

# TopoSampler: A topology constrained noise sampling in GANs

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## Objectives

- Introduce a topological perspective towards disconnected manifold learning in GANs
- Demonstrate the importance of prior-space topology in disconnected manifold learning.
- Run initial experiments on a novel noise module for learning topologically constrained priors.
- Run initial experiments on a homeomorphism constrained generator.

## Introduction

Learning distribution with disconnected manifold is a challenging problem. The distribution learned by a regular vanilla GAN, with unimanifolded-prior, creates a global cover over the disconnected components. This produces samples, which are unrealistic interpolation between two completely distinct classes.

*Motivation for exploring topological perspective towards disconnected manifold learning:*

- Disconnectedness in manifold is topologically represented as  $0^{th}$  dimensional holes in space. This makes it interesting to study a generalized form of manifold disconnectedness in terms of d-dimensional holes.
- current method are either resource intensive (multi-generator) or have lower overall precision.(rejection sampling)

## Proposed Solution

We found empirical evidence on the important of prior space topology in learning disconnected posteriors. Based on that we divide the learning problem in two parts:

- **Prior Topology Optimization:** We explicitly introduce d-dimensional holes in the unimanifolded prior space, by regularizing it to be homologically similar to the data space
- **Homeomorphic density estimation:** Next, we learn an isometric map from the learned prior to the posterior space. This ensures, the d-dimensional holes in the prior space, are preserved during GAN training.

## Method Overview

- By leveraging a Neural Network, we learn a mapping from a gaussian distribution to a latent space. Using results from [1] we create a synthetic prior space, with a sample space regularized to be topologically similar to the data space.
- We use a lipschitz-constrained GAN to learn a homeomorphism between the synthetic prior space and the target data space (i.e., the posterior space). The weights of the generator are singular-value normalized to ensure 1-Lipschitz continuity. Along with 1-Lipschitz learnable layers, usage of 1-Lipschitz activations in the generator ensures  $L \leq 1$  throughout, thus explicitly establishing an isometry, thereby homeomorphism. [2]

## Experiments

The following observations are made in our experiments.

- increasing the dimension of prior space, reduces the quality of samples generated by a GAN.
- Neural Networks are inherently not suitable are introducing holes in the manifold. Demonstrated by the “stretching effect” of a manifold when topological regularization is performed. (See figure 1(a))
- Lipschitz constraining the generator although makes the training highly unstable, does have a homeomorphic effect with respect to the prior. (See figure 1(b))

## Optimization Objective

Let  $\mathcal{X} = \{x_0, x_1, \dots\}$  with  $x_i \in \mathbb{R}^d$  denote the original data samples, which we consider to be samples from an underlying manifold  $\mathbf{M}_{\mathcal{X}}$ , and probability distribution  $P(\mathcal{X})$ . Let the generator of the proposed GAN be represented as  $\mathcal{G}_{\theta}$  and the discriminator as  $\mathcal{D}_{\phi}$ . Similarly, a parametric function  $N_{\psi}$  with a latent sample space  $\mathfrak{N}$ , is used for mapping  $\mathcal{N}(0, 1) \rightarrow P(\mathfrak{N})$ , whose sample space manifold,  $\mathbf{M}_{\eta}$ , is explicitly regularized to be topologically similar to  $\mathbf{M}_{\mathcal{X}}$ . This topological similarity is explicitly induced using signature loss  $\mathcal{L}(\mathcal{X}, \mathfrak{N})$  defined as:

$$\mathcal{L}(\mathfrak{N}, \mathcal{X}) = \frac{1}{2} \|D_{\mathcal{X}}[\Pi_{\mathcal{X}}] - D_{\mathfrak{N}}[\Pi_{\mathcal{X}}]\|^2 + \frac{1}{2} \|D_{\mathcal{X}}[\Pi_{\mathfrak{N}}] - D_{\mathfrak{N}}[\Pi_{\mathfrak{N}}]\|^2$$

Where  $D_{\mathcal{X}}$  and  $D_{\mathfrak{N}}$  denotes the pairwise distances between sample sets  $\mathcal{X}$  and  $\mathfrak{N}$  respectively.  $\Pi_{\mathcal{X}}$  and  $\Pi_{\mathfrak{N}}$  are the indices of topologically significant simplices found by Vietoris–Rips Filtration  $\mathfrak{R}_{\epsilon}(\mathcal{X})$  and  $\mathfrak{R}_{\epsilon}(\mathfrak{N})$  of sample spaces  $\mathcal{X}$  and  $\mathfrak{N}$ .

