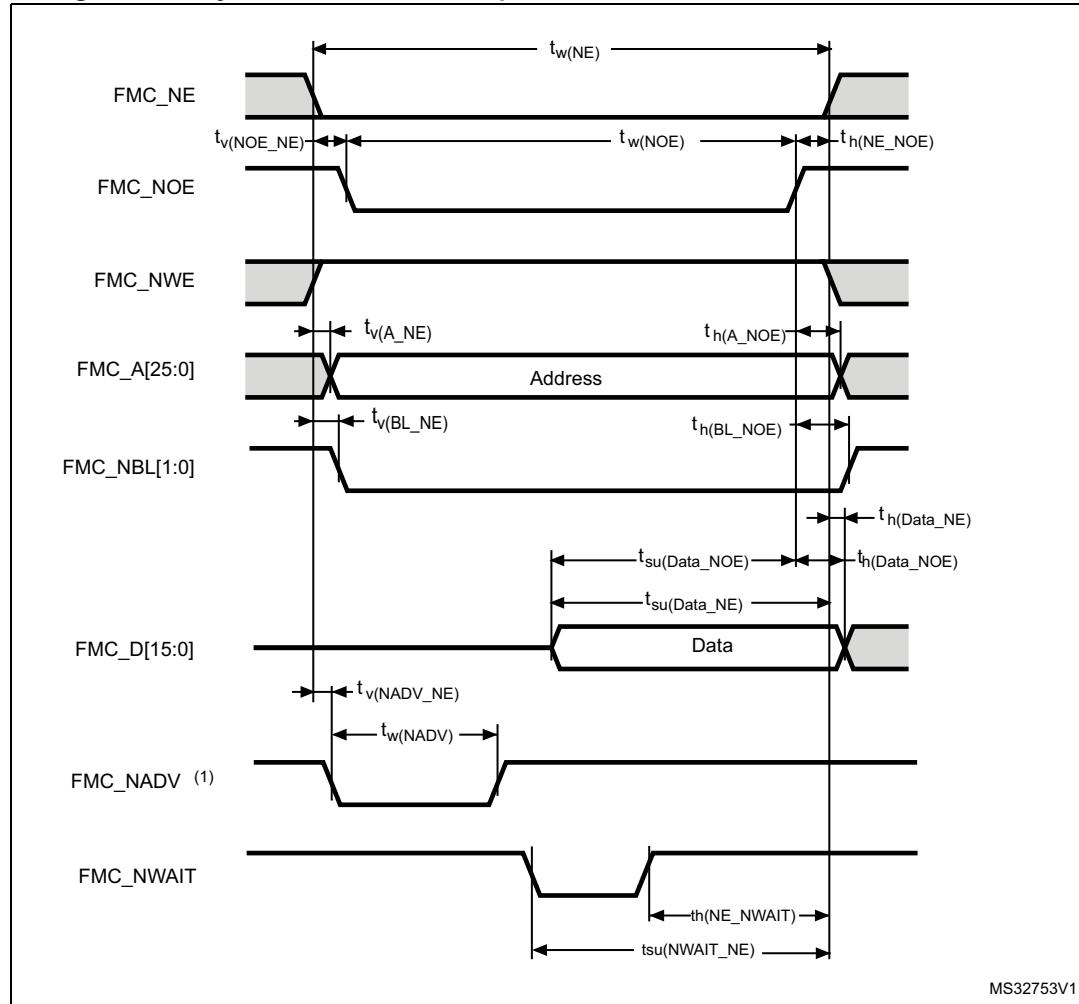
Asynchronous waveforms and timings

[Figure 27](#) through [Figure 29](#) represent asynchronous waveforms and [Table 65](#) through [Table 72](#) provide the corresponding timings. The results shown in these tables are obtained with the following FMC configuration:

- AddressSetupTime = 0x1
- AddressHoldTime = 0x1
- DataSetupTime = 0x1 (except for asynchronous NWAIT mode , DataSetupTime = 0x5)
- BusTurnAroundDuration = 0x0
- Capacitive load C_L = 30 pF

In all timing tables, the T_{KERCK} is the $f_{mc_ker_ck}$ clock period.

Figure 27. Asynchronous non-multiplexed SRAM/PSRAM/NOR read waveforms



1. Mode 2/B, C and D only. In Mode 1, FMC_NADV is not used.

MS32753V1

Table 65. Asynchronous non-multiplexed SRAM/PSRAM/NOR read timings⁽¹⁾

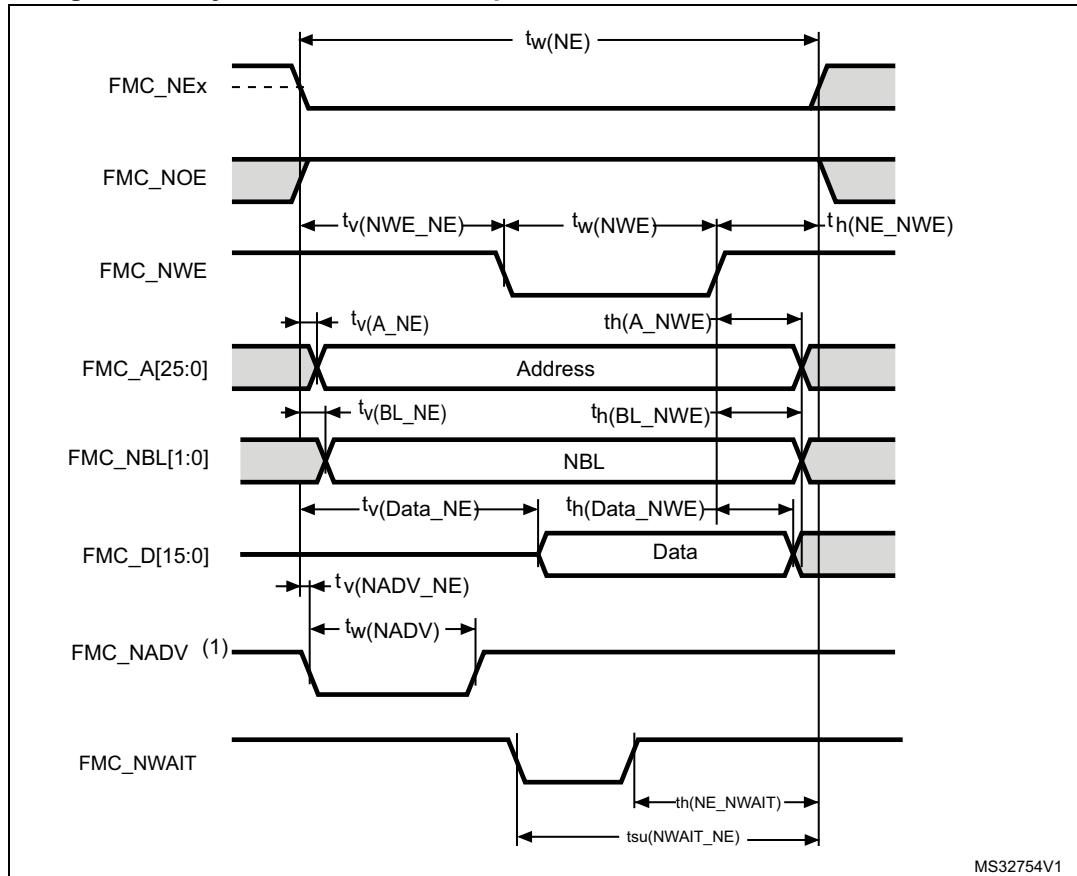
Symbol	Parameter	Min	Max	Unit
$t_w(NE)$	FMC_NE low time	$3T_{fmc_ker_ck}-1$	$3T_{fmc_ker_ck}+1$	ns
$t_v(NO_E_NE)$	FMC_NEx low to FMC_NOE low	0	0.5	
$t_w(NO_E)$	FMC_NOE low time	$2T_{fmc_ker_ck}-1$	$2T_{fmc_ker_ck}+1$	
$t_h(NE_NOE)$	FMC_NOE high to FMC_NE high hold time	0	-	
$t_v(A_NE)$	FMC_NEx low to FMC_A valid	-	0.5	
$t_h(A_NOE)$	Address hold time after FMC_NOE high	0	-	
$t_{su}(Data_NE)$	Data to FMC_NEx high setup time	11	-	
$t_{su}(Data_NOE)$	Data to FMC_NOEx high setup time	11	-	
$t_h(Data_NOE)$	Data hold time after FMC_NOE high	0	-	
$t_h(Data_NE)$	Data hold time after FMC_NEx high	0	-	
$t_v(NADV_NE)$	FMC_NEx low to FMC_NADV low	-	0	
$t_w(NADV)$	FMC_NADV low time	-	$T_{fmc_ker_ck}+1$	

1. Guaranteed by characterization results.

Table 66. Asynchronous non-multiplexed SRAM/PSRAM/NOR read-NWAIT timings⁽¹⁾⁽²⁾

Symbol	Parameter	Min	Max	Unit
$t_w(NE)$	FMC_NE low time	$7T_{fmc_ker_ck}+1$	$7T_{fmc_ker_ck}+1$	ns
$t_w(NO_E)$	FMC_NOE low time	$5T_{fmc_ker_ck}-1$	$5T_{fmc_ker_ck}+1$	
$t_w(NWAIT)$	FMC_NWAIT low time	$T_{fmc_ker_ck}-0.5$	-	
$t_{su}(NWAIT_NE)$	FMC_NWAIT valid before FMC_NEx high	$4T_{fmc_ker_ck}+11$	-	
$t_h(NE_NWAIT)$	FMC_NEx hold time after FMC_NWAIT invalid	$3T_{fmc_ker_ck}+11.5$	-	

1. Guaranteed by characterization results.
 2. N_{WAIT} pulse width is equal to 1 AHB cycle.

Figure 28. Asynchronous non-multiplexed SRAM/PSRAM/NOR write waveforms

1. Mode 2/B, C and D only. In Mode 1, FMC_NADV is not used.

MS32754V1

Table 67. Asynchronous non-multiplexed SRAM/PSRAM/NOR write timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$3T_{fmc_ker_ck} - 1$	$3T_{fmc_ker_ck}$	ns
$t_{v(NWE_NE)}$	FMC_NEx low to FMC_NWE low	$T_{fmc_ker_ck}$	$T_{fmc_ker_ck} + 1$	
$t_{w(NWE)}$	FMC_NWE low time	$T_{fmc_ker_ck} - 0.5$	$T_{fmc_ker_ck} + 0.5$	
$t_{h(NE_NWE)}$	FMC_NWE high to FMC_NE high hold time	$T_{fmc_ker_ck}$	-	
$t_{v(A_NE)}$	FMC_NEx low to FMC_A valid	-	2	
$t_{h(A_NWE)}$	Address hold time after FMC_NWE high	$T_{fmc_ker_ck} - 0.5$	-	
$t_{v(BL_NE)}$	FMC_NEx low to FMC_BL valid	-	0.5	
$t_{h(BL_NWE)}$	FMC_BL hold time after FMC_NWE high	$T_{fmc_ker_ck} - 0.5$	-	
$t_{v(Data_NE)}$	Data to FMC_NEx low to Data valid	-	$T_{fmc_ker_ck} + 2.5$	
$t_{h(Data_NWE)}$	Data hold time after FMC_NWE high	$T_{fmc_ker_ck} + 0.5$	-	
$t_{v(NADV_NE)}$	FMC_NEx low to FMC_NADV low	-	0	
$t_{w(NADV)}$	FMC_NADV low time	-	$T_{fmc_ker_ck} + 1$	

1. Guaranteed by characterization results.

Table 68. Asynchronous non-multiplexed SRAM/PSRAM/NOR write-NWAIT timings⁽¹⁾⁽²⁾

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$8T_{fmc_ker_ck} - 1$	$8T_{fmc_ker_ck} + 1$	ns
$t_{w(NWE)}$	FMC_NWE low time	$6T_{fmc_ker_ck} - 1.5$	$6T_{fmc_ker_ck} + 0.5$	
$t_{su(NWAIT_NE)}$	FMC_NWAIT valid before FMC_NEx high	$5T_{fmc_ker_ck} + 13$	-	
$t_{h(NE_NWAIT)}$	FMC_NEx hold time after FMC_NWAIT invalid	$4T_{fmc_ker_ck} + 13$	-	

1. Guaranteed by characterization results.

2. N_WAIT pulse width is equal to 1 AHB cycle.

Figure 29. Asynchronous multiplexed PSRAM/NOR read waveforms

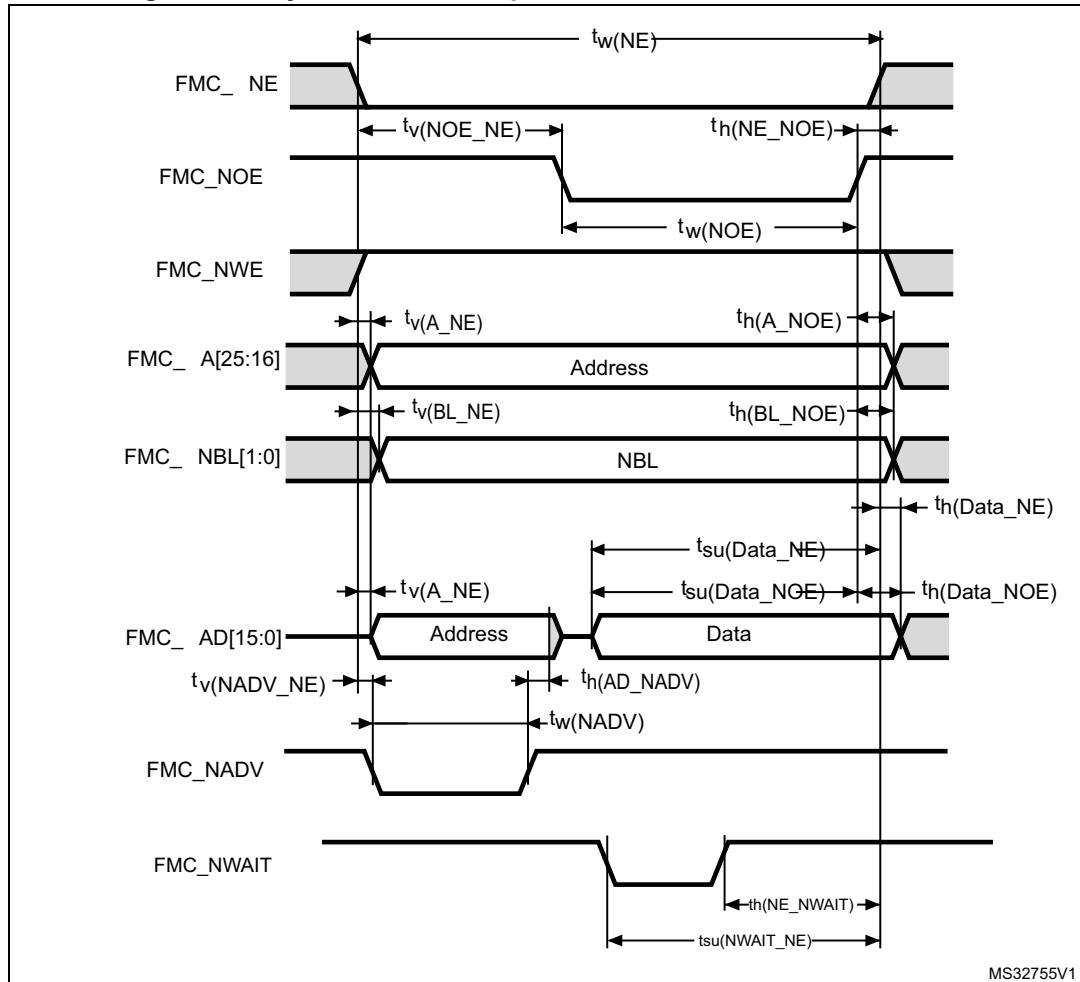


Table 69. Asynchronous multiplexed PSRAM/NOR read timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$4T_{fmc_ker_ck} - 1$	$4T_{fmc_ker_ck} + 1$	ns
$t_{v(NOE_NE)}$	FMC_NEx low to FMC_NOE low	$2T_{fmc_ker_ck}$	$2T_{fmc_ker_ck} + 0.5$	
$t_{tw(NOE)}$	FMC_NOE low time	$T_{fmc_ker_ck} - 1$	$T_{fmc_ker_ck} + 1$	
$t_{h(NE_NOE)}$	FMC_NOE high to FMC_NE high hold time	0	-	
$t_{v(A_NE)}$	FMC_NEx low to FMC_A valid	-	0.5	
$t_{v(NADV_NE)}$	FMC_NEx low to FMC_NADV low	0	0.5	
$t_{w(NADV)}$	FMC_NADV low time	$T_{fmc_ker_ck} - 0.5$	$T_{fmc_ker_ck} + 1$	
$t_{h(AD_NADV)}$	FMC_AD(address) valid hold time after FMC_NADV high)	$T_{fmc_ker_ck} + 0.5$	-	
$t_{h(A_NOE)}$	Address hold time after FMC_NOE high	$T_{fmc_ker_ck} - 0.5$	-	
$t_{su(Data_NE)}$	Data to FMC_NEx high setup time	11	-	
$t_{su(Data_NOE)}$	Data to FMC_NOE high setup time	11	-	
$t_{h(Data_NE)}$	Data hold time after FMC_NEx high	0	-	
$t_{h(Data_NOE)}$	Data hold time after FMC_NOE high	0	-	

1. Guaranteed by characterization results.

Table 70. Asynchronous multiplexed PSRAM/NOR read-NWAIT timings⁽¹⁾⁽²⁾

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$8T_{fmc_ker_ck} - 1$	$8T_{fmc_ker_ck}$	ns
$t_{w(NOE)}$	FMC_NWE low time	$5T_{fmc_ker_ck} - 1.5$	$5T_{fmc_ker_ck} + 0.5$	
$t_{su(NWAIT_NE)}$	FMC_NWAIT valid before FMC_NEx high	$4T_{fmc_ker_ck} + 11$	-	
$t_{h(NE_NWAIT)}$	FMC_NEx hold time after FMC_NWAIT invalid	$3T_{fmc_ker_ck} + 11.5$	-	

1. Guaranteed by characterization results.

2. N_WAIT pulse width is equal to 1 AHB cycle.

Table 71. Asynchronous multiplexed PSRAM/NOR write timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(NE)$	FMC_NE low time	$4T_{fmc_ker_ck} - 1$	$4T_{fmc_ker_ck}$	ns
$t_v(NWE_NE)$	FMC_NEx low to FMC_NWE low	$T_{fmc_ker_ck} - 1$	$T_{fmc_ker_ck} + 0.5$	
$t_w(NWE)$	FMC_NWE low time	$2T_{fmc_ker_ck} - 0.5$	$2T_{fmc_ker_ck} + 0.5$	
$t_h(NE_NWE)$	FMC_NWE high to FMC_NE high hold time	$T_{fmc_ker_ck} - 0.5$	-	
$t_v(A_NE)$	FMC_NEx low to FMC_A valid	-	0	
$t_v(NADV_NE)$	FMC_NEx low to FMC_NADV low	0	0.5	
$t_w(NADV)$	FMC_NADV low time	$T_{fmc_ker_ck}$	$T_{fmc_ker_ck} + 1$	
$t_h(AD_NADV)$	FMC_AD(address) valid hold time after FMC_NADV high	$T_{fmc_ker_ck} + 0.5$	-	
$t_h(A_NWE)$	Address hold time after FMC_NWE high	$T_{fmc_ker_ck} + 0.5$	-	
$t_h(BL_NWE)$	FMC_BL hold time after FMC_NWE high	$T_{fmc_ker_ck} - 0.5$	-	
$t_v(BL_NE)$	FMC_NEx low to FMC_BL valid	-	0.5	
$t_v(Data_NADV)$	FMC_NADV high to Data valid	-	$T_{fmc_ker_ck} + 2$	
$t_h(Data_NWE)$	Data hold time after FMC_NWE high	$T_{fmc_ker_ck} + 0.5$	-	

1. Guaranteed by characterization results.

Table 72. Asynchronous multiplexed PSRAM/NOR write-NWAIT timings⁽¹⁾⁽²⁾

Symbol	Parameter	Min	Max	Unit
$t_w(NE)$	FMC_NE low time	$9T_{fmc_ker_ck} - 1$	$9T_{fmc_ker_ck}$	ns
$t_w(NWE)$	FMC_NWE low time	$7T_{fmc_ker_ck} - 0.5$	$7T_{fmc_ker_ck} + 0.5$	
$t_{su}(NWAIT_NE)$	FMC_NWAIT valid before FMC_NEx high	$5T_{fmc_ker_ck} + 11$	-	
$t_h(NE_NWAIT)$	FMC_NEx hold time after FMC_NWAIT invalid	$4T_{fmc_ker_ck} + 11.5$	-	

1. Guaranteed by characterization results.

2. N_{WAIT} pulse width is equal to 1 AHB cycle.

Synchronous waveforms and timings

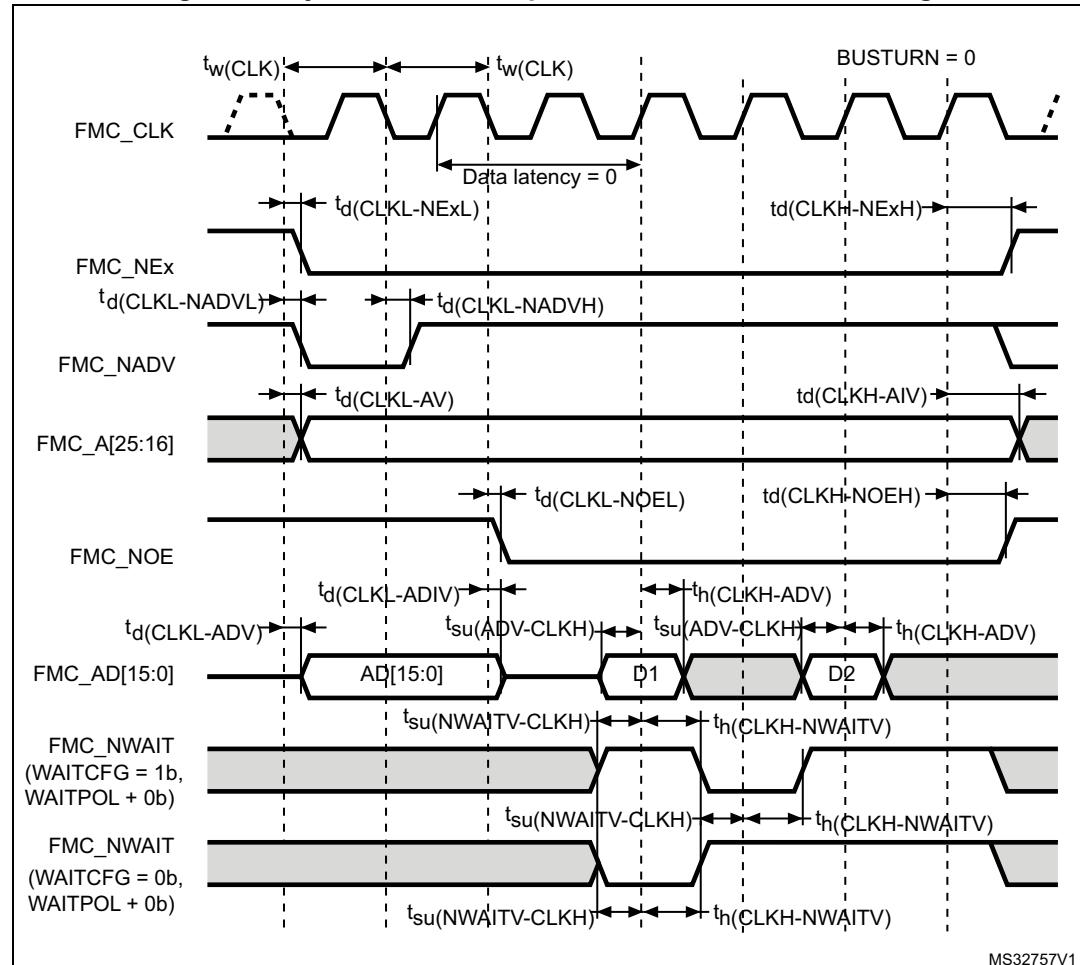
Figure 30 through *Figure 33* represent synchronous waveforms and *Table 73* through *Table 76* provide the corresponding timings. The results shown in these tables are obtained with the following FMC configuration:

- BurstAccessMode = FMC_BurstAccessMode_Enable
- MemoryType = FMC_MemoryType_CRAM
- WriteBurst = FMC_WriteBurst_Enable
- CLKDivision = 1
- DataLatency = 1 for NOR flash; DataLatency = 0 for PSRAM

In all the timing tables, the $T_{fmc_ker_ck}$ is the $f_{mc_ker_ck}$ clock period, with the following FMC_CLK maximum values:

- For $2.7 \text{ V} < V_{DD} < 3.6 \text{ V}$, FMC_CLK = 125 MHz at 20 pF
- For $1.8 \text{ V} < V_{DD} < 1.9 \text{ V}$, FMC_CLK = 100 MHz at 20 pF
- For $1.62 \text{ V} < V_{DD} < 1.8 \text{ V}$, FMC_CLK = 100 MHz at 15 pF

Figure 30. Synchronous multiplexed NOR/PSRAM read timings



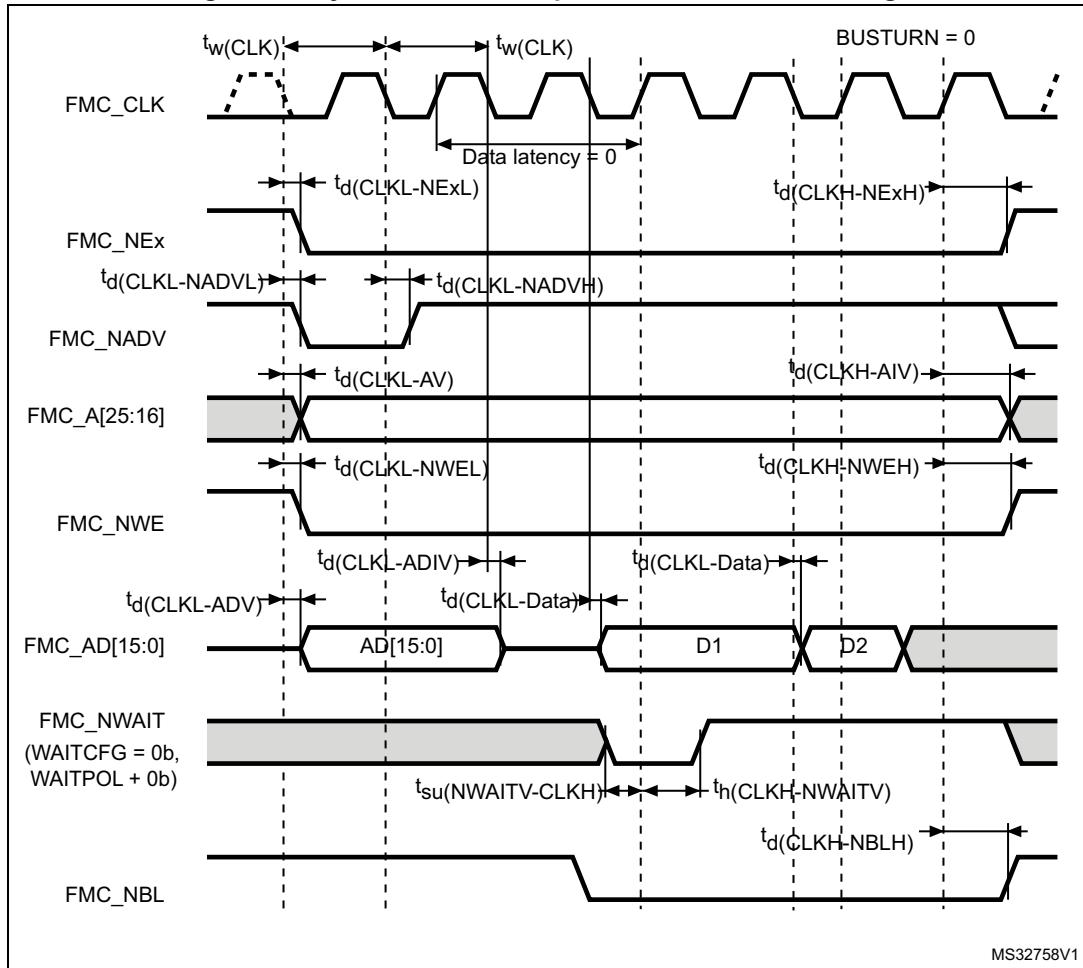
MS32757V1

Table 73. Synchronous multiplexed NOR/PSRAM read timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(CLK)$	FMC_CLK period	$2T_{fmc_ker_ck} - 1$	-	ns
$t_d(CLKL-NExL)$	FMC_CLK low to FMC_NEx low (x=0..2)	-	1	
$t_d(CLKH_NExH)$	FMC_CLK high to FMC_NEx high (x= 0...2)	$T_{fmc_ker_ck} + 0.5$	-	
$t_d(CLKL-NADVl)$	FMC_CLK low to FMC_NADV low	-	1	
$t_d(CLKL-NADVh)$	FMC_CLK low to FMC_NADV high	0	-	
$t_d(CLKL-AV)$	FMC_CLK low to FMC_Ax valid (x=16...25)	-	2.5	
$t_d(CLKH-AIV)$	FMC_CLK high to FMC_Ax invalid (x=16...25)	$T_{fmc_ker_ck}$	-	
$t_d(CLKL-NOEL)$	FMC_CLK low to FMC_NOE low	-	1.5	
$t_d(CLKH-NOEH)$	FMC_CLK high to FMC_NOE high	$T_{fmc_ker_ck} - 0.5$	-	
$t_d(CLKL-ADV)$	FMC_CLK low to FMC_AD[15:0] valid	-	3	
$t_d(CLKL-ADIV)$	FMC_CLK low to FMC_AD[15:0] invalid	0	-	
$t_{su}(ADV-CLKH)$	FMC_A/D[15:0] valid data before FMC_CLK high	3	-	
$t_h(CLKH-ADV)$	FMC_A/D[15:0] valid data after FMC_CLK high	0	-	
$t_{su}(NWAIT-CLKH)$	FMC_NWAIT valid before FMC_CLK high	3	-	
$t_h(CLKH-NWAIT)$	FMC_NWAIT valid after FMC_CLK high	1	-	

1. Guaranteed by characterization results.

Figure 31. Synchronous multiplexed PSRAM write timings



MS32758V1

Table 74. Synchronous multiplexed PSRAM write timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(\text{CLK})$	FMC_CLK period, $V_{DD} = 2.7$ to 3.6 V	$2T_{fmc_ker_ck} - 1$	-	Ns
$t_d(\text{CLKL-NExL})$	FMC_CLK low to FMC_NEx low ($x = 0..2$)	-	1	
$t_d(\text{CLKH-NExH})$	FMC_CLK high to FMC_NEx high ($x = 0..2$)	$T_{fmc_ker_ck} + 0.5$	-	
$t_d(\text{CLKL-NADVl})$	FMC_CLK low to FMC_NADV low	-	1.5	
$t_d(\text{CLKL-NADVh})$	FMC_CLK low to FMC_NADV high	0	-	
$t_d(\text{CLKL-AV})$	FMC_CLK low to FMC_Ax valid ($x = 16..25$)	-	2	
$t_d(\text{CLKH-AIV})$	FMC_CLK high to FMC_Ax invalid ($x = 16..25$)	$T_{fmc_ker_ck}$	-	
$t_d(\text{CLKL-NWEL})$	FMC_CLK low to FMC_NWE low	-	1.5	
$t_d(\text{CLKH-NWEH})$	FMC_CLK high to FMC_NWE high	$T_{fmc_ker_ck} + 0.5$	-	
$t_d(\text{CLKL-ADV})$	FMC_CLK low to FMC_AD[15:0] valid	-	2.5	
$t_d(\text{CLKL-ADIV})$	FMC_CLK low to FMC_AD[15:0] invalid	0	-	
$t_d(\text{CLKL-DATA})$	FMC_A/D[15:0] valid data after FMC_CLK low	-	2.5	
$t_d(\text{CLKL-NBLL})$	FMC_CLK low to FMC_NBL low	-	2	
$t_d(\text{CLKH-NBLH})$	FMC_CLK high to FMC_NBL high	$T_{fmc_ker_ck} + 0.5$	-	
$t_{su}(\text{NWAIT-CLKH})$	FMC_NWAIT valid before FMC_CLK high	2	-	
$t_h(\text{CLKH-NWAIT})$	FMC_NWAIT valid after FMC_CLK high	2	-	

