Pre-Experiment Survey

Thank you for participating in this experiment titled "Assisted Teleoperation: SUB-EXPERIMENT NAME"! In order for us to better understand the results of your use of the experimental system, we'd like to ask you a few questions about your background and familiarity with teleoperation and robotic devices.

Please do not hesitate to ask the investigator any questions you may have about this form or the experiment in general.

Bookkeeping:				
Subject ID: 19 / Noww. Today's Date: 10 / 10 /	1			
Today's Date: 10 /	2024 (de	d/mm/yy	ууу)	
About You:				
Age:	y	ears		
Gender:	F		Prefer not to say.	
Handedness:	□ Left ✓	Right	□ Ambidextrous	
U.S. Citizen or Resident Alien:	□ Yes ✓	No 🗆	Prefer not to say.	
How experienced are you with te	leoperation	and hur	man-robot interactive device	es?
- · · · · · · · · · · · · · · · · · · ·				
□ None This is my first		ıch a dev	ice.	
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and wish to share them, please use the space below:

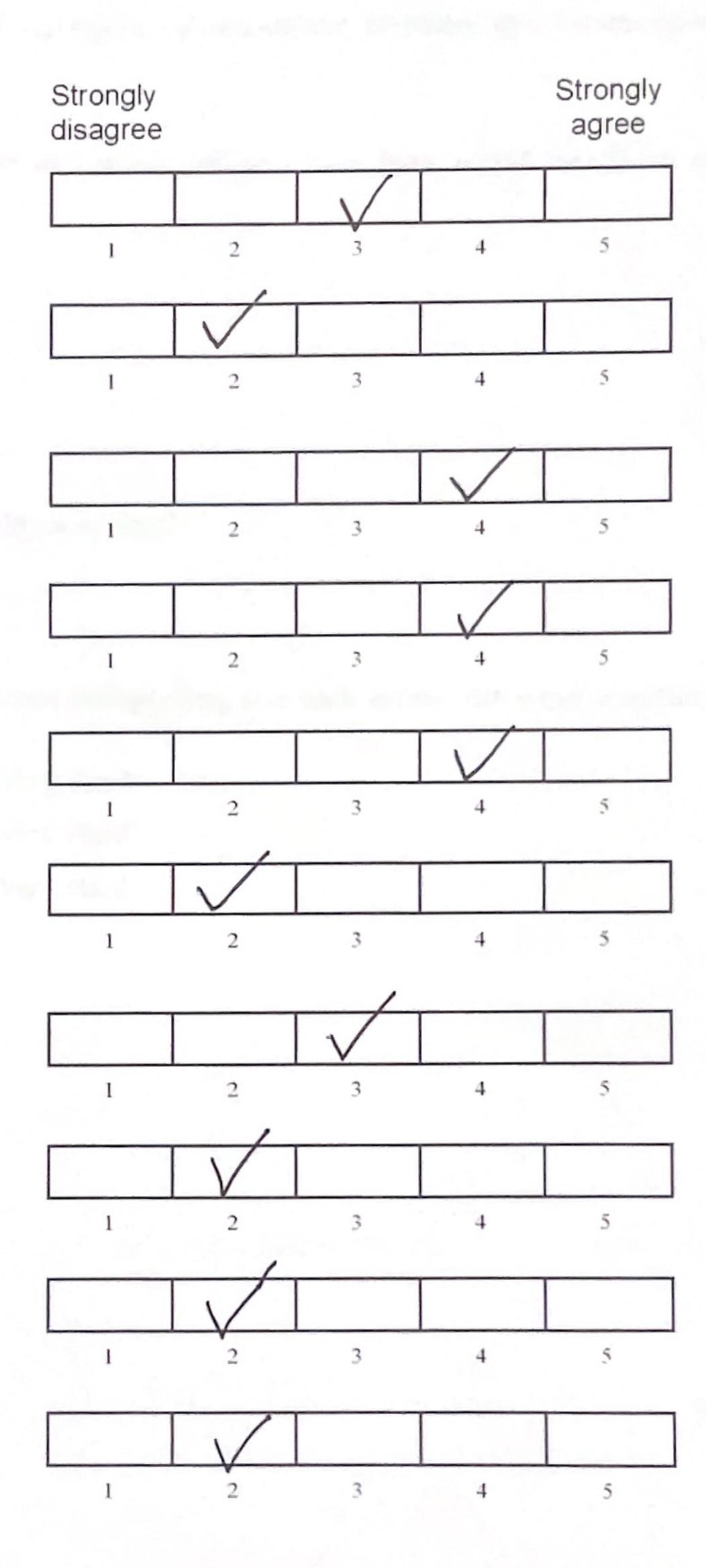
5

System Usability Scale

Zhow Yuxuam.

© Digital Equipment Corporation, 1986.

- 1. I think that I would like to use this system frequently
- I found the system unnecessarily complex
- I thought the system was easy to use
- I think that I would need the support of a technical person to be able to use this system
- I found the various functions in this system were well integrated
- I thought there was too much inconsistency in this system
- I would imagine that most people would learn to use this system very quickly
- I found the system very cumbersome to use
- I felt very confident using the system
- I needed to learn a lot of things before I could get going with this system



Post-Experiment Survey

Thank you for participating in this experiment titled "Assisted Teleoperation: SUB-EXPERIMENT NAME"!

In order for us to characterize your experience with the system, please answer the following questions about the experiment you have just completed.

Please do not hesitate to ask the investigator any questions you may have about this form or the experiment in general.

KOO	KKOO	ning.
	NNCC	ping:

Subject ID:	Zhao Mixnam	
Task ID:		
Today's Date:	10 / 11 /	2024 (dd/mm/yyyy)

Your Experience:

How would you rate the difficulty you had when completing the task under different conditions?

	/
Condition 1:	Very Easy □—□—□—□ Very Hard
Condition 2:	Very Easy □—□—□—□ Very Hard
Condition n:	Very Easy □—□—□—□ Very Hard

Feedback:

How would you compare the strategies you used to complete the task in the different conditions'
St Condition 3 is the easiest to complete the task.
The gray dot helps. The sline line helps.
The gray dat helps.
The blue line helps.
In the different conditions, did you feel like you were commanding the robot as if it were another
person, or did you feel like the robot was a projection of your own body?
I fest like the poot was a projection of my own body.
Were there any instances where you expected the system to behave one way, but it did something
else?
I was expecting some depth information to tell me whether my hands ove on the same
level.

Any other comments or suggestions on how you think the system should behave	ave?	
The positions to be measured can be marked more clearly.		
The positions to be measured can be marked more clearly. If there is asses some wint about whether the position has been faint	anunatery	reacheo
that would be great.		