In adversarial optimization, the discriminator objective remains the same, Whereas the generator loss is appended with  $\mathcal{L}$  as a regularization term.

$$\mathbb{E}_{z' \sim P(\mathfrak{N})} [\ln(1 - \mathcal{D}_{\phi}(\mathcal{G}_{\theta}(z')))] + \left[ \frac{1}{B} \sum \mathcal{L}(N_{\psi}(z), x_r) \right]_{z \sim \mathcal{N}(0,1), x_r \sim P(\mathcal{X})}$$

## Conclusion

- This work studies the problem of learning disconnected sample space manifolds in GANs by topologically aligning the prior space to the original data space.
- We introduce a persistent homology perspective towards augmenting the prior distribution to stay in the same homology class as that of our unknown data manifold.

## References

- [1] Michael Moor, Max Horn, Bastian Rieck, and Karsten Borgwardt. Topological autoencoders, 2020.
- [2] Takeru Miyato, Toshiki Kataoka, Masanori Koyama, and Yuichi Yoshida. Spectral normalization for generative adversarial networks. In *International Conference on Learning Representations*, 2018.
- [3] Mahyar Khayatkhoei, Ahmed Elgammal, and Maneesh Singh. Disconnected manifold learning for generative adversarial networks, 2019.

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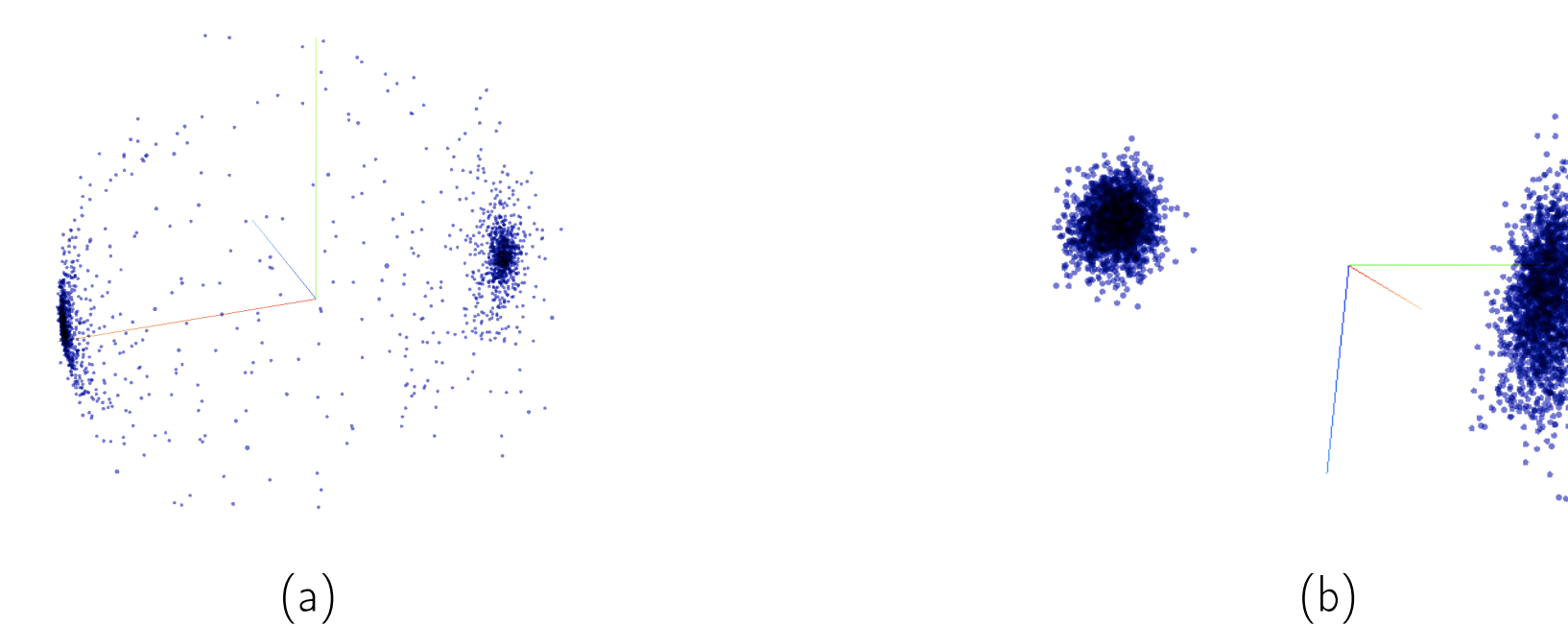


Figure 1: Figure 1(a), the sparsely spread samples between two distribution demonstrates the “stretching effect” of topological regularization. Figure 1(b), GAN learns a hole preserving map between prior and posterior. Here disconnected prior was used to learn a disconnected posterior.

For more information please refer to the paper.