1. Guaranteed by characterization results.

Figure 32. Synchronous non-multiplexed NOR/PSRAM read timings

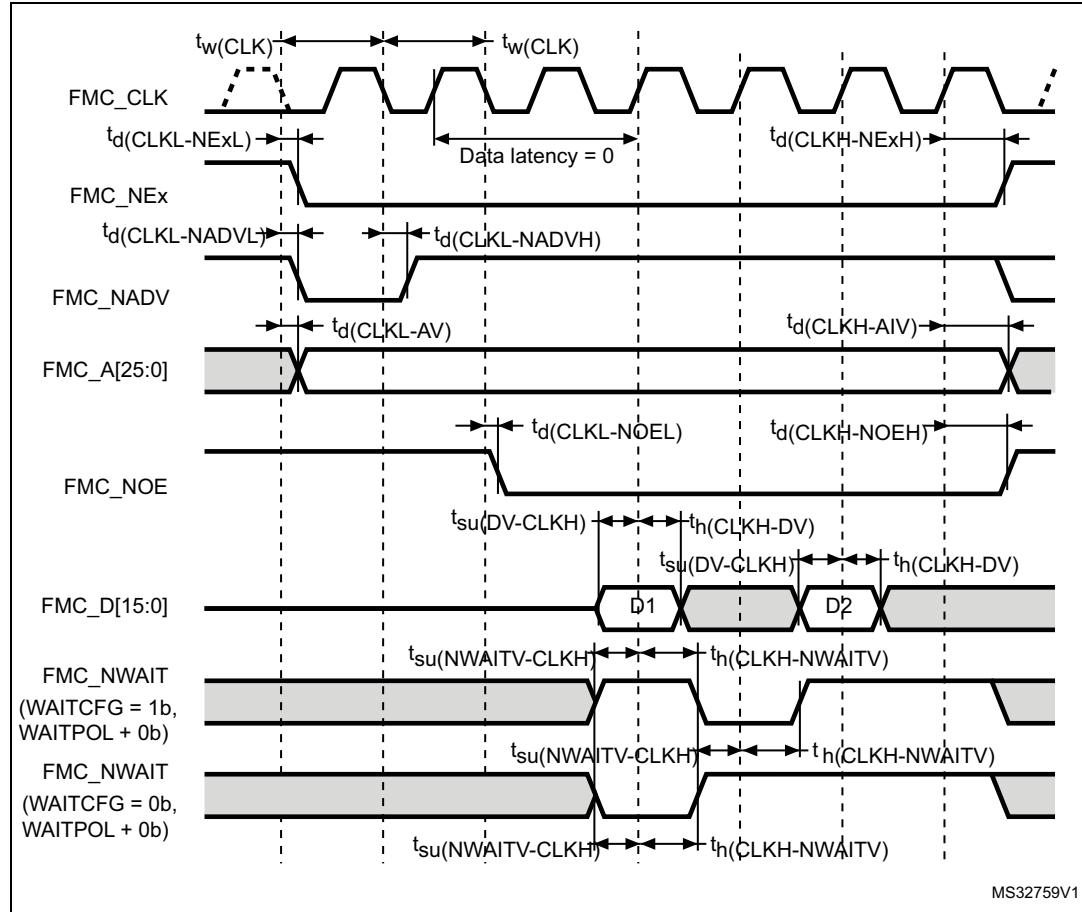
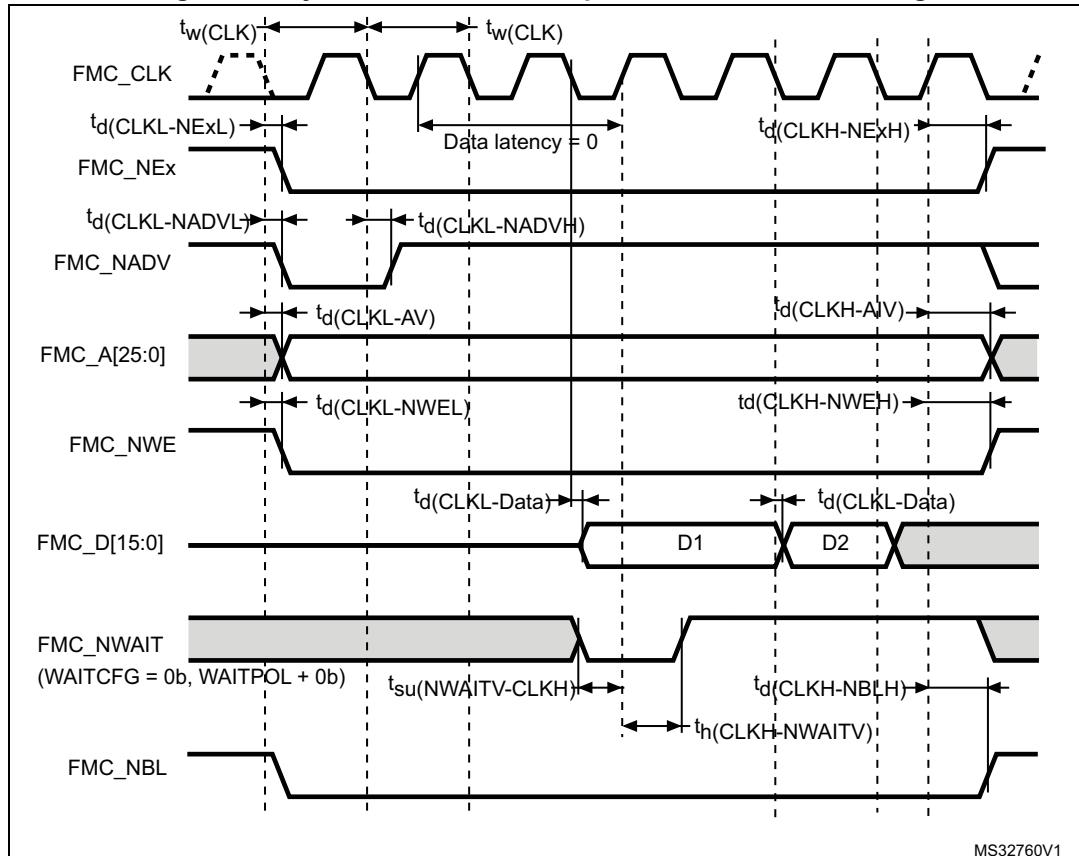


Table 75. Synchronous non-multiplexed NOR/PSRAM read timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(CLK)$	FMC_CLK period	$2T_{fmc_ker_ck}-1$	-	ns
$t_{(CLKL-NExL)}$	FMC_CLK low to FMC_NEx low (x=0..2)	-	1	
$t_d(CLKH-NExH)$	FMC_CLK high to FMC_NEx high (x= 0...2)	$2T_{fmc_ker_ck}+0.5$	-	
$t_d(CLKL-NADVl)$	FMC_CLK low to FMC_NADV low	-	0.5	
$t_d(CLKL-NADVh)$	FMC_CLK low to FMC_NADV high	0	-	
$t_d(CLKL-AV)$	FMC_CLK low to FMC_Ax valid (x=16...25)	-	2	
$t_d(CLKH-AIV)$	FMC_CLK high to FMC_Ax invalid (x=16...25)	$2T_{fmc_ker_ck}$	-	
$t_d(CLKL-NOEL)$	FMC_CLK low to FMC_NOE low	-	1.5	
$t_d(CLKH-NOEH)$	FMC_CLK high to FMC_NOE high	$2T_{fmc_ker_ck}-0.5$	-	
$t_{su}(DV-CLKH)$	FMC_D[15:0] valid data before FMC_CLK high	3	-	
$t_h(CLKH-DV)$	FMC_D[15:0] valid data after FMC_CLK high	0	-	
$t_{su}(NWAIT-CLKH)$	FMC_NWAIT valid before FMC_CLK high	3	-	
$t_h(CLKH-NWAIT)$	FMC_NWAIT valid after FMC_CLK high	1	-	

1. Guaranteed by characterization results.

Figure 33. Synchronous non-multiplexed PSRAM write timings



MS32760V1

Table 76. Synchronous non-multiplexed PSRAM write timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_{(CLK)}$	FMC_CLK period	$2T_{fmc_ker_ck} - 1$	-	ns
$t_{d(CLKL-NExL)}$	FMC_CLK low to FMC_NEx low (x=0..2)	-	2	
$t_{(CLKH-NExH)}$	FMC_CLK high to FMC_NEx high (x= 0...2)	$T_{fmc_ker_ck} + 0.5$	-	
$t_{d(CLKL-NADVl)}$	FMC_CLK low to FMC_NADV low	-	0.5	
$t_{d(CLKL-NADVh)}$	FMC_CLK low to FMC_NADV high	0	-	
$t_{d(CLKL-AV)}$	FMC_CLK low to FMC_Ax valid (x=16...25)	-	2.	
$t_{d(CLKH-AIV)}$	FMC_CLK high to FMC_Ax invalid (x=16...25)	$T_{fmc_ker_ck}$	-	
$t_{d(CLKL-NWEL)}$	FMC_CLK low to FMC_NWE low	-	1.5	
$t_{d(CLKH-NWEH)}$	FMC_CLK high to FMC_NWE high	$T_{fmc_ker_ck} + 1$	-	
$t_{d(CLKL-Data)}$	FMC_D[15:0] valid data after FMC_CLK low	-	3.5	
$t_{d(CLKL-NBLL)}$	FMC_CLK low to FMC_NBL low	-	2	
$t_{d(CLKH-NBLH)}$	FMC_CLK high to FMC_NBL high	$T_{fmc_ker_ck} + 1$	-	
$t_{su(NWAIT-CLKH)}$	FMC_NWAIT valid before FMC_CLK high	2	-	
$t_h(CLKH-NWAIT)$	FMC_NWAIT valid after FMC_CLK high	2	-	

1. Guaranteed by characterization results.

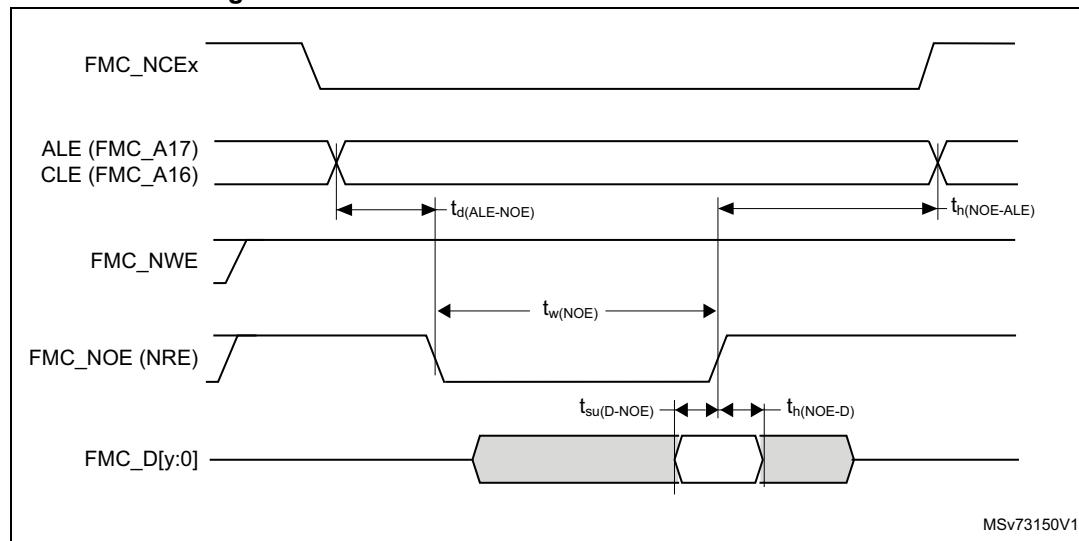
NAND controller waveforms and timings

[Figure 34](#) and [Figure 35](#) represent synchronous waveforms, and [Table 77](#) and [Table 78](#) provide the corresponding timings. The results shown in this table are obtained with the following FMC configuration:

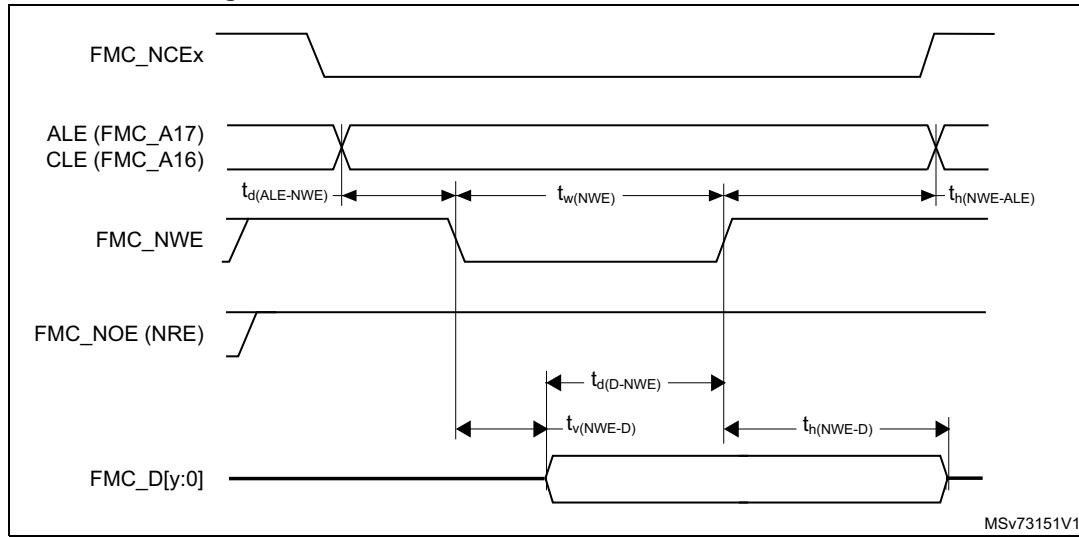
- COM.FMC_SetupTime = 0x01
- COM.FMC_WaitSetupTime = 0x03
- COM.FMC_HoldSetupTime = 0x02
- COM.FMC_HiZSetupTime = 0x01
- ATT.FMC_SetupTime = 0x01
- ATT.FMC_WaitSetupTime = 0x03
- ATT.FMC_HoldSetupTime = 0x02
- ATT.FMC_HiZSetupTime = 0x01
- Bank = FMC_Bank_NAND
- MemoryDataWidth = FMC_MemoryDataWidth_16b
- ECC = FMC_ECC_Enable
- ECCPageSize = FMC_ECCPageSize_512Bytes
- TCLRSetupTime = 0
- TARSetupTime = 0
- Capacitive load C_L = 30 pF

In all timing tables, the $T_{fmc_ker_ck}$ is the fmc_ker_ck clock period.

Figure 34. NAND controller waveforms for read access



1. $y = 7$ or 15 , depending on the NAND flash memory interface.

Figure 35. NAND controller waveforms for write access

1. $y = 7$ or 15 , depending on the NAND flash memory interface.

Table 77. Switching characteristics for NAND flash read cycles⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(\text{NOE})$	FMC_NOE low width	$4T_{\text{fmc_ker_ck}} - 0.5$	$4T_{\text{fmc_ker_ck}} + 0.5$	ns
$t_{su}(\text{D-NOE})$	FMC_D[15-0] valid data before FMC_NOE high	8	-	
$t_h(\text{NOE-D})$	FMC_D[15-0] valid data after FMC_NOE high	0	-	
$t_d(\text{ALE-NOE})$	FMC_ALE valid before FMC_NOE low	-	$3T_{\text{fmc_ker_ck}} + 1$	
$t_h(\text{NOE-ALE})$	FMC_NWE high to FMC_ALE invalid	$4T_{\text{fmc_ker_ck}} - 2$	-	

1. Guaranteed by characterization results.

Table 78. Switching characteristics for NAND flash write cycles⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(\text{NWE})$	FMC_NWE low width	$4T_{\text{fmc_ker_ck}} - 0.5$	$4T_{\text{fmc_ker_ck}} + 0.5$	ns
$t_v(\text{NWE-D})$	FMC_NWE low to FMC_D[15-0] valid	0	-	
$t_h(\text{NWE-D})$	FMC_NWE high to FMC_D[15-0] invalid	$2T_{\text{fmc_ker_ck}} - 0.5$	-	
$t_d(\text{D-NWE})$	FMC_D[15-0] valid before FMC_NWE high	$5T_{\text{fmc_ker_ck}} - 1$	-	
$t_d(\text{ALE-NWE})$	FMC_ALE valid before FMC_NWE low	-	$3T_{\text{fmc_ker_ck}} + 0.5$	
$t_h(\text{NWE-ALE})$	FMC_NWE high to FMC_ALE invalid	$2T_{\text{fmc_ker_ck}} - 1$	-	

1. Guaranteed by characterization results.

SDRAM waveforms and timings

In all timing tables, the TKERCK is the fmc_ker_ck clock period, with the following FMC_SDCLK maximum values:

- For $2.7 \text{ V} < V_{DD} < 3.6 \text{ V}$: FMC_SDCLK = 110 MHz at 20 pF
- For $1.8 \text{ V} < V_{DD} < 1.9 \text{ V}$: FMC_SDCLK = 100 MHz at 20 pF
- For $1.62 \text{ V} < V_{DD} < 1.8 \text{ V}$, FMC_SDCLK = 100 MHz at 15 pF

Figure 36. SDRAM read access waveforms (CL = 1)

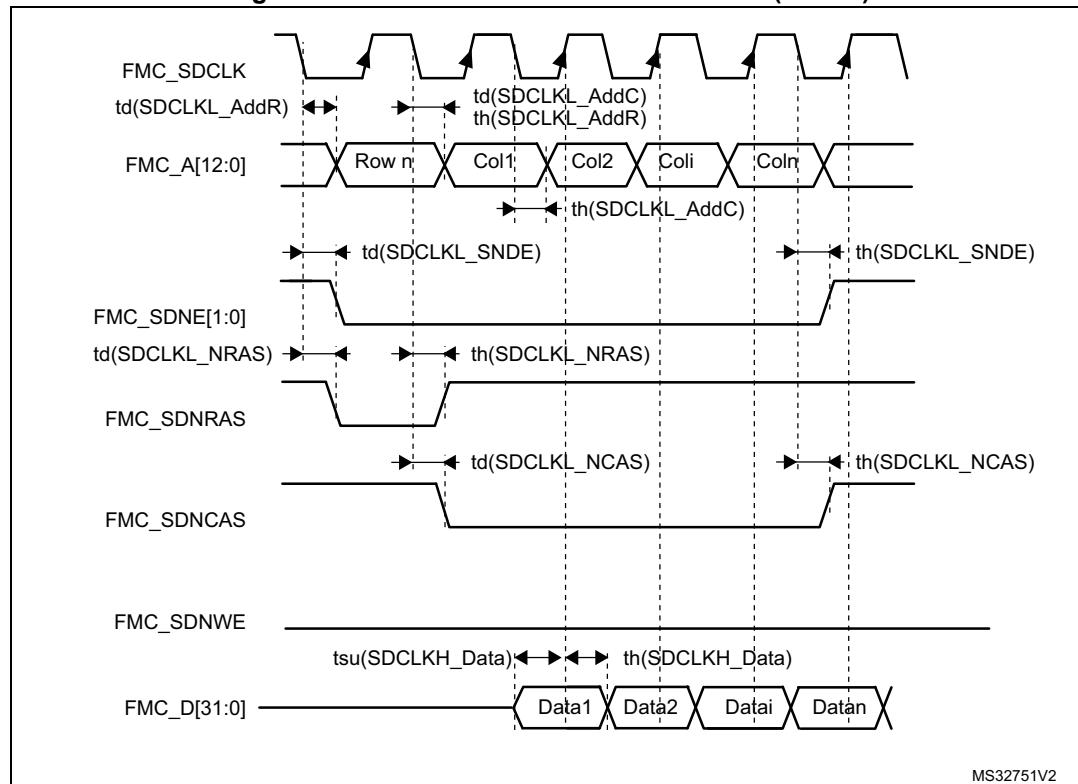


Table 79. SDRAM read timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(SDCLK)$	FMC_SDCLK period	$2T_{fmc_ker_ck} - 1$	$2T_{fmc_ker_ck} + 0.5$	ns
$t_{su}(SDCLKH_Data)$	Data input setup time	3	-	
$t_h(SDCLKH_Data)$	Data input hold time	0	-	
$t_d(SDCLKL_Add)$	Address valid time	-	1.5	
$t_d(SDCLKL_SDNE)$	Chip select valid time	-	1.5	
$t_h(SDCLKL_SDNE)$	Chip select hold time	0.5	-	
$t_d(SDCLKL_SDNRAS)$	SDNRAS valid time	-	1	
$t_h(SDCLKL_SDNRAS)$	SDNRAS hold time	0.5	-	
$t_d(SDCLKL_SDNCAS)$	SDNCAS valid time	-	0.5	
$t_h(SDCLKL_SDNCAS)$	SDNCAS hold time	0	-	

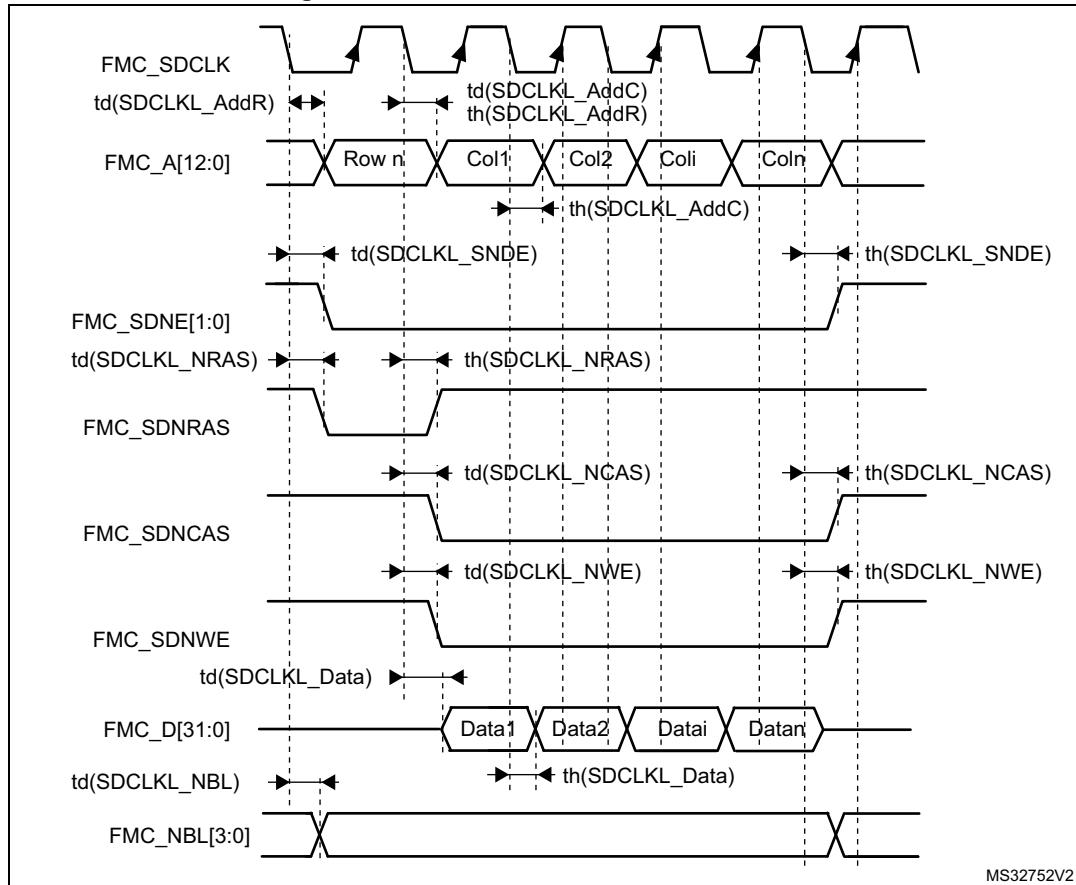
1. Guaranteed by characterization results.

Table 80. LPSDR SDRAM read timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(SDCLK)$	FMC_SDCLK period	$2T_{fmc_ker_ck} - 1$	$2T_{fmc_ker_ck} + 0.5$	ns
$t_{su}(SDCLKH_Data)$	Data input setup time	3	-	
$t_h(SDCLKH_Data)$	Data input hold time	0.5	-	
$t_d(SDCLKL_Add)$	Address valid time	-	2.5	
$t_d(SDCLKL_SDNE)$	Chip select valid time	-	2.5	
$t_h(SDCLKL_SDNE)$	Chip select hold time	0	-	
$t_d(SDCLKL_SDNRAS)$	SDNRAS valid time	-	0.5	
$t_h(SDCLKL_SDNRAS)$	SDNRAS hold time	0	-	
$t_d(SDCLKL_SDNCAS)$	SDNCAS valid time	-	1.5	
$t_h(SDCLKL_SDNCAS)$	SDNCAS hold time	0	-	

1. Guaranteed by characterization results.

Figure 37. SDRAM write access waveforms

Table 81. SDRAM Write timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(\text{SDCLK})$	FMC_SDCLK period	$2T_{\text{fmc_ker_ck}} - 1$	$2T_{\text{fmc_ker_ck}} + 0.5$	ns
$t_d(\text{SDCLKL_Data})$	Data output valid time	-	1	
$t_h(\text{SDCLKL_Data})$	Data output hold time	0	-	
$t_d(\text{SDCLKL_Add})$	Address valid time	-	1.5	
$t_d(\text{SDCLKL_SDNWE})$	SDNWE valid time	-	1.5	
$t_h(\text{SDCLKL_SDNWE})$	SDNWE hold time	0.5	-	
$t_d(\text{SDCLKL_SDNE})$	Chip select valid time	-	1.5	
$t_h(\text{SDCLKL_SDNE})$	Chip select hold time	0.5	-	
$t_d(\text{SDCLKL_SDNRAS})$	SDNRAS valid time	-	1	
$t_h(\text{SDCLKL_SDNRAS})$	SDNRAS hold time	0.5	-	
$t_d(\text{SDCLKL_SDNCAS})$	SDNCAS valid time	-	1	
$t_d(\text{SDCLKL_SDNCAS})$	SDNCAS hold time	0.5	-	

1. Guaranteed by characterization results.

Table 82. LPSDR SDRAM Write timings⁽¹⁾

Symbol	Parameter	Min	Max	Unit
$t_w(\text{SDCLK})$	FMC_SDCLK period	$2T_{\text{fmc_ker_ck}} - 1$	$2T_{\text{fmc_ker_ck}} + 0.5$	ns
$t_d(\text{SDCLKL_Data})$	Data output valid time	-	2.5	
$t_h(\text{SDCLKL_Data})$	Data output hold time	0	-	
$t_d(\text{SDCLKL_Add})$	Address valid time	-	2.5	
$t_d(\text{SDCLKL-SDNWE})$	SDNWE valid time	-	2.5	
$t_h(\text{SDCLKL-SDNWE})$	SDNWE hold time	0	-	
$t_d(\text{SDCLKL- SDNE})$	Chip select valid time	-	3	
$t_h(\text{SDCLKL- SDNE})$	Chip select hold time	0	-	
$t_d(\text{SDCLKL-SDNRAS})$	SDNRAS valid time	-	1.5	
$t_h(\text{SDCLKL-SDNRAS})$	SDNRAS hold time	0	-	
$t_d(\text{SDCLKL-SDNCAS})$	SDNCAS valid time	-	1.5	
$t_d(\text{SDCLKL-SDNCAS})$	SDNCAS hold time	0	-	

1. Guaranteed by characterization results.

6.3.19 Quad-SPI interface characteristics

Unless otherwise specified, the parameters given in [Table 83](#) and [Table 84](#) for QUADSPI are derived from tests performed under the ambient temperature, f_{AHB} frequency and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#), with the following configuration:

- Output speed is set to OSPEEDR[1:0] = 11
- Measurement points are done at CMOS levels: $0.5V_{\text{DD}}$
- IO Compensation cell activated.
- HSLV activated when $V_{\text{DD}} \leq 2.7$ V
- VOS level set to VOS1

Refer to [Section 6.3.16: I/O port characteristics](#) for more details on the input/output alternate function characteristics.

The following table summarizes the parameters measured in SDR mode.

Table 83. QUADSPI characteristics in SDR mode⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
F_{ck1}/T_{CK}	QUADSPI clock frequency	2.7 < V_{DD} < 3.6 V CL = 20 pF	-	-	133	MHz
		1.62 < V_{DD} < 3.6 V CL = 15 pF	-	-	100	
$t_{w(CKH)}$	QUADSPI clock high and low time Even division	PRESCALER[7:0] = n = 0,1,3,5...	$T_{CK}/2-0.5$	-	$T_{CK}/2$	ns
$t_{w(CKL)}$			$T_{CK}/2$	-	$T_{CK}/2+0.5$	
$t_{w(CKH)}$	QUADSPI clock high and low time Odd division	PRESCALER[7:0] = n = 2,4,6,8...	$(n/2)*T_{CK}/(n+1)-0.5$	-	$(n/2)*T_{CK}/(n+1)$	
$t_{w(CKL)}$			$(n/2+1)*T_{CK}/(n+1)$	-	$(n/2+1)*T_{CK}/(n+1)+0.5$	
$t_{s(IN)}$	Data input setup time	2.7 < V_{DD} < 3.6 V	2	-	-	
		1.62 < V_{DD} < 3.6 V	2	-	-	
$t_{h(IN)}$	Data input hold time	2.7 < V_{DD} < 3.6 V	1	-	-	
		1.62 < V_{DD} < 3.6 V	2.5	-	-	
$t_{v(OUT)}$	Data output valid time	-	-	1	2	
$t_{h(OUT)}$	Data output hold time	-	0	-	-	

1. Guaranteed by characterization results.

The following table summarizes the parameters measured in DDR mode.

