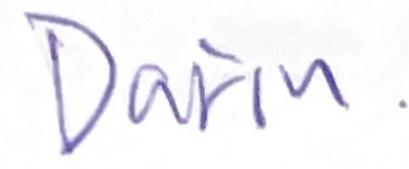
Pre-Experiment Survey

Thank you for participating in this experiment titled "Assisted Teleoperation: SUB-EXPERIMENT NAME"!

In order for us to better understand the results of your use of the experimental system, we'd like to ask you a
few questions about your background and familiarity with teleoperation and robotic devices.

Please do not hesitate to ask the investigator any questions you may have about this form or the experiment in general.

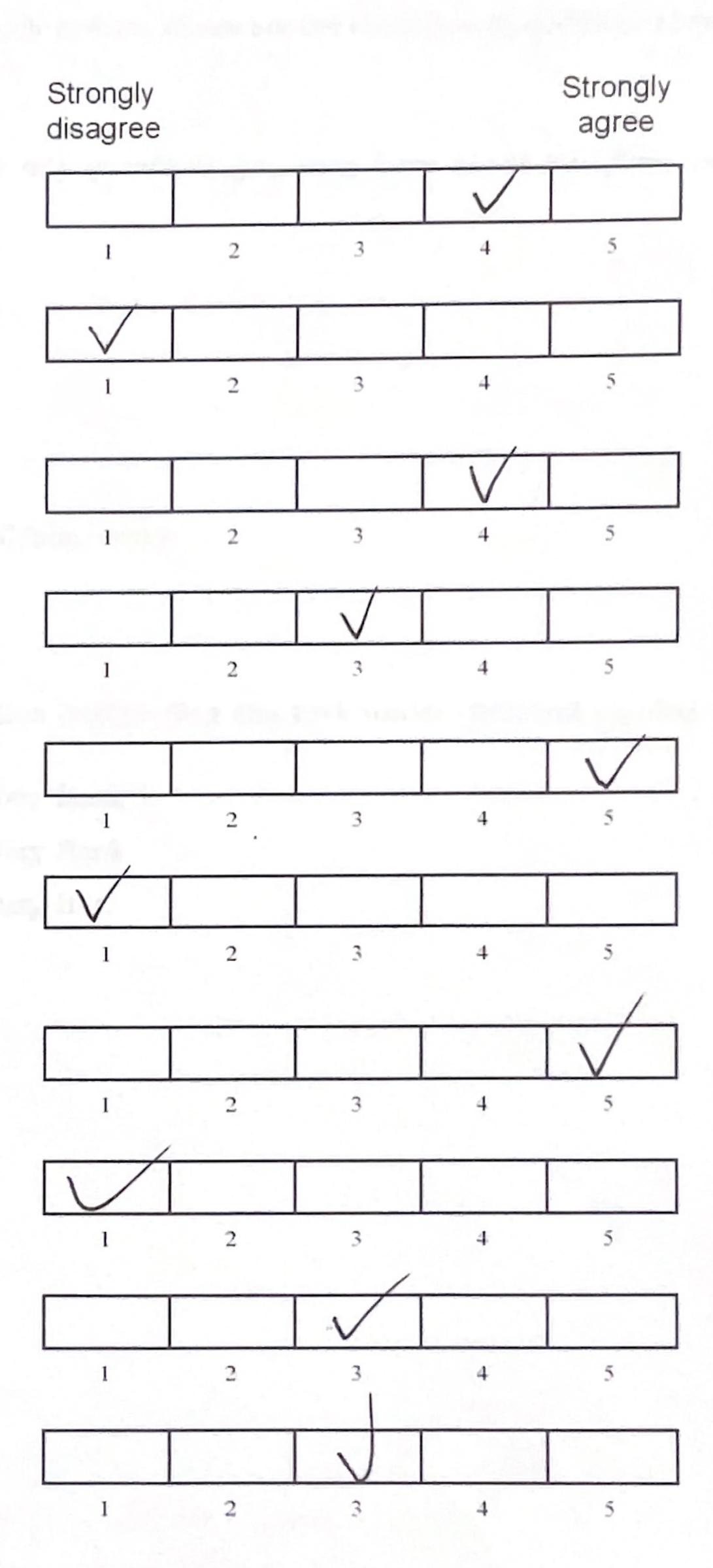
Bookkeeping:	Jann Shav.			
Subject ID: 20 Today's Date: 20	1 2024 (dd,		уу)	
About You:				
	Age: 21 ye nder: Male			
	ness: 🗆 Left			
U.S. Citizen or Resident A	lien: Yes	No \square	Prefer not to say.	
How experienced are you w	ith teleoperation a	and hur	nan-robot interactive device	es?
□ Limited I've used	ny first time using such such a device once o one or more devices	or twice.		
□ Experienced I've deve	loped teleoperation s	ystems,	myself.	
Are you currently experience	cing any of the foll	lowing?		
Injuries to your hand or arm	□ Left □ Right	No	□ Prefer not to say.	
Neurological disorders:	□ Yes	No	□ Prefer not to say.	
Uncorrected impaired vision:	□ Yes	VNo	□ Prefer not to say.	
Poor depth perception:	□ Yes	No No	□ Prefer not to say.	
Color blindness:	□ Yes	th No	□ Prefer not to say.	
Headache:	□ Yes	No	□ Prefer not to say.	
Fatigue:	□ Yes	₽No	□ Prefer not to say.	
If there are any other factor	s which you think	might	affect your performance in	this experiment
and wish to share them, ple	ase use the space	below:		



System Usability Scale

© Digital Equipment Corporation, 1986.

- 1. I think that I would like to use this system frequently
- I found the system unnecessarily complex
- I thought the system was easy to use
- 4. I think that I would need the support of a technical person to be able to use this system
- I found the various functions in this system were well integrated
- I thought there was too much inconsistency in this system
- I would imagine that most people would learn to use this system very quickly
- 8. I found the system very cumbersome to use
- I felt very confident using the system
- 10. I needed to learn a lot of things before I could get going with this system



Post-Experiment Survey

Thank you for participating in this experiment titled "Assisted Teleoperation: SUB-EXPERIMENT NAME"!

In order for us to characterize your experience with the system, please answer the following questions about the experiment you have just completed.

Please do not hesitate to ask the investigator any questions you may have about this form or the experiment in general.

Bookkeeping:

Your Experience:

How would you rate the difficulty you had when completing the task under different conditions?

Feedback:

How would you compare the strategies you used to complete the task in the different conditions?
Very complicate for me at first for and I'm gerting more and more confidence ge it.
In the different conditions, did you feel like you were commanding the robot as if it were another person, or did you feel like the robot was a projection of your own body? I feel very confident for this well designed System to be used on my own body, if the technician operators cell well trained.
Were there any instances where you expected the system to behave one way, but it did something else?
I did not find any counter-intuitive command on operation was received here. The only thing confused me was the XYZ cover when I fire can it & I don't know how to receive it.

Any other comments or suggestions on how you think the system should behave?	
This recient/mashine is really good. The only thing I comes to my mind is the a section for users to endicate sensitivity, like mice for computers.	E
	_