Table 84. QUADSPI characteristics in DDR mode⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
F_{CK1}/T_{CK}	QUADSPI clock frequency	$2.7 < V_{DD} < 3.6 \text{ V}$ $CL = 20 \text{ pF}$	-	-	100	MHz
		$1.62 < V_{DD} < 3.6 \text{ V}$ $CL = 15 \text{ pF}$	-	-	100	
$t_w(CKH)$	QUADSPI clock high and low time Even division PRESCALER[7:0] = n = 0,1,3,5...		$T_{CK}/2 - 0.5$	-	$T_{CK}/2$	ns
$t_w(CKL)$			$T_{CK}/2$	-	$T_{CK}/2 + 0.5$	
$t_w(CKH)$	QUADSPI clock high and low time Odd division PRESCALER[7:0] = n = 2,4,6,8...		$(n/2)*T_{CK}/(n+1) - 0.5$	-	$(n/2)*T_{CK}/(n+1)$	
$t_w(CKL)$			$(n/2+1)*T_{CK}/(n+1)$	-	$(n/2+1)*T_{CK}/(n+1) + 0.5$	
$t_{sr(IN)}, t_{sf(IN)}$	Data input setup time	$2.7 < V_{DD} < 3.6 \text{ V}$	2.5	-	-	
		$1.62 < V_{DD} < 3.6 \text{ V}$	1.5	-	-	
$t_{hr(IN)}, t_{hf(IN)}$	Data input hold time	$2.7 < V_{DD} < 3.6 \text{ V}$	1	-	-	
		$1.62 < V_{DD} < 3.6 \text{ V}$	2.5	-	-	
$t_{vr(OUT)}, t_{vf(OUT)}$	Data output valid time	DHHC=0	-	5	6	
		DHHC=1 PRESCALER[7:0] = 1,2...	-	$T_{CK}/4 + 1$	$T_{CK}/4 + 2$	
$t_{hr(OUT)}, t_{hf(OUT)}$	Data output hold time	DHHC=0	3	-	-	
		DHHC=1 PRESCALER[7:0]=1,2...	$T_{CK}/4$	-	-	

1. Guaranteed by characterization results.

Figure 38. QUADSPI timing diagram - SDR mode

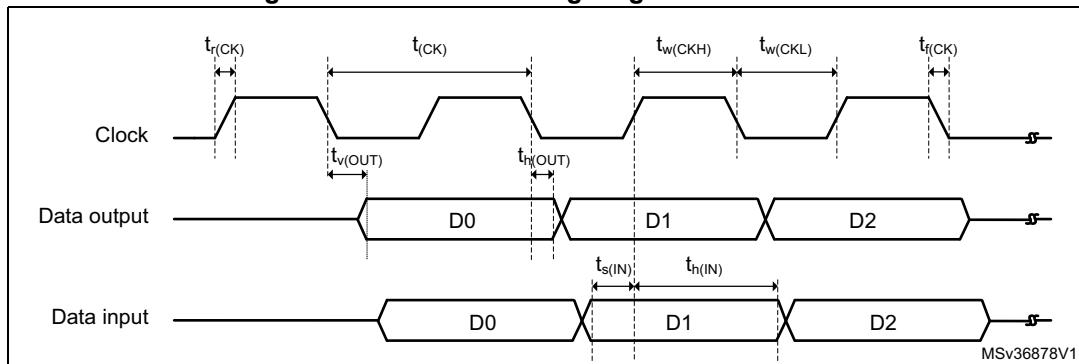
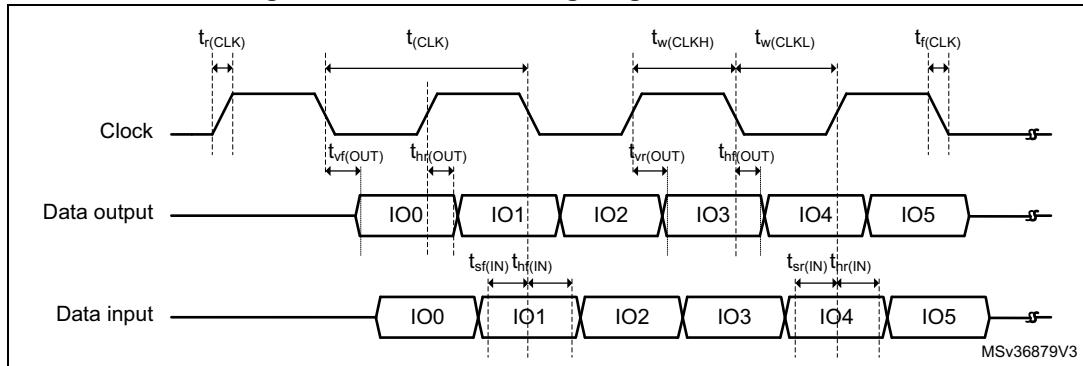


Figure 39. Quad-SPI timing diagram - DDR mode



6.3.20 Delay block (DLYB) characteristics

Unless otherwise specified, the parameters given in [Table 85](#) for Delay Block are derived from tests performed under the ambient temperature, $f_{\text{RCC_C_CK}}$ frequency and VDD supply voltage summarized in [Table 13: General operating conditions](#), with the following configuration:

Table 85. Delay Block characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t_{init}	Initial delay	-	1400	2200	2400	ps
t_{Δ}	Unit Delay	-	35	40	45	-

6.3.21 16-bit ADC characteristics

Unless otherwise specified, the parameters given in [Table 86](#) are derived from tests performed under the ambient temperature, f_{HCLK} frequency and V_{DDA} supply voltage conditions summarized in [Table 13: General operating conditions](#).

Table 86. ADC characteristics⁽¹⁾⁽²⁾⁽³⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Analog supply voltage for ADC ON	-	1.62	-	3.6	V
$V_{\text{REF}+}$	Positive reference voltage	-	1.62	-	V_{DDA}	V
$V_{\text{REF}-}$	Negative reference voltage	-			V_{SSA}	V
f_{ADC}	ADC clock frequency	$1.62 \text{ V} \leq V_{\text{DDA}} \leq 3.6 \text{ V}$	BOOST = 11	0.12	-	50
			BOOST = 10	0.12	-	25
			BOOST = 01	0.12	-	12.5
			BOOST = 00	-	-	6.25
						MHz

Table 86. ADC characteristics⁽¹⁾⁽²⁾⁽³⁾ (continued)

Symbol	Parameter	Conditions			Min	Typ	Max	Unit		
$f_s^{(4)}$	Sampling rate for Direct channels	Resolution = 16 bits, $V_{DDA} > 2.5 \text{ V}$	$T_J = 90 \text{ }^\circ\text{C}$	$f_{ADC} = 36 \text{ MHz}$	SMP = 1.5	-	-	3.60		
		Resolution = 16 bits		$f_{ADC} = 37 \text{ MHz}$	SMP = 2.5	-	-	3.35		
		Resolution = 14 bits	$T_J = 125 \text{ }^\circ\text{C}$	$f_{ADC} = 50 \text{ MHz}$	SMP = 2.5	-	-	5.00		
		Resolution = 12 bits		$f_{ADC} = 50 \text{ MHz}$	SMP = 2.5	-	-	5.50		
		Resolution = 10 bits		$f_{ADC} = 50 \text{ MHz}$	SMP = 1.5	-	-	7.10		
		Resolution = 8 bits		$f_{ADC} = 50 \text{ MHz}$	SMP = 1.5	-	-	8.30		
		Resolution = 14 bits	$T_J = 140 \text{ }^\circ\text{C}$	$f_{ADC} = 49 \text{ MHz}$	SMP = 2.5	-	-	4.90		
		Resolution = 12 bits		$f_{ADC} = 50 \text{ MHz}$	SMP = 2.5	-	-	5.50		
		Resolution = 10 bits		$f_{ADC} = 50 \text{ MHz}$	SMP = 1.5	-	-	6.70		
		Resolution = 8 bits		$f_{ADC} = 50 \text{ MHz}$	SMP = 1.5	-	-	8.30		
	Sampling rate for Fast channels	Resolution = 16 bits, $V_{DDA} > 2.5 \text{ V}$	$T_J = 90 \text{ }^\circ\text{C}$	$f_{ADC} = 32 \text{ MHz}$	SMP = 2.5	-	-	2.90		
		Resolution = 16 bits		$f_{ADC} = 31 \text{ MHz}$	SMP = 2.5	-	-	2.80		
		Resolution = 14 bits	$T_J = 125 \text{ }^\circ\text{C}$	$f_{ADC} = 33 \text{ MHz}$	SMP = 2.5	-	-	3.30		
		Resolution = 12 bits		$f_{ADC} = 39 \text{ MHz}$	SMP = 2.5	-	-	4.30		
		Resolution = 10 bits		$f_{ADC} = 48 \text{ MHz}$	SMP = 2.5	-	-	6.00		
		Resolution = 8 bits		$f_{ADC} = 50 \text{ MHz}$	SMP = 2.5	-	-	7.10		
		Resolution = 12 bits	$T_J = 140 \text{ }^\circ\text{C}$	$f_{ADC} = 37 \text{ MHz}$	SMP = 2.5	-	-	4.10		
		Resolution = 10 bits		$f_{ADC} = 46 \text{ MHz}$	SMP = 2.5	-	-	5.70		
		Resolution = 8 bits		$f_{ADC} = 50 \text{ MHz}$	SMP = 2.5	-	-	7.10		
	Sampling rate for Slow channels	Resolution = 16 bits	$T_J = 90 \text{ }^\circ\text{C}$	$f_{ADC} = 10 \text{ MHz}$	SMP = 1.5	-	-	1.00		
		resolution = 14 bits	$T_J = 125 \text{ }^\circ\text{C}$			-	-			
		resolution = 12 bits				-	-			
		resolution = 10 bits				-	-			
		resolution = 8 bits	$T_J = 140 \text{ }^\circ\text{C}$			-	-			
		resolution = 12 bits				-	-			
		resolution = 10 bits				-	-			
		resolution = 8 bits				-	-			
$V_{AIN}^{(5)}$	Conversion voltage range	-		-	-	0	-	V_{REF+} V		
V_{CMIV}	Common mode input voltage	-		-	-	$V_{REF}/2 - 10\%$	$V_{REF}/2$	$V_{REF}/2 + 10\%$ V		

Table 86. ADC characteristics⁽¹⁾⁽²⁾⁽³⁾ (continued)

Symbol	Parameter	Conditions			Min	Typ	Max	Unit
$R_{AIN}^{(6)}$	External input impedance	Resolution = 16 bits, $T_J = 140^\circ\text{C}$	-	-	-	-	50	Ω
		Resolution = 16 bits, $T_J = 125^\circ\text{C}$	-	-	-	-	170	
		Resolution = 14 bits, $T_J = 140^\circ\text{C}$	-	-	-	-	200	
		Resolution = 14 bits, $T_J = 125^\circ\text{C}$	-	-	-	-	435	
		Resolution = 12 bits, $T_J = 140^\circ\text{C}$	-	-	-	-	700	
		Resolution = 12 bits, $T_J = 125^\circ\text{C}$	-	-	-	-	1150	
		Resolution = 10 bits, $T_J = 140^\circ\text{C}$	-	-	-	-	3700	
		Resolution = 10 bits, $T_J = 125^\circ\text{C}$	-	-	-	-	5650	
		Resolution = 8 bits, $T_J = 140^\circ\text{C}$	-	-	-	-	18000	
		Resolution = 8 bits, $T_J = 125^\circ\text{C}$	-	-	-	-	26500	
C_{ADC}	Internal sample and hold capacitor	-	-	-	-	4	-	pF
$t_{ADCVREG_STUP}$	ADC LDO startup time	-	-	-	-	5	10	us
t_{STAB}	ADC Power-up time	LDO already started	-	-	1	-	-	conversion cycle
t_{CAL}	Offset and linearity calibration time	-	-	-	165010	-	-	1/f _{ADC}
t_{OFF_CAL}	Offset calibration time	-	-	-	1280	-	-	1/f _{ADC}
t_{LATR}	Trigger conversion latency regular and injected channels without conversion abort	CKMODE = 00	-	-	1.5	2	2.5	1/f _{ADC}
		CKMODE = 01	-	-	-	-	2.5	
		CKMODE = 10	-	-	-	-	2.5	
		CKMODE = 11	-	-	-	-	2.25	
$t_{LATRINJ}$	Trigger conversion latency regular injected channels aborting a regular conversion	CKMODE = 00	-	-	2.5	3	3.5	1/f _{ADC}
		CKMODE = 01	-	-	-	-	3.5	
		CKMODE = 10	-	-	-	-	3.5	
		CKMODE = 11	-	-	-	-	3.25	
t_S	Sampling time	-	-	-	1.5	-	810.5	1/f _{ADC}
t_{CONV}	Total conversion time (including sampling time)	Resolution = N bits	-	-	$t_S + 0.5 + N/2$	-	-	1/f _{ADC}
t_{TRIG}	External trigger period	Resolution = 16 bits	-	-	$t_{CONV} + [t_{LATR} \text{ or } t_{LATRINJ}]$	-	-	1/f _{ADC}

Table 86. ADC characteristics⁽¹⁾⁽²⁾⁽³⁾ (continued)

Symbol	Parameter	Conditions				Min	Typ	Max	Unit
I_{DDA_D} (ADC)	ADC consumption on V_{DDA} , BOOST=11, Differential mode	Resolution = 16 bits, $f_{ADC}=25$ MHz	-	-	-	1440	-	-	μA
		Resolution = 14 bits, $f_{ADC}=30$ MHz	-	-	-	1350	-	-	
		Resolution = 12 bits, $f_{ADC}=40$ MHz	-	-	-	990	-	-	
	ADC consumption on V_{DDA} , BOOST=10, Differential mode $f_{ADC}=25$ MHz	Resolution = 16 bits	-	-	-	1080	-	-	
		Resolution = 14 bits	-	-	-	810	-	-	
		Resolution = 12 bits	-	-	-	585	-	-	
	ADC consumption on V_{DDA} , BOOST=01, Differential mode $f_{ADC}=12.5$ MHz	Resolution = 16 bits	-	-	-	630	-	-	
		Resolution = 14 bits	-	-	-	432	-	-	
		Resolution = 12 bits	-	-	-	315	-	-	
	ADC consumption on V_{DDA} , BOOST=00, Differential mode $f_{ADC}=6.25$ MHz	Resolution = 16 bits	-	-	-	360	-	-	
		Resolution = 14 bits	-	-	-	270	-	-	
		Resolution = 12 bits	-	-	-	225	-	-	
I_{DDA_SE} (ADC)	ADC consumption on V_{DDA} , BOOST=11, Single-ended mode	Resolution = 16 bits, $f_{ADC}=25$ MHz	-	-	-	720	-	-	μA
		Resolution = 14 bits, $f_{ADC}=30$ MHz	-	-	-	675	-	-	
		Resolution = 12 bits, $f_{ADC}=40$ MHz	-	-	-	495	-	-	
	ADC consumption on V_{DDA} , BOOST=10, Single-ended mode $f_{ADC}=25$ MHz	Resolution = 16 bits	-	-	-	540	-	-	
		Resolution = 14 bits	-	-	-	405	-	-	
		Resolution = 12 bits	-	-	-	292.5	-	-	
	ADC consumption on V_{DDA} , BOOST=01, Single-ended mode $f_{ADC}=12.5$ MHz	Resolution = 16 bits	-	-	-	315	-	-	
		Resolution = 14 bits	-	-	-	216	-	-	
		Resolution = 12 bits	-	-	-	157.5	-	-	
	ADC consumption on V_{DDA} , BOOST=00, Single-ended mode $f_{ADC}=6.25$ MHz	Resolution = 16 bits	-	-	-	180	-	-	
		Resolution = 14 bits	-	-	-	135	-	-	
		Resolution = 12 bits	-	-	-	112.5	-	-	
I_{DD} (ADC)	ADC consumption on V_{DD}	$f_{ADC}=50$ MHz	-	-	-	400	-	-	μA
		$f_{ADC}=25$ MHz	-	-	-	220	-	-	
		$f_{ADC}=12.5$ MHz	-	-	-	180	-	-	
		$f_{ADC}=6.25$ MHz	-	-	-	120	-	-	
		$f_{ADC}=3.125$ MHz	-	-	-	80	-	-	

1. Guaranteed by design.
2. The voltage booster on ADC switches must be used for $V_{DDA} < 2.4$ V (embedded I/O switches).
3. All ADC power consumption values reported for the 14-bit and 12-bit resolutions correspond to the power-optimized mode. The values provided for the 16-bit resolution also apply to the 14-bit and 12-bit resolutions in standard mode.
4. These values are valid for UFBGA176+25 and one ADC. Refer to *Getting started with the STM32H7 Series MCU 16-bit ADC (AN5354)* for values of other packages and multiple ADCs operation.
5. Depending on the package, V_{REF+} can be internally connected to V_{DDA} and V_{REF-} to V_{SSA} .
6. The tolerance is 10 LSBs for 16-bit resolution, 4 LSBs for 14-bit resolution, and 2 LSBs for 12-bit, 10-bit and 8-bit resolutions.

Table 87. Minimum sampling time vs $R_{AIN}^{(1)(2)}$

Resolution	R_{AIN} (Ω)	Minimum sampling time (s)		
		Direct channels ⁽³⁾	Fast channels ⁽⁴⁾	Slow channels ⁽⁵⁾
16 bits	47	7.37E-08	1.14E-07	1.72E-07
14 bits	47	6.29E-08	9.74E-08	1.55E-07
	68	6.84E-08	1.02E-07	1.58E-07
	100	7.80E-08	1.12E-07	1.62E-07
	150	9.86E-08	1.32E-07	1.80E-07
	220	1.32E-07	1.61E-07	2.01E-07
12 bits	47	5.32E-08	8.00E-08	1.29E-07
	68	5.74E-08	8.50E-08	1.32E-07
	100	6.58E-08	9.31E-08	1.40E-07
	150	8.37E-08	1.10E-07	1.51E-07
	220	1.11E-07	1.34E-07	1.73E-07
	330	1.56E-07	1.78E-07	2.14E-07
	470	2.16E-07	2.39E-07	2.68E-07
	680	3.01E-07	3.29E-07	3.54E-07
10 bits	47	4.34E-08	6.51E-08	1.08E-07
	68	4.68E-08	6.89E-08	1.11E-07
	100	5.35E-08	7.55E-08	1.16E-07
	150	6.68E-08	8.77E-08	1.26E-07
	220	8.80E-08	1.08E-07	1.40E-07
	330	1.24E-07	1.43E-07	1.71E-07
	470	1.69E-07	1.89E-07	2.13E-07
	680	2.38E-07	2.60E-07	2.80E-07
	1000	3.45E-07	3.66E-07	3.84E-07
	1500	5.15E-07	5.35E-07	5.48E-07
	2200	7.42E-07	7.75E-07	7.78E-07
	3300	1.10E-06	1.14E-06	1.14E-06

Table 87. Minimum sampling time vs $R_{AIN}^{(1)(2)}$ (continued)

Resolution	R_{AIN} (Ω)	Minimum sampling time (s)		
		Direct channels ⁽³⁾	Fast channels ⁽⁴⁾	Slow channels ⁽⁵⁾
8 bits	47	3.32E-08	5.10E-08	8.61E-08
	68	3.59E-08	5.35E-08	8.83E-08
	100	4.10E-08	5.83E-08	9.22E-08
	150	5.06E-08	6.76E-08	9.95E-08
	220	6.61E-08	8.22E-08	1.11E-07
	330	9.17E-08	1.08E-07	1.32E-07
	470	1.24E-07	1.40E-07	1.63E-07
	680	1.74E-07	1.91E-07	2.12E-07
	1000	2.53E-07	2.70E-07	2.85E-07
	1500	3.73E-07	3.93E-07	4.05E-07
	2200	5.39E-07	5.67E-07	5.75E-07
	3300	8.02E-07	8.36E-07	8.38E-07
	4700	1.13E-06	1.18E-06	1.18E-06
	6800	1.62E-06	1.69E-06	1.68E-06
	10000	2.36E-06	2.47E-06	2.45E-06
	15000	3.50E-06	3.69E-06	3.65E-06

1. Guaranteed by design.
2. Data valid at up to 140 °C, with a 47 pF PCB capacitor, and $V_{DDA}=1.6$ V.
3. Direct channels are connected to analog I/Os (PA0_C, PA1_C, PC2_C and PC3_C) to optimize ADC performance.
4. Fast channels correspond to PF3, PF5, PF7, PF9, PA6, PC4, PB1, PF11 and PF13.
5. Slow channels correspond to all ADC inputs except for the Direct and Fast channels.

Table 88. ADC accuracy⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions ⁽³⁾		Min	Typ	Max	Unit
ET	Total undadjusted error	Direct channel	Single ended	-	+10/-20	-	LSB
			Differential	-	±15	-	
		Fast channel	Single ended	-	+10/-20	-	
			Differential	-	±15	-	
		Slow channel	Single ended	-	±10	-	
			Differential	-	±10	-	
EO	Offset error	-		-	±10	-	
EG	Gain error	-		-	±15	-	
ED	Differential linearity error	Single ended		-	+3/-1	-	
		Differential		-	+4.5/-1	-	
EL	Integral linearity error	Direct channel	Single ended	-	±11	-	Bits
			Differential	-	±7	-	
		Fast channel	Single ended	-	±13	-	
			Differential	-	±7	-	
		Slow channel	Single ended	-	±10	-	
			Differential	-	±6	-	
ENOB	Effective number of bits	Single ended		-	12.2	-	dB
		Differential		-	13.2	-	
SINAD	Signal-to-noise and distortion ratio	Single ended		-	75.2	-	
		Differential		-	81.2	-	
SNR	Signal-to-noise ratio	Single ended		-	77.0	-	
		Differential		-	81.0	-	
THD	Total harmonic distortion	Single ended		-	87	-	
		Differential		-	90	-	

1. Data guaranteed by characterization for BGA packages. The values for LQFP packages might differ.

2. ADC DC accuracy values are measured after internal calibration.

3. ADC clock frequency = 25 MHz, ADC resolution = 16 bits, $V_{DDA}=V_{REF+}=3.3$ V and BOOST=11.

Note: ADC accuracy vs. negative injection current: injecting a negative current on any analog input pins should be avoided as this significantly reduces the accuracy of the conversion being performed on another analog input. It is recommended to add a Schottky diode (pin to ground) to analog pins which may potentially inject negative currents.

Any positive injection current within the limits specified for $I_{INJ(PIN)}$ and $\sum I_{INJ(PIN)}$ in [Section 6.3.15](#) does not affect the ADC accuracy.

Figure 40. ADC accuracy characteristics

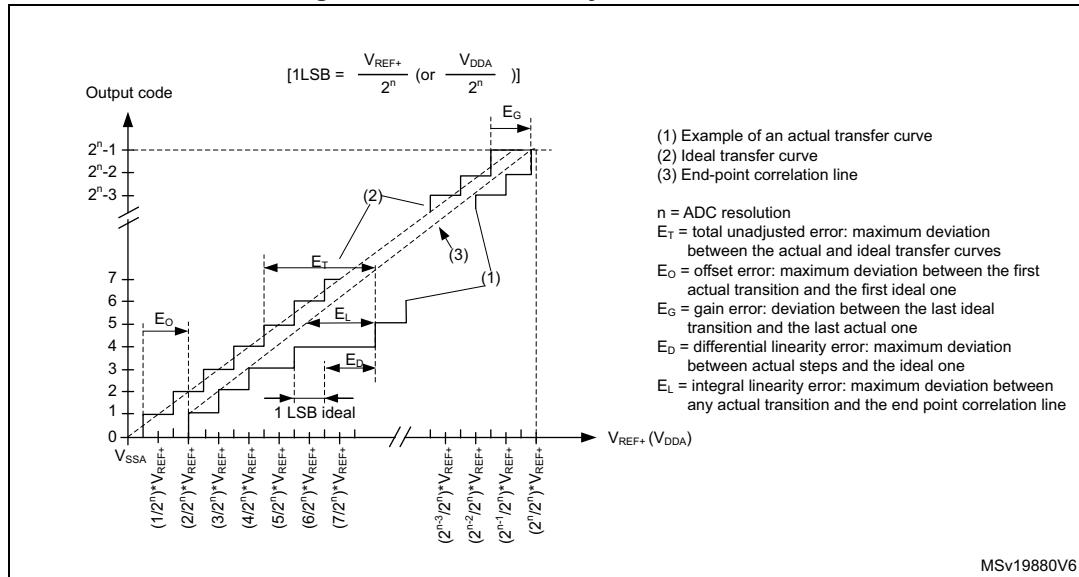
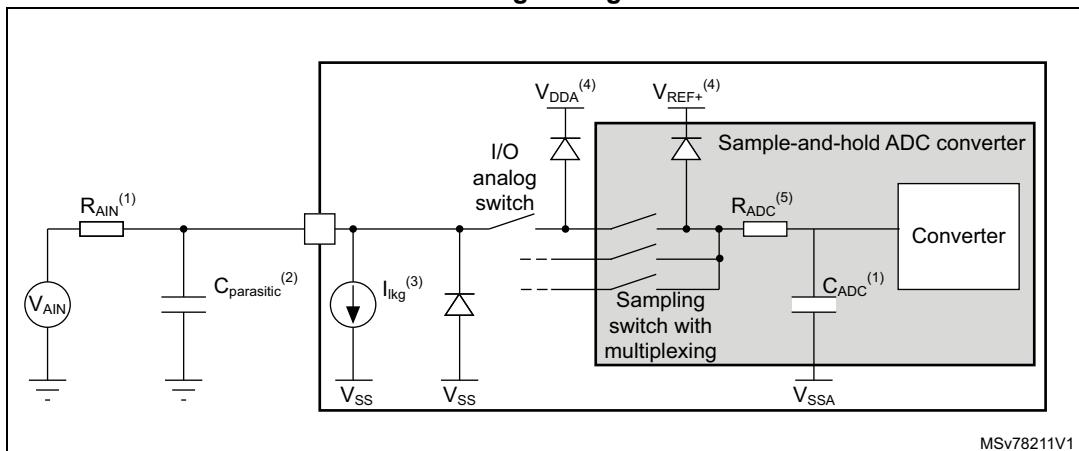


Figure 41. Typical connection diagram when using the ADC with FT/TT pins featuring analog switch function

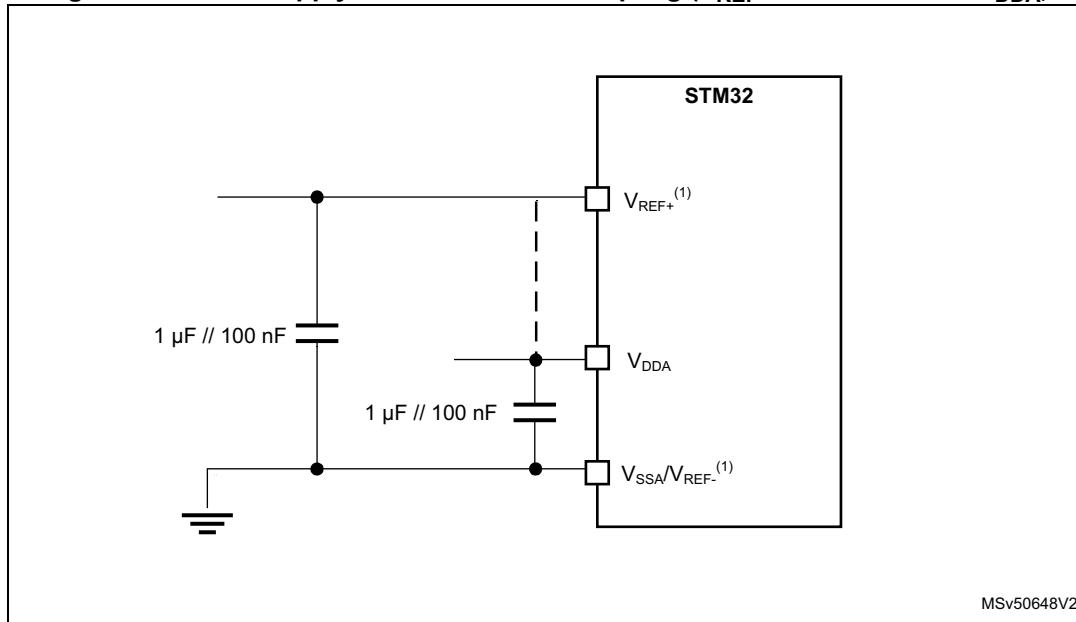


1. Refer to [Section 6.3.21: 16-bit ADC characteristics](#) for the values of R_{AIN} and C_{ADC} .
2. $C_{parasitic}$ represents the capacitance of the PCB (dependent on soldering and PCB layout quality) plus the pad capacitance (refer to [Table 59: I/O static characteristics](#) for the value of the pad capacitance). A high $C_{parasitic}$ value downgrades conversion accuracy. To remedy this, f_{ADC} should be reduced.
3. Refer to [Table 59: I/O static characteristics](#) for the value of I_{lkg} .
4. Refer to [Figure 13: Power supply scheme](#).
5. The R_{ADC} is used to compute the minimum sampling time, refer to [Table 87: Minimum sampling time vs \$R_{AIN}\$](#) .

General PCB design guidelines

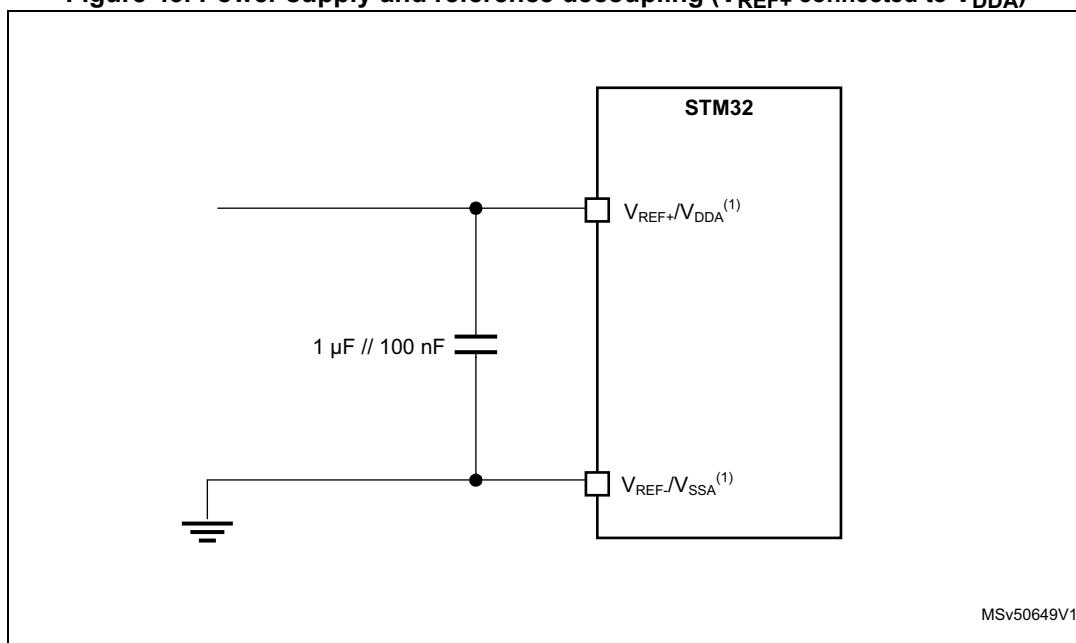
Power supply decoupling should be performed as shown in [Figure 42](#) or [Figure 43](#), depending on whether V_{REF+} is connected to V_{DDA} or not. The 100 nF capacitors should be ceramic (good quality). They should be placed them as close as possible to the chip.

Figure 42. Power supply and reference decoupling (V_{REF+} not connected to V_{DDA})



1. V_{REF+} input is available on all package whereas the V_{REF-} s available only on UFBGA176+25 and TFBGA240+25. When V_{REF-} is not available, it is internally connected to V_{DDA} and V_{SSA} .

Figure 43. Power supply and reference decoupling (V_{REF+} connected to V_{DDA})



1. V_{REF+} input is available on all package whereas the V_{REF-} s available only on UFBGA176+25 and TFBGA240+25. When V_{REF-} is not available, it is internally connected to V_{DDA} and V_{SSA} .

6.3.22 DAC characteristics

Table 89. DAC characteristics⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
V_{DDA}	Analog supply voltage	Positive reference voltage Negative reference voltage	-	1.8	3.3	3.6	V
V_{REF+}	Positive reference voltage		-	1.80	-	V_{DDA}	
V_{REF-}	Negative reference voltage		-	-	V_{SSA}	-	
R_L	Resistive Load	DAC output buffer ON	connected to V_{SSA}	5	-	-	kΩ
			connected to V_{DDA}	25	-	-	
R_O	Output Impedance	DAC output buffer OFF		10.3	13	16	
R_{BON}	Output impedance sample and hold mode, output buffer ON	DAC output buffer ON	$V_{DD} = 2.7\text{ V}$	-	-	1.6	kΩ
			$V_{DD} = 2.0\text{ V}$	-	-	2.6	
R_{BOFF}	Output impedance sample and hold mode, output buffer OFF	DAC output buffer OFF	$V_{DD} = 2.7\text{ V}$	-	-	17.8	kΩ
			$V_{DD} = 2.0\text{ V}$	-	-	18.7	
C_L	Capacitive Load	DAC output buffer OFF		-	-	50	pF
C_{SH}		Sample and Hold mode		-	0.1	1	μF
V_{DAC_OUT}	Voltage on DAC_OUT output	DAC output buffer ON		0.2	-	$V_{REF+} - 0.2$	V
		DAC output buffer OFF		0	-	V_{REF+}	
$t_{SETTLING}$	Settling time (full scale: for a 12-bit code transition between the lowest and the highest input codes when DAC_OUT reaches the final value of $\pm 0.5\text{ LSB}$, $\pm 1\text{ LSB}$, $\pm 2\text{ LSB}$, $\pm 4\text{ LSB}$, $\pm 8\text{ LSB}$)	Normal mode, DAC output buffer ON, $C_L \leq 50\text{ pF}$, $R_L \geq 5\text{ kΩ}$	$\pm 0.5\text{ LSB}$	-	2.05	-	μs
			$\pm 1\text{ LSB}$	-	1.97	-	
			$\pm 2\text{ LSB}$	-	1.67	-	
			$\pm 4\text{ LSB}$	-	1.66	-	
			$\pm 8\text{ LSB}$	-	1.65	-	
		Normal mode, DAC output buffer OFF, $\pm 1\text{ LSB}$ $C_L = 10\text{ pF}$		-	1.7	2	
$t_{WAKEUP}^{(3)}$	Wakeup time from off state (setting the ENx bit in the DAC Control register) until the final value of $\pm 1\text{ LSB}$ is reached	Normal mode, DAC output buffer ON, $C_L \leq 50\text{ pF}$, $R_L = 5\text{ kΩ}$	-	5	7.5	μs	
		Normal mode, DAC output buffer OFF, $C_L \leq 10\text{ pF}$	-	2	5		
PSRR	DC V_{DDA} supply rejection ratio	Normal mode, DAC output buffer ON, $C_L \leq 50\text{ pF}$, $R_L = 5\text{ kΩ}$	-	-80	-28	dB	

Table 89. DAC characteristics⁽¹⁾⁽²⁾ (continued)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
t_{SAMP}	Sampling time in Sample and Hold mode $C_L=100\text{ nF}$ (code transition between the lowest input code and the highest input code when DAC_OUT reaches the $\pm 1\text{LSB}$ final value)	MODE<2:0>_V12=100/101 (BUFFER ON)		-	0.7	2.6	ms
		MODE<2:0>_V12=110 (BUFFER OFF)		-	11.5	18.7	
		MODE<2:0>_V12=111 (INTERNAL BUFFER OFF)		-	0.3	0.6	μs
C_{int}	Internal sample and hold capacitor	-		1.8	2.2	2.6	pF
t_{TRIM}	Middle code offset trim time	Minimum time to verify the each code		50	-	-	μs
V_{offset}	Middle code offset for 1 trim code step	$V_{\text{REF}+}=3.6\text{ V}$		-	850	-	μV
		$V_{\text{REF}+}=1.8\text{ V}$		-	425	-	
$I_{\text{DDA(DAC)}}$	DAC quiescent consumption from V_{DDA}	DAC output buffer ON	No load, middle code (0x800)	-	360	-	μA
			No load, worst code (0xF1C)	-	490	-	
		DAC output buffer OFF	No load, middle/worst code (0x800)	-	20	-	
		Sample and Hold mode, $C_{\text{SH}}=100\text{ nF}$		-	$360 \cdot T_{\text{ON}} / (T_{\text{ON}} + T_{\text{OFF}})$ ⁽⁴⁾	-	
		DAC output buffer ON	No load, middle code (0x800)	-	170	-	
$I_{\text{DDV(DAC)}}$	DAC consumption from $V_{\text{REF}+}$		No load, worst code (0xF1C)	-	170	-	
	DAC output buffer OFF	No load, middle/worst code (0x800)	-	160	-		
	Sample and Hold mode, Buffer ON, $C_{\text{SH}}=100\text{ nF}$ (worst code)		-	$170 \cdot T_{\text{ON}} / (T_{\text{ON}} + T_{\text{OFF}})$ ⁽⁴⁾	-		
	Sample and Hold mode, Buffer OFF, $C_{\text{SH}}=100\text{ nF}$ (worst code)		-	$160 \cdot T_{\text{ON}} / (T_{\text{ON}} + T_{\text{OFF}})$ ⁽⁴⁾	-		

1. Guaranteed by design unless otherwise specified.

2. TBD stands for "to be defined".
3. In buffered mode, the output can overshoot above the final value for low input code (starting from the minimum value).
4. T_{ON} is the refresh phase duration, while T_{OFF} is the hold phase duration. Refer to the product reference manual for more details.

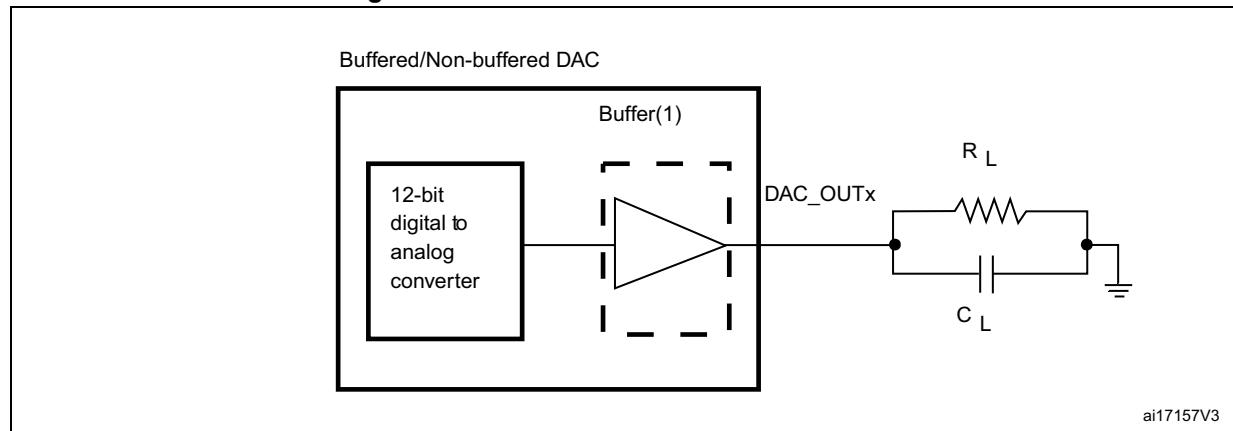
Table 90. DAC accuracy⁽¹⁾

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
DNL	Differential non linearity ⁽²⁾	DAC output buffer ON		-2	-	2	LSB
		DAC output buffer OFF		-2	-	2	
-	Monotonicity	10 bits		-	-	-	-
INL	Integral non linearity ⁽³⁾	DAC output buffer ON, $C_L \leq 50 \text{ pF}$, $R_L \geq 5 \text{ k}\Omega$		-4	-	4	LSB
		DAC output buffer OFF, $C_L \leq 50 \text{ pF}$, no R_L		-4	-	4	
Offset	Offset error at code 0x800 ⁽³⁾	DAC output buffer ON, $C_L \leq 50 \text{ pF}$, $R_L \geq 5 \text{ k}\Omega$	$V_{REF+} = 3.6 \text{ V}$	-	-	± 15	LSB
		$V_{REF+} = 1.8 \text{ V}$		-	-	± 30	
		DAC output buffer OFF, $C_L \leq 50 \text{ pF}$, no R_L		-	-	± 8	
Offset1	Offset error at code 0x001 ⁽⁴⁾	DAC output buffer OFF, $C_L \leq 50 \text{ pF}$, no R_L		-	-	± 5	LSB
OffsetCal	Offset error at code 0x800 after factory calibration	DAC output buffer ON, $C_L \leq 50 \text{ pF}$, $R_L \geq 5 \text{ k}\Omega$	$V_{REF+} = 3.6 \text{ V}$	-	-	± 6	LSB
		$V_{REF+} = 1.8 \text{ V}$		-	-	± 7	
Gain	Gain error ⁽⁵⁾	DAC output buffer ON, $C_L \leq 50 \text{ pF}$, $R_L \geq 5 \text{ k}\Omega$		-	-	± 1	%
		DAC output buffer OFF, $C_L \leq 50 \text{ pF}$, no R_L		-	-	± 1	
SNR	Signal-to-noise ratio ⁽⁶⁾	DAC output buffer ON, $C_L \leq 50 \text{ pF}$, $R_L \geq 5 \text{ k}\Omega$, 1 kHz, BW = 500 KHz		-	67.8	-	dB
		DAC output buffer OFF, $C_L \leq 50 \text{ pF}$, no R_L , 1 kHz, BW = 500 KHz		-	67.8	-	
THD	Total harmonic distortion ⁽⁶⁾	DAC output buffer ON, $C_L \leq 50 \text{ pF}$, $R_L \geq 5 \text{ k}\Omega$, 1 kHz		-	-78.6	-	dB
		DAC output buffer OFF, $C_L \leq 50 \text{ pF}$, no R_L , 1 kHz		-	-78.6	-	
SINAD	Signal-to-noise and distortion ratio ⁽⁶⁾	DAC output buffer ON, $C_L \leq 50 \text{ pF}$, $R_L \geq 5 \text{ k}\Omega$, 1 kHz		-	67.5	-	dB
		DAC output buffer OFF, $C_L \leq 50 \text{ pF}$, no R_L , 1 kHz		-	67.5	-	

Table 90. DAC accuracy⁽¹⁾ (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
ENOB	Effective number of bits	DAC output buffer ON, $C_L \leq 50 \text{ pF}$, $R_L \geq 5 \text{ k}\Omega$, 1 kHz	-	10.9	-	bits
		DAC output buffer OFF, $C_L \leq 50 \text{ pF}$, no R_L , 1 kHz	-	10.9	-	

1. Guaranteed by characterization.
2. Difference between two consecutive codes minus 1 LSB.
3. Difference between the value measured at Code i and the value measured at Code i on a line drawn between Code 0 and last Code 4095.
4. Difference between the value measured at Code (0x001) and the ideal value.
5. Difference between the ideal slope of the transfer function and the measured slope computed from code 0x000 and 0xFFFF when the buffer is OFF, and from code giving 0.2 V and ($V_{REF+} - 0.2 \text{ V}$) when the buffer is ON.
6. Signal is -0.5dBFS with $F_{sampling}=1 \text{ MHz}$.

Figure 44. 12-bit buffered /non-buffered DAC

1. The DAC integrates an output buffer that can be used to reduce the output impedance and to drive external loads directly without the use of an external operational amplifier. The buffer can be bypassed by configuring the BOFFx bit in the DAC_CR register.

6.3.23 Voltage reference buffer characteristics

Table 91. VREFBUF characteristics⁽¹⁾

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
V _{DDA}	Analog supply voltage	Normal mode	VSCALE = 000	2.8	3.3	3.6	V
			VSCALE = 001	2.4	-	3.6	
			VSCALE = 010	2.1	-	3.6	
			VSCALE = 011	1.8	-	3.6	
		Degraded mode	VSCALE = 000	1.62	-	2.80	
			VSCALE = 001	1.62	-	2.40	
			VSCALE = 010	1.62	-	2.10	
			VSCALE = 011	1.62	-	1.80	
V _{REFBUF_OUT}	Voltage Reference Buffer Output, at 30 °C, I _{load} = 100 µA	Normal mode	VSCALE = 000	2.498	2.5	2.5035	V
			VSCALE = 001	2.046	2.049	2.052	
			VSCALE = 010	1.801	1.804	1.806	
			VSCALE = 011	1.4995	1.5015	1.504	
		Degraded mode ⁽²⁾	VSCALE = 000	V _{DDA} - 150 mV	-	V _{DDA}	
			VSCALE = 001	V _{DDA} - 150 mV	-	V _{DDA}	
			VSCALE = 010	V _{DDA} - 150 mV	-	V _{DDA}	
			VSCALE = 011	V _{DDA} - 150 mV	-	V _{DDA}	
TRIM	Trim step resolution	-	-	-	±0.05	±0.1	%
C _L	Load capacitor	-	-	0.5	1	1.50	uF
esr	Equivalent Serial Resistor of C _L	-	-	-	-	2	Ω
I _{load}	Static load current	-	-	-	-	4	mA
I _{line_reg}	Line regulation	2.8 V ≤ V _{DDA} ≤ 3.6 V	I _{load} = 500 µA	-	200	-	ppm/V
			I _{load} = 4 mA	-	100	-	
I _{load_reg}	Load regulation	500 µA ≤ I _{LOAD} ≤ 4 mA	Normal Mode	-	50	-	ppm/mA
T _{coeff}	Temperature coefficient	-40 °C < T _J < +125 °C		-	-	T _{coeff} V _{REFINT} + 100	ppm/°C
PSRR	Power supply rejection	DC	-	-	60	-	dB
		100KHz	-	-	40	-	

Table 91. VREFBUF characteristics⁽¹⁾ (continued)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
t _{START}	Start-up time	C _L =0.5 µF	-	-	300	-	µs
		C _L =1 µF	-	-	500	-	
		C _L =1.5 µF	-	-	650	-	
I _{INRUSH}	Control of maximum DC current drive on V _{REFBUF_OUT} during startup phase ⁽³⁾	-		-	8	-	mA
I _{DDA(VREFBUF)}	VREFBUF consumption from V _{DDA}	I _{LOAD} = 0 µA	-	-	15	25	µA
		I _{LOAD} = 500 µA	-	-	16	30	
		I _{LOAD} = 4 mA	-	-	32	50	

1. Guaranteed by design.
2. In degraded mode, the voltage reference buffer cannot accurately maintain the output voltage (V_{DDA}—drop voltage).
3. To properly control VREFBUF I_{INRUSH} current during the startup phase and the change of scaling, V_{DDA} voltage should be in the range of 1.8 V-3.6 V, 2.1 V-3.6 V, 2.4 V-3.6 V and 2.8 V-3.6 V for VSCALE = 011, 010, 001 and 000, respectively.

6.3.24 Temperature sensor characteristics

Table 92. Temperature sensor characteristics

Symbol	Parameter	Min	Typ	Max	Unit
T _L ⁽¹⁾	V _{SENSE} linearity with temperature	-	-	±3	°C
Avg_Slope ⁽²⁾	Average slope	-	2	-	mV/°C
V ₃₀ ⁽³⁾	Voltage at 30°C ± 5 °C	-	0.62	-	V
t _{start_run}	Startup time in Run mode (buffer startup)	-	-	25.2	µs
t _{S_temp} ⁽¹⁾	ADC sampling time when reading the temperature	9	-	-	
I _{sens} ⁽¹⁾	Sensor consumption	-	0.18	0.31	
I _{sensbuf} ⁽¹⁾	Sensor buffer consumption	-	3.8	6.5	µA

1. Guaranteed by design.
2. Guaranteed by characterization.
3. Measured at V_{DDA} = V_{REF} = 3.3 V ± 10 mV. The V₃₀ ADC conversion result is stored in the TS_CAL1 byte.

Table 93. Temperature sensor calibration values

Symbol	Parameter	Memory address
TS_CAL1	Temperature sensor raw data acquired value at 30 °C, V _{DDA} = V _{REF} = 3.3 V	0x1FF1 E820 -0x1FF1 E821
TS_CAL2	Temperature sensor raw data acquired value at 130 °C, V _{DDA} = V _{REF} = 3.3 V	0x1FF1 E840 - 0x1FF1 E841

6.3.25 Temperature and V_{BAT} monitoring

Table 94. V_{BAT} monitoring characteristics

Symbol	Parameter	Min	Typ	Max	Unit
R	Resistor bridge for V _{BAT}	-	26	-	KΩ
Q	Ratio on V _{BAT} measurement	-	4	-	-
Er ⁽¹⁾	Error on Q	-10	-	+10	%
t _{S_vbat} ⁽¹⁾	ADC sampling time when reading V _{BAT} input	9	-	-	μs
V _{BATHigh}	High supply monitoring	-	3.55	-	V
V _{BATlow}	Low supply monitoring	-	1.36	-	

1. Guaranteed by design.

Table 95. V_{BAT} charging characteristics

Symbol	Parameter	Condition	Min	Typ	Max	Unit
R _{BC}	Battery charging resistor	VBRS in PWR_CR3=0	-	5	-	KΩ
		VBRS in PWR_CR3=1	-	1.5	-	

Table 96. Temperature monitoring characteristics

Symbol	Parameter	Min	Typ	Max	Unit
TEMP _{high}	High temperature monitoring	-	117	-	°C
		-	-25	-	

6.3.26 Voltage booster for analog switch

Table 97. Voltage booster for analog switch characteristics⁽¹⁾

Symbol	Parameter	Condition	Min	Typ	Max	Unit
V _{DD}	Supply voltage	-	1.62	2.6	3.6	V
t _{SU(BOOST)}	Booster startup time	-	-	-	50	μs
I _{DD(BOOST)}	Booster consumption	1.62 V ≤ V _{DD} ≤ 2.7 V		-	125	μA
		2.7 V < V _{DD} < 3.6 V		-	250	

1. Guaranteed by characterization results.

6.3.27 Comparator characteristics

Table 98. COMP characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	
V_{DDA}	Analog supply voltage	-	1.62	3.3	3.6	V	
V_{IN}	Comparator input voltage range	-	0	-	V_{DDA}		
V_{BG}	Scaler input voltage	-	(2)				
V_{SC}	Scaler offset voltage	-	-	± 5	± 10	mV	
$I_{DDA(SCALER)}$	Scaler static consumption from V_{DDA}	BRG_EN=0 (bridge disable)	-	0.2	0.3	μA	
		BRG_EN=1 (bridge enable)	-	0.8	1		
t_{START_SCALER}	Scaler startup time	-	-	140	250	μs	
t_{START}	Comparator startup time to reach propagation delay specification	High-speed mode	-	2	5	μs	
		Medium mode	-	5	20		
		Ultra-low-power mode	-	15	80		
$t_D^{(3)}$	Propagation delay for 200 mV step with 100 mV overdrive	High-speed mode	-	50	80	ns	
		Medium mode	-	0.5	1.2	μs	
		Ultra-low-power mode	-	2.5	7		
	Propagation delay for step > 200 mV with 100 mV overdrive only on positive inputs	High-speed mode	-	50	120	ns	
		Medium mode	-	0.5	1.2	μs	
		Ultra-low-power mode	-	2.5	7		
V_{offset}	Comparator offset error	Full common mode range	-	± 5	± 20	mV	
V_{hys}	Comparator hysteresis	No hysteresis	-	0	-	mV	
		Low hysteresis	5	10	22		
		Medium hysteresis	8	20	37		
		High hysteresis	16	30	52		
$I_{DDA(COMP)}$	Comparator consumption from V_{DDA}	Ultra-low-power mode	Static	-	400	600	nA
			With 50 kHz ± 100 mV overdrive square signal	-	800	-	
		Medium mode	Static	-	5	7	μA
			With 50 kHz ± 100 mV overdrive square signal	-	6	-	
		High-speed mode	Static	-	70	100	
			With 50 kHz ± 100 mV overdrive square signal	-	75	-	

1. Guaranteed by design, unless otherwise specified.

2. Refer to [Table 20: Embedded reference voltage](#).

3. Guaranteed by characterization results.

6.3.28 Operational amplifier characteristics

Table 99. Operational amplifier characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Analog supply voltage Range	-	2	3.3	3.6	V
CMIR	Common Mode Input Range	-	0	-	V_{DDA}	
VI_{OFFSET}	Input offset voltage	25°C, no load on output	-	-	±1.5	mV
		All voltages and temperature, no load	-	-	±2.5	
ΔVI_{OFFSET}	Input offset voltage drift	-	-	±3.0	-	µV/°C
TRIMOFFSETP TRIMLPOFFSETP	Offset trim step at low common input voltage (0.1* V_{DDA})	-	-	1.1	1.5	mV
TRIMOFFSETN TRIMLPOFFSETN	Offset trim step at high common input voltage (0.9* V_{DDA})	-	-	1.1	1.5	
I_{LOAD}	Drive current	-	-	-	500	µA
I_{LOAD_PGA}	Drive current in PGA mode	-	-	-	270	
C_{LOAD}	Capacitive load	-	-	-	50	pF
CMRR	Common mode rejection ratio	-	-	80	-	dB
PSRR	Power supply rejection ratio	$C_{LOAD} \leq 50\text{pf} / R_{LOAD} \geq 4 \text{ k}\Omega^{(1)}$ at 1 kHz, $V_{com}=V_{DDA}/2$	50	66	-	dB
GBW	Gain bandwidth for high supply range	200 mV ≤ Output dynamic range ≤ $V_{DDA} - 200$ mV	4	7.3	12.3	MHz
SR	Slew rate (from 10% and 90% of output voltage)	Normal mode	-	3	-	V/µs
		High-speed mode	-	30	-	
AO	Open loop gain	200 mV ≤ Output dynamic range ≤ $V_{DDA} - 200$ mV	59	90	129	dB
Φm	Phase margin	-	-	55	-	°
GM	Gain margin	-	-	12	-	dB
V_{OHSAT}	High saturation voltage	$I_{load}=\text{max or } R_{LOAD}=\text{min, Input at } V_{DDA}$	$V_{DDA} - 100$ mV	-	-	mV
V_{OLSAT}	Low saturation voltage	$I_{load}=\text{max or } R_{LOAD}=\text{min, Input at } 0 \text{ V}$	-	-	100	

Table 99. Operational amplifier characteristics (continued)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
t_{WAKEUP}	Wake up time from OFF state	Normal mode	$C_{LOAD} \leq 50\text{pf}$, $R_{LOAD} \geq 4\text{k}\Omega$, follower configuration	-	0.8	3.2	μs
		High speed mode	$C_{LOAD} \leq 50\text{pf}$, $R_{LOAD} \geq 4\text{k}\Omega$, follower configuration	-	0.9	2.8	
PGA gain	Non inverting gain error value	PGA gain = 2	-1	-	1	$\%$	
		PGA gain = 4	-2	-	2		
		PGA gain = 8	-2.5	-	2.5		
		PGA gain = 16	-3	-	3		
	Inverting gain error value	PGA gain = 2	-1	-	1		
		PGA gain = 4	-1	-	1		
		PGA gain = 8	-2	-	2		
		PGA gain = 16	-3	-	3		
	External non-inverting gain error value	PGA gain = 2	-1	-	1		
		PGA gain = 4	-3	-	3		
		PGA gain = 8	-3.5	-	3.5		
		PGA gain = 16	-4	-	4		
$R_{network}$	R2/R1 internal resistance values in non-inverting PGA mode ⁽²⁾	PGA Gain=2	-	10/10	-	$\text{k}\Omega/\text{k}\Omega$	
		PGA Gain=4	-	30/10	-		
		PGA Gain=8	-	70/10	-		
		PGA Gain=16	-	150/10	-		
	R2/R1 internal resistance values in inverting PGA mode ⁽²⁾	PGA Gain = -1	-	10/10	-		
		PGA Gain = -3	-	30/10	-		
		PGA Gain = -7	-	70/10	-		
		PGA Gain = -15	-	150/10	-		
Delta R	Resistance variation (R1 or R2)	-	-15	-	15	%	

Table 99. Operational amplifier characteristics (continued)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
PGA BW	PGA bandwidth for different non inverting gain	Gain=2	-	GBW/2	-	-	MHz
		Gain=4	-	GBW/4	-	-	
		Gain=8	-	GBW/8	-	-	
		Gain=16	-	GBW/16	-	-	
	PGA bandwidth for different inverting gain	Gain = -1	-	5.00	-	-	MHz
		Gain = -3	-	3.00	-	-	
		Gain = -7	-	1.50	-	-	
		Gain = -15	-	0.80	-	-	
en	Voltage noise density	at 1 KHz	output loaded with 4 kΩ	-	140	-	nV/√Hz
		at 10 KHz		-	55	-	
I _{DDA(OPAMP)}	OPAMP consumption from V _{DDA}	Normal mode	no Load, quiescent mode, follower	-	570	1000	μA
		High-speed mode		-	610	1200	

1. R_{LOAD} is the resistive load connected to VSSA or to VDDA.
2. R₂ is the internal resistance between the OPAMP output and the OPAMP inverting input. R₁ is the internal resistance between the OPAMP inverting input and ground. PGA gain = 1 + R₂/R₁.

6.3.29 Digital filter for Sigma-Delta Modulators (DFSDM) characteristics

Unless otherwise specified, the parameters given in [Table 100](#) for DFSDM are derived from tests performed under the ambient temperature, f_{PCLKx} frequency and supply voltage conditions summarized in [Table 13: General operating conditions](#).

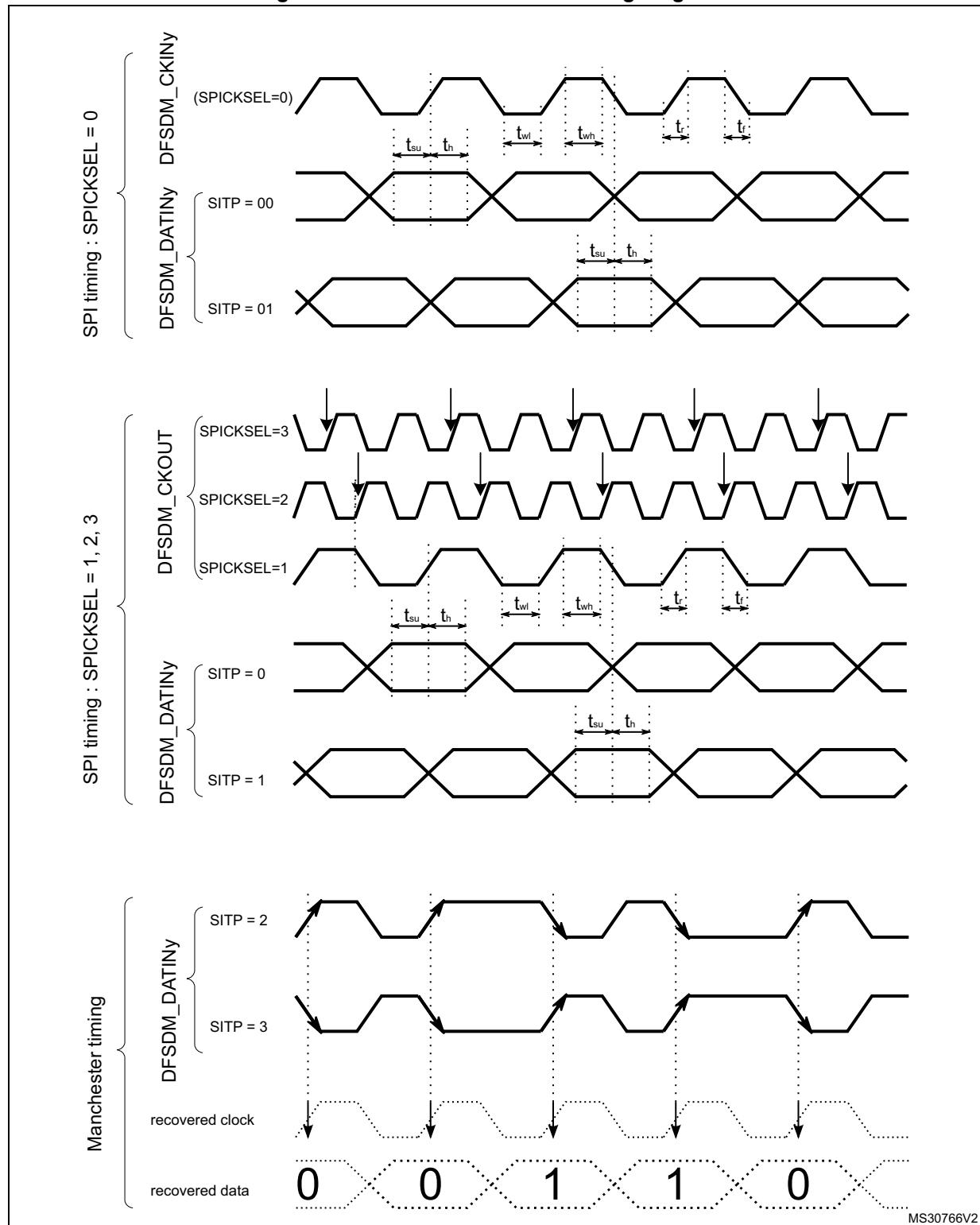
- Output speed is set to OSPEEDR[1:0] = 10
- Capacitive load C_L = 30 pF
- Measurement points are done at CMOS levels: 0.5V_{DD}
- VOS level set to VOS1

Refer to [Section 6.3.16: I/O port characteristics](#) for more details on the input/output alternate function characteristics (DiFSDM_CKINx, DFSDM_DATINx, DFSDM_CKOUT for DFSDM).

Table 100. DFSDM measured timing - 1.62-3.6 V

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
$f_{DFSDMCLK}$	DFSDM clock	$1.62 < V_{DD} < 3.6 \text{ V}$		-	-	250	MHz
f_{CKIN} ($1/T_{CKIN}$)	Input clock frequency	SPI mode ($SITP[1:0]=0,1$), External clock mode ($SPICKSEL[1:0]=0$), $1.62 < V_{DD} < 3.6 \text{ V}$	-	-	-	20	
		SPI mode ($SITP[1:0]=0,1$), External clock mode ($SPICKSEL[1:0]=0$), $2.7 < V_{DD} < 3.6 \text{ V}$	-	-	-	20	
		SPI mode ($SITP[1:0]=0,1$), Internal clock mode ($SPICKSEL[1:0]=1'0$), $1.62 < V_{DD} < 3.6 \text{ V}$	-	-	-	20	
		SPI mode ($SITP[1:0]=0,1$), Internal clock mode ($SPICKSEL[1:0]=1'0$), $2.7 < V_{DD} < 3.6 \text{ V}$	-	-	-	20	
f_{CKOUT}	Output clock frequency	$1.62 < V_{DD} < 3.6 \text{ V}$		-	-	20	%
$DuCy_{CK OUT}$	Output clock frequency duty cycle	$1.62 < V_{DD} < 3.6 \text{ V}$	Even division, $CKOUTDIV[7:0] = 1, 3, 5\dots$	45	50	55	
			Odd division, $CKOUTDIV[7:0] = 2, 4, 6\dots$	$((n/2+1)/(n+1)) *100 - 5$	$((n/2+1)/(n+1)) *100$	$((n/2+1)/(n+1)) *100 + 5$	ns
$t_{wh}(CKIN)$ $t_{wl}(CKIN)$	Input clock high and low time	SPI mode ($SITP[1:0]=0,1$), External clock mode ($SPICKSEL[1:0]=0$), $1.62 < V_{DD} < 3.6 \text{ V}$	$T_{CKIN}/2 - 0.5$	$T_{CKIN}/2$	-	-	
t_{su}	Data input setup time	SPI mode ($SITP[1:0]=0,1$), External clock mode ($SPICKSEL[1:0]=0$), $1.62 < V_{DD} < 3.6 \text{ V}$	1.5	-	-	-	
t_h	Data input hold time	SPI mode ($SITP[1:0]=0,1$), External clock mode ($SPICKSEL[1:0]=0$), $1.62 < V_{DD} < 3.6 \text{ V}$	0.5	-	-	-	
$T_{Manchester}$	Manchester data period (recovered clock period)	Manchester mode ($SITP[1:0]=2,3$), Internal clock mode ($SPICKSEL[1:0]=1'0$), $1.62 < V_{DD} < 3.6 \text{ V}$	$(CKOUTDIV+1) * T_{DFSDMCLK}$	-	$(2 * CKOUTDIV) * T_{DFSDMCLK}$	-	

Figure 45. Channel transceiver timing diagrams



6.3.30 Camera interface (DCMI) timing specifications

Unless otherwise specified, the parameters given in [Table 101](#) for DCMI are derived from tests performed under the ambient temperature, f_{HCLK} frequency and VDD supply voltage summarized in [Table 13: General operating conditions](#), with the following configuration:

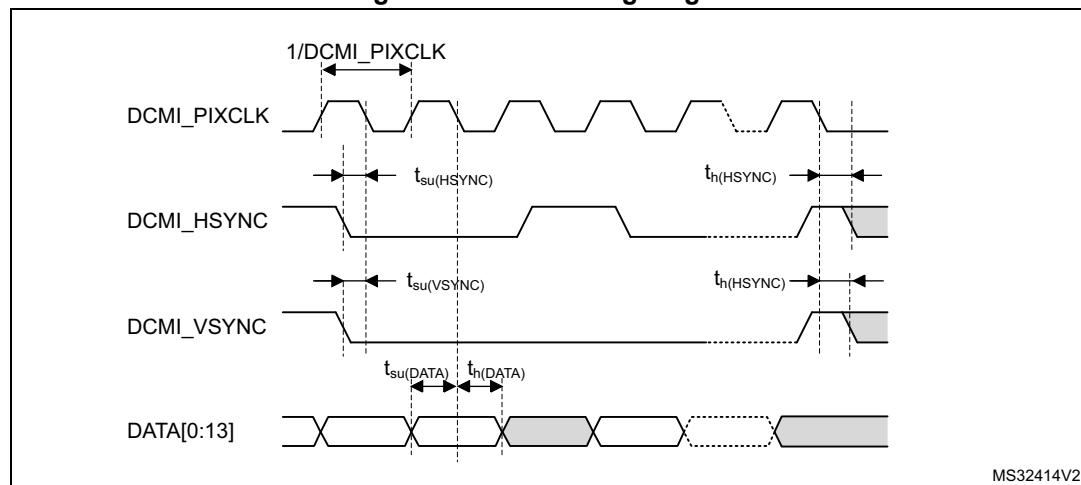
- DCMI_PIXCLK polarity: falling
- DCMI_VSYNC and DCMI_HSYNC polarity: high
- Data formats: 14 bits
- Capacitive load $C_L=30\text{ pF}$
- Measurement points are done at CMOS levels: $0.5V_{DD}$
- VOS level set to VOS1

Table 101. DCMI characteristics⁽¹⁾

Symbol	Parameter	Min	Max	Unit
-	Frequency ratio DCMI_PIXCLK/ f_{HCLK}	-	0.4	-
DCMI_PIXCLK	Pixel Clock input	-	80	MHz
D_{pixel}	Pixel Clock input duty cycle	30	70	%
$t_{su}(\text{DATA})$	Data input setup time	3	-	-
$t_h(\text{DATA})$	Data hold time	1	-	-
$t_{su}(\text{Hsync}), t_{su}(\text{Vsync})$	DCMI_HSYNC/ DCMI_VSYNC input setup time	2	-	ns
$t_h(\text{Hsync}), t_h(\text{Vsync})$	DCMI_HSYNC/ DCMI_VSYNC input hold time	1	-	-

1. Guaranteed by characterization results.

Figure 46. DCMI timing diagram



6.3.31 LCD-TFT controller (LTDC) characteristics

Unless otherwise specified, the parameters given in [Table 102](#) for LCD-TFT are derived from tests performed under the ambient temperature, f_{HCLK} frequency and VDD supply voltage summarized in [Table 13: General operating conditions](#), with the following configuration:

- LCD_CLK polarity: high
- LCD_DE polarity: low
- LCD_VSYNC and LCD_HSYNC polarity: high
- Pixel formats: 24 bits
- Output speed is set to OSPEEDR_y[1:0] = 11
- Capacitive load $C_L=30\text{ pF}$
- Measurement points are done at CMOS levels: 0.5VDD
- IO Compensation cell activated.
- HSLV activated when $V_{DD} \leq 2.7\text{ V}$
- VOS level set to VOS1

Table 102. LTDC characteristics⁽¹⁾

Symbol	Parameter		Min	Max	Unit
f_{CLK}	LTDC clock output frequency	2.7< $V_{DD}<3.6\text{ V}$ 20pF	-	150	MHz
		2.7< $V_{DD}<3.6\text{ V}$		133	
		1.62< $V_{DD}<3.6\text{ V}$		90	
D_{CLK}	LTDC clock output duty cycle		45	55	%
$t_{w(CLKH)}, t_{w(CLKL)}$	Clock High time, low time		$t_{w(CLK)}//2-0.5$	$t_{w(CLK)}//2+0.5$	-
$t_v(DATA)$	Data output valid time	2.7< $V_{DD}<3.6\text{ V}$	-	0.5	
$t_h(DATA)$		1.62< $V_{DD}<3.6\text{ V}$		5	
$t_v(DATA)$	Data output hold time		0	-	-
$t_v(HSYNC), t_v(VSYNC), t_v(DE)$	HSYNC/VSYNC/DE output valid time	2.7< $V_{DD}<3.6\text{ V}$	-	0.5	
		1.62< $V_{DD}<3.6\text{ V}$		5	
$t_h(HSYNC), t_h(VSYNC), t_h(DE)$	HSYNC/VSYNC/DE output hold time		0	-	

1. Guaranteed by characterization results.

Figure 47. LCD-TFT horizontal timing diagram

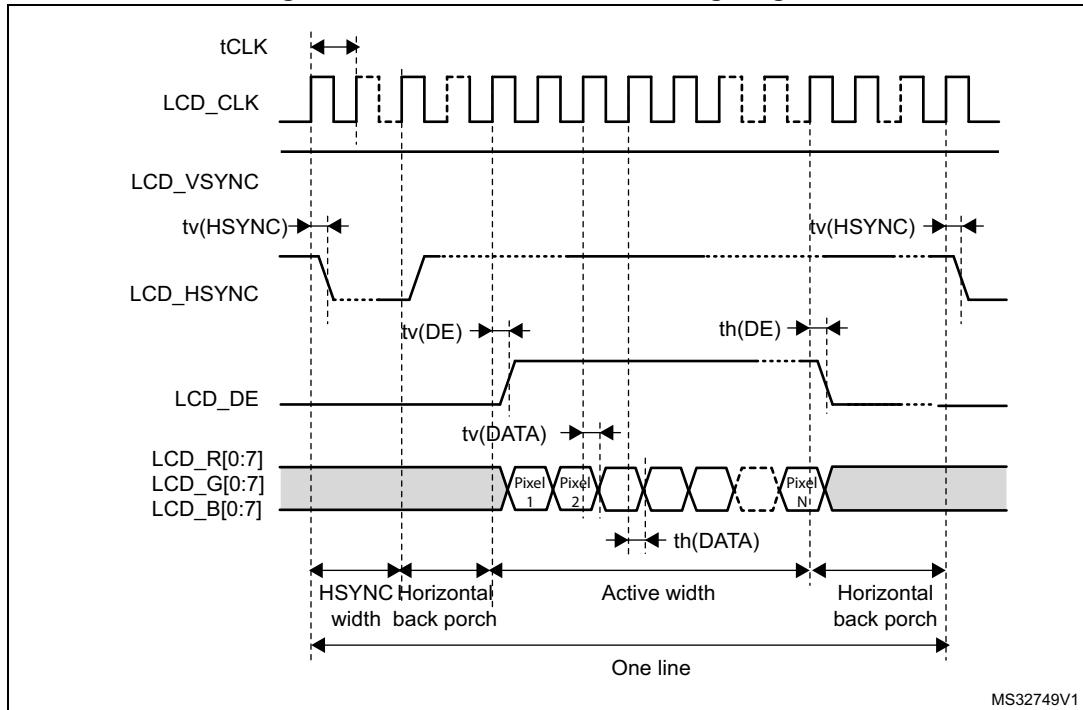
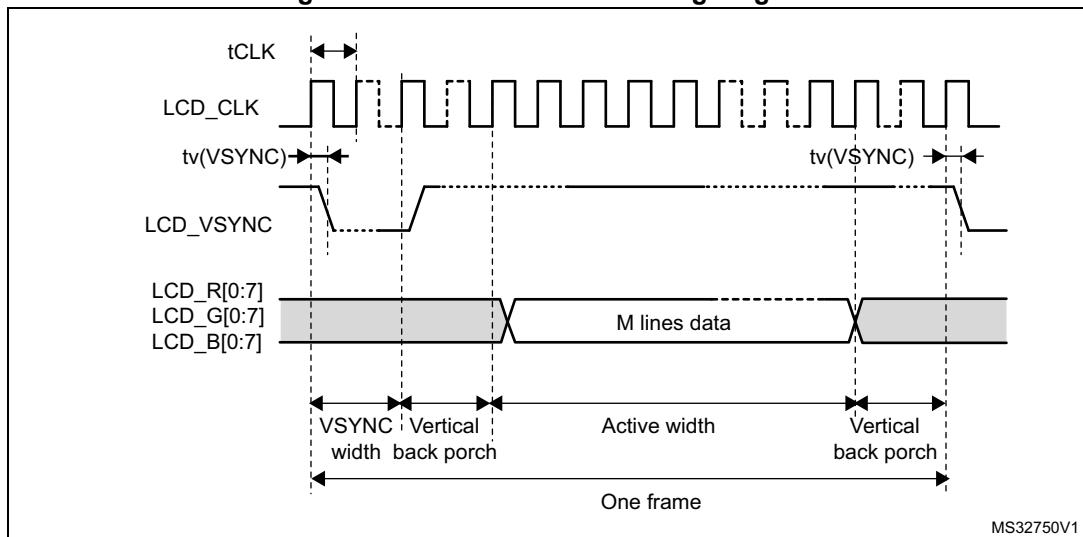


Figure 48. LCD-TFT vertical timing diagram



6.3.32 Timer characteristics

The parameters given in [Table 103](#) are guaranteed by design.

Refer to [Section 6.3.16: I/O port characteristics](#) for details on the input/output alternate function characteristics (output compare, input capture, external clock, PWM output).

Table 103. TIMx characteristics⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions ⁽³⁾	Min	Max	Unit
$t_{\text{res}(\text{TIM})}$	Timer resolution time	AHB/APBx prescaler=1 or 2 or 4, $f_{\text{TIMxCLK}} = 240 \text{ MHz}$	1	-	t_{TIMxCLK}
		AHB/APBx prescaler>4, $f_{\text{TIMxCLK}} = 120 \text{ MHz}$	1	-	t_{TIMxCLK}
f_{EXT}	Timer external clock frequency on CH1 to CH4	$f_{\text{TIMxCLK}} = 240 \text{ MHz}$	0	$f_{\text{TIMxCLK}}/2$	MHz
Res_{TIM}	Timer resolution		-	16/32	bit
$t_{\text{MAX_COUNT}}$	Maximum possible count with 32-bit counter	-	-	65536×65536	t_{TIMxCLK}

1. TIMx is used as a general term to refer to the TIM1 to TIM17 timers.
2. Guaranteed by design.
3. The maximum timer frequency on APB1 or APB2 is up to 240 MHz, by setting the TIMPRE bit in the RCC_CFGR register, if APBx prescaler is 1 or 2 or 4, then $\text{TIMxCLK} = \text{rcc_hclk1}$, otherwise $\text{TIMxCLK} = 4 \times F_{\text{rcc_pclkx_d2}}$.

6.3.33 Communication interfaces

I²C interface characteristics

The I²C interface meets the timings requirements of the I²C-bus specification and user manual revision 03 for:

- Standard-mode (Sm): with a bit rate up to 100 kbit/s
- Fast-mode (Fm): with a bit rate up to 400 kbit/s
- Fast-mode Plus (Fm+): with a bit rate up to 1 Mbit/s.

The I²C timings requirements are guaranteed by design when the I²C peripheral is properly configured (refer to RM0399 reference manual) and when the i2c_ker_ck frequency is greater than the minimum shown in the table below:

Table 104. Minimum i2c_ker_ck frequency in all I²C modes

Symbol	Parameter	Condition		Min	Unit
f(I2CCLK)	I2CCLK frequency	Standard-mode	-	2	MHz
		Fast-mode	Analog Filtre ON DNF=0	8	
			Analog Filtre OFF DNF=1	9	
		Fast-mode Plus	Analog Filtre ON DNF=0	17	
			Analog Filtre OFF DNF=1	16	-

The SDA and SCL I/O requirements are met with the following restrictions:

- The SDA and SCL I/O pins are not “true” open-drain. When configured as open-drain, the PMOS connected between the I/O pin and V_{DD} is disabled, but still present.
- The 20 mA output drive requirement in Fast-mode Plus is not supported. This limits the maximum load C_{Load} supported in Fm+, which is given by these formulas:

$$t_{r(SDA/SCL)} = 0.8473 \times R_P \times C_{Load}$$

$$R_P(\min) = (V_{DD} - V_{OL(\max)}) / I_{OL(\max)}$$

Where R_P is the I²C lines pull-up. Refer to [Section 6.3.16: I/O port characteristics](#) for the I²C I/Os characteristics.

All I²C SDA and SCL I/Os embed an analog filter. Refer to the table below for the analog filter characteristics:

Table 105. I²C analog filter characteristics⁽¹⁾

Symbol	Parameter	Min	Max	Unit
t _{AF}	Maximum pulse width of spikes that are suppressed by analog filter	50 ⁽²⁾	80 ⁽³⁾	ns

1. Guaranteed by characterization results.
2. Spikes with widths below t_{AF(min)} are filtered.
3. Spikes with widths above t_{AF(max)} are not filtered.

USART (SPI mode) interface characteristics

Unless otherwise specified, the parameters given in [Table 106](#) for USART are derived from tests performed under the ambient temperature, f_{PCLKx} frequency and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#), with the following configuration:

- Output speed is set to OSPEEDR[1:0] = 10
- Capacitive load C_L = 30 pF
- Measurement points are done at CMOS levels: 0.5V_{DD}
- IO Compensation cell activated.
- VOS level set to VOS1

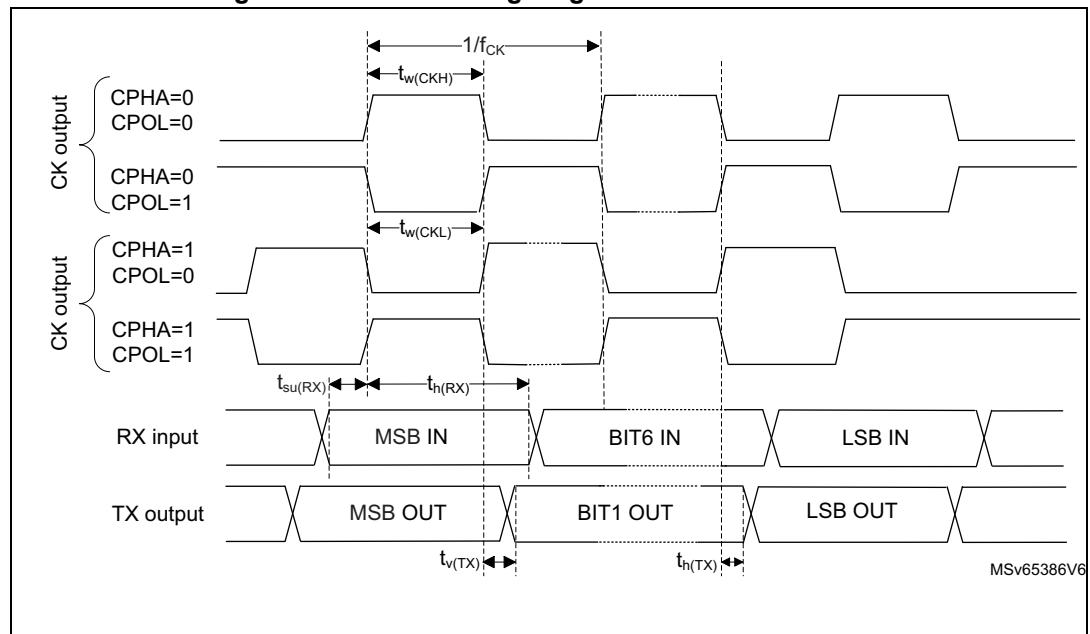
Refer to [Section 6.3.16: I/O port characteristics](#) for more details on the input/output alternate function characteristics (NSS, CK, TX, RX for USART).

Table 106. USART (SPI mode) characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{CK}	USART clock frequency	SPI master mode	-	-	12.5	MHz
		SPI slave mode			25	
$t_{su(NSS)}$	NSS setup time	SPI slave mode	$t_{ker}+1$	-	-	-
$t_h(NSS)$	NSS hold time	SPI slave mode	2	-	-	
$t_w(CKH), t_w(CKL)$	CK high and low time	SPI master mode	$1/f_{CK}/2-2$	$1/f_{CK}/2$	$1/f_{CK}/2+2$	
$t_{su(RX)}$	Data input setup time	SPI master mode	$t_{ker}+6$	-	-	
		SPI slave mode	1.5	-	-	
$t_h(RX)$	Data input hold time	SPI master mode	0	-	-	
		SPI slave mode	1.5	-	-	
$t_v(TX)$	Data output valid time	SPI slave mode	-	12	20	ns
		SPI master mode	-	0.5	1	
$t_h(TX)$	Data output hold time	SPI slave mode	9	-	-	
		SPI master mode	0	-	-	

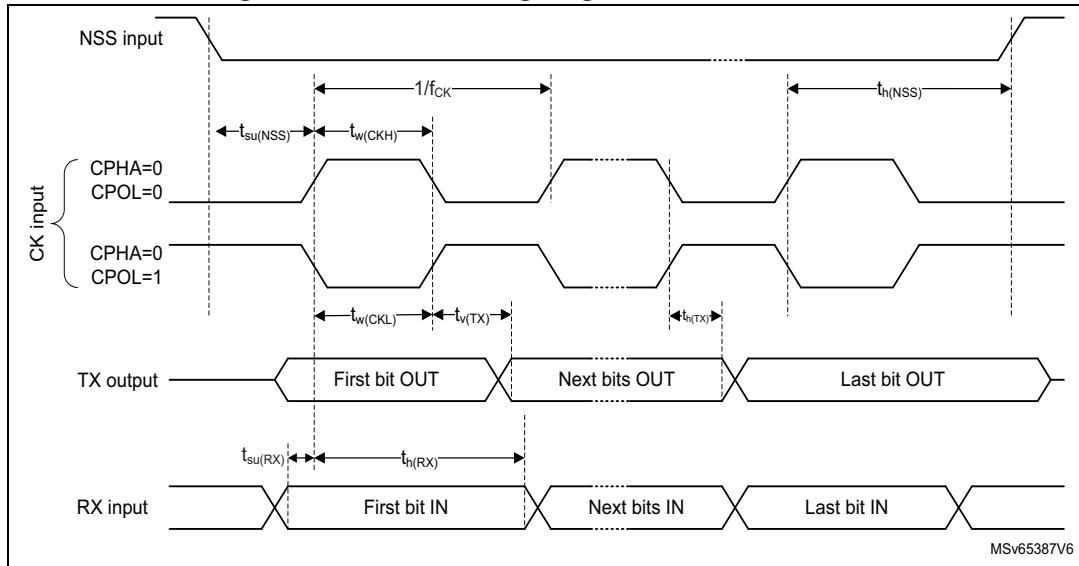
1. Guaranteed by characterization results.

Figure 49. USART timing diagram in SPI master mode



1. Measurement points are done at $0.5V_{DD}$ and with external $C_L = 30\text{ pF}$.

Figure 50. USART timing diagram in SPI slave mode



SPI interface characteristics

Unless otherwise specified, the parameters given in [Table 107](#) for SPI are derived from tests performed under the ambient temperature, f_{PCLK_X} frequency and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#), with the following configuration:

- Output speed is set to OSPEEDR[1:0] = 11
- Capacitive load $C_L = 30 \text{ pF}$
- Measurement points are done at CMOS levels: $0.5V_{\text{DD}}$
- IO Compensation cell activated.
- HSLV activated when $V_{\text{DD}} \leq 2.7 \text{ V}$
- VOS level set to VOS1

Refer to [Section 6.3.16: I/O port characteristics](#) for more details on the input/output alternate function characteristics (NSS, SCK, MOSI, MISO for SPI).

Table 107. SPI dynamic characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{SCK}	SPI clock frequency	Master mode $1.62 < V_{DD} < 3.6 \text{ V}$ SPI1, 2, 3	-	-	80	MHz
		Master mode $2.7 < V_{DD} < 3.6 \text{ V}$ SPI1, 2, 3			100	
		Master mode $1.62 < V_{DD} < 3.6 \text{ V}$ SPI4, 5, 6			50	
		Slave receiver mode $1.62 < V_{DD} < 3.6 \text{ V}$			100	
		Slave mode transmitter/full duplex $2.7 < V_{DD} < 3.6 \text{ V}$			31	
		Slave mode transmitter/full duplex $1.62 < V_{DD} < 3.6 \text{ V}$			29	
$t_{su(NSS)}$	NSS setup time	Slave mode	2	-	-	ns
$t_h(NSS)$	NSS hold time	Slave mode	1	-	-	
$t_w(SCKH)$, $t_w(SCKL)$	SCK high and low time	Master mode	$T_{PCLK}-2$	T_{PCLK}	$T_{PCLK}+2$	
$t_{su(MI)}$	Data input setup time	Master mode	2	-	-	
$t_{su(SI)}$		Slave mode	1	-	-	
$t_h(MI)$	Data input hold time	Master mode	3	-	-	
$t_h(SI)$		Slave mode	2	-	-	
$t_a(SO)$	Data output access time	Slave mode	9	13	27	
$t_{dis(SO)}$	Data output disable time	Slave mode	0	1	5	
$t_v(SO)$	Data output valid time	Slave mode $2.7 < V_{DD} < 3.6 \text{ V}$	-	12.5	16	
		Slave mode $1.62 < V_{DD} < 3.6 \text{ V}$	-	12.5	17	
		Master mode	-	1	3	
$t_h(SO)$	Data output hold time	Slave mode $1.62 < V_{DD} < 3.6 \text{ V}$	10	-	-	
$t_h(MO)$		Master mode	0	-	-	

1. Guaranteed by characterization results.

Figure 51. SPI timing diagram - slave mode and CPHA = 0

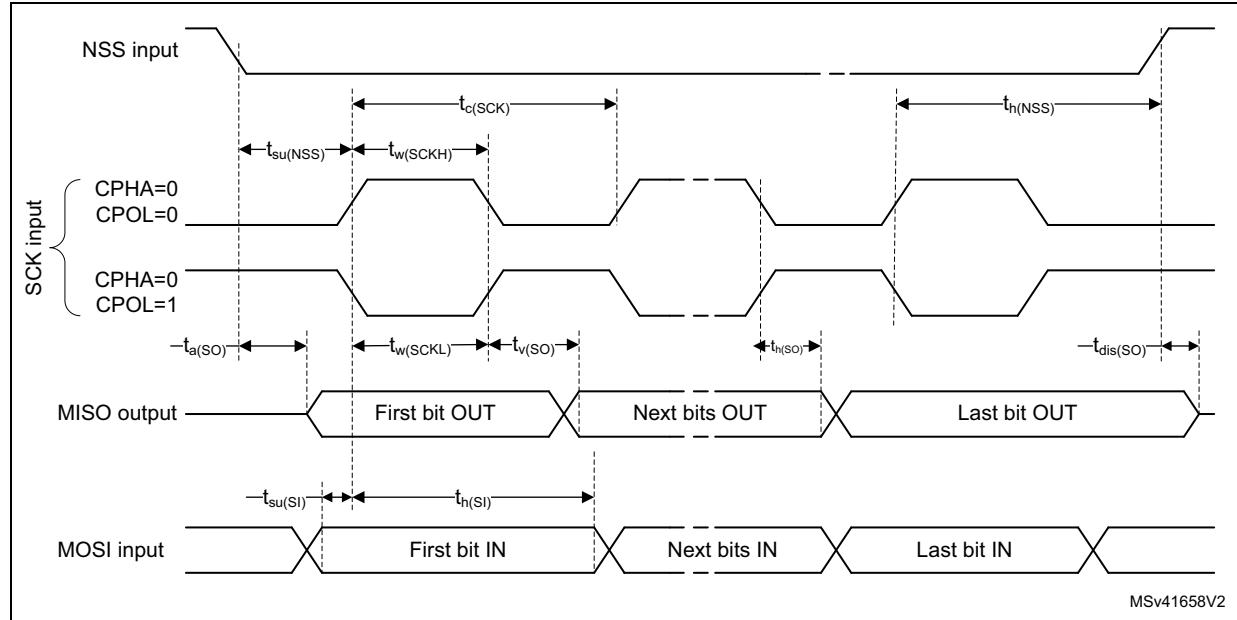


Figure 52. SPI timing diagram - slave mode and CPHA = 1

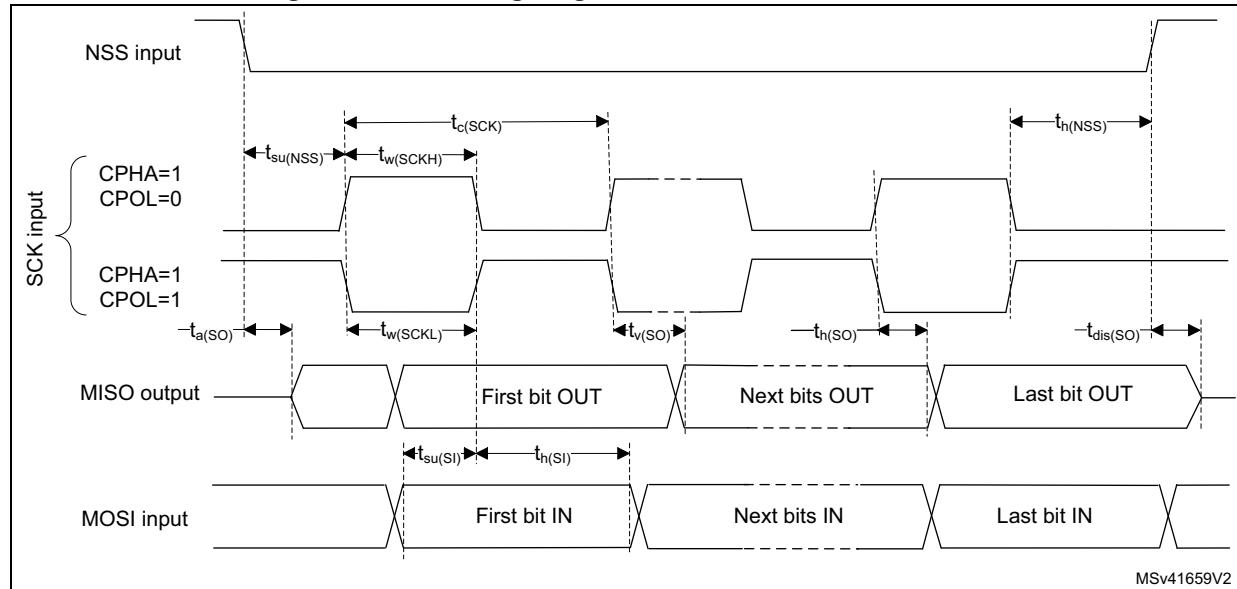
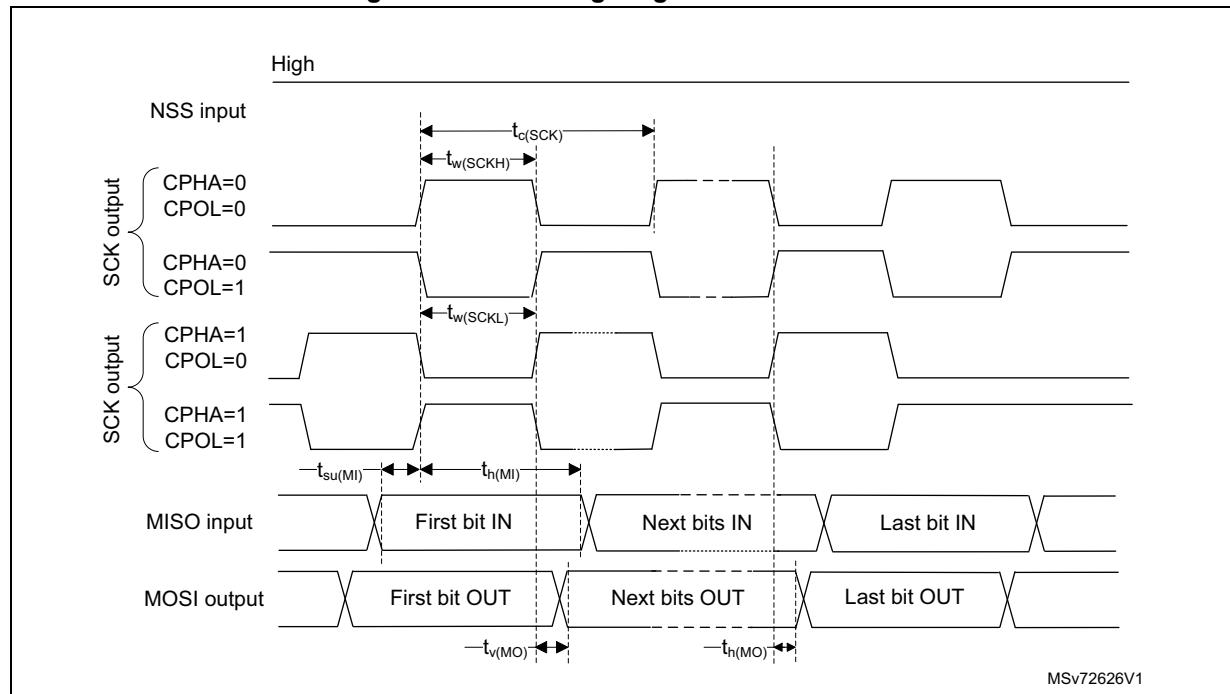


Figure 53. SPI timing diagram - master mode



I²S Interface characteristics

Unless otherwise specified, the parameters given in [Table 108](#) for I²S are derived from tests performed under the ambient temperature, f_{PCLK_x} frequency and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#), with the following configuration:

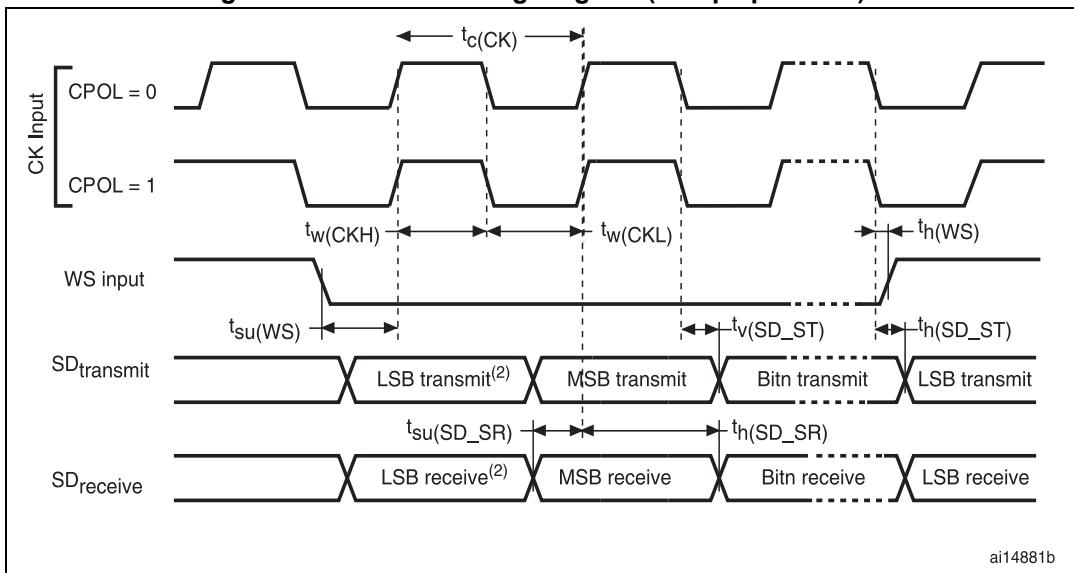
- Output speed is set to OSPEEDRy[1:0] = 10
- Capacitive load $C_L = 30 \text{ pF}$
- Measurement points are done at CMOS levels: $0.5V_{DD}$
- IO Compensation cell activated.
- HSLV activated when $V_{DD} \leq 2.7 \text{ V}$
- VOS level set to VOS1

Refer to [Section 6.3.16: I/O port characteristics](#) for more details on the input/output alternate function characteristics (CK,SD,WS).

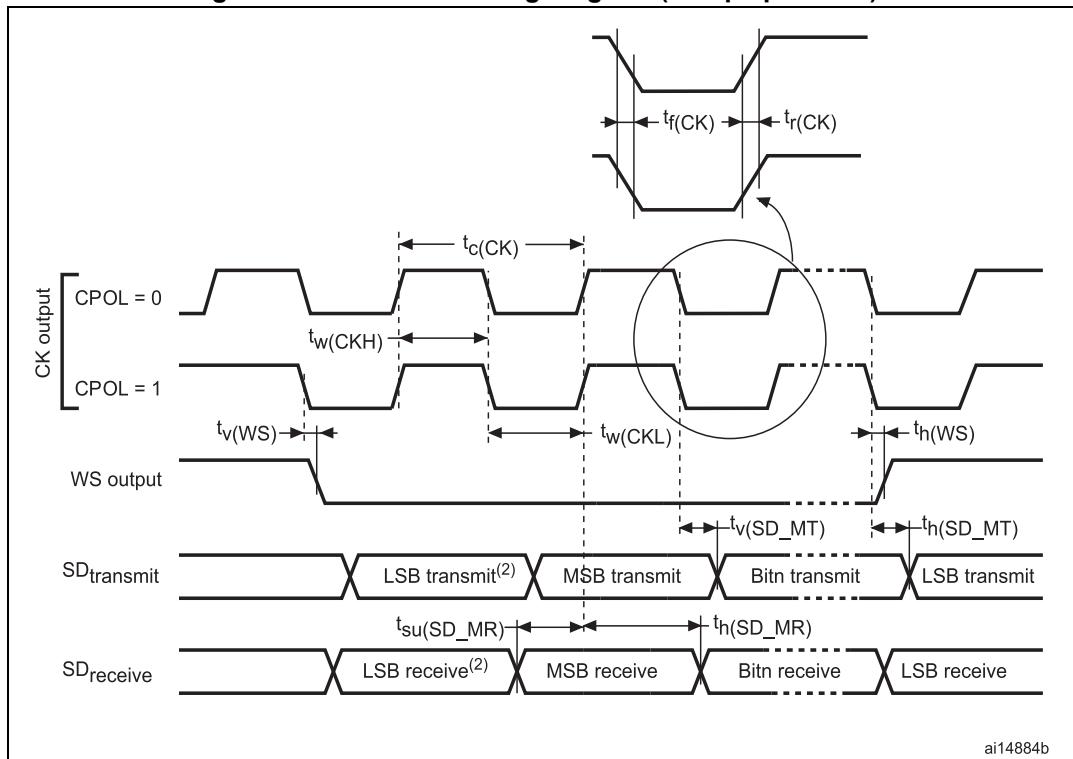
Table 108. I²S dynamic characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Max	Unit
f_{MCK}	I ² S main clock output	-	256x8K	256F _S	MHz
f_{CK}	I ² S clock frequency	Master data	-	64F _S	MHz
		Slave data	-	64F _S	
$t_{v(WS)}$	WS valid time	Master mode	-	3	ns
$t_{h(WS)}$	WS hold time	Master mode	0	-	
$t_{su(WS)}$	WS setup time	Slave mode	1	-	
$t_{h(WS)}$	WS hold time	Slave mode	1	-	
$t_{su(SD_MR)}$	Data input setup time	Master receiver	1	-	
$t_{su(SD_SR)}$		Slave receiver	1	-	
$t_{h(SD_MR)}$	Data input hold time	Master receiver	4	-	
$t_{h(SD_SR)}$		Slave receiver	2	-	
$t_{v(SD_ST)}$	Data output valid time	Slave transmitter (after enable edge)	-	17	
$t_{v(SD_MT)}$		Master transmitter (after enable edge)	-	3	
$t_{h(SD_ST)}$	Data output hold time	Slave transmitter (after enable edge)	9	-	
$t_{h(SD_MT)}$		Master transmitter (after enable edge)	0	-	

1. Guaranteed by characterization results.

Figure 54. I²S slave timing diagram (Philips protocol)⁽¹⁾

1. LSB transmit/receive of the previously transmitted byte. No LSB transmit/receive is sent before the first byte.

Figure 55. I²S master timing diagram (Philips protocol)⁽¹⁾

1. LSB transmit/receive of the previously transmitted byte. No LSB transmit/receive is sent before the first byte.

SAI characteristics

Unless otherwise specified, the parameters given in [Table 109](#) for SAI are derived from tests performed under the ambient temperature, f_{PCLKx} frequency and VDD supply voltage conditions summarized in [Table 13: General operating conditions](#), with the following configuration:

- Output speed is set to OSPEEDR[1:0] = 10
- Capacitive load $C_L = 30 \text{ pF}$
- IO Compensation cell activated.
- Measurement points are done at CMOS levels: 0.5VDD
- VOS level set to VOS1.

Refer to [Section 6.3.16: I/O port characteristics](#) for more details on the input/output alternate function characteristics (SCK,SD,WS).

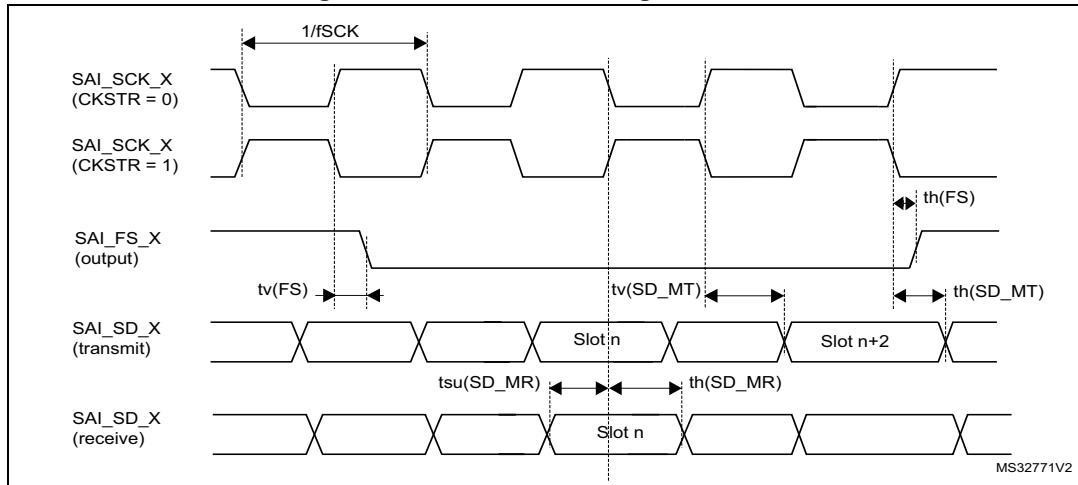
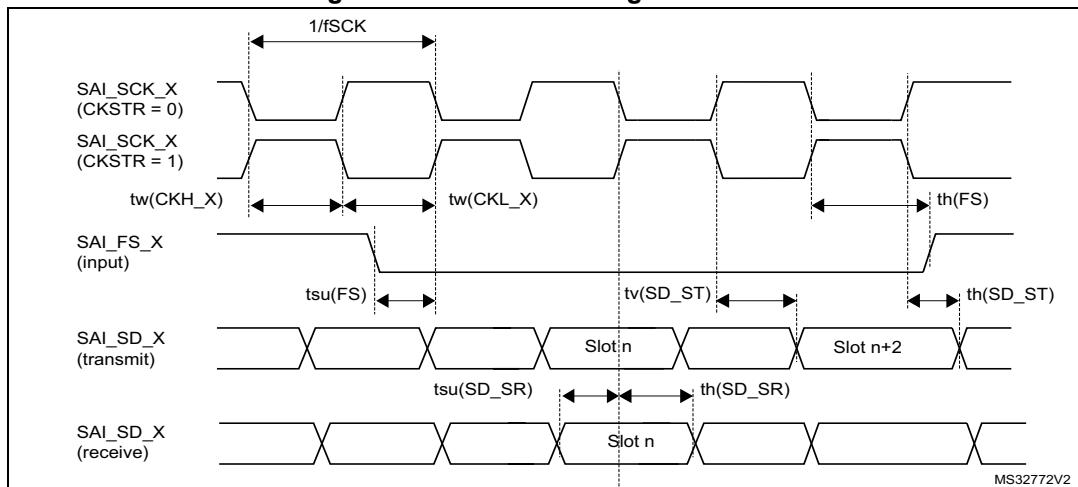
Table 109. SAI characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Max	Unit
f_{MCK}	SAI Main clock output	-	256x8K	$256xF_S$	MHz
f_{CK}	SAI clock frequency ⁽²⁾	Master Data: 32 bits	-	$128xF_S^{(3)}$	
		Slave Data: 32 bits	-	$128xF_S^{(3)}$	

Table 109. SAI characteristics⁽¹⁾ (continued)

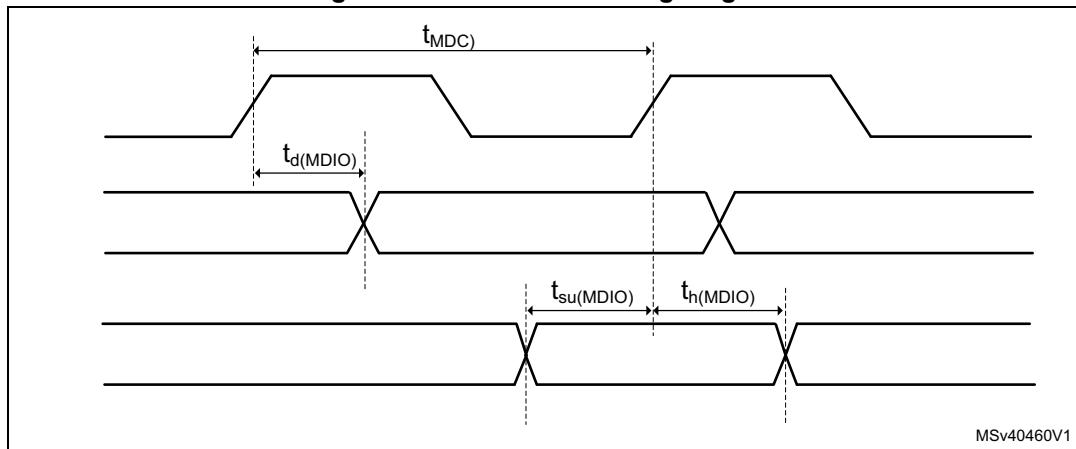
Symbol	Parameter	Conditions	Min	Max	Unit
$t_{v(FS)}$	F_S valid time	Master mode $2.7 \leq V_{DD} \leq 3.6$	-	13	ns
		Master mode $1.62 \leq V_{DD} \leq 3.6$	-	20	
$t_{su(FS)}$	F_S hold time	Master mode	8	-	
$t_h(FS)$	F_S setup time	Slave mode	1	-	
	F_S hold time	Slave mode	1	-	
$t_{su(SD_A_MR)}$	Data input setup time	Master receiver	0.5	-	
$t_{su(SD_B_SR)}$		Slave receiver	1	-	
$t_h(SD_A_MR)$	Data input hold time	Master receiver	3.5	-	
$t_h(SD_B_SR)$		Slave receiver	2	-	
$t_{v(SD_B_ST)}$	Data output valid time	Slave transmitter (after enable edge) $2.7 \leq V_{DD} \leq 3.6$	-	14	
		Slave transmitter (after enable edge) $1.62 \leq V_{DD} \leq 3.6$	-	20	
$t_h(SD_B_ST)$	Data output hold time	Slave transmitter (after enable edge)	9	-	
$t_{v(SD_A_MT)}$	Data output valid time	Master transmitter (after enable edge) $2.7 \leq V_{DD} \leq 3.6$	-	12	
		Master transmitter (after enable edge) $1.62 \leq V_{DD} \leq 3.6$	-	19	
$t_h(SD_A_MT)$	Data output hold time	Master transmitter (after enable edge)	7.5	-	

1. Guaranteed by characterization results.
2. APB clock frequency must be at least twice SAI clock frequency.
3. With $F_S=192$ kHz.

Figure 56. SAI master timing waveforms**Figure 57. SAI slave timing waveforms****MDIO characteristics****Table 110. MDIO Slave timing parameters**

Symbol	Parameter	Min	Typ	Max	Unit
F_{MDC}	Management Data Clock	-	-	30	MHz
$t_d(MDIO)$	Management Data Input/output output valid time	8	10	19	ns
$t_{su}(MDIO)$	Management Data Input/output setup time	1	-	-	
$t_h(MDIO)$	Management Data Input/output hold time	1	-	-	

Figure 58. MDIO Slave timing diagram



SD/SDIO MMC card host interface (SDMMC) characteristics

Unless otherwise specified, the parameters given in [Table 111](#) and [Table 112](#) for SDIO are derived from tests performed under the ambient temperature, f_{PCLK_x} frequency and V_{DD} supply voltage summarized in [Table 13: General operating conditions](#), with the following configuration:

- Output speed is set to OSPEEDR_y[1:0] = 0x11
- Capacitive load $C_L = 30 \text{ pF}$
- Measurement points are done at CMOS levels: $0.5V_{\text{DD}}$
- IO Compensation cell activated.
- HSLV activated when $V_{\text{DD}} \leq 2.7 \text{ V}$
- VOS level set to VOS1

Refer to [Section 6.3.16: I/O port characteristics](#) for more details on the input/output characteristics.

Table 111. Dynamics characteristics: SD / MMC characteristics, $V_{\text{DD}} = 2.7 \text{ to } 3.6 \text{ V}^{(1)(2)}$

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{PP}	Clock frequency in data transfer mode	-	0	-	133	MHz
-	SDIO_CK/fPCLK2 frequency ratio	-	-	-	8/3	-
$t_{\text{W(CKL)}}$	Clock low time	$f_{\text{PP}} = 52 \text{ MHz}$	8.5	9.5	-	ns
$t_{\text{W(CKH)}}$	Clock high time	$f_{\text{PP}} = 52 \text{ MHz}$	8.5	9.5	-	
CMD, D inputs (referenced to CK) in eMMC legacy/SDR/DDR and SD HS/SDR⁽³⁾/DDR⁽³⁾ mode						
t_{ISU}	Input setup time HS	-	2.5	-	-	ns
t_{IH}	Input hold time HS	-	0.5	-	-	
$t_{\text{IDW}}^{(4)}$	Input valid window (variable window)	-	3	-	-	-
CMD, D outputs (referenced to CK) in eMMC legacy/SDR/DDR and SD HS/SDR/DDR⁽³⁾ mode						
t_{ov}	Output valid time HS	-	-	3.5	5	ns
t_{OH}	Output hold time HS	-	3	-	-	

Table 111. Dynamics characteristics: SD / MMC characteristics, V_{DD} = 2.7 to 3.6 V⁽¹⁾⁽²⁾ (continued)

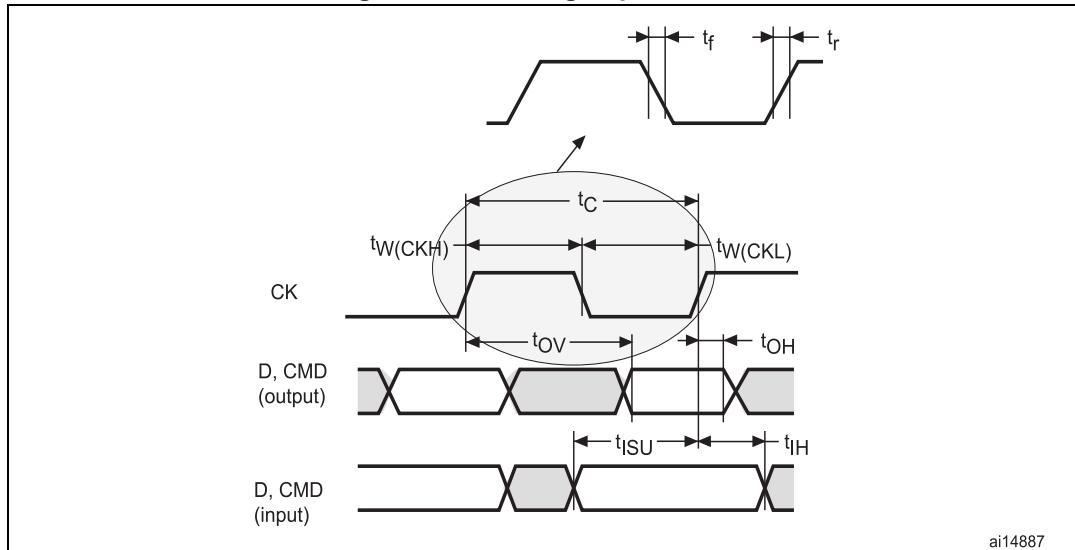
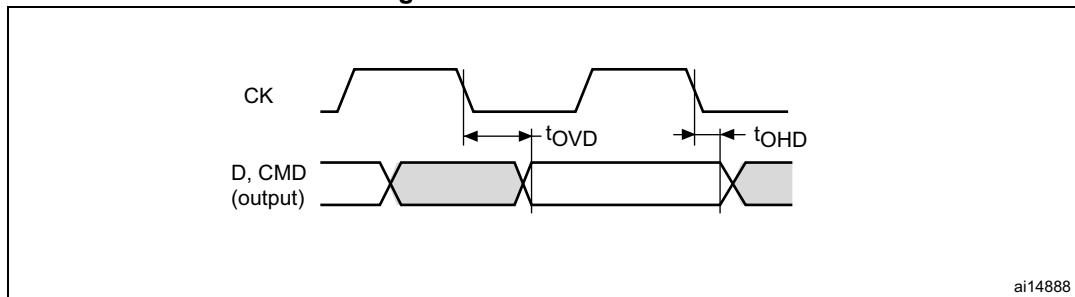
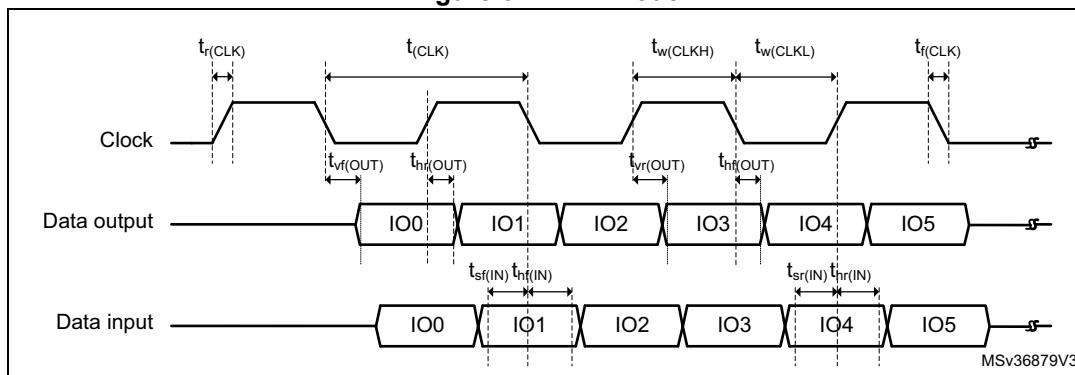
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
CMD, D inputs (referenced to CK) in SD default mode						
t _{ISUD}	Input setup time SD	-	2.5	-	-	ns
t _{IHD}	Input hold time SD	-	0.5	-	-	
CMD, D outputs (referenced to CK) in SD default mode						
t _{OVD}	Output valid default time SD	-	-	0.5	2	ns
t _{OHD}	Output hold default time SD	-	0	-	-	

1. Guaranteed by characterization results.
2. Above 100 MHz, C_L = 20 pF.
3. An external voltage converter is required to support SD 1.8 V.
4. The minimum window of time where the data needs to be stable for proper sampling in tuning mode.

Table 112. Dynamics characteristics: eMMC characteristics VDD = 1.71V to 1.9V⁽¹⁾⁽²⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f _{PP}	Clock frequency in data transfer mode	-	0	-	120	MHz
-	SDIO_CK/fPCLK2 frequency ratio	-	-	-	8/3	-
t _{W(CKL)}	Clock low time	f _{PP} = 52 MHz	8.5	9.5	-	ns
t _{W(CKH)}	Clock high time	f _{PP} = 52 MHz	8.5	9.5	-	
CMD, D inputs (referenced to CK) in eMMC mode						
t _{ISU}	Input setup time HS	-	2	-	-	ns
t _{IH}	Input hold time HS	-	1.5	-	-	
t _{IDW} ⁽³⁾	Input valid window (variable window)	-	3.5	-	-	
CMD, D outputs (referenced to CK) in eMMC mode						
t _{OVD}	Output valid time HS	-	-	5	7	ns
t _{OHD}	Output hold time HS	-	3	-	-	

1. Guaranteed by characterization results.
2. C_L = 20 pF.
3. The minimum window of time where the data needs to be stable for proper sampling in tuning mode.

Figure 59. SDIO high-speed mode**Figure 60. SD default mode****Figure 61. DDR mode**

USB OTG_FS characteristics

The USB interface is fully compliant with the USB specification version 2.0 and is USB-IF certified (for Full-speed device operation).

Table 113. USB OTG_FS electrical characteristics

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$V_{DD33USB}$	USB transceiver operating voltage	-	3.0 ⁽¹⁾	-	3.6	V
R_{PUI}	Embedded USB_DP pull-up value during idle	-	900	1250	1600	Ω
R_{PUR}	Embedded USB_DP pull-up value during reception	-	1400	2300	3200	
Z_{DRV}	Output driver impedance ⁽²⁾	Driver high and low	28	36	44	

1. The USB functionality is ensured down to 2.7 V but not the full USB electrical characteristics which are degraded in the 2.7 to 3.0 V voltage range.
2. No external termination series resistors are required on USB_DP (D+) and USB_DM (D-); the matching impedance is already included in the embedded driver.

USB OTG_HS characteristics

Unless otherwise specified, the parameters given in [Table 114](#) for ULPI are derived from tests performed under the ambient temperature, f_{PCLKx} frequency and V_{DD} supply voltage summarized in [Table 13: General operating conditions](#), with the following configuration:

- Output speed is set to OSPEEDRy[1:0] = 11
- Capacitive load $C_L=20 \text{ pF}$
- Measurement points are done at CMOS levels: $0.5V_{DD}$
- IO Compensation cell activated.
- VOS level set to VOS1

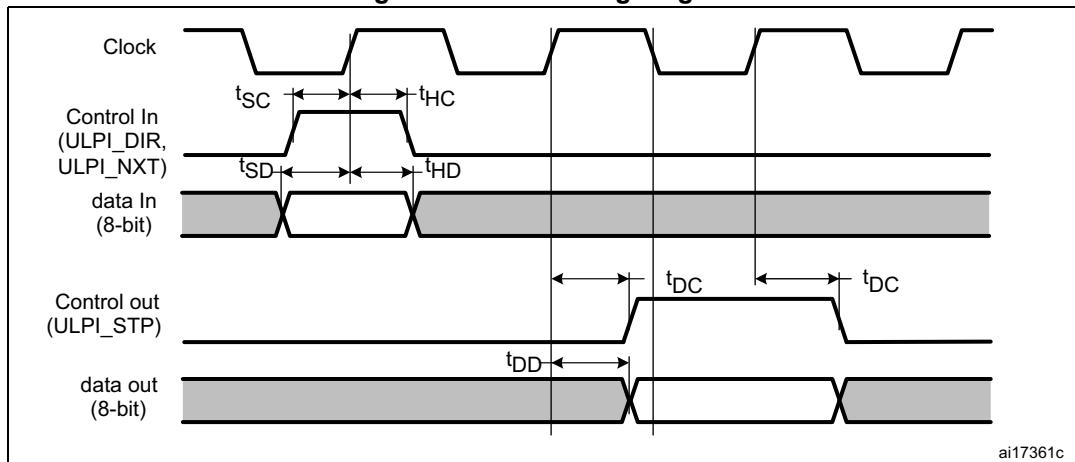
Refer to [Section 6.3.16: I/O port characteristics](#) for more details on the input/output characteristics.

Table 114. Dynamics characteristics: USB ULPI⁽¹⁾

Symbol	Parameter	Condition	Min	Typ	Max	Unit
t_{SC}	Control in (ULPI_DIR, ULPI_NXT) setup time	-	2.5	-	-	ns
		-	4.5 ⁽²⁾	-	-	
t_{HC}	Control in (ULPI_DIR, ULPI_NXT) hold time	-	2	-	-	
t_{SD}	Data in setup time	-	2.5	-	-	
t_{HD}	Data in hold time	-	0	-	-	
t_{DC}/t_{DD}	Control/Datal output delay	$2.7 < V_{DD} < 3.6 \text{ V}$ $C_L=20 \text{ pF}$	-	9	9.5	
		$1.71 < V_{DD} < 3.6 \text{ V}$ $C_L=15 \text{ pF}$	-	9	14	

1. Guaranteed by characterization results.
2. When using PC2_C/PC3_C.

Figure 62. ULPI timing diagram



ai17361c

Ethernet interface characteristics

Unless otherwise specified, the parameters given in [Table 115](#), [Table 116](#) and [Table 117](#) for SMI, RMII and MII are derived from tests performed under the ambient temperature, $f_{rcc_c_ck}$ frequency and V_{DD} supply voltage conditions summarized in [Table 13: General operating conditions](#), with the following configuration:

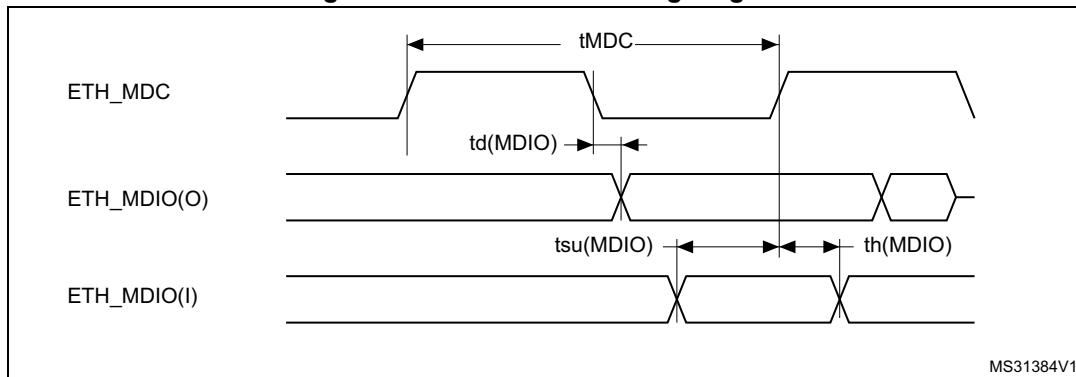
- Output speed is set to OSPEEDR[1:0] = 10
- Capacitive load $C_L=20\text{ pF}$
- Measurement points are done at CMOS levels: $0.5V_{DD}$
- IO Compensation cell activated.
- HSLV activated when $VDD \leq 2.7\text{ V}$
- VOS level set to VOS1

Refer to [Section 6.3.16: I/O port characteristics](#) for more details on the input/output characteristics:

Table 115. Dynamics characteristics: Ethernet MAC signals for SMI (1)

Symbol	Parameter	Min	Typ	Max	Unit
t_{MDC}	MDC cycle time(2.5 MHz)	400	400	403	ns
$T_d(\text{MDIO})$	Write data valid time	0.5	1.5	4	
$t_{su}(\text{MDIO})$	Read data setup time	12.5	-	-	
$t_h(\text{MDIO})$	Read data hold time	0	-	-	

1. Guaranteed by characterization results.

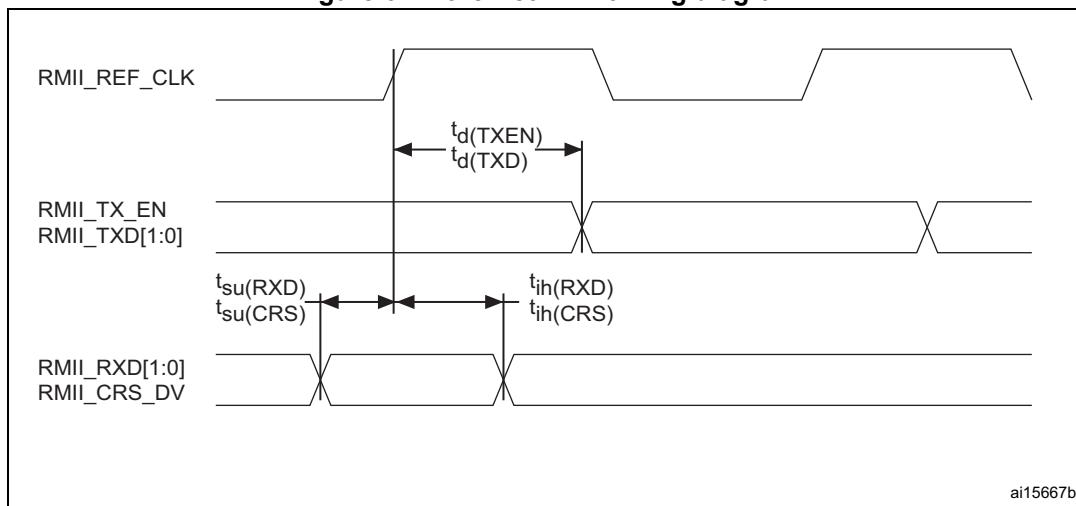
Figure 63. Ethernet SMI timing diagram

MS31384V1

Table 116. Dynamics characteristics: Ethernet MAC signals for RMII⁽¹⁾

Symbol	Parameter	Min	Typ	Max	Unit
$t_{su(RXD)}$	Receive data setup time	2	-	-	ns
$t_{ih(RXD)}$	Receive data hold time	2	-	-	
$t_{su(CRS)}$	Carrier sense setup time	1.5	-	-	
$t_{ih(CRS)}$	Carrier sense hold time	1.5	-	-	
$t_d(TXEN)$	Transmit enable valid delay time	7	8	9.5	
$t_d(TXD)$	Transmit data valid delay time	8	9	11	

1. Guaranteed by characterization results.

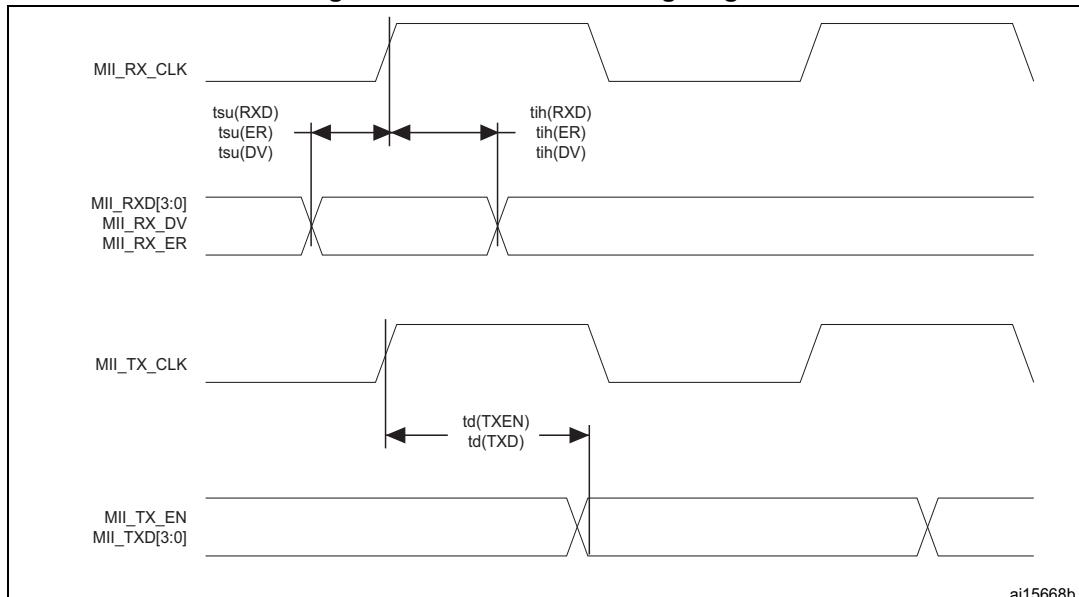
Figure 64. Ethernet RMII timing diagram

ai15667b

Table 117. Dynamics characteristics: Ethernet MAC signals for MII⁽¹⁾

Symbol	Parameter	Min	Typ	Max	Unit
$t_{su(RXD)}$	Receive data setup time	2	-	-	ns
$t_{ih(RXD)}$	Receive data hold time	2	-	-	
$t_{su(DV)}$	Data valid setup time	1.5	-	-	
$t_{ih(DV)}$	Data valid hold time	1.5	-	-	
$t_{su(ER)}$	Error setup time	1.5	-	-	
$t_{ih(ER)}$	Error hold time	0.5	-	-	
$t_d(TXEN)$	Transmit enable valid delay time	9	10	11	
$t_d(TXD)$	Transmit data valid delay time	8.5	9.5	12.5	

1. Guaranteed by characterization results.

Figure 65. Ethernet MII timing diagram

ai15668b

JTAG/SWD interface characteristics

Unless otherwise specified, the parameters given in [Table 118](#) and [Table 119](#) for JTAG/SWD are derived from tests performed under the ambient temperature, $f_{rcc_c_ck}$ frequency and V_{DD} supply voltage summarized in [Table 13: General operating conditions](#), with the following configuration:

- Output speed is set to OSPEEDR[1:0] = 0x10
- Capacitive load $C_L=30\text{ pF}$
- Measurement points are done at CMOS levels: $0.5V_{DD}$
- VOS level set to VOS1

Refer to [Section 6.3.16: I/O port characteristics](#) for more details on the input/output characteristics:

Table 118. Dynamics JTAG characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
F_{pp}	T_{CK} clock frequency	$2.7V < V_{DD} < 3.6V$	-	-	37	MHz
$1/t_c(TCK)$		$1.62 < V_{DD} < 3.6V$	-	-	27.5	
$t_{is}(TMS)$	TMS input setup time	-	2.5	-	-	
$t_{ih}(TMS)$	TMS input hold time	-	1	-	-	
$t_{is}(TDI)$	TDI input setup time	-	1.5	-	-	
$t_{ih}(TDI)$	TDI input hold time	-	1	-	-	
$t_{ov}(TDO)$	TDO output valid time	$2.7V < V_{DD} < 3.6V$	-	8	13.5	-
		$1.62 < V_{DD} < 3.6V$	-	8	18	-
$t_{oh}(TDO)$	TDO output hold time	-	7	-	-	

Table 119. Dynamics SWD characteristics:

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
F_{pp}	SWCLK clock frequency	$2.7V < V_{DD} < 3.6V$	-	-	71	MHz
$1/t_c(SWCLK)$		$1.62 < V_{DD} < 3.6V$	-	-	52.5	
$t_{is}(SWDIO)$	SWDIO input setup time	-	2.5	-	-	ns
$t_{ih}(SWDIO)$	SWDIO input hold time	-	1	-	-	
$t_{ov}(SWDIO)$	SWDIO output valid time	$2.7V < V_{DD} < 3.6V$	-	8.5	14	ns
		$1.62 < V_{DD} < 3.6V$	-	8.5	19	
$t_{oh}(SWDIO)$	SWDIO output hold time	-	8	-	-	

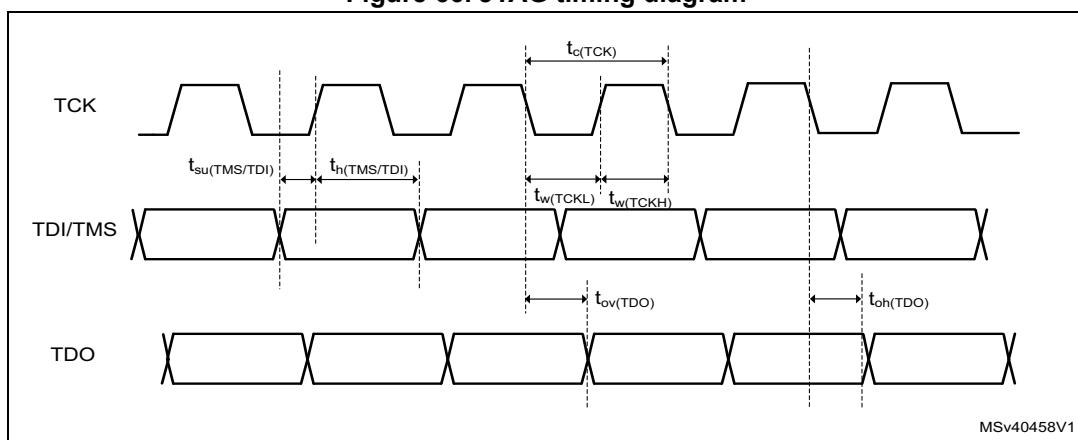
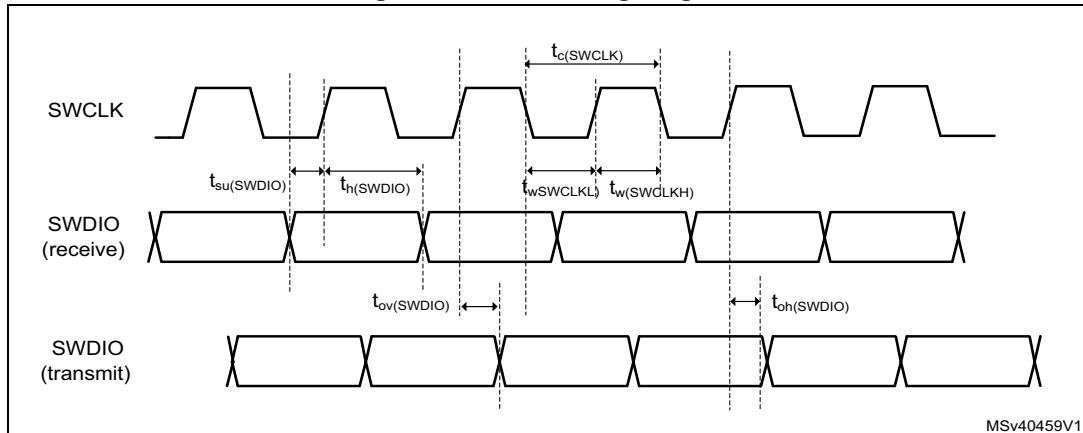
Figure 66. JTAG timing diagram

Figure 67. SWD timing diagram



7 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at www.st.com. ECOPACK is an ST trademark.

7.1 Device marking

Refer to technical note “Reference device marking schematics for STM32 microcontrollers and microprocessors” (TN1433) available on www.st.com, for the location of pin 1 / ball A1 as well as the location and orientation of the marking areas versus pin 1 / ball A1.

Parts marked as “ES”, “E” or accompanied by an engineering sample notification letter, are not yet qualified and therefore not approved for use in production. ST is not responsible for any consequences resulting from such use. In no event will ST be liable for the customer using any of these engineering samples in production. ST’s Quality department must be contacted prior to any decision to use these engineering samples to run a qualification activity.

A WLCSP simplified marking example (if any) is provided in the corresponding package information subsection.

7.2 LQFP144 package information (1A)

This LQFP is a 144-pin, 20 x 20 mm low-profile quad flat package.

Note: See *list of notes in the notes section*.

Figure 68. LQFP144 - Outline⁽¹⁵⁾

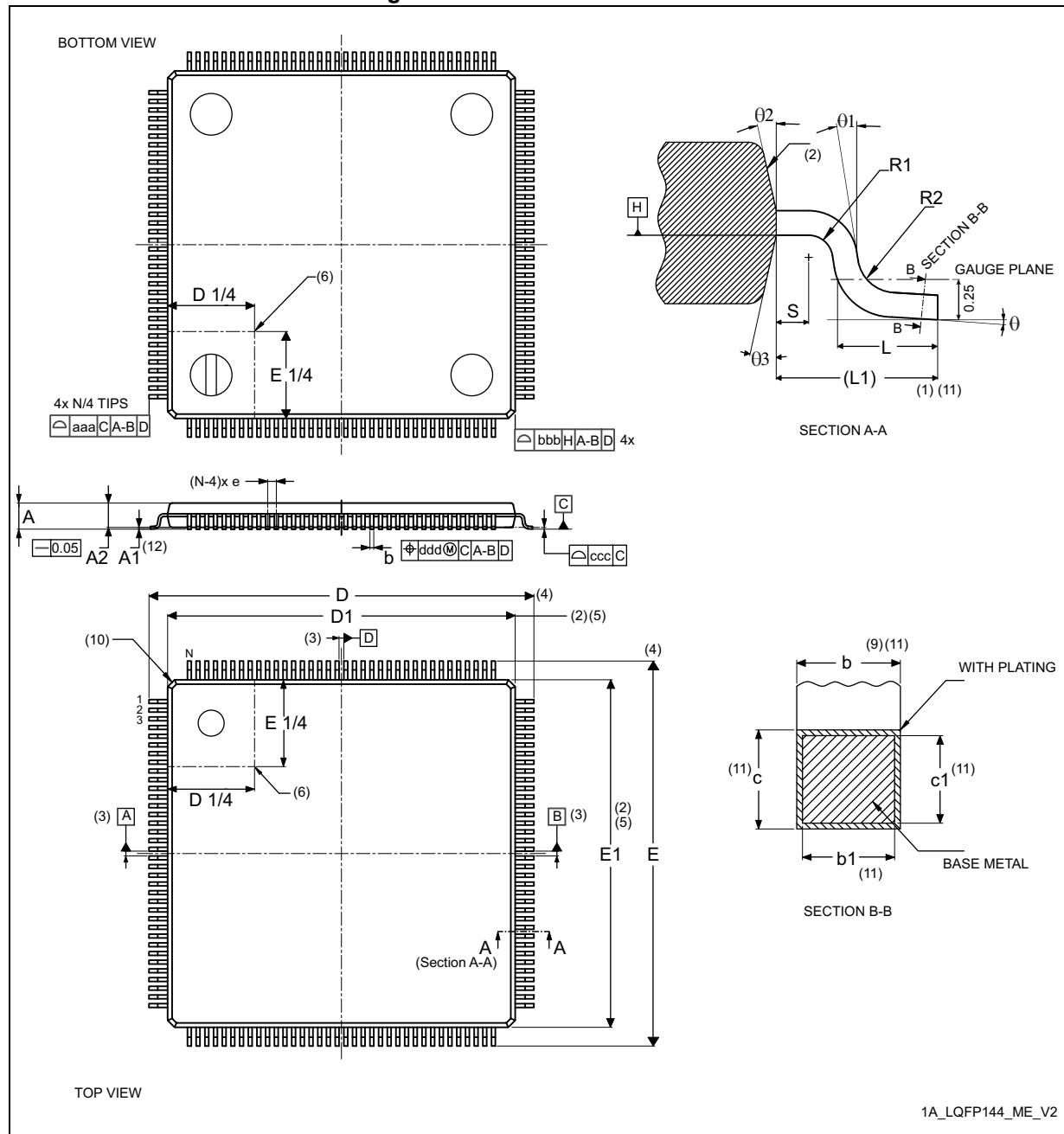
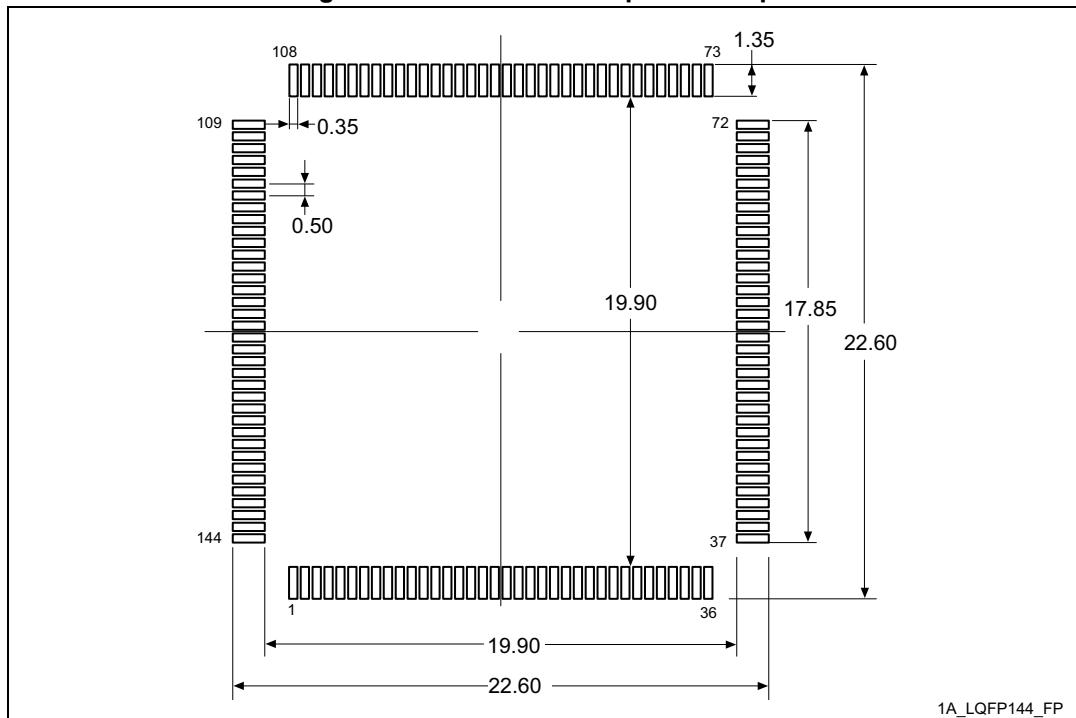


Table 120. LQFP144 - Mechanical data

Symbol	millimeters			inches ⁽¹⁴⁾		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.60	-	-	0.0630
A1 ⁽¹²⁾	0.05	-	0.15	0.0020	-	0.0059
A2	1.35	1.40	1.45	0.0531	0.0551	0.0571
b ⁽⁹⁾⁽¹¹⁾	0.17	0.22	0.27	0.0067	0.0087	0.0106
b1 ⁽¹¹⁾	0.17	0.20	0.23	0.0067	0.0079	0.0090
c ⁽¹¹⁾	0.09	-	0.20	0.0035	-	0.0079
c1 ⁽¹¹⁾	0.09	-	0.16	0.0035	-	0.0063
D ⁽⁴⁾	22.00 BSC			0.8661 BSC		
D1 ⁽²⁾⁽⁵⁾	20.00 BSC			0.7874 BSC		
E ⁽⁴⁾	22.00 BSC			0.8661 BSC		
E1 ⁽²⁾⁽⁵⁾	20.00 BSC			0.7874 BSC		
e	0.50 BSC			0.0197 BSC		
L	0.45	0.60	0.75	0.0177	0.0236	0.0295
L1	1.00 REF			0.0394 REF		
N ⁽¹³⁾	144					
θ	0°	3.5°	7°	0°	3.5°	7°
θ1	0°	-	-	0°	-	-
θ2	10°	12°	14°	10°	12°	14°
θ3	10°	12°	14°	10°	12°	14°
R1	0.08	-	-	0.0031	-	-
R2	0.08	-	0.20	0.0031	-	0.0079
S	0.20	-	-	0.0079	-	-
aaa	0.20			0.0079		
bbb	0.20			0.0079		
ccc	0.08			0.0031		
ddd	0.08			0.0031		

Notes:

1. Dimensioning and tolerancing schemes conform to ASME Y14.5M-1994.
2. The Top package body size may be smaller than the bottom package size by as much as 0.15 mm.
3. Datums A-B and D to be determined at datum plane H.
4. To be determined at seating datum plane C.
5. Dimensions D1 and E1 do not include mold flash or protrusions. Allowable mold flash or protrusions is "0.25 mm" per side. D1 and E1 are Maximum plastic body size dimensions including mold mismatch.
6. Details of pin 1 identifier are optional but must be located within the zone indicated.
7. All dimensions are in millimeters.
8. No intrusion allowed inwards the leads.
9. Dimension "b" does not include dambar protrusion. Allowable dambar protrusion shall not cause the lead width to exceed the maximum "b" dimension by more than 0.08 mm. Dambar cannot be located on the lower radius or the foot. Minimum space between protrusion and an adjacent lead is 0.07 mm for 0.4 mm and 0.5 mm pitch packages.
10. Exact shape of each corner is optional.
11. These dimensions apply to the flat section of the lead between 0.10 mm and 0.25 mm from the lead tip.
12. A1 is defined as the distance from the seating plane to the lowest point on the package body.
13. "N" is the number of terminal positions for the specified body size.
14. Values in inches are converted from mm and rounded to 4 decimal digits.
15. Drawing is not to scale.

Figure 69. LQFP144 - Footprint example

1. Dimensions are expressed in millimeters.

7.3 LQFP176 package information (1T)

This LQFP is a 176-pin, 24 x 24 mm, 0.5 mm pitch, low profile quad flat package.

Note: See *list of notes in the notes section*.

Figure 70. LQFP176 - Outline⁽¹⁵⁾

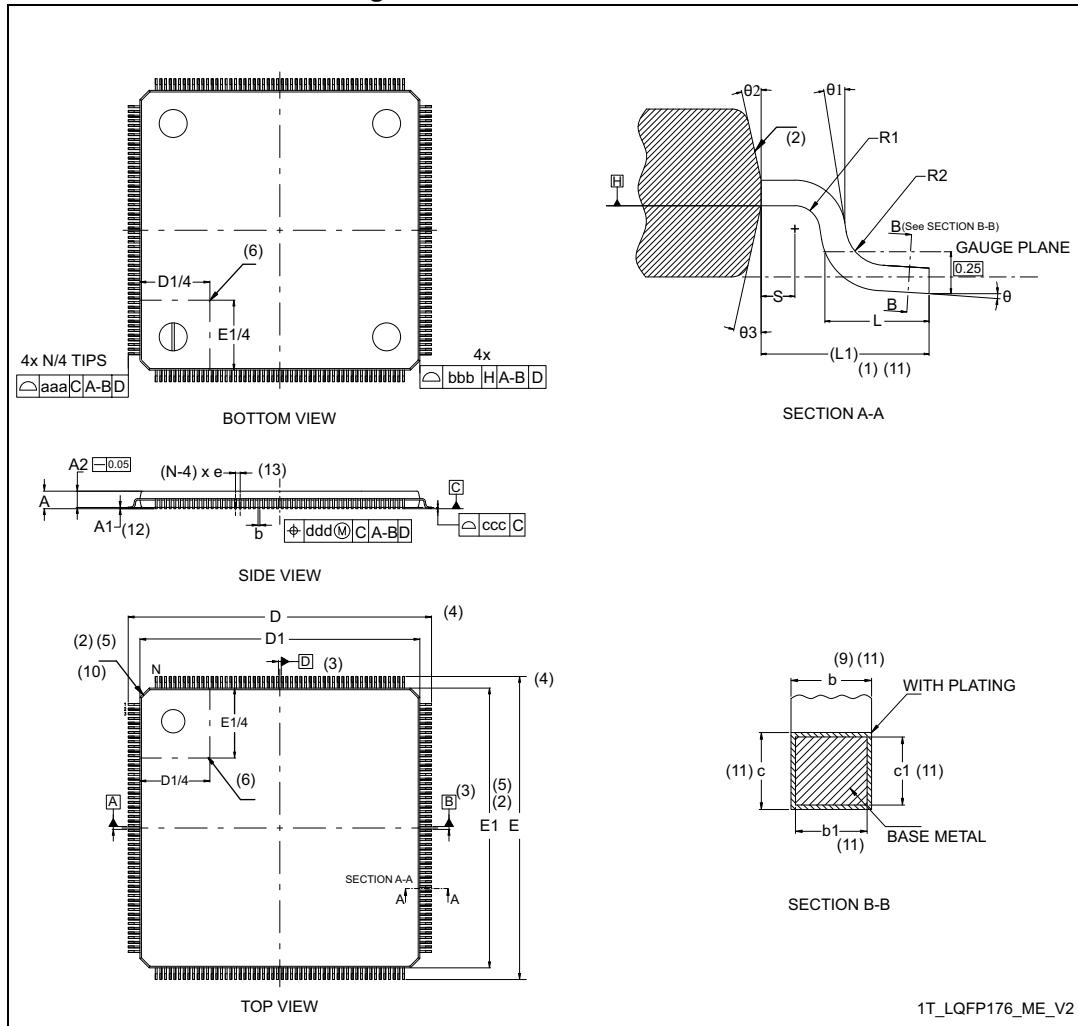
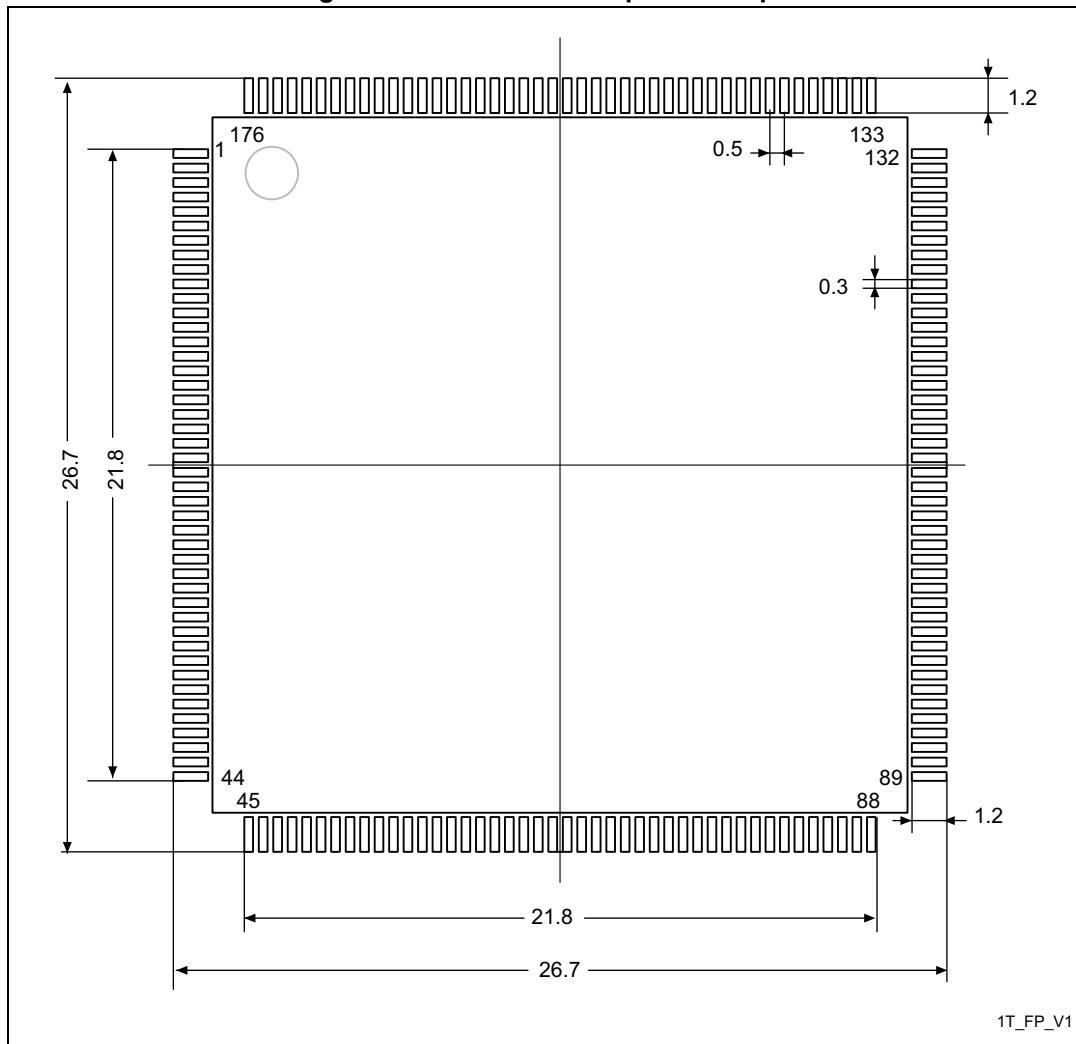


Table 121. LQFP176 - Mechanical data

Symbol	millimeters			inches ⁽¹⁴⁾		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.600	-	-	0.0630
A1 ⁽¹²⁾	0.050	-	0.150	0.0020	-	0.0059
A2	1.350	1.400	1.450	0.0531	0.0551	0.0571
b ⁽⁹⁾⁽¹¹⁾	0.170	0.220	0.270	0.0067	0.0087	0.0106
b1 ⁽¹¹⁾	0.170	0.200	0.230	0.0067	0.0079	0.0091
c ⁽¹¹⁾	0.090	-	0.200	0.0035	-	0.0079
c1 ⁽¹¹⁾	0.090	-	0.160	0.0035	-	0.063
D ⁽⁴⁾	26.000			1.0236		
D1 ⁽²⁾⁽⁵⁾	24.000			0.9449		
E ⁽⁴⁾	26.000			0.0197		
E1 ⁽²⁾⁽⁵⁾	24.000			0.9449		
e	0.500			0.1970		
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1 ⁽¹⁾⁽¹¹⁾	1			0.0394 REF		
N ⁽¹³⁾	176					
θ	0°	3.5°	7°	0°	3.5°	7°
θ1	0°	-	-	0°	-	-
θ2	10°	12°	14°	10°	12°	14°
θ3	10°	12°	14°	10°	12°	14°
R1	0.080	-	-	0.0031	-	-
R2	0.080	-	0.200	0.0031	-	0.0079
S	0.200	-	-	0.0079	-	-
aaa ⁽¹⁾	0.200			0.0079		
bbb ⁽¹⁾	0.200			0.0079		
ccc ⁽¹⁾	0.080			0.0031		
ddd ⁽¹⁾	0.080			0.0031		

Notes:

1. Dimensioning and tolerancing schemes conform to ASME Y14.5M-1994.
2. The Top package body size may be smaller than the bottom package size by as much as 0.15 mm.
3. Datums A-B and D to be determined at datum plane H.
4. To be determined at seating datum plane C.
5. Dimensions D1 and E1 do not include mold flash or protrusions. Allowable mold flash or protrusions is "0.25 mm" per side. D1 and E1 are Maximum plastic body size dimensions including mold mismatch.
6. Details of pin 1 identifier are optional but must be located within the zone indicated.
7. All dimensions are in millimeters.
8. No intrusion allowed inwards the leads.
9. Dimension "b" does not include dambar protrusion. Allowable dambar protrusion shall not cause the lead width to exceed the maximum "b" dimension by more than 0.08 mm. Dambar cannot be located on the lower radius or the foot. Minimum space between protrusion and an adjacent lead is 0.07 mm for 0.4 mm and 0.5 mm pitch packages.
10. Exact shape of each corner is optional.
11. These dimensions apply to the flat section of the lead between 0.10 mm and 0.25 mm from the lead tip.
12. A1 is defined as the distance from the seating plane to the lowest point on the package body.
13. "N" is the number of terminal positions for the specified body size.
14. Values in inches are converted from mm and rounded to 4 decimal digits.
15. Drawing is not to scale.

Figure 71. LQFP176 - Footprint example

1. Dimensions are expressed in millimeters.

7.4 LQFP208 package information (UH)

This LQFP is a 208-pin, 28 x 28 mm low-profile quad flat package.

Note: See *list of notes in the notes section*.

Figure 72. LQFP208 - Outline⁽¹⁵⁾

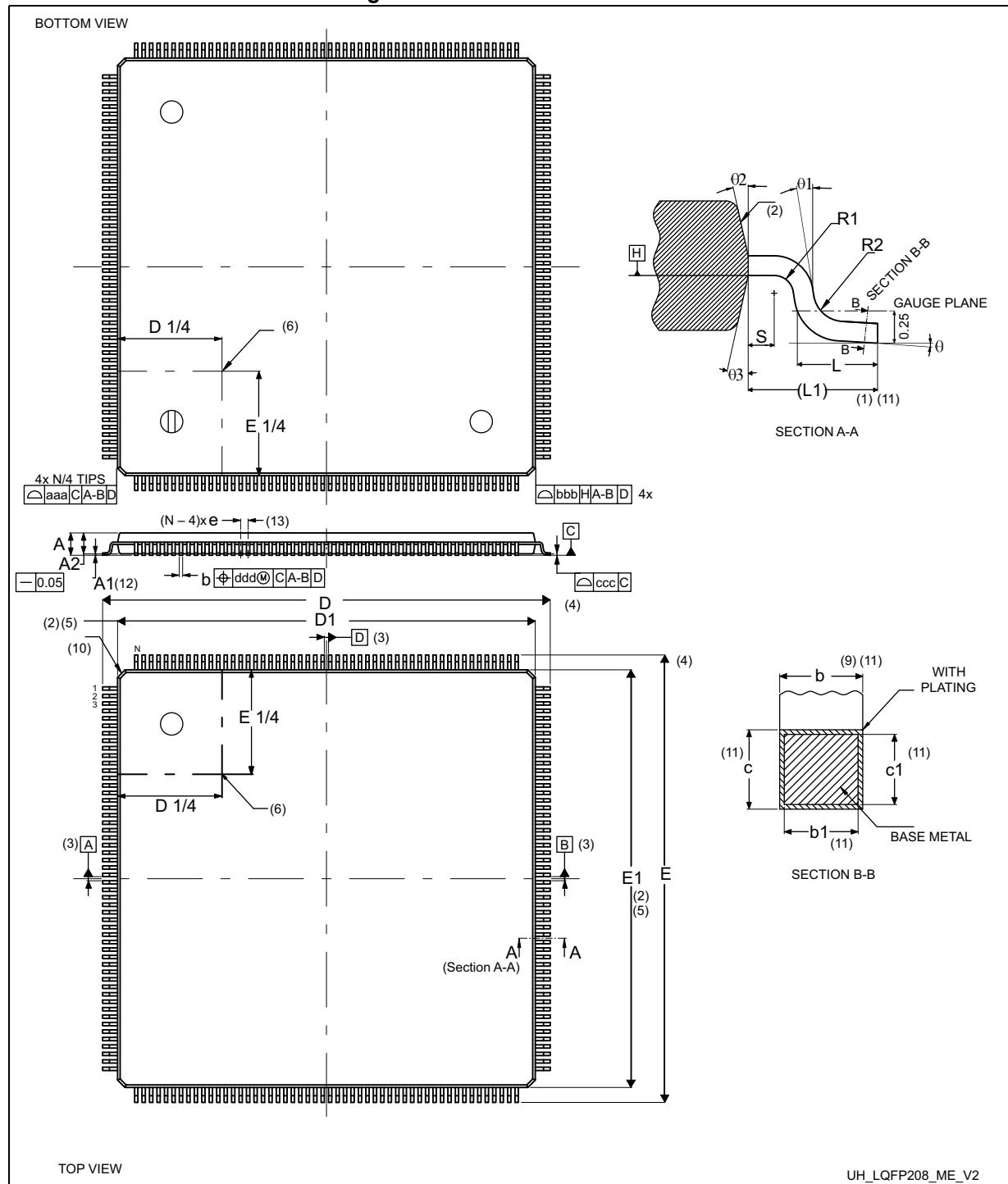
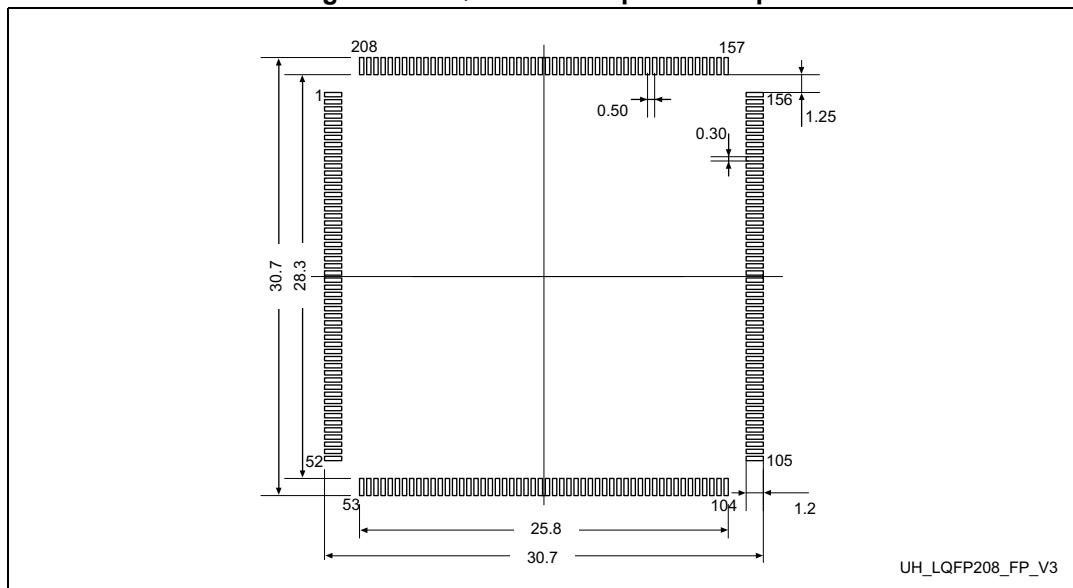


Table 122. LQFP208 - Mechanical data

Symbol	millimeters			inches ⁽¹⁵⁾		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.60	-	-	0.0630
A1 ⁽¹²⁾	0.05	-	0.15	0.0020	-	0.0059
A2	1.35	1.40	1.45	0.0531	0.0551	0.0571
b ⁽⁹⁾⁽¹¹⁾	0.17	0.22	0.27	0.0067	0.0087	0.0106
b1 ⁽¹¹⁾	0.17	0.20	0.23	0.0067	0.0079	0.0091
c ⁽¹¹⁾	0.09	-	0.20	0.0035	-	0.0079
c1 ⁽¹¹⁾	0.09	-	0.16	0.0035	-	0.0063
D ⁽⁴⁾	30.00 BSC			1.1732 BSC		
D1 ⁽²⁾⁽⁵⁾	28.00 BSC			1.0945 BSC		
E ⁽⁴⁾	30.00 BSC			1.1732 BSC		
E1 ⁽²⁾⁽⁵⁾	28.00 BSC			1.0945 BSC		
e	0.50 BSC			0.0197 BSC		
L	0.45	0.60	0.75	0.0177	0.0236	0.0295
L1	1.00 REF			0.0394 REF		
N ⁽¹³⁾	208					
θ	0°	3.5°	7°	0°	3.5°	7°
θ1	0°	-	-	0°	-	-
θ2	10°	12°	14°	10°	12°	14°
θ3	10°	12°	14°	10°	12°	14°
R1	0.08	-	-	0.0031	-	-
R2	0.08	-	0.20	0.0031	-	0.0079
S	0.20	-	-	0.0079	-	-
aaa ⁽¹⁾⁽⁷⁾	0.20			0.0079		
bbb ⁽¹⁾⁽⁷⁾	0.20			0.0079		
ccc ⁽¹⁾⁽⁷⁾	0.08			0.0031		
ddd ⁽¹⁾⁽⁷⁾	0.08			0.0031		

Notes:

1. Dimensioning and tolerancing schemes conform to ASME Y14.5M-1994.
2. The Top package body size may be smaller than the bottom package size by as much as 0.15 mm.
3. Datums A-B and D to be determined at datum plane H.
4. To be determined at seating datum plane C.
5. Dimensions D1 and E1 do not include mold flash or protrusions. Allowable mold flash or protrusions is "0.25 mm" per side. D1 and E1 are Maximum plastic body size dimensions including mold mismatch.
6. Details of pin 1 identifier are optional but must be located within the zone indicated.
7. All dimensions are in millimeters.
8. No intrusion allowed inwards the leads.
9. Dimension "b" does not include dambar protrusion. Allowable dambar protrusion shall not cause the lead width to exceed the maximum "b" dimension by more than 0.08 mm. Dambar cannot be located on the lower radius or the foot. Minimum space between protrusion and an adjacent lead is 0.07 mm for 0.4 mm and 0.5 mm pitch packages.
10. Exact shape of each corner is optional.
11. These dimensions apply to the flat section of the lead between 0.10 mm and 0.25 mm from the lead tip.
12. A1 is defined as the distance from the seating plane to the lowest point on the package body.
13. "N" is the number of terminal positions for the specified body size.
14. Values in inches are converted from mm and rounded to 4 decimal digits.
15. Drawing is not to scale.

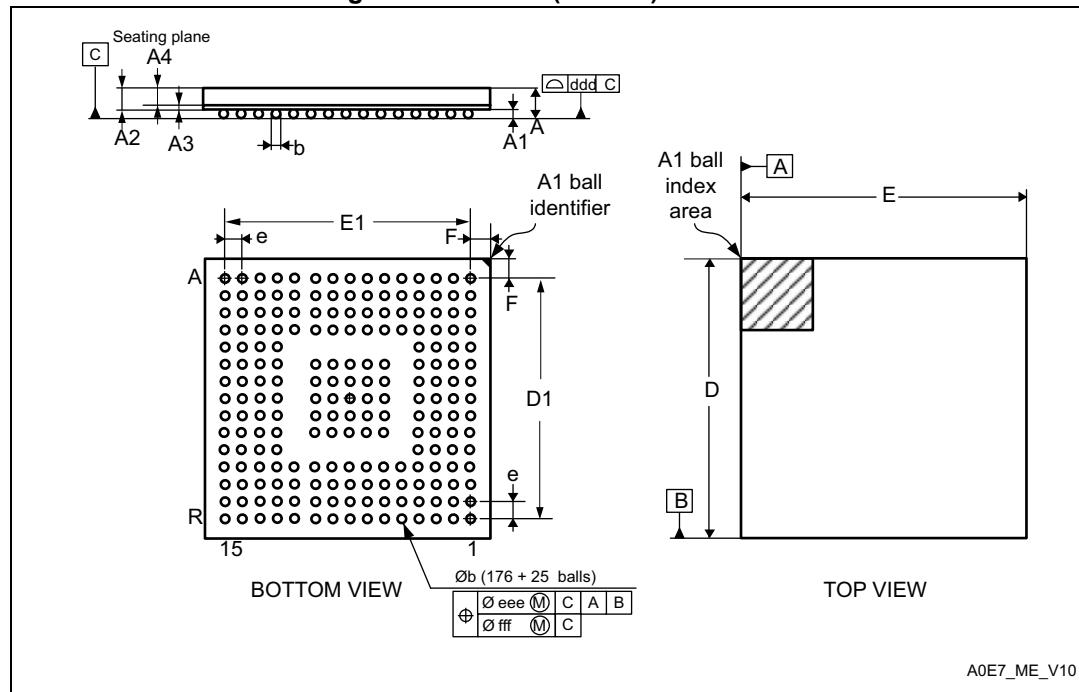
Figure 73. LQFP208 - footprint example

1. Dimensions are expressed in millimeters.

7.5 UFBGA(176+25) package information (A0E7)

This UFBGA is a 176+25-ball, 10 x 10 mm, 0.65 mm pitch, ultra fine pitch ball grid array package.

Figure 74. UFBGA(176+25) - Outline



1. Drawing is not to scale.

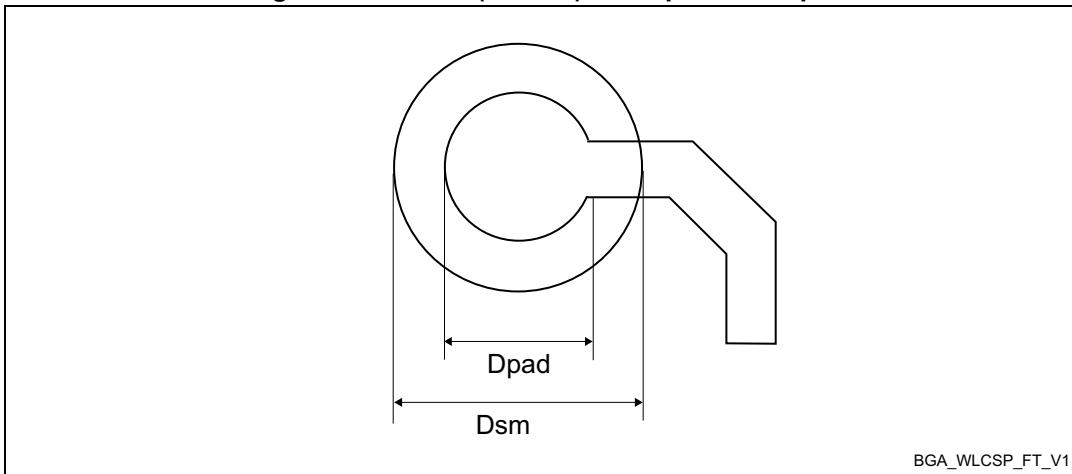
Table 123. UFBGA(176+25) - Mechanical data

Symbol	millimeters			inches ⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	-	-	0.600	-	-	0.0236
A1	0.050	0.080	0.110	0.0020	0.0031	0.0043
A2	-	0.450	-	-	0.0177	-
A3	-	0.130	-	-	0.0051	-
A4	-	0.320	-	-	0.0126	-
b	0.240	0.290	0.340	0.0094	0.0114	0.0134
D	9.850	10.000	10.150	0.3878	0.3937	0.3996
D1	-	9.100	-	-	0.3583	-
E	9.850	10.000	10.150	0.3878	0.3937	0.3996
E1	-	9.100	-	-	0.3583	-
e	-	0.650	-	-	0.0256	-
F	-	0.450	-	-	0.0177	-
ddd	-	-	0.080	-	-	0.0031

Table 123. UFBGA(176+25) - Mechanical data (continued)

Symbol	millimeters			inches⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
eee	-	-	0.150	-	-	0.0059
fff	-	-	0.050	-	-	0.0020

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 75. UFBGA(176+25) - Footprint example**Table 124. UFBGA(176+25) - Example of PCB design rules (0.65 mm pitch BGA)**

Dimension	Values
Pitch	0.65 mm
Dpad	0.300 mm
Dsm	0.400 mm typ. (depends on the soldermask registration tolerance)
Stencil opening	0.300 mm
Stencil thickness	Between 0.100 mm and 0.125 mm
Pad trace width	0.100 mm

7.6 TFBGA240+25 package information (A07U)

This TFBGA is a 240+25-ball, 14 x 14 mm, 0.8 mm pitch, thin profile fine pitch ball grid array package.

Note: [Figure 76](#) and [Figure 77](#) are not to scale.

Refer to the notes section for the list of notes on [Figure 76](#), [Table 125](#), and [Table 126](#).

Figure 76. TFBGA240+25 - Outline

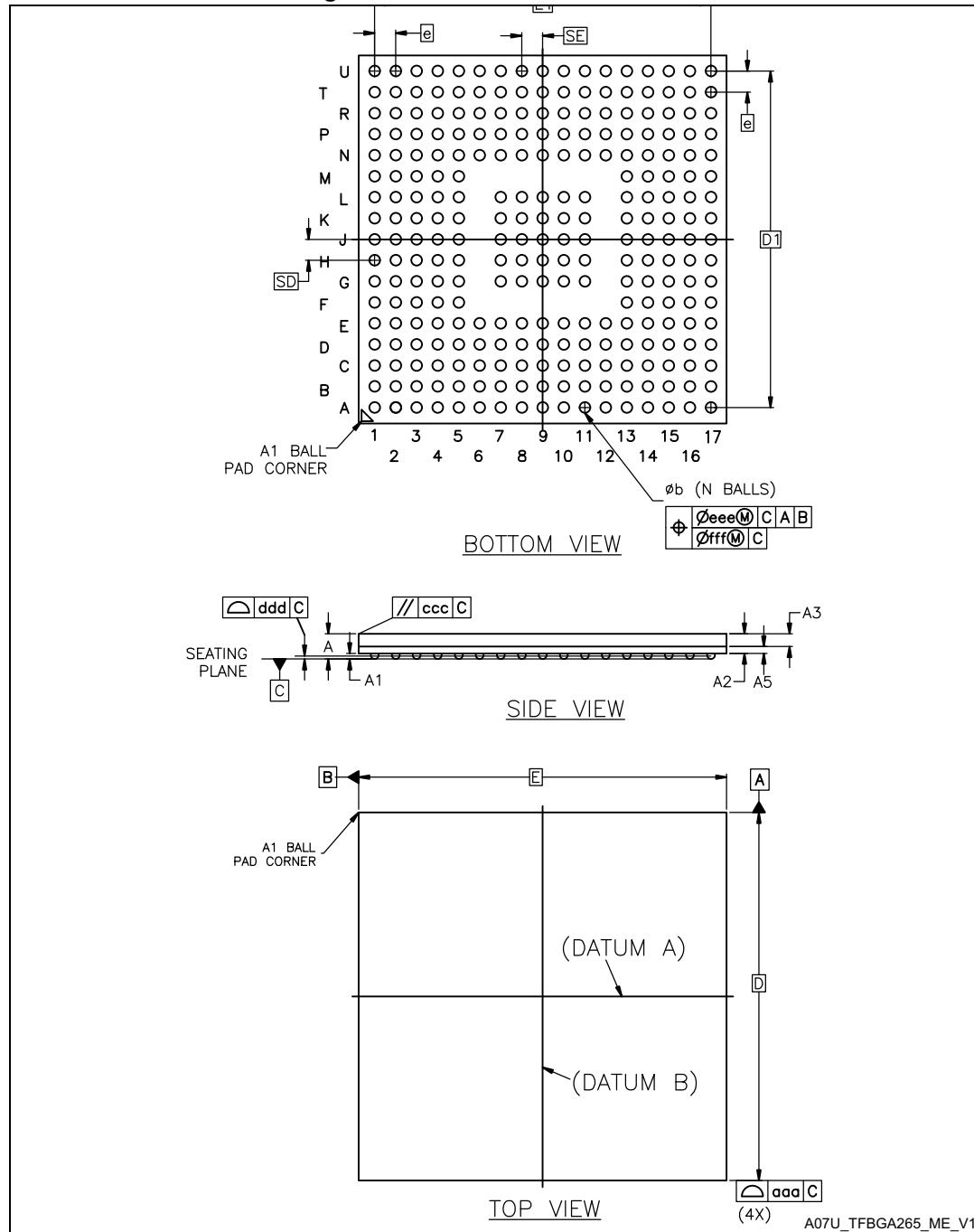


Table 125. TFBGA240+25 - Mechanical data

Symbol	Millimeters			Inches ⁽²⁾		
	Min	Typ	Max	Min	Typ	Max
A ⁽³⁾	-	-	1.200	-	-	0.0472
A1 ⁽⁴⁾	0.150	-	-	0.0059	-	-
A2	-	0.760	-	-	0.0299	-
b ⁽⁶⁾	0.320	0.400	0.450	0.0126	0.0157	0.0177
D	14.000 BSC ⁽⁷⁾			0.5512 BSC		
D1	12.800 BSC			0.5039 BSC		
E	14.000 BSC			0.5512 BSC		
E1	12.800 BSC			0.0315 BSC		
e ⁽¹⁰⁾	0.800 BSC			0.0315 BSC		
N ⁽¹¹⁾	265			265		
SD ⁽¹²⁾	0.800 BSC			0.0315 BSC		
SE ⁽¹²⁾	0.800 BSC			0.0315 BSC		

Table 126. TFBGA240+25 - Tolerance of form and position

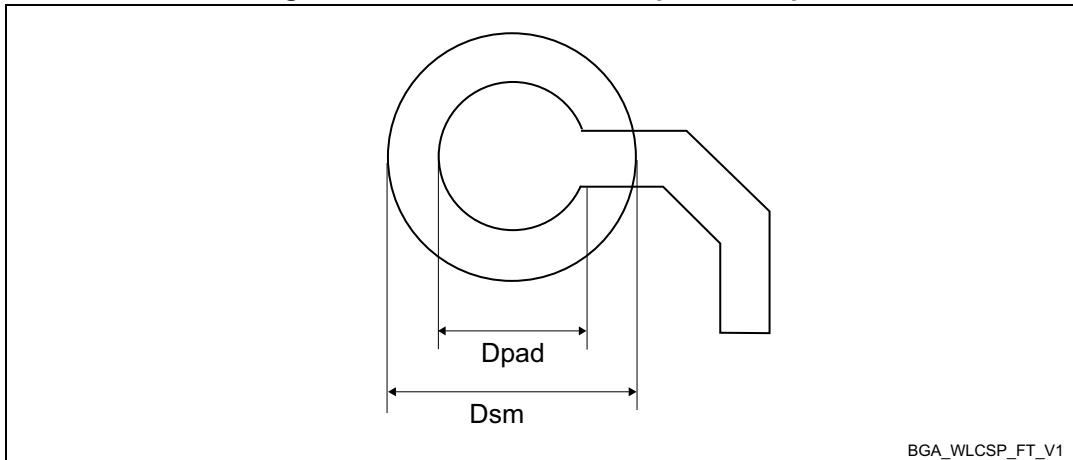
Symbol	Millimeters			Inches ⁽²⁾		
	Min	Typ	Max	Min	Typ	Max
aaa ⁽¹³⁾	0.150			0.0059		
ccc ⁽¹³⁾	0.200			0.0079		
ddd ⁽¹³⁾	0.100			0.0039		
eee ⁽¹³⁾	0.150			0.0059		
fff ⁽¹³⁾	0.080			0.0031		

Notes:

1. Dimensioning and tolerancing schemes conform to ASME Y14.5M-1994.
2. Values in inches are converted from millimeters and rounded to four decimal digits.
3. The profile height, A, is the distance from the seating plane to the highest point on the package. It is measured perpendicular to the seating plane.
4. A1 is defined as the distance from the seating plane to the lowest point on the package body.
5. TFBGA stands for thin profile fine pitch ball grid array: $1.00 \text{ mm} < A \leq 1.20 \text{ mm}$ / fine pitch $e < 1.00 \text{ mm}$.
6. Dimension b is measured at the maximum diameter of the terminal (ball) in a plane parallel to primary datum C.
7. BSC stands for basic dimensions. It corresponds to the nominal value and has no tolerance. For tolerances, refer to [Table 126](#).
8. Primary datum C is defined by the plane established by the contact points of three or more solder balls that support the device when it is placed on top of a planar surface.
9. The terminal (ball) A1 corner must be identified on the top surface of the package by using a corner chamfer, ink or metallized markings, or other feature of package body or integral heat slug. A distinguishing feature is allowed on the bottom surface of the package to identify the terminal A1 corner. Exact shape of each corner is optional.
10. e represents the solder ball grid pitch.
11. N represents the total number of balls on the BGA.
12. Basic dimensions SD and SE are defined with respect to datums A and B. They define the position of the center ball(s) in the outer row or column of a fully populated matrix.
13. For the tolerance of form and position definitions, see the following table.

Table 127. Tolerance of form and position definitions

Symbol	Definition
aaa	The profile tolerance controls the location and orientation of the sides of the package.
ccc	The parallelism tolerance controls the orientation of the top surface of the package with respect to the seating plane, datum C.
ddd	The profile tolerance controls the location of the crowns of the balls with respect to datum C (coplanarity).
eee	The tolerance of position that controls the location of the pattern of balls with respect to datum's A and B.
fff	The tolerance of position that controls the location of the balls within the matrix with respect to each other.

Figure 77. TFBGA240+25 - Footprint example**Table 128. TFBGA240+25 - Example of PCB design rules**

Dimension	Values
Pitch	0.8 mm
Dpad	0.400 mm
Dsm	0.470 mm typical (depends on solder mask registration tolerance)
Stencil opening	0.400 mm
Stencil thickness	Between 0.100 mm and 0.125 mm

7.7 Thermal characteristics

The maximum chip-junction temperature, T_J max, in degrees Celsius, may be calculated using the following equation:

$$T_J \text{ max} = T_A \text{ max} + (P_D \text{ max} \times \Theta_{JA})$$

Where:

- T_A max is the maximum ambient temperature in $^{\circ}\text{C}$,
- Θ_{JA} is the package junction-to-ambient thermal resistance, in $^{\circ}\text{C}/\text{W}$,
- P_D max is the sum of P_{INT} max and $P_{I/O}$ max (P_D max = P_{INT} max + $P_{I/O}$ max),
- P_{INT} max is the product of I_{DD} and V_{DD} , expressed in Watts. This is the maximum chip internal power.

$P_{I/O}$ max represents the maximum power dissipation on output pins where:

$$P_{I/O} \text{ max} = \sum (V_{OL} \times I_{OL}) + \sum ((V_{DD} - V_{OH}) \times I_{OH}),$$

taking into account the actual V_{OL} / I_{OL} and V_{OH} / I_{OH} of the I/Os at low and high level in the application.

Table 129. Thermal characteristics

Symbol	Definition	Parameter	Value	Unit
Θ_{JA}	Thermal resistance junction-ambient	Thermal resistance junction-ambient LQFP144 - 20 x 20 mm /0.5 mm pitch	43.7	°C/W
		Thermal resistance junction-ambient LQFP176 - 24 x 24 mm /0.5 mm pitch	43.0	
		Thermal resistance junction-ambient LQFP208 - 28 x 28 mm /0.5 mm pitch	42.4	
		Thermal resistance junction-ambient UFBGA176+25 - 10 x 10 mm /0.65 mm pitch	37.4	
		Thermal resistance junction-ambient TFBGA240+25 - 14 x 14 mm / 0.8 mm pitch	36.6	
Θ_{JC}	Thermal resistance junction-case	Thermal resistance junction-ambient LQFP144 - 20 x 20 mm /0.5 mm pitch	11.3	°C/W
		Thermal resistance junction-ambient LQFP176 - 24 x 24 mm /0.5 mm pitch	11.2	
		Thermal resistance junction-ambient LQFP208 - 28 x 28 mm /0.5 mm pitch	11.1	
		Thermal resistance junction-ambient UFBGA176+25 - 10 x 10 mm /0.65 mm pitch	23.9	
		Thermal resistance junction-ambient TFBGA240+25 - 14 x 14 mm / 0.8 mm pitch	7.4	
Θ_{JB}	Thermal resistance junction-board	Thermal resistance junction-ambient LQFP144 - 20 x 20 mm /0.5 mm pitch	38.3	°C/W
		Thermal resistance junction-ambient LQFP176 - 24 x 24 mm /0.5 mm pitch	39.4	
		Thermal resistance junction-ambient LQFP208 - 28 x 28 mm /0.5 mm pitch	40.3	
		Thermal resistance junction-ambient UFBGA176+25 - 10 x 10 mm /0.65 mm pitch	19.3	
		Thermal resistance junction-ambient TFBGA240+25 - 14 x 14 mm / 0.8 mm pitch	24.3	

7.7.1 Reference documents

- JESD51-2 Integrated Circuits Thermal Test Method Environment Conditions - Natural Convection (Still Air). Available from www.jedec.org.
- For information on thermal management, refer to application note “Guidelines for thermal management on STM32 applications” (AN5036) available from www.st.com.

8 Ordering information

Example:

Device family

STM32 = Arm-based 32-bit microcontroller

Product type

H = High performance

Device subfamily

755 = STM32H7x5 High performance and industrial product line with cryptographic accelerator

Pin count

Z = 144 pins

I = 176 pins/176+25 balls

B = 208 pins

X = 240+25 balls

Flash memory size

I = 2 Mbytes

Package

T = LQFP ECOPACK2

K = UFBGA pitch 0.65 mm ECOPACK2

H = TFBGA ECOPACK2

Temperature range

3 = Extended temperature range: -40 to 125 °C

6 = -40 to 85 °C

Option

A = Advanced mission profile (VOS1, 480 MHz)

Packing

TR = tape and reel

No character = tray or tube

1. The tape and reel packing is not available on all packages.

For a list of available options (such as speed and package) or for further information on any aspect of this device, please contact your nearest ST sales office.

9 Important security notice

The STMicroelectronics group of companies (ST) places a high value on product security, which is why the ST product(s) identified in this documentation may be certified by various security certification bodies and/or may implement our own security measures as set forth herein. However, no level of security certification and/or built-in security measures can guarantee that ST products are resistant to all forms of attacks. As such, it is the responsibility of each of ST's customers to determine if the level of security provided in an ST product meets the customer needs both in relation to the ST product alone, as well as when combined with other components and/or software for the customer end product or application. In particular, take note that:

- ST products may have been certified by one or more security certification bodies, such as Platform Security Architecture (www.psacertified.org) and/or Security Evaluation standard for IoT Platforms (www.trustcb.com). For details concerning whether the ST product(s) referenced herein have received security certification along with the level and current status of such certification, either visit the relevant certification standards website or go to the relevant product page on www.st.com for the most up to date information. As the status and/or level of security certification for an ST product can change from time to time, customers should re-check security certification status/level as needed. If an ST product is not shown to be certified under a particular security standard, customers should not assume it is certified.
- Certification bodies have the right to evaluate, grant and revoke security certification in relation to ST products. These certification bodies are therefore independently responsible for granting or revoking security certification for an ST product, and ST does not take any responsibility for mistakes, evaluations, assessments, testing, or other activity carried out by the certification body with respect to any ST product.
- Industry-based cryptographic algorithms (such as AES, DES, or MD5) and other open standard technologies which may be used in conjunction with an ST product are based on standards which were not developed by ST. ST does not take responsibility for any flaws in such cryptographic algorithms or open technologies or for any methods which have been or may be developed to bypass, decrypt or crack such algorithms or technologies.
- While robust security testing may be done, no level of certification can absolutely guarantee protections against all attacks, including, for example, against advanced attacks which have not been tested for, against new or unidentified forms of attack, or against any form of attack when using an ST product outside of its specification or intended use, or in conjunction with other components or software which are used by customer to create their end product or application. ST is not responsible for resistance against such attacks. As such, regardless of the incorporated security features and/or any information or support that may be provided by ST, each customer is solely responsible for determining if the level of attacks tested for meets their needs, both in relation to the ST product alone and when incorporated into a customer end product or application.
- All security features of ST products (inclusive of any hardware, software, documentation, and the like), including but not limited to any enhanced security features added by ST, are provided on an "AS IS" BASIS. AS SUCH, TO THE EXTENT PERMITTED BY APPLICABLE LAW, ST DISCLAIMS ALL WARRANTIES, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE, unless the applicable written and signed contract terms specifically provide otherwise.

10 Revision history

Table 130. Document revision history

Date	Revision	Changes
16-May-2019	1	<p>Initial release.</p>
02-Feb-2023	2	<p>Added reference to errata sheet ES0392 in Section 1: Introduction.</p> <p>Figure 1: STM32H750xB block diagram: changed APB1 and APB2 maximum frequency to 120 MHz, and WKUP[5:0] to WKUP[6:1].</p> <p>Added note 1 to Table 2: STM32H755xl features and peripheral counts (added information on SDRAM availability)</p> <p>Updated Figure 5: STM32H755xl bus matrix.</p> <p>Modified Section 3.5.1: Power supply scheme</p> <p>Modified note on Section 3.5.3: Voltage regulator (SMPS step-down converter and LDO)</p> <p>Modified note in Section 3.5.3: Voltage regulator (SMPS step-down converter and LDO)</p> <p>Updated Section 3.24: Digital camera interface (DCMI) (modified supported format)</p> <p>Added Full-duplex mode in Section 3.34: Serial peripheral interfaces (SPI)/integrated interchip sound interfaces (I2S).</p> <p>Updated Section 3.27: True random number generator (RNG).</p> <p>Updated number of microphones that can be supported by the SAI in Section 3.35: Serial audio interfaces (SAI).</p> <p>Removed FDCAN1_RXFD_MODE, FDCAN1_TXFD_MODE, FDCAN2_RXFD_MODE and FDCAN2_TXFD_MODE functions from Table 8: STM32H750xB pin-ball definition and all alternate function tables.</p> <ul style="list-style-type: none"> – Additional modifications made on Table 8: STM32H750xB pin-ball definition: Added note to VDD50USB. – Added note to PB12 and PB13. – Change PB1 I/O structure to TT_A. – Replaced PI8 WKUP3 additional function by WKUP2. – Replaced PC13 WKUP2 additional function by WKUP3. – For TFBGA24+25, extra VDD signals replaced by '-'. <p>Updated Figure 13: Power supply scheme.</p> <p>Updated Section 6.2: Absolute maximum ratings introduction to device mission profile.</p> <p>Updated V_{CORE} max value in Table 13: General operating conditions</p> <p>Changed f_{CPU2} to 100 MHz in Table 13: General operating conditions.</p> <p>Replaced Min V_{DD} by Min V_{DDLDO} in Table 14: Supply voltage and maximum frequency configuration.</p> <p>Replaced VBOR0 with VBOR0/POR/PDR in Table 19: Reset and power control block characteristics</p> <p>Updated section I/O dynamic current consumption and I/O static current consumption.</p> <p>Updated Table 41: High-speed external user clock characteristics.</p> <p>Removed note 1 from Table 33: Typical and maximum current consumption in Stop, LDO regulator ON and Table 35: Typical and maximum current consumption in Sleep mode, LDO regulator ON.</p> <p>In Table 52: Flash memory programming: removed reference to single bank configuration in title and added $t_{ERASE128KB}$ typical and maximum values.</p>

Table 130. Document revision history

Date	Revision	Changes
02-Feb-2023	2 (continued)	<p>Modified Table 55: EMI characteristics for fHSE = 8 MHz and fCPU = 400 MHz. Added reference to AN4899 in Section 6.3.16: I/O port characteristics. Changed capacitance value for speed 10 and t_r/t_f, and speed for 11 and $t_r/t_f/F_{max}$ Table 63: Output timing characteristics (HSLV ON). Updated $t_{su(DV-CLKH)}/t_{h(DV-CLKH)}$ and $t_{su(NWAIT-CLKH)}/t_{h(NWAIT-CLKH)}$ in Table 73: Synchronous multiplexed NOR/PSRAM read timings. Changed $t_{(NWAIT-CLKH)}$ to $t_{su(NWAIT-CLKH)}$ and updated $t_{su(DV-CLKH)}/t_{h(DV-CLKH)}$ and $t_{su(NWAIT-CLKH)}/t_{h(NWAIT-CLKH)}$ in Table 75: Synchronous non-multiplexed NOR/PSRAM read timings. Updated $t_{su(SDCLKH_Data)}$ and $t_{h(SDCLKH_Data)}$ in Table 79: SDRAM read timings and Table 80: LPDDR SDRAM read timings. Replaced FMC_CLK by FMC_SDCLK in Section : SDRAM waveforms and timings. Updated $t_{s(IN)}$ and $t_{h(IN)}$ in Table 83: QUADSPI characteristics in SDR mode and $t_{sr(IN)}/t_{sf(IN)}$ and $t_{hr(IN)}/t_{hf(IN)}$ in Table 84: QUADSPI characteristics in DDR mode. Added reference to AN5354 application note in note of Table 86: ADC characteristics. Updated Figure 40: ADC accuracy characteristics and Figure 41: Typical connection diagram when using the ADC with FT/TT pins featuring analog switch function. Changed V_{DAC_OUT} maximum value to $V_{REF+} - 0.2$ in Table 90: DAC accuracy. Changed temperature condition to 130 °C for TS_CAL2 in Table 93: Temperature sensor calibration values. Updated T_L maximum value in Table 92: Temperature sensor characteristics. Updated DuCyCKOUT in Table 100: DFSDM measured timing - 1.62-3.6 V. Updated Figure 49: USART timing diagram in SPI master mode and Figure 50: USART timing diagram in SPI slave mode. Updated $t_{su(MI)}$ and $t_{h(MI)}$ in Table 107: SPI dynamic characteristics. Updated Table 11: Current characteristics. Updated $t_{ISU}, t_{IH}, t_{ISUD}, t_{IHd}$ and t_{OH} in Table 111: Dynamics characteristics: SD / MMC characteristics, VDD = 2.7 to 3.6 V. Updated t_{ISU}, t_{IH} in Table 112: Dynamics characteristics: eMMC characteristics VDD = 1.71V to 1.9V. Added Section : USB OTG_FS characteristics. Updated Table 114: Dynamics characteristics: USB ULPI. Updated Section 7.5: LQFP144 package information (1A), Section 7.8: LQFP176 package information (1T), Section 7.9: LQFP208 package information, Section 7.10: UFBGA(176+25) package information (A0E7), and Section 7.12: TFBGA240+25 package information. Modified title for footprint figure and PCB design rules table (examples instead of recommendations). Added note related to the availability of tape and reel packing in Section 8: Ordering information. Added Section 9: Important security notice.</p>

Table 130. Document revision history

Date	Revision	Changes
19-Jan-2026	3	<p>In the context of I2C, replaced master and slave by controller and target, respectively.</p> <p>Updated features on cover page.</p> <p>Updated Table 2: STM32H755xl features and peripheral counts.</p> <p>Updated Figure 1: STM32H755xl block diagram.</p> <p>Updated Section 3.4: Boot modes.</p> <p>Updated Table 7: Legend/abbreviations used in the pinout table.</p> <p>Updated Table 8: STM32H755xl pin-ball definition.</p> <p>Updated Table 9: Alternate functions.</p> <p>Updated Figure 13: Power supply scheme.</p> <p>Updated Table 13: General operating conditions.</p> <p>Updated Table 15: VCAP operating conditions.</p> <p>Updated Figure 16: External components for SMPS step-down converter.</p> <p>Updated Table 39: Peripheral current consumption in Run mode.</p> <p>Updated Section : Low-speed external user clock generated from an external source.</p> <p>Updated Figure 23: Typical application with an 8 MHz crystal.</p> <p>Updated Table 59: I/O static characteristics.</p> <p>Updated Figure 40: ADC accuracy characteristics.</p> <p>Updated Table 86: ADC characteristics.</p> <p>Updated Table 92: Temperature sensor characteristics.</p> <p>Updated Table 93: Temperature sensor calibration values.</p> <p>Updated Section : I2C interface characteristics.</p> <p>Updated Table 120: LQFP144 - Mechanical data.</p> <p>Updated Table 121: LQFP176 - Mechanical data.</p> <p>Updated Table 122: LQFP208 - Mechanical data.</p> <p>Updated Table 128: TFBGA240+25 - Example of PCB design rules.</p>

IMPORTANT NOTICE – READ CAREFULLY

STMicroelectronics NV and its subsidiaries (“ST”) reserve the right to make changes, corrections, enhancements, modifications, and improvements to ST products and/or to this document at any time without notice.

In the event of any conflict between the provisions of this document and the provisions of any contractual arrangement in force between the purchasers and ST, the provisions of such contractual arrangement shall prevail.

The purchasers should obtain the latest relevant information on ST products before placing orders. ST products are sold pursuant to ST's terms and conditions of sale in place at the time of order acknowledgment.

The purchasers are solely responsible for the choice, selection, and use of ST products and ST assumes no liability for application assistance or the design of the purchasers' products.

No license, express or implied, to any intellectual property right is granted by ST herein.

Resale of ST products with provisions different from the information set forth herein shall void any warranty granted by ST for such product.

If the purchasers identify an ST product that meets their functional and performance requirements but that is not designated for the purchasers' market segment, the purchasers shall contact ST for more information.

ST and the ST logo are trademarks of ST. For additional information about ST trademarks, refer to www.st.com/trademarks. All other product or service names are the property of their respective owners.

Information in this document supersedes and replaces information previously supplied in any prior versions of this document.

© 2026 STMicroelectronics – All rights